

255RC2



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1. Transpose

Definition

Given $A = (a_{ij})$, $A^T := (a_{ji})$

Proposition

Let A, B be matrices, $\lambda \in \mathbb{R}$.

- ① $(A + B)^T = A^T + B^T$, $(\lambda A)^T = \lambda A^T$
- ② $(AB)^T = B^T A^T$
- ③ $(A^T)^T = A$
- ④ If A is invertible, so is A^T , and $(A^T)^{-1} = (A^{-1})^T$

Definition

A matrix A is called **symmetric** if $A = A^T$

A matrix A is called **skew-symmetric** if $A^T = -A \iff A + A^T = 0$

Remark

- ① A symmetric or skew-symmetric matrix is necessarily square.
- ② For a skew-symmetric matrix, if $i = j$, then $a_{ij} = 0$

Example

$A = \begin{pmatrix} 1 & -4 & -2 \\ 4 & 1 & 3 \\ 2 & -3 & 2 \end{pmatrix}$ is not skew-symmetric.

2. Matrix as a Function

Definition

An $n \times m$ Matrix can be interpreted as a function $F : M_{m \times p} \rightarrow M_{n \times p}$

Property

For $M \in M_{n \times m}$, $A, B \in M_{m \times p}$, $\alpha, \beta \in \mathbb{R}$

We have $M(\alpha A + \beta B) = \alpha MA + \beta MB$

Question

- ① Do you know other function with such property?
- ② Why we want such property?

3. Orthogonal Matrices and Orthonormal Vectors

Definition

A matrix $A \in M_n(\mathbb{R})$ is called an orthogonal matrix iff $A^T = A^{-1}$

Properties.

- I_n is an orthogonal matrix.
- If A and B are orthogonal matrices, then AB is also orthogonal.
- If A is an orthogonal matrix, then A^{-1} is also orthogonal matrix.
- If A is an orthogonal matrix, then $\det(A) = \pm 1$.

Examples.

► Rotation Matrix.

Rotation by θ in \mathbb{R}^2 is given by

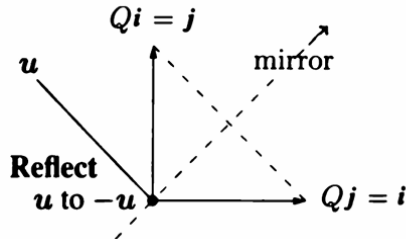
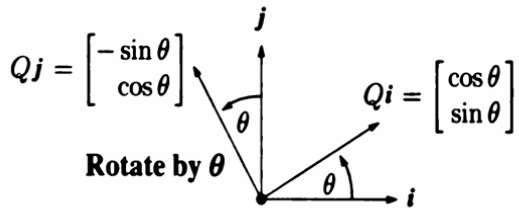
$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}.$$

► Reflection Matrix.

Reflect (x_1, x_2) across $\theta/2$ in \mathbb{R}^2 is given by

$$\begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}.$$

You can treat such matrix as a function $Q : \mathbb{R}^2 \rightarrow \mathbb{R}^2$



Definition

Let $\{v_1, \dots, v_k\} \in \mathbb{R}$ be a subset of k distinct vectors, then $\{v_1, \dots, v_k\}$ is an **orthogonal set of vectors** if $\langle v_i, v_j \rangle = 0$ for all $1 \leq i, j \leq k, i \neq j$.

Also, $\{q_1, \dots, q_k\}$ is an **orthonormal set of vectors** if it is an orthogonal set and all of its vectors are unit vectors (i.e., $\|q_i\| = 1$ for $i \leq i \leq k$).

Remark

Any set containing a single vector is orthogonal; any set containing a single unit vector is orthonormal.

Example.

$\bar{i}, \bar{j}, \bar{k} \in \mathbb{R}^3$.

Proposition

Given vectors $q_i \in \mathbb{R}^n$, $i = 1, \dots, m$ such that

$$\langle q_i, q_j \rangle = q_i^T q_j = \delta_{ij} = \begin{cases} 1, & i = j, \\ 0, & i \neq j, \end{cases} \quad (\delta_{ij} : \text{Kronecker})$$

then we call the set of vectors $\{q_i\}$ orthonormal, and

$$Q = \begin{bmatrix} | & & | \\ q_1 & \dots & q_m \\ | & & | \end{bmatrix} \Rightarrow Q^T Q = I_m.$$

Proof

$$Q^T Q = \begin{bmatrix} - & q_1^T & - \\ & \vdots & \\ - & q_m^T & - \end{bmatrix} \begin{bmatrix} | & & | \\ q_1 & \dots & q_m \\ | & & | \end{bmatrix} = \begin{bmatrix} q_1^T q_1 & \dots & q_1^T q_m \\ \vdots & \ddots & \vdots \\ q_m^T q_1 & \dots & q_m^T q_m \end{bmatrix} = I_m$$

Proposition

$$\text{Let } Q = \begin{bmatrix} | & | & & | \\ \mathbf{q}_1 & \mathbf{q}_2 & \cdots & \mathbf{q}_n \\ | & | & & | \end{bmatrix} \in M_n(\mathbb{R}),$$

where $\{\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n\}$ is a set of orthonormal vectors in \mathbb{R}^n .

Then Q is an orthogonal matrix, $Q^T = Q^{-1}$.

We verify that $QQ^T = I_n$ and $Q^TQ = I_n$.

