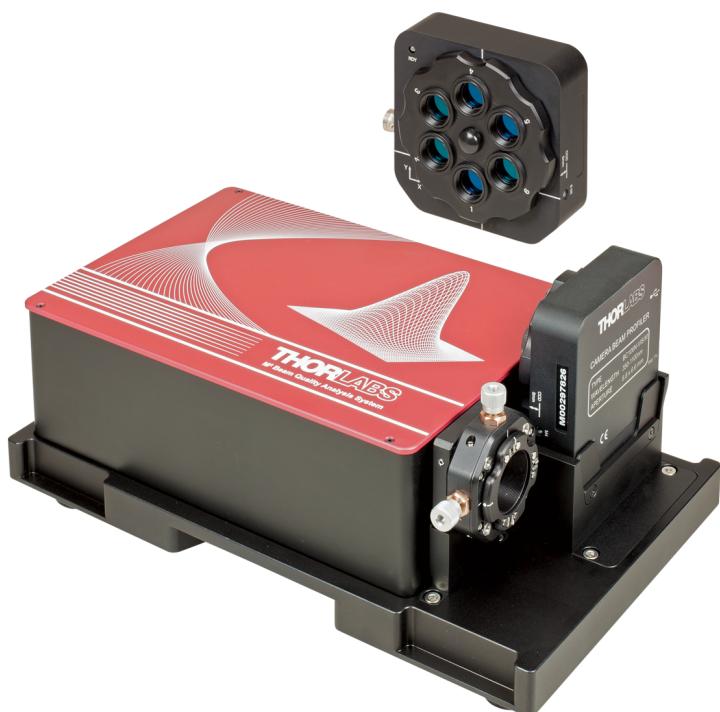

THORLABS

Thorlabs Beam Beam Analyzing Software

BC106N M2MS-BC106N Operation Manual



2019

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We aim to develop and produce the best solution for your application in the field of optical measurement technique. To help us to live up to your expectations and constantly improve our products permanently we need your ideas and suggestions. Therefore, please let us know about possible criticism or ideas. We and our international partners are looking forward to hearing from you.

Thorlabs GmbH

Warning

Sections marked by this symbol explain dangers that might result in personal injury or death. Always read the associated information carefully, before performing the indicated procedure.

Attention

Paragraphs preceded by this symbol explain hazards that could damage the instrument and the connected equipment or may cause loss of data.

Note

This manual also contains "NOTES" and "HINTS" written in this form.

Please read this advice carefully!

1 General Information

Thorlabs makes every effort to keep this manual as up to date as possible. For the latest version of the manual please visit www.thorlabs.com.

This section contains general information about the Beam Profiler's safety.

1.1 Safety

Attention

The safety of any system incorporating the equipment is the responsibility of the assembler of the system.

All statements regarding safety of operation and technical data in this instruction manual will only apply when the unit is operated correctly as it was designed for.

The Beam Profiler must not be operated in explosion endangered environments! To prevent the Beam Profiler from overheating, do not cover the instrument.

This precision device is only serviceable if properly packed into the complete original packaging including the plastic foam sleeves. If necessary, ask for replacement packaging. Refer servicing to qualified personnel!

Before applying power to the PC system used to operate the Beam Profiler, make sure that the protective conductor of the 3 conductor mains power cord is correctly connected to the protective earth contact of the socket outlet! Improper grounding can cause electric shock with damages to your health or even death!

The instrument must only be operated with a duly shielded and low resistance USB cable delivered by Thorlabs.

Only with written consent from Thorlabs may changes to single components be carried out or components not supplied by Thorlabs be used.

Be very careful when removing the glass protection of the sensor. Do no stick anything into the aperture, as this might damage the sensor! Prevent any kind of dust entering the entrance aperture!

Warning

The M2MS M² Measurement System comes with an alignment laser that is powered by a M2MS internal driver. Be careful when using this laser!



2 Getting Started

2.1 Ordering Codes and Accessories

Ordering Code	Short Description
BC106N-UV	CCD Camera Beam Profiler, 190 - 350 nm*
BC106N-VIS	CCD Camera Beam Profiler, 350 - 1100 nm

*Design range of Lumigen coating, sensitivity is given throughout 1100 nm but shows increased non-uniformity and noise compared to uncoated BC106N-VIS.

The wavelength range of supplied UV ND filters starts at 220 nm.

For beam quality (M^2) measurement, Thorlabs offers hardware extension sets and complete M^2 Measurement Systems:

Hardware Extension Sets:

Item Number	Description
M2MS	M2 Measurement System Extension Set
M2MS-AL	M2 Measurement System Extension Set, 250 - 600 nm (aluminum mirrors)

M^2 Measurement System with Camera Beam Profiler

The M2MS-BC106 comprises the M2MS Extension and a mounted BC106N Beam Profiler. The following models are available:

Item Number	Description
M2MS-BC106UV-AL	M2 Measurement System with BC106N-UV, 250 - 350 nm
M2MS-BC106UV-AL/M	M2 Measurement System with BC106N-UV, 250 - 350 nm, metric
M2MS-BC106VIS	M2 Measurement System with BC106N-VIS, 400 - 1100 nm
M2MS-BC106VIS/M	M2 Measurement System with BC106N-VIS, 400 - 1100 nm, metric

Please visit our homepage <http://www.thorlabs.com> for further information.

2.2 Unpacking

Inspect the packaging for damage. If the shipping container seems to be damaged, keep it until you have inspected the contents and you have inspected the instrument mechanically and electrically.

Verify that you have received the following items:

1. BC106N (/M) Beam Profiler

- 1 BC106N Beam Profiler instrument with mounted filter wheel containing
- 6 Attenuation filters, see section [Filter Wheel](#)¹⁹ in the full manual
- 6 Filter caps in front of filters
- 1 USB 2.0 Cable A to Mini B, length 3.0 m
- Quick Reference

If you have purchased an M² Meter Set M2MS-BC106N:

2. M2MS-BC106NUV-AL (/M)

- M2MS-BC106UV-AL (/M) Measurement System with Mounted BC106N-UV (/M) Camera Beam Profiler
- Power supply 100 to 240 V AC / 15 V 3 A DC
- Cable USB 2.0 A to Mini B, 3 m length
- Cable USB 2.0 A to Mini B, angled, 0.5 m length
- 1 pcs. 0.05" Hex Key
- M2MS Accessory Box UV, that includes:
 - 1 pcs. LA4158-UV Plano Convex Lens, f = 250 mm, UV AR coating
 - 1 pcs. LA1461-A Plano Convex Lens, f = 250 mm, AR coating 350 - 700 nm
 - 4 pcs. CL6 Rail clamps
 - 1 pcs. M2MS Adjustment laser
 - 1 pcs. Ball Driver 3 mm
 - 1 pcs. spare screw M4x10
- Quick Reference

3. M2MS-BC106NVIS (/M)

- M2MS-BC106VIS (/M) Measurement System with Mounted BC106N-VIS (/M) Camera Beam Profiler
- Power supply 100 to 240 V AC / 15 V 3 A DC
- Cable USB 2.0 A to Mini B, 3 m length
- Cable USB 2.0 A to Mini B, angled, 0.5 m length
- 1 pcs. 0.05" Hex Key
- M2MS Accessory Box VIS, that includes:
 - 1 pcs. LA1461-A Plano Convex Lens, f = 250 mm, AR coating 350 - 700 nm
 - 1 pcs. LA1461-B Plano Convex Lens, f = 250 mm, AR coating 650 - 1050 nm
 - 1 pcs. LA1461-C Plano Convex Lens, f = 250 mm, AR coating 1050 - 1700 nm
 - 1 pcs. LA5255-D Plano Convex Lens, f = 250 mm, AR coating 1650 - 3000 nm
 - 4 pcs. CL6 Rail clamps
 - 1 pcs. M2MS Adjustment laser
 - 1 pcs. Ball Driver 3 mm
 - 1 pcs. spare screw M4x10
- Quick Reference

2.3 Preparation

1. Install the Thorlabs Beam software on your computer as described in [Software Installation](#)^[10].
2. Connect the camera using the supplied USB cable to the PC as described in [Connection to the PC](#)^[16].
3. Remove the filter caps screwed on the attenuation filters.
4. Rotate the filter wheel to set optical ND filter with the highest loss (40 dB for BC106N-UV; 60 dB for BC106N-VIS) in front of the camera aperture which is behind the bottom attenuation filter. This prevents damage to the camera sensor.
5. Mount the Camera Beam Profiler instrument so that its optical aperture is exposed to the optical beam.
6. Switch on your light source but be sure to not exceed the maximum allowed optical power to the instrument. See [Power Ranges](#)^[175] for details

Attention

Please install the software prior to connecting the instrument to a PC via USB interface. Use only the supplied high speed (USB 2.0) cable, not full speed (USB 1.1) cables or thin profile cables with increased resistance, as this can cause transmission errors and improper instrument operation!

2.4 Requirements

Minimum Hardware and Software Requirements:

- Operating system: Windows 7® (32 or 64 Bit), Windows 8.1® (32 or 64 Bit) or Windows 10® (32 or 64 Bit)
- NI-VISA™ Runtime 15.0 or higher
- USB 2.0 high speed port
- Monitor resolution minimum 1024 x 758 pixel (\geq 16 bit color depth)
- Processor: Pentium 4 (min. 2.6 GHz), Intel or A64 3000+ AMD (min 3.0 GHz), 4.0 GB RAM
- OpenGL (specification GLX 1.3 up) compatible graphics adapter:
 - Radeon (X100 series \geq X850, X1000 series \geq X1600, HD series \geq 2400)
 - Geforce 7 series \geq 7600, 8 series \geq 8500, 9 series \geq 9600
 - Quadro FX series \geq FX770M

Recommended for Optimal Performance hardware features:

- USB 2.0 high speed port
- Processor: Intel Core 2 i5 or AMD Ryzen 5 (min. 3.0 GHz), 8.0 GB RAM
- OpenGL (specification GLX 1.3 up) compatible graphics adapter:
 - Radeon HD series \geq 7000
 - Geforce GTX series \geq 500

2.5 Installation

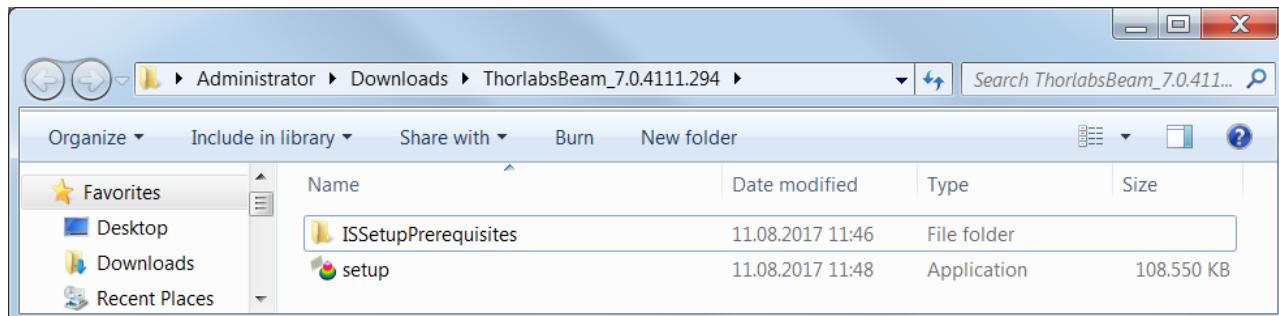
2.5.1 Software Installation

The "Thorlabs Beam" software V7.0 (or higher) can be downloaded from the Thorlabs website:

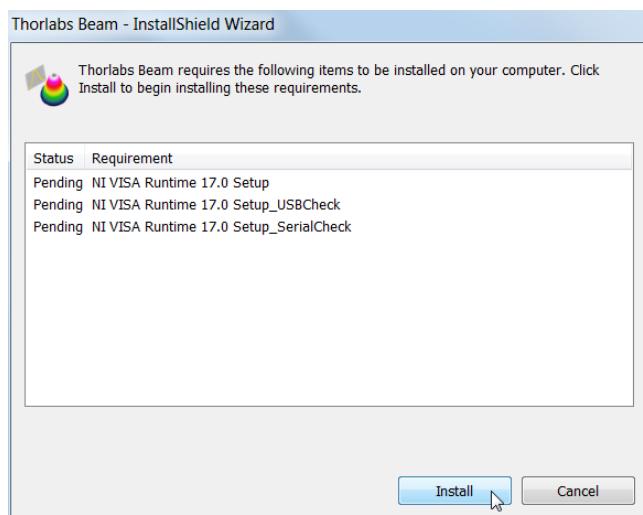
http://www.thorlabs.com/software_pages/ViewSoftwarePage.cfm?Code=Beam

Save the ZIP file to your computer and unpack this archive. The Install Shield Wizards starts by double-clicking the setup.exe, see below.

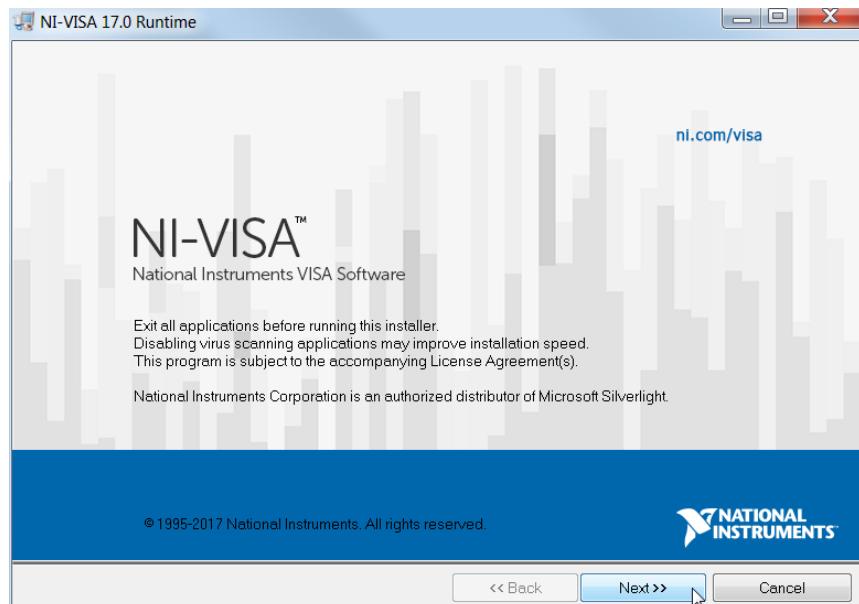
The installation contains 2 main parts - the NI-VISA™ Runtime V17.0 and the Beam Software itself, including also drivers and the manual. The following procedure describes the installation on a Windows 7® 64 bit operating system.



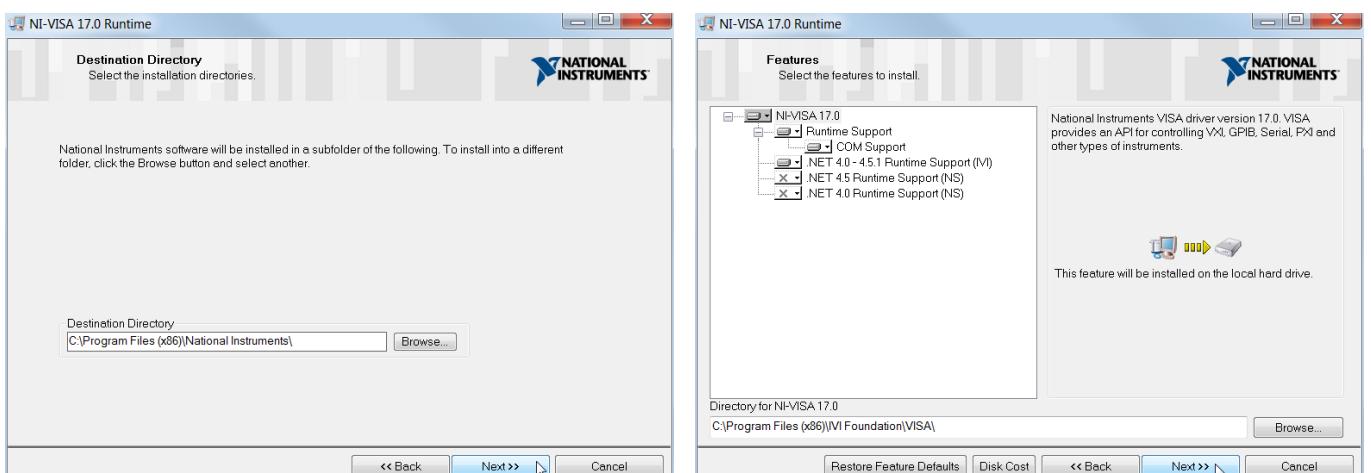
Click the "**setup.exe**". The installer will perform a check for installed NI-VISA™ Runtime Version. If NI-VISA™ is not installed to the target PC or the installed version is before 15.0, the installer recognizes that and requests the installation of NI software:



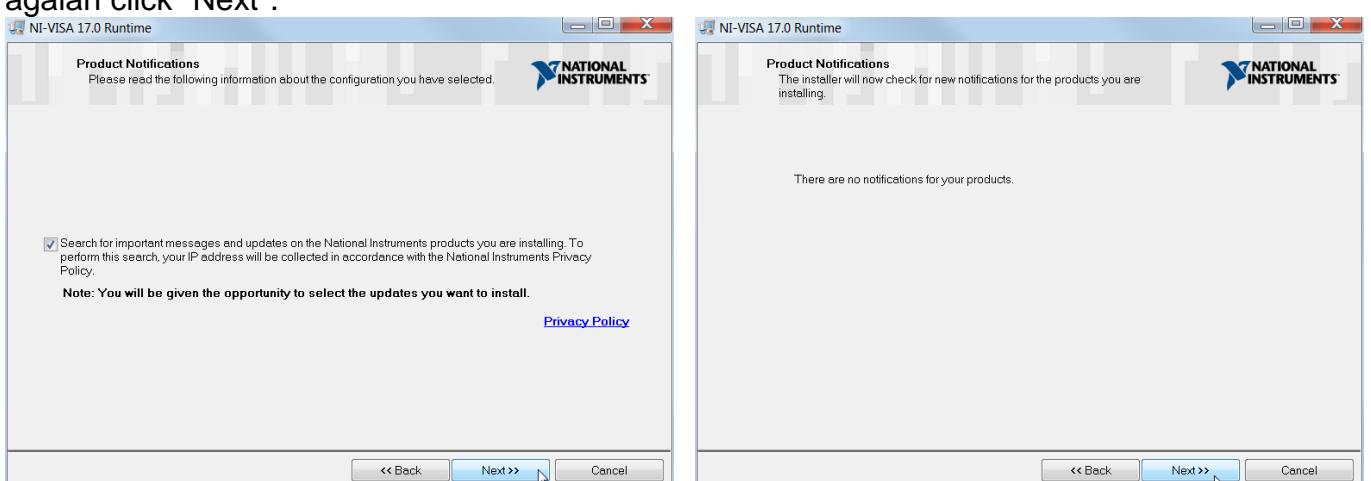
Click to **Install** and follow the instructions:



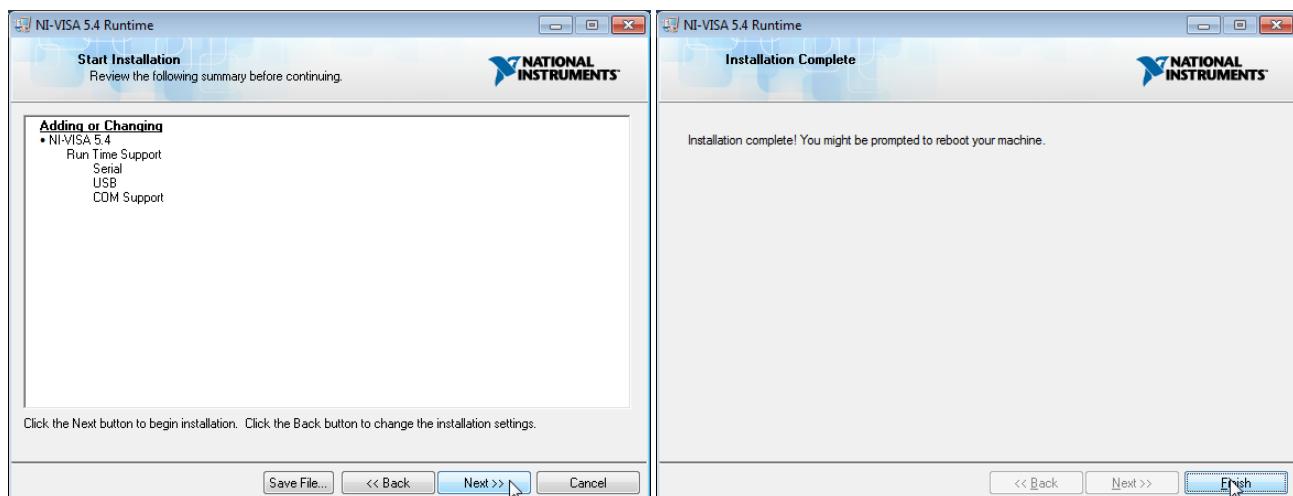
Click Next >> to continue.



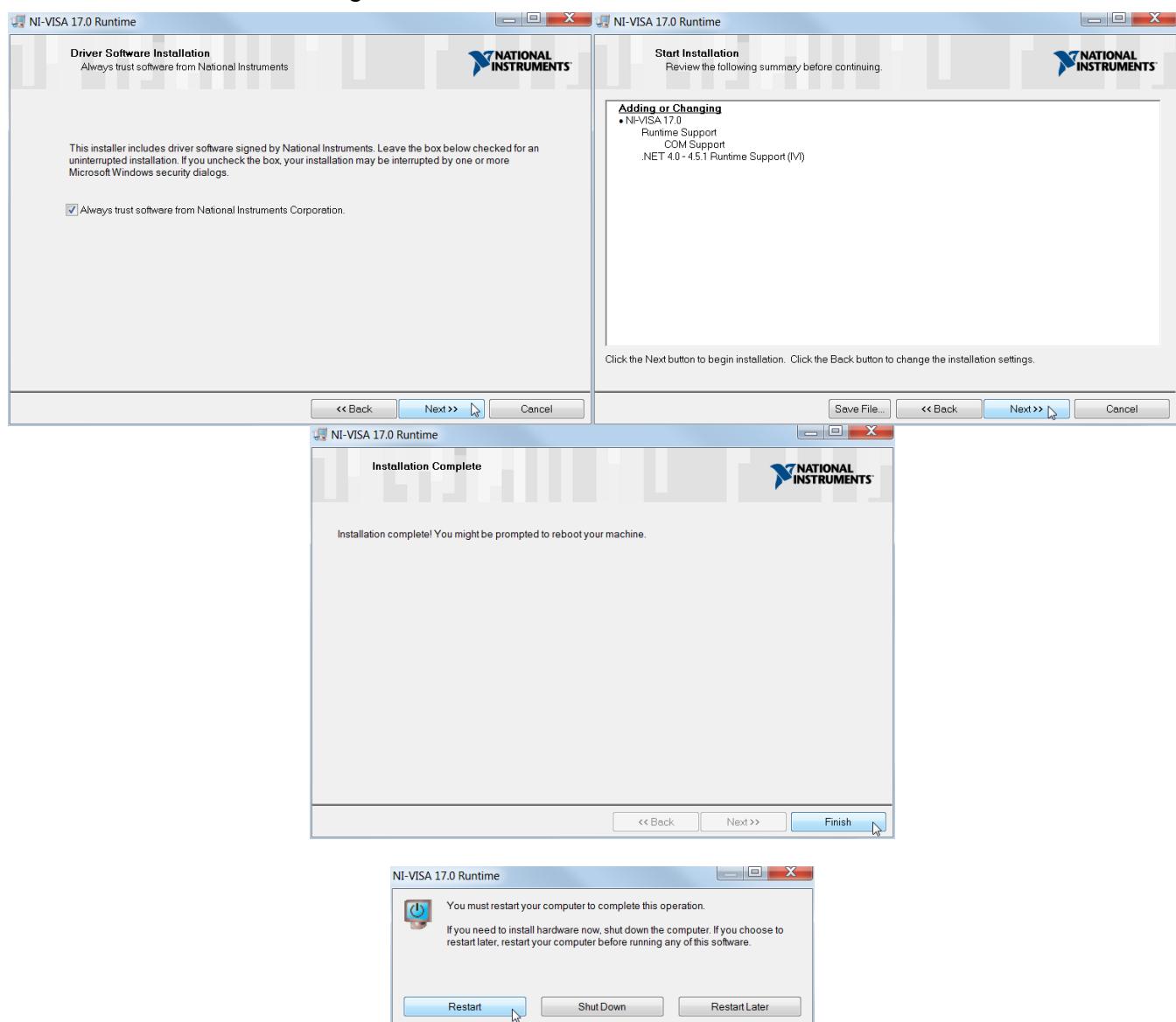
Mark the tick box "Search for important messages..." Click "Next". The following window opens, again click "Next".



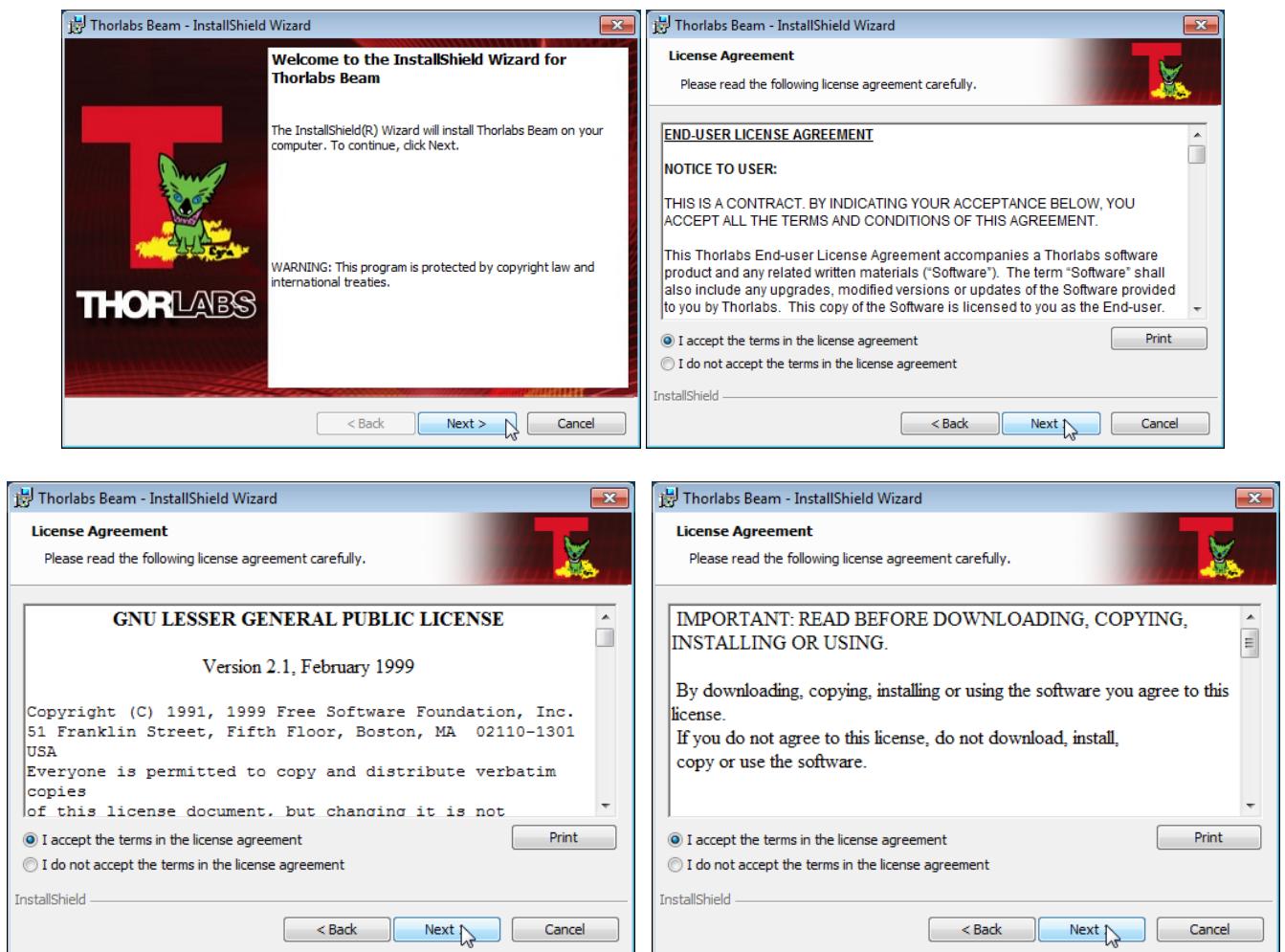
Then Next >> to continue installation and click "Finish".



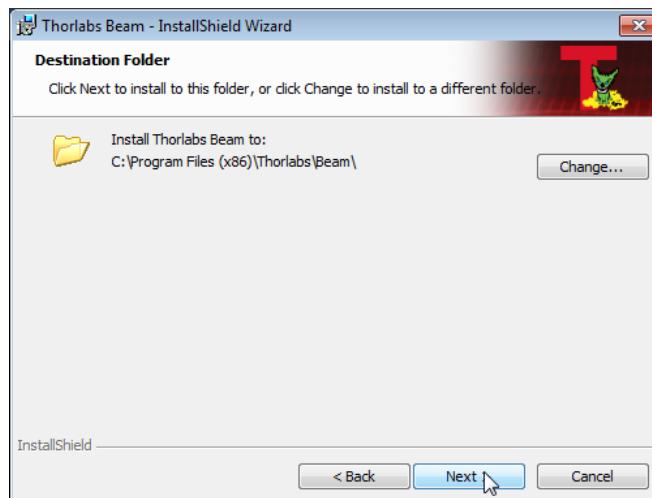
Click "Next" in both following screens and click "Finish" to finalize the installation.



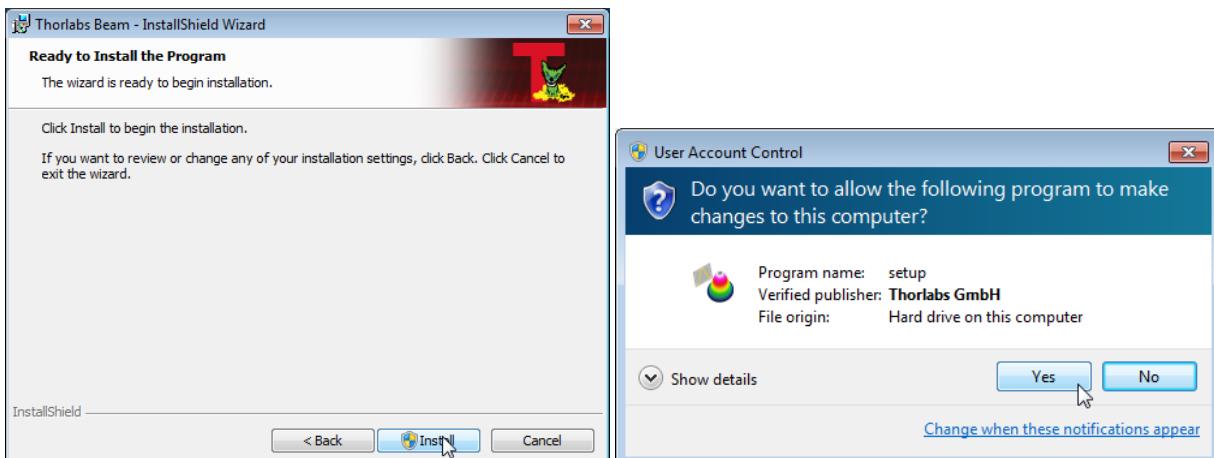
Please reboot the PC when this message appears. After restarting the PC, the installer continues to install the software. If not, please execute the "setup.exe" again.



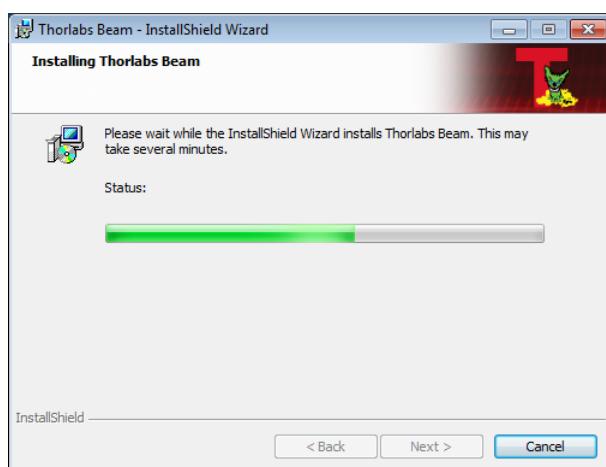
Please read this license agreements carefully, choose "I agree" and click 'Next'.



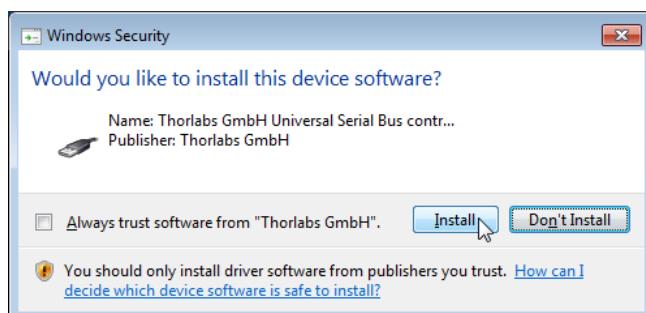
It is recommended to follow the recommended path, click "Next" and then "Install" to proceed.



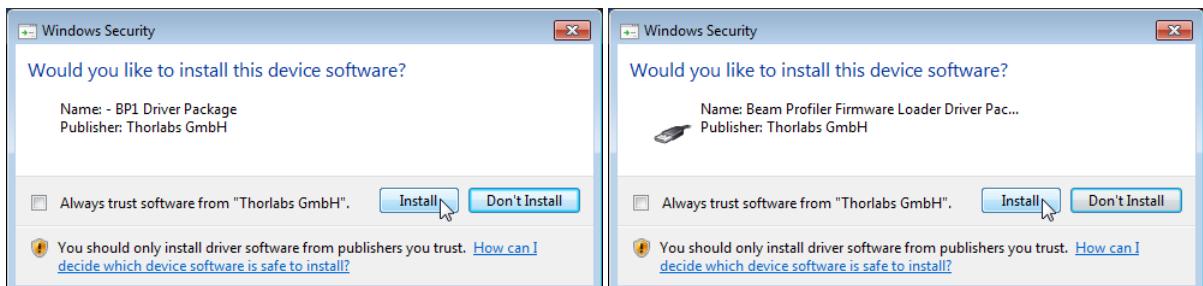
Click "Yes" to allow Beam Software installation.

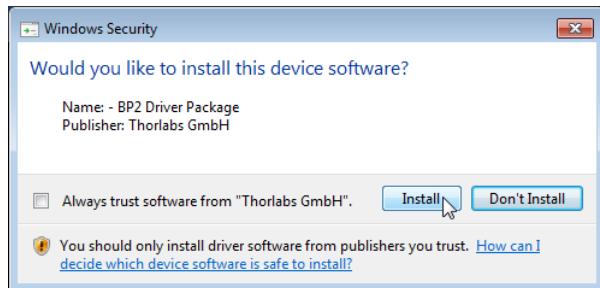


A new window appears, click "Next" to continue. Windows Security will ask your confirmation to install the Thorlabs USB driver.

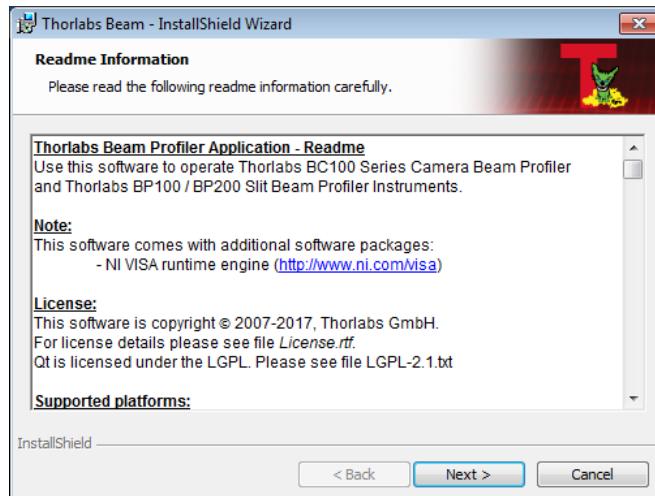


You may check the box "Always trust software from "Thorlabs GmbH", this will shorten the installation. However, if you do not want to do that, please click the "Install" button. You will be asked then to confirm the installation of further Thorlabs software components. Please proceed as described above.

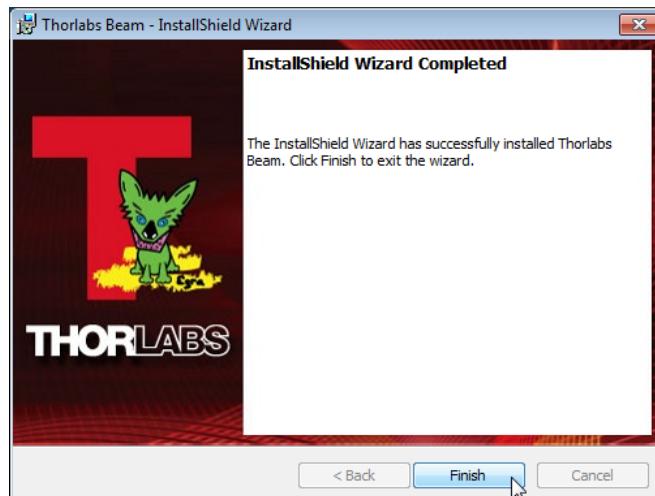




Now, all drivers are installed and the "Read Me" comes up:



Click "Next", then "Finish" to complete the software installation.



2.5.2 Connection to the PC

Connect the Beam Profiler to a USB 2.0 high speed port of your computer. Use only the cable that comes with the Beam Profiler or a cable qualified for high speed USB2.0 standard.

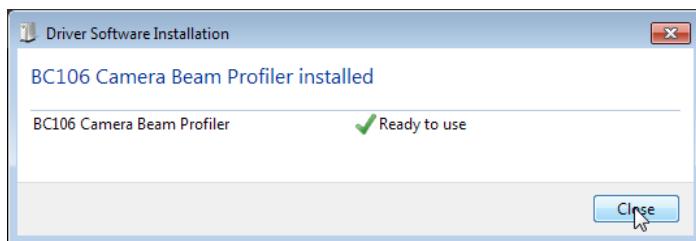
Attention

Do not use low speed USB cables as this can cause transmission errors and improper instrument operation!

Also, it is strongly recommended to use a PC USB port for connection. Avoid use of USB hubs as some models may not be able to deliver the specified max. current (500mA).

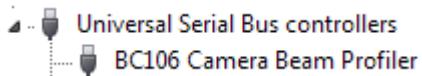
After connecting the instrument to the PC the operating system loads the appropriate USB drivers for the Beam Profiler instrument.

Once connected, an icon will appear in the task bar indicating that the driver installation is in progress. If you click on this icon, the window below appears:



If you want to verify the correct driver installation, check the presence of the instrument in the Device Manager: From the Start button select Control Panel to Device Manager.

The following entry under the USB-Devices group indicates that the Thorlabs Camera Beam Profiler device is properly installed.

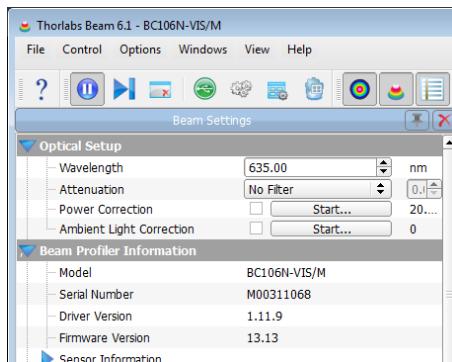


If you cannot see such an entry please check the [troubleshooting](#) section.

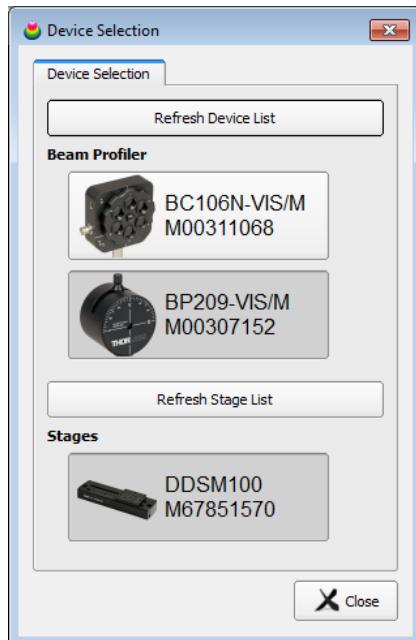
2.5.3 Start the Application

Click the "Programs" → "Thorlabs" → "Thorlabs Beam Application" entry, or simply click the appropriate icon added to your desktop.

When the application is started, the connected instrument is recognized, automatically connected and shown in the Beam Settings panel:



Usually the Beam software connects automatically to the instrument that has been connected first. If you have connected more than one Beam Profiler and want to use another than the connected device, click to the icon "Device Connection" and click the desired instrument:



Click on 'Refresh Device List' for an update in the case that you have very recently connected to or removed a Beam Profiler instrument from your PC. If an expected instrument is still missing check if the USB driver is properly installed (see chapter [Troubleshooting](#) [160]).

After selecting a Beam Profiler it will be connected and displayed in the Beam Settings panel, where all available settings and adjustments to the Beam Profiler can be made. See the [Settings Panel](#) [34] chapter for a detailed description.

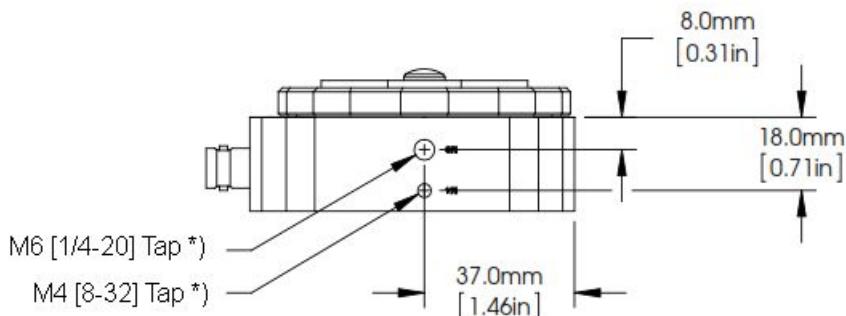
It is advisable to read the steps described in the [Measurement with the Beam Profiler](#) [80] chapter carefully in order to setup your Beam Profiler device properly.

When the Beam Profiler application is started the first time, three preselected windows are opened and arranged automatically. Otherwise, the arrangement of the last session (selected windows and its position) will be recovered. See the [Child Windows](#) [54] chapter for a detailed description of each window.

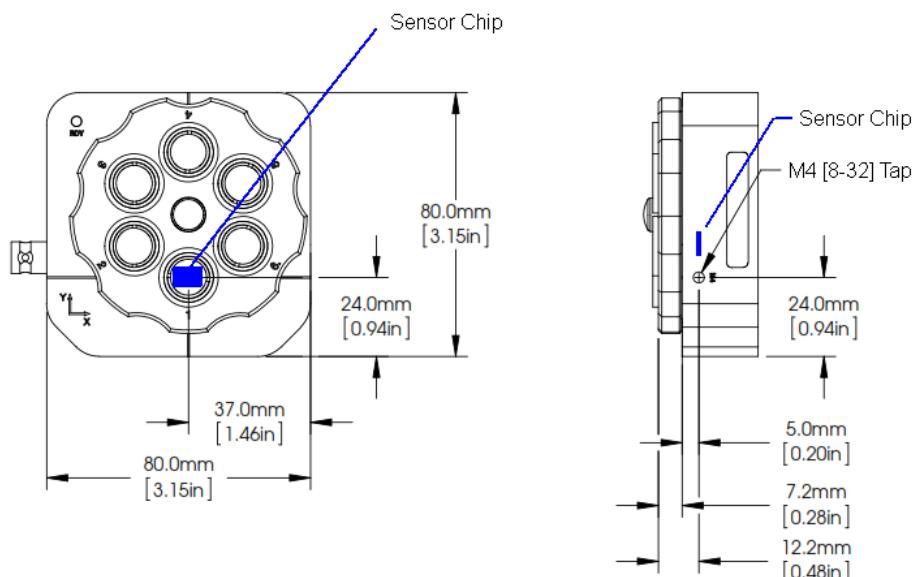
3 Operating Elements

3.1 Mounting and Sensor Position

On the bottom side of the Beam Profiler, a mounting plate is provided with one M6 hole (front) and one UNC8-32 hole (rear).



Mount the Beam Profiler on your optical board using Thorlabs post, post holder and base. The following drawing shows the sensor position with respect to the Beam Profiler housing edge:



The sensor is centered with respect to the holes in the mounting base, its depth measured from the front surface of the filter wheel is 12.2 mm [0.48 inches]; from the front of the BC106N housing - 5.0 mm [0.20 inches].

3.2 Filter Wheel

The Thorlabs BC106N Camera Beam Profiler is equipped with a filter wheel containing six different neutral density (ND) optical attenuation filters. The filter types and their nominal losses are model dependent. These filters are designed to quickly and easily adapt the light source power (which may exceed the saturation power of the camera) to a power level within the dynamic range of the CCD camera.



Filter wheel components:

Position	BC106N-UV	BC106N-VIS
1	1x 20 dB UV, reflective	1x 20 dB VIS, absorptive, A coated
2	1x 30 dB UV, reflective	1x 40 dB VIS, absorptive, A coated
3	1x 40 dB UV, reflective	1x 60 dB VIS, absorptive, A coated
4	1x 20 dB VIS, absorptive	1x 20 dB VIS, absorptive, B coated
5	1x 30 dB VIS, absorptive	1x 40 dB VIS, absorptive, B coated
6	1x 40 dB VIS, absorptive	1x 60 dB VIS, absorptive, B coated

The Model BC106N-VIS is equipped with six absorptive neutral density (ND) filters made from glass. There are 2 sets of filters - one set comes with A type anti-reflection coating (350 to 700 nm), the other - with B type AR coating (650 to 1050 nm)

Model BC106N-UV offers a wavelength range of 190 - 350 nm. Since the AR coated absorptive ND filters are applicable only for the wavelength range 220 - 350 nm, three reflective filters (fused silica) for the UV range from 190 - 350 nm are added.

See section [Wavelength Response](#)  for detailed data.

Attention

Be sure to have selected the appropriate ND filter corresponding to the actual operating wavelength! Beware of the reflected from reflective UV filters light!

Which attenuation to choose?

To adapt a light source with unknown power level to the Camera Beam Profiler it is highly recommended to use the automatic exposure control (see chapter [Camera Beam Profiler Parameters](#)  of the camera). In addition, it is advisable to start with the highest loss attenuation filter (40 or 60 dB) in order to prevent damage to the camera.

In case the Beam Profiler software displays an error "Power too high, camera saturated!" the light intensity exceeds the maximum detectable power of the BC106N Beam Profiler. In this case additional means for external beam attenuation are required.

In case the Beam Profiler software doesn't show a "Power too high" error it can be operated with this setting and the measurement results are reliable. However, in order to minimize beam distortions introduced by the ND filters, it is recommended to select the lowest possible attenuation.

Rotate the filter wheel a 30 degree revolution to bring the nearest lower attenuation filter in front of the camera aperture. If a "Power too high" error appears, rotate the filter wheel back to the previous filter as this will be the optimal filter to use. If no error appears, rotate the wheel further until the lowest attenuation filter is in use.

At low optical beam power the Beam Profiler camera can be operated without any attenuation filter in front of it. For this, remove the filter wheel - remove the black cap in the center, then remove the screw and detach the the filter wheel:



When using a high loss attenuation filter in conjunction with a low power light source the software will display a "Power too low" warning. This means the source is attenuated too much so that the camera's gain and exposure regulation is not able to achieve an evaluable signal level. In this case reduce the optical attenuation down to the lowest available filter loss (10 dB) or remove the filter wheel completely.

Attention

For proper power measurement results, the actually chosen ND filter loss (in dB) must be entered into the Beam Profiler software! See section [Device Settings](#) [40].

For correct beam profiling results it is highly recommended to shield ambient light from entering the Beam Profiler aperture. Using attenuation filters provided within the filter wheel will attenuate ambient light but will also absorb power of the light source by the same amount so that the ratio between both remains unchanged.

3.3 CCD Sensor Protective Glass Window

The CCD sensor is protected by a glass window. Depending on the BC106N type, this window is either uncoated, A or B coated:

Camera Beam Profiler	Coating	Color Code (frame)
BC106N-UV (/M)	none (Fused Silica)	white
BC106N-VIS (/M)	A (350 to 700 nm)	grey
	B (650 to 1050 nm)	black

The BC106N-VIS (/M) comes with A coated window mounted while the B coated window is attached in a separate box.

In particular cases, for example in order to avoid interference effects caused by the window, or if often measuring at different wavelengths (e.g., 532 nm and 1064 nm), it might be advantageous to remove the protection glass window in front of the sensor - just unscrew it from the housing:



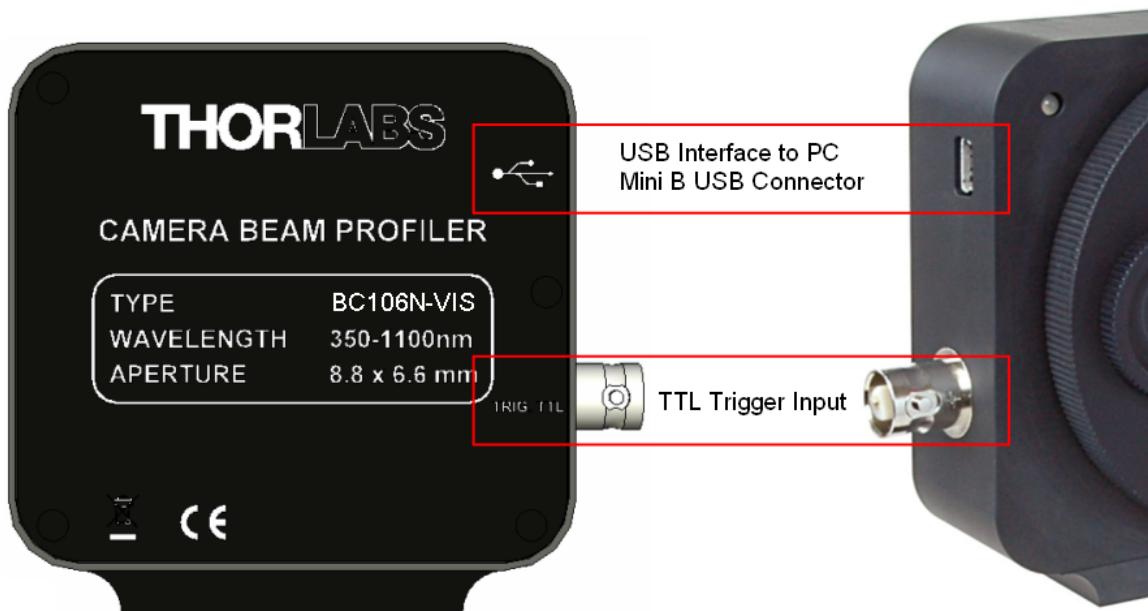
Attention

Be very careful when operating the Beam Profiler without a protecting glass window!
When the protective window in front of CCD camera sensor is removed, the sensor is extremely vulnerable! Dust and other contamination must be prevented from entering the Beam Profiler aperture. See section [Cleaning](#) [158] for detailed recommendations.

3.4 Connectors

The BC106N Camera Beam Profiler provides two connectors on the left side of the instrument body.

- Mini B USB connector, labeled with the USB symbol  For connection to your PC, see chapter [Connection to the PC](#)^[16]
- TTL Trigger input, labeled **TRIG TTL**
For synchronizing a [Pulsed Laser Sources](#)^[92] to the Beam Profiler, see [Trigger Input](#)^[23] for specifications.



3.5 Trigger Input

An TTL trigger input is provided for synchronizing the Camera Beam Profiler's global shutter with [Pulsed Laser Sources](#)⁹². The appropriate BNC connector is located on the left side of the instrument body, see [Connectors](#)²².

