



**Mahindra University Hyderabad**  
École Centrale School of Engineering  
End Semester Regular Examination, December-2024

Program: B. Tech.

Branch: CM

Year: IV

Semester: I

Subject: Dynamical Systems (MA4125)

Date: 12/12/2024

Start Time: 10:00 AM

Time Duration: 180 Minutes

Max. Marks: 100

**Instructions:**

- 1) All questions are compulsory.
- 2) Everything you write (including any notes and rough work) must be in the answer booklet.
- 3) Give proper justification for your answers. Marks will not be awarded for guess work.

**Q 1:**

**20 Marks**

Consider the nonlinear system  $\dot{X} = F(X)$ , where  $X = [x_1 \ x_2]^T \in \mathbb{R}^2$  and  $F(X) = \begin{bmatrix} x_1 - x_2 - x_1^3 \\ x_1 + x_2 - x_2^3 \end{bmatrix}$

- i) Show that the origin is an unstable focus for this system. **10 Marks**
- ii) Determine the region where the Poincare-Bendixson theorem can be applied to show the existence of a periodic orbit. **10 Marks**

**Q 2:**

**25 Marks**

- i) Consider the function  $V = \frac{1}{4}x_1^4 + \frac{1}{2}x_2^2 + \frac{1}{3}x_3^3$ . Show that this is a possible candidate for Lyapunov function. Study stability of the origin of the system  $\dot{x}_1 = x_2$ ,  $\dot{x}_2 = -x_1^3 - x_2^3 - x_3^3$ ,  $\dot{x}_3 = x_2 - x_3$ . **10 Marks**
- ii) Consider the system  $\dot{x}_1 = -x_1 + x_1x_2$ ,  $\dot{x}_2 = \frac{x_1}{1+x_1^2}$ . Find the function  $\phi(x_1)$  in Lyapunov function of the form  $V = \phi(x_1) + x_2^2$  so that the origin is asymptotically stable. Is the origin globally asymptotically stable **15 Marks**

**Q 3:**

**20 Marks**

Consider the system  $\dot{x}_1 = ax_1 - x_1x_2$ ,  $\dot{x}_2 = bx_1^2 - cx_2$ , where  $a$  and  $c$  are positive constants with  $c > a$ . Let  $D = \{(x_1, x_2)^T \in \mathbb{R}^2 | x_2 \geq 0\}$ .

- i) Find the value of  $b$  for which the system is a gradient system and find potential function  $U$ . **10 Marks**
- ii) Show, using Bendixson's criterion, that there are no periodic orbits through any point in  $D$ . **10 Marks**

Q 4:

20 Marks

Find the limit cycle of the system  $\dot{x}_1 = x_2 + x_1(x_1^2 + x_2^2 - 1)$ ,  $\dot{x}_2 = -x_1 + x_2(x_1^2 + x_2^2 - 1)$  and investigate its stability. Also find the complete solution of the system.

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Q 5:

15 Marks

Consider the one dimensional system  $\dot{x} = \alpha - x - \exp(-x)$ ,  $\alpha \in \mathbb{R}$ . Show that the system exhibits saddle node bifurcation and determine the critical points and the bifurcation value for this differential equation. Draw the bifurcation diagram.

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