PhD Midway Seminar

Simulation Tool and its application

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Introduction





My PhD Plan

PhD Program	
Phase 1	Make a simulation Tool
Phase 2	Apply it for comparing different estimation Methods
Phase 3	Extend the simulation tool for model with background information
Phase 4	Apply it to test multi- matrix extension of PLS models such as LPLS and UPLS

- Make Simulation Tools for multiresponse linear model data
- Using the tool, compare various estimation techniques and understand them
- Extend the simulation tool incorporating model with background information
 - Apply this extended tool to test multi-matrix extension of partial least square (PLS) models such as LPLS and UPLS (both uses background information about X and Y for analysis)





What I learn

- Advanced Multivariate Model and technique to analyze it
- Programming concept for developing statistical packages and applications for various statistical methods
- Extending and improving existing methods in statistics
- And, obviously, to properly document what I have done





Today's Special

Today I will talk about:

- Simulation tool (simulatr) we are building
- A comparative study of various estimation techniques by simulating linear model data using simulatr





simrel-m: A versatile tool for simulating multi-response linear model data



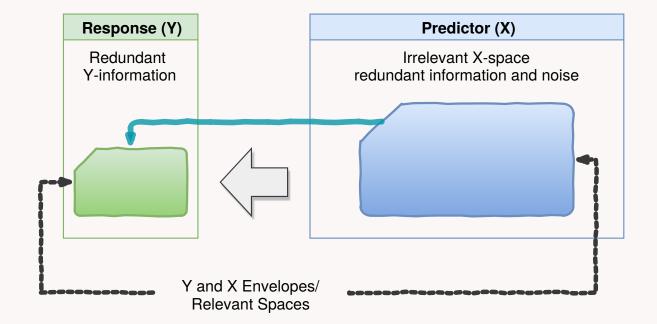


Overview

simrel-M is an extension of simrel (Sæbø, Almøy, & Helland, 2015) r-package for simulating multi-response data

- ullet Uses the idea of reduction of random regression model by separating latent space of ${f X}$ into subspaces that is relevant and irrelevant for predicting each response
- The underlying concept is based on reparameterizing the population model,

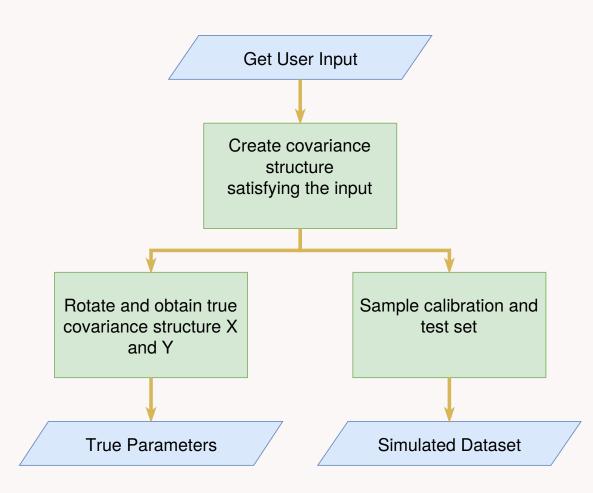
$$\mathbf{Y} = oldsymbol{\mu}_Y + \mathbf{B}^t \left(\mathbf{X} - oldsymbol{\mu}_X
ight) + oldsymbol{\epsilon}, ext{ where } oldsymbol{\epsilon} \sim N(0, oldsymbol{\Sigma}_{Y|X})$$







Underlying procedure



- Collect population input parameter from users such as: number of variables, coefficient of determination and the position of relevant components
- Make a covariance matrix satisfying input parameters
- Rotate the covariance matrix orthogonally
- Sample calibration and validation sets





A comparative study of different estimation methods using simulated data





Overview

Four estimation methods were considered

Ordinary Least Squares (OLS)