TTL Trigger input parameters:

Parameter	Value
Save Static Voltage Level	-0.5V ≤ U ≤ 6.5V
Max. LO Level	1.5 V
Min. HI Level	3.5 V
Input Impedance	> 100 kW
Min. Pulse Width	10 µs
Min. Slew Rate	5 ns/V
Applicable Safety Standards	IEC 61000-4-2 (ESD 15kV air, 8kV contact) IEC 61000-4-5 (Lightning 12A 8/20µs) IEC 61000-4-4 (EFT 40A 5/50ns)

Attention

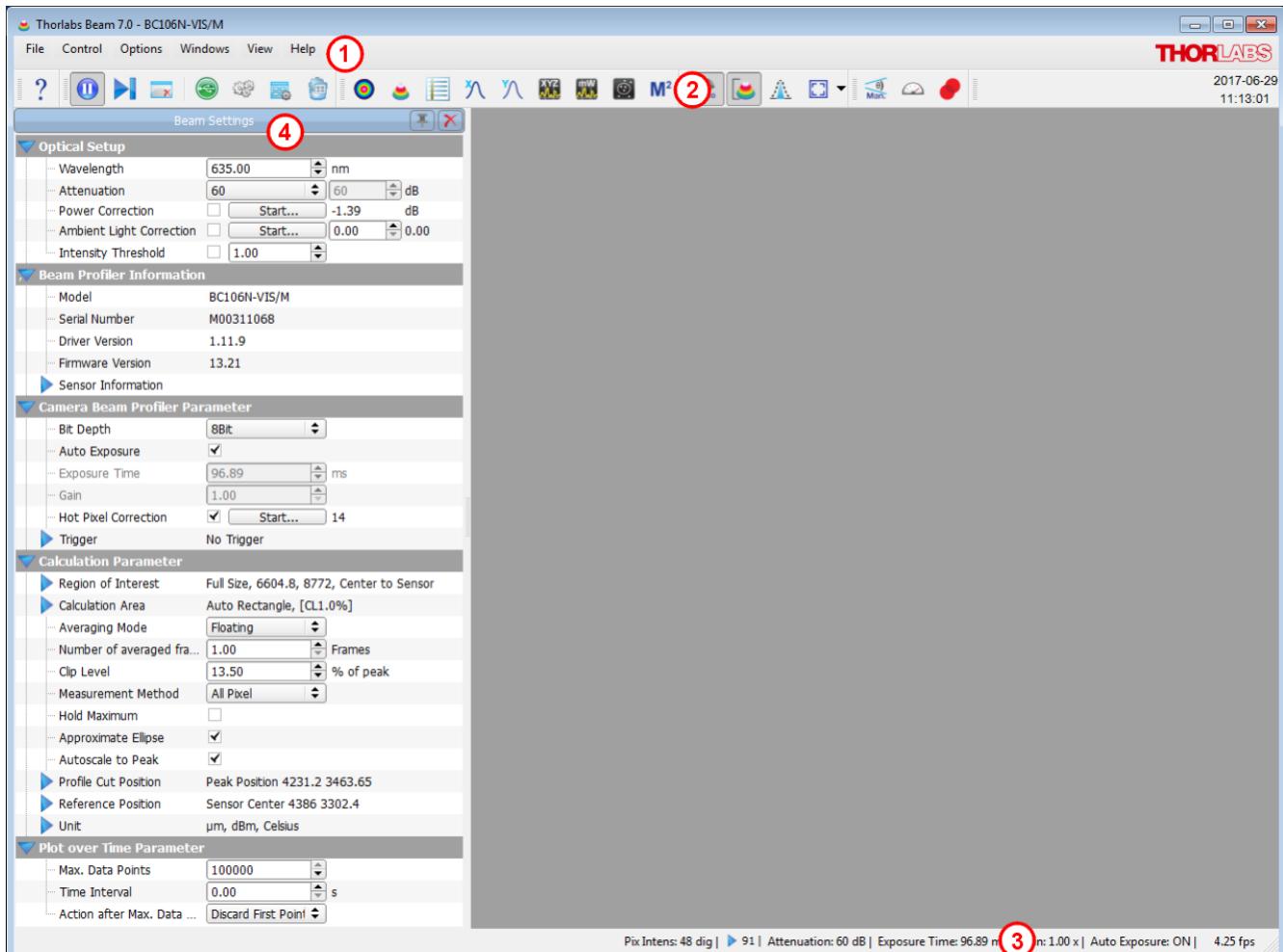
Be sure to enter only a TTL compatible signal to the BNC jack not exceeding the range from -0.5 V to +6.5 V). Higher or lower voltages may damage the Beam Profiler input!

Note

Use only shielded coaxial cables for connecting the trigger source. Do not connect a trigger cable without a signal source because it may capture disturbing pulses that may trigger the shutter.

4 The Graphics User Interface (GUI)

The main window consists of a menu bar (1), a tool bar (2), a status bar (3) and common frame for displaying several child windows. When starting the application, an additional window is displayed within the main window - the [Beam Settings](#)^[34] (4) panel. This panel can be unpinned from the main window and moved to a different display location, e.g., to a second monitor.



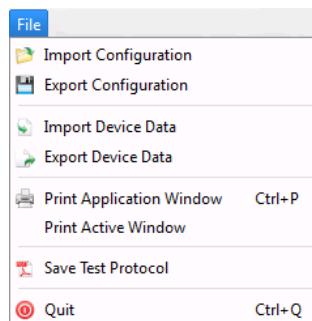
4.1 Menu Bar

All user activities can be done using the menu bar items

File Control Options Windows View Help

4.1.1 File Menu

These menu entries deal with files or printing.



The entries in the first block, **Import** and **Export Configuration**, are related to XML files which contain information about the chosen Beam Profiler device and its settings, file export parameters and application settings. In order to copy the GUI appearance and Beam Profiler settings to another PC you need to save the configuration file, copy it and load it on the target system.

The second part allows to import and export data originally retrieved from the Beam Profiler:

Export

- RAW format: This is a product specific bitmap with additional information, here pixel pitch (distance between 2 pixels) and exposure time.
- BMP format: This is the standard, uncompressed bitmap image retrieved from the camera.
- CSV format: Intensity values are saved to a text matrix. This matrix saves values according to selected precision mode (8 or 12bit - see [Camera Beam Profiler Parameter](#)^[40]). The 1st value in the 1st line represents the intensity of the left upper pixel in the 2D projection.
- TIFF (8bit), PNG and JPG formats: Standard picture formats for easy integrating of measurement results into external documents.
- A sequential saving is available as well. Details please see in section [Calculation Results](#)^[65]

Import

The import is limited to Device Data allowing reconstruction of the original measurement result with the Beam software.

- RAW format: Along with the bitmap, saved from the camera, pixel pitch and exposure time are used for calculation, so the imported beam profile will reproduce the true size and also the optical power.
- BMP format: Only the bitmap will be shown. The dimensions in X and Y direction are not the original ones (pixel pitch will be considered as 1)

The third block prints the currently displayed content of the child windows.

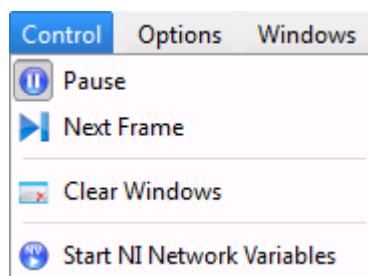
With the **Print Application Window** a screenshot of the Beam Profiler application is printed.

The **Print Active Window** entry prints the current active child window of the Beam Profiler application. This function gives you the opportunity to print a specific child window.

The **Save Test Protocol** opens a dialog window, where individual data can be entered. Click "Save" and then "Close" to save a test report with the calculation results and the current projection image to the indicated location. If the 3D Profile window is opened, a screenshot of the 3D Profile is also included in the test report.

See some detailed examples for data export in the [Save Measurement Results](#)⁸⁵ chapter.

4.1.2 Control Menu



Use the two first menu entries to start and pause the continuous operation of the Beam Profiler device including retrieving measurement data, performing calculations and displaying graphs and numerical results to the output windows. 'Next Frame' starts a single measurement and returns to pause state.

When the GUI is started or the active Beam Profiler instrument is changed, the application will start continuous operation automatically. Pausing the consecutive operation is advantageous for detailed analysis of a single image. The paused Beam Profiler can be restarted at any time.

The "Clear Windows" function resets the content of all windows, including child windows. The window content will be filled with the next measurement result received from the instrument. This function may be useful in combination with a trigger mode while waiting for the next image or for a synchronous restart of all plots and time-based measurements.

Note

The measurement of all beam parameters and the accumulation of calculated data is started automatically with the software start. "Clear Windows" deletes all accumulated data and restarts the measurement.

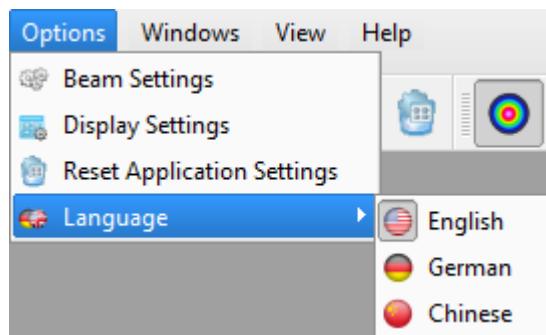
Start NI Network Variables

Note

In order to use this command, you need to have installed additional National Instruments® software (Distributed System Manager, NI CVI Runtime Engine). This feature is a data interface for handing over to an external program environment the parameters:

- saturation
- total power
- centroid positions X and Y
- 4-sigma width X and Y

4.1.3 Options Menu



These entries allow changing the device (Beam Profiler) and application (GUI) specific settings and let you choose a language.

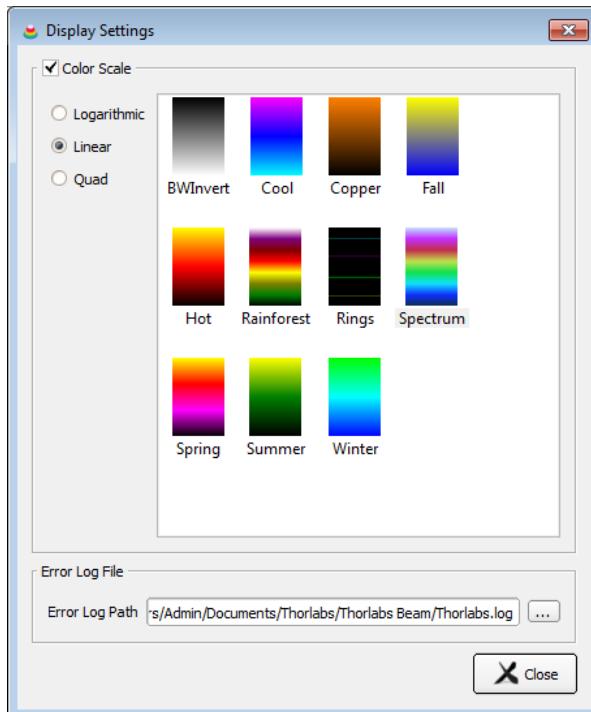
Beam Settings

The *Beam Settings* panel contains all important information about the optical settings, the properties of the active Beam Profiler and a summary of the calculated beam parameters. Please see the detailed description of this panel in the section [Beam Settings](#)³⁴.



Display Settings Panel

Here, the different styles for **2D Projection** and **3D Profile** are listed for selection.



There are 3 different color scale types available:

- Logarithmic is recommended to view lower intensity values with a good resolution
- Linear
- Quad offers a better resolution for higher intensity values.

User-Configured Color Scales

If a certain color scale is required it is possible to create a custom color scale which can be loaded automatically by starting the application. To do so a few things have to be considered.

When starting the application loads valid *.lut files from the folder

...\\My Documents\\Thorlabs\\Thorlabs Beam\\LUT

A valid *.lut file must fulfill the following criteria:

- Ordinary text file with 9 columns and 256 rows
- Values must be tab-separated
- The first three columns have 256 entries
- The last six columns have only 129
- Each value represents a 8 bit intensity (0- 255) of R(ed), G(reen) and B(lue), respectively.

The first three columns represent the linear scale of a user-made color scale, the next three columns the logarithmic scale and the last three columns the quad scale.

Such a color scale could look like this (The first two rows are not part of the *.lut file; they are shown here only for illustration):

Linear Scale			Logarithmic Scale			Quad Scale		
R	G	B	R	G	B	R	G	B
0	255	0	0	255	0	0	255	0
1	255	0	1	255	0	3	255	0
2	255	0	2	255	0	10	255	0
...
127	255	0	240	255	0	254	255	0
128	255	0	255	255	0	255	255	0
129	255	0						
...						
254	255	0						
255	255	0						

"..." stands for the intermediary values.



Reset Application Settings to Defaults

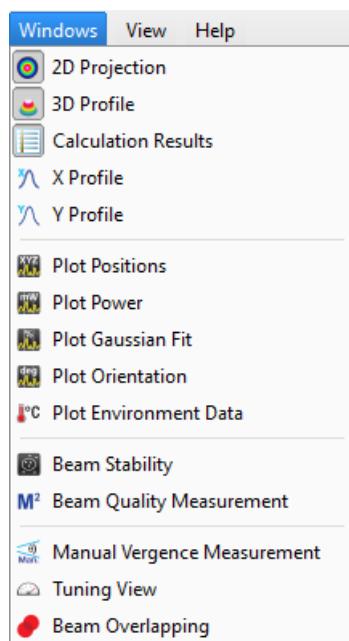
This button resets all BEAM application settings to defaults:

Application Setting	Default Value	Explanation
Intensity Threshold	Disabled	
Auto Exposure	Enabled	Exposure time set to automatic
Trigger Mode	No Trigger	Instrument set to continuous data acquisition
Region of Interest	Full Size	ROI is set to full sensor size.
Calculation Area Preset	Auto Rectangle	Software determines a rectangular area in which the power level is above the clip level.
Calculation Area Clip Level	1.0 %	For defining the Calculation Area in automatic mode, the lower intensities limit is set to 1% of the peak intensity to clip noise.
Averaging Mode	None	No averaging
Clip Level	13.50 %	The clip level for calculating the ellipse and beam width is set to 13.5% of the difference between the baseline and the peak intensity.
Measurement Method	All Pixels	All pixels are used for calculation, no slit emulation.
Hold Maximum	Disabled	
Approximate Ellipse	Enabled	The ellipse is approximated to get a smooth surrounding.
Autoscale to Peak	Enabled	The diagrams that show intensities, are scaled to the peak intensity.
Profile Cut Position	Peak Position	The X and Y profiles are taken from the row and column where the peak is located.
Reference Position	Sensor Center	Reference position is set to the sensor center. Centroid and peak positions are calculated relative to the reference position.
Position Unit	µm	All position units are displayed in µm.
Power Unit	mW	All power units are displayed in mW.
Plot Method	Latest Data	After reaching the max. number of data to be plotted, with the next data acquisition the first data set will be discarded and the the most recent set will be added.
Plot Interval	Every Meas.	For every measurement, the data are plotted
Max. Data Points	100000	The maximum number of data to be plotted
Velocity	200 mm/s	Translation speed of the stage

Language

The language of the application can be selected.

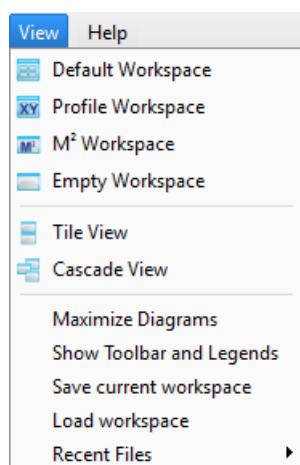
4.1.4 Windows Menu



When the GUI is started the first time, the Default Workspace is opened by default. To close and open the windows, toggle the corresponding entry in the windows menu.

An open child window can also be closed by pressing the \times in the upper right corner of the child window.

4.1.5 View Menu



From this menu entry, a number of pre-configured child window arrangements ("workspaces") can be quickly selected:

- Default: Settings panel, Numeric results, 2D projection, 3D profile
- Profile: 2D projection, 3D profile, numeric results, X and Y profiles
- M²: Beam Quality Measurement, X and Y profiles
- Empty workspace

Further, the active child windows can be arranged, tiled, and cascaded.

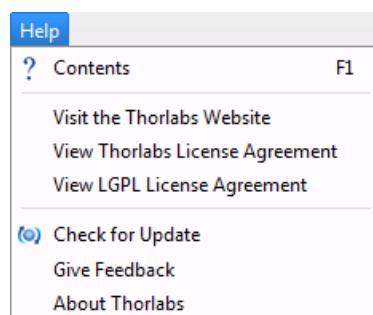
'Maximize Diagrams' turns off the side and top toolbars in all child windows simultaneously, **'Show Toolbar and Legends'** turns them on again.

'Save Current / Load Workspace' saves your Beam software GUI appearance to a ini-file that can be loaded at any time.

'Recent Files' lists recently used workspace files so that you can quickly load often used workspaces.

4.1.6 Help Menu

Click 'Contents', the first entry within the help menu, or press the 'F1' key on the keyboard to open the online help file, which contains all information included in this manual.



With a click on the link *Visit the Thorlabs Website* this website is opened in the browser window.

View Thorlabs (LPGL) License Agreement will open the license files of the installer package.

Check for Update searches for available software updates.

Give Feedback opens a dialog, where you can post your feedback about BEAM software and send it by email to Thorlabs Tech Support.

About Thorlabs displays device information and software versions details:



If you have trouble with the software, please submit the version of the application to Thorlabs. This can help in resolving your problem.

4.2 Tool Bar

For the most important menu entries there are also symbols provided in the tool bar.

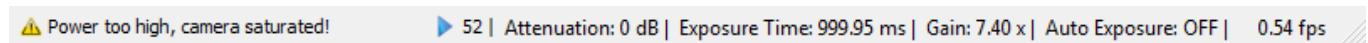


Clicking on a toolbar symbol will have the same effect as clicking on the original menu entry. When moving the mouse over the icons, a tool tip will be displayed.

In the table below the toolbar icons are explained.

- | | |
|--|---|
| | Open the online help file |
| | Pause and start the continuous device operation |
| | Take a single measurement |
| | Clear the content of each window |
| | Restore Beam Settings panel (if unpinned or closed) |
| | Open the Device Connection dialog |
| | Open the Display Settings panel |
| | Reset application settings to defaults |
| | Open child window 2D Projection |
| | Open child window 3D Profile |
| | Open child window Calculation Results |
| | Open child window X Profile |
| | Open child window Y Profile |
| | Open child window Plot Position |
| | Open child window Plot Power |
| | Open child window Beam Stability |
| | Open child window Beam Quality (M²) |
| | Toggle auto exposure on/off |
| | Toggle auto scale to peak on/off |
| | Toggle max hold on/off |
| | Change ROI (drop down) |
| | Open child window Manual Vergence Measurement |
| | Open child window Tuning View |
| | Open child window Beam Overlapping |

4.3 Status Bar



The status bar displays important status information about the Camera Beam Profiler concerning

- Errors and warnings, see chapter [Warnings and Errors](#).
- Plot Data Point Status, see section [Plots](#).
- Attenuation setting (by [Filter Wheel](#) or external attenuator).
- Camera settings like Exposure Time and Gain.
- Current refresh rate of the application in frames per seconds (fps).
- Alternatively, if stored Device Data are loaded, the location of the file is displayed.

4.4 Save Settings

The actual settings of the GUI including configurations of the graphical displays and the instrument setup are automatically saved when exiting the program. When starting the Beam software again, the most recent settings are automatically loaded.

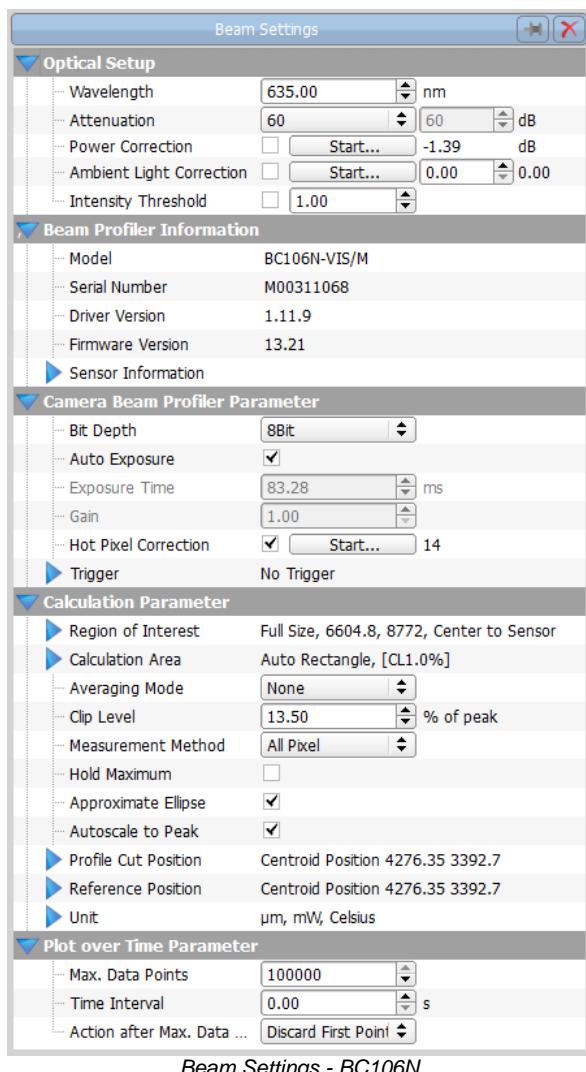
Exception: Actual zoom settings of 3D graphs, the rotation and translations are not stored. This is to see the full aperture range and full amplitude range on every start of the GUI.

Note

The stop state of the previous measurement will be ignored at a new start of the Beam software because it always starts in continuous mode.

4.5 Beam Settings

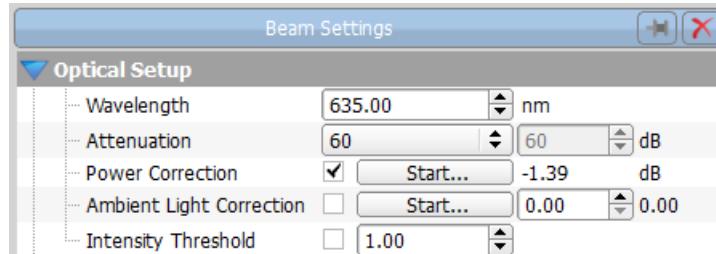
The **Beam Settings** panel is a very convenient visualization of all important information and settings that can be made to the instrument and to the calculation parameters. For a better visibility, the Beam Settings topics are arranged in expandable group boxes that allow to show or hide topics. Further, the Beam Settings panel is the only child window that can be detached: When starting the application, this panel arranged by default within the main window. Drag and drop it to any convenient location within or outside the GUI main window, e.g., to a second PC monitor. When detached, the **Pin** icon in the upper right corner changes from to . Click to this icon to bring the panel back into the GUI frame. The panel view can be customized easily by expanding or hiding topics.



Beam Settings - BC106N

Please read this section carefully and follow the setup instructions in order maximize the accuracy of your measurements.

4.5.1 Optical Setup



This part of the **Beam Settings** panel

- Sets the [operating wavelength](#)³⁵,
- Sets the [attenuation](#)³⁶ in accordance with the used ND Filter,
- Executes a [power correction](#)³⁶,
- Executes [ambient light correction](#)³⁷
- Sets the [intensity threshold](#)³⁸.

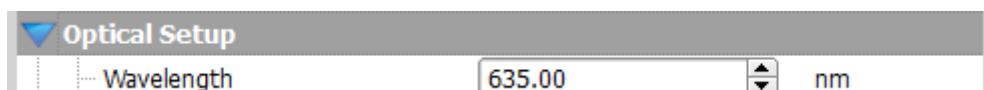
Initial Settings

When this camera is connected for the first time, the following default values are set:

Parameter	Default Value
Wavelength	635nm
Attenuation [dB]	No Filter (0 dB)
Power Correction	OFF, factory calibration active
Ambient Light Correction	OFF

4.5.1.1 Wavelength

Enter the operating wavelength in nm as a precondition for proper measurement of the Total Power. It enables consideration of the known response curve stored within the Beam Profiler instrument. The correct wavelength is important for accurate Beam Quality (M^2) results as well.



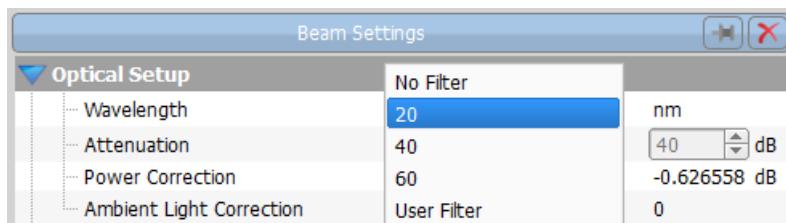
The available range is limited to 190 - 350 nm for BC106N-UV and 350 - 1100 nm for BC106N-VIS, respectively.

4.5.1.2 Attenuation

The attenuation is given by the selection of the neutral density (ND) filter that is placed in front of the optical input. You can select a filter by rotating the [filter wheel](#)¹⁹. Select the **nominal attenuation** of the chosen ND filter in order to include the attenuation in the calculation of the Total Power.



Select the active filter from the drop-down list.



Select '**No Filter**' in the case that you have removed the filter in front of the entrance aperture so that no attenuation (0 dB) is present. If you are using external attenuation filters or beam splitters, select '**User Filter**' and enter its attenuation value into the control on the right. Only values between 0 and 100dB are accepted by the software.

Note

The correct selection of this attenuation value is a precondition for a proper power measurement and for the [Ambient Light Correction](#)³⁷.

4.5.1.3 Power Correction

The Power Correction allows to adjust the measured by the Beam Profiler total beam power to the power level measured by a reference power meter.

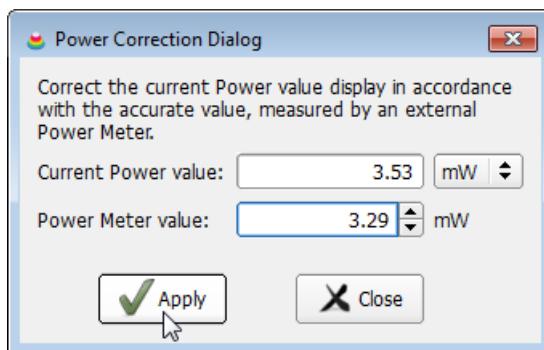
Preconditions:

Be sure to have set the following settings accurately:

- Operating wavelength
- Nominal loss of the selected ND filter



Click the 'Start' button - the Power Correction Dialog appears.



The 'Current power value' is the actually measured by the Beam Profiler power. Enter the power meter reading into the 'Power meter value' control. Click 'Apply' and both values will coincide. Click 'Close' to leave the panel.

The difference between the entered power value and the actually measured by the instrument power will be displayed as an offset, here -0.405707 dB.



This offset (in dB) is stored in the Beam Profiler and is read out and activated automatically each time after connecting this instrument.

Note

The user calibrated power reading is correct only at the actual wavelength and the selected ND filter. If any of these parameters changes, the power correction needs to be carried out again.

After executing the Power Correction it is activated automatically, which is indicated by the check mark.

In contrast to that, the activation state is saved in the software. When restarting the software using the same instrument, the offset is recognized, read out and the same activation state (active / inactive) as in the previous software session will be restored.

If the power correction is not active, the attempt to activate it lets the software check the camera for a saved offset. If no saved offset is found, the Power Correction dialog opens and asks for a power meter value. If an offset is recognized, it will be applied immediately. For this reason it is recommended to perform a power correction if the environment of the instrument was changed.

4.5.1.4 Ambient Light Correction

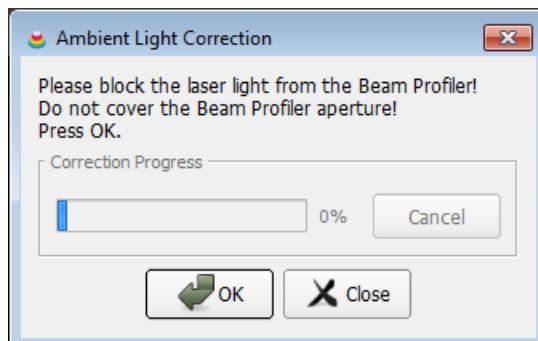
It is highly recommended to shield ambient light from entering the entrance aperture as best possible, e.g. using the supplied ND attenuation filters. However, a considerably high ambient light level may still occur within the camera image that cannot be distinguished from beam power. Accordingly, an offset level will add up to the measured beam profile which leads to inaccurate beam parameters. Therefore, a correction for the remaining ambient light level is provided and should be carried out in the case where the ambient light level is measurable (The far-off wings of the X Y profiles do not go down to zero intensity level).

Note

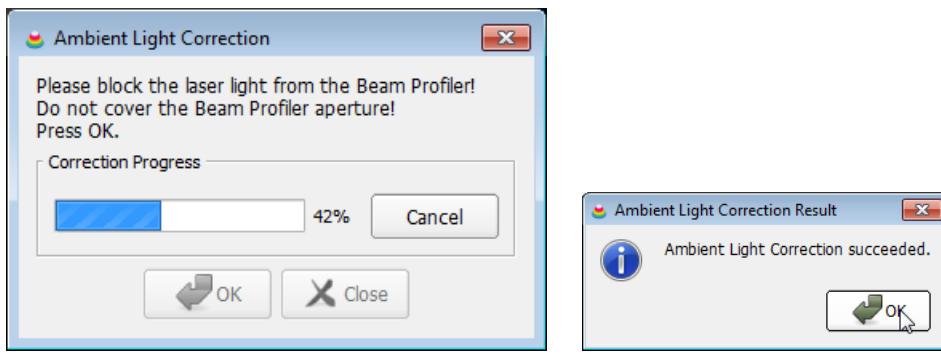
It is recommended to proceed with the ambient light correction after a 30 min warm-up time and repeat it if needed (e.g., ambient light conditions changed).



Click the 'Start' button - the Ambient Light Correction Dialog appears.



Make sure the laser is blocked, but not the ambient light, click "OK"; the correction starts.



Click OK and close the Ambient Light Correction window. The Ambient Light Correction appears enabled, and the correction factor will be displayed.



Note

- Thorlabs Beam software uses a unique approach for Ambient Light Correction - please see details in section [Application Notes](#).
- When ambient light power is changed or a different ND filter is used, a new correction is required, otherwise beam profiles are displayed using an unreal (positive or negative) offset and the accuracy of measurement results may worse.
- Ambient light correction is disabled by any software restart, reconnection of a camera Beam Profiler, or change of the ND filter settings in the software.

4.5.1.5 Intensity Threshold

The Intensity Threshold applies to the raw data retrieved from the camera, and allows to clip the intensities below a user-defined threshold.

Warning!

Using the intensity threshold may exceed the [Calculation Area Clip Level](#). In such case, the calculation area will change and this way falsify the beam diameter calculation. The beam centroid position will not be affected.

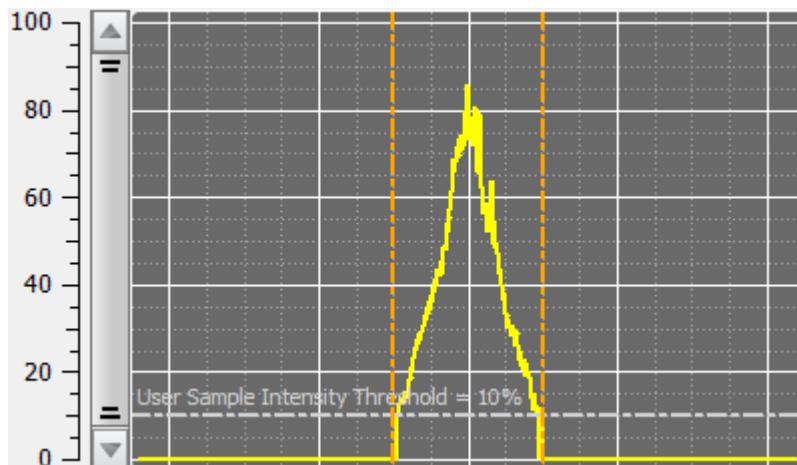
A typical situation to enable the intensity threshold is, for example, the task to define the beam centroid in an environment with an high and instable ambient light level. The changing ambient light interferes the centroid position calculation. Applying an appropriate intensity threshold, the varying ambient light can be omitted.

The entered value is the percentage of the maximum ADC output level:



In above example, all intensities below 10% of the ADC maximum output level are omitted.

The threshold is shown in the X and Y profiles as a dot-and-dashed line with a label, if the option **Auto Scale to Peak**  is disabled - in this case, the intensity scale of the X or Y profile displays the percentage of the ADC maximum output level:



If **Auto Scale to Peak** is enabled, the intensity scale displays the percentage of the peak level, and thus, the Intensity Threshold label cannot be displayed.

4.5.2 Beam Profiler Information

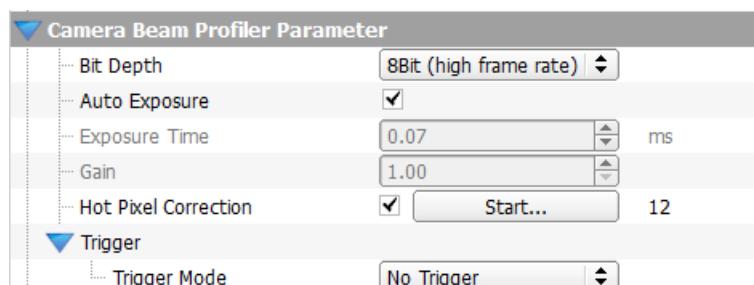
Beam Profiler Information	
Model	BC106N-VIS/M
Serial Number	M00311068
Driver Version	1.11.9
Firmware Version	13.21
Sensor Information	
Width Height	
Pixel Resolution	1360 1024 pix
Pixel Size	6.45 6.45 μm
Sensor Size	8.77 6.60 mm

These data are read out from the BC106N instrument and cannot be changed. Beside general information (Beam Profiler model, serial number and driver version), other important sensor information are stated:

- Max. camera resolution of the Region of Interest (ROI) in pixels
- Pixel size
- Max. available physical sensor size

4.5.3 Camera Beam Profiler Parameter

This section contains a number of important camera settings that are accessible by the user. Please become familiar with the meaning of these controls in order to prevent improper adjustments which may lead to erroneous measurement results. All visible controls are explained below.



Details on the individual parameters are explained in the subsequent sections.

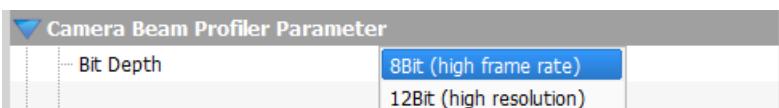
Initial Settings

When this camera is connected for the first time, the following default camera parameters are set:

Parameter	Default Value
Bit Depth	FAST (8 bit data)
Auto Exposure Control	ON
Gain	1.0 (minimum)
Hot Pixel Correction	ON
Region Of Interest	Full Size
Trigger	
No Trigger	(selected)
Software Trigger	OFF, 50% min AD saturation
Single Pulse	100ms Target Delay, Rising Edge
Repetitive Pulses	1.000kHz Rep. Rate, Rising Edge

4.5.3.1 Bit Depth

The **Bit Depth** controls the number of bits used for digitization of each single camera pixel.



	Fast Mode	Precision Mode
Used ADC Resolution	8 bit	12 bit
Available Digits	0 - 255	0 - 4095
Quantization Noise	medium	low
Achievable Frame Rate	maximum	reduced

By default, Fast Mode is selected in order to enable a maximum frame rate. For low-noise and high-accurate measurement results it is recommended to enable the Precision Mode.

4.5.3.2 Exposure Control

Exposure time is the period of time when the CCD global shutter is open and the image sensor is exposed. For CW sources there is a linear dependency between exposure time and mean image brightness. Increase the exposure time to increase brightness and vice versa.

1. Auto Exposure Control

The exposure control of the Beam Profiler camera includes adjustments for Exposure Time and electrical Gain factor. Both settings determine the sensitivity of the camera and need to be adapted to the actual beam power in order to ensure a nearly full scale amplitude measured by the camera's AD converter.

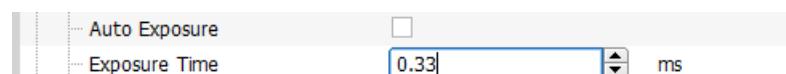
By default, both settings are controlled automatically in order to achieve an Image Saturation between 80 and 95% of the available AD range.



It is highly recommended to use this automatic exposure control. When activated, the Beam Profiler software will automatically adapt both the exposure time and gain. Both controls become gray and display the actually used values. The goal is to keep the brightest pixel of the selected ROI at a high saturation level but prevent saturation (100%) due to the limited range of the AD converter that is digitizing the image.

However, in case of unstable or pulsed laser power it might be advantageous or even required to disable the automatic exposure control and set the optimal values manually. For this, remove the 'Auto Exposure Control' check mark.

2. Manual Exposure Control

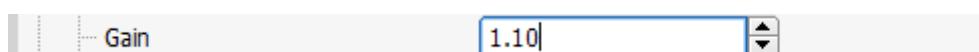


Exposure time can range from 0.020 ms to 1000 ms with a step width of 0.063 ms. The lowest exposure times (20µs, 43µs, 74µs, 136µs, ...) are separated by smaller steps.

Use the arrows in order to increase and decrease the exposure time stepwise. The step size is automatically adapted to the actual value so that a change of about 20% is achieved. To enter a certain value just overwrite the present one.

4.5.3.3 Gain Control

The Gain can be set manually only with Auto Exposure disabled.



Gain Factor denotes the linear amplification factor of the electrical amplifier between the CCD sensor and the AD converter. Higher gain increases image brightness, but also image noise. Therefore, it is recommended to use primarily the exposure time control for brightness adjustments.

Gain settings higher than 1.0 should be used only if

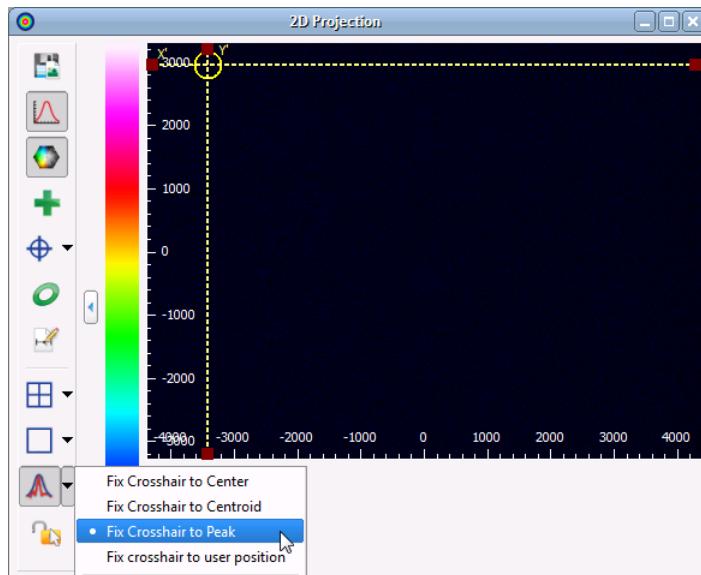
- the exposure time is already set to its maximum value or
- the exposure time is set below 1 ms and brightness change between two successive exposure times is too large.

4.5.3.4 Hot Pixel Correction

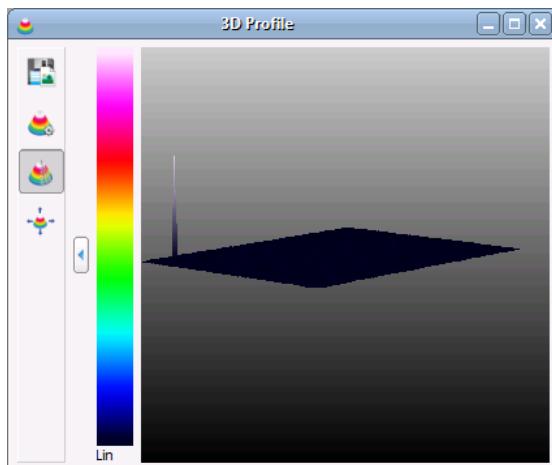
Hot pixels appear as an unwanted property of CCD sensors and are due to different charge leakage rates between individual pixels. They appear as points of high intensity particularly at long exposure time and their intensity depends on the temperature as well.

Hot pixels may cause measurement errors, particularly in 4σ measurements, which is important for M^2 beam quality measurements, and may impact the baseline definition during ambient light correction.

Hot pixels can be displayed in the software, using 2D projection and fixing the crosshair to peak. Darken the aperture and set exposure control to Auto. The crosshair will go to the hot pixel with the highest intensity:



Hot pixels can be displayed in 3D view (auto scale to peak disabled), either:



Thorlabs Beam offers a hot pixel correction feature.

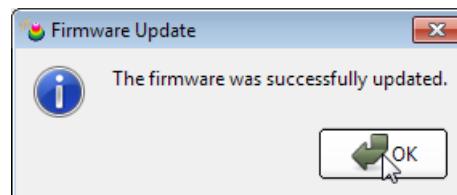
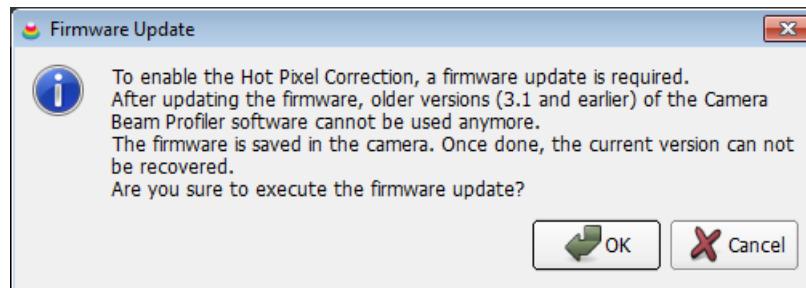
Note

- Hot pixel correction is possible only if your BC106N firmware is of version 13.20 and up. In the case that the device firmware is older, hot pixel correction is disabled and a firmware update is proposed.
- Note that with firmware V13.20 and later, the Beam software versions V3.1 and earlier cannot be used anymore.

If the firmware is older than V13.20, you will be asked for firmware update:

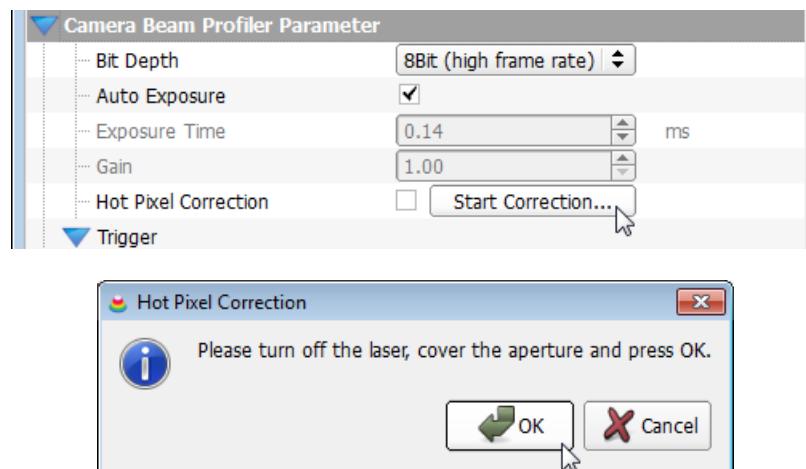
... Hot Pixel Correction Update Firmware...

Click the **Update Firmware** button and follow the instruction:

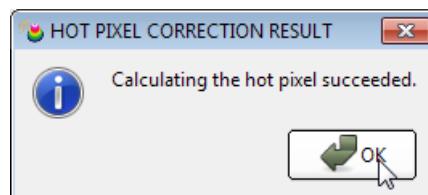


After a successful firmware update you need to restart the Beam software. This is required in order to read-out from the BC106N the correct firmware version.

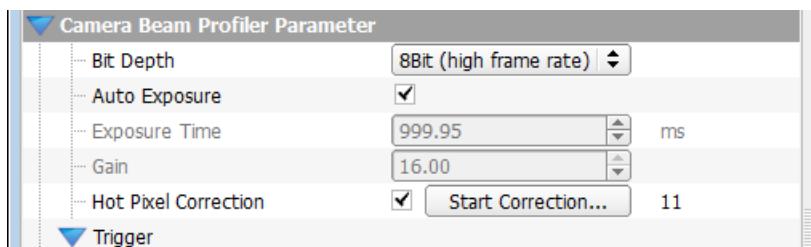
Start the Hot pixel Correction by clicking the **Start Correction** button:



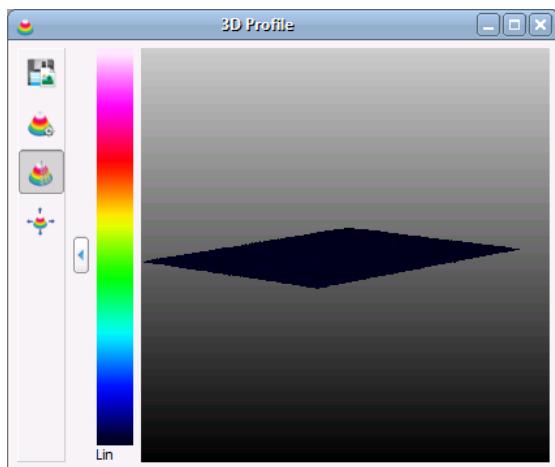
Click **OK**. The correction starts; hot pixels are being smoothed by interpolation to adjacent pixels and a maximum of 100 hot pixel can be saved.



Click **OK**. Hot Pixel Correction data are saved to the camera's internal non-volatile memory and remain there unless overwritten with the next hot pixel correction. The number of hot pixels will be displayed to the left. Set the check mark to activate Hot Pixel Correction:

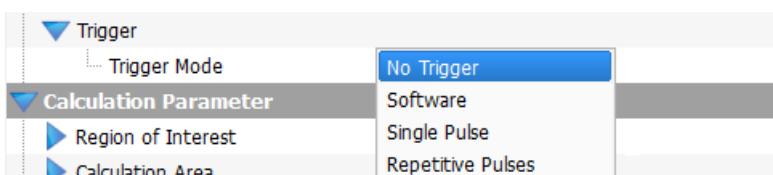


Below is the 3D projection of the same camera as above, but after correction - indeed, no hot pixels can be seen anymore.



4.5.3.5 Trigger

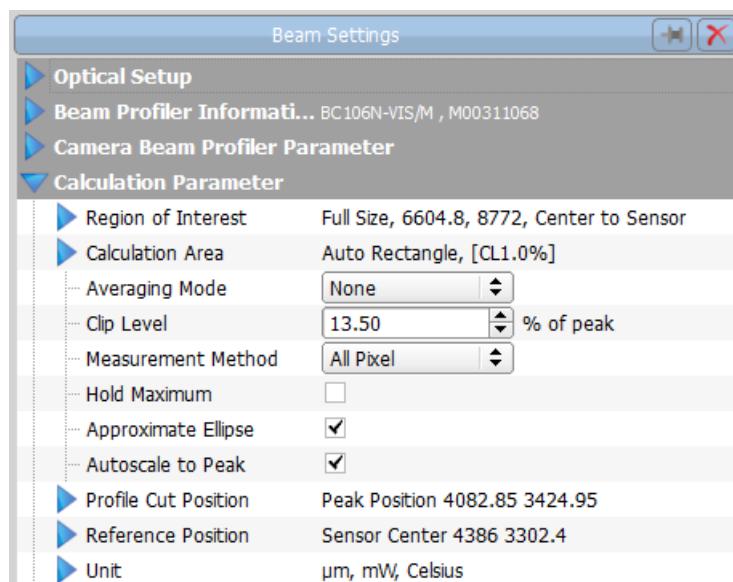
The electrical TTL-level trigger input is used to synchronize laser pulses with the camera exposure. See chapter [Pulsed Laser Sources](#)⁹² for a detailed description of the implemented trigger functionality.



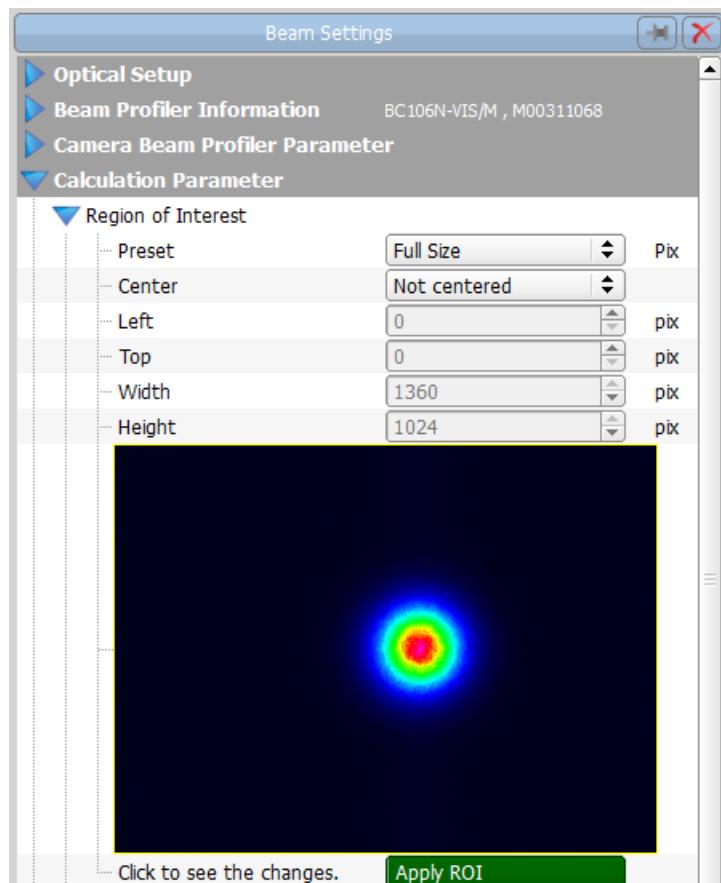
By default 'No Trigger' is chosen for continuous caption of CW light sources.

4.5.4 Calculation Parameter

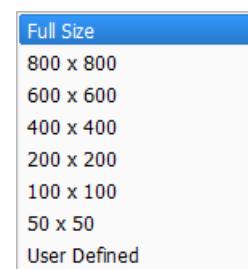
This section is used to set the parameter for beam profile calculation. Below is shown the view of the Calculation Parameter section at the first start of the Beam software or after pressing the "[Reset Application Settings to Defaults](#)" button ():



4.5.4.1 Region of Interest



The ROI defines a subarea within the maximum available camera sensor surface, whereas the maximum ROI is 1360 x 1024 (full size) and the smallest 32 x 32 pixel. Only image data of the selected ROI are transmitted from the Camera Beam Profiler to the PC so that a narrowed ROI size reduces bandwidth requirements and therefore increases measurement speed (frames per second, fps).



There are some ROI presets that can be selected from the list. To confirm, click to the **Apply ROI** button - this button applies the changes that were made not only to the ROI, but also to the [Center settings](#) of the ROI. By selecting a predefined ROI it is automatically centered to the sensor center. See the preview image for visualizing the adjusted size which is displayed as a yellow rectangle. To shift the selected

ROI within the available sensor area click right into this rectangle and drag the mouse; the "Preset" name changes immediately to User Defined.

A user defined ROI can be easily defined by drawing a rectangle into the preview image (click left, hold down and draw a rectangle). The last preset value is replaced automatically by "User Defined" and the chosen ROI size and position is displayed within the controls on the right.

These values can also be modified by entering the desired Width, Height, Left and Top values into the appropriate controls. Its unit can be switched between pixels or μm .

Note

The ROI point of origin (0,0) is located in the upper left corner of the entire sensor area so that 'Left' and 'Top' describe the upper left ROI borders with respect to this corner. In contrast to that, measurement coordinates X and Y are defined with respect to the center of the ROI, see below.

Center

Any user defined ROI can be centered to either the sensor center or to the centroid of the measured beam. The latter may be useful if the beam centroid is located far away from the sensor center and the user defined ROI does not cover the sensor center.