Exercise

Determine whether the following matrices are orthogonal matrices

$$\begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}.$$

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}.$$

Proposition

The orthogonal matrices are precisely the matrices that preserve the inner product in \mathbb{R}^n i.e., $\forall x, y \in \mathbb{R}^n$, $\langle x, y \rangle = \langle Ax, Ay \rangle$ or $x^T y = (Ax)^T Ay$.

Proof.

If A is orthogonal, i.e., $A^{-1} = A^T$, then $A^T A = I_n$, so
 $(Ax)^T (Ay) = x^T A^T Ay = x^T I_n y = x^T y$. □

① Magnitude of Determinant and Column Norms:

- $|\det(A)| = 1$.
- Column vectors \mathbf{q}_i have unit norm: $\|\mathbf{q}_i\| = 1$.
- *Implication:* The transformation represented by A is a rotation or a reflection.

② Defining Property and Its Consequences:

- $A^T A = I_n$ (which means $A^{-1} = A^T$).
- The original note mentions this "has very good symmetric properties."
- *Implications include:*
 - Preservation of inner products (hence, lengths and angles are preserved: $\langle Ax, Ay \rangle = \langle x, y \rangle$).
 - The inverse A^{-1} is easy to compute (it's just the transpose A^T).

③ Applications in Data Processing:

- Effective in removing redundant information from data

4. Kernel and Image

Definition

- Given matrix $A \in M_{m \times n}(\mathbb{R})$. The kernel, or nullspace of A , is defined as

$$\ker A = N(A) = \{x \in \mathbb{R}^n \mid Ax = \mathbf{0}\} \subseteq \mathbb{R}^n$$

where $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

- The image of A , or column space, is defined as

$$\begin{aligned} \operatorname{im} A = C(A) &= \{y \in \mathbb{R}^m \mid \exists x \in \mathbb{R}^n, y = Ax\} \\ &= \{Ax \mid x \in \mathbb{R}^n\} \end{aligned}$$

(The image is a subspace of \mathbb{R}^m).

Definition

A function $f : A \rightarrow B$ is called injective, if

$$\forall x_1, x_2 \in A, f(x_1) = f(x_2) \implies x_1 = x_2$$

$$\text{i.e., } \forall x_1, x_2 \in A, x_1 \neq x_2 \implies f(x_1) \neq f(x_2)$$

Proposition

Given $A \in M_{m \times n}(\mathbb{R})$, i.e., $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$

then, A is injective $\iff \ker A = N(A) = \{0\}$

Proof

(\Rightarrow) Assume A is injective, that is,

$$\forall x_1, x_2 \in \mathbb{R}^n, Ax_1 = Ax_2 \implies x_1 = x_2.$$

Take $v \in \ker A$, i.e., $Av = 0$. We also know that $A0 = 0$, hence $Av = A0$. By injectivity of A , $v = 0$. Therefore $\ker A = \{0\}$.

(\Leftarrow) Conversely, suppose $\ker A = \{0\}$.

Take $v_1, v_2 \in \mathbb{R}^n$, s.t. $Av_1 = Av_2$. We want to show that $v_1 = v_2$. Indeed, we have $A(v_1 - v_2) = 0$, but $\ker A = \{0\}$, hence $v_1 - v_2 = 0$. So $v_1 = v_2$.

Proposition

Given $A \in M_{m \times n}(\mathbb{R})$, $\ker(A) = \ker(A^T A)$

Proof

(\subseteq) Take $x \in \ker(A)$, i.e., $Ax = 0$. So $(A^T A)x = A^T(Ax) = A^T 0 = 0$. So $x \in \ker(A^T A)$.

(\supseteq) Take $x \in \ker(A^T A)$, i.e., $A^T Ax = 0$. So $x^T A^T Ax = x^T 0 = 0$.

$(Ax)^T Ax = \|Ax\|^2 = 0 \implies Ax = 0 \implies x \in \ker A$.

$(v_1^2 + v_2^2 + \cdots + v_n^2 = 0 \implies v_i = 0)$

5. Projection Matrix

Definition

A matrix $P \in M_n(\mathbb{R})$ is a projection matrix, if $P^2 = P$.

It is called an orthogonal projection, if $P = P^T$.

Example

For an orthonormal matrix Q

- $(QQ^T)^T = (Q^T)^T Q^T = QQ^T$
- $(QQ^T)^2 = (QQ^T)(QQ^T) = Q(Q^T Q)Q^T = QI_k Q^T = QQ^T$

$QQ^T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a projection

Proposition

A projection matrix P is an orthogonal projection if

$$\ker P \perp \operatorname{im} P$$

i.e., $\forall x \in \ker P, \forall y \in \operatorname{im} P,$

$$\langle x, y \rangle = x^T y = 0 \in \mathbb{R}$$

Exercise

Show that $\ker P \perp \operatorname{im} P$ if $P = P^T$

Example

$$\{q_1, q_2\} = \left\{ \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{pmatrix}, \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \\ 0 \end{pmatrix} \right\}$$

$$Q = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \\ 0 & 0 \end{bmatrix}, \quad Q^T = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 1/\sqrt{2} & -1/\sqrt{2} & 0 \end{bmatrix}$$

$$QQ^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ 0 \end{pmatrix}$$

- ① VV255, Lecture Notes 24SU, Runze Cai
- ② VV255 RC2, Jiayue Huang, et al
- ③ Introduction to Linear Algebra, Sixth Edition, Gilbert Strang

Thank you and Enjoy your Summer Semester!