- Although unbiased, suffer highly from multicollinearity
- Widely used and can be used as
 Based on Latent Structure and reference for comparison Envelope
- Relatively new method (Cook, Helland, & Su, 2013) and is also based on reduction of regression • model
- Based on Maximum Likelihood but works better than OLS in papproaches n

Partial Least Squares (PLS)

- Well established and widely used method
- free of multicollinearity problem **Bayes PLS**
- Bayesian Estimation of regression coefficient
 - Promising performance was shown in previous studies (Helland, Sæbø, & Tjelmeland, 2012)





Simulation Design

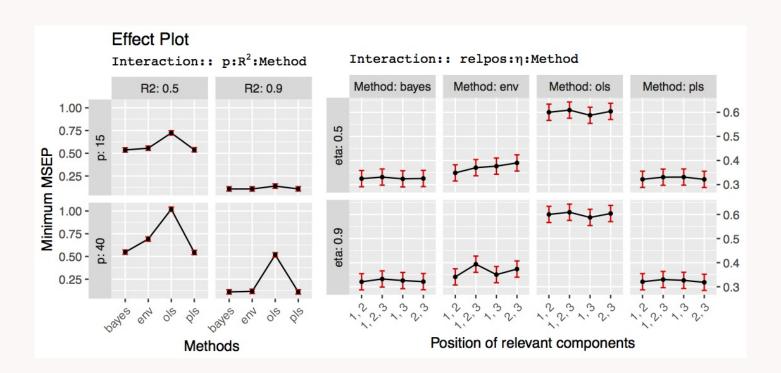
From the possible combination of following parameter combination, 32 single response calibration sets were simulated with 5 replication of each.

- Number of sample observations: 50
- Number of predictor variables: 15 and 40
- Coefficient of determination (\mathbb{R}^2) : 0.5 and 0.9
- Level of multicollinearity: 0.5 and 0.9
- Position of relevant components: 1 and 2; 1 and 3; 2 and 3; 1, 2 and 3





A Systematic Comparison

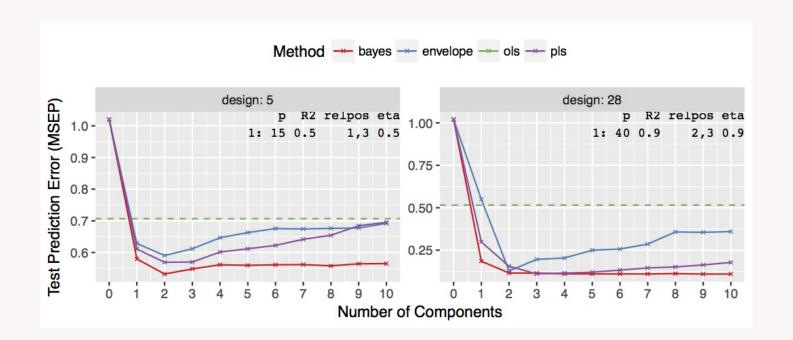


- Bayes PLS has out-performed others methods in all kinds of data
- Envelope has performed better than OLS in all situations and PLS in some situations
- OLS prediction is very poor in noisy data with many predictor variables
- Position of relvant component and the decaying factor of eigenvalue has less impact on prediction in all the models





A Systematic Comparison



- Bayes PLS has approached to its OLS prediction is poor especially minimum error with very few component and remained low for • Envelope method captured its additional component
- PLS has moderate performance but better than envelope in many situations.