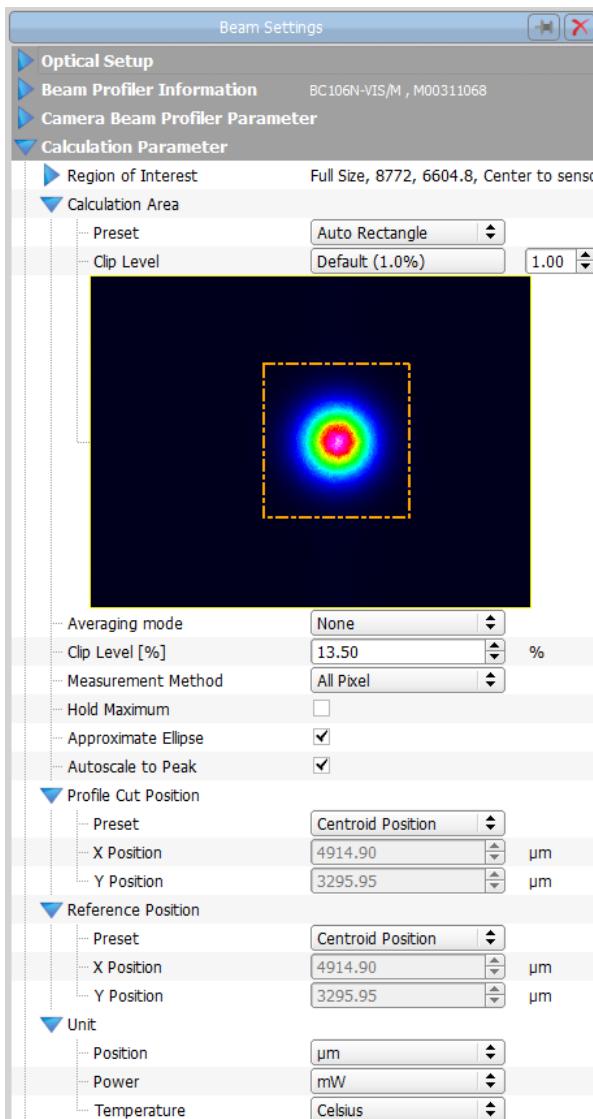
In the case that the measured beam is considerably smaller than the Camera Beam Profiler aperture, it is advisable to limit the area captured by the camera. Reduce the image area by determining a ROI that is well filled by the beam. However, it's not recommended to narrow ROI too much - lower intensity areas surrounding the laser beam will be cut off! This may lead to incorrect numerical results (for instance Beam Centroid position) or even prevent calculation of the beam width because the selected clip level (default 13.5% of the peak intensity) is not reached within the ROI.

When the beam under test does not fit to the selected ROI area, you need to increase field of view by enlarging the ROI. The ROI height and width should be at least two times the beam width.

Note

Don't forget to click the **Apply ROI** button, as soon as it becomes highlighted green!

4.5.4.2 Calculation Area



The Calculation Area defines a specific area within the already selected Region of Interest (ROI), see [Camera Beam Profiler Parameter](#)⁴⁰. Whereas the ROI determines the image area that is retrieved from the camera and displayed, the Calculation Area can be equal to or smaller than the ROI and defines the image area, that is used for all numerical calculations. That is, all pixels within the ROI are displayed while only the pixels within the Calculation Area are used for calculations.

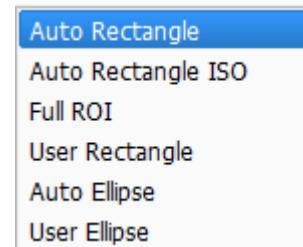
Such a limitation is especially advantageous for:

- Selecting and analyzing only a single beam spot among multiple beams
- Rejecting ambient or stray light
- Reducing measurement noise
- Increasing performance

Note

It is advisable to set the camera ROI to the smallest feasible area instead of working with a large ROI and shrinking the Calculation Area afterwards. This will increase measurement speed.

Six presets are provided to chose a Calculation Area.



Auto Rectangle:

The software will analyze every image from the BC106N automatically and determine the area in which a measurable amount of power is present. Areas with a lower power level than the [clip level](#)⁴⁸ will be excluded from further calculations.

Auto Rectangle ISO:

The rectangular calculation area is calculated according to ISO11146-2 using multiple iteration steps. The clip level is determined during the calculation.

Full ROI:

The entire image area defined by the ROI is involved in beam calculations.

User Rectangle:

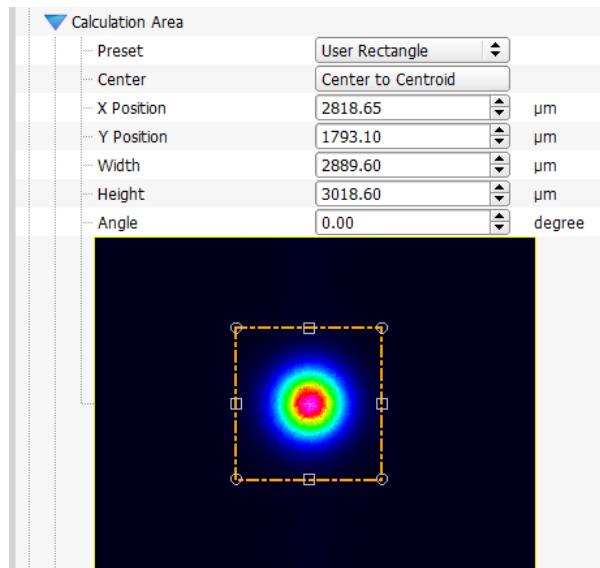
A rectangular area, set by user input is defined as Calculation Area. Enter pixel values which describe the Calculation Area position and size or simply drag a rectangle into the 2D Projection window.

Auto Ellipse:

An elliptical area is created automatically by the software around the beam shape. Criteria: [Clip Level](#)⁴⁸. Areas with a lower power level than the clip level will be excluded from further calculations. The clip level can be set up in the Application Settings.

User Ellipse:

An elliptical area, set by user input is defined as Calculation Area. Enter pixel values which describe the Calculation Area position and size or simply drag an ellipse into the 2D Projection window.



When 'User Rectangle' or 'User Ellipse' is selected, you need to enter size and position of the Calculation Area numerically or drag and drop the borders of the user rectangle (ellipse). All values are in μm or pixels, depending on the [unit selection](#)⁵¹, and the point of origin is situated in the upper left corner of the entire sensor area. X (Y) Positions describe the position of the left (upper) border of the user rectangle (ellipse). Further, a defined calculation area can be rotated by entering numerically the desired rotation angle.

The Calculation Area can also be set and visualized within the [2D Projection](#)⁵⁵ window. See the appropriate chapter for details.

Clip Level of the Calculation Area

If the calculation area is detected automatically (**Auto Rectangle** or **Auto Ellipse**), the borders of the Calculation Area in all four directions are defined by the calculation area clip level. The border in one direction is set when all pixel values fall (seen from the peak) below the Clip Level. Decreasing the Clip Level increases the Calculation Area which in return increases for example the 4σ diameters, but also increases the noise. For a steep beam profile, 1.0% is an optimal clip level value. If the beam profile is rather flat, it might be advantageous to lower the clip level.

The clip level is set by default to 1 % and can be set between 0.01 and 13.5 %. In order to quickly return to the recommended 1.0% clip level, just click to the box *Default (1.0%)*.



Note The *Clip Level of Calculation Area* is different from the [Clip Level](#)⁴⁹ used for beam profile calculations!

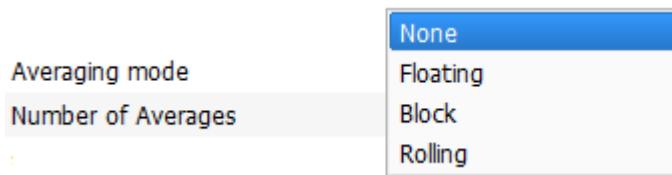
Attention

The calculation area must not cut off lower intensity parts of the beam profile. This may cause inaccurate calculation results!

Note

When the ROI size or position is changed and the Calculation Area was not set to 'Automatic' and does not fit into the new ROI, the Calculation Area will be reset to 'Full Size', in other words, to the new ROI.

4.5.4.3 Averaging Mode



Three modes are available - floating, block and rolling. The number of frames can be set between 1 and 100.

In **Floating mode**, the average is calculated from the weighted previous average and the recent frame. Example: Floating average is made for 10 frames. The previous average value is multiplied by 9, then the recent frame value is added and the sum is divided by 10, which gives the new average value.

In **Block mode**, the indicated number of frames is accumulated, after finishing the average is calculated and displayed. This is the slowest mode.

In **Rolling mode**, the averaging is done over the indicated most recent number of frames. Example: Rolling average is made for 10 frames. The most recent 10 frames are averaged and displayed, the value is updated with each new frame.

Setting the frames to numbers higher than 1 to enables noise reduction.

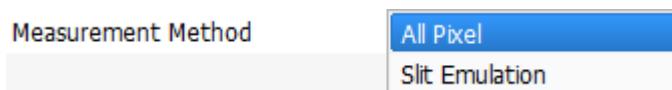
This option is helpful for unstable light sources with fluctuating intensity or beam shape, or if the update rate on the screen is too high for easy data readout. Also use this option to suppress Beam Profiler noise in case of low intensity.

4.5.4.4 Clip Level

In contrast to the [Calculation Area Clip Level](#)⁴⁸, the **Clip Level** parameter is used to determine the beam width. It defines a relative intensity level between dark level (0%) and peak level (100%) of the measured beam profile at which the beam width is determined. The ISO11146 Standard recommends a default value of $1/e^2 = 13.5\%$ of the peak intensity. Other values from 5% to 95% can be set by entering manually.

Click on *Default (1/e²)* to set the default Clip Level of 13.5%. See Appendix [Application Note](#)¹⁶⁷ for details.

4.5.4.5 Measurement Method



Switch between the normal mode where all calculations are calculated with every single pixel ("All Pixels") or the slit emulation mode ("Slit Emulation") where some calculation results (e.g. Beam Width with clip level and the Gaussian fit) depend on the row and column sum.

4.5.4.6 Hold Maximum

The **Hold Maximum** feature is recommended for pulsed laser sources. In all subsequent scans for each pixel only the maximum values are stored, displayed and used for calculation.

4.5.4.7 Approximate Ellipse

Enable the **Approximate Ellipse** check box in order to get the best fitted beam ellipse. This setting provides more stable and reliable ellipse results.

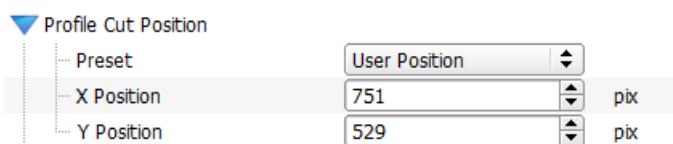
Otherwise, ellipse data are retrieved from single minimum and maximum diameters of the elliptical beam cross section. These results are more noisy and therefore less reliable than the fitted results.

4.5.4.8 Autoscale to Peak

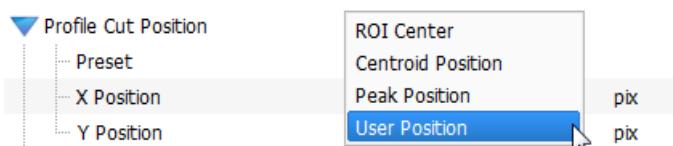
Enable the '**Autoscale to Peak**' check box to scale the X and Y profiles to their peak intensities. Disabling will scale the X and Y profiles to the value of AD saturation.

4.5.4.9 Profile Cut Position

The profile cut position determines the location of the crosshair in the [2D Projection](#)⁵⁶.



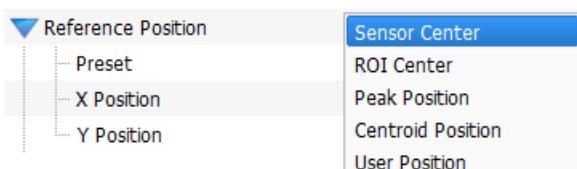
The position of these X and Y cross sections can be fixed to the ROI Center, to the centroid, to the peak, or to a user defined position.



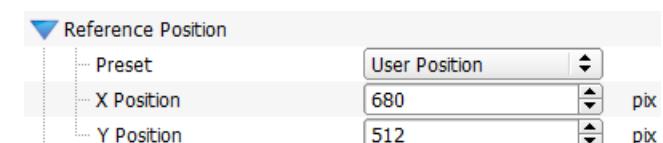
For the user defined position, the X and Y positions are to be entered numerically.

4.5.4.10 Reference Position

The reference position influences the calculation results. Peak and Centroid positions refer to the reference position. By default, the reference position is set to the sensor center. In the 2D Projection window it is displayed as a grey crosshair.



The Reference Position can be set to predefined positions (see above) or to a user defined position. The X and Y coordinates of a user defined position are to be entered numerically or set in the [2D Projection](#)⁵⁶ (Reference Position Editor):



4.5.4.11 Unit



The measurement units that are displayed in the Beam Software can be selected in the **Unit** topic.

Position units: **µm or pixel.**

Total Power units: **mW or dBm.**

Temperature: **°C, °F or K.**

(Temperature is measured inside the camera.)

The following table gives an overview on all available units:

Unit	Description
pix	Location, width or distance, related to the image sensor pixels. The origin of the coordinate system ($X=0, Y=0$) is the sensor center, not the image center! Positive X values go to the right, positive Y values to the top of the image.
µm	Location, width or distance in µm, calculated from the camera pixels. 1 pixel = 6.45 µm. The origin of the coordinate system ($X=0, Y=0$) is the sensor, center not the image center! Positive X values go to the right, positive Y values to the top of the image.
mW	The Total Power of the beam is calculated from the integral intensity of the image using the wavelength dependent sensor response, the Exposure Time and Gain of the camera as well as the filter attenuation and the power correction value.
dBm	The Total Power translated from mW into dBm: $10 * \log(P[mW])$, 0 dBm refers to 1 mW
%	Relative level between 0 and 100%
deg	Angle in degree with respect to the X axis, range -90° to +90°

4.5.5 Plot Over Time Parameter



The Beam software allows to show different plots of beam measurements:

[Plot Positions](#)⁷³

[Plot Power](#)⁷⁴

[Plot Gaussian Fit](#)⁷⁵

[Plot Orientation](#)⁷⁶ [Plot Environment Data](#)⁷⁷ and

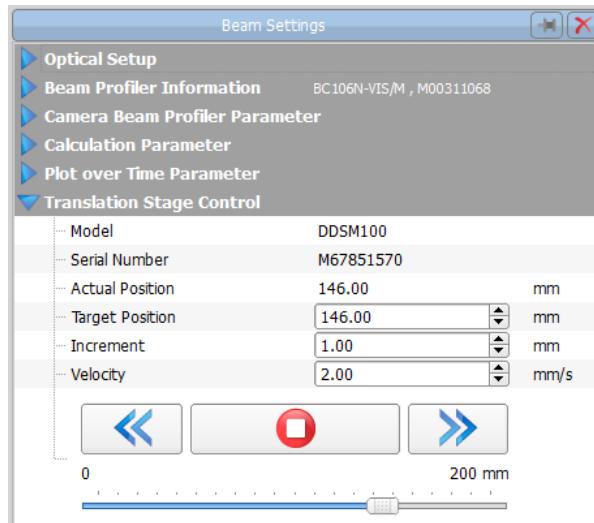
[Beam Stability](#)⁷⁸

The section **Plot Over Time Parameter** is used to configure these plots:

- The maximum number N of data points in the plots can be defined (N=1 to 100000).
- The time interval between two data points can be selected (between 0 = every measurement to 1000 s; default = every measurement).
- Specify the action performed after the maximum number N of recorded data points is reached:
 - "Discard first points" means the 1st data set is discarded and the most recent data point will be added to the plot. In other words, after reaching the maximum number N of plotted data points, the plot continues and displays the most recent N data points.
 - "Discard last points" means that all data points beyond N will be discarded. In other words, after reaching the maximum number N of data points, the plot stops.

4.5.6 Translation Stage Control

If a translation stage is detected, an appropriate topic at the bottom of the Beam Settings panel appears. The description in this section assumes a Thorlabs DDSM100 Linear Translation Stage, as it is used in the [M2MS Extension Set](#)¹⁰¹.



This panel allows the user to manually control the translation stage. This is useful for a coarse setup of the M² or Divergence Measurement.

Actual Position displays the present stage position.

Target Position

Enter a value between 0 and 200 mm, press 'Enter' on your keyboard, and the stage will travel with the set **Velocity** to the new position.

Note

The total displacement reaches from 0 to 200 mm, although the stage translation path is only 100 mm. This results from the mechanical design of the [M2MS](#)¹⁰¹ M² Meter Set.

Increment

Enter the increment for moving the stage stepwise.

Velocity

This is the speed of the stage when traveling between two positions (e.g., between the actual and the target position).



Pressing these buttons moves the stage backward / forward for one step, equal to the **Increment**.



Pressing this button interrupts the continuous stage travel to a target position.

The slider bar on the bottom of the panel has two functions - it shows the stage position, and the slider can be moved with the mouse in order to start a stage travel.

4.6 Child Windows

When starting the application first time, three child windows are opened and arranged automatically:

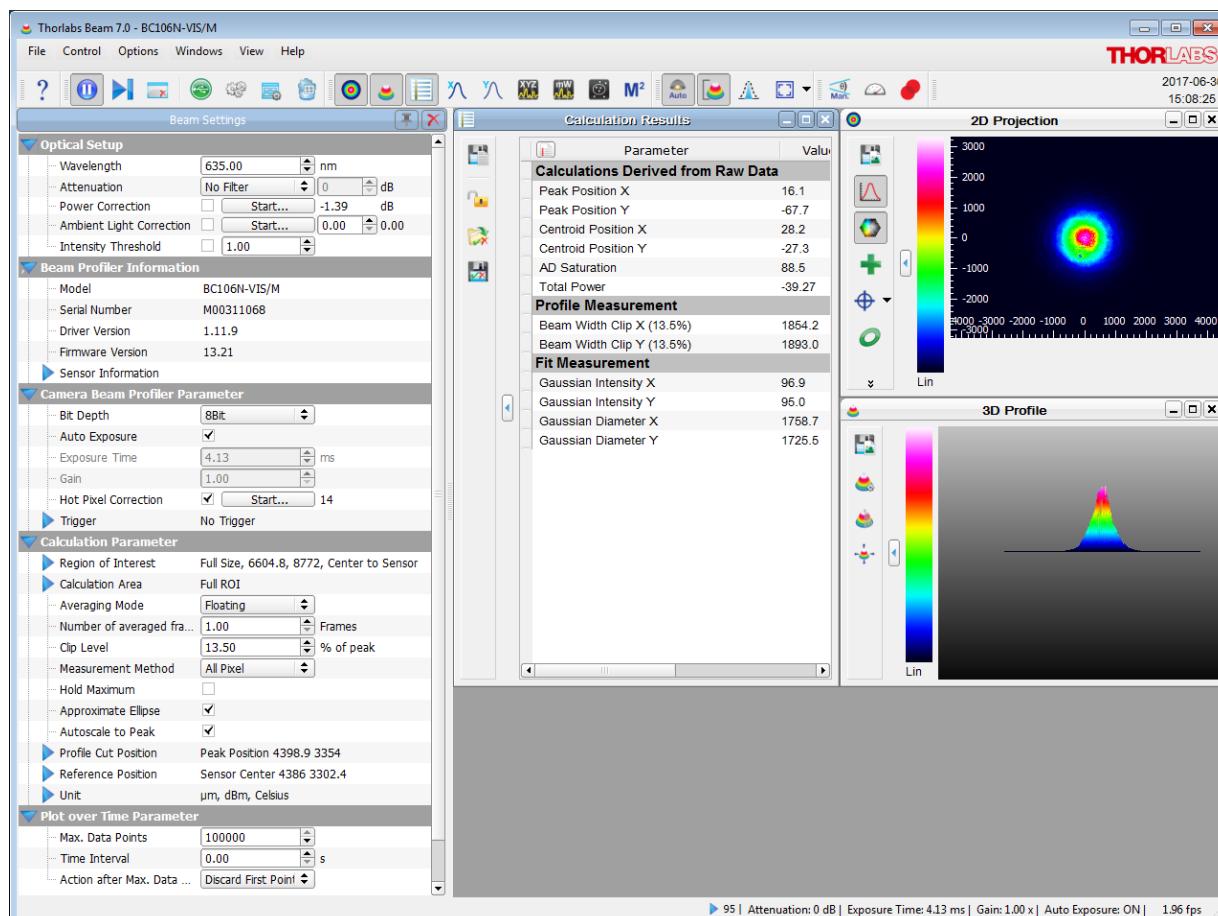
- [2D Projection](#) [55]
- [3D Profile](#) [58]
- [Calculation Results](#) [62]

The application also provides other windows:

- [X Profile](#) [60]
- [Y Profile](#) [60]
- [Plot Positions](#) [72]
- [Plot Power](#) [74]
- [Plot Gaussian Fit](#) [75]
- [Plot Orientation](#) [76]
- [Plot Environment Data](#) [77]
- [Beam Stability](#) [78]
- [Beam Quality \(M²\)](#) [98]
- [Manual Vergence Measurement](#) [66]
- [Tuning View](#) [68]
- [Beam Overlapping](#) [70]

All above windows can be opened and closed by clicking the symbols in the toolbar or by selecting the entries in the menu "Windows".

The appearance of the Thorlabs Beam software can be arranged according to your requirements and taste. All child windows can be resized and positioned very flexible. Here is an example of arranging some child windows:



To close a child window deselect the menu entry or the appropriate toolbar symbol or click the close button "X" in the upper right corner of the child window.

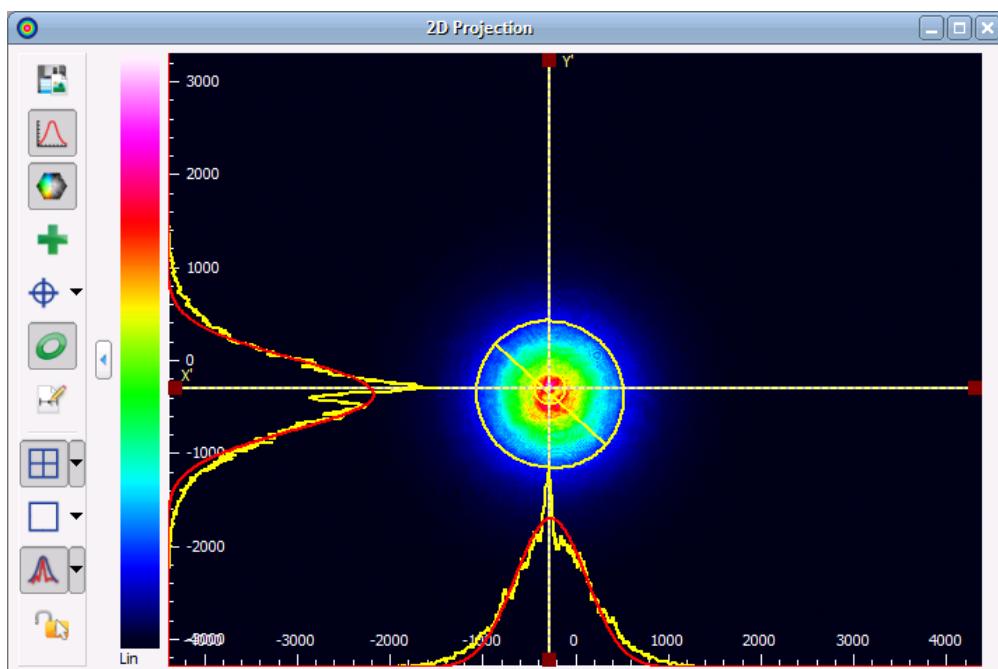
Each child window can be moved and resized. If a child window is closed its settings are stored so that it will have the same position and size when it is reopened.

When the GUI application is closed and reopened, the main panel will have the same child panels open in their former positions. To arrange the windows automatically use the function "Tile View" from the "[View](#)"³⁰ menu.

4.6.1 2D Projection

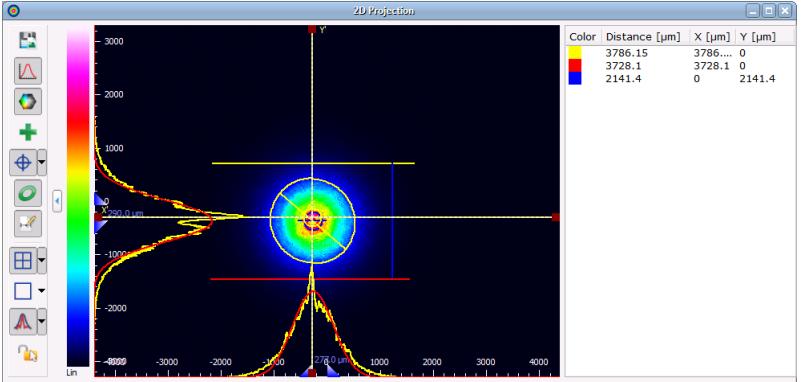
The 2D Projection graph shows the image from the Beam Profiler indicating the power intensity distribution within the selected Region of Interest (ROI).

This window can be opened and closed via the menu item "2D Projection" in the window menu or via the toggle button  in the toolbar.



On the left side of the 2D Projection window a toolbar is located with the following toggle buttons:

Toolbar Icon	Associated Action
	Save Diagram or Image
	Opens a dialog box to specify the properties of the saved screenshots / diagrams.
	Show or hide the x and y scale
	Changes the color of the image from gray scale to color (see Display Settings ²⁷)
	Marks the Peak Position using a green cross
	Marks the Beam Centroid using a blue cross within a blue circle; resets the centroid indicators
	Displays the approximated Beam Ellipse in yellow color. The ellipse is drawn corresponding to fitted or unfitted numerical data. See Beam Settings ⁵⁰ to enable/disable the ellipse fit.

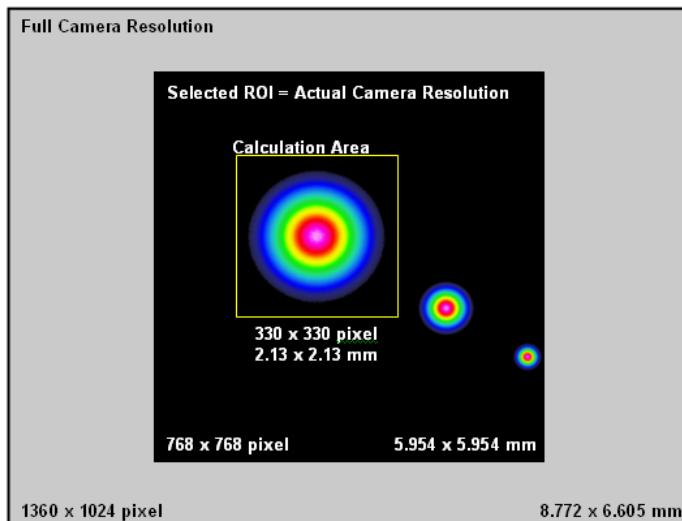
Toolbar Icon	Associated Action																
 Distance Measurement Mode	<p>The distance measurement editor opens a table beside the projection image. When drawing lines into the projection image, the distance is inserted into the table. A maximum of 10 distances can be drawn. Remove a distance entry by selecting the entry and pressing the "DEL" key or select the entry and choose the "Delete Distance" entry from the context menu.</p>  <table border="1"> <thead> <tr> <th>Color</th> <th>Distance [μm]</th> <th>X [μm]</th> <th>Y [μm]</th> </tr> </thead> <tbody> <tr> <td>Yellow</td> <td>3786.15</td> <td>3786....</td> <td>0</td> </tr> <tr> <td>Red</td> <td>3728.1</td> <td>3728.1</td> <td>0</td> </tr> <tr> <td>Blue</td> <td>2141.4</td> <td>0</td> <td>2141.4</td> </tr> </tbody> </table>	Color	Distance [μm]	X [μm]	Y [μm]	Yellow	3786.15	3786....	0	Red	3728.1	3728.1	0	Blue	2141.4	0	2141.4
Color	Distance [μm]	X [μm]	Y [μm]														
Yellow	3786.15	3786....	0														
Red	3728.1	3728.1	0														
Blue	2141.4	0	2141.4														
 <ul style="list-style-type: none"> Set Reference Position to Sensor Center Set Reference Position to ROI Center Set Reference Position to Peak Position Set Reference Position to Centroid Position Set Reference Position to User Position 	<p>The reference position for calculations can be displayed or hidden as a grey crosshair by toggling the  button. A drop-down menu allows to set the reference to typical positions or to define a user position. Detailed explanations please see in section Beam Settings <small>[50]</small>.</p>																
 <ul style="list-style-type: none"> Set Calculation Area Automatic Set Calculation Area Automatic ISO Set Calculation Area to Full Size Set Calculation Area by User Set Calculation Area Automatic Ellipse Set Elliptical Calculation Area by user 	<p>The Calculation Area is a subarea of the ROI, it can be displayed or hidden by toggling the  button. Only pixels within this Calculation Area are interrogated and recognized for beam data calculation.</p> <p>A drop-down menu allows to make a choice from several presets; additionally a rectangular or elliptical calculation area can be defined by the user. Detailed explanations please see in section Beam Settings <small>[47]</small>.</p>																
 <ul style="list-style-type: none"> Fix Crosshair to Center Fix Crosshair to Centroid Fix Crosshair to Peak Fix crosshair to User Position <hr/> <p>Reset the Angle to 0</p> <hr/> <p><input checked="" type="checkbox"/> Show Profile Curve</p> <p><input checked="" type="checkbox"/> Show Fit Curve</p>	<p>The crosshair, that shows the X and Y profile cuts for calculation, can be displayed or hidden by toggling the  button.</p> <p>The position of these X and Y cross sections can be fixed to the ROI Center, the centroid, the peak or to a user defined position.</p> <p>Additionally, X and Y profiles and their curve fits can be drawn into the 2D graph displaying the power distribution within a horizontal and a vertical cross section.</p> <p>Please see also section Beam Settings <small>[50]</small>.</p>																
	<p>This button locks or unlocks the mouse interactions within the 2D Projection.</p>																

If the window height is smaller than the full toolbar, the lower symbols are packed into a context menu which is accessible via an arrow button on the bottom of the toolbar.

Attention

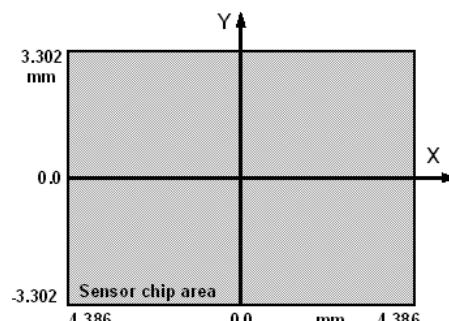
The calculation area must not cut off lower intensity parts of the beam profile. This may cause improper calculation results!

The following graph shows an example of chosen ROI and Calculation Area:

**Example:**

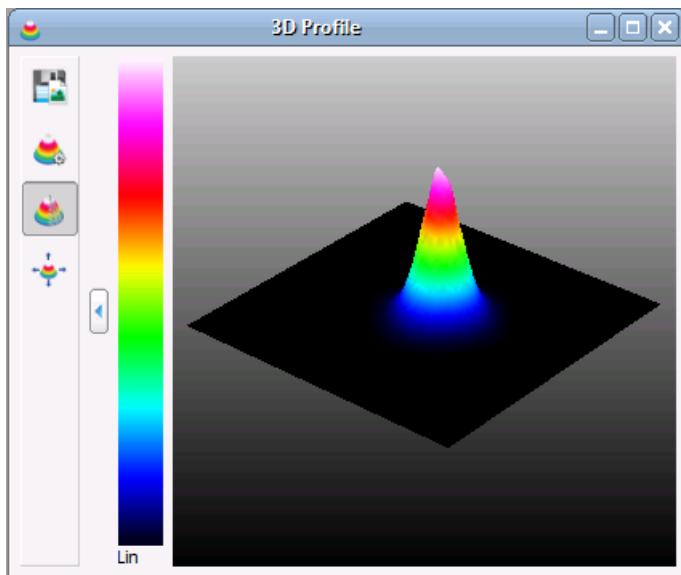
The beam in this example enters the Beam Profiler several times: once directly and additionally from multiple reflections. The ROI is selected to 768x768 pixels so that all 3 beams are visible within the 2D Projection window. But, in order to limit the image interrogation to the main beam the calculation area was chosen much smaller.

Within this 2D Projection panel, coordinates X and Y are defined as follows:



Independently of the selected unit (pixel or μm) within the Application Settings panel (see [Beam Settings, Unit](#) [51]), the origin of the coordinate system is the selected reference position. Horizontal axis is X and vertical axis is Y. Both axes are also labeled on the Beam Profiler housing.

4.6.2 3D Profile



The 3D Profile illustrates the power density distribution of the measured optical beam. Whereas the beam's cross-section is parallel with the X-Y-plane, the relative power intensity is shown in the Z direction (Pseudo 3D). This window can be opened and closed via the menu item "3D Profile" in the window menu or via the toggle button  in the toolbar. It can be closed via the X button in the upper right corner of the child window.

The 3D profile can be moved, rotated and zoomed with the mouse:

Rotate: Press right mouse button and move mouse

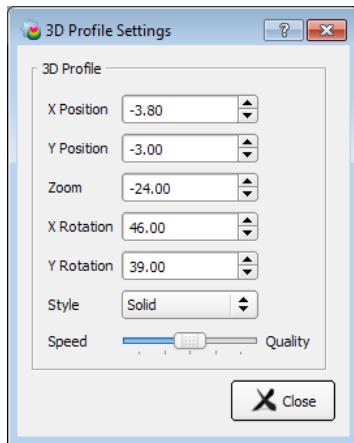
Move: Press left mouse button and move mouse

Zoom: Scroll mouse wheel

The following table summarizes the toolbar symbols available within the 3D Profile window and its appropriate action.

Toolbar Icon	Associated Action
	Opens a dialog box to specify the properties of the saved screenshots / diagrams.
	Opens the 3D Profile Settings dialog box.
	Toggles the appearance of the profile between solid to wired (default).
	Resets the manipulations of translation, rotation and zoom to the default view.

Position, size and rotation angle are also displayed within the 3D Profile Settings dialog box. Here you can input numerical values to define the 3D Profile appearance:

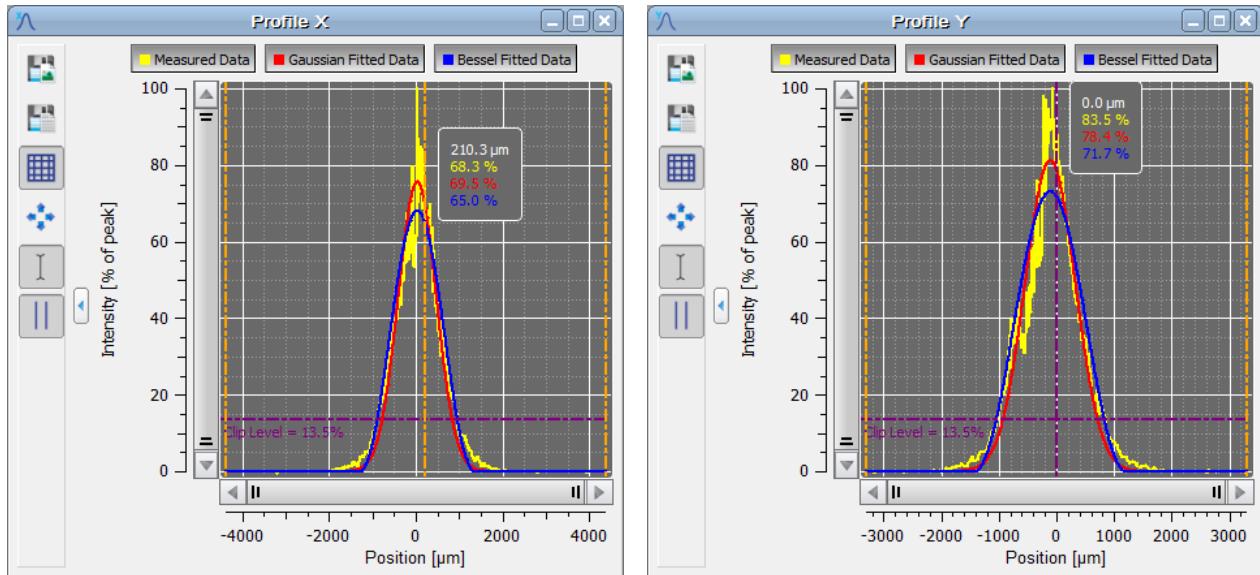
**Note**

- If the slider "Speed - Quality" is in the far right position, the 3D image is displayed with highest quality, i.e., with full resolution.
- The higher the 3D image quality is set, the more system resources are used. Depending on the system capabilities, the software may slow down.

4.6.3 X and Y Profiles

Each of the two windows can be opened and closed via the menu item "X Profiles" or "Y Profiles" in the window menu or clicking on the appropriate toolbar symbols.

The windows can also be closed via the X button in the upper right corner of the child window.



The X profile displays a single pixel row taken from the received camera image, while the Y profile shows a single pixel column. The column and row are defined by the position of cross hair within the [2D Projection](#)⁵⁵ graph.

The yellow curve shows the measured profile, while the red curve shows the approximated [Gaussian](#)¹⁶⁷ fit function and the blue - the approximated [Bessel](#)¹⁶⁸ fit. The curves can be shown / hidden by toggling the appropriate button above the diagram.

If "Autoscale to Peak" is enabled and the cross hair in 2D projection is fixed to peak, the measured curve shows relative intensities from 0 to 100%, where 100% denotes the maximum value in the selected row / column.

If the "Autoscale to Peak" function is disabled, the X and Y profiles will show a peak amplitude equal to the AD converter saturation.

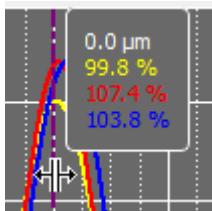
The amplitude of the Gaussian fit curve may be lower or even higher than the peak intensity of the measured curve.

The selected clip level (default 13.5%) is displayed if the "Auto Scale to Peak" function is enabled (button).

The horizontal scale is displayed in pixels or μm and its range refers to the selected [Region of Interest](#)⁴⁵. The unit of the scale can be changed in the [Beam Settings / Unit](#)⁵¹ dialog.

Toolbar Icon	Associated Action
	Opens a dialog box to specify the properties of the saved screenshots / diagrams.
	Opens a dialog box to save measurement data to XLS or CSV file.
	Toggle button to display grid in the diagram. Default: grid is shown.
	Zoom Home button
	Cursor mode - toggle button to show or hide the cursor.
	Show / Hide calculation area

Cursor Mode



Move the mouse pointer close to the vertical cursor line. The mouse pointer changes to . The cursor line can be moved with the left mouse button pressed to a position inside the diagram. The current values at the cursor position are shown in a rectangle next to the cursor in the colors of the plotted curve.

4.6.4 Zooming and Panning Diagrams

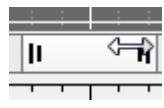
All diagrams, e.g. X and Y profiles, plot diagrams, M² and divergence diagrams, that have a slider, can be manipulated for X and Y scale (zoom) as well as for X and Y positioning (pan).

Zoom Mode

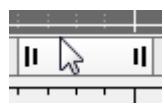
To zoom in the diagram, draw a rectangle with the left mouse button pressed. Right clicking the diagram undoes last zoom action.

 Zoom Home button returns to display of the complete diagram.

Zooming the Diagram Axes

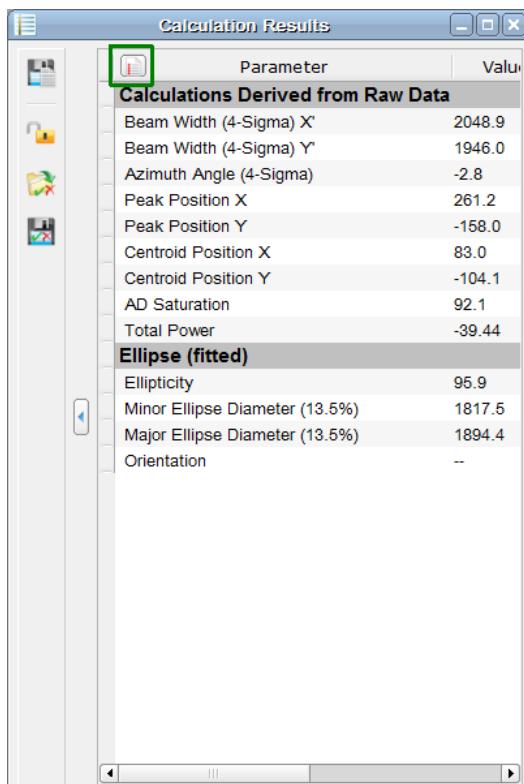
 Move the mouse cursor over an edge of the vertical or horizontal scroll bar slider. The cursor changes to $\uparrow\downarrow$ or $\leftarrow\rightarrow$. Press and hold left mouse button and move the mouse. This will zoom in on the appropriate part of the diagram axis. Return to default view using the Zoom Home button.

Panning the Diagram Axes

 Move the mouse pointer over the center of the vertical or horizontal scroll bar slider and press left mouse button. Now the slider can be moved to pan (shift) across the diagram. Return to default view using the Zoom Home button.

4.6.5 Calculation Results

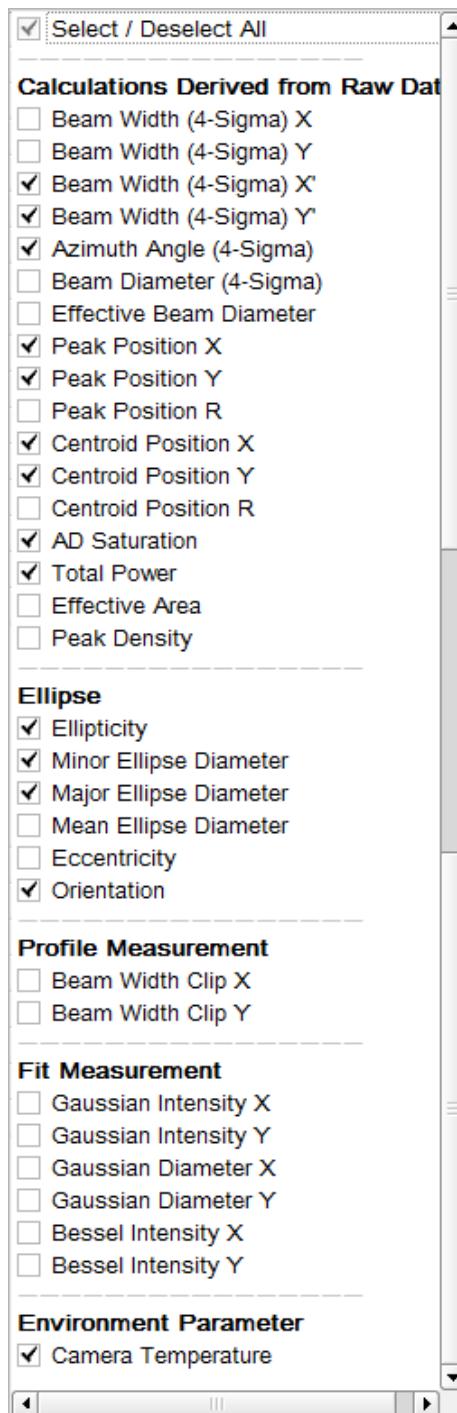
In this window the results of the calculations are displayed. It can be opened and closed via the menu item "Calculation Results" in the window menu or via the toggle button in the toolbar .



The screenshot shows a software window titled "Calculation Results". On the left is a toolbar with icons for file operations. The main area contains a table with two sections: "Calculations Derived from Raw Data" and "Ellipse (fitted)". The first section lists parameters like Beam Width (4-Sigma) X' and Y'. The second section lists parameters like Ellipticity, Minor/Ellipse Diameter, Major/Ellipse Diameter, and Orientation. A green square box highlights the first column header "Parameter".

Parameter	Value
Calculations Derived from Raw Data	
Beam Width (4-Sigma) X'	2048.9
Beam Width (4-Sigma) Y'	1946.0
Azimuth Angle (4-Sigma)	-2.8
Peak Position X	261.2
Peak Position Y	-158.0
Centroid Position X	83.0
Centroid Position Y	-104.1
AD Saturation	92.1
Total Power	-39.44
Ellipse (fitted)	
Ellipticity	95.9
Minor Ellipse Diameter (13.5%)	1817.5
Major Ellipse Diameter (13.5%)	1894.4
Orientation	--

The width of the columns is predefined but can be resized. With the first start of the Beam Software, the parameters as shown above are displayed in this table. Click the marked green  icon in the table in order to select or deselect parameters to be calculated and displayed. The fewer calculation results are enabled, the higher the speed performance of the software.



Note

- Even if the Gaussian and / or Bessel Fit calculations are disabled from display in the Calculation results panel, the appropriate fitted curves are still shown in the X and Y Profile windows, if enabled there.
- Centroid Position: This parameter is very sensitive to ambient light which may shift the calculated centroid! See [Ambient Light Correction](#)^[37].

The units of the calculations can be changed in [Beam Settings / Unit](#)^[51].

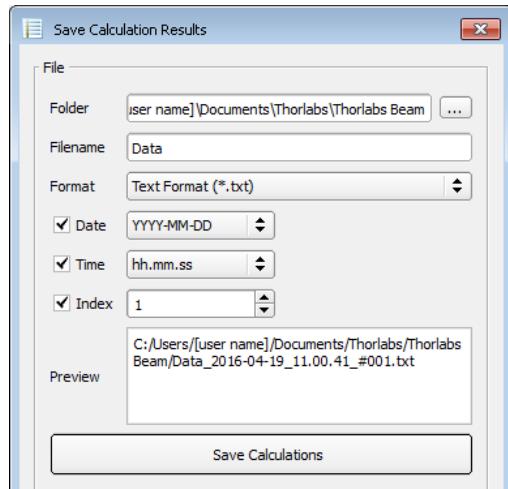
If a calculation failed the value turns to "--".

For details on these parameters, please see section "[Application Note](#)^[164]"

Handling of Calculation Results and Settings

Toolbar Symbol	Associated Action
	Save Calculation Results
	Lock / Unlock Test Parameters
	Load Test Parameter Configuration
	Save Test Parameter Configuration

Save Calculations opens a dialog box:



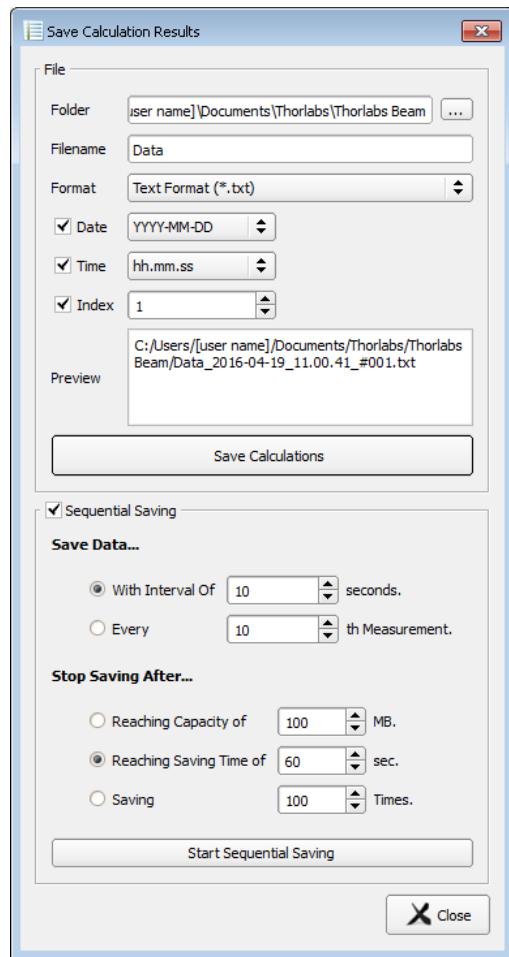
- Select the destination folder (see the preview pane)
- Define the file name
- Select file format (*.txt, *.csv or *.xls)
- Add date, time stamp, index (optional)
- Click "Save Calculations"

Lock / Unlock Test Parameters; Load / Save Test Parameter Configuration.

These functions are related to the configuration of the [Pass / Fail Test](#)^[84] functionality.

Sequential Saving

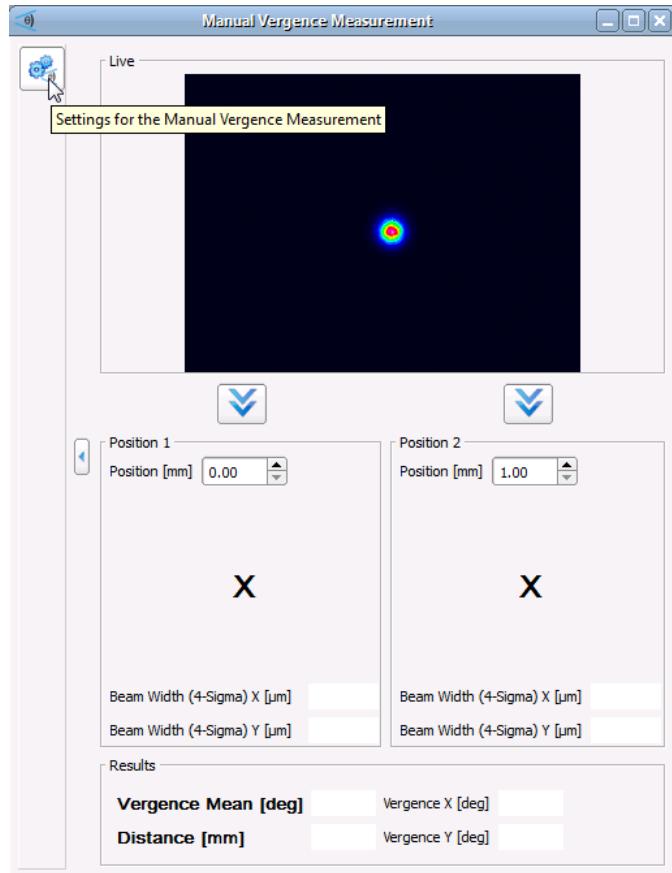
This feature is used to save sequentially sets of the [selected calculation results](#)⁶², e.g for a long term analysis.



- Select the destination **folder** (see the preview pane).
- Define the file name.
- Select the export format.
- Add date and/or time stamp (optional)
- **Save Data...** Select either
 - the time interval between two records (1 to 10^6 sec.) or
 - the n-th measurement to be recorded (n = 1 to 10^5)
- **Stop Saving after...** Define when the sequential saving shall be terminated:
 - after reaching a certain file size (1 to 100 MB)
 - after reaching a certain recording time (1 to 10^6 sec.)
 - after reaching a certain number of data sets (1 to 10^5)
- Click "Start Sequential Saving"

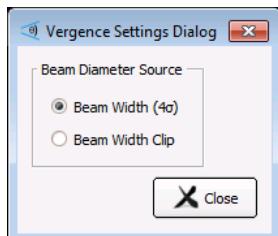
The data sets are recorded to one single file, with each new record appended to the previously recorded data sets.

4.6.6 Manual Vergence Measurement



Vergence refers to the divergence or convergence angle of a light beam. The manual vergence measurement allows this angle to be measured using a simple mechanical setup. The Beam Profiler is mounted so that it can slide along the beam propagation trace. This can be done using, for example, a Thorlabs M2 translation stage or a Thorlabs dovetail optical rail (RLA series) in combination with a rail carrier (RC series) and a post.

Open the Manual Vergence Measurement Window either by selecting the appropriate item from the Menu bar (Windows → Manual Vergence Measurement) or simply by clicking the  icon:



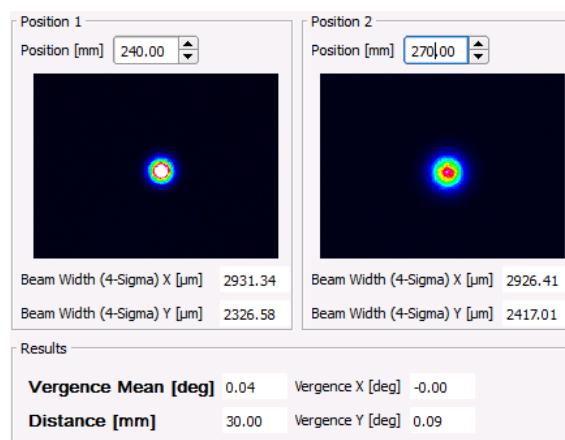
1. Click the  icon in the left upper corner to open "Settings for the Manual Vergence Measurements". Select the beam diameter calculation method. Measure the distance between the light source and the front plane of the Beam Profiler and enter this value to the box "Position 1" in millimeters and click the  icon.

 Position 1 Position [mm] <input type="text" value="240.00"/>	 Position 2 Position [mm] <input type="text" value="241.00"/>
--	--

2. The software calculates the beam width at position 1.



3. Move the Beam Profiler, measure the distance again, enter the new distance into the box "Position 2" and press the 2nd icon.
4. The beam width at position 2 is calculated and based on the entered distance change, the vergence angle in X and Y axes is displayed.



Note

The accuracy of the entered distance between the two positions (shift) of the Beam Profiler is significant for vergence measurement accuracy.

