

TESS Asteroseismic Predictions for Red Giants using Machine Learning

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ABSTRACT

Summary: This paper presents a method to predict Red Giant mode detectability with TESS, using the Machine Learning algorithm Classification. It requires only the global parameters $\Delta\nu$, ν_{\max} , the stellar magnitude and length of observation.

Method: Lightcurves for *Kepler* stars with fitted radial mode frequencies were used to generate equivalent TESS lightcurves. The lightcurves were cut down, *Kepler* white noise was removed, the bandpass was adjusted, and TESS white noise was added. A detection test was run on the observed modes in these ‘TESS-like’ lightcurves. Classifiers were then used to predict mode detectability with TESS based upon the global asteroseismic parameters ν_{\max} and $\Delta\nu$, as well as the stellar magnitude.

Application: By changing only the length of dataset and instrumental noise level, this tool can make predictions for any future mission such as K2, PLATO or CoRoT. This is therefore an ideal tool for target selection.

1 INTRODUCTION

Satellites such as *Kepler* have allowed asteroseismology of solar-like and Red Giant stars to advance rapidly since the last century (Chaplin & Miglio (2013)). Power spectra can now be resolved to detect individual modes of oscillation in Red Giant stars (Davies & Miglio 2016). The larger amount of available information is a perfect platform on which to use Classification. This is not a new technique to astrophysics (for example, Green et al. (2015)), although it has never been applied to asteroseismic target selection.

Future space missions such as TESS (Ricker et al. 2014), K2 (Howell et al. 2014), CoRoT (Baglin et al. 2006) and PLATO (Rauer et al. 2014) will add to our understanding of stellar structure and evolution. In order to select asteroseismic targets for these missions, the potential detectability modes inside these stars needs to be estimated.

In this work, individual fitted modes from Davies & Miglio (2016) were used to make asteroseismic predictions for TESS. By separating the targets into those with detected modes, and those without, Machine Learning was used to select a set of targets for future observation. Section 2 describes how the timeseries of every star was treated before transforming it to a power spectra. Section 3 then goes on to describe the detection test that was run of every fitted mode.

Lastly, Section 4 describes classification into stars with detected modes, and stars without. This was done by giving information on every target (the frequency of maximum solar-like amplitude ν_{\max} , the large separation between modes of the same angular degree $\Delta\nu$, the magnitude, and which modes were detected inside the star) was given to a supervised Classifier. This data given to the Classifier is called the training set—it was used to train the algorithm. 30% of the sample was kept to test the algorithm—this data is known as the testing set. The Classifier recognised patterns be-

tween the variables in the training set, and made predictions on the testing set with a ????????% accuracy.

2 TRANSFORMING THE LIGHTCURVES

Firstly, the timeseries data from *Kepler* observations needed to be adjusted for a different satellite and mission. This could either be done in the time or frequency domain. Both methods were tested and compared. The time domain method was chosen to transform the lightcurves, and was used in the rest of this work.

Several different adjustments needed to be made to the *Kepler* data. One difference between the missions is the length of observation. The *Kepler* mission observed for 4 years, while TESS’ nominal 2 year mission will observe stars for between 27 days to 1 year, according to the star’s ecliptic latitude (Figure 1). This distinction is made clear in the timeseries, see Figure 2.

As well as reducing the dataset length, the bandpass that TESS will observe in is much redder than that of *Kepler*, Figure 3. This has the effect of reducing the amplitude of stellar signals (i.e the signal due to stellar granulation and oscillation). Campante et al. (2016) found this bandpass correction to be 0.85.

Thirdly, the instrumental noise level in *Kepler* is different to the noise level in TESS. The noise level for the *Kepler* satellite depends on the *Kepler* magnitude of the star, K_p . The noise can be calculated using

$$\frac{10^6}{c} \times \sqrt{c + 9.5 \times 10^5 \left(\frac{14}{K_p} \right)^5}, \quad (1)$$

where

$$c = 1.28 \times 10^{0.4(12-K_p)+7}, \quad (2)$$

from Chaplin et al. (2011).

