## VELOCITY RESONANCE

The displacement of a driven oscillation is given by  $x = A sin (pt - 0) \rightarrow (1)$ 

Substitute for A

e for 
$$t$$
  
 $x = \frac{10}{\sqrt{(\omega_0^2 - p^2)^2 + 4k^2p^2}}$ 

.. The velocity of the driver oscillator at that instant is v= dx = pAcos(pt-0) -> 2).

$$V = \frac{f_0}{\sqrt{(\omega_0^2 - p^2)^2 + 4 \kappa^2 p^2}} \quad \text{p cos} \left(pt - \theta\right)$$

$$\left(V = V_0 \sin\left(pt - \theta + \frac{\pi}{2}\right)\right) \quad \text{sin} \left(\frac{\pi}{2} + \theta\right)$$

$$= \cos \theta$$

$$\sin \left(\frac{\pi}{2} + \theta\right)$$

where 
$$V_0 = \frac{f_0 p}{\sqrt{(w_0^2 - p^2)^2 + 4k^2 p^2}}$$
  $\frac{2 p_0 = tan^4 \left(\frac{2kp}{w_0^2 - p^2}\right)}{\left(\frac{2kp}{w_0^2 - p^2}\right)}$ 

Vo is known as velocity Amplitude Thus the velocity Amplitude Vo varies with J. when \$=0, v=0. & maximum when \$= wo. Hence at the foreguery \$=10. (driving frequency is equal to the Hatter at frequency). of the inpressed force, the velocity has the maximum value & we call it as relouty Resonance.

(w2-p2)

from characters by dividing

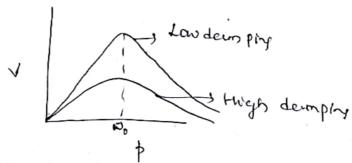
2KPA= do sin o

(w3-p2)A = fo coso-

consider of () V = vo sin (pt-o+ M2)

relocity phase constant =  $-0 + \pi l_2 = -\pi l_2 + \pi l_2 = 0$ Alow, as we know the displacement at Personance large behind in phase by  $\pi l_2$  behind the driving force  $l_3$ as we have just seen velocity then leads the displacement in phase by  $\pi l_2$ .

therefore at Personance, the relocate of driving oscillation is in phase with the diriving force. This is the most favourable situation for transfer of energy from the applied force to the oscillator, because the recte of work done on the Oscillator by the impressed force is FV which is always the for F&V in phase.



when \$2 wo, the velocity amplitude is smaller then \$2 wo.

## Sharpners of Esonance

Let Riso nance the amplitude of the Oscillating system becomes maximum. It decreases from their maximum value with charge in prequency of Impressed force. The Term Sharpness of resonance refers to rate of fall of amplitude with change in foxed frequency on either side of Risonant frequency

the Reite at which the Amplitude changes corresponding to small change in frequency of Applied external force

change in Amp = Amax - A.

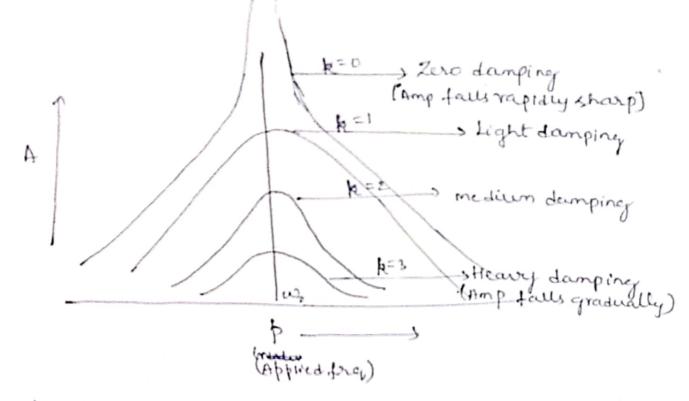
= 
$$\frac{fo}{2k\omega}$$
 -  $\frac{fo}{4k^2p^2+(\omega^2p^2)^2}$  bicog weep

=  $\frac{fo}{2k\omega}$  -  $\frac{fo}{2k\phi}$  | Amax - A.