Hint

If you are using the Beam Profiler together with a M2MS Extension Set, i.e. within a M2MS-BC106x measurement system, the Manual Vergence measurement is even more simple:

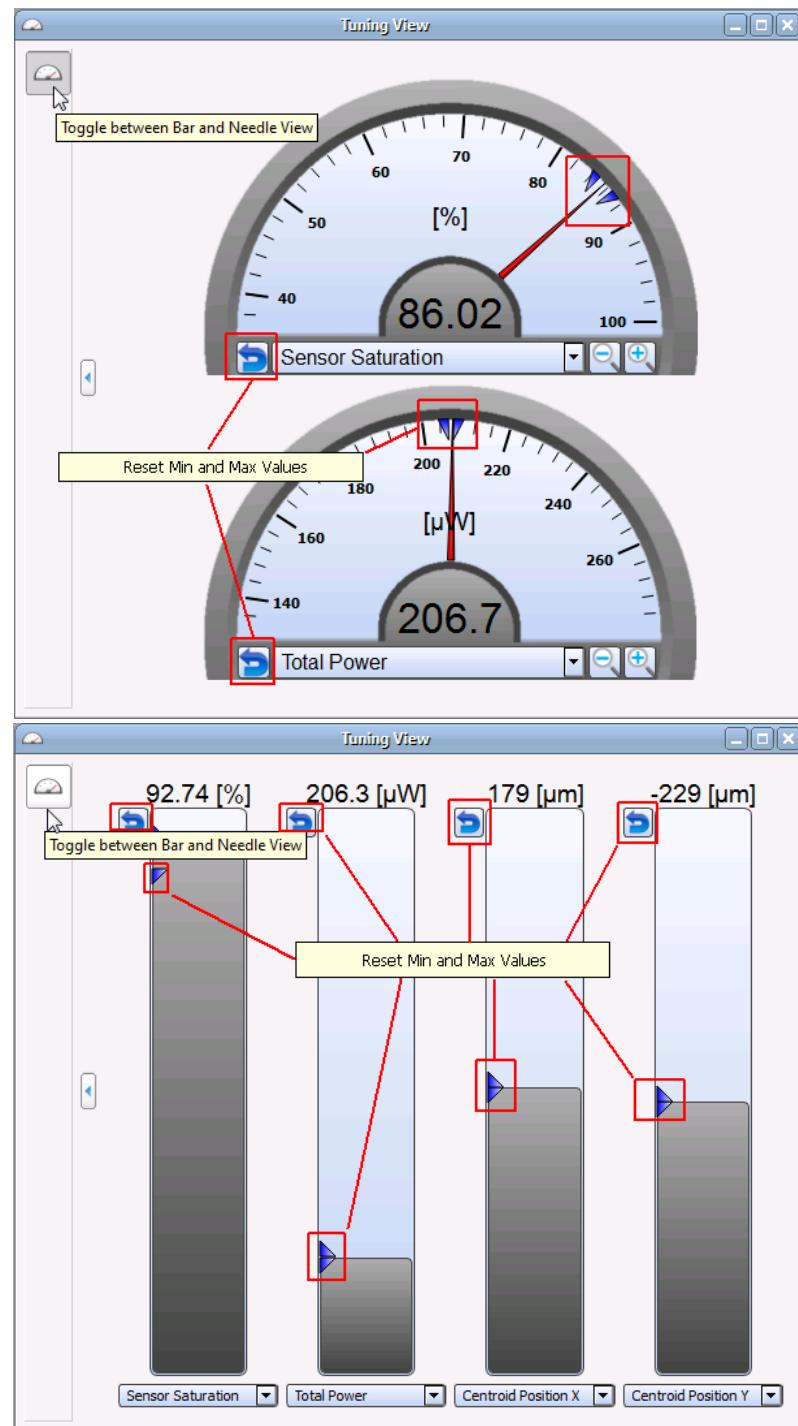
- Remove the focusing lens from the system.
- Feed the laser beam into the M2MS-BC106x input aperture and align it.
- Open in the Beam Settings panel the [Translation Stage Control](#) topic.
- Use the stage slider to set 0 and 200 mm positions and proceed as described above.

4.6.7 Tuning View

The Tuning View child window allows selectable values to be displayed in an analog way, which can be helpful for adjusting the optical setup.

Select from the Menu bar (Windows -> Tuning View) or simply click the  icon. The tuning view can display either two needle scales or 4 bar graphs. Each scale or graph can be assigned to one of the following parameters:

- Sensor Saturation
- Total Power
- Ellipticity
- Beam Width 4σ (X)
- Beam Width 4σ (Y)
- Peak Position X
- Peak Position Y
- Centroid Position X
- Centroid Position Y
- Ellipse Diameter min.
- Ellipse Diameter max.
- Beam Width Clip X
- Beam Width Clip Y

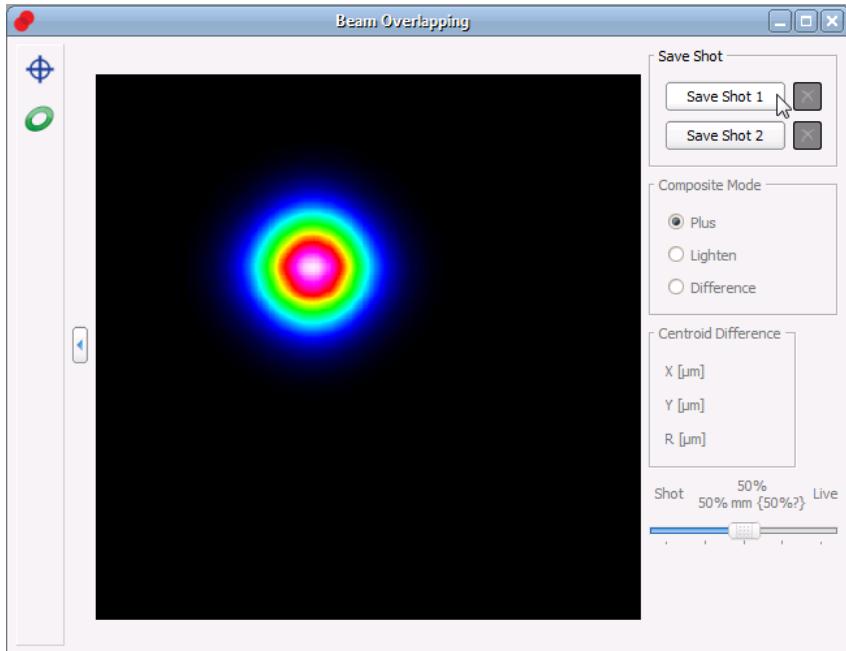


On the scales, the observed minimum and maximum values are shown as blue triangles. They can be reset using the buttons marked above.

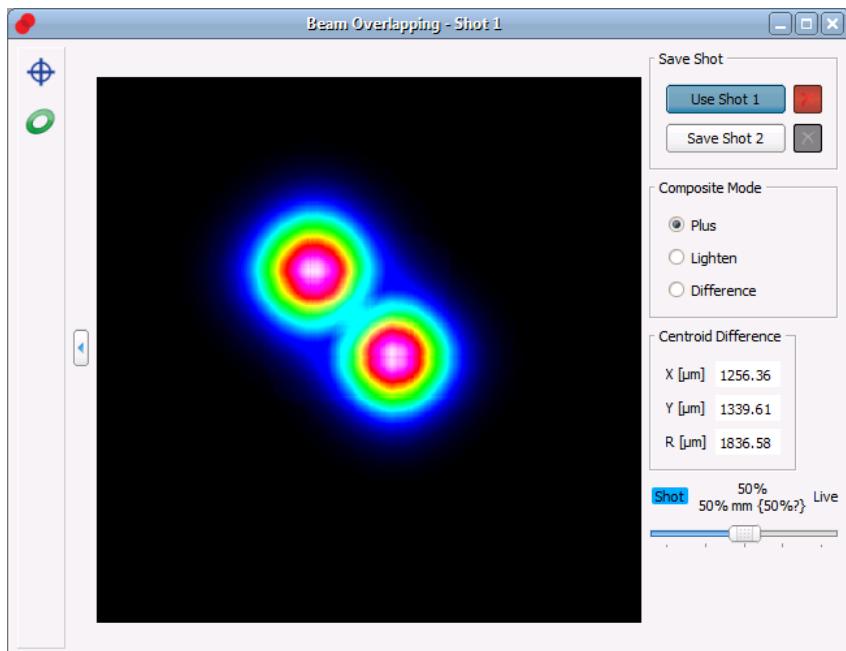
4.6.8 Beam Overlapping

The Beam Overlapping tool is useful to for adjusting the location of a light beam. For example, two sources can be adjusted in such way that their spots overlap at a certain location and are concentric.

Select from the Menu bar (Windows -> Beam Overlapping) or simply click the  icon.

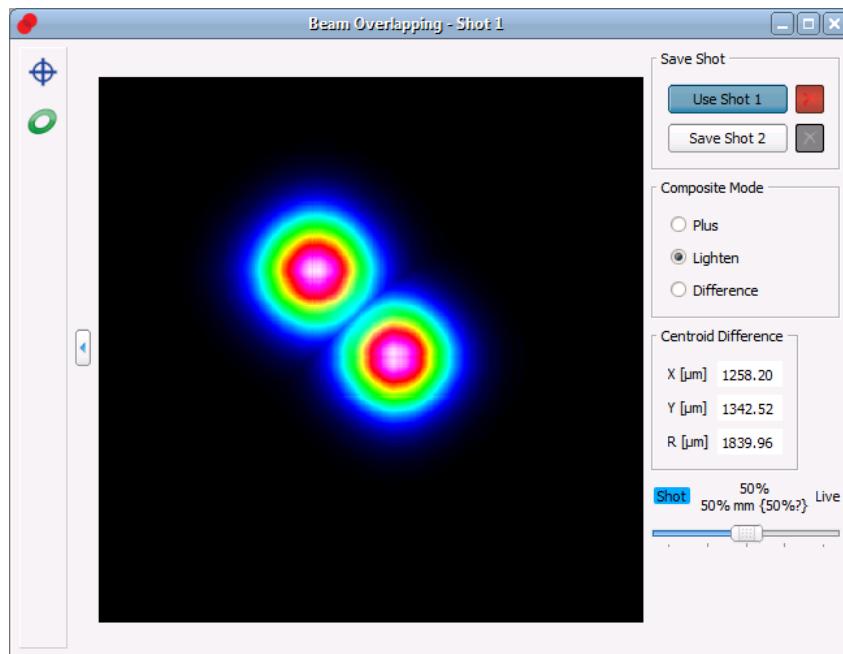


Take a snapshot of the reference position by clicking to the button "Save Shot 1" or "Save Shot 2". The software instantly starts to overlay the live image from the Beam Profiler with the captured snapshot. The overlay method can be selected in the box "Composite Mode":



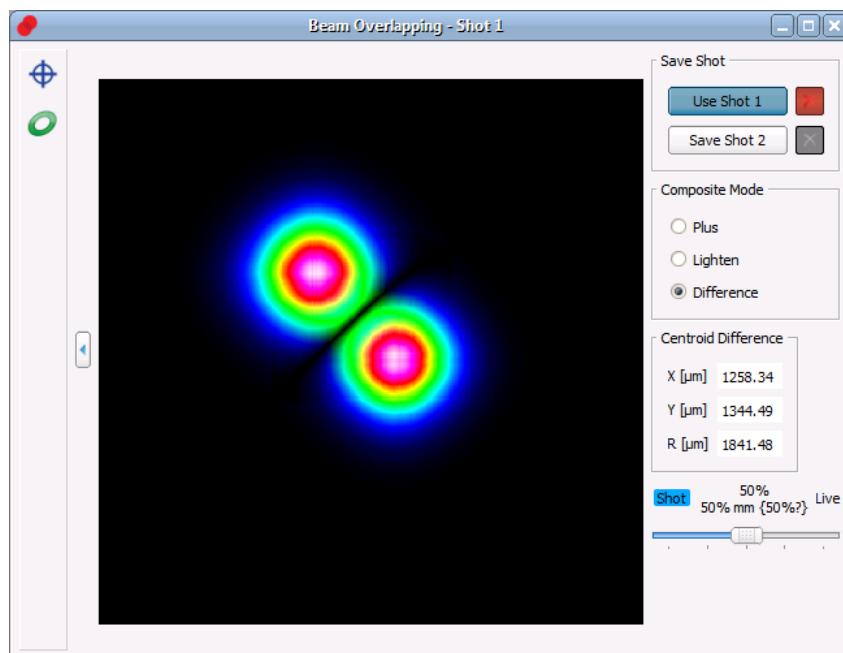
Overlay "Plus"

In "Plus" mode the intensities of the snap shot and the live image are added. This eases the adjustment particularly of regions with lower intensity.



Overlay "Lighten"

In "Lighten" mode, within the overlapping region only the "pixel" with higher intensity will be displayed; the intensities of the snapshot and the current beam are not added.



Overlay "Difference"

Finally, in the "Difference" mode, the intensities are subtracted. The more regions appear black within the overlay, the better the live image fits to the snapshot.

The centroid shift between snapshot and live image is displayed in X and Y axis direction, R is the resulting absolute distance between these centroids.

For improved visualization of the overlay, the intensities of the snapshot and the live image can be weighted in 25% steps (slider).

4.6.9 Plots

Thorlabs Beam software offers several additional plot windows to show the beam behavior:

[Plot Positions](#)  73

[Plot Power](#)  74

[Plot Gaussian Fit](#)  75

[Plot Orientation](#)  76

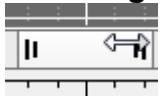
[Plot Environment Data](#)  77

[Beam Stability](#)  78

All plot windows are accessible via the "Windows" menu, while **Plot Positions**, **Plot Power** and **Beam Stability** also have buttons in the toolbar. The diagrams can be cleared using the "Clear Windows" command (Menu Bar -> Control or  button).

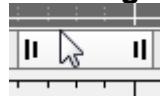
Convenient view functions allow a detailed analysis of the parameter's behavior over time.

- **Display / Hide** a certain parameter: Appropriate buttons are located above the diagrams.
- **Zoom Out**: Press and hold left mouse button and mark the desired diagram area.
- **Undo Zoom**: Right click on the diagram to reproduce the previous zoom status.
- **Zooming Diagram Axes**



Move the mouse cursor over an edge of the vertical or horizontal scroll bar slider. The cursor changes to  or . Press and hold left mouse button and move the mouse. This will zoom in on the appropriate part of the diagram axis. Return to default view by right clicking to the diagram.

- **Panning the Diagram Axes**



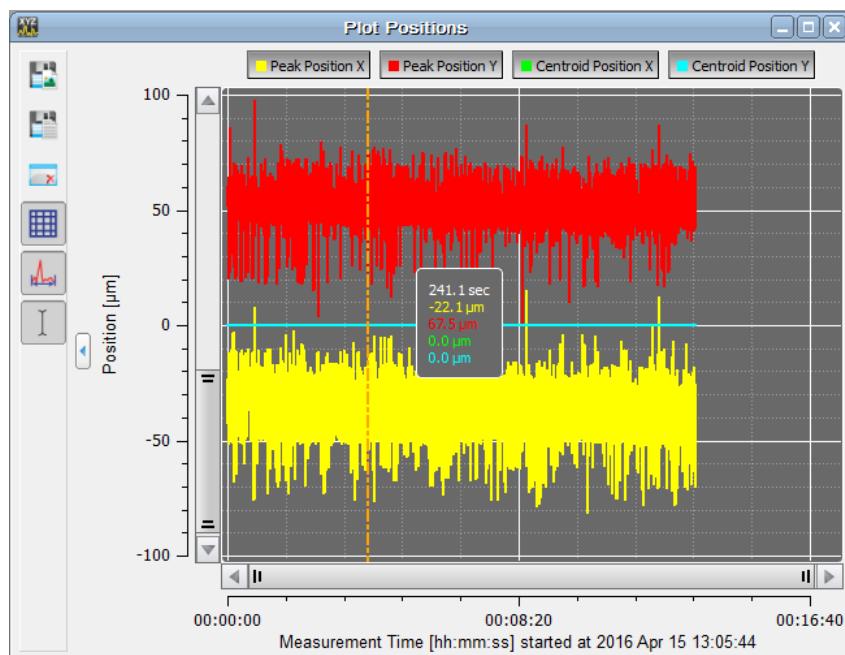
Move the mouse pointer over the center of the vertical or horizontal scroll bar slider and press left mouse button. Now the slider can be moved to pan (shift) across the diagram. Return to default view using the Zoom Home button.

- **Autoscale**: This button in the left toolbar returns the diagram to default view (auto scaled)
- **Cursor Mode**: If the mouse position is near to the vertical cursor line, the mouse cursor changes to . The cursor line can be moved with the left mouse button pressed to a position inside the diagram. The current values at the cursor position are shown in a rectangle next to the cursor in the colors of the plotted curve.

The individual plot windows are explained in detail in the next sections.

4.6.9.1 Plot Positions

Toolbar:  , Menu bar: Windows -> Plot Positions

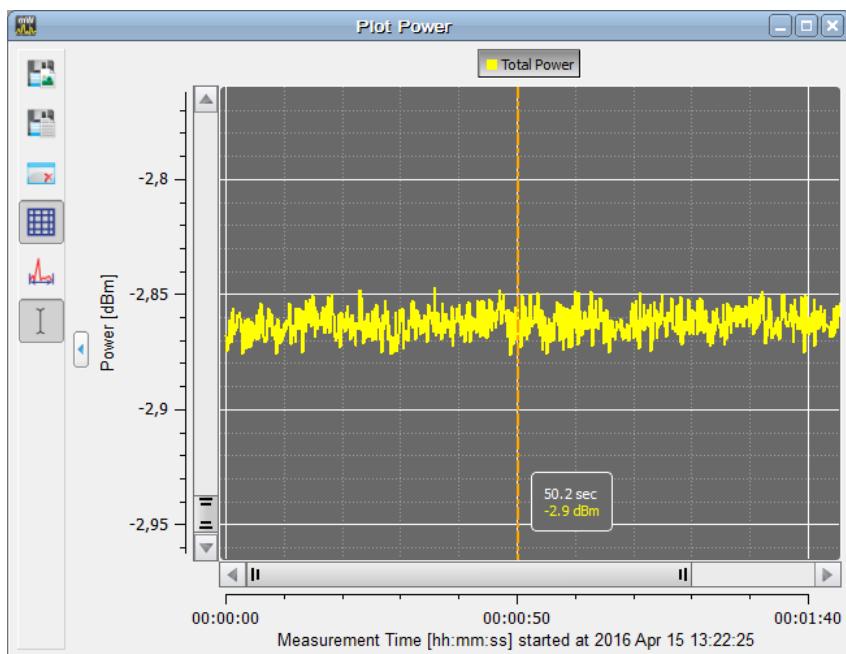


The positions of X and Y peak and of X and Y centroid positions can be displayed vs. time.

Toolbar Icon	Associated Action
	Save Diagram or Image: Opens a dialog box to specify the properties of the saved diagram or image.
	Save Data: Opens a dialog box to specify the properties of the saved calculation data
	Clear all plots
	Show or Hide the grid in the diagram:
	Autoscale ON/OFF
	Show or hide the cursor

4.6.9.2 Plot Power

Toolbar:  Menu bar: Windows -> Plot Power



The total power measured by the Beam Profiler vs. time can be displayed.

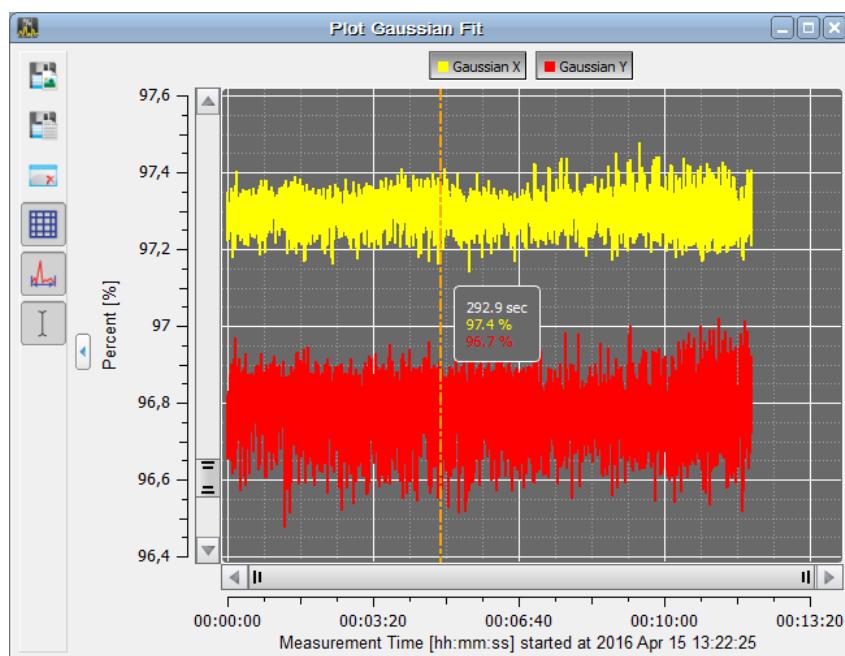
Note

The power indication of Thorlabs Beam Profiler instruments is not calibrated vs. wavelength, it is based on a typical responsivity curve of the used sensor and the manually entered wavelength (see [Optical Setup / Wavelength](#) [35])

Toolbar Icon	Associated Action
	Save Diagram or Image: Opens a dialog box to specify the properties of the saved diagram or image.
	Save Data: Opens a dialog box to specify the properties of the saved calculation data
	Clear all plots
	Show or Hide the grid in the diagram:
	Autoscale ON/OFF
	Show or hide the cursor

4.6.9.3 Plot Gaussian Fit

Menu bar: Windows -> Plot Gaussian Fit

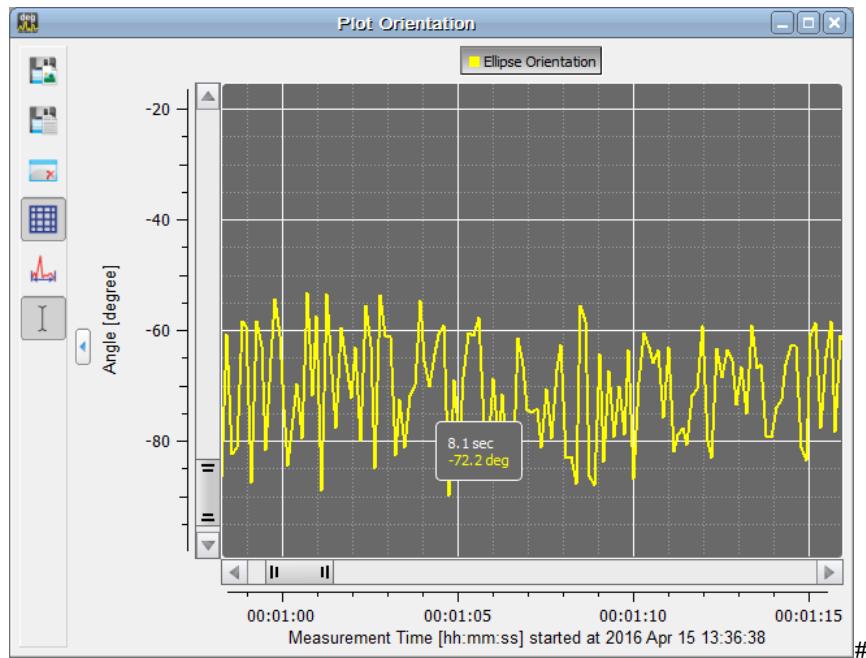


This window plots the Gaussian Intensity value (see [Calculation Results](#)) which shows the coefficient of determination of the fit.

Toolbar Icon	Associated Action
	Save Diagram or Image: Opens a dialog box to specify the properties of the saved diagram or image.
	Save Data: Opens a dialog box to specify the properties of the saved calculation data
	Clear all plots
	Show or Hide the grid in the diagram:
	Autoscale ON/OFF
	Show or hide the cursor

4.6.9.4 Plot Orientation

Menu bar: Windows -> Plot Orientation

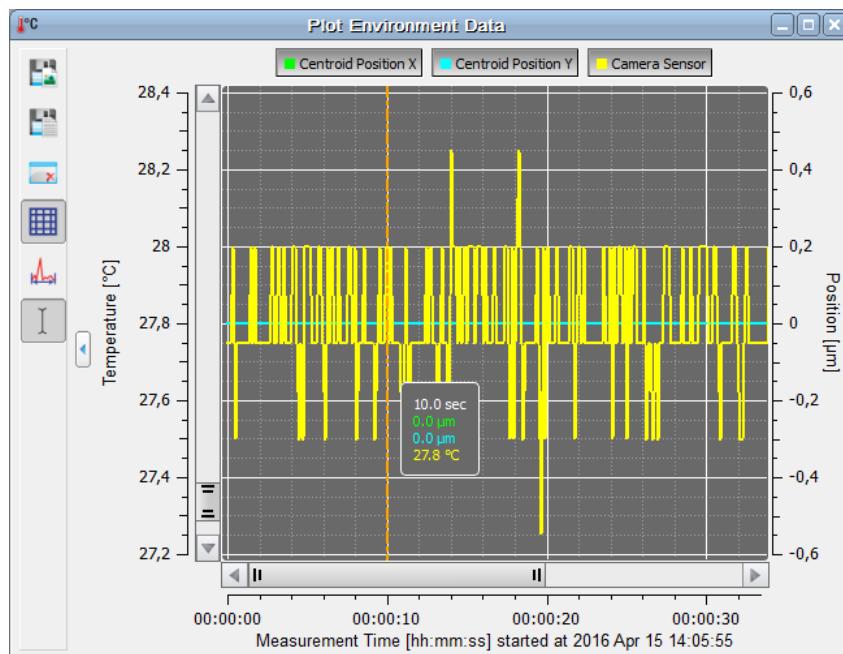


This windows plots the orientation (in degrees) of the ellipse, see [Calculation Results](#) ^[62].

Toolbar Icon	Associated Action
	Save Diagram or Image: Opens a dialog box to specify the properties of the saved diagram or image.
	Save Data: Opens a dialog box to specify the properties of the saved calculation data
	Clear all plots
	Show or Hide the grid in the diagram:
	Autoscale ON/OFF
	Show or hide the cursor

4.6.9.5 Plot Environment Data

In this window the position of the X and Y centroids can be logged together with the reading of the camera's internal temperature sensor vs. time.

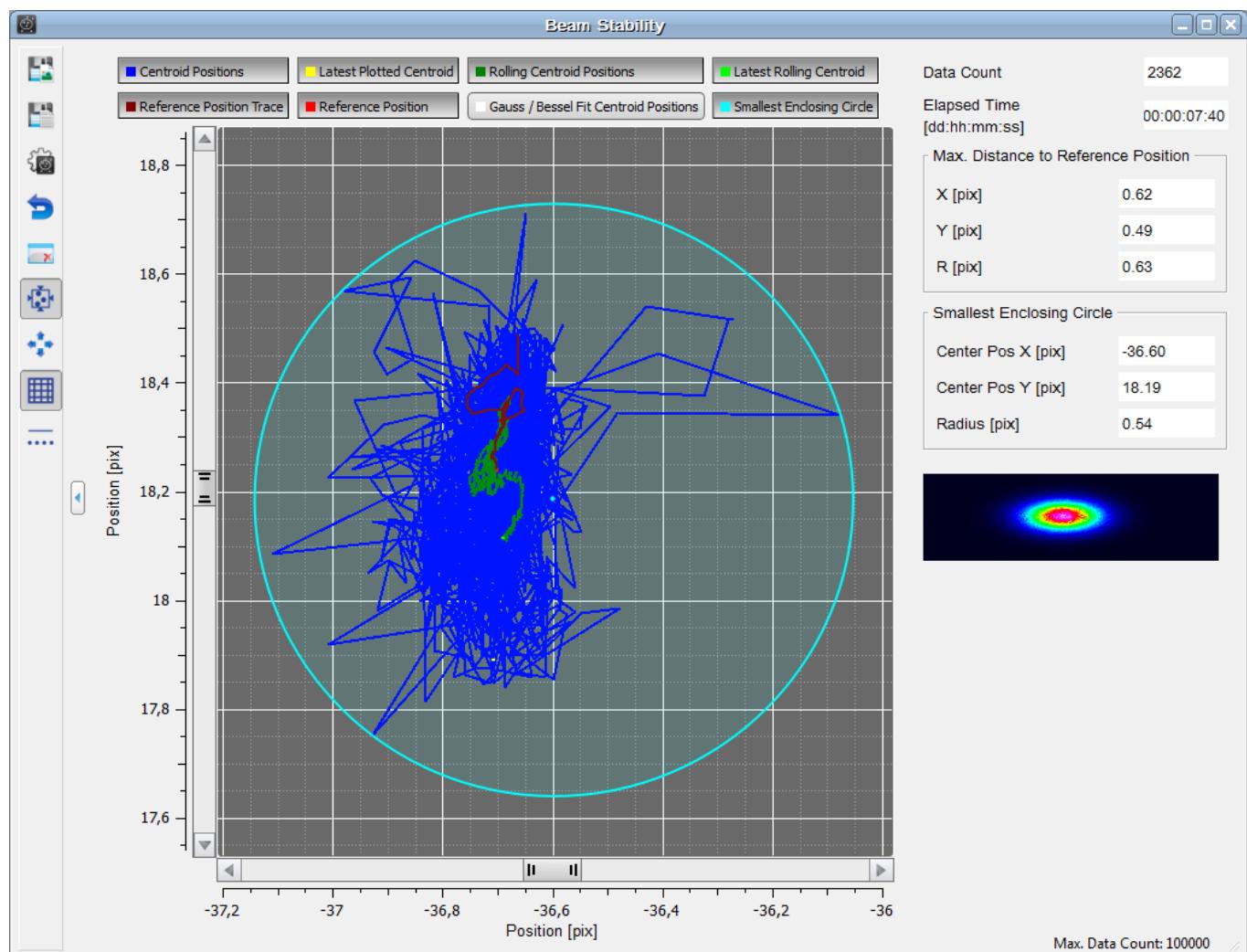


The temperature axis is located to the left (yellow curve), the centroid position axis (blue and green curves) is shown to the right.

Toolbar Icon	Associated Action
	Save Diagram or Image: Opens a dialog box to specify the properties of the saved diagram or image.
	Save Data: Opens a dialog box to specify the properties of the saved calculation data
	Clear all plots
	Show or Hide the grid in the diagram:
	Autoscale ON/OFF
	Show or hide the cursor

4.6.9.6 Beam Stability

Toolbar: , Menu bar: Windows → Beam Stability



This feature allows the beam stability vs. time to be recorded in a very versatile way. Accumulated data can be retrieved in graphic display by enabling several plots:

<input checked="" type="checkbox"/> Centroid Positions	Plots the trace of the centroid positions as blue line
<input type="checkbox"/> Latest Plotted Centroid	Plots the most recent centroid position as yellow dot
<input type="checkbox"/> Rolling Centroid Positions	Plots the trace of the rolling centroid positions ⁴⁹ as a dark green line
<input type="checkbox"/> Latest Rolling Centroid	Plots the most recent rolling centroid position as a bright green dot
<input type="checkbox"/> Reference Position Trace	Plots the trace of the reference positions ⁷⁹ as dark red line
<input type="checkbox"/> Reference Position	Plots the reference position as a bright red dot
<input type="checkbox"/> Gauss_Bessel Fit Centroid Positions	Plots the Gauss / Bessel fitted centroid positions
<input type="checkbox"/> Smallest Enclosing Circle	Plots the smallest enclosing circle around centroid position cloud
<input type="checkbox"/> Centroid Positions	Plot disabled
<input checked="" type="checkbox"/> Centroid Positions	Plot enabled

Most of the beam stability characteristics are given in numerically:

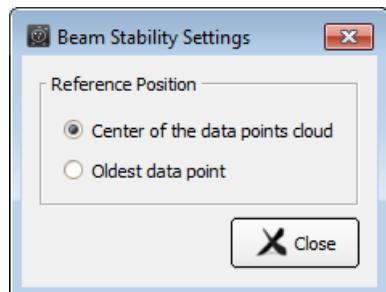
Data Count: The actual count of displayed measurement results.

Elapsed Time: Time since last start of stability measurement

Max. Distance to Reference Position of the centroid positions is given in distance (X), distance (Y) and as radial distance (R). The reference position can be defined in the Settings Dialog (see below the [table](#) 79) as either the oldest centroid position or the center of the centroid positions data cloud.

Toolbar Icon	Associated Action
	Save Diagram or Image: Opens a dialog box to specify the properties of the saved diagram or image.
	Save Data: Opens a dialog box to specify the properties of the saved calculation data
	Shows the Settings Dialog (see below)
	Reset Data: Clears Beam Stability data only
	Stops and restarts the measurements, clears all accumulated plot data
	Sets the zoom factor so that all data points are located within the diagram area
	Zoom out to the entire sensor area
	Show or Hide the grid in the diagram:
	Display results as dots or wired

Settings Dialog



Reference Position: Reference for calculation of beam stability. Can be set to the center of the data cloud or to the oldest displayed data point.

Note

The maximum number of data points to be displayed, the handling of data points after reaching the maximum and the time interval between two displayed data points is set in the menu [Beam Settings / Plot over Time Parameter](#) 52.

5 Measurement with the Beam Profiler

General Guidelines for Operating the Camera Beam Profiler BC106N

To achieve correct and reliable measurement results, it is recommended that these basic guidelines are followed.

1. Provide stable mounting of the Beam Profiler using the appropriate threads on its base plate.
2. Be sure to operate the instrument within its allowed [Power Range](#)¹⁷⁵.
3. Choose a neutral density (ND) filter out of the [Filter wheel](#)¹⁹ which is suited for the operating wavelength (UV / VIS) of your light source.
4. Select a filter attenuation which is adapted to the applied laser power.
5. Align the beam to be measured so that it is perpendicular to the front face of the Beam Profiler.
6. Minimize ambient light entering the Beam Profiler aperture, use a high loss ND filter for its attenuation.
7. Perform a [Ambient Light Correction](#)³⁷ in case of weak light sources compared to the ambient power level.

Attention

Do not stick anything into the Beam Profiler aperture if the protection glass is removed. The windowless image sensor chip might be damaged.

Prevent dust or other contamination from entering the aperture!

Keep beam power below the allowed limit to avoid damage to the instrument!

For accurate power measurements:

1. Enter the correct [operating wavelength](#)³⁵.
2. Enter the [attenuation](#)³⁶ of the chosen ND filter.
3. Perform a [Power Correction](#)³⁶

Performance Optimization

As soon as a BC106N device is selected within the 'Device Selection' panel, the measurement starts in the continuous mode. It may be advantageous to stop the continuous measurement for a detailed analysis of a beam profile captured with the last image. Also, user interactions with the GUI will work more fluently when the continuous flow of image data is stopped.

Measurement speed of the Camera Beam Profiler depends on various device settings like Fast/Precision mode, image resolution (ROI) and the selected exposure time. Also the number of open child windows used to visualize the measured results and the number of activated numerical parameters to be calculated may reduce the available display update rate, depending on the performance of your PC.

Note

1. For accurate measurement results (power values, M² results) the correct wavelength must be entered. Thorlabs Beam Profiler instruments are not calibrated for power with respect to the wavelength. The power calculation is based on a typical responsivity curve of the used sensor and manually entered wavelength (see [Beam Settings / Optical Setup](#)³⁵)
2. Ensure that the beam power is within the specified [power range](#)¹⁷⁵.
3. Align the laser beam so that it is perpendicular to the front panel.

5.1 Operating the Instrument

Be sure that the Camera Beam Profiler is connected to the PC and the driver is installed properly as described in chapter [Connection to the PC](#)^[16].

Start the Thorlabs Beam Application 7.0.

At the initial program start, the GUI opens and displays the Beam Settings panel, the Calculation Results, 2D Projection and 3D Profile. Child windows can be opened and closed via the entries in the menu "Window" or via the symbols in the toolbar of the main window. The activated windows can be sized and arranged as desired.

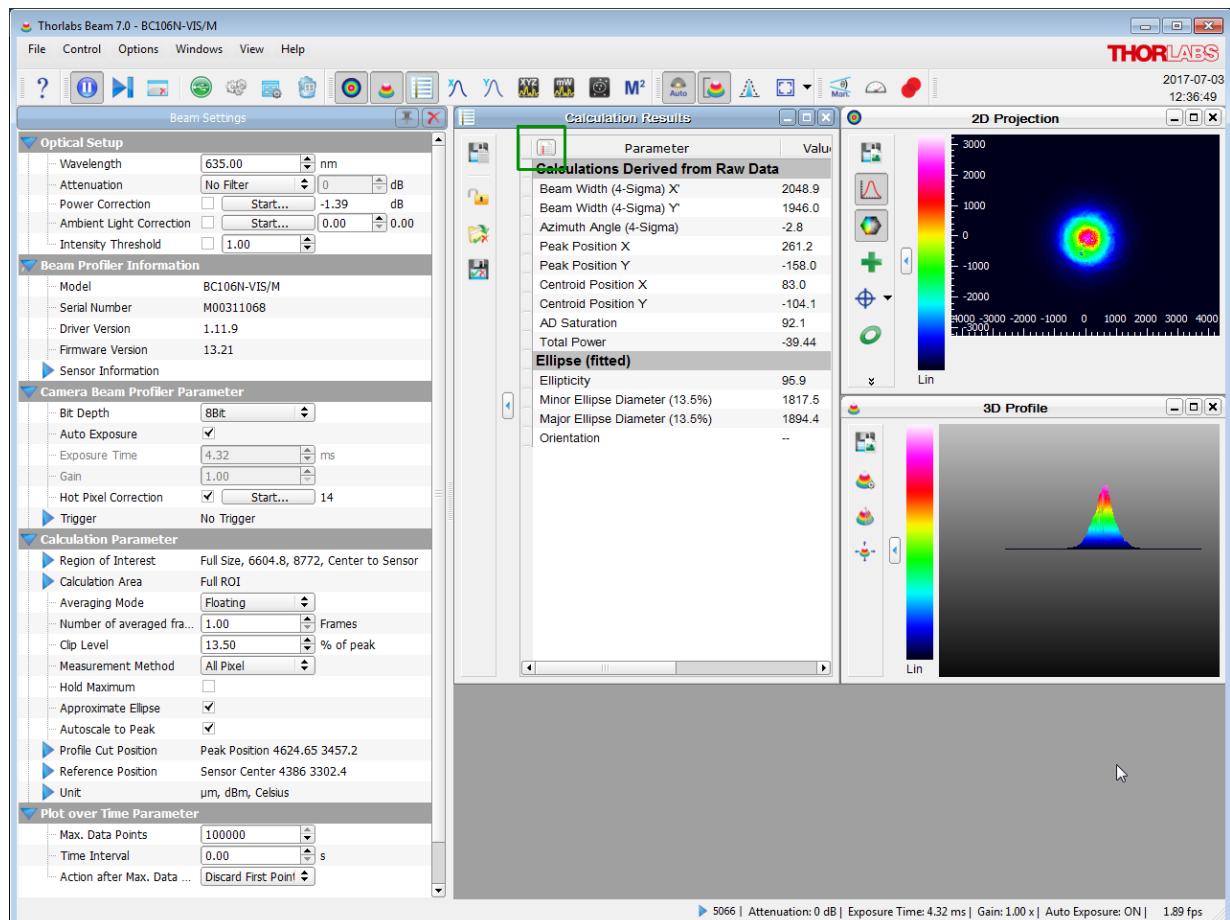
The recognized Beam Profiler will be connected automatically, and the continuous image acquisition starts.

If more than one device was recognized during the initial application start, the first recognized device will be connected and started. Please see section [Start the Application](#)^[17] for details on how to select a different device.

Verify the settings in the section [Optical Setup](#)^[35] if you have started the Beam software for the 1st time. More details on the hardware settings please see the [Camera Beam Profiler Parameter](#)^[40] section

Note

The configuration of child windows is saved when the BEAM software is exited. When the BEAM software is next opened, these windows and their last positions and appearances are restored. Also, the most recent device selection will be restored when restarting the BEAM application, together with the most recent settings that were made in the settings panel.



The child window [2D Projection](#)⁵⁵ shows the measured intensity distribution across the sensor area in gray or color scale whereas the [3D Profile](#)⁵⁸ is plots the beam intensity with respect to the 3rd dimension (Z scale). Numerical calculation results are displayed in the appropriate [Calculation Results](#)⁶² window. The parameters to be calculated can be selected by clicking the  icon in left upper corner the [Calculation Results](#)⁶² window.

All contents of the child windows including available options are explained in chapter [Child Windows](#)⁵⁴.

5.2 Pass/Fail Test

The Calculation Results panel includes a pass/fail test.

	Parameter	Value	Unit	Test	Min.	Max.
Calculations Derived from Raw Data						
	Beam Width (4-Sigma) X	2983.33	µm	Pass	<input checked="" type="checkbox"/> 2900.00	<input checked="" type="checkbox"/> 3100.00
	Beam Width (4-Sigma) Y	3039.07	µm	Pass	<input checked="" type="checkbox"/> 2900.00	<input checked="" type="checkbox"/> 3100.00
	Beam Diameter (4-Sigma)	3010.45	µm		2900.00	3100.00
	Peak Position X	-19.53	µm		0.00	0.00
	Peak Position Y	53.56	µm		0.00	0.00
	Centroid Position X (Reference Position)	0.00	µm		0.00	0.00
	Centroid Position Y	0.00	µm		0.00	0.00
	AD Saturation	85.71	%	Pass	<input checked="" type="checkbox"/> 80.00	<input checked="" type="checkbox"/> 95.00
	Total Power	0.36	mW	 Fail	<input checked="" type="checkbox"/> 0.50	<input checked="" type="checkbox"/> 0.75
Ellipse (fitted)						
	Ellipticity	99.44	%	Pass	<input checked="" type="checkbox"/> 95.00	<input checked="" type="checkbox"/> 100.00
	Minor Ellipse Diameter (13.5%)	2716.25	µm	Pass	<input checked="" type="checkbox"/> 2600.00	<input checked="" type="checkbox"/> 2800.00
	Major Ellipse Diameter (13.5%)	2731.49	µm	Pass	<input checked="" type="checkbox"/> 2600.00	<input checked="" type="checkbox"/> 2800.00
	Eccentricity	10.55	%		0.00	0.00
	Orientation	--	deg		0.00	0.00
Profile Measurement						
	Beam Width Clip X (13.5%)	2689.34	µm	Pass	<input checked="" type="checkbox"/> 2600.00	<input checked="" type="checkbox"/> 2800.00
	Beam Width Clip Y (13.5%)	2699.78	µm	Pass	<input checked="" type="checkbox"/> 2600.00	<input checked="" type="checkbox"/> 2800.00
Fit Measurement						
	Gaussian Intensity X	97.37	%		0.00	0.00
	Gaussian Intensity Y	96.98	%		0.00	0.00
	Gaussian Diameter X	2527.47	µm		0.00	0.00
	Gaussian Diameter Y	2505.24	µm		0.00	0.00
	Bessel Intensity X	93.00	%		0.00	0.00
	Bessel Intensity Y	92.52	%		0.00	0.00
Environment Parameter						
	Camera Temperature	24.25	°C	 Fail	<input checked="" type="checkbox"/> 22.00	<input checked="" type="checkbox"/> 24.00

For each parameter a minimum and / or maximum can be set as criteria.

Pass / fail test criteria can be set to "not below minimum", "not above maximum" or "between minimum and maximum" by checking the appropriate boxes in the **Min.** and **Max.** columns.

Test results will be displayed in the column **Test** only for those parameters that are selected as test criteria:



Pass The selected test criteria was fulfilled; test passed.

Fail The test criteria **Min.** was underrun; test failed

Fail The test criteria **Max.** was exceeded; test failed

Note

Please note the following explanations of the parameters.

As per definition, the beam ellipse has a major and a minor axis. For a pass / fail test, for the minor and major ellipse diameter a minimum and maximum value can be entered. In the example given above, the "pass" ranges are:

- Minor axis diameter must be between **Min.** = 2600 and **Max.** = 2800 µm
- Major axis diameter must be between **Min.** = 2600 and **Max.** = 2800 µm

The test is passed only if both conditions are fulfilled.

Handling Pass / Fail Test Settings and Results

Toolbar Symbol	Associated Action
	Save Calculation Results
	Lock / Unlock Test Parameters
	Load Test Parameter Configuration
	Save Test Parameter Configuration

Save Calculations opens a dialog box to enter file properties (name, format, comments). For details please see the [Calculation Results](#) [64] section.

Lock By default, pass/fail test parameters are unlocked. They can be locked in order to prevent manipulation of margins and parameters included in pass/fail test. Optionally, the lock can be secured by entering a password.

Note

A password can be entered only once and cannot be changed! In case of troubles, please contact Thorlabs for a solution.

Load / Save Test Parameter Configuration.

The **Load** and **Save** buttons in the **Calculation Results** toolbar allow you to load and save the configuration of the pass/fail test.

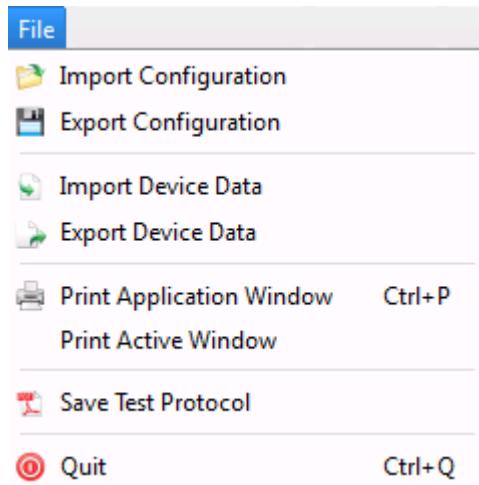
In order to reconstruct a pass/fail test configuration automatically with the next session, save the parameter to a test parameter configuration file. This file will be loaded with the next start of the application. If more than one configuration file is saved, the most recently saved file will be loaded automatically.

To load test parameter from a file click to the "Load Test Parameter" button and select the test parameter configuration file.

5.3 Save Measurement Results

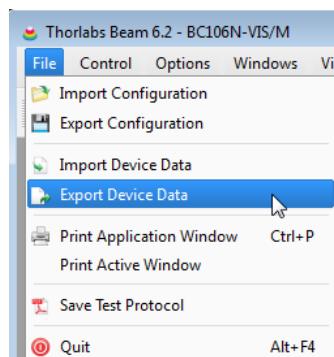
In addition to allowing the [Calculation Results](#)⁶⁴ to be saved, the Beam Software will:

- [Export Device Data](#)⁸⁵
- [Print Windows](#)⁸⁹
- [Save a Test Protocol](#)⁹⁰

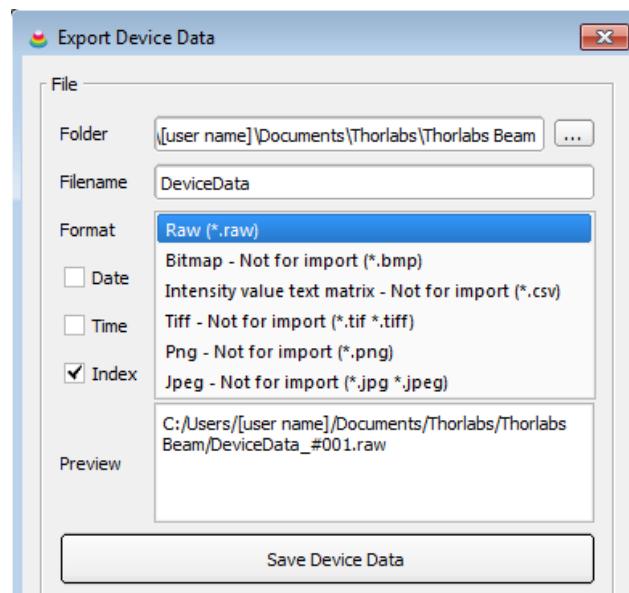


5.3.1 Export Device Data

To export the data to a delimiter separated text document or to an image, select 'File → Export Device Data ...' from the Menu.



A dialog opens and asks for the type of file and the path where to save the file.



Select the desired path and file name and choose the export format.

- *.**raw** is the true image from the camera (intensity value per pixel), with an additional header, including information on pixel pitch and base line. The resolution of the raw data equals to the resolution of the retrieved camera image, i.e., 8 or 12 bit. Raw data can be reloaded into the Beam software and allow to reconstruct the exact image with exception of the total power, because the exposure time cannot be saved within a *.raw file. Raw data format cannot be used for import to standard Windows applications.
- *.**bmp** is the standard uncompressed RGB 24bit bitmap format. Therefore, the retrieved camera data are reduced to a 8 bit resolution and saved to the three color channels. This is necessary to achieve the compatibility of the exported image with the standard and thus, to make it readable by standard picture viewers. *.bmp files can be imported by the Beam software, as this is an uncompressed image format,.
- *.**tiff** For export to the TIFF format, the camera image is reduced, similar to the *.bmp, to 8bit and saved to the RGB channels, resulting in a 24 bit image. TIFF images are loss-free compressed.
- *.**png** The PNG format is based on a loss-free compression. PNG uses four channels - RGB and the alpha channel that comprises the transparency information (here: white =255 for each pixel). For this reason, PNG are compressed 32 bit images.
- *.**jpg** JPEG images are lossily compressed 24bit images. The reduced to a 8 bit resolution camera image is saved to RGB channels and subjected to a memory saving compression.

Note

Compressed images cannot be imported by the Beam software.

Intensity Value Text Matrix

This is a CSV (comma separated values) file format. The comment "Not for import" is related only to importing into the Beam Software: A data file cannot be imported in order to reconstruct a beam profile.

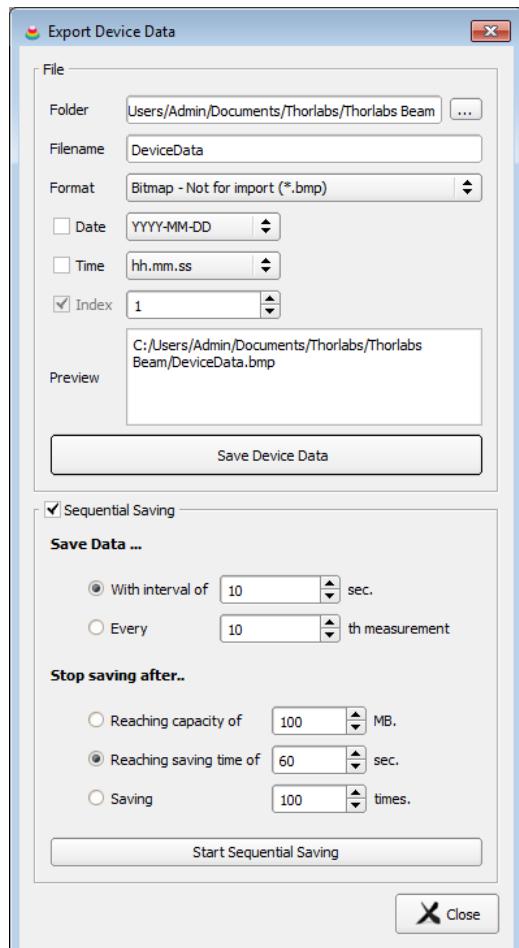
Intensity values are saved to a text matrix with a header:

Thorlabs Beam					
Version: 7.0.4082.298					
Date: 03.07.2017					
Time: 13:22:47					
Device: BC106N-VIS/M					
S/N: M00311068					
Resolution: Fast (8 bit)					
Sensor Resolution [pix]: Width: 1360, Height: 1024					
Pixel Size [μm]: Horizontal: 6.45, Vertical: 6.45					
Region of Interest [pix]: Horizontal: 0, Vertical: 0, Width 1360, Height 1024					
Wavelength [nm]: 635					
Attenuation [dB]: 0					
Exposure Time [ms]: 4.257					
Gain: 1					
Base Level [digits]: 48.762					
3	3	3	3	3	3
3	3	2	3	3	3

The 1st value in the 1st line represents the intensity of the left upper pixel in the 2D Projection.

Sequential Saving

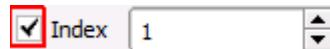
The export of measurement data, described above, can be repeated sequentially, using the Sequential Saving feature on the bottom of the **Export Device Data** panel. This feature generates one single file per data set, with appending the file name created by appending an incremented index. The start index number can be freely selected between 1 and 10000. With each saved measurement, the index is incremented by 1.