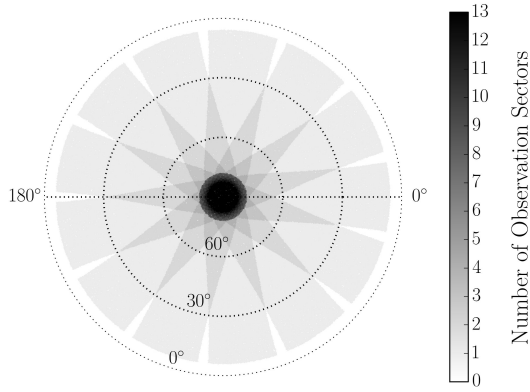


Figure 1. TESS field of view, centred around the ecliptic pole. Each strip will be observed for 27 days before the satellite rotates. Image taken from [Campante et al. \(2016\)](#).

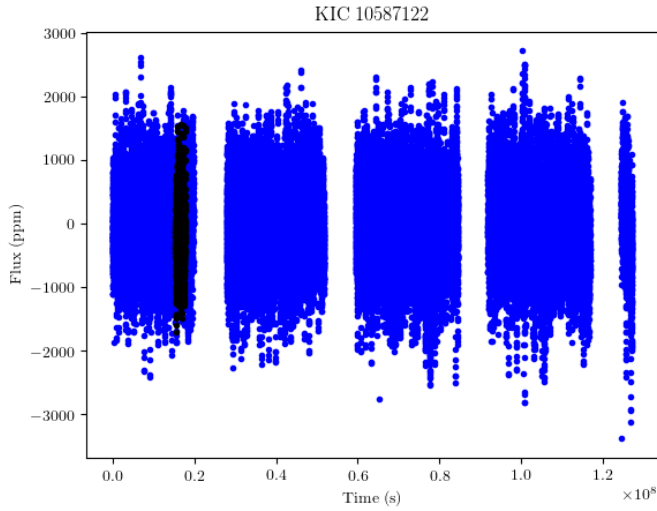


Figure 2. The 4-year long Power Spectra of KIC 10587122 is plotted in blue. Overplotted is the 27-day time segment with most coverage (the period with fewest gaps in the data). Reducing the length of observation this drastically will badly hamper mode detectability.

As well as subtracting this noise from the signal, instrumental noise from TESS needed to be added. This noise was estimated using the ‘calc noise’ IDL procedure (from William Chaplin, private communication), which depends on the I_c -band magnitude of the star and the number of pixels in the photometric aperture used when observing the star. This is given by

$$N_{\text{aper}} = 10 \times (n + 10), \quad (3)$$

where n is

$$n = 10^{-5.0} \times 10^{0.4 \times (20 - I_{\text{mag}})}. \quad (4)$$

These three adjustments - the length of observation, the band-pass, and the noise level - were performed in the time and frequency domains for comparison. The methods used are outlined in Figures 6 and 7. The resulting Power Spectra are compared in Figures 4 and 5. From these results, it was decided to add noise in the time domain, before transforming to frequency.

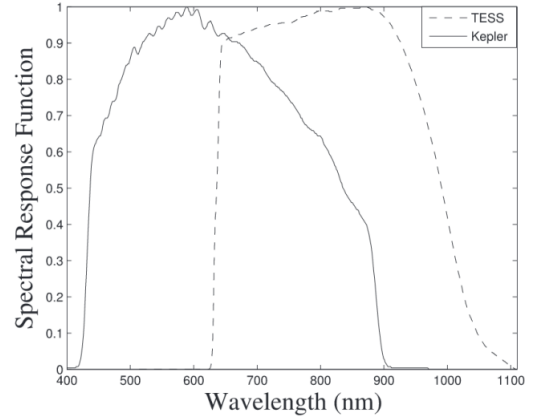


Figure 3. The bandpass of the *Kepler* and TESS missions. TESS will observe at longer (i.e redder) wavelengths than *Kepler*. This will reduce the amplitude of oscillations and granulation, whilst the white noise level will be unaffected.