=  $\frac{fo}{2k\omega}$  -  $\frac{fo}{2k\phi}$  | Amax - A.

| Since | S

sharpness in soversly proportional to k



when the k is large curves are flat -> Personance is

if k is small -> curves are shoup -> peak

if k=0, A is Infinity

when the damping is low, the amplitude falls very rapidly on either side of Resonant frequency of that the Resonance is sharp. On the other hand for high damping the besonance falls of very slowly on either side of resonance fusionance is flut or sharp according to the damping for the oscillating system is large or small.

Example for flat resonance is known of an air column of a despirate bottle with luning fork. Due to its large damping the air column respond with tuning fork over a wide range in the neighbourhood of resonance.

Thus in this case it is actually difficult to give an exact point of Personance. of the resonce is said to be flat.

sut in case of sonameter wire the damping is small suponds only one particular freques, its own natural frequency, hence resonance is starp.

## Quality factor

I factor is a measure of sharpness of Personance, which explains how fast energy decay is an oscillating system, Its a dimensionless parameter.

The mathematical representation is

Energy stored = 
$$KE + PE$$
 |  $\lambda = A \sin(\beta t - \theta)$   
=  $\frac{1}{2}mv^2 + \frac{1}{2}kx^2$  |  $\frac{dx}{dt} = A + \cos(\beta t - \theta)$   
=  $\frac{1}{2}m\left[A^2 + \cos^2(\beta t - \theta)\right] + \frac{1}{2}k\left[A^2 + \sin^2(\beta t - \theta)\right]$ 

E = 1/2 m A2 p2 cos2 (pt-0) + 1/2 m w 2 A2 sin2 (pt-0) -> (2)

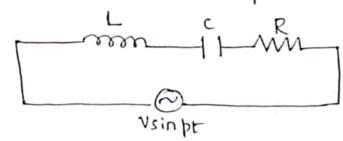
where wo = 1/2 m => k= m w 2

Energy loss per cycle = damping force x velocity  
= 
$$T. VV \times V$$
  
=  $T. V \left(\frac{dx}{dt}\right) \times \left(\frac{dx}{dt}\right)$   
=  $TV \left(\frac{dx}{dt}\right) \times \left(\frac{dx}{dt}\right)$ 

where 
$$T = \frac{\partial R}{\partial \omega} = \frac{\partial R}{\partial \phi}$$
 is  $\frac{\partial R}{\partial \phi} = \frac{\partial R}{\partial \phi} = \frac$ 

## LCR Resonance

consider a series her ext in which Vsinpt is the applied AC voltage, the voltage drop across the Inductor L, Pesistor R & capacitor C respectively.



of the voltage drop across each of the elements.

or

divide throughout by I we have

the above egr occumbles the egr of motion of the vibrating says given by,

$$\frac{d^2y}{dt^2} + \left(\frac{x}{m}\right) \frac{dy}{dt} + \left(\frac{k}{m}\right) \frac{y}{dt} = \left(\frac{f}{m}\right) sinpt} = \frac{1}{(3)}$$

compare of (2) & (3)

$$R \rightarrow r, L \rightarrow m$$
,  $t \rightarrow k$ ,  $q \rightarrow y$ ,  $v \rightarrow f$ ,  $R \rightarrow r$ .

Log  $q \cdot y \cdot y$  are analogous quentity

Thus 
$$\frac{1}{Lc} \rightarrow \frac{k}{m} = \omega^2 \Rightarrow \omega = \sqrt{\frac{k}{m}}$$

Pusonance contr  $\phi = \omega = \sqrt{\frac{k}{m}}$ 

Apprehence from Natural

Apprehence from  $\omega = \omega = \sqrt{\frac{k}{m}}$