- with large number of predictor
- minimum error and the error increased with additional components



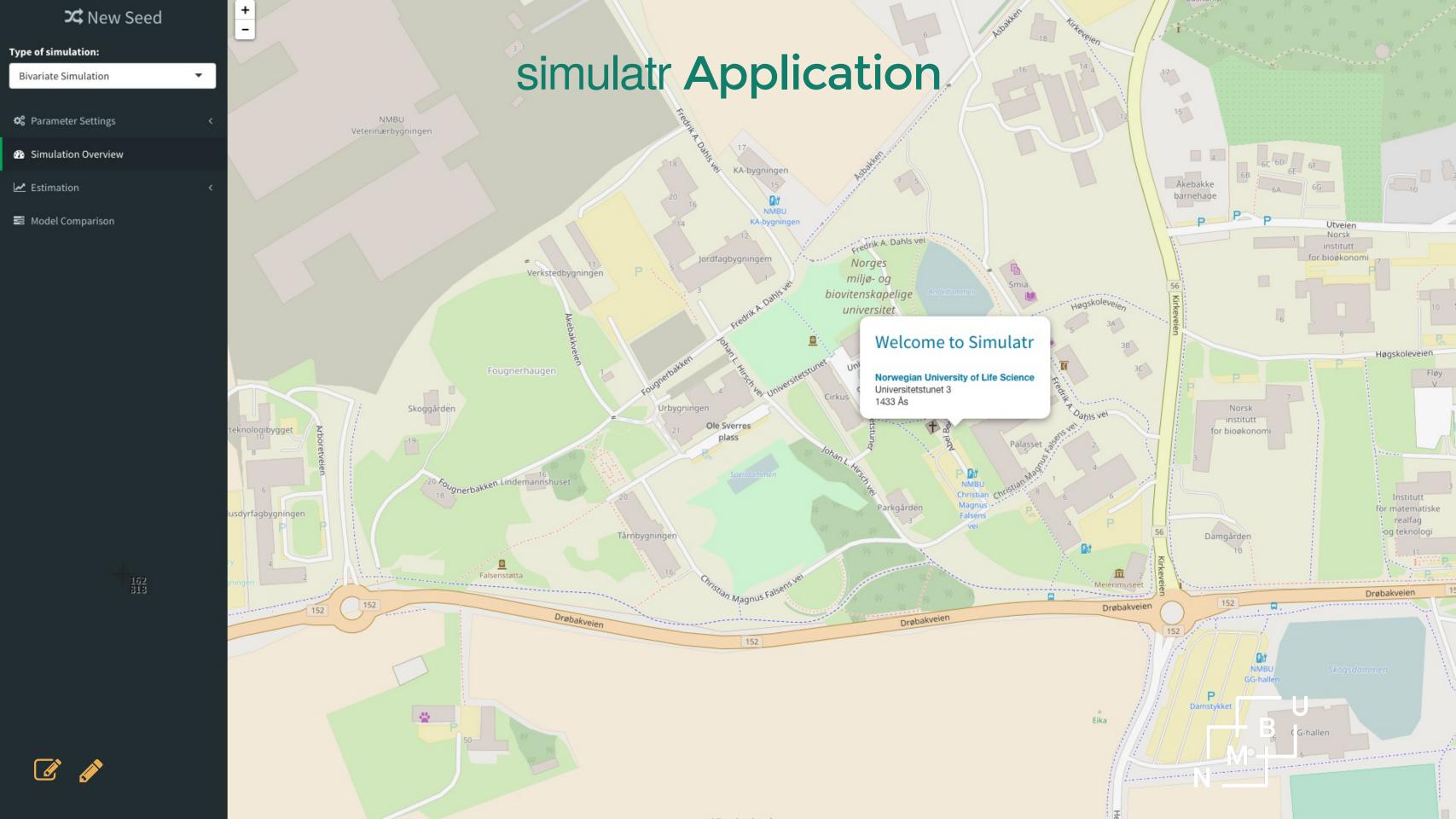


Demonstration



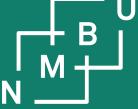






Dakujem teşekkür ederim salamat SUWUN salamak ASANTE mersi 감사합니다 GRAZAS Ευχαριστώ kiikos merci GRAZZii TAKK Рахмет kiitos sywyn धन्यवाद HVALA DAKUJEM teşekkür ederim hvala kiikos mahalo GRACIAS salamak ASANTE Благодарам спасибо gracias

References







References

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