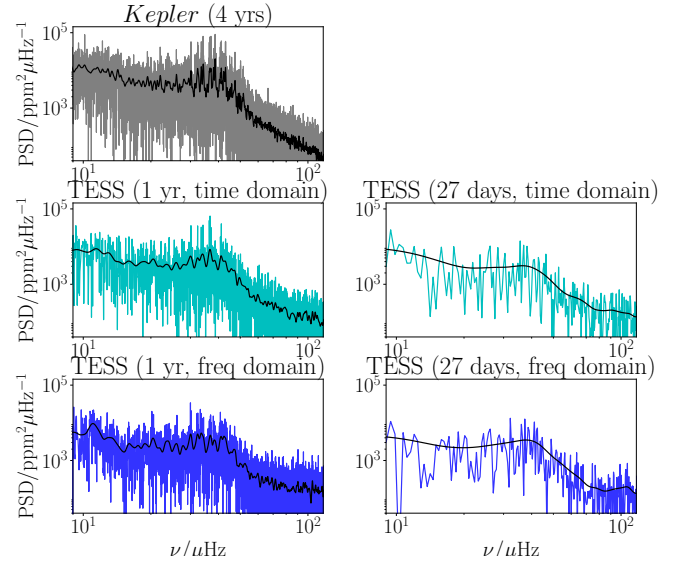


Figure 4. The Power spectra of KIC 10587122 is plotted five times. The original Power Spectra is plotted in grey. The power spectra after making the data look like TESS are plotted in blue. The data was transformed in the time domain (light blue) or frequency domain (dark blue). The left column shows 1 year of TESS observation (the maximum). The right column shows 27-days (the minimum). Based on this, the time series was chosen to transform the data in.

After noise was added to the stars and power spectra were made, a detection test was run on every fitted mode of every star.

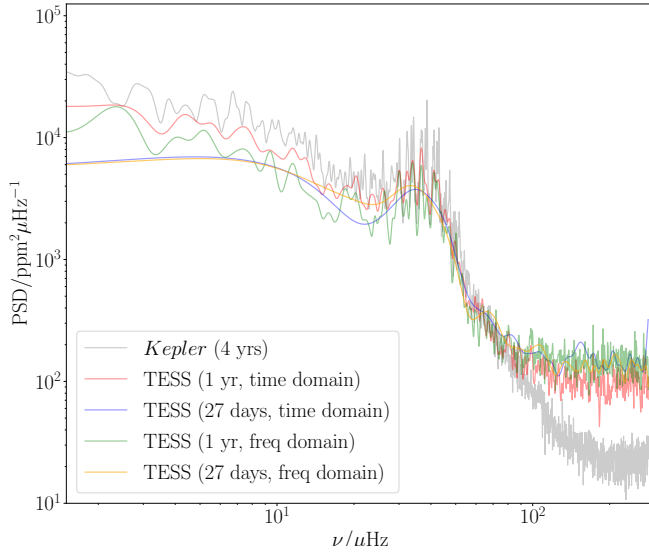


Figure 5. The Power Spectra of KIC 10587122. The original power spectra is in grey. The data was transformed into TESS observation and overplotted. The transformation was done in the time and frequency domains for comparison. Based on this, the time series was chosen to transform the data in.

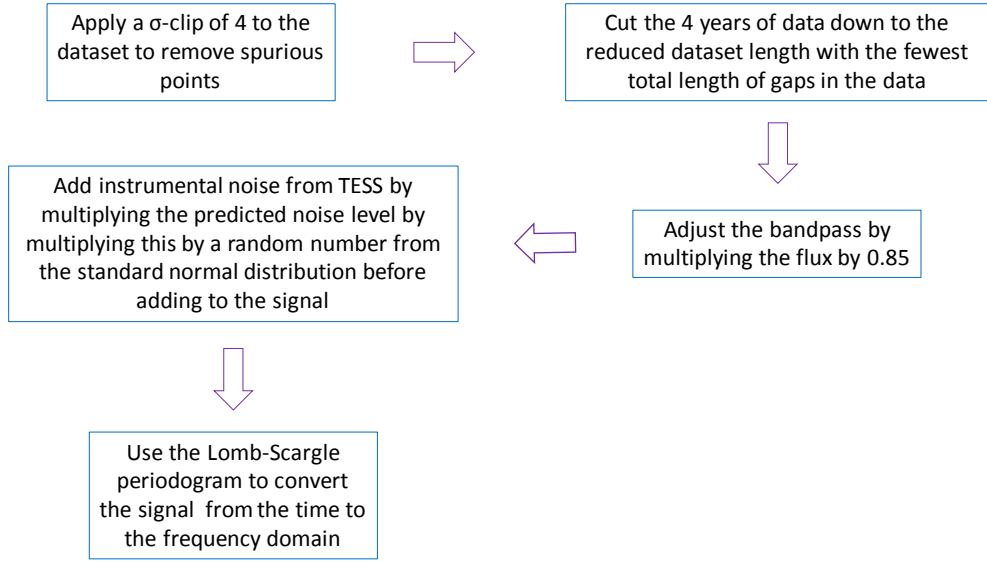


Figure 6. Flow chart of the method to convert the data from *Kepler* to TESS observations in the time domain.