- Select the destination **folder** (see the preview pane).
- Enter the base file name.
- Select the export format [export format](#)⁸⁶.
- Add date and/or time stamp (optional)
- Check the box **Index** and define start index.
- Check the box "**Sequential Saving**"
- Save Data... Select either
 - the time interval between two records (1 to 10^6 sec.) or
 - the n-th measurement to be recorded (n = 1 to 10^5)
- Stop Saving after... Define when the sequential saving shall be terminated:
 - after reaching a certain file size (1 to 100 MB)
 - after reaching a certain recording time (1 to 10^6 sec.)
 - after reaching a certain number of data sets (1 to 10^5)
- Click "Start Sequential Saving"

Attention

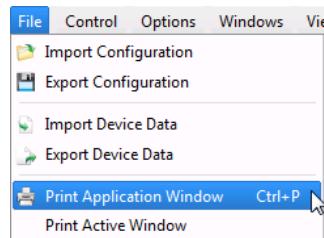
For sequential saving, an index value is appended to the selected file name. Make sure, the check box "Index" is marked.



Once the box "**Sequential Saving**" is checked, the indexing is enabled automatically.

5.3.2 Print Windows

Select 'File → Print Application Window' or 'File → Print Active Window' to print screenshots of the appropriate window.



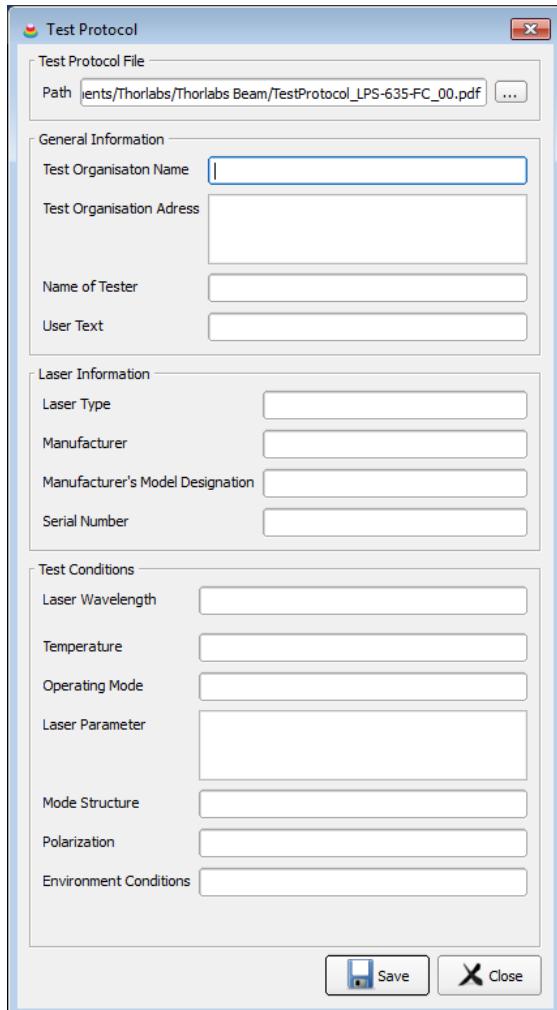
If a PDF creating software is installed as a printer, the screenshot can be printed also as a PDF file.

5.3.3 Save Test Protocol

To save a Test Protocol in pdf format select 'File → Save Test Protocol'.



A dialog box opens:



Here, additional information can be entered in order to save it together with the test report.

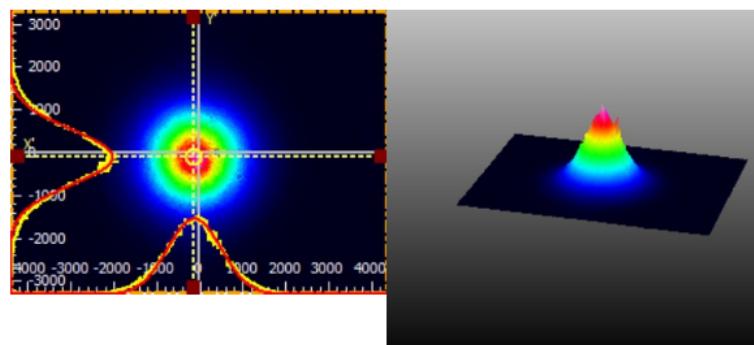
The results of the measurement are saved to a compact test protocol. It contains the Beam Profiler data and settings and [selected numerical calculation results](#)⁶². If the 2D Projection and the 3D Profile windows were activated, these plots will also be included.

Example:



Laser Beam Measurement Test Protocol

Measurement Instrument:	Thorlabs Beam, version 7.0.4082.298	
Date:	07-03-2017 13:36:08	
Test Organisation Name:	Thorlabs	
Test Organisation Adress:	Hans-Boeckler-Str. 6 D-85221 Dachau Germany	
Name of Tester:	Max Mustermann	
Laser Type:	Pigtailed Laser Diode	
Manufacturer:	Thorlabs, Inc.	
Manufacturer's Model Designation:	LPS-635-FC	
Serial Number:	130326-061	
Laser Wavelength:	635 nm	
Temperature in K:	298	
Operating Mode:	CW; Constant Current	
Laser Parameter:	ILD = 46.7 mA Popt = 1 mW	
Mode Structure:	SM	
Polarization:	NA	
Environmental Conditions:	Test Lab	
Model:	BC106N-VIS/M	
Serial Number:	M00311068	
Attenuation:	dB 0	
Exposure Time:	ms 10.00	
Gain:	1	
Parameter:	Unit:	Result:
Beam Width (4-Sigma) X	μm	2942.2
Beam Width (4-Sigma) Y	μm	3225.0
Beam Diameter (4-Sigma)	μm	3085.9
Peak Position X	μm	-35.5
Peak Position Y	μm	-229.0
Centroid Position X	μm	-110.2
Centroid Position Y	μm	-125.2
AD Saturation	%	86.9
Total Power	dBm	-19.12
Ellipticity	%	97.6
Minor Ellipse Diameter	μm	2575.7
Major Ellipse Diameter	μm	2639.7
Orientation	deg	83.8
Camera Temperature	°C	31.5



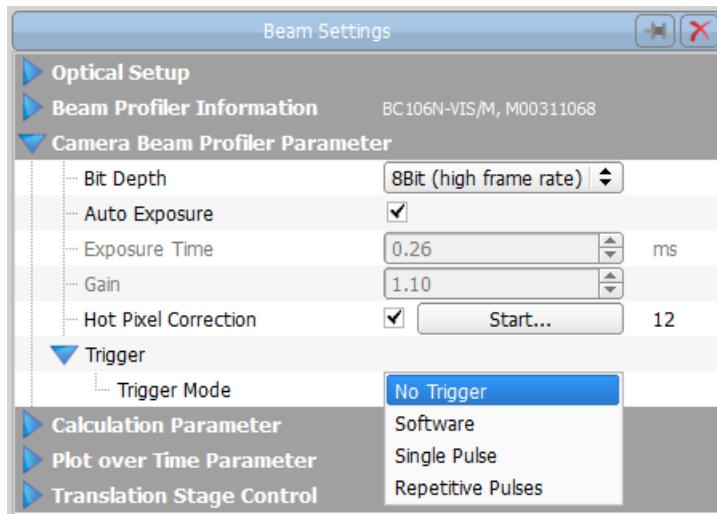
5.4 Pulsed Laser Sources

Overview

The BC106N Camera Beam Profiler is able to capture beam profiles in different trigger modes. Basically, you can work using a continuous or single shot mode. Use these control buttons in the toolbar to enable one of these modes and click to pause image acquisition.

In order to capture beam data of pulsed light sources, various modes to trigger exposure with respect to the laser pulse occurrence are offered.

Open the 'Beam Settings' panel and look into the topic "Camera Beam Profiler Parameter" - "Trigger":



There are three trigger modes:

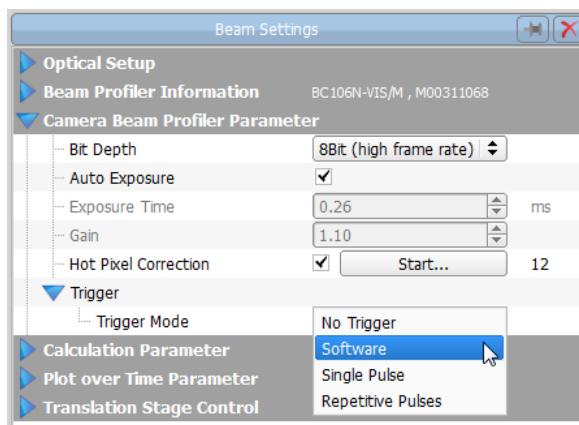
5.4.1 No Trigger

This mode is dedicated mainly for CW sources. A constant beam power is expected so that image capturing can start at any time. This mode should be used also for pulsed sources with high repetition rates above 50 kHz - such pulse trains appear as CW signal to the camera.

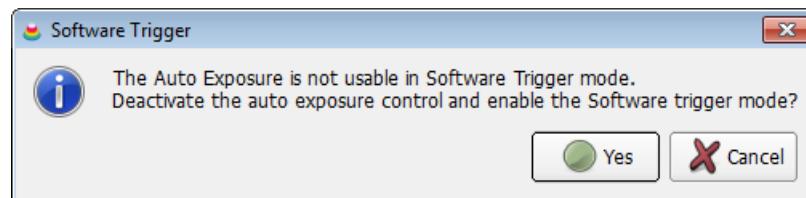
5.4.2 Software Trigger

Software trigger can be used for pulsed light sources which do not provide an electrical trigger signal for synchronization to the Beam Profiler. Also, rarely or irregularly occurring optical pulses can be captured. In this case the Beam Profiler is restricted to trigger on the captured image brightness.

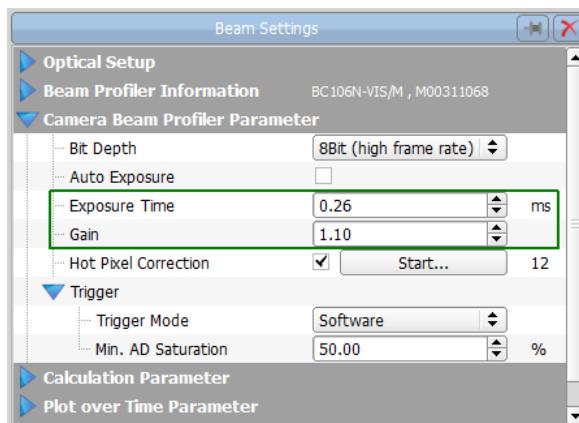
Make sure BC106N is continuous measurement mode; if not click  in the toolbar. Select "Software Trigger" in the Beam Settings panel.



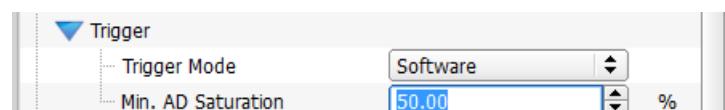
'Software Trigger' mode requires a manual exposure control. As for this, an appropriate warning appears, if auto exposure is enabled:



To confirm, click "Yes" and enter the desired 'Exposure Time' and the 'Gain Factor' manually (tab Beam Profiler Parameters)



Then define the 'Min. Image Saturation' level in %, that will be the software controlled brightness trigger level.



A default value of 50 % indicates that only images with a half scale maximum brightness are triggered, captured and interrogated afterwards. Dark images taken by the camera with a max-

imum brightness lower than the selected ‘Min. AD Saturation’ level will be ignored and not displayed.

Adjusting Exposure Time and Gain

Adjust both the ‘Exposure Time’ and the ‘Gain Factor’ controls so that a low ‘AD Saturation’ (in % of full scale brightness) results when no laser pulse is captured. Increase ‘Exposure Time’ and ‘Gain Factor’ so that a detected laser pulse exceeds the ‘Min. AD Saturation’ threshold. Decrease both controls in case the detected pulse reaches the limiting 100% saturation because its real intensity may be considerably higher.

The status bar informs you about the activated software trigger function.

The Beam Profiler is waiting for an image reaching the selected saturation threshold. In case the actual AD saturation level is below the threshold, the status bar informs you about a waiting software trigger event.

SW Trigger 50.00 % ▶ 1000 | Attenuation: 20 dB | Exposure Time: 0.26 ms | Gain: 1.10 x | Auto Exposure: OFF | 6.66 fps

For frequently occurring pulses it is recommended to adjust the Exposure Time slightly shorter than the pulse period so that only a single pulse is captured.

Prevent ambient light from entering the input aperture and use one of the neutral density filters for its attenuation.

Note that the image brightness of a captured single optical pulse isn’t adjustable by the ‘Exposure Time’ control in case the single optical pulse is shorter than the adjusted exposure duration. Use the supplied ND filters of the filter wheel and the ‘Gain Factor’ control to adjust image brightness. In order to ensure a minimum noise level it is recommended to keep the gain value as low as possible.

Another possibility is to activate the Beam Profiler’s single shot measurement mode by clicking  in the toolbar in combination with this Software Trigger. Although a continuous image capturing is performed in the background, the first image fulfilling the software trigger condition will stop this process and the appropriate image is displayed and interrogated.

5.4.3 External Trigger

The BC106N has an external [TTL trigger input](#)^[23] that allows to synchronize image capturing with single pulses or pulse trains. This input is suited for pulsed light sources that provide an electrical trigger output signal. Additionally, a trigger delay can be programmed to align the camera's exposure exactly to the occurrence of a single or a repetitive light pulse. Feed the TTL level trigger signal from the laser source or from the appropriate driving pulse generator into the BNC connector of the BC106N.



Attention

Be sure to enter only a TTL compatible signal to the BNC jack not exceeding the range between -0.5 V and +6.5 V. Higher or lower voltages may damage the trigger input. See section [Trigger Input](#)^[23] for details.

5.4.3.1 Single Pulse

Check the 'Single Pulse' option:



Trigger Edge: Select the active edge of the trigger signal to 'Rising' or 'Falling'.

Target Delay: Enter a delay to postpone the start of the exposure with respect to the TTL trigger pulse.

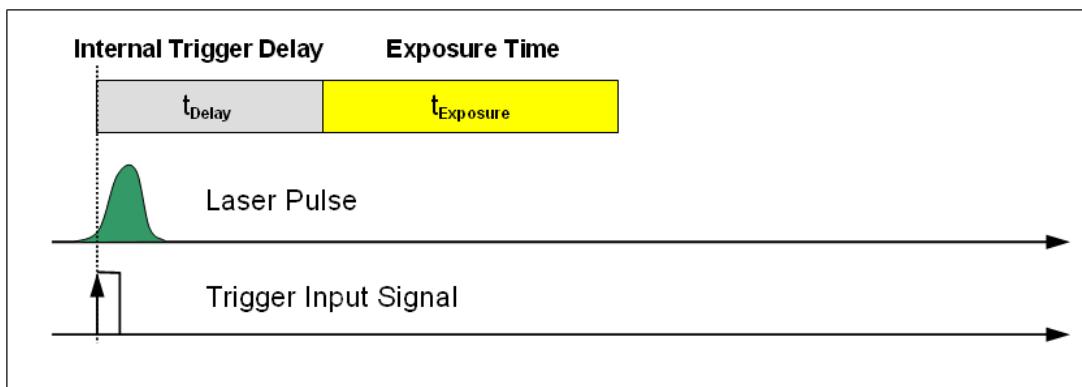
Explanation: Pulsed laser sources often offer the possibility to delay the start of the laser pulse with respect to the TTL trigger output pulse. The target delay is dedicated to compensate this pulse delay.

In the status bar the selected trigger mode, its status and delay time will be displayed:

Waiting for hardware trigger... HW Trigger (Single Pulse) 100.000 ms

Note about Delay

The internal TTL trigger circuit of the BC106N has an intrinsic delay t_{Delay} . This internal delay is inevitable. As a result, the camera cannot start exposure before the internal trigger delay time has expired. An optical pulse that is received during the time span t_{Delay} cannot be detected. The following figure illustrates this situation:



The internal trigger delay t_{Delay} depends on the selected exposure time:

Exposure Time	Internal Trigger Delay
20 μs	96 μs
43 μs	73 μs
$\geq 74 \mu\text{s}$	42 μs

When entering a desired delay to the box 'Target Delay', the software displays the resulting 'Actual Delay' as the closest possible value.

Example for exposure time = 0.020ms (20 μs):

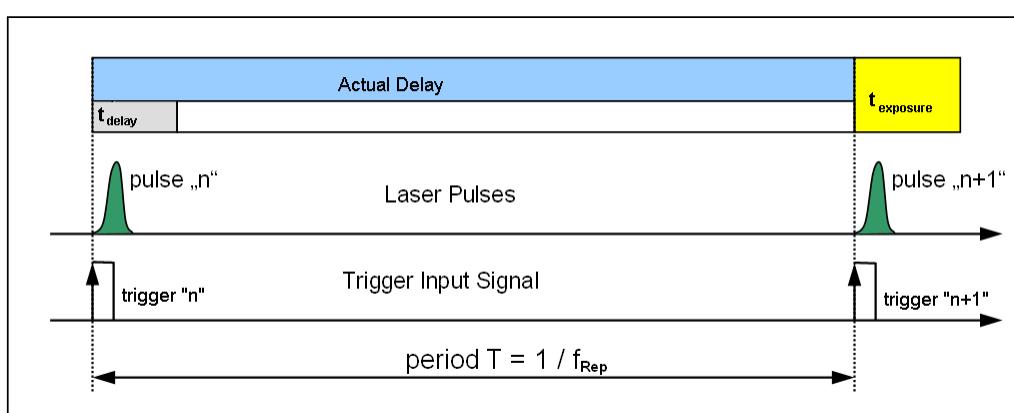
Target Delay	Actual Delay
0.000 ms	0.096 ms
0.050 ms	0.096 ms
0.100 ms	0.100 ms

5.4.3.2 Repetitive Pulses

This trigger mode allows to capture pulses that are shorter than the intrinsic camera trigger delay and thus, normally cannot be "seen" by the camera. These pulses must have a constant repetition rate; a trigger output on the light source is required.

A constant repetition rate is equal to a constant time interval between two adjacent pulses. So, if set the delay time to the repetition interval, the first pulse releases the trigger. Due to the delay time equal to the repetition interval, the camera is triggered on the next pulse, and so on.

The diagram below illustrates this case.



The laser source outputs a trigger signal "n" (rising edge) when the optical pulse "n" is released. The pulse duration is shorter than the internal trigger delay, that's why the appropriate laser pulse cannot be captured.

Entering the laser's repetition rate, software calculates a delay (displayed as 'Actual Delay') to capture the next possible laser pulse - this can be the pulse "n+1" or, for high repetition rates, "n+2", "n+3" etc.

Check 'Repetitive Pulse' and enter the repetition frequency in kHz within the available range 0.001 to 50 kHz. The optimal trigger delay is calculated and displayed.



If the repetition rate is significantly higher than 50kHz, a number of subsequent pulse will be captured, as for this reason beam profiles of successive pulses cannot be resolved anymore. In such cases the pulsed light source appears more and more like a CW source. In such cases the trigger functionality can be disabled by checking 'No Trigger' and the external trigger signal can be omitted. In order to achieve a constant beam power set a suitably long exposure time that performs an average over a high number of laser pulses.

6 Beam Quality (M^2) Measurement

The **Beam Quality** panel can be opened from the menu bar (Menu **Windows**) or by clicking the **M^2** icon in the tool bar.

6.1 General

The M^2 value is an important measure of the beam quality. It is widely used in the laser industry as a specification, and its method of measurement is defined in the ISO 11146 standard. It is particularly useful to describe the degree of divergence and the focusability (minimum focus diameter) of a real laser beam.

For more detailed information about Beam Quality, please see section [M² Theory](#) [150].

Motivation

Many laser applications require maximum optical power density at minimum beam diameter. Besides the focusing optics, the quality of the light source itself is the main influence to the focusability of the beam. A high beam quality is a pre-condition for optimal focusability.

Beam Quality

Beam Propagation measurements according to the standard **ISO 11146** describe the beam quality using a single parameter, which is either the **Times-Diffraction-Limit Factor M^2** or the **Beam quality $K = 1/M^2$** (also known as *beam quality factor* or *beam propagation factor*).

Whereas the beam quality K is directly proportional to the quality level ($K=1$ optimal, decreasing K stands for poorer quality), its reciprocal value M^2 ($M^2=1$ optimal, increasing M for poorer quality) is used more often.

Please do not confuse the beam quality ($K \leq 1$) and times-diffraction-limit factor ($M^2 \geq 1$).

Diffraction Limit

Depending on the wavelength λ and beam divergence angle θ , the theoretical limit for the minimum beam waist diameter d_0 is called the **diffraction limit**. The beam waist cannot be decreased beyond this value.

M^2 expresses how close the diffraction limit of the analyzed beam is to the diffraction limit of an ideal Gaussian beam. The beam parameter product $d_0 * \theta$ describes that mathematically. For beams of worse quality, the product $d_0 * \theta$ is increased by the factor M^2

$$d_0 \theta \rightarrow M^2 d_0 \theta$$

where d_0 is beam waist at the focus and θ - the divergence angle.

M^2 is also known as

- the ratio of the waist diameter d_0 of the measured beam to that of an ideal Gaussian beam (TEM_{00}) at the same divergence angle θ .
- the ratio of the divergence angle θ of the measured beam to that of an ideal Gaussian beam (TEM_{00}) at the same waist diameter d_0 ,

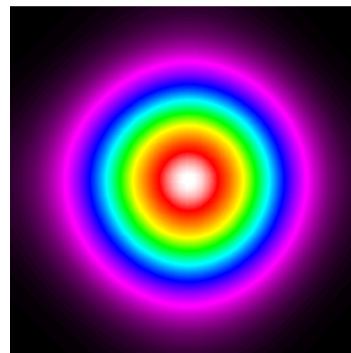
Worse beam quality results from laser imperfections like inhomogeneities which lead to appearance of higher transverse modes.

How to Measure Beam Quality

Ideal beam quality ($K=1$, $M^2=1$) with a diffraction limited waist size is possible if only the fundamental mode TEM_{00} (which has an ideal Gaussian shape) exists. The existence of higher modes decrease beam quality which leads to larger waist diameters. Often, such distortions can be easily discovered by looking at the non Gaussian beam profile.

But in many cases, several higher modes are distributed in a way that generate a nearly Gaussian shape but the beam itself suffers from a bad beam quality.

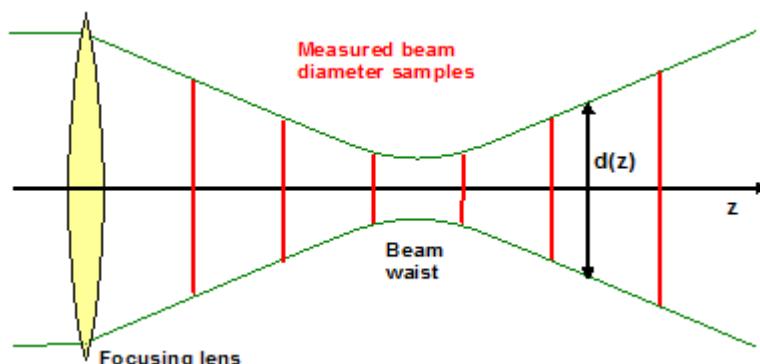
The following example shows a beam with nearly perfect Gaussian shape but having a multi-mode origin leading to bad quality $M^2 = 1.79$.



Note

A nearly Gaussian shape is not an indicator of high beam quality! Therefore, a single-shot beam shape measurement from a Beam Profiler does not provide a correct information about the beam quality.

Although a single Beam Profiler result is not a measure of beam quality, the Thorlabs Camera Beam Profiler Series can be used to accurately measure the beam quality. For this purpose, a beam propagation measurement is carried out according to the ISO11146 standard. The key idea is to measure the variation of beam diameter $d(z)$ along the axis of beam propagation z .



The Beam Profiler is mounted on a translation stage which is controlled by the Beam Profiler software. At several z positions the beam diameter and other parameters are measured and stored.

Besides finding the **times-diffraction-limit factor M^2** , the Thorlabs Beam Propagation measurement determines the following parameters of an optical beam:

- beam waist width d_{0x} , d_{0y}
- beam waist z-position z_{0x} , z_{0y}
- Rayleigh range z_{Rx} , z_{Ry}
- divergence angle θ_x , θ_y
- waist asymmetry

- divergence asymmetry
- astigmatism

Note

The Thorlabs Beam Quality measurement tool can handle CW sources and some pulsed sources only! For more information about pulsed laser sources read chapter [Pulsed Laser Sources](#)⁹².

6.2 Hardware Extensions

Thorlabs offers both the translation stages as extension and complete M² Meter Sets that include the stage and the Beam Profiler:

Item Number	Description
M2MS	M2 Measurement System Extension Set
M2MS-AL	M2 Measurement System Extension Set, 250 - 600 nm (AL mirrors)
M2MS-BC106UV-AL	M2 Measurement System with BC106N-UV, 250 - 350 nm
M2MS-BC106UV-AL/M	M2 Measurement System with BC106N-UV, 250 - 350 nm, metric
M2MS-BC106VIS	M2 Measurement System with BC106N-VIS, 400 - 1100 nm
M2MS-BC106VIS/M	M2 Measurement System with BC106N-VIS, 400 - 1100 nm, metric
M2MS-BP209VIS	M2 Measurement System with BP209-VIS, 400 - 1100 nm
M2MS-BP209VIS/M	M2 Measurement System with BP209-VIS, 400 - 1100 nm, metric
M2MS-BP209VIS-AL	M2 Measurement System with BP209-VIS, 250 - 600 nm
M2MS-BP209VIS-AL/M	M2 Measurement System with BP209-VIS, 250 - 600 nm, metric
M2MS-BP209IR	M2 Measurement System with BP209-IR, 900 - 1700 nm
M2MS-BP209IR/M	M2 Measurement System with BP209-IR, 900 - 1700 nm, metric
M2MS-BP209IR2	M2 Measurement System with BP209-IR2, 1000 - 2700 nm
M2MS-BP209IR2/M	M2 Measurement System with BP209-IR2, 1000 - 2700 nm, metric

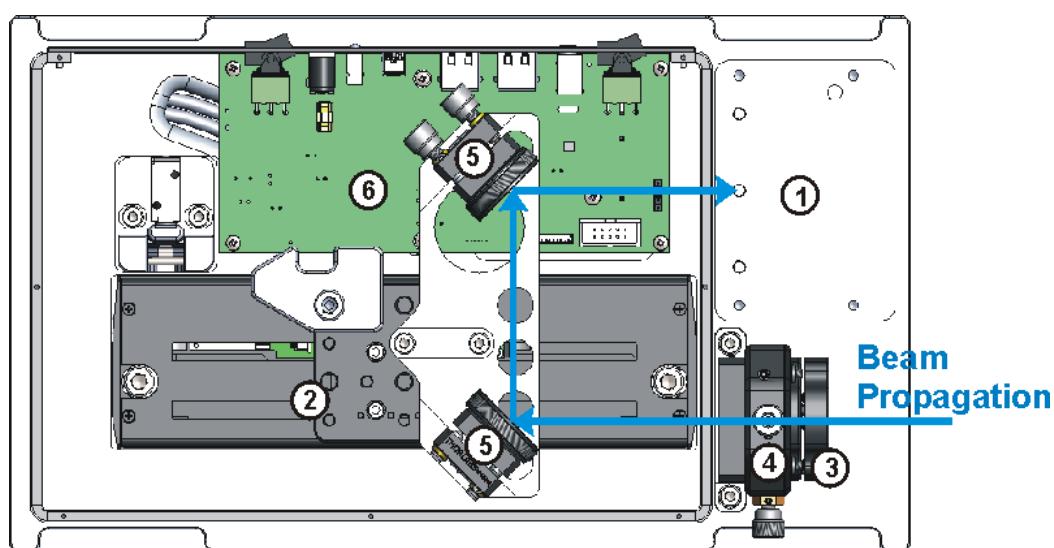
Note

Systems with aluminum (AL) mirrors are dedicated for use with UV Beam Profilers, as the standard protected silver mirrors show a significant drop of reflectance below 400nm.

6.3 M2MS Operating Principle

The Thorlabs M2MS M^2 Meter System is a compact instrument that includes all components required to measure beam quality:

- ① Beam Profiler (not shown below)
- ② Linear Translation Stage Thorlabs DDSM100
- ③ Lenses with different AR coatings
- ④ Lens centering assembly (X-Y translation mount)
- ⑤ 2 tilted mirrors
- Adjustment Laser (not shown below)
- ⑥ Integrated control electronics (translation stage controller, USB 2.0 hub and driver for alignment laser)



The beam under test enters the the focal lens (3), hits the two tilted mirrors (5) and leaves the enclosure towards the Beam Profiler's input aperture (1). The translation stage is moved by the control software stepwise, this way changing the path length between the focal lens and the Beam Profiler. The maximum travel range of the stage (100 mm) is doubled by the use of two mirrors so that the resulting path length range is 200 mm. The focal length of the lens is selected in such a way that the beam waist will be close to the middle of the travel range.

During the M^2 measurement, the stage moves stepwise along the beam propagation direction and at each position the beam geometry is measured. From the results, the software calculates beam parameters and beam quality.

The mirrors are factory aligned; there is no need to re-align them.

For fine beam alignment, an alignment laser is supplied. Please see section [Beam Alignment](#)^[109] for details.

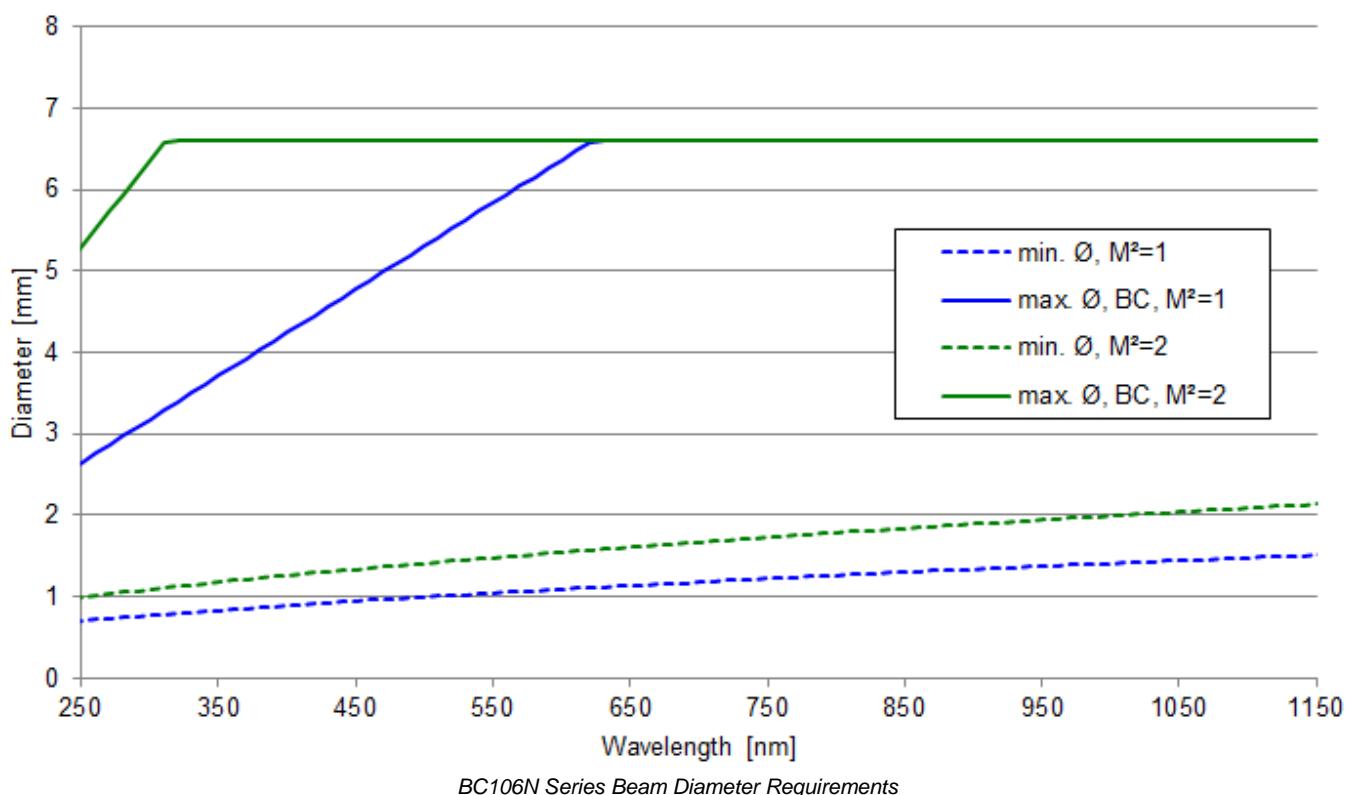
6.4 Beam Diameter Requirements

The Beam Quality measurement is based on the determination of the waist diameter of a focused beam and the convergence (divergence) of the beam before (after) the beam waist.

Ideal Gaussian beams have the best focusability, which results in the minimum possible beam diameter and $M^2=1$. The absolute minimum waist diameter increases with as the focal length of the lens increases. In other words, for a given focal length, the smaller the waist diameter the closer M^2 is to 1.

The minimum waist diameter increases (at a constant M^2) with the wavelength.

Limitations to the measurement of the beam diameter are given by the capabilities of the Beam Profiler, see [Technical Data](#)^[169]. The initial (unfocused) beam diameter must not exceed the maximum measurable beam diameter, the waist diameter must be greater than the minimum beam diameter. The following diagram illustrates the requirements for the initial beam diameter depending on the wavelength and for $M^2=1$ and $M^2=2$ (lens with a focal length of 250 mm as delivered with the M2MS system):



6.5 M^2 Meter Extension Set

The M^2 Meter Extension Set is compatible with all Thorlabs Beam Profilers of BP100, BP209 and BC106 Series. Suitable mounting adapters are supplied.

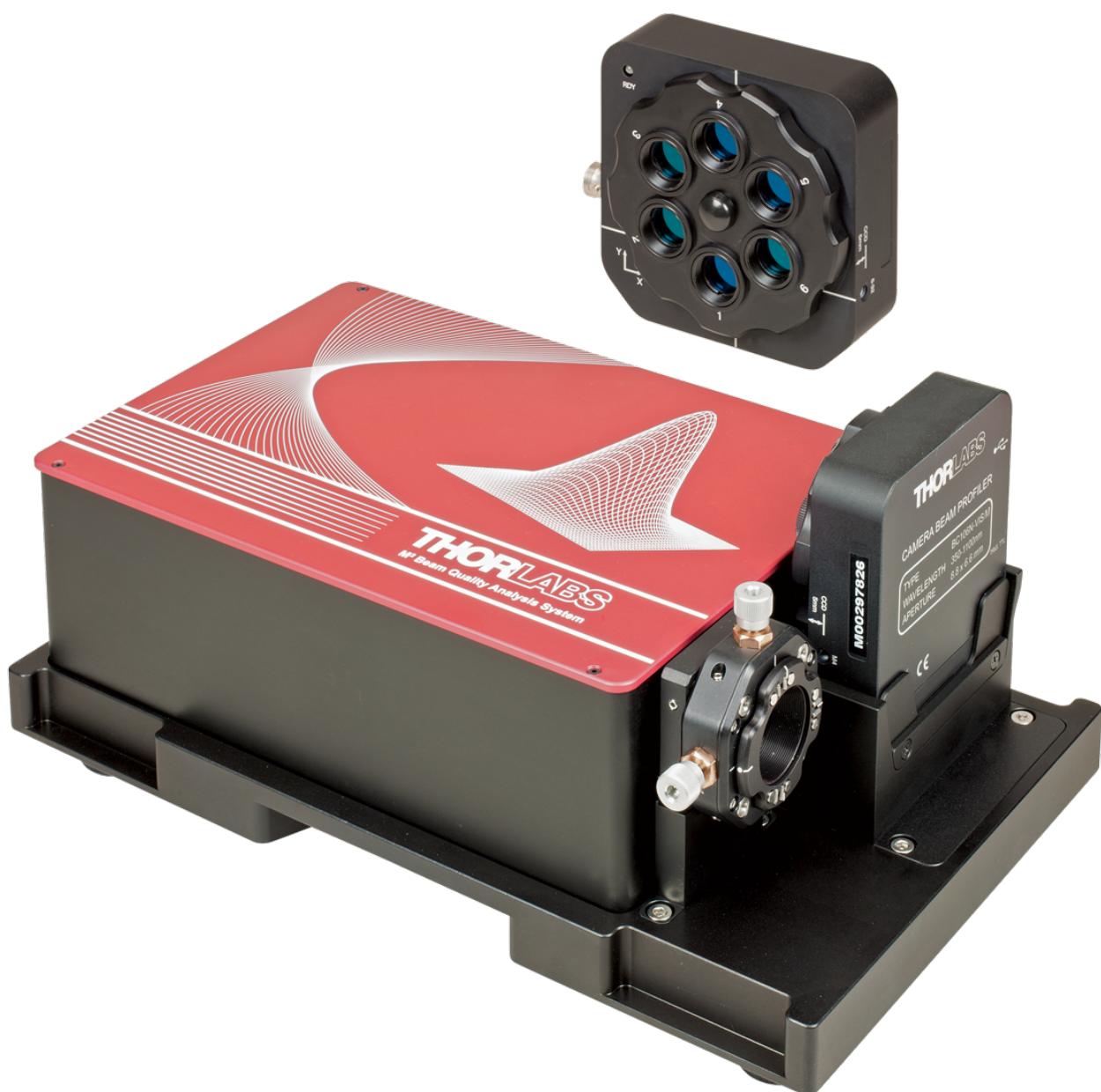


*M2MS M^2 Measurement System Extension Set
with adapters for BC106 and BP209 beam profilers*

6.6 M^2 Meter Set with BC106N Camera Beam Profiler

The M2MS-BC106 set features:

- Accurate M^2 Measurements
- Measures Divergence, Waist Diameter, Rayleigh Range and Astigmatism
- Compatible with CW and Quasi-CW Pulsed Laser Sources
- Short Measurement Cycles
- Fully ISO11146 Compliant



6.7 Setting Up

The M2MS Measurement System is a complete system that is factory aligned. The mounting adapter for the Beam Profiler provides a secure and reproducible positioning of the Beam Profiler's input aperture to the M2MS. This eases the mechanical setup.

Note

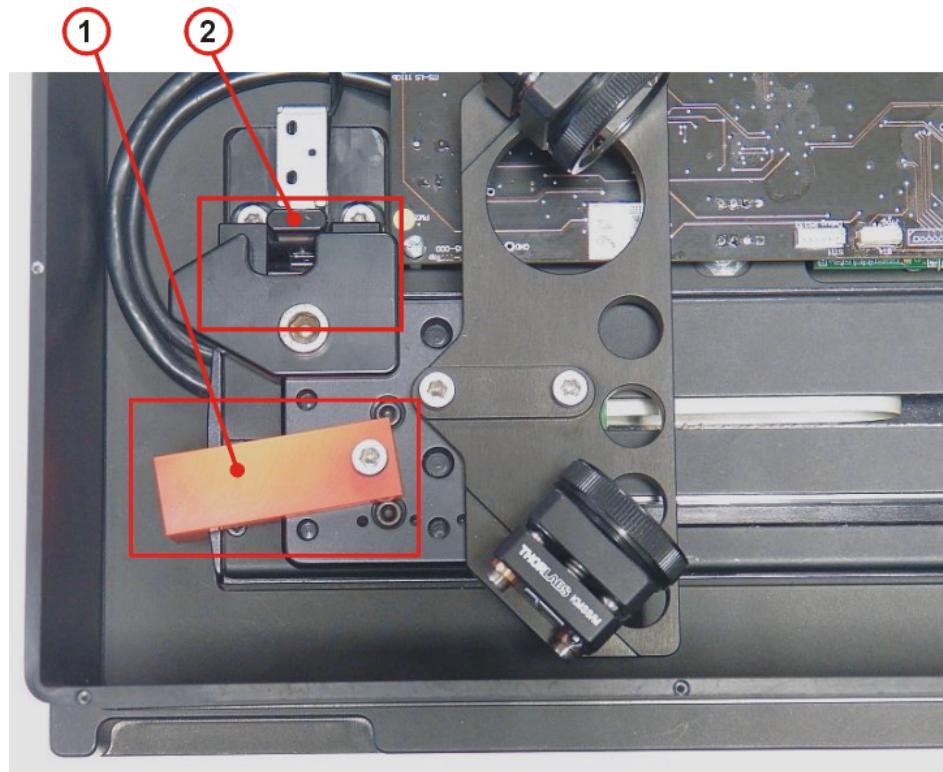
It is strongly recommended to fix the M2MS properly to the optical table using the four rail clamps that are included in the M2MS Accessory Box. To ensure a proper mounting, first remove the rubber feet from the M2MS base plate.

Transportation Lock and Stop Position Latch

In order to avoid transportation damages to the translation stage, it is locked when delivered. This lock must be removed prior to powering-up the stage, and it must be re-installed for transportation. Additionally, the DDSM100 stage is fixed at its initial position by a solenoid controlled latch, which is the left stop in the photo (2). This latch fixes the stage when the power supply is switched off and releases the stage when power is applied.

Removal of the Transportation Lock

1. Remove the 4 screws fixing the top cover using a 0.05" hex key (supplied with the M2MS) and remove the cover.
2. Remove the M4 screw that fixes the red stopper (1), and remove the stopper using the 3 mm ball driver included with the accessory box. Keep the stopper and the fixing screw in a safe place.

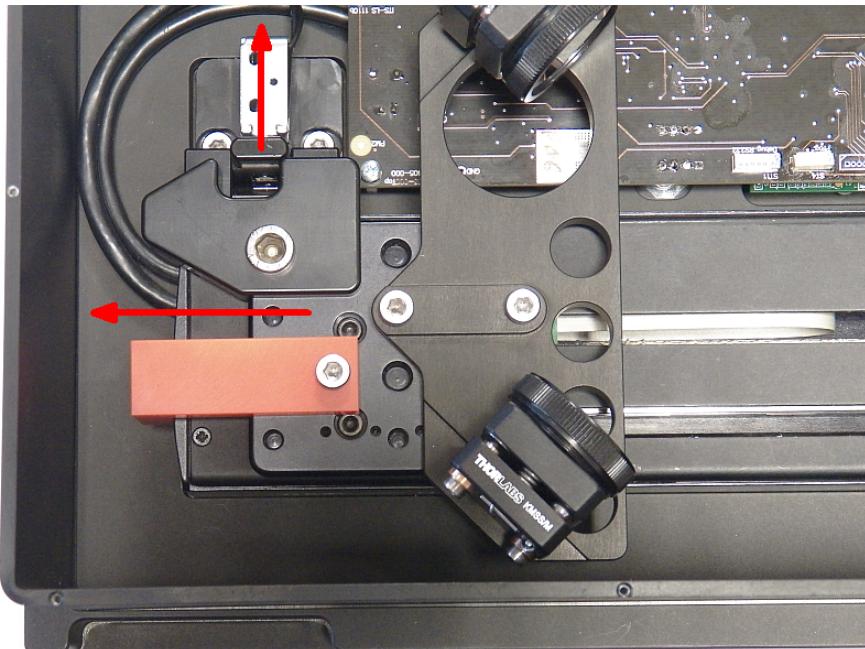


1 - Transportation Lock
2 - Electromagnetic Endpoint Latch

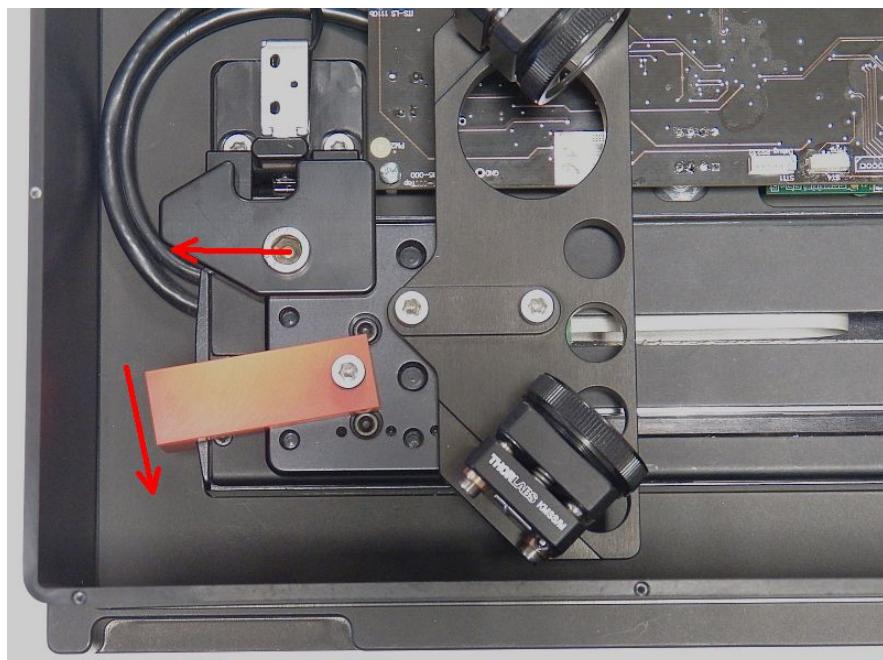
3. Close the M2MS.

Installing the Transportation Lock

1. Switch off the power supply.
2. Remove the 4 screws fixing the top cover using a 0.05" hex key (supplied with the M2MS) and remove the cover.
3. Move the stop latch as indicated in the picture below and place the platform of the stage against the left stop. Then install the transportation lock; don't tighten the fixing screw yet.



4. Push the platform to the left stop, turn the lock counterclockwise and tighten the lock screw.



5. Place back the top cover and fix it using the 4 screws. Now, the M2MS is ready for transportation.

6.7.1 Mounting the Beam Profiler

If you purchased a complete M2MS Measurement System that includes the Beam Profiler, you can skip this section. Otherwise, if the Extension Set was purchased separately, please mount your Beam Profiler as described in the following.

Install your BC106N-xxx(/M) on the BC106 mounting adapter:



Firmly press the BC106N front against the front stopper surface and secure it in place using the supplied M6 (BC106N-xxx/M) or 1/4" (BC106N-xxx) hex screw.

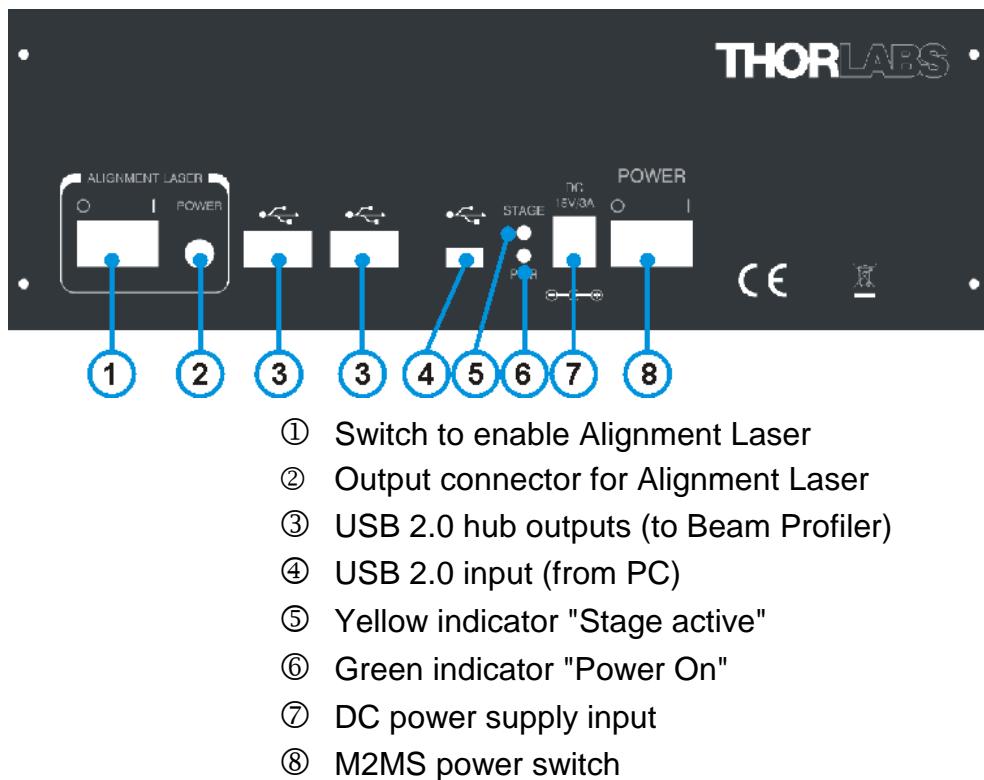
Place the mounted Beam Profiler into the recess using the dowel pins on the M2MS base plate:



Fix it using the supplied M4x10 Hex screws.

6.7.2 Connection to the PC

The M2MS comprises an integrated control electronics with translation stage controller, an USB 2.0 hub and a current source for the alignment laser.



Attention!

It is strongly recommended that only the supplied USB cables are used to connect the Beam Profiler and the control PC to the M2MS. These cables were selected and tested under point of fulfilling the entire USB 2.0 specifications. The operation systems Windows® 7, 8.1 and 10 are less tolerant to deviation from this specification than former operating systems.

The use of other than the supplied USB 2.0 cables may lead to USB connection instabilities.

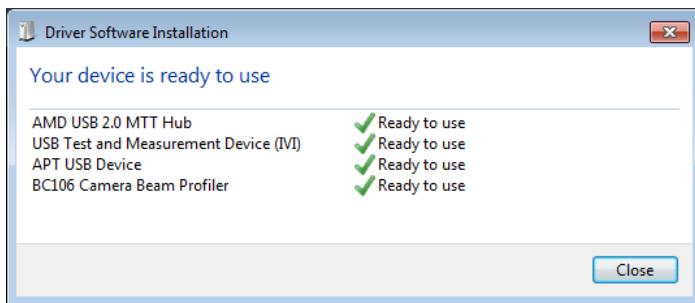
Attention

Do NOT connect the M2MS to a computer prior to installing the Beam Software!

Attention!

Prior to connecting the M2MS to the power supply, make sure the [transportation lock is removed](#)! Otherwise the stage drive may be damaged!

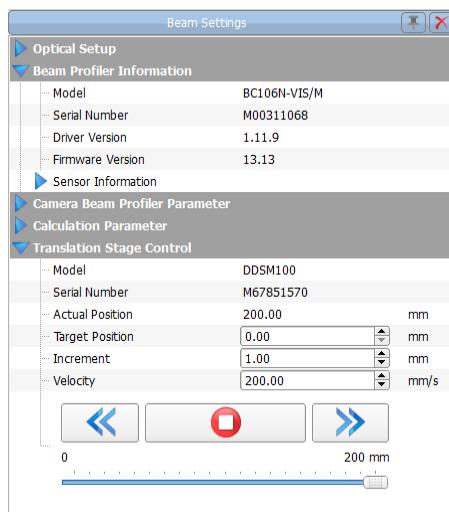
1. Connect AC power to the power supply and its output to the DC jack (7).
2. Connect the Beam Profiler using the supplied angled USB 2.0 cable to one of the USB hub outputs (3).
3. Switch the M2MS on (8). The green **Power On** indicator lights up.
4. Connect the M2MS to the PC using the supplied 3 m long USB 2.0 cable; do not start the BEAM software yet.
5. The PC's operating system recognizes the connected new hardware and performs the driver installation:



Note

The first three entries ("AMD USB2.0 MTT Hub", "USB Test and Measurement Device (IVI)" and the "APT USB Device") are hardware components of the M2MS extension.

- Start the Beam Software. It should automatically connect to the Beam Profiler and to the translation stage. This can be seen in the Beam Settings Panel:



- Upon starting the Thorlabs Beam software, the translation stage will be initialized and homed automatically. This means that it is recognized in the tab **Stage Selection** and moves to the 200 mm position in the case it's not there yet. This can take a few seconds. The initialization can be forced manually by clicking the "Refresh Stage List" button in the **Device Selection** window. After the stage is identified and its serial number is read-out, double click the DDSM100(M) button.

6.8 M^2 Measurement

Prior to starting the Beam Quality measurements, the beam of the laser under test needs to be aligned to the M2MS Measurement System. It is important that the beam center hits the center of the Beam Profiler's aperture at every position of the translation stage. Please read the following section carefully and follow the instructions.

6.8.1 Beam Alignment

Why Beam Alignment?

The Beam Profiler has a defined input aperture, so when moving the translation stage it must be ensured that the laser beam remains within the aperture. Ideally, the beam centroid remains centered within the aperture during movement of the stage - this is a precondition for correct beam quality measurements.