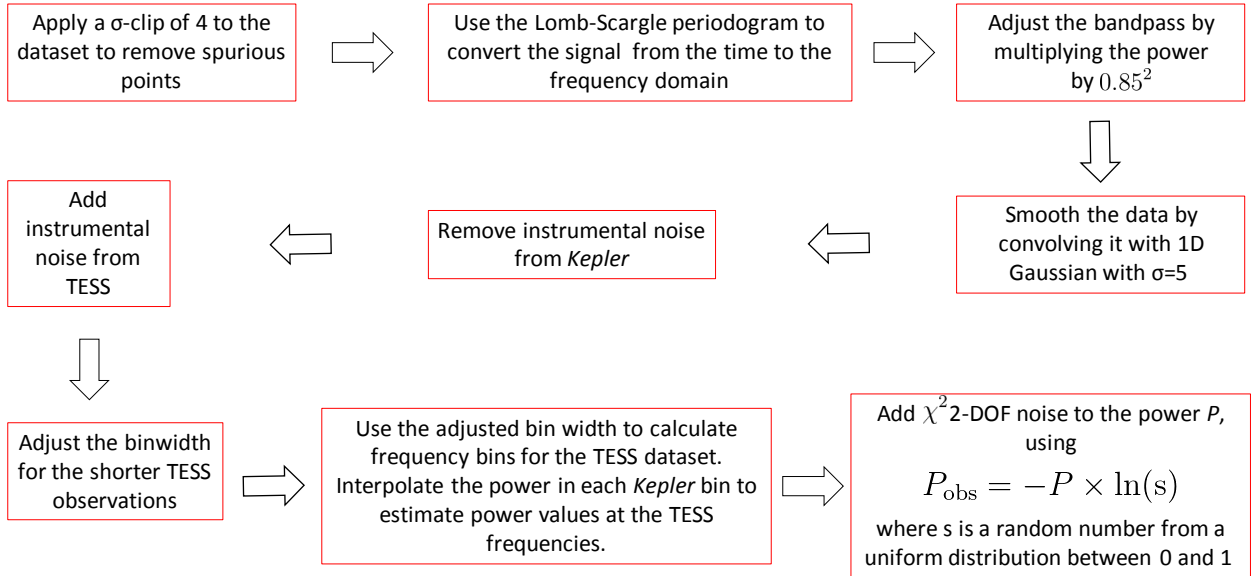


Figure 7. Flow chart of the method to convert the data from *Kepler* to TESS observations in the frequency domain.

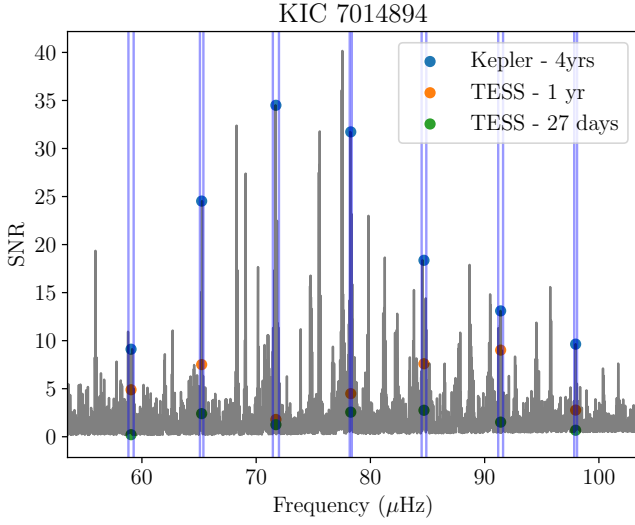


Figure 8. The power spectra of KIC 7014894 after background subtraction. The SNR value of every mode in the star was extracted from the SNR spectrum. The values for every mode in the original Kepler SNR are plotted in blue. The orange points are the SNR values after degrading the signal to 1 year of TESS observation. The green points are to 27 days.

3 DETECTION TEST

Section 2 described the method to transform the *Kepler* lightcurves into TESS observations. A detection test was then run on the stars, to determine which modes were still visible with observation by TESS, and which could not be recovered.

First, a moving median from Davies & Miglio (2016) was used. The width of the moving median is from the star’s envelope width. This predicted envelope width was calculated as

$$\Gamma_{\text{env}} = 0.66 * \nu_{\text{max}}^{0.88}, \quad (5)$$

from Mosser et al. (2012). The moving median was used to interpolate between frequencies in the power spectrum. This moving median is a good estimate of the background of the star. It was divided out of the power spectrum to get Signal-to-Noise spectrum,

$$\text{SNR} = P/B. \quad (6)$$

An example of this is shown in Figure 8.

Once the SNR spectrum for the star was recovered, the SNR values of every mode were extracted. To ensure the correct SNR value was used, a window was fitted around each peak-bagged mode frequency. The size of the window was given as the linewidth of the mode. The highest value in the window was taken as the SNR of the mode. Figure 9 is an example of this process for one star.

Once all mode SNR values for the star were calculated, a detection test was run on every mode (Chaplin et al. 2011), (Campante et al. 2016).

The probability P that the SNR lies above some threshold $\text{SNR}_{\text{thresh}}$ is

$$P(\text{SNR} \geq \text{SNR}_{\text{thresh}}) = p. \quad (7)$$

A false-alarm probability p of 1% was set; there is a 99% chance that the signal is due to solar-like oscillations, rather than noise. Equation 7 is solved for $\text{SNR}_{\text{thresh}}$ by substituting P with

$$P = \int_x^\infty \frac{e^{-x}}{\Gamma(N)} x^{N-1} dx. \quad (8)$$

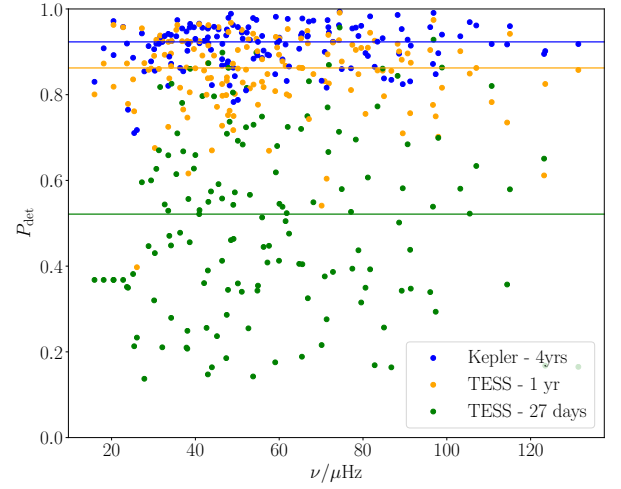


Figure 9. A plot showing the result of the detection test, after running on every mode in 20 stars. The results of the original power spectra are plotted in blue. The results of 1 year of TESS observation are in orange. 27 days of TESS observation is in green. At this short an observation, detecting individual modes will be extremely difficult.

$\Gamma(N)$ is the Gamma function. The lower bound of Equation 8 is set to $x = 1 + \text{SNR}_{\text{thresh}}$. N is the number of frequency bins. The noise in this bin is assumed to follow $\chi^2_{2n_{\text{bins}}}$ d.o.f statistics.

Once $\text{SNR}_{\text{thresh}}$ is found, Equation 8 is solved again. This time it is solved for P by setting $x = (1 + \text{SNR}_{\text{thresh}})/(1 + \text{SNR})$. Here, SNR is the observed Signal-to-noise Ratio calculated from Equation 6. This calculates the probability that the frequency spike was due to stochastic excitation in the convective envelope of the star.

This detection test was applied to every mode of every star in the 1000-star sample. Classification was then applied to this dataset. This is described in Section 4.

4 CLASSIFICATION

Section 2 describes how the lightcurves of every star were treated before a detection test was run on the modes in Section 3. After this, Classification was applied to the stars to separate them into a suitable target list, and a list of stars that are not suitable for observation with TESS.

This could be done without using Machine Learning, although it takes much longer. In the age where datasets from missions such as MAST and Gaia

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