The M2MS Measurement System is factory aligned. A beam entering the M2MS exactly parallel the stage movement direction will remain centered to the Beam Profiler aperture during stage movement. In other words, the beam alignment is dependent only on the position of the light source. In the common case, the light source is a device with open beam output. In order to direct the beam under test into the M2MS, a combination of two adjustable mirrors is required, Thorlabs offers a variety of such items.

The beam alignment is executed in 3 steps, guided by a software wizard:

1. [Coarse alignment](#)^[111]: Determine the correct location of the Laser Under Test output aperture by means of an auxiliary laser (included).
2. [Beam Alignment](#)^[114] of the Laser Under Test for minimum beam displacement and pointing angle without focusing lens.
3. [Alignment of the focusing lens](#)^[118] for minimum beam displacement and pointing angle.

6.8.1.1 Coarse Alignment

For a coarse alignment, Thorlabs provides an alignment laser that is included with the accessory box. For this step, the alignment laser is mounted on the M2MS in place of the Beam Profiler. It is mounted and aligned in such way that its output beam enters the M2MS exactly centered in the Beam Profiler's aperture and is parallel to the stage movement direction. The alignment beam is reverse directed - it virtually exits the Beam Profiler and is redirected by the two mirrors of the stage into the center of the laser source aperture (see the drawing in section [M2MS Operating Principle](#) [101]).

Warning

Be careful when using this laser!



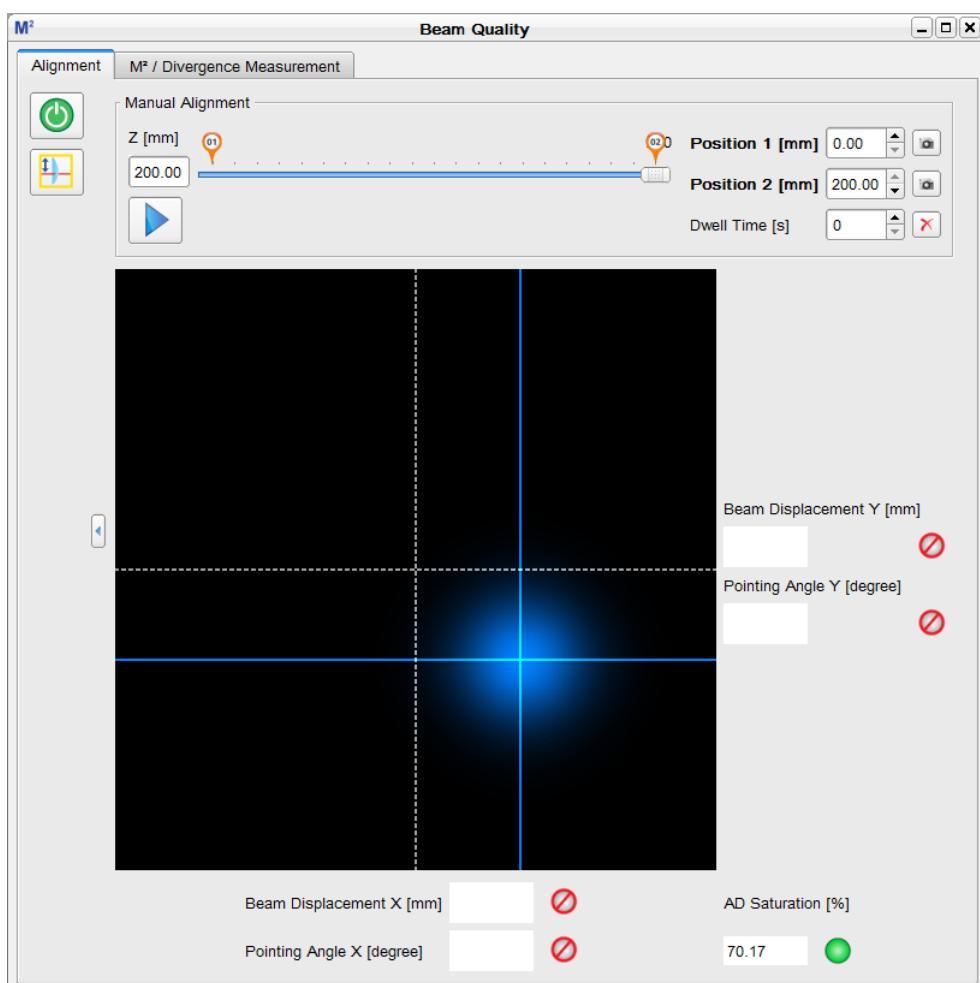
- Remove the Beam Profiler together with its mounting adapter from the M2MS base.
- Install the adjustment laser in place of the Beam Profiler and connect its 3.5 mm plug to the [Alignment Laser output \(2\)](#) [108].
- Make sure the M2MS is switched on and connected to the control PC, the Beam software is started and the stage has been initialized.
- Remove the focal lens from the magnetic holder.
- Switch on the alignment laser.
- Align your optical system so that the spot of the alignment laser hits the center of your light source.

6.8.1.2 Fine Alignment

After coarse alignment, the beam under test needs to be fine-adjusted using the **Alignment** feature of the M² measurement panel. This is executed in two steps.

Preparation

- Switch off the alignment laser and replace it with your Beam Profiler.
- Remove the focusing lens (see  in the drawing in the [M2MS Operating Principle](#) [101] section).
- Connect the Beam Profiler to one of the M2MS USB outputs (, [Connection to the PC](#) [108] section).
- Make sure it is being recognized by the Beam software (Toolbar  [Device Selection](#) [109]). If it is not recognized automatically, press the **Refresh Device List** button.
- Make sure the stage is recognized and initialized. If not, press the [Refresh Stage List button](#) [109] and after the stage was recognized, double click to the DDSM100 button. The stage initializes and moves to the 200 mm position.
- Enable the Laser Under Test.
- Open M² child window either from the menu "Windows" -> "M² Quality Measurement" or by clicking the **M²** button, and switch to the Alignment tab.

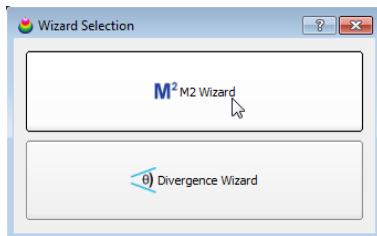


Explanation of indicators and icons

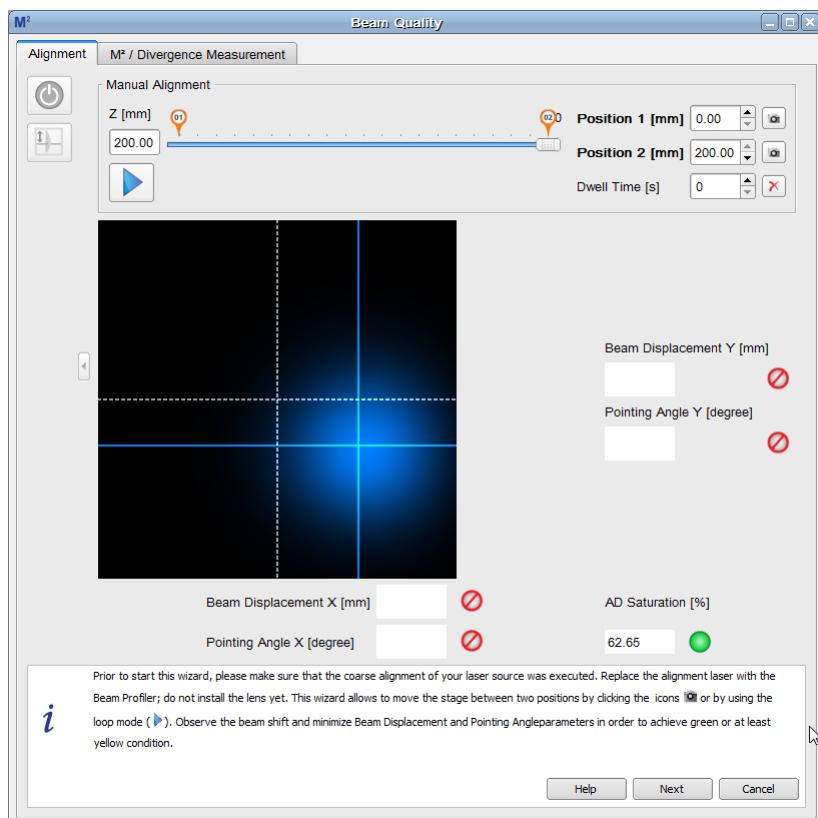
	Start the Alignment Wizard
	Start the Focusing Lens Alignment Wizard
Z [mm]	This box shows the actual stage position; after initialization = 200 mm.
Position 1 (2) [mm]	Here the left and right positions for the stage movement can be entered numerically.
	Markers for left and right positions. Instead of numerical entry of the markers' positions, the markers can be move by drag-and-drop.
	Clicking these capture buttons, the stage moves to the related position, if not there yet, and captures the beam centroid position (amber crosshair). This snapshot will remain until the stage comes back to the appropriate position.
	This button starts the stage loop movement mode and the stage moves continuously between positions 1 and 2. A dwell time at the end positions can be entered. During the loop mode, the software automatically captures the beam centroids (yellow cross hair) at the left and right stop.
Dwell Time	Enter the desired time [sec]. The dwelling can be disabled by clicking to the icon.
	Centroid crosshair of the actual beam position.
	Crosshair of the sensor center
Beam Displacement	is the centroid shift in X (Y) direction between position 2 and 1 [mm]. The box is first time filled after the 2nd capture.
Pointing Angle	is the angle [°] in X (Y) direction between the beam axis and the stage movement direction. The box is first time filled after the 2nd capture.
Alignment Success Indicator	Alignment not successful Alignment sufficient for correct Beam Quality Measurement (displacement < 0.65 mm, angle < 0.35°) Good alignment (displacement < 0.35 mm, angle < 0.15°)
AD Saturation	Displays the current saturation of the Beam Profiler's AD converter. For proper beam alignment function the value must be 80 to 95 %. The green bulb to the right of the numeric field indicates the "GOOD" range.

6.8.1.2.1 M² Beam Alignment Wizard

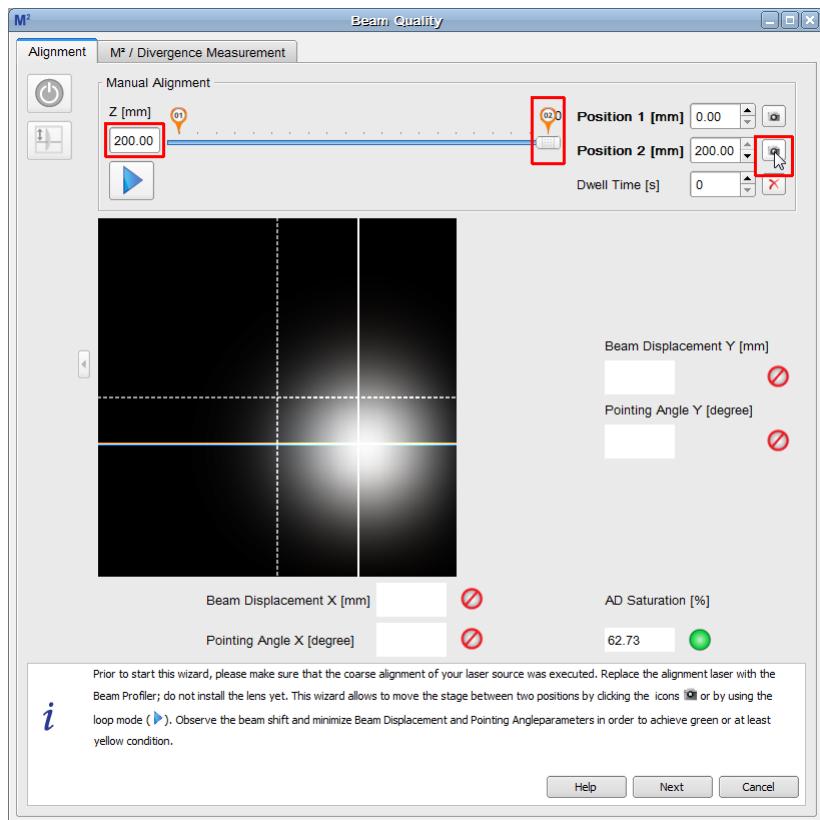
Press the **Start Wizard** button . You will be requested to select whether you want to adjust for M² or Divergence Measurement. Make your choice:



The wizard starts:

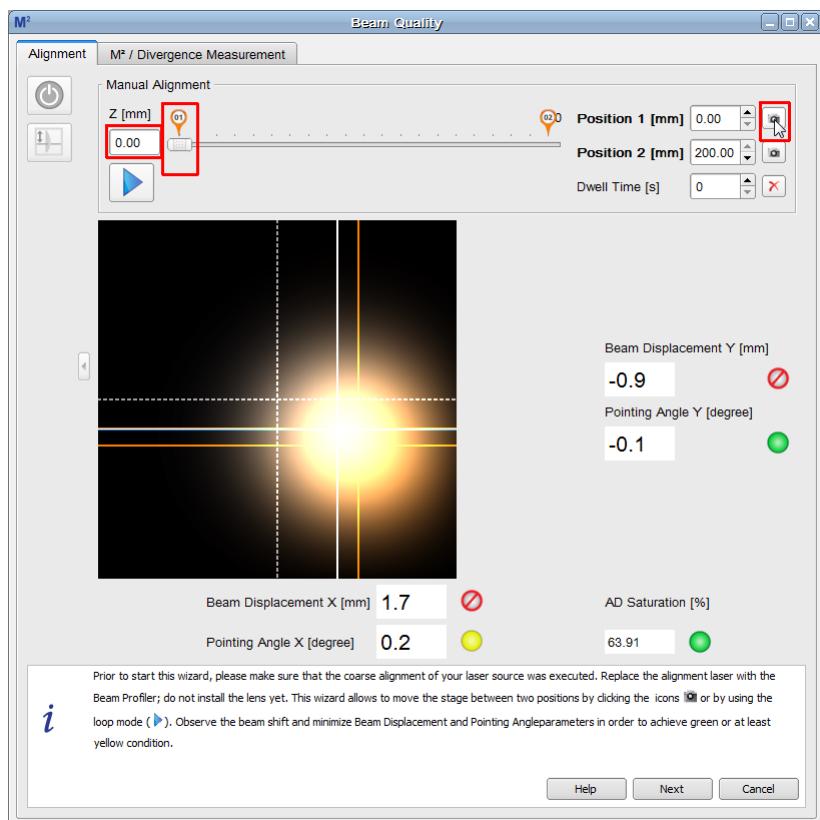


- For a successful alignment, the optical power level must be adjusted in such way that the AD Saturation is between 80 to 95 %. The green bulb to the right of the numeric field indicates the "GOOD" range. During alignment this condition must not change!
- After initialization, the stage is at Position 2 (200 mm). Click the capture button of Position 2 - the centroid is captured, and its crosshair color changes to amber. As the actual beam centroid that is marked by a blue crosshair, is located at the same position, the resulting color is white:



Centroid captured at Position 2

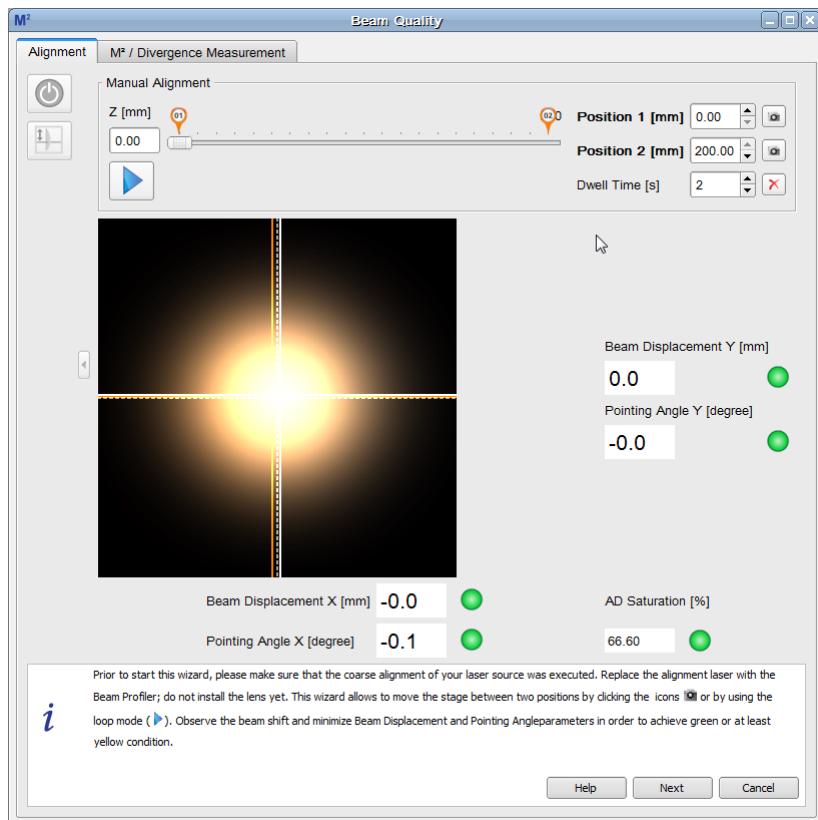
- Click to the Position 1 capture button (0 mm). The stage moves to Position 1 and captures the second centroid position:



Centroid captured at Position 1

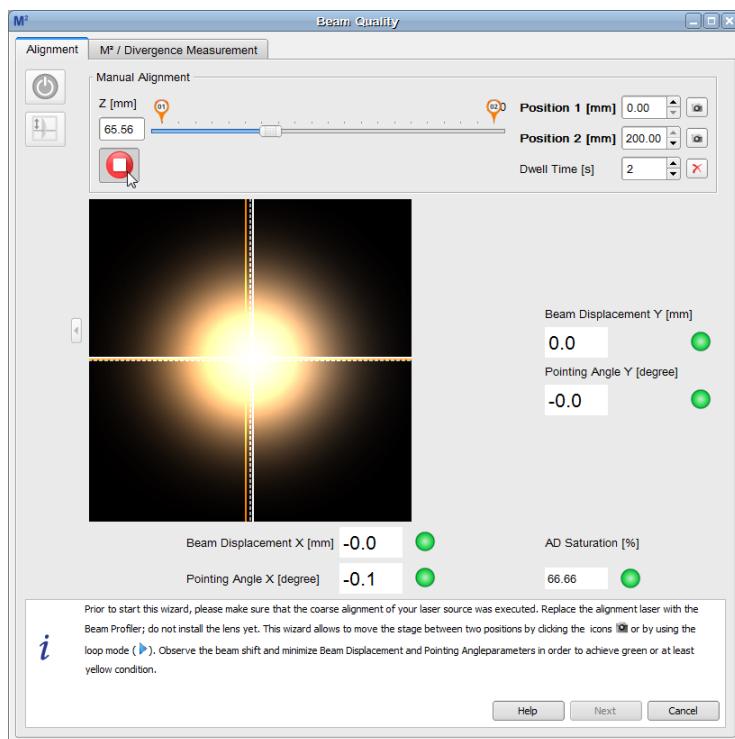
- Now, the beam displacement and the pointing angle are displayed numerically.

- Align the beam position using the controls of your laser source. Subsequently click the capture button of position 1 and 2, observe the alignment, and improve it until all four alignment criteria are fulfilled (bulbs must be at least yellow):



Well aligned beam position

- The movement of the stage between the two stop positions can be controlled automatically by the software. Just push the loop button and enter a convenient dwell time value. The stage starts a loop move, dwelling at the stop position for the given time. During the dwelling a realignment can be made. Please keep in mind, that the numeric alignment indicators are being updated only after the next move.

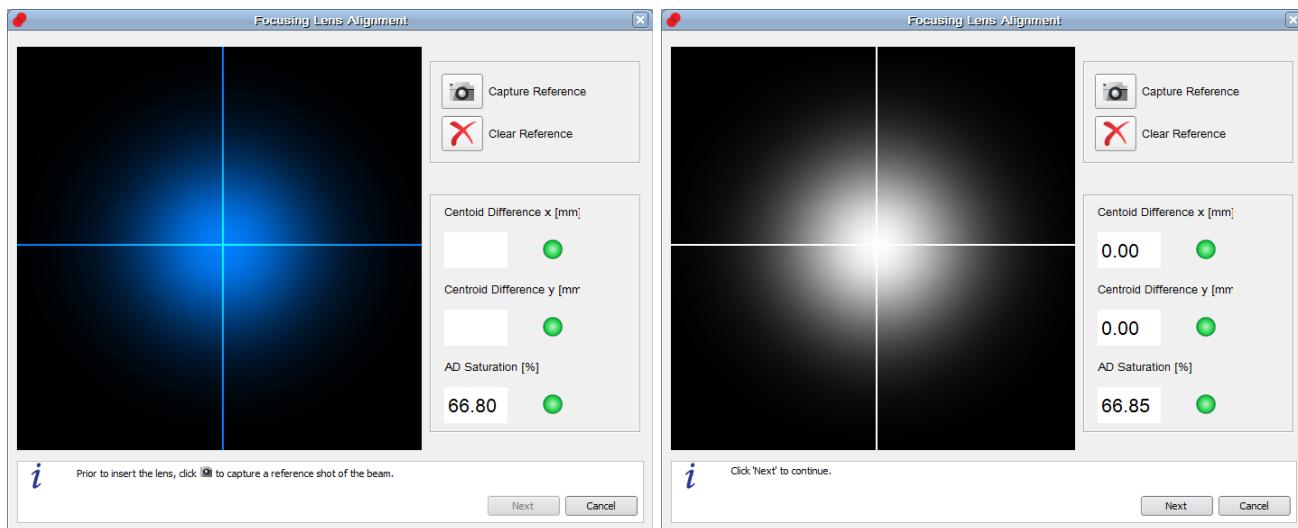


Alignment Move Loop

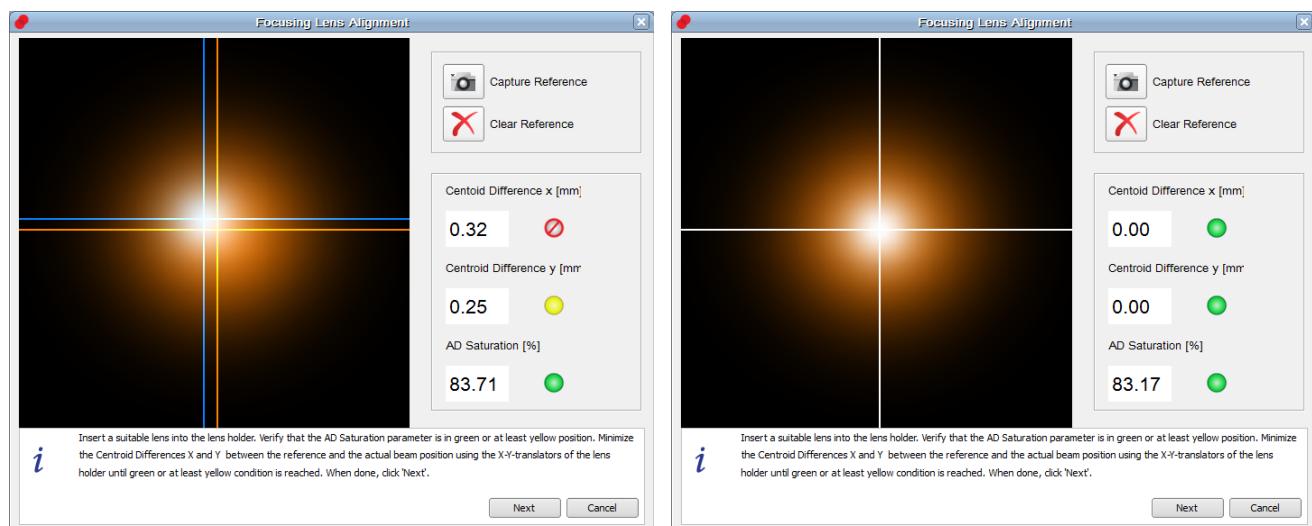
- The loop terminates by clicking the button.
- After finishing, click **Next** to continue.

6.8.1.2.2 Alignment of the Focusing Lens

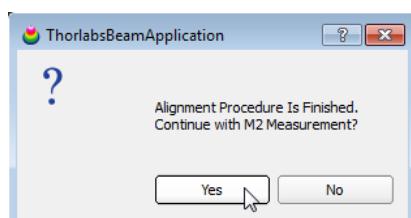
- After finishing the Beam Alignment, the wizard guides you to the alignment of the focusing lens. As a first step, capture the beam position without lens, then click 'Next':



- Verify that the holder of the focal lens is centered (markers on the CXY1 translator and the lens holder should match), place the mounted focal lens back to the magnetic holder. Make sure that the AD Saturation is still in green or at least yellow condition. Observe the actual beam position and minimize the difference to the reference, using the X-Y translators of the lens holder until the indicators are green or at least yellow.

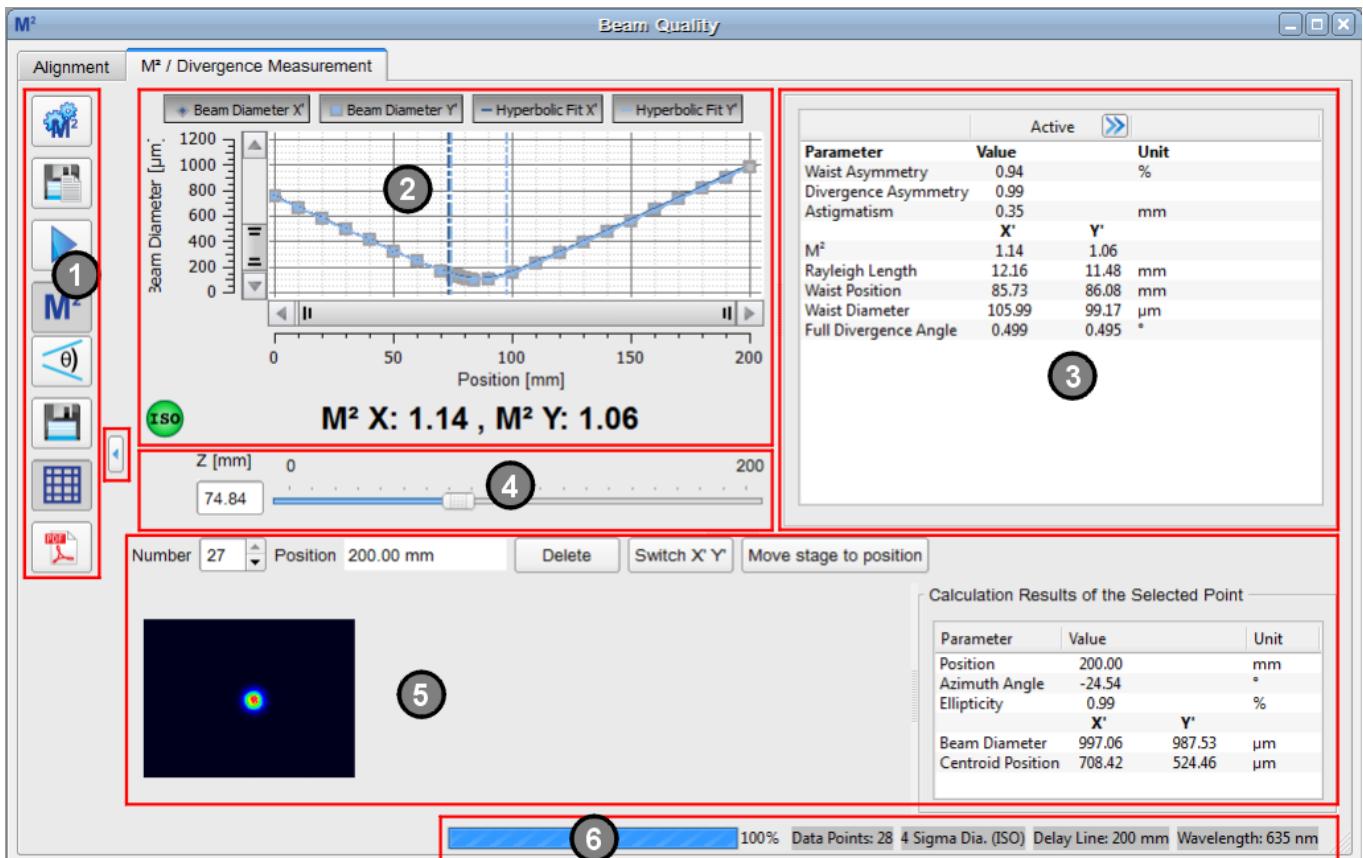


- Then click 'Next' to finish the Focusing Lens Alignment.
- Select if you want to continue with M² measurement:



6.8.2 M^2 Measurement Panel

This section concerns the M^2 measurement and its settings. Click **M^2 / Divergence Measurement** in the **Beam Quality Measurement** window to enter the M^2 Measurement section.



The M^2 panel is divided into 6 subpanels:

1. Toolbar

M² Settings	Opens the Settings for the M^2 measurement
Auto Save Data	Save Beam Profile Data during M^2 Measurement
Start / Stop	Starts / stops a M^2 measurement
M²	Switches to M^2 measurement
Divergence	Switches to Divergence measurement
Save Data	After a successful M^2 measurement this button is enabled and plot data can be saved.
Grid	Disables/Enables the grid in the diagram
PDF Test Protocol	Saves the results of a M^2 measurement into a PDF file

2. M^2 Diagram

The measured data are plotted in the diagram. The 4 buttons above the diagram allow the display to be configured: The buttons **Beam Diameter X' (Y')** enable / disable the display of the measured data at the individual positions, while the buttons **Hyperbolic Fit X' (Y')** enable / disable the curve fit to the measured data points.

After the measurement is finished, below the diagram the M² results for the X and Y axes are displayed. To the left, an indicator shows if the measurement was successful and ISO compliant. See also section [M² Troubleshooting](#)^[133].

The red marked button  between the toolbar and the diagram expands the diagram over the entire M² window

3. Numeric Results

In this area, the Beam Quality measurement results are displayed in detail. Please see section [M² Measurement Results](#)^[129] for more details.

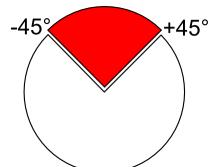
4. Position Bar

The Position Bar below the M² Diagram shows the actual position of the translation stage as seen before in the **Alignment** tab.

5. Selected Data Points

Select in the header of this sub-panel the **Number** of the desired measured data point. For this selected point, the position of stage and the 2D projection of the beam are displayed. The table **Calculation Results of the Selected Point** to the right contains the following information:

Parameter	Explanation
Position [mm]	The actual Z position of the translation stage for the selected data point.
Azimuth Angle [deg]	For 4 σ beam widths the azimuth angle is the absolute azimuth angle, calculated in accordance with ISO11146-1 using 4 σ beam widths. Note that the rotation range is <u>not</u> identical with the Orientation ^[62] used for the ellipse. Rotation angle range:



In case of ellipse clip level beam width the azimuthal angle shows a difference angle to a reference angle. Latter is calculated out of ten frames at the beginning of each beam quality measurement.

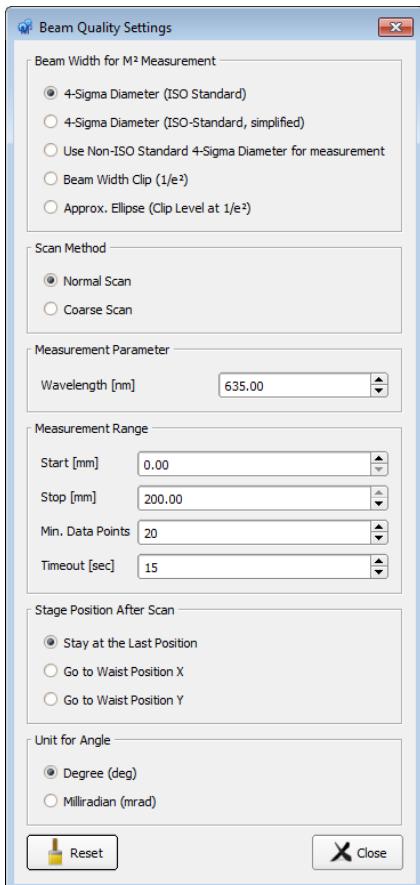
Ellipticity	The ellipticity of the fitted to an ellipse beam (see Application Note ^[166])
Beam Diameter X' [μm] Beam Diameter Y' [μm]	For 4 σ beam widths these are the ISO11146 compliant 4 σ beam diameters in the transformed coordinate system (not lab system) at the actual Z position. In case of ellipse clip level beam widths the shown values are the minor and major ellipse axes.
Centroid Position X' Centroid Position Y'	The positions of the beam centroids.

6. Status Bar

- Measurement progress bar
- Total number of measured data points
- Beam width setting for M² measurement
- Delay Line: Measurement range (difference between Start and Stop positions)
- Wavelength setting for beam quality calculation

6.8.3 M^2 Settings

For a successful and reliable measurement, the appropriate measurement settings are essential. Click  to enter the **M^2 Measurement Settings** dialog.



Beam Width

The calculation of the **4σ Diameter** follows the ISO 11146-1:2005 standard.

According to ISO11146-1, if the [ellipticity](#) ¹⁶⁶ is larger than 0.87, the beam profile may be considered to be of circular symmetry at the measuring location. In this case a simplified 4σ calculation can apply.

It is strongly advisable to select the 4σ (ISO) option to ensure that the M^2 measurement is in conformity with ISO11146-1.

Note

There are two different types of 4σ diameters considered:

When measuring the Beam Profile, in the [Calculation Results](#) ⁶² window the 4σ diameters are related to X and Y direction (lab system - see [Coordinate systems](#)) ¹⁶⁴

When measuring the M^2 beam quality, 4σ diameters are calculated for X' and Y' of the transformed coordinate system, which in general is oriented at a non-vanishing angle to the lab system. For more information see the ISO11146-1:2005 standard.

The **Approximated Ellipse** beam width is based on the 13.5% clip level. At the beginning of a measurement a reference angle is determined by averaging over 10 frames. This angle is then used to evaluate all following frames and ellipses.

Since the clip level width suffers from more noise and unsteadiness than the 4σ diameter you should only use this option with well-justified reasons.

Measurement Parameters

Setting the wavelength is mandatory for a correct M^2 measurement. If the lasing wavelength is unknown, measure the wavelength using a spectrometer.

Attention

Do not use the nominal wavelength of the laser, use the actual (measured) value! Accuracy of this input significantly impacts the measurement accuracy.

Measurement Parameter	
Wavelength [nm]	635.00
Measurement Range	
Start [mm]	0.00
Stop [mm]	200.00
Min. Data Points	10
Timeout [sec]	15

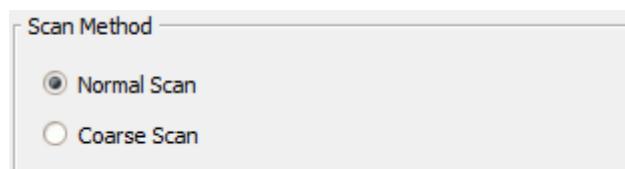
Measurement Range

The **Measurement Range** determines the distance between the Start and Stop position, in other words, the travel distance of the sleigh during the measurement. The travel distance can range from 5 mm to the full length of the stage.

Min. Data Points is the (minimum) number of Z positions at which measurements will be made.. The actual number depends also on the **Scan Method**.

Timeout is the max. waiting time for a valid camera image. This is to allow the Auto exposure function to obtain a valid camera image.

Scan Method



The software provides two different kinds of scan methods, the **Normal Scan** and the **Coarse Scan**.

The **Coarse Scan** just moves the translation stage from **Start** to **Stop** positions (or vice versa depending on the position prior to start the measurement). The number of recorded beam widths equates exactly to the entered number of **Data Points**.

The **Normal Scan** pursues an ISO compliant measurements. The ISO standard requires that "*... at least 10 measurements shall be taken. Approximately half of the measurements shall be distributed within one Rayleigh Length on either side of the beam waist, and approximately half of them shall be distributed beyond two Rayleigh Lengths from the beam waist.*"

The first run of the Normal Scan is executed with respect to the entered number of **Data Points**, in other words, like a coarse scan. A preliminary Rayleigh Length is calculated in order to evaluate if the number of measured data points is sufficient to fulfill the ISO standard requirements. If so, a hyperbolic fit is applied. If not, a second run adds additional measurements within the Rayleigh Length on both sides and/or beyond twice the Rayleigh Length.

For a M² measurement, running the Normal Scan is highly advised. The coarse scan is suitable for a first estimate of the beam waist position or other preliminary measurements.

Reset



Restores the default settings for M² settings:

Parameter	Default Setting
Beam Width	4-Sigma Diameter (ISO-Standard)
Wavelength	635 nm
Timeout	15 sec
Start	0 mm
Stop	200 mm
Min. Data Points	10
Scan Method	Normal Scan

Calculation Area

The settings for the **Calculation Area** can be made in the [Beam Settings panel](#)⁴⁷. During a Beam Quality Measurement (M² or Divergence), the Automatic Calculation Area is enabled by default for effective noise reduction. Reflections and artifacts from filters, lenses or other optical elements can be suppressed as well using the automatic Calculation Area.

This setting can be changed to manual, but this may affect the measurement.

By default the Clip Level of the Calculation Area is set to 1%. This is a reasonable value for most applications and measurements. Lowering the clip level leads to increased calculation area and noise level, this way increasing the measured the beam width.

For some cases it might be useful to adjust the Clip Level to cover the whole intensity.

Initial settings

Independently from the user-defined settings the following options are set automatically for every beam quality measurement.

Setting	Parameter
Calculation Area	Automatic
Auto Exposure	On
Ambient Light Correction	remains as set
Ellipse Clip Level	13.5%
Approximate Ellipse	On

Note

It is strongly recommended to run an [ambient light correction](#)^[37] prior to any measurement, and then enable Ambient Light Correction. This ensures the most accurate measurement.

Please be aware of the fact that ambient light correction is disabled any time the Beam software is started and/or the settings for [attenuation](#)^[36] (filter wheel) are changed in the software.

6.8.4 Saving the M² Measurement Results

Besides the standard function "[Save M² Test Results](#)"¹²⁴ the Thorlabs Beam software offers an [automatic saving of beam profile data](#)¹²⁶ when an M² measurement is executed.

6.8.4.1 Saving M² Test Results

The beam quality measurement results can be saved in two different ways:

1. Save Test Results

 Save measurement data as CSV (default). The [Save Test Protocol](#)⁹⁰ dialog opens, select the desired path, file name and file format (csv, txt or xls), fill in the desired fields and click Save. Below is an example:

```
Thorlabs Beam M2 Data Export

Date MM-DD-YYYY;07-04-2017
Time HH:MM:SS;15:12:07

Beam Profiler
Model;BC106N-VIS/M
Serial Number;M00311068
Test Method;Full Image
Wavelength;[nm];635
Beam Quality Measurement;M2
Beam Diameter Measure Method;4-Sigma Diameter (ISO-standard)

Parameter;Unit;Result;
M2x'; ;1.13;
M2y'; ;1.04;
M2 mean; ;1.08;

Beam Waist Position X';mm;85.77;
Beam Waist Position Y';mm;85.94;
Beam Waist Diameter X';μm;103.57;
Beam Waist Diameter Y';μm;97.24;

Rayleigh Length X';mm;11.76;
Rayleigh Length Y';mm;11.23;

Divergence Angle X';deg;0.504;
Divergence Angle Y';deg;0.496;

Divergence Asymmetry;%;0.984;

Z;X';Y';
50.00;330.74;324.50;
52.46;310.68;304.41;
53.75;299.99;294.70;
54.91;290.67;285.45;
57.36;270.61;265.44;
57.50;269.68;264.99;
59.82;250.56;246.00;
61.25;239.69;235.89;
65.00;210.59;206.05;
68.75;182.46;178.74;
72.50;156.66;151.46;
75.94;136.16;130.84;
76.25;134.82;129.66;
77.91;125.34;120.92;
79.87;116.32;112.90;
80.00;116.74;112.80;
81.84;107.49;103.95;
83.75;103.78;97.72;
83.81;103.11;97.63;
87.50;103.60;96.06;
91.25;115.40;107.74;
95.00;131.54;124.17;
98.75;155.21;145.72;
102.50;179.70;171.23;
106.25;208.61;201.04;
110.00;237.04;230.26;
113.75;266.47;260.29;
117.50;297.40;291.12;
121.25;329.56;322.25;
125.00;361.16;353.43;
```

2. Save Test Protocol

 Save measurement data as *.pdf file. The [Save Test Protocol](#) dialog opens, fill in the desired fields and click Save. The M^2 Measurement Results will appear in the PDF documents as in the example below:

M^2 Test Protocol

General Information: The test has been performed in accordance with ISO 11146.

Date (MM-DD-YYYY): 07-12-2017
 Time: 10:21:47
 Test Organisation: Thorlabs GmbH
 Performer: Beam Profiler

Information Concerning the Tested Laser:

Laser type: Pigtailed FP Laser Diode
 Laser Manufacturer: Thorlabs Inc.
 Model Designation: LPS-635-FC
 Serial Number: 140416-51

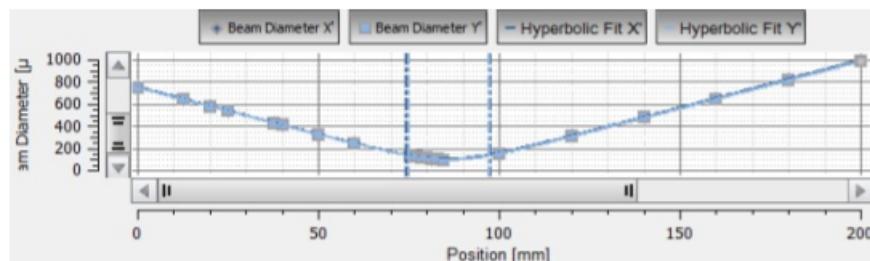
Test Conditions:

Laser Wavelength: 635 nm
 Operating Mode: CW

Information Concerning Testing and Evaluation:

Thorlabs Beam, Version 7.0.4097.310
 Test Equipment: BC106N-VIS/M
 Measurement Method: 4-Sigma Diameter (ISO Standard)
 Model: BC106N-VIS/M
 Serial Number: M00311068
 Test Method: Full Image
 Wavelength: 635 nm
 Scan Range: 0.00 - 200.00 mm
 Min. Data Points: 10

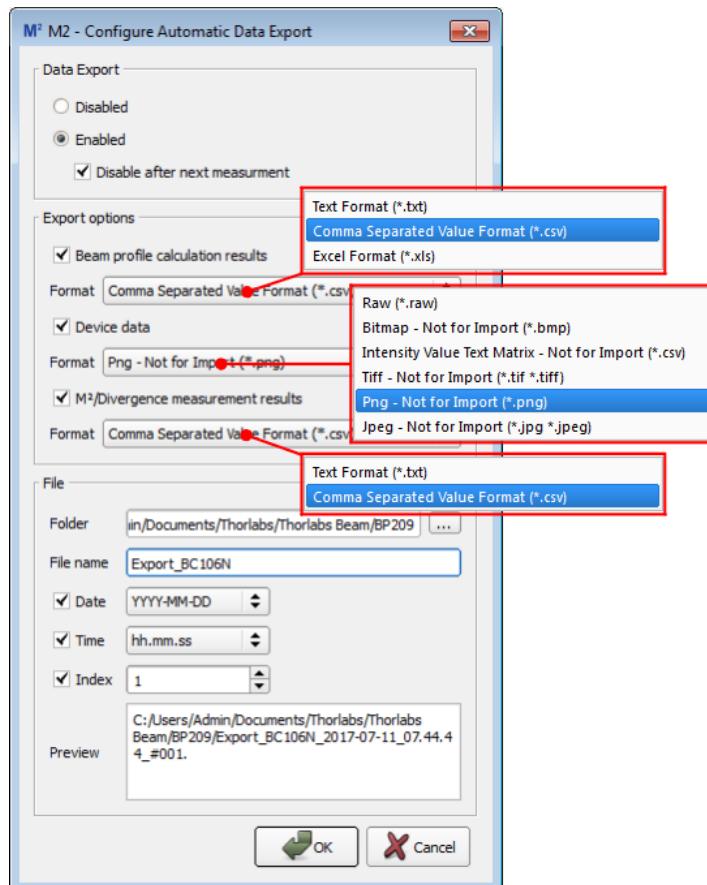
Parameter:	Unit:	Result:
$M^2 X$		1.09
$M^2 Y'$		1.02
M^2 mean		1.05
Beam Waist Position X	mm	85.93
Beam Waist Position Y'	mm	86.14
Beam Waist Diameter X	μm	101.38
Beam Waist Diameter Y'	μm	95.17
Rayleigh Length X	mm	11.63
Rayleigh Length Y'	mm	11.01
Divergence Angle X	deg	0.50
Divergence Angle Y'	deg	0.50
Divergence asymmetry	%	0.99



6.8.4.2 Saving Beam Profile Data During M² Measurement

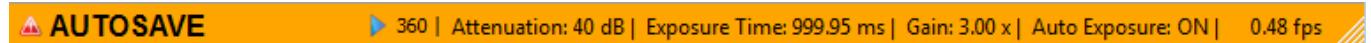
The Thorlabs Beam Software V7.0 comes with a new feature: During an M² measurement, the beam profile calculation results, the device data and the M² measurement results can be saved automatically at each position of the translation stage.

To configure this automatic data export click the  icon in toolbar on the left side of the M² panel. A dialog opens:

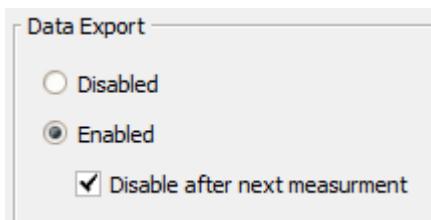


Section Data Export

Select **Enable** to activate the automatic export. The toolbar icon changes to  and the status bar on the bottom of the GUI appears as



The Data Export remains active until **Disable** is checked. If the data shall be saved only once, please check the boxes



Select **Disable after next measurement** to stop the automatic export after the first run of the M² measurement.

Section Export Options

Here the data to be exported can be selected by checking the appropriate box.

Beam Profile Calculation Results can be saved as *.csv, *.txt, or *.xls files. A single file is saved; for each stage position the data are appended to the existing file. The export file contains the header (information about Beam software version, time stamp of measurement start, and information about the used beam profiler) and all calculation results (see section [Calculation Results](#)⁶²; option "Select All"). The name of this file is formed by appending the string "data" to the base file name.

With **Device Data** enabled, at each stage position the intensity values that are retrieved from the beam profiler are saved to an individual file. For device data and file formats, please see section [Export Device Data](#)⁸⁵. The name of this file is formed by appending the string "device" to the base file name.

When **M^2 / Divergence Measurement Results** is enabled, the M^2 test results are saved in *.txt or *.csv format as well; see section [Saving \$M^2\$ Test Results](#)¹²⁴.

Section File

- Select the desired target file folder for the automatic data export.
- Choose a file name.
- Add the date (optional)
- Add the time stamp (optional)
- Add an index (optional). The index must be set manually!
- The box Preview shows the prefix of the file name with selected options.

When done, click **OK**. Now, the M^2 measurement with automatic data export can be started.

File Naming with Automatic Data Export

Beam Profile Calculation Results	
 Export_BC106N_2017-07-11_07.44.44_#001_Data.csv	prefix with date, time and manual index "Data" stands for Beam Profile Calculation Results
Device Data	
 Export_BC106N_2017-07-11_07.44.44_#001_Device_2017-07-11_09.14.56_#001.png	prefix with date, time and manual index "Device" stands for Exported Device Data (here: image of the beam). Followed by individual time stamp and automatic index of the appropriate stage position
M^2 / Divergence Measurement Results	
 Export_BC106N_2017-07-11_07.44.44_#001_Results.csv	prefix with date, time and manual index "Results" stands for M^2 test results

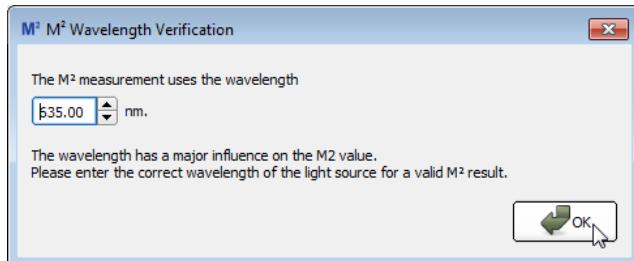
6.8.5 Running the M² Measurement

Prior to starting a measurement, make sure that the following conditions are fulfilled:

- The beam is aligned properly - it should ideally remain centered with respect to the sensor center over the entire scan range. Section [Beam Alignment](#)^[109] describes in detail how to achieve this.
- The beam diameter should be in accordance with the [Requirements to Beam Diameter](#)^[102].
- The exact wavelength of the laser under test is well known, as the wavelength value influences the M² results.
- Ambient light may disturb the measurement and should be avoided.
- Reflections and interferences are avoided as far as possible.
- The laser system is warmed up - depending on the source this might take up to 1 hour.
- The laser output is spatially and temporally stable.

Start the measurement by clicking the **Start** button ▶.

You will be prompted to confirm the laser wavelength:



Verify the wavelength and click **OK**.

While running the measurement most of the buttons and options are disabled, e.g. the M² Measurement Settings and the Toolbar. This is intentional and prevents any settings changes during the measurement.

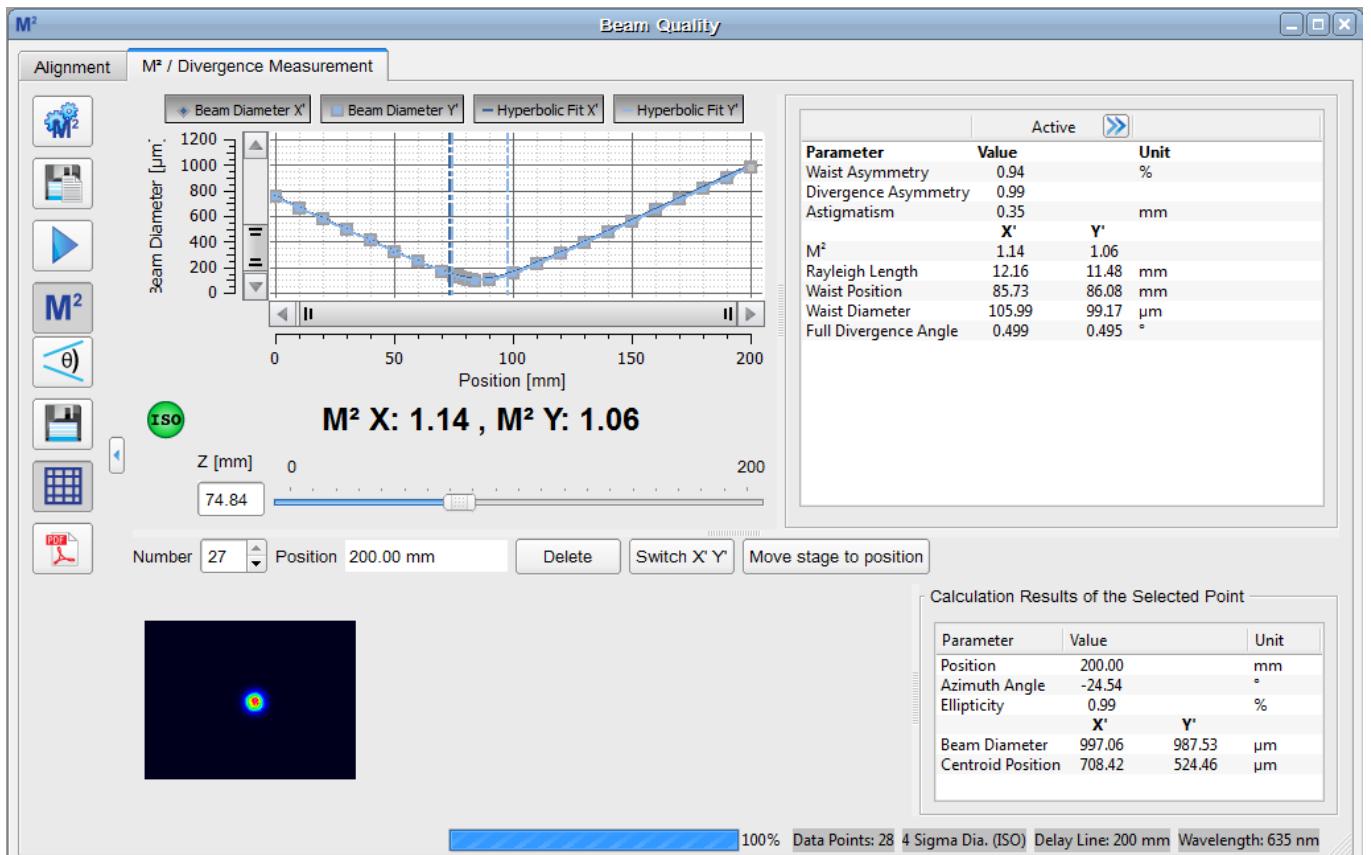
The measurement can be interrupted at any time by clicking the **Stop** button ☛.

After starting the measurement the X axis of the graph is adapted to the user-defined scan range, for example from 50 to 125 mm. The Y axis scales automatically to the recorded beam width.

If the **Normal Scan** is applied the scale on the graph zooms in when the fine scanning adds additional data points. After this step (at the end of the measurement) the full scan range is shown again.

6.8.6 M^2 Measurement Results

After a successful M^2 measurement, the **Beam Quality Measurement** window appears as below.



The green bulb indicates that the measurement was successful and fulfills the ISO 11146 standards:



M² X: 1.14 , M² Y: 1.06

In the case that a different from the ISO standard beam width criteria was used (see [M² Settings](#) 121), a successful measurement is shown without the ISO indication:



M² X: 1.14 , M² Y: 1.06

In general, the X' and Y' axes do not coincide with the lab system (described by the X and Y axes). Furthermore, the M² value for X' is independent from the one for Y'. For highly elliptical beams, such as those from semiconductor lasers, M²X' and M²Y' will differ much more than in this example.

Diagram Legend

- ◆ Beam Diameter X'
- Beam Diameter Y'
- Hyperbolic Fit X'
- Hyperbolic Fit Y'

These values can also be found in the listing of the complete results next to the diagram:

Parameter	Value	Unit
Waist Asymmetry	0.94	%
Divergence Asymmetry	0.99	
Astigmatism	0.35	mm
	X'	Y'
M ²	1.14	1.06
Rayleigh Length	12.16	11.48 mm
Waist Position	85.73	86.08 mm
Waist Diameter	105.99	99.17 μm
Full Divergence Angle	0.499	0.495 °

Waist Asymmetry stands for the ellipticity at the waist position and is calculated by taking the ratio of the waist diameters in both X' and Y' directions. A waist asymmetry of 1.0 indicates a round beam spot.

$$\text{waist asymmetry} = \frac{d_{0y}}{d_{0x}}$$

Divergence Asymmetry is the ratio of the divergence angles in Y and X axes. Values differing from 1.0 indicate that the beam ellipticity is changing with Z position, for instance when an elliptical beam is focussed to a round spot.

$$\text{divergence asymmetry} = \frac{\theta_y}{\theta_x}$$

Astigmatism is known as the effect that the beam waist in X and Y scan direction is not at the same z position. So there is a difference between the positions of minimal spot diameters z_{0y} and z_{0x} .

$$\text{astigmatism_abs} = z_{0y} - z_{0x}$$

M² X' and M² Y' are the M² value for X' / Y' axis, calculated from the hyperbolic fit of the measured data points.

Rayleigh Length X' (Y') is the calculated distance [mm] from the beam waist position X' (Y') to the position, where the beam diameter of the appropriate axis is $\sqrt{2}$ times larger than the waist diameter. See also section [M2 Theory](#) [150].

Waist Position X' (Y') Z position of the beam waist (smallest beam diameter). This is the calculated beam waist position in mm derived from the curve fit. This value may differ from the position where the smallest beam width was measured.

Waist Diameter X' (Y') is the beam diameter in the X' (Y') direction at the focal point. This is the calculated minimum beam diameter [μm], derived from the curve fit. This value may differ from the smallest measured beam width.

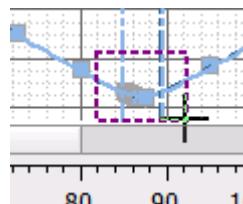
Full Divergence Angle is explained in section [M2 Theory](#) [150].

Note

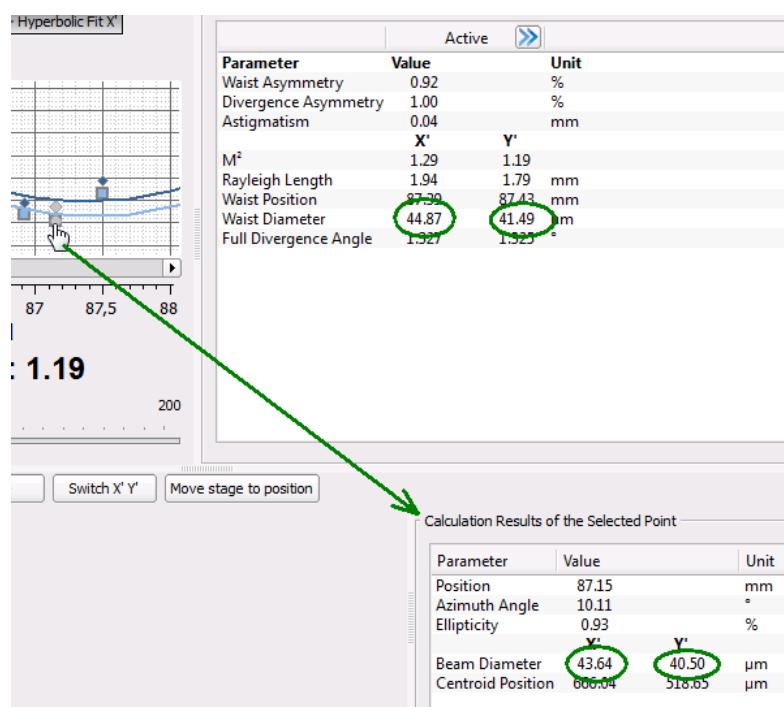
All results are calculated from the applied fit!

Display the Results at a Certain Z Position

After measurement is finished, the calculated beam diameter, the beam centroid positions (X' and Y'), and the beam ellipticity as well as azimuthal angle can be retrieved for a certain Z position from the diagram. To do this, move the mouse pointer over the measured curves. For better visualization, the curves can be zoomed by dragging a rectangle:



As soon as the mouse pointer hits a measurement point, its shape changes to . Click this point. The position and calculated values corresponding to the clicked point will appear in the **Calculations Results of the Selected Point** panel:

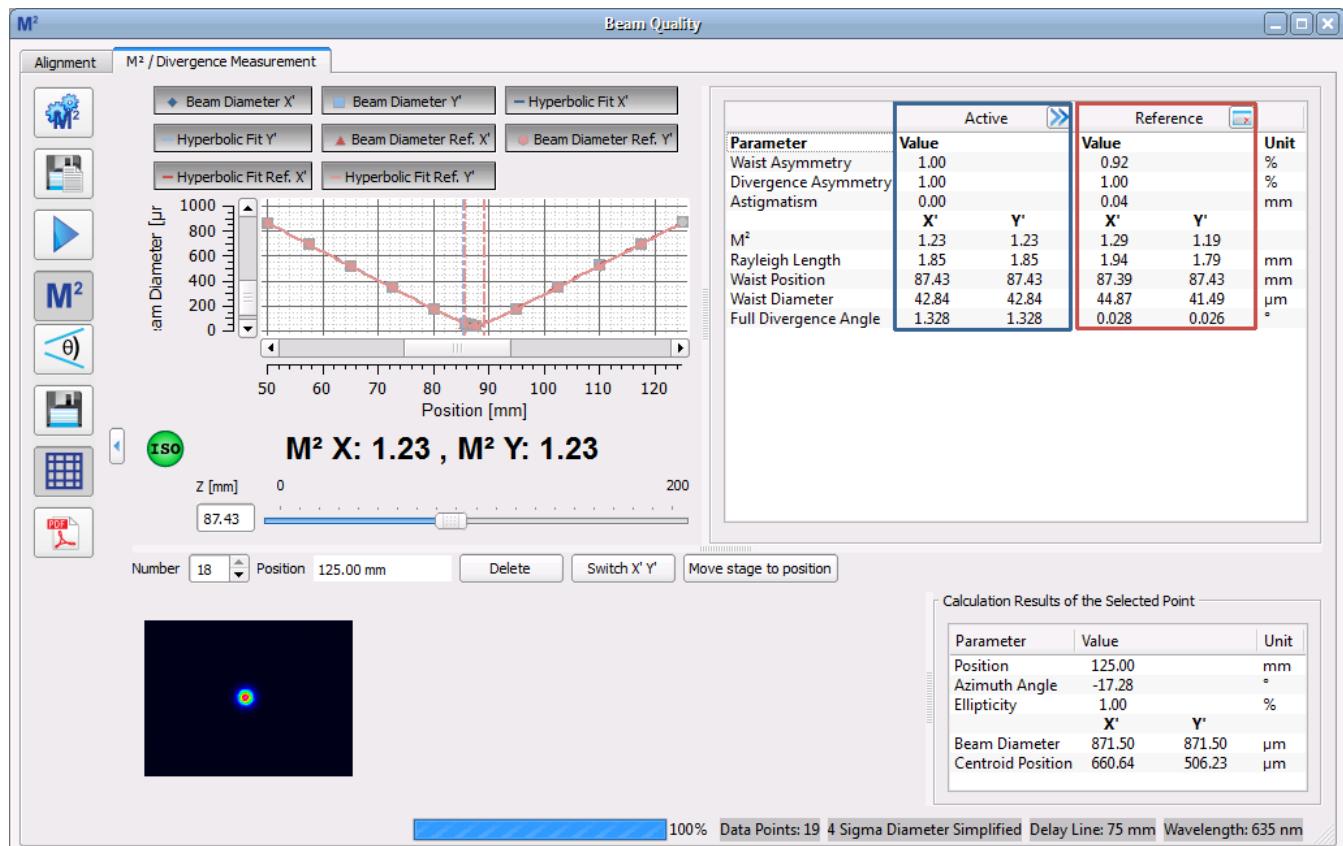


Note

In contrast to the **Results** pane, the results shown here are calculated from the measured data point without a hyperbolic fit. Therefore, the diameter value displayed at the actual waist may differ from the X' (Y') waist diameters.

Reference Measurement

After a M^2 measurement is completed, the results can be saved and afterwards used as a reference. To do this just click the button, the active results become the reference. Further, the reference data are added to the diagram in a different color.



Reference Diagram Legend:

- Beam Diameter Reference X'
- Beam Diameter Reference Y'
- Hyperbolic Fit Reference X'
- Hyperbolic Fit Reference Y'

Clicking to the Clear icon deletes the reference data.

Please refer to section [Saving M² Test Results](#)^[124] for details about how to save the results of the beam quality measurement.

6.8.7 M^2 Troubleshooting

Below are examples of typical problems that may occur and appropriate recommendations for resolving them.

The beam does not hit the sensor at all positions of the stage.

Perform a proper [Beam Alignment](#) .

A timeout error occurs during a measurement.

A timeout always occurs when the Beam Profiler camera does not get a valid image. This may be caused by:

- Saturation of the camera. Since the beam is focused the intensity is the higher the smaller the beam width. This may lead to a saturation of the camera. To resolve, attenuate the laser beam with additional ND filters or decrease the laser output power. Alternatively use a lens with larger focal length if possible; this will increase the diameter of the focal spot and in this way lower the focal power density.
- A Normal Scan is applied and the Fine Scan shall add data points. The exposure time has then to change from long exposure times to small values. This can take more time than the timeout allows. Set the timeout to a greater value to solve this problem ([M² Settings](#) ).
- The beam power to the sensor is too low. Remove ND filters or increase output power of the laser.
- The beam size is too small and no ellipse could be calculated (if Clip Level Ellipse is selected as beam width). Use a lens with a longer focal length to increase focal beam size.
- The beam does not hit the CCD sensor. Align the beam, see section [Beam Alignment](#) .

Parasitic reflections walk over the CCD sensor during the measurement.

This may happen, if the beam is not perfectly aligned and/or the filters are not parallel to the CCD chip. The laser beam is reflected from the CCD surface back to a filter and again back to the CCD sensor. The position of such a double reflection changes with stage movement.

The detection of these reflections can be improved by using the logarithmic color scale that accentuates smaller intensities.

The scale can be switched from **linear** to **logarithmic** by clicking on the color scale.

Then perform a proper [Beam Alignment](#) .



The M^2 value differs substantially from the expected value.

For example, the beam has a nearly Gaussian intensity distribution and M^2 values are larger than 1.1:

- Check set wavelength (see [M² Settings](#) )
- Check Clip Level of the **Calculation Area**:
 - ▶ If the selected Clip Level is too high, the beam might be cut off and the measured beam area might be smaller than the actual beam extend. This results in a too small beam waist and a too small M^2 (even below 1).
 - ▶ If the selected Clip Level is too low, the Calculation Area and the measurement captures the beam plus noise around the beam. The measured beam width is then larger than

the actual beam width. This leads to an increased M^2 .

□ **M^2 is smaller than 1.0 - How can this be?**

M^2 values < 1.0 are non-physical but may be due to

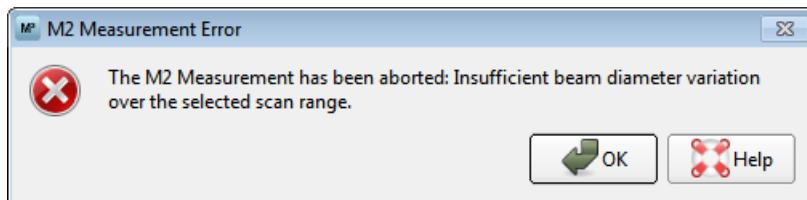
- A too small Calculation Area (Clip Level too high - see [M2 Settings](#))
- The accuracy of the measured result. An error of 5% should be considered.
- The wavelength setting was not made properly. Set the wavelength to the correct value; M^2 results will be corrected without running a new measurement.

□ **The beam profile looks distorted (particularly, at the end positions of the stage).**

Even if a laser is expected to produce a Gaussian beam with $M^2 = 1.0$, the beam still can be influenced by every optical element between laser and Beam Profiler. For instance, a focusing lens could be mounted with a tilt or could produce a height distortion which results in optical aberrations and reduced beam quality.

Filters and mirrors may impact on the beam profile as well in the case that surfaces are contaminated. Clean surfaces according to manufacturer's instructions.

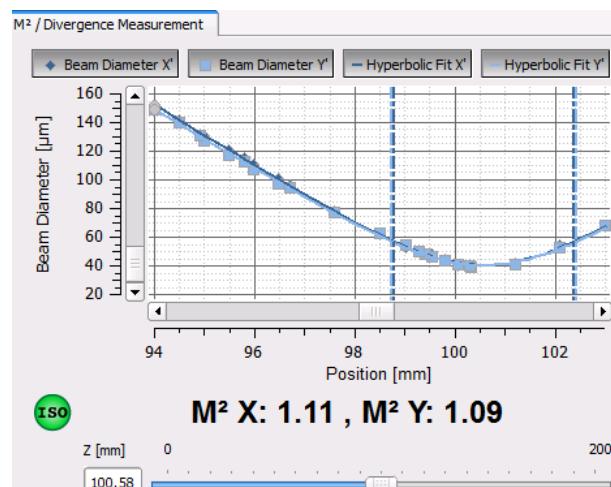
□ **Error message**



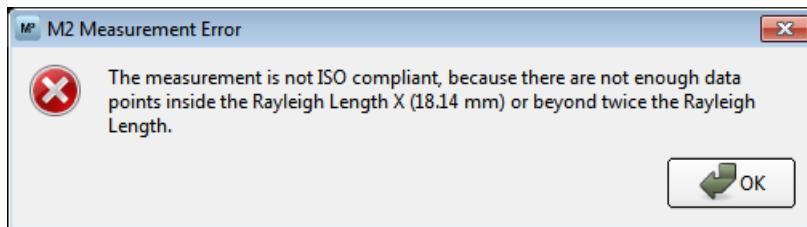
"The M² Measurement has been aborted: Insufficient beam diameter variation over the selected scan range."

The software could not locate sufficient measurement points within the doubled Rayleigh Length.

- Extend the [Measurement Range](#).
- Select a focusing lens with a shorter focal length.
- Rule of the thumb: the beam diameter variation within the scan range should not underrun a ratio of 1:2.5 at least at one side of the beam waist - see the example below.



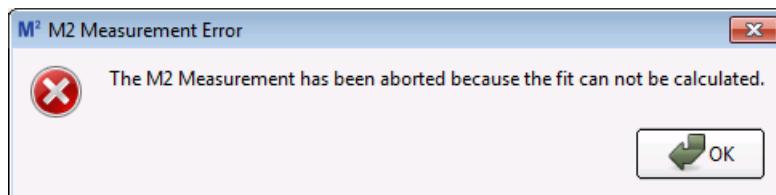
□ Error message



"The measurement is not ISO compliant, because there are not enough data points inside the Rayleigh Length X (Y)(xx mm) or beyond twice the Rayleigh Length"

- The software could not measure with the required resolution.
- Increase the minimum number of data points (see [M² Settings](#) [121]).
- If the error message persists, increase the scan range as well.

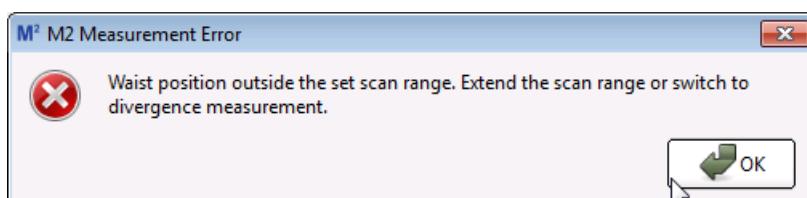
□ Error message



"The M² measurement has been aborted because fit cannot be calculated."

- The calculation of the hyperbolic fit from the measured data points is impossible. Possible reasons are, for example, that the beam waist is far away from the scan range, or that no focal lens was used.
- Reset the M² Settings to default - that sets the scan range to its maximum.
- Check your setup to make sure the beam waist is within the scan range.
- If no focal lens was used, only a divergence measurement is possible!

□ Error message



"Waist position outside the scan range. Extend the scan range or switch to divergence measurement."

- The calculation of the hyperbolic fit from the measured data points resulted in a beam waist position outside the scan range. Usually this happens if the beam waist is close to one of the scan end positions. Extend the scan range.
- Reset the M² Settings to default - that sets the scan range to its maximum

6.9 Divergence Measurement

The **Divergence Measurement** calculates the divergence angle of an unfocused convergent or divergent beam by measuring the beam diameter at different points along beam propagation axis. A linear fit is applied to the measured data.

The measurement technique is very similar to the Beam Quality (M^2) measurement, thus the same hardware can be used with exception of the focusing lens.

The Divergence Measurement is part of the **Beam Quality** measurement tool and uses the M2MS extension as well.

6.9.1 Beam Alignment

Why Beam Alignment?

The Beam Profiler has a defined input aperture, so when moving the translation stage it must be ensured that the laser beam remains within the aperture. Ideally, the beam centroid remains centered within the aperture during movement of the stage - this is a precondition for correct beam quality measurements.

The M2MS Measurement System is factory aligned. A beam entering the M2MS exactly parallel the stage movement direction will remain centered to the Beam Profiler aperture during stage movement. In other words, the beam alignment is dependent only on the position of the light source. In the common case, the light source is a device with open beam output. In order to direct the beam under test into the M2MS, a combination of two adjustable mirrors is required, Thorlabs offers a variety of such items.

The beam alignment is executed in 2 steps, guided by a software wizard:

1. [Coarse alignment](#)¹³⁷: Determine the correct location of the Laser Under Test output aperture by means of an auxiliary laser (included).
2. [Beam Alignment](#)¹³⁸ of the Laser Under Test for minimum beam displacement and pointing angle.

6.9.1.1 Coarse Alignment

For a coarse alignment, Thorlabs provides an alignment laser that is included with the accessory box. For this step, the alignment laser is mounted on the M2MS in place of the Beam Profiler. It is mounted and aligned in such way that its output beam enters the M2MS exactly centered in the Beam Profiler's aperture and is parallel to the stage movement direction. The alignment beam is reverse directed - it virtually exits the Beam Profiler and is redirected by the two mirrors of the stage into the center of the laser source aperture (see the drawing in section [M2MS Operating Principle](#) [101]).

Warning

Be careful when using this laser!



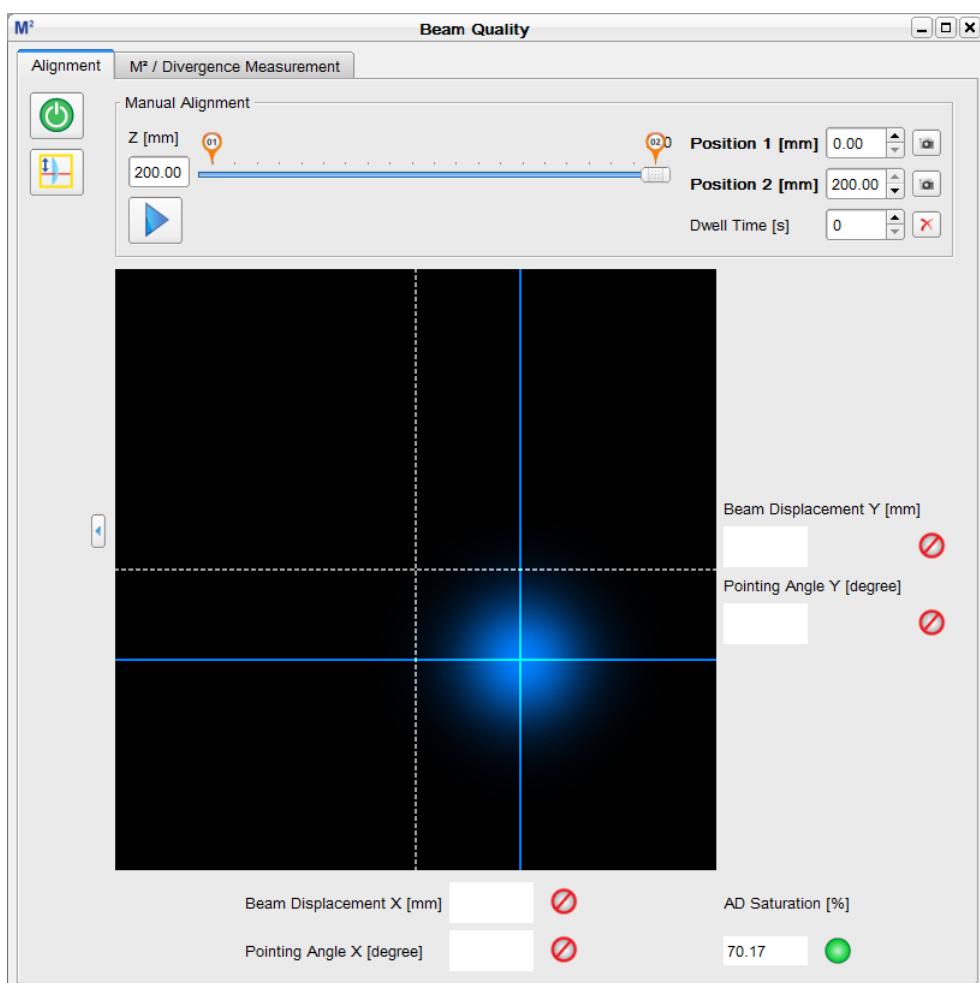
- Remove the Beam Profiler together with its mounting adapter from the M2MS base.
- Install the adjustment laser in place of the Beam Profiler and connect its 3.5 mm plug to the [Alignment Laser output \(2\)](#) [108].
- Make sure the M2MS is switched on and connected to the control PC, the Beam software is started and the stage has been initialized.
- Remove the focal lens from the magnetic holder.
- Switch on the alignment laser.
- Align your optical system so that the spot of the alignment laser hits the center of your light source.

6.9.1.2 Fine Alignment

After coarse alignment, the beam under test needs to be fine-adjusted using the **Alignment** feature of the M² measurement panel. This is executed in two steps.

Preparation

- Switch off the alignment laser and replace it with your Beam Profiler.
- Remove the focusing lens (see  in the drawing in the [M2MS Operating Principle](#) [101] section).
- Connect the Beam Profiler to one of the M2MS USB outputs (, [Connection to the PC](#) [108] section).
- Make sure it is being recognized by the Beam software (Toolbar  [Device Selection](#) [109]). If it is not recognized automatically, press the **Refresh Device List** button.
- Make sure the stage is recognized and initialized. If not, press the [Refresh Stage List button](#) [109] and after the stage was recognized, double click to the DDSM100 button. The stage initializes and moves to the 200 mm position.
- Enable the Laser Under Test.
- Open M² child window either from the menu "Windows" -> "M² Quality Measurement" or by clicking the **M²** button, and switch to the Alignment tab.

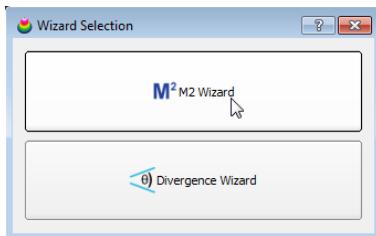


Explanation of indicators and icons

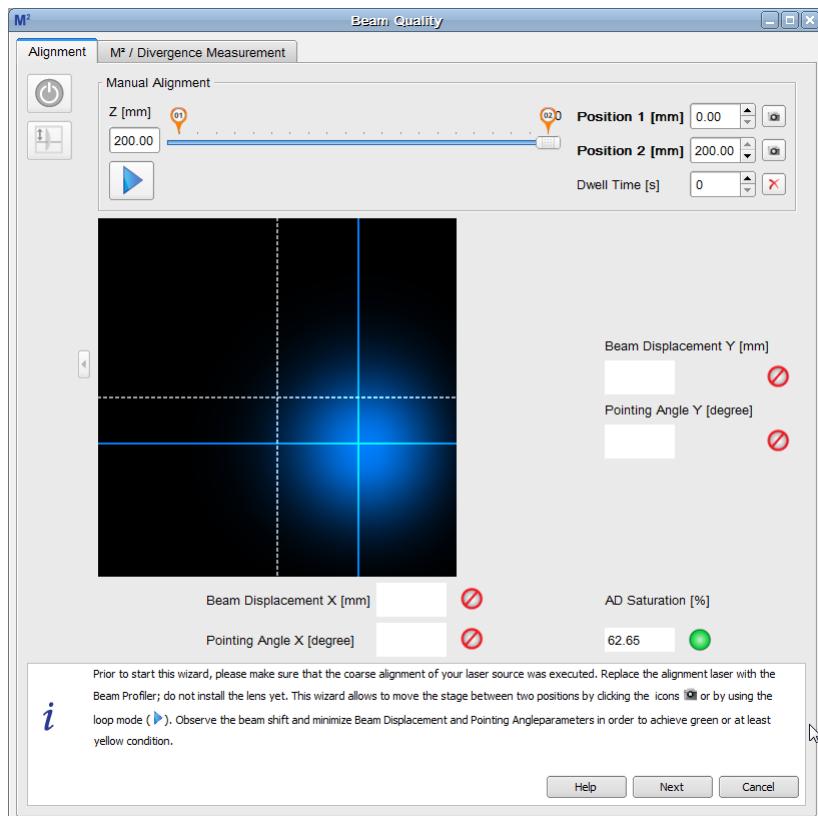
	Start the Alignment Wizard
	Start the Focusing Lens Alignment Wizard
Z [mm]	This box shows the actual stage position; after initialization = 200 mm.
Position 1 (2) [mm]	Here the left and right positions for the stage movement can be entered numerically.
	Markers for left and right positions. Instead of numerical entry of the markers' positions, the markers can be move by drag-and-drop.
	Clicking these capture buttons, the stage moves to the related position, if not there yet, and captures the beam centroid position (amber crosshair). This snapshot will remain until the stage comes back to the appropriate position.
	This button starts the stage loop movement mode and the stage moves continuously between positions 1 and 2. A dwell time at the end positions can be entered. During the loop mode, the software automatically captures the beam centroids (yellow cross hair) at the left and right stop.
Dwell Time	Enter the desired time [sec]. The dwelling can be disabled by clicking to the icon.
	Centroid crosshair of the actual beam position.
	Crosshair of the sensor center
Beam Displacement	is the centroid shift in X (Y) direction between position 2 and 1 [mm]. The box is first time filled after the 2nd capture.
Pointing Angle	is the angle [°] in X (Y) direction between the beam axis and the stage movement direction. The box is first time filled after the 2nd capture.
Alignment Success Indicator	Alignment not successful Alignment sufficient for correct Beam Quality Measurement (displacement < 0.65 mm, angle < 0.35°) Good alignment (displacement < 0.35 mm, angle < 0.15°)
AD Saturation	Displays the current saturation of the Beam Profiler's AD converter. For proper beam alignment function the value must be 80 to 95 %. The green bulb to the right of the numeric field indicates the "GOOD" range.

6.9.1.3 Divergence Beam Alignment Wizard

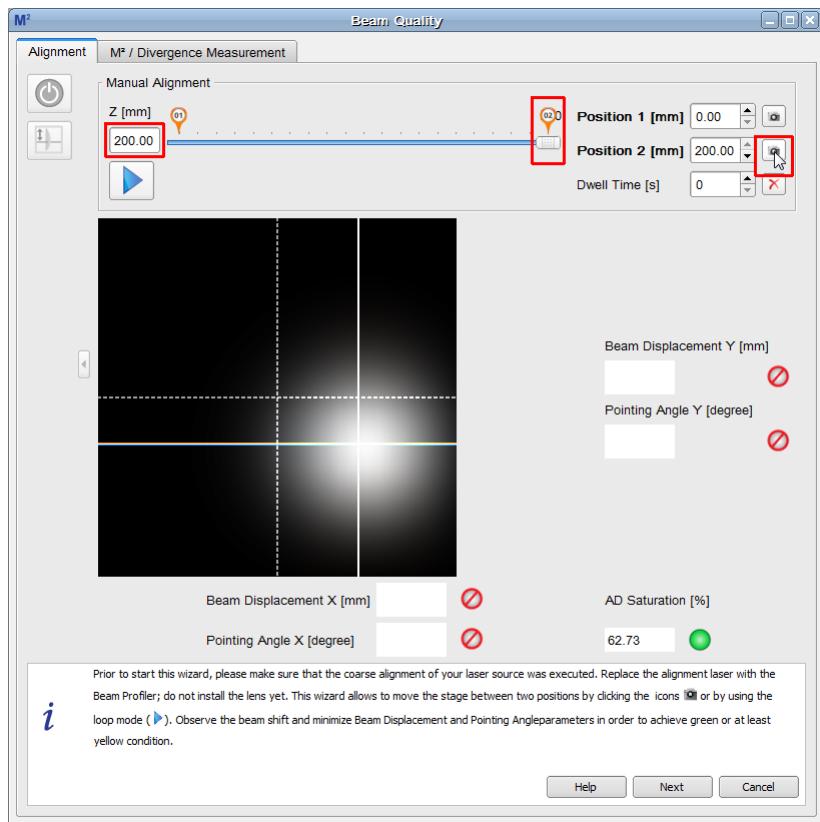
Press the **Start Wizard** button . You will be requested to select whether you want to adjust for M² or Divergence Measurement. Make your choice:



The wizard starts:

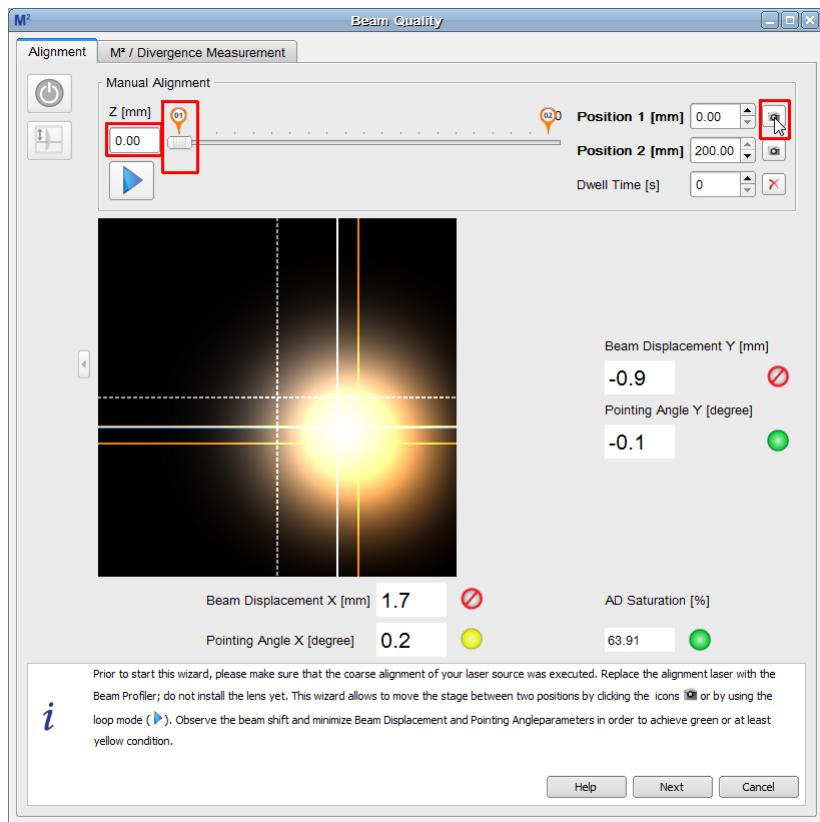


- For a successful alignment, the optical power level must be adjusted in such way that the AD Saturation is between 80 to 95 %. The green bulb to the right of the numeric field indicates the "GOOD" range. During alignment this condition must not change!
- After initialization, the stage is at Position 2 (200 mm). Click the capture button of Position 2 - the centroid is captured, and its crosshair color changes to amber. As the actual beam centroid that is marked by a blue crosshair, is located at the same position, the resulting color is white:



Centroid captured at Position 2

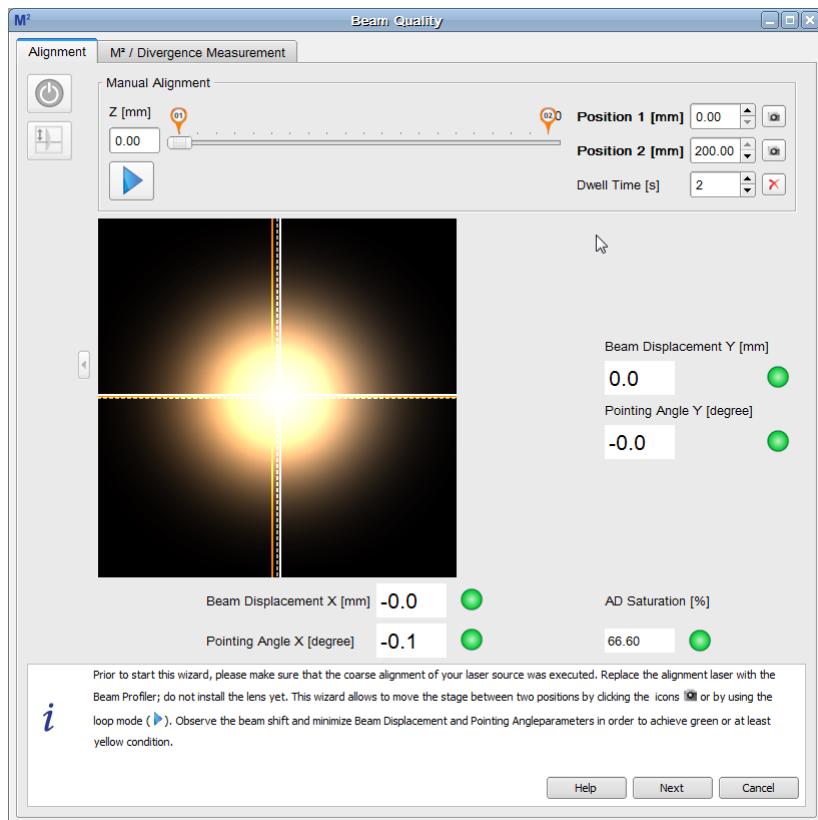
- Click to the Position 1 capture button (0 mm). The stage moves to Position 1 and captures the second centroid position:



Centroid captured at Position 1

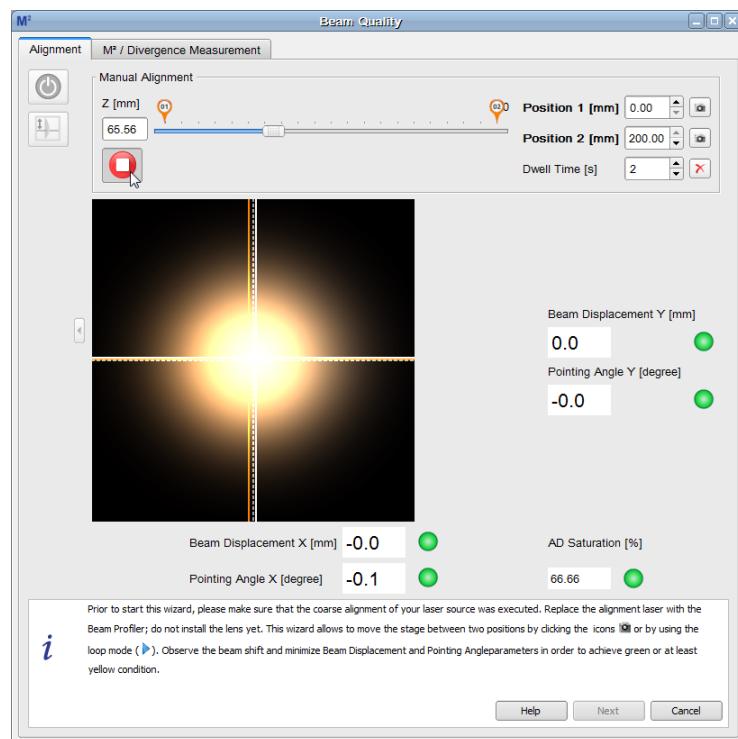
- Now, the beam displacement and the pointing angle are displayed numerically.

- Align the beam position using the controls of your laser source. Subsequently click the capture button of position 1 and 2, observe the alignment, and improve it until all four alignment criteria are fulfilled (bulbs must be at least yellow):



Well aligned beam position

- The movement of the stage between the two stop positions can be controlled automatically by the software. Just push the loop button and enter a convenient dwell time value. The stage starts a loop move, dwelling at the stop position for the given time. During the dwelling a realignment can be made. Please keep in mind, that the numeric alignment indicators are being updated only after the next move.

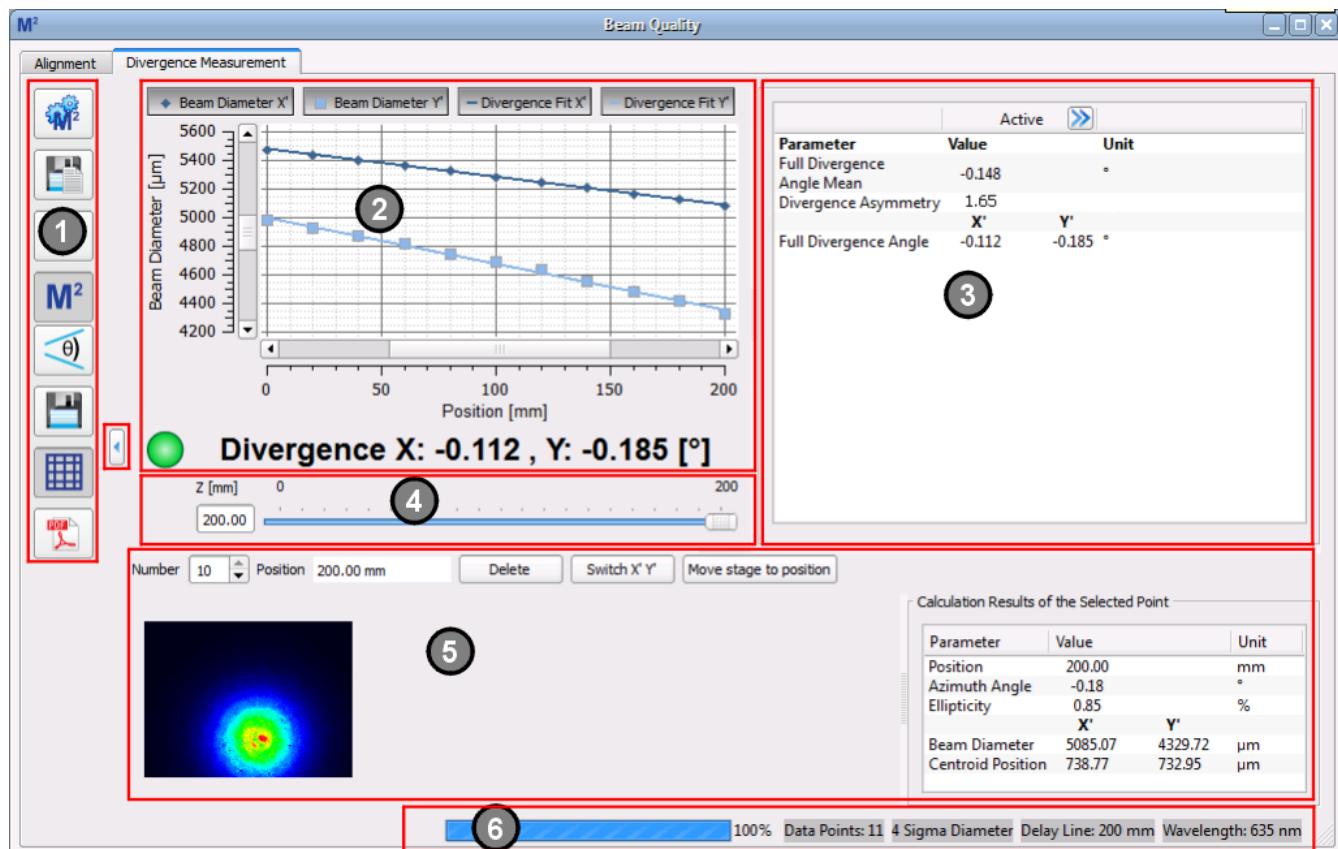


Alignment Move Loop

- The loop terminates by clicking the button.
- After finishing, click **Next** to continue.

6.9.2 Divergence Measurement Panel

The **Divergence Measurement Panel** is derived from M² Measurement window:



The Divergence Measurement panel is divided into 6 sub panels:

1. Toolbar

	Divergence Settings	Opens the settings for the Divergence measurement <small>[146]</small>
	Auto Save Data	Save Beam Profile Data during M² Measurement <small>[126]</small>
	Start / Stop	Starts / stops a Divergence measurement
	M ²	Switches to M ² measurement
	Divergence	Switches to Divergence measurement
	Save Data	After a successful Divergence measurement this button is enabled and plot data can be saved.
	Grid	Disables/Enables the grid in the diagram
	PDF Test Protocol	Saves the results of a Divergence measurement into a PDF file

2. Divergence Diagram

The measured data are plotted in the diagram. The 4 buttons above the diagram allow the display to be configured: The buttons **Beam Diameter X' (Y')** enable / disable the display of the measured data at the individual positions, while the buttons **Divergence Fit X' (Y')** enable / disable the curve fit to the measured data points.

After the measurement is finished, below the diagram the Divergence results for the X and Y axes are displayed. To the left, an indicator shows if the measurement was successful.

The red marked button  between the toolbar and the diagram expands the diagram over the entire Divergence window.

3. Numeric Results

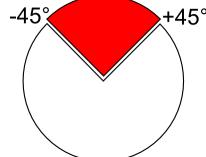
In this area, the beam quality measurement results are displayed in detail. Please see section [Divergence Measurement Results](#)^[149] for more details.

4. Position Bar

The Position Bar below the Divergence Diagram shows the actual position of the translation stage as seen before in the [Alignment](#)^[112] tab.

5. Individual Data Points

Select in the header of this sub-panel the **Number** of the desired measured data point. For this selected point, the position of stage and the the 2D projection of the beam are displayed. The table **Calculation Results of the Selected Point** to the right contains the following information:

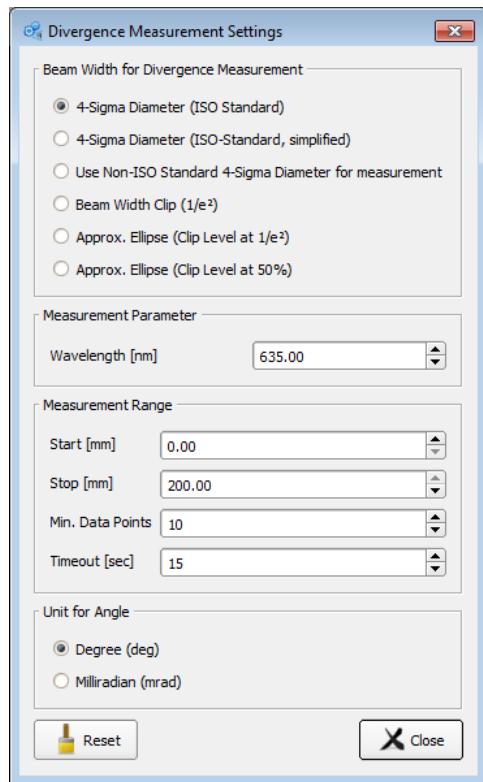
Parameter	Explanation
Position [mm]	The actual Z position of the translation stage for the selected data point.
Azimuth Angle [deg]	For 4σ beam widths the azimuth angle is the absolute azimuth angle, calculated in accordance with ISO11146-1 using 4σ beam widths. Note that the rotation range is <u>not</u> identical with the Orientation ^[62] used for the ellipse. Rotation angle range:
	
	In case of ellipse clip level beam width the azimuthal angle shows a difference angle to a reference angle. Latter is calculated out of ten frames at the beginning of each beam quality measurement.
Ellipticity	The ellipticity of the fitted to an ellipse beam (see Application Note ^[166])
Beam Diameter X' [μm]	For 4σ beam widths these are the ISO11146 compliant 4σ beam diameters in the transformed coordinate system (not lab system) at the actual Z position.
Beam Diameter Y' [μm]	In case of ellipse clip level beam widths the shown values are the minor and major ellipse axes.
Centroid Position X'	The positions of the beam centroids.
Centroid Position Y'	

6. Status Bar

- Measurement progress bar
- Total number of measured data points
- Beam width setting for divergence measurement
- Delay Line: Measurement range (difference between Start and Stop positions)
- Wavelength setting (not relevant for divergence calculation)

6.9.3 Divergence Measurement Settings

For a successful and reliable measurement, the appropriate measurement settings are essential. Click to  to enter the **Divergence Measurement Settings**.



Beam Width

The Beam Width calculation is based on an ellipse-based approximation with two possible clip levels. At the beginning of a measurement a reference angle is determined by averaging over 10 frames. This angle is then used to evaluate all following frames and ellipses.

Measurement Parameters

The wavelength is not relevant for divergence measurement.

Measurement Range

determines the distance from the starting to the stopping point over which the sleigh is driven during the measurement. **Start** has to be at least 5 mm smaller than **Stop** and ≥ 0 mm. Valid values for Stop are

$5 \text{ mm} < \text{Stop} < \text{stage length}$.

Note

It is advisable to set up a scan range > 40 mm to ensure higher accuracy. A scan over the entire translation length is often the best choice.

Timeout is the max. waiting time for a valid camera image. This is to allow the Auto exposure function to obtain a valid camera image

Stage Position After Scan

is not relevant for divergence measurement.

Angle Unit

Degree or milliradian can be selected.

Reset



Restores the default settings for divergence settings:

Parameter	Default Setting
Beam Width	4σ Diameter (ISO Standard)
Start	0 mm
Stop	200 mm
Min. Data Points	10
Timeout	15 sec

Calculation Area

The settings for the **Calculation Area** can be made in the [Beam Settings Panel](#)^[47]. During a Beam Quality Measurement (M^2 or Divergence) the Automatic Calculation Area is enabled by default for effective noise reduction. Reflections and artifacts from filters, lenses or other optical

elements can be suppressed as well using the automatic Calculation Area which is close to the beam profile.

This setting can be changed to manual, but this may affect the measurement.

By default the Clip Level of the Calculation Area is set to 1%. This is a reasonable value for most applications and measurements. Lowering the clip level leads to increased calculation area and noise level, this way increasing the measured beam width.

Note

Setting the Clip Level of the Calculation Area for divergence measurements is not as critical as for M^2 measurements. Increasing the Clip Level will give smaller beam widths but might cut the beam profile.

Initial Settings

Independently from the user-defined settings, the following options are set automatically for every divergence measurement.

Setting	Parameter
Calculation Area	Automatic
Auto Exposure	On
Ambient Light Correction	remains as set

Note

It is strongly recommended to run an [ambient light correction](#)³⁷ prior to any measurement, and then enable Ambient Light Correction.

Please be aware of the fact that ambient light correction is disabled any time the Beam software is started and/or the settings for [attenuation](#)³⁶ (filter wheel) are changed in the software.

6.9.4 Saving the Divergence Measurement Results

Besides the standard function "Save Divergence Measurement Results" the Thorlabs Beam software offers an automatic saving of beam profile data when a Divergence measurement is executed.

For details, please see section [Saving the M² Measurement Results](#)¹²⁴.

Note

The Divergence measurement results cannot be saved as PDF Test Protocol, only as CSV, TXT or XLS files.

6.9.5 Running the Divergence Measurement

The divergence measurement is designed to measure low divergent or convergent beam propagation. Therefore, the measurement requires removing any focusing elements which produce a beam waist within the scan range.

Prior to starting the measurement, make sure that:

- The beam is aligned properly - it should ideally remain centered with respect to the sensor center over the entire scan range. See chapter [Beam Alignment](#)¹³⁶ for aligning the beam.
- The ambient light is turned off or dimmed as far as possible. Ambient light may disturb the measurement and should be avoided.
- Reflections and interferences are avoided as far as possible.
- The laser system is warmed up - depending on the source this might take up to 1 hour.
- The laser output is spatially and temporally stable.

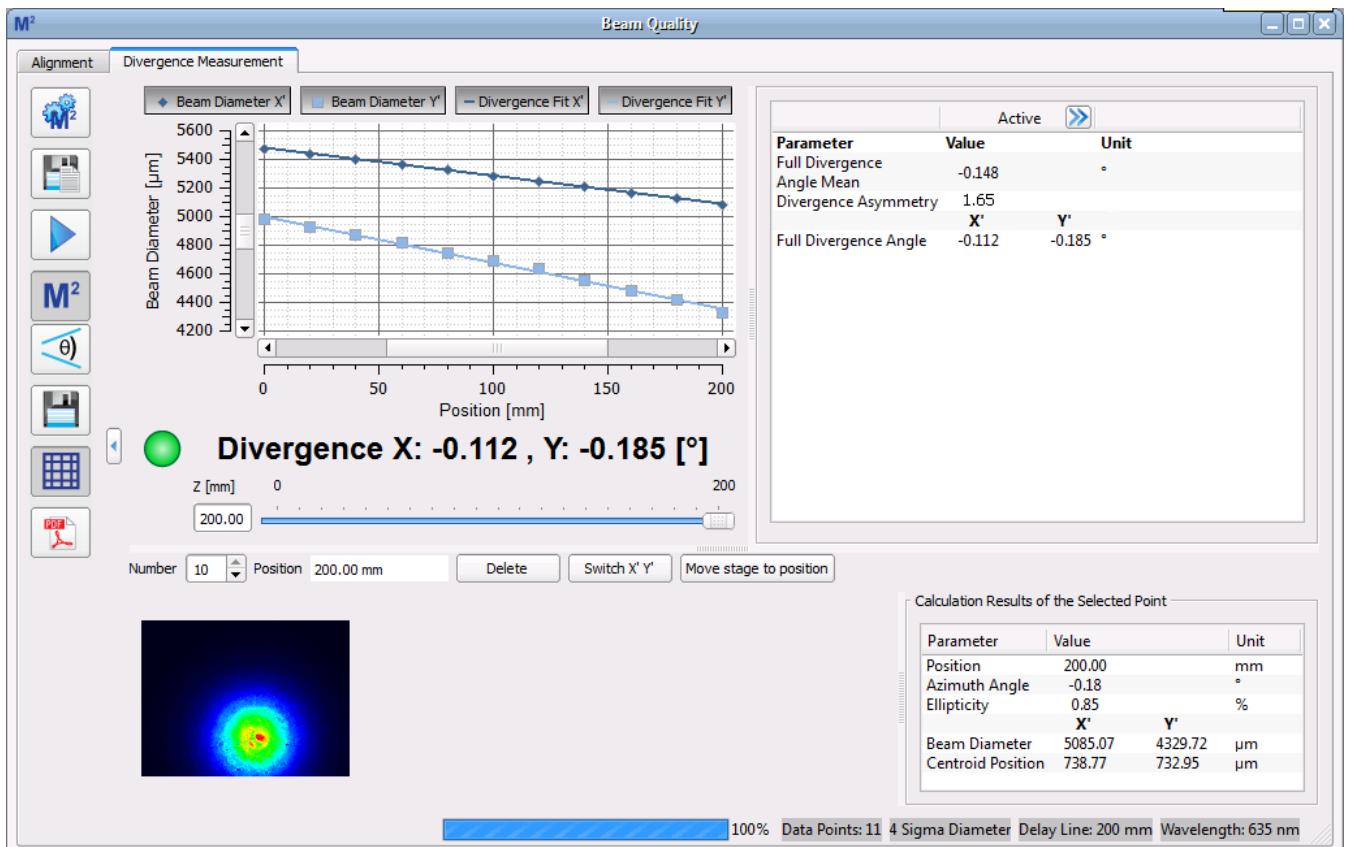
Start the measurement by clicking the **Start** button ▶.

While running the measurement, most of the buttons and options are disabled, e.g. the Divergence measurement settings and the toolbar. This prevents the modification of settings during a measurement.

If necessary, the measurement can be interrupted by clicking the **Stop** button □.

After starting the measurement the X axis of the graph is adapted to the user-defined scan range, for example from 0 to 120 mm. The Y axis scales automatically to the recorded beam widths.

6.9.6 Divergence Measurement Results



The green bulb indicates that the measurement was successful.

Divergence X: -0.112 , Y: -0.185 [°]

These values can also be found in the listing of the complete **Results**.

Parameter	Value	Unit
Full Divergence	-0.148	°
Angle Mean	1.65	
Divergence Asymmetry	X' 1.65 Y' 1.65	
Full Divergence Angle	-0.112 -0.185 °	

Negative values indicate a converging beam, while positive values indicate a diverging beam.

Note

All results are calculated from the applied linear fit!

Full Divergence Angle X' (Y') is explained in chapter [M² Theory](#)

Divergence Asymmetry Asymmetry is the quotient of divergence angles in Y and X scan directions. Values differing from 1.0 indicate that the beam ellipticity is changing with z position, for instance an elliptical beam is focused to a round spot.

$$\text{divergence asymmetry} = \frac{\theta_y}{\theta_x}$$

Reference Measurement

The actual measurement results can be saved and used as reference afterwards, same as for [M² Measurement Results](#)

6.10 M² Theory

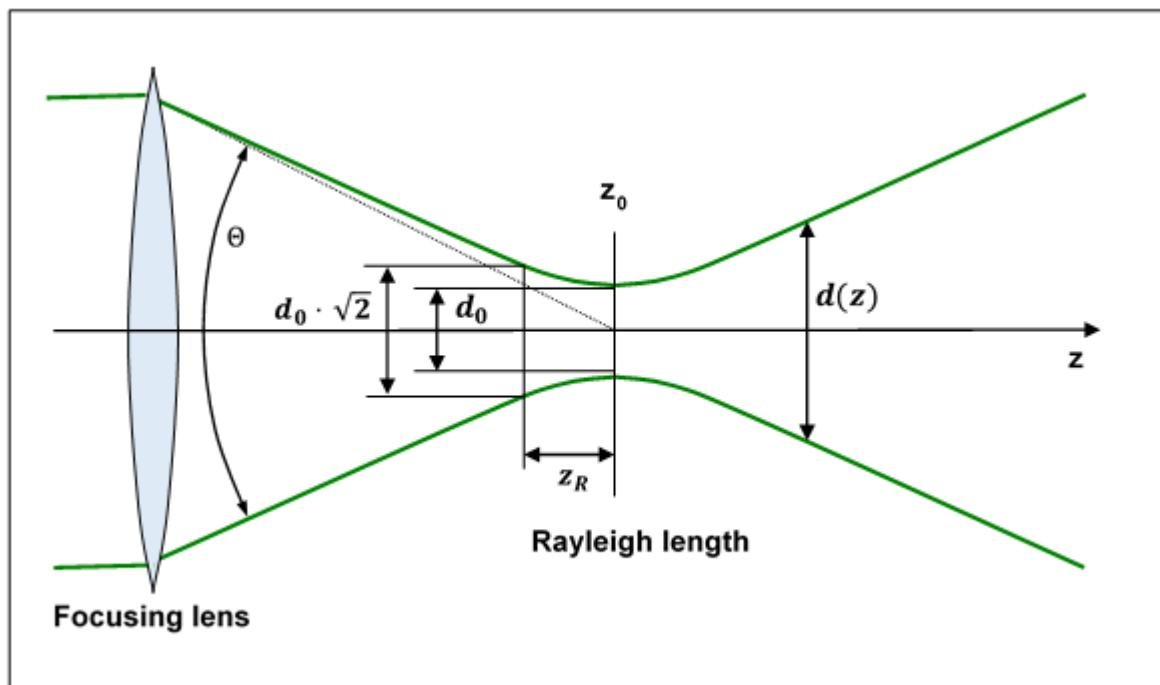
The diameter $d(z)$ of a focused laser beam increases with distance z from its waist position and can be calculated as follows:

$$d(z) = d_0 \sqrt{1 + \left(\frac{z}{z_R}\right)^2}$$

with

- d_0 Waist Diameter
- z_R Rayleigh Length
- λ Wavelength

In this equation it was assumed that the waist location is at zero. Otherwise z has to be replaced with $(z-z_0)$



The Rayleigh Length z_R determines the distance from the beam waist to the position where the beam diameter has increased by a factor of $\sqrt{2} = 1.41$ compared to the minimum diameter at the waist.

From the equation for $d(z)$ it can be seen that the beam diameter increases linearly with z in the far field ($z \gg z_R$). The full divergence angle Θ can be calculated by

$$\Theta \approx \frac{d(z; z \gg z_R)}{z} = \frac{d_0}{z_R}$$

For laser beams with fundamental mode TEM₀₀ (Gaussian Beam shape) it can be theoretically shown that the Rayleigh Length is given by

$$z_{RG} = \frac{\pi d_{0G}^2}{4\lambda}$$

Thus the product of the minimum diameter of a Gaussian beam (at waist) and the divergence angle $d_{0G} \cdot \Theta_G$ (AKA 'Beam Parameter Product', BPP) is constant for a given wavelength:

$$d_{0G} \Theta_G = \frac{4\lambda}{\pi}$$

For mode mixture (MM) beams, i.e. beams which feature higher order modes than just the fundamental mode TEM₀₀, the product of beam diameter and divergence increases by a factor of M².

$$d_{0MM} \Theta_{MM} = M^2 d_{0G} \Theta_G = M^2 \frac{4\lambda}{\pi}$$

Finally, the times-diffraction-limit factor M² is calculated by

$$M^2 = \frac{\pi}{4\lambda} d_{0MM} \Theta_{MM}$$

The Rayleigh Length is now given by

$$z_{RMM} = \frac{\pi d_{0MM}^2}{M^2 \lambda}$$

The reciprocal of the times-diffraction-limit factor M² is called the beam propagation factor or beam quality K.

$$K = \frac{1}{M^2}$$

The following table illustrates the differences between a perfect Gaussian beam and non-perfect beam.

Parameter	Gaussian Beam	Mode Mixture Beam
Times-diffraction-limit factor M ²	1	> 1
Beam propagation factor = Beam quality K	1	< 1
Beam waist for given lens	minimal	larger
Divergence angle θ at given beam waist d_0	narrow	wider

Reasons for Non-Ideal Gaussian Beam with M² > 1

Using a Gaussian beam is preferred because of its minimum divergence angle and the ability to achieve the minimal focus diameter. Differences to Gaussian shape can be due to

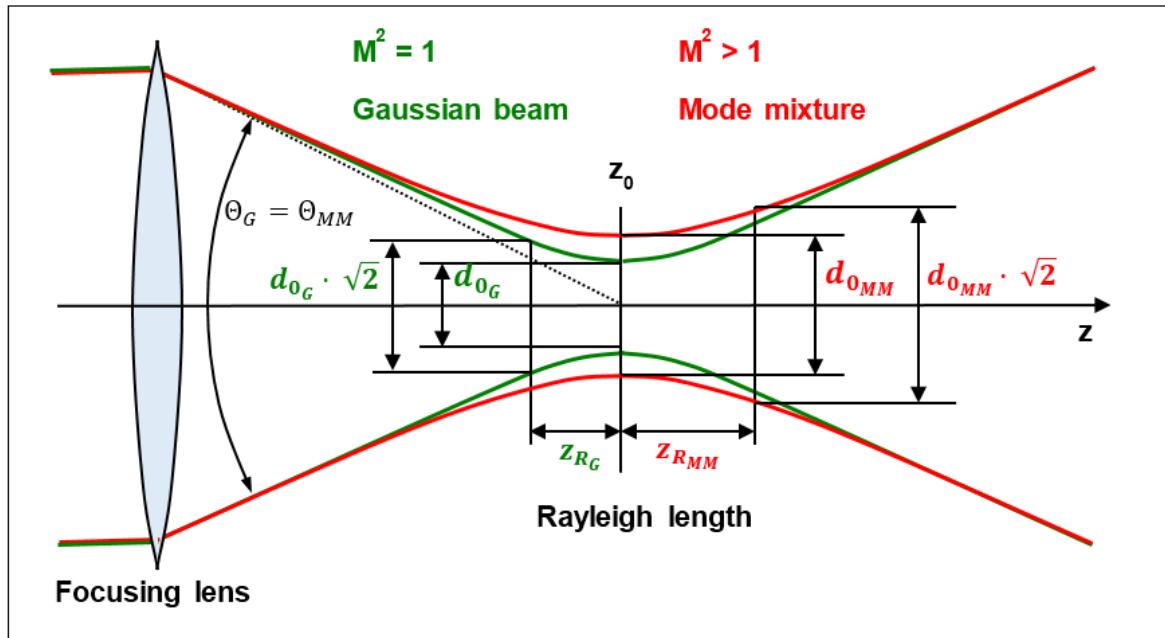
- existence of higher order modes
- amplitude and phase distortions due to inhomogeneous gain medium in lasers
- presence of extraordinary beams

These distortions lead to a larger beam waist compared to Gaussian beams when the same focal lens is used. This results in a lower maximum achievable power density in the focal point.

Comparison of Propagation Between Fundamental Mode TEM₀₀ (Ideal Gaussian beam) and Mode Mixture Beams

With a given divergence angle (i.e. knowing the focal length of the lens), the fundamental mode alone produces the theoretically smallest possible beam waist (green curve). If beam quality worsens (red curve), the beam waist increases. If divergence is fixed, beam waist increases linearly by the factor M² compared to the underlying Gaussian.

$$d_{0MM} (\Theta_{MM} = \Theta_G) = M^2 \cdot d_{0G}$$



The appropriate power density at z_0 is reduced by a factor $(M^2)^2$. Also the Rayleigh Length increases by a factor of M^2 .

$$z_{R_{MM}} (\Theta_{MM} = \Theta_G) = \frac{\pi d_{0MM}^2}{M^2 \cdot 4\lambda} = M^2 \frac{\pi d_{0G}^2}{4\lambda} = M^2 \cdot z_{R_G}$$

7 Write Your Own Application

In order to write your own application, you need a specific instrument driver and some tools for use in different programming environments. The driver and tools are being installed to your computer during software installation and cannot be found in the installation package.

In this section the location of drivers and files, required for programming in different environments, are given for installation under Windows 7, Windows 8.1 and Windows 10 (32 and 64 bit).

In order to fully support 64 bit LabView version, the installation package provides two installer components, the 32bit and the 64bit component:

- for Windows 7 (32/64 bit), Windows 8.1 (32/64 bit) and Windows 10 (32/64 bit): Install "Thorlabs Beam VXIpnnp Instrument Driver (32bit)"
- for Windows 7 (64 bit), Windows 8.1 (64 bit) and Windows 10 (64 bit): Install "Thorlabs Beam VXIpnnp Instrument Driver (64 bit)"

In other words, the 32 bit VXIpnnp driver works with both 32 and 64 bit operating systems, while the 64 bit driver requires a 64 bit operating system.

Note

The Beam software and drivers contains 32 bit and 64 bit applications.

In 32 bit systems, only the 32 bit components are installed to

C:\Program Files\...

In 64 bit systems the 64 bit components are being installed to

C:\Program Files\...

while 32 bit components can be found at

C:\Program Files (x86)\...

In the table below you will find a summary of what files you need for particular programming environments.

Programming environment	Necessary files
C, C++, CVI	*.h (header file) *.lib (static library)
C#	.net wrapper dll
Visual Studio	*.h (header file) *.lib (static library) or .net wrapper dll
LabView	*.fp (function panel) and VXIpnnp Instrument Driver. Beside that, LabVIEW driver vi's are provided with the *.llb container file. Note: LabVIEW drivers and components are installed only, if a LabVIEW installation was recognized.

Note

All above environments require also the VXIpnnp Instrument Driver dll !

During NI-VISA Runtime installation, a system environment variable **VXIPNPPATH** for including files is created. It contains the information where the drivers are installed to, usually to
C:\Program Files\IVI Foundation\VISA\WinNT\.

This is the reason, why after installation of a NI-VISA Runtime a system reboot is required: This environment variable is necessary for installation of the instrument driver software components.

In the next sections the locations of above files are described in detail.

7.1 32 bit Operating System

Note

According to the VPP6 (Rev6.1) Standard the installation of the 32 bit VXIpnP driver includes both the WINNT and GWINNT frameworks.

VXIpnP Instrument driver:

C:\Program Files\IVI Foundation\VISA\WinNT\Bin\TLBC1_32.dll

Note

This instrument driver is required for all development environments!

Header file

C:\Program Files\IVI Foundation\VISA\WinNT\include\TLBC1.h

Static Library

C:\Program Files\IVI Foundation\VISA\WinNT\lib\msc\TLBC1_32.lib

Function Panel

C:\Program Files\IVI Foundation\VISA\WinNT\TLBC1\TLBC1.fp

Online Help for VXIpnP Instrument driver:

C:\Program Files\IVI Foundation\VISA\WinNT\TLBC1\Manual\TLBC1.html

NI LabVIEW driver

The LabVIEW Driver is a 32 bit driver and compatible with 32bit NI-LabVIEW versions 8.5 and higher only.

C:\Program Files\National Instruments\LabVIEW xxxx\Instr.lib\TLBC1...
...\\TLBC1.llb

(LabVIEW container file with driver vi's and an example. "LabVIEW xxxx" stands for actual LabVIEW installation folder.)

.net wrapper dll

C:\Program Files\Microsoft.NET\Primary Interop Assemblies...
...\\Thorlabs.TLBC1_32.Interop.dll

C:\Program Files\IVI Foundation\VISA\VisaCom\...
...\\Primary Interop Assemblies\\Thorlabs.TLBC1_32.Interop.dll

Example for C

Project file:

C:\Program Files\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\CVI C Sample\\TLBC1_CSample.prj

Source file:

C:\Program Files\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\CVI C Sample\\sample.c

Executable sample demo:

C:\Program Files\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\CVI C Sample\\TLBC1_CSample.exe

Example for C#

Solution file:

```
C:\Program Files\IVI Foundation\VISA\WinNT\TLBC1\Examples...
...\\MS VS 2012 CSharp Demo\BC1_CSharpDemo.sln
```

Project file:

```
C:\Program Files\IVI Foundation\VISA\WinNT\TLBC1\Examples...
...\\MS VS 2012 CSharp Demo\BC1_CSharpDemo\BC1_CSharpDemo.csproj
```

Executable sample demo:

```
C:\Program Files\IVI Foundation\VISA\WinNT\TLBC1\Examples...
...\\MS VS 2012 CSharp Demo\BC1_CSharpDemo\bin\Release...
...\\BC1_CSharpDemo.exe
```

Example for LabView

```
C:\Program Files\National Instruments\LabVIEW xxxx\Instr.lib\TLBC1...
...\\TLBC1.llb
```

(LabVIEW container file with driver vi's and an example. "LabVIEW xxxx" stands for actual LabVIEW installation folder.)

7.2 64 bit Operating System

Note

According to the VPP6 (Rev6.1) Standard the installation of the 64 bit VXIpnnp driver includes the WINNT, WIN64, GWINNT and GWIN64 frameworks. That means, that the 64 bit driver includes the 32 bit driver as well.

In case of a 64 bit operating system, 64bit drivers and applications are installed to

"C:\Program Files"

while the 32 bit files - to

"C:\Program Files (x86)"

Below are listed both installation locations, so far applicable.

VXIpnnp Instrument driver:

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\Bin\TLBC1_32.dll  
C:\Program Files\IVI Foundation\VISA\Win64\Bin\TLBC1_32.dll  
C:\Program Files\IVI Foundation\VISA\Win64\Bin\TLBC1_64.dll
```

Note

This instrument driver is required for all development environments!

Header file

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\include\TLBC1.h  
C:\Program Files\IVI Foundation\VISA\Win64\include\TLBC1.h
```

Static Library

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\lib\msc...  
..\TLBC1_32.lib  
C:\Program Files\IVI Foundation\VISA\Win64\lib\msc\TLBC1_32.lib  
C:\Program Files\IVI Foundation\VISA\Win64\Lib_x64\msc\TLBC1_64.lib
```

Function Panel

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\TLBC1\TLBC1.fp
```

Online Help for VXIpnnp Instrument driver:

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\TLBC1\Manual...  
..\TLBC1.html
```

NI LabVIEW driver

The LabVIEW Driver supports 32bit and 64bit NI-LabVIEW2009 and higher.

```
C:\Program Files\National Instruments\LabVIEW xxxx\Instr.lib\TLBC1...  
..\TLBC1.llb
```

(LabVIEW container file with driver vi's and an example. "LabVIEW xxxx" stands for actual LabVIEW installation folder.)

.net wrapper dll

```
C:\Program Files (x86)\Microsoft.NET\Primary Interop Assemblies...
...\\Thorlabs.TLBC1_32.Interop.dll

C:\Program Files (x86)\IVI Foundation\VISA\VisaCom\...
...\\Primary Interop Assemblies\\Thorlabs.TLBC1_32.Interop.dll

C:\Program Files\IVI Foundation\VISA\VisaCom64\...
...\\Primary Interop Assemblies\\Thorlabs.TLBC1_64.Interop.dll
```

Example for C**Project file:**

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\CVI C Sample\\TLBC1_CSample.prj
```

Source file:

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\CVI C Sample\\sample.c
```

Executable sample demo:

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\CVI C Sample\\TLBC1_CSample.exe
```

Example for C#**Solution file:**

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\MS VS 2012 CSharp Demo\\BC1_CSharpDemo.sln
```

Project file:

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\MS VS 2012 CSharp Demo\\BC1_CSharpDemo\\BC1_CSharpDemo.csproj
```

Executable sample demo:

```
C:\Program Files (x86)\IVI Foundation\VISA\WinNT\TLBC1\Examples\...
...\\MS VS 2012 CSharp Demo\\BC1_CSharpDemo\\bin\\Release\\...
...\\BC1_CSharpDemo.exe
```

Example for LabView

```
C:\Program Files\\National Instruments\\LabVIEW xxxx\\Instr.lib\\TLBC1...
...\\TLBC1.llb
```

(LabVIEW container file with driver vi's and an example. "LabVIEW xxxx" stands for actual LabVIEW installation folder.)

8 Maintenance and Repair

Protect the Beam Profiler from adverse environmental conditions. The Beam Profiler is not water resistant.

Attention

To avoid damage to the instrument, do not expose it to spray, liquids or solvents!

The unit does not need a regular maintenance by the user.

The BC106N does not contain any modules that could be repaired by the user himself. If a malfunction occurs, please contact Thorlabs first. If necessary, you will be provided with the required return information.

Do not remove covers!

8.1 Version and Other Information

The menu entry **Help → About Thorlabs** displays relevant Beam software data.



In case of a support request, please submit the software version of the application. This will help to locate the error.

8.2 Cleaning

The camera sensor is extremely vulnerable when the protective glass window was removed to prevent optical interferences!

Removing dust from the naked sensor chip can only be done using compressed gas which is free from oil and water. Thorlabs duster spray (Tetrafluoroethane) can be recommended. Keep the gas nozzle at least at a distance of **4 inches (10 cm)** from the sensor surface, otherwise liquid gas drops may hit the sensor and leave marks visible in the camera image!

Attention

The camera sensor cannot be cleaned by conventional methods using ethanol or cleaning tissue! Warranty will be voided if other cleaning methods than duster spray are used.

Keep a distance of minimum 4 inches (10 cm) when cleaning using compressed gas.

In the case that a professional cleaning of the windowless CCD sensor is required, please contact us. A list of our worldwide branches can be found at the end of this manual.

ND Filters

ND filters (see [Filter Wheel¹⁹](#)) can be cleaned by conventional methods using pure ethanol and/or cleaning tissue. You may clean the front surface of the ND filters without unscrewing the appropriate filter holder. After tissue cleaning, it is recommended to remove remaining lint using compressed air.

In case dust is still visible within the camera image, unscrew the filter holder and clean the ND filter's rear surface. In addition, remove dust from the sensor itself (compressed air only!).

The outer surfaces of the instrument may be cleaned using a wet lint-free cloth.

8.3 Troubleshooting

Software Installation failed

In order to install the Beam software on your PC, you need administrator privileges. Otherwise, an installation is impossible. If you have trouble with software installation, please contact your system administrator.

No Beam Profiler recognized

If after starting of Beam software no instrument was recognized, the Device Settings button in the Menu bar is crossed out ().

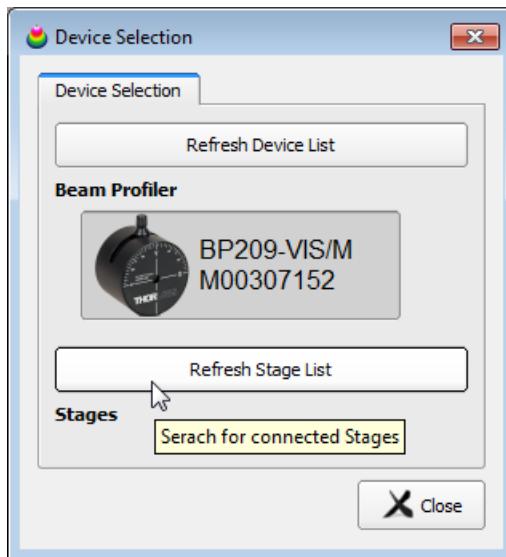
- Check if you have connected a BC106N instrument.
- Check the USB cable. Make sure you are using the supplied with instrument cable.
- Check proper driver installation
- Check if the green LED lights up - LED off indicates that the Beam Profiler's firmware was not loaded.

See section [Connection to the PC](#)^[16] for details.

You may unplug and reconnect the Beam Profiler to a different USB port or use a different USB cable. Wait a few seconds, until the green LED lights up. Then click '**Refresh Device List**' within the Device Selection panel. See chapter [Start the Application](#)^[17] for a detailed description.

An older external VT-80 stage is connected, but not recognized

- If the M² translation stage was not initialized after Beam software start,
 - Check if the stage is powered up (red LED blinking)
 - Check the connection of the stage to the PC
- If the USB-to-Serial converter is used, check for proper driver installation used.
- Press the Refresh button



Fixed sample image instead of live camera image

The Beam software selects a stored camera image automatically if no camera is found during program start. This is indicated by the image name in the status bar.

- Connect a BC106N Beam Profiler to the PC and wait a few seconds until its LED lights up green.
- Click '**Refresh Device List**' in the Device Selection panel.

- Select the instrument and click 'Close'

See chapter [Start the Application](#)¹⁷ for a detailed description.

□ Erroneous or no measurement results

- Remove the protection cap from the used ND filter.
- Verify that the beam under test enters the aperture of the Beam Profiler.
- Check if the power level is within the measurable [Power Range](#)¹⁷⁵.
- Check Exposure Time and Gain settings. Choose '**Auto Exposure Control**' in Device Settings.
- Observe **error messages** in the status bar. Ambient light power may be too high or beam power too low or high. See [Warnings and Errors](#)¹⁶¹.

□ Results and graphs are not being updated

- The device is in the pause mode. Resume the device by clicking the Start  button in the Menu bar.
- **Max Hold**  was activated - switch off **Max Hold** mode by clicking the  icon.
- The "**Average over frame**" rate might be high, check its value in the [Beam Settings panel](#)⁴⁹.
- You may have activated the '**Software Trigger**' mode but the 'Min. Image Saturation' limit is not reached. Increase Exposure Time or even Gain to achieve a sufficiently high pulse intensity.
- The '**Hardware Trigger**' mode may be activated but no TTL trigger pulse is launched into the BNC input jack. Provide a [trigger signal](#)⁹⁵.

□ Menu, toolbar and setting controls react slowly

- The performance of your PC's graphics adapter may be too poor. Particularly, the 3D Profile window is resource-consuming at high resolution, which can decrease its update rate significantly. See [System Requirements](#)⁹.
- The AD converter was set to Precision mode (12 bit data) - see [Bit Depth Settings](#)⁴⁰.

8.3.1 Warnings and Errors

Warnings and error messages will appear in the status bar as soon as improper measurement conditions are detected. For this reason, please keep always an eye on the status bar in order to prevent measurement errors. Below some examples are shown:

 Power too high, camera saturated! Attenuation: 40 dB | Exposure Time: 9.93 ms | Gain: 1.20 x | Auto Exposure: OFF | 8.17 fps

□ Power too high, camera saturated!

Explanation: Some pixels within the selected ROI or Calculation Area are saturated because they reach the maximum digit value (255 in Fast Mode (8 bit data) and 4095 in Precision Mode (12 bit data)). Therefore, the local beam intensity may be even higher than displayed. Beam parameters cannot be calculated correctly!

Resolving: Decrease Exposure Time and Gain settings or reduce the beam intensity using a higher attenuation ND filter of the [Filter Wheel](#)¹⁹. You may also cascade two filters. If Exposure Control is set to Auto, a short appearance of this error is harmless as Exposure Time and Gain will be adjusted automatically.

□ Power too low!

Explanation The brightest pixel values fall below 10% of the available saturation range. This means that 90% of the available dynamic range remains unused. This causes a digitizing noise that increases the measurement noise.

Resolving Increase Exposure Time and Gain settings or increase the beam intensity using a lower attenuation ND filter of the [Filter Wheel](#)^[19]. You may also remove the filter.

□ High ambient power level!

Explanation The lowest pixel intensity within the selected camera ROI or Calculation Area is too high. Therefore, the beam edges cannot be detected or distinguished from a constant ambient light level. The reasons are either the laser beam diameter is wider than the chosen ROI or the ambient light is too high. Beam parameters cannot be calculated correctly!

Resolving Select the ROI so that its height and width is at least twice the beam diameter. Reduce the influence of ambient light by proper shielding, alternatively select a higher attenuation out of the [Filter Wheel](#)^[19] and increase the beam power.

Attention

As soon as an error or warning is displayed in the status bar, the calculated beam parameters are not reliable!

Specific error under Japanese and Chinese operating systems

Under the following conditions

- Windows®7 (32 or 64 bit), Japanese
- Installed Microsoft® Office 10
- Installed Thorlabs BEAM Software 5.0

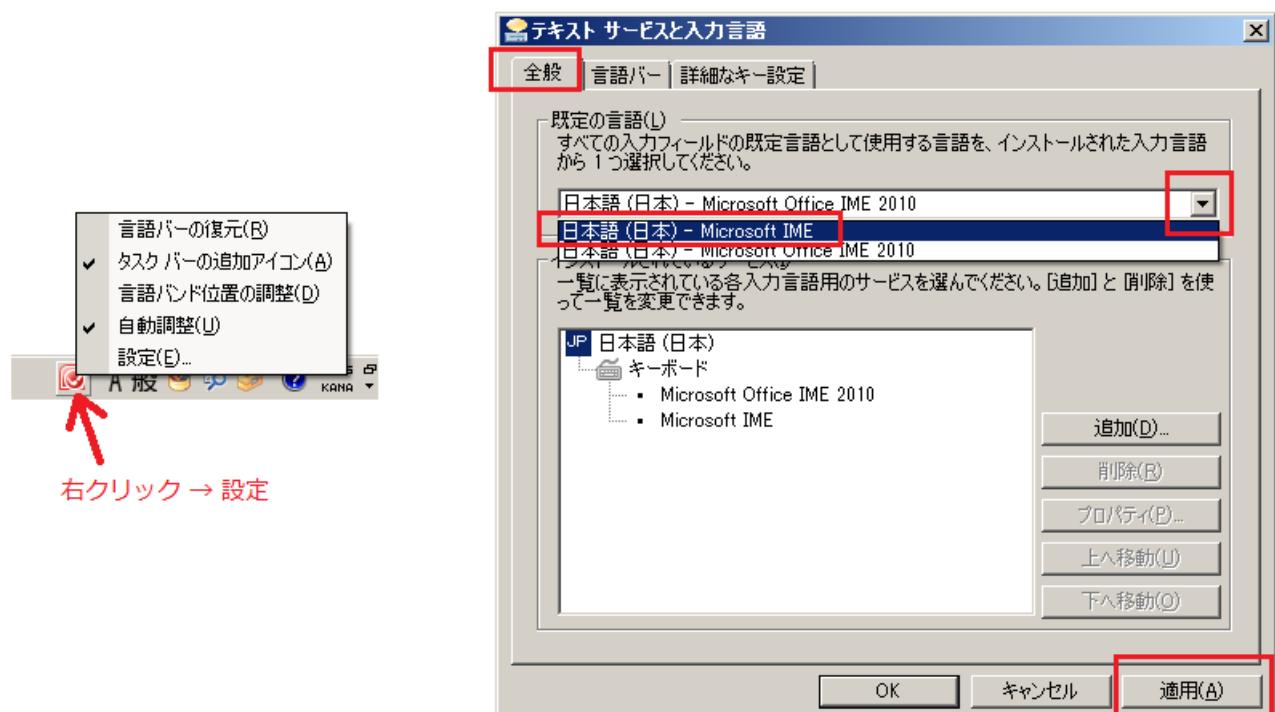
the Beam Software cannot be started, and an error message

"Microsoft Visual C++ Runtime Library: Runtime Error! Program: C... R6030 -CRT not initialized"

occurs. This error is caused by changing the input method editor (IME) after installation of MS Office 2010.

Resolving

Set the IME back to standard Microsoft IME as shown in the screenshot below:



9 Application Note

This chapter contains some background information about the measurement methods of beam profiles.

Beam profiles can be characterized by a number of different parameters. We aim to offer a software that allows to measure all usual beam parameters based on ISO11146-1 standard.

In the following sections detailed explanations are given to the measured parameters.

9.1 Ambient Light Correction

Thorlabs Beam software implements a unique Ambient Light Correction (ALC) method. The procedure can be started from the Beam Settings panel, topic "[Optical Setup](#)"³⁷.

After the laser beam has been blocked and only ambient light enters the sensor, the ALC records a number of images at different exposure times and averages them. Intermediate values are interpolated. This allows a precise calculation of the camera's baseline with ambient light valid at different exposure times.

An outstanding property of the ALC is that the original baseline of the camera (black level) is corrected for the average intensity of the ambient light "noise". This turns out to be a significant advantage, particularly for M² measurements - the 4σ values can be determined with a higher accuracy, as in this case the interference caused by ambient light is nearly eliminated.

9.2 Coordinate Systems

Lab System

The lab system (AKA reference system) of coordinates is based on the true X and Y coordinate orientation of the CCD camera chip (X = lines, Y = columns).

Transformed System

The transformed system of coordinates is based on the calculated beam axes (minor and major axes for elliptical fit or for 4σ beam diameter).

9.3 Raw Data Measurements

Lab (or Reference or Sensor) Coordinate System

4σ Beam Width is the width of a beam in X and Y axes (centroids), derived from the second moment calculation:

$$d_{\sigma_x} = 4 * \sigma_x \quad d_{\sigma_y} = 4 * \sigma_y$$

where σ_x and σ_y are the standard deviation of the horizontal or vertical marginal distribution, respectively:

$$\sigma_x = \sqrt{\frac{\sum[(x-x_{centroid})^2 * p(x,y)]}{Sum_Intensity}} \quad \sigma_y = \sqrt{\frac{\sum[(y-y_{centroid})^2 * p(x,y)]}{Sum_Intensity}}$$

and

$$\sigma_{xy} = \sqrt{\frac{\sum [(x - x_{centroid}) * (y - y_{centroid}) * p(x, y)]}{Sum_Intensity}}$$

Note

The **4σ Beam Width** measurement is not in conformity with ISO11146! In accordance with ISO11146-3, beam diameters shall be defined at a $1/e^2$ clip level for Slit Beam Profilers, while for Camera Beam Profilers the $4\sigma X'$ and $4\sigma Y'$ beam widths apply.

Transformed Coordinate system

According to ISO11146-1, the second moment beam widths are calculated in the transformed coordinate system that follows the elliptical fit ($4\sigma X'$ and $4\sigma Y'$ beam width). Here, the following formulas are used:

$$d_{\sigma_x'} = 2\sqrt{2} * \sqrt{(\sigma_x^2 + \sigma_y^2) + \gamma \sqrt{(\sigma_x^2 - \sigma_y^2)^2 + 4(\sigma_{xy}^2)^2}}$$

$$d_{\sigma_y'} = 2\sqrt{2} * \sqrt{(\sigma_x^2 + \sigma_y^2) - \gamma \sqrt{(\sigma_x^2 - \sigma_y^2)^2 + 4(\sigma_{xy}^2)^2}}$$

where the coefficient

$$\gamma = sgn(\sigma_x^2 - \sigma_y^2)$$

The azimuthal angle is calculated by the formula

$$\varphi = \frac{1}{2} \arctan \left(\frac{2\sigma_{xy}}{\sigma_x^2 - \sigma_y^2} \right)$$

According to ISO11146-1, if the [ellipticity](#) is larger than 0.87, the beam profile may be considered to be of circular symmetry at that measuring location. In this case, ISO11146-1 allows the calculation of only one common 4σ beam width (4σ simplified).

Beam Diameter (4σ simplified) is the diameter derived from the second moment calculation on radial distance (pixel-centroid):

$$d_{\sigma} = 2\sqrt{2} * \sqrt{(\sigma_x^2 + \sigma_y^2)}$$

Effective Beam Diameter is the diameter of an equivalent circular beam area, within which the pixel intensities are above a level X (in per cent of the peak intensity = clip level):

$$D_{eff} = \sqrt{\frac{4 * N * A_{pix}}{\pi}}$$

with

N number of pixels with intensities above clip level

A_{pix} pixel size (for BC106N = $6.45 * 6.45 \mu\text{m}^2$)

Peak Position

X, Y: position of the pixel with highest intensity (AD value) which is found first with respect to reference position.

$$R = \sqrt{X^2+Y^2}$$

is the dial distance of peak position's pixel from the reference position (= sensor center).

Centroid Position

X, **Y** and **R** position (first moment), calculated over all pixels with respect to the above reference position.

$$X = \text{SUM} [x * p(x,y)] / I \quad Y = \text{SUM} [y * p(x,y)] / I$$

where:

- p(x,y) intensity at location (x,y);
- I total intensity;
- SUM of pixels taken over the entire area

AD Saturation

Saturation level of the instrument's AD converter. For a good SNR (signal-to-noise ratio) the saturation level should be not below 40% and not be above 95%.

Total Power

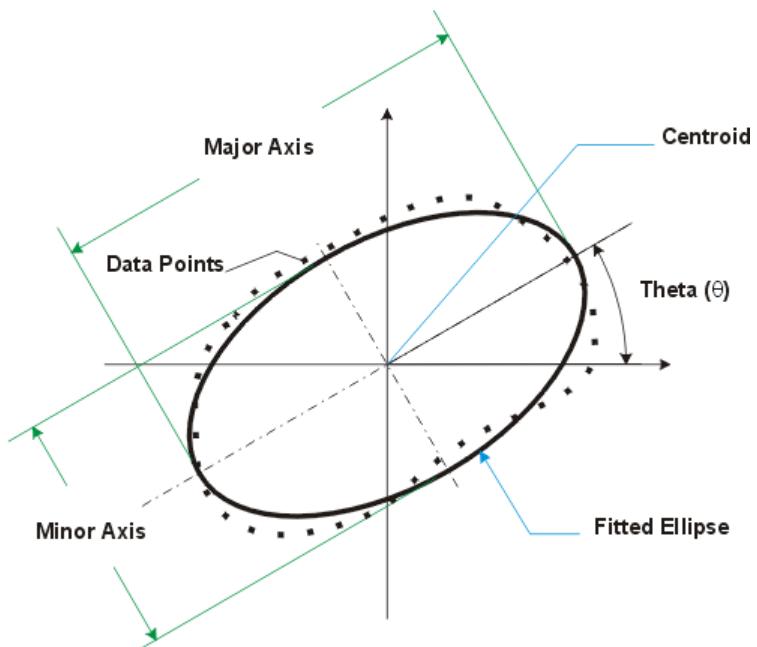
Total power within the [Calculation Area](#) [47].

Peak Density

Power on peak pixel divided by its area ($6.45 * 6.45 \mu\text{m}^2$)

9.4 Ellipse (Fitted)

The beam shape is fit to an ellipse using the set clip level.



Diameter (clip level) is given for the minor axis (**min**), major axis (**max**) and their arithmetic **mean** value.

Ellipticity and **Eccentricity** of the beam are defined in ISO 11146-1 as

$$\text{Ellipticity} = \frac{d_{\min}}{d_{\max}} \quad \text{Eccentricity} = \sqrt{\frac{d_{\max}^2 - d_{\min}^2}{d_{\max}^2}}$$

with d_{\min} = minor axis and d_{\max} = major axes of the approximated beam ellipse.

Orientation denotes the angle θ between the major ellipse axis and the horizontal X axis. Range: $-90^\circ < \theta \leq 90^\circ$.

9.5 X-Y-Profile Measurement

Beam Width at Clip Level (xx%)

Beam width is the distance between the two points where the opposite edges of a captured beam profile are bisected by the X or Y axis and the intensity falls to a certain percentage of the peak power. This percentage is called clip level.

Preferred clip levels are for instance 50 % (Full Width at Half Maximum) and 13.53% (exactly $1/e^2$). Since the Beam software supports a variable clip level, the beam width is always displayed with its clip level in brackets.

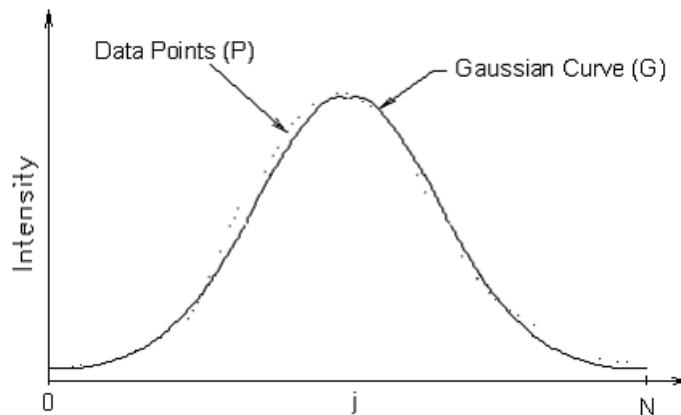
Note

Please note that 'Beam Width' is always the diameter, not the radius of the beam.

9.6 Gaussian Fit Measurement

The beam profiles of coherent light sources, such as lasers and the output of fibers, show a distribution more or less close to Gaussian. If focusing a Gaussian beam, it converges into a waist, after which it diverges.

The Gaussian fit uses the method of least squares in order to fit the X and Y cross section profile of a beam to a Gaussian shape. In other words, the Gaussian fit represents an approximation of captured measurement data to a Gaussian distribution.



Gaussian Intensity is the intensity distribution of the Gaussian fitted beam profile.

Gaussian Diameter is the width of the Gaussian fitted profile at a $1/e^2$ intensity clip level.

9.7 Bessel Fit

One of the most important properties of a Bessel beam is that it is non-diffractive. This means, apart from Gaussian beams, their shape does not change during propagation, and they don't have a focus in terms of a location with highest intensity along the propagation direction. Its distribution can be described by a Bessel function of the first kind.

Ideal Bessel beams do not exist, but a good approximation - a Bessel-Gauss beam - can be achieved by focusing a Gaussian beam using an axicon lens, a narrow annular aperture, or a axisymmetric diffraction grating. The output of some step index fibers can also have a profile close to a Bessel beam.

The Bessel fit approximates a given beam profile to a Bessel function distribution.

10 Appendix

10.1 Technical Data BC106

Model	BC106N-UV	BC106N-VIS
Wavelength Range	190 - 350 nm ¹⁾	350 - 1100 nm
Power Range	50 fW - 1 W ²⁾	1 fW - 1 W ³⁾
Attenuation Filters (nominal values, on filter wheel)	20, 30, 40 dB VIS 20, 30, 40 dB UV	20, 40, 60 dB VIS A-coated 20, 40, 60 dB VIS B-coated
Beam Diameter	30 µm - 6.6 mm	
Compatible Light Sources	CW, Pulsed	
Pulse Frequency	1 Hz - 50 kHz (Single Pulse Exposure), unlimited (Multi Pulse Exposure)	
Sensor		
Coating	Lumigen	None
Chip	2/3" EXview HAD™ CCD Sensor Sony ICX285AL, windowless	
Aperture Size, max.	8.77 x 6.6 mm	
Pixel Size	6.45 µm x 6.45 µm	
Resolution, max.	1360 x 1024 pixel, ROI selectable	
Camera		
Shutter	Global	
Frame Rate, max., at full resolution	10 fps ⁴⁾	
Frame Rate, at 640 x 480 pix	>27 fps ⁴⁾	
Frame Rate, at 320 x 240 pix	>43 fps ⁴⁾	
Image Digitization	8 bit (0 - 255 digits) or 12 bit (0 - 4095 digits)	
Signal to Noise Ratio	≥ 62 dB	
Exposure Range	20 µs – 1 s	
Gain Range	1x - 16x	
Image Capture Modes	Single Frame, Continuous, Hardware Triggered	
Sensor Distance to Surface	16.7 mm (6.65")	
Interfaces		
Trigger Input	TTL Level , BNC Jack ⁵⁾	
Trigger Delay	42 µs - 1 s, Programmable	
PC Interface	USB 2.0, USB 1.1 compatible	

General	
Operating Temperature	+ 5 ... + 35 °C
Storage Temperature	- 40 ... + 70 °C
Warm-up time	not required
Size (H x W x D, with Base Plate, Filter Wheel and Filters)	80 x 80 x 36.5 mm
Weight	310 g
Mounting Holes, Imperial Version	bottom: UNC1/4-20 and 8/32; side: 8/32
Mounting Holes, Metric Version	bottom: M6 and M4, side: M4
Power Supply	2.4 W, USB bus powered

All technical data are valid at $23 \pm 5^\circ\text{C}$ and $45 \pm 15\%$ rel. humidity.

- ¹⁾ Design range of Lumigen coating, sensitivity is given throughout 1100 nm but shows increased non-uniformity and noise compared to BC106N-VIS. Wavelength range of supplied UV ND filters starts at 220 nm, see chapters [Filter Wheel](#)¹⁸¹ and [Wavelength Response](#)¹⁷².
- ²⁾ @ 200 nm, depending on beam diameter and ND filter
- ³⁾ @ 550 nm, depending on beam diameter and ND filter
- ⁴⁾ Highly depending on PC processor and graphic adapter performance.
- ⁵⁾ See chapter [Trigger Input](#)²³ for detailed data.

10.2 Technical Data M2MS-BC106

Item #	M2MS-BC106VIS	M2MS-BC106VIS/M	M2MS-BC106UV-AL	M2MS-BC106UV-AL/M
Beam Profiler	BC106N-VIS	BC106N-VIS/M	BC106N-UV	BC106N-UV/M
Wavelength Range	400 - 1100 nm		250 - 350 nm	
Beam Diameter Range	30 µm - 6.6 mm (at Beam Profiler Input Aperture)			
Power Range	1 fW - 1 W		50 fW - 1 W	
Translation Stage	DDSM100/M			
Travel Range	100mm			
Velocity (Max)	500 mm/s			
Effective Translation Range	200 mm, -100 mm to +100 mm from Focal Point			
Lens Focal Length	250 mm			
Optical Axis Height	70 mm (without additional feet)			
M ² Measurement Range	1.0 - No Upper Limit			
Typical M ² Accuracy	±5 %, Depending on Optics and Alignment			
Accepted Beam Diameter for 5% Uncertainty	30 µm - 3.5 mm (at Beam Profiler Input Aperture)			
Minimum Detectable Divergence Angle	<0.1 mrad			
Applicable Light Sources	CW, Pulsed			
Typical Measurement Time	15 - 30 s, Depending on Beam Shape and Settings			
General				
Size	300 mm x 175 mm x 126mm			
Weight	4.6kg			

10.3 Technical Data M2MS Extension Sets

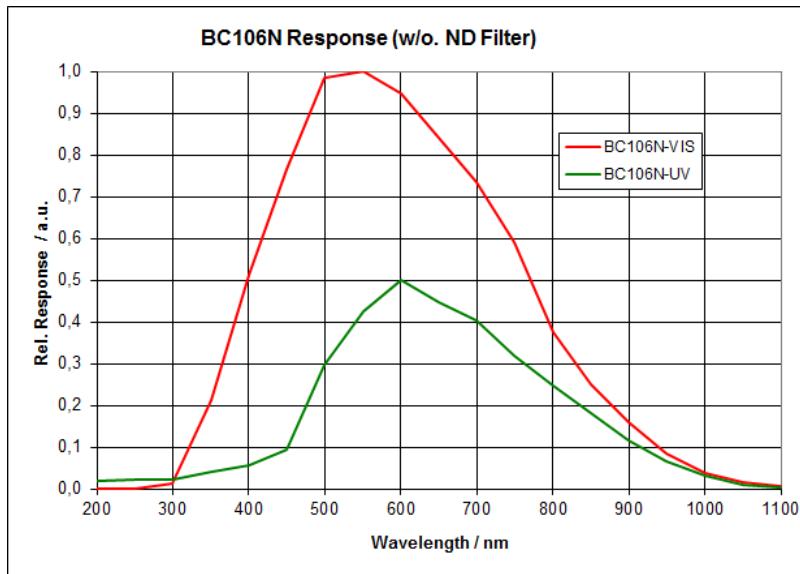
Item #	M2MS	M2MS-AL
Wavelength Range	400-2700 nm ¹⁾	250-600nm ¹⁾
Beam Profiler Compatibility	BC106 series, BP209 series, BP10x series	
Translation Stage	DDSM100/M	
Travel Range	100mm	
Velocity (Max)	500 mm/s	
Effective Translation Range	200 mm, -100 mm to +100 mm from Focal Point	
Lens Focal Length	250 mm	
Optical Axis Height	70 mm (without additional feet)	
M ² Measurement Range	1.0 - No Upper Limit	
Typical M ² Accuracy	±5 %, Depending on Optics and Alignment	
Minimum Detectable Divergence Angle	<0.1 mrad	
Applicable Light Sources	CW, Pulsed*	
Size	300 mm x 175 mm x 109mm (without Beam Profiler)	
Typical Measurement Time	15 - 30 s, Depending on Beam Shape and Settings	

¹⁾ Depending on the Beam Profiler Type

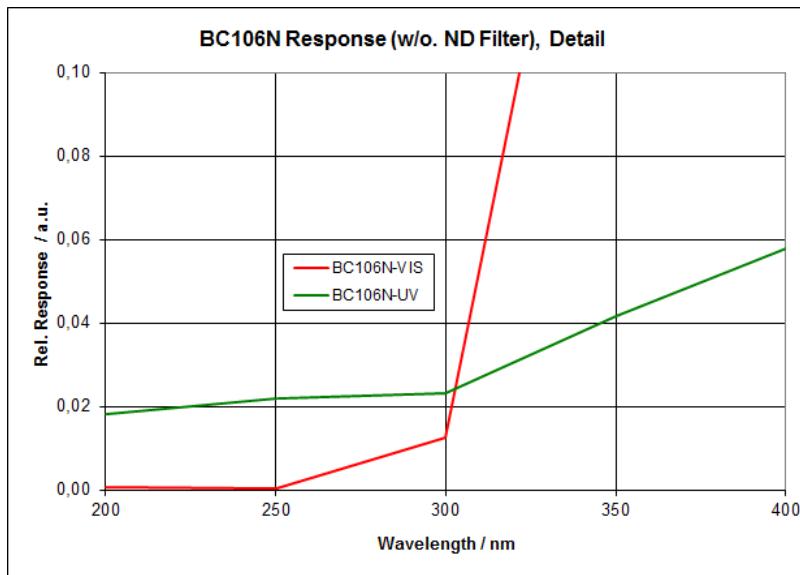
10.4 Wavelength Response

1. Wavelength Dependent Sensitivity of BC106N Models

The following diagrams show the typical relative wavelength response of both BC106N models. Whereas model BC106N-VIS offers about double sensitive in the visible wavelength range, it suffers from nearly zero sensitivity in the UV range below 300 nm.



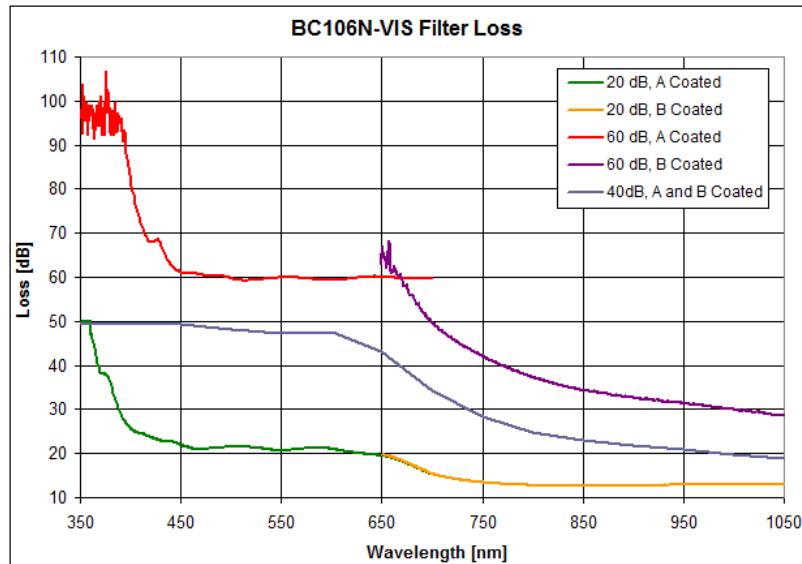
As shown below in detail, the sensitivity of model BC106N-UV considerably exceeds model BC106N-VIS below 300 nm.



Both response diagrams are measured without any ND Filter.

2. Wavelength Dependent Loss of VIS ND Filters

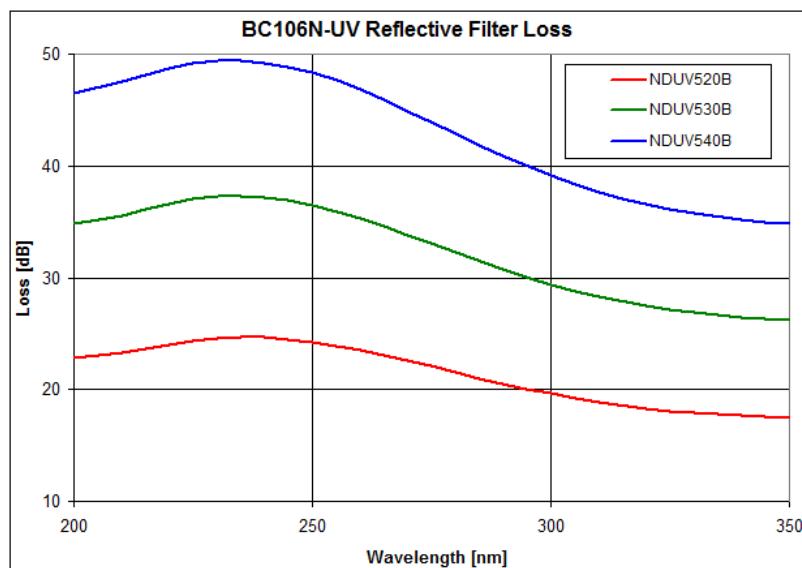
The following diagram shows the measured wavelength dependent loss of the ND filters supplied with the BC106N-VIS Camera Beam Profiler.



As can be seen, the ND filters keep their nominal loss values only coarsely within a limited wavelength range in the visible. Large deviations are outside this range will require a [Power Correction](#)³⁶.

3. Wavelength Dependent Loss of UV Reflective ND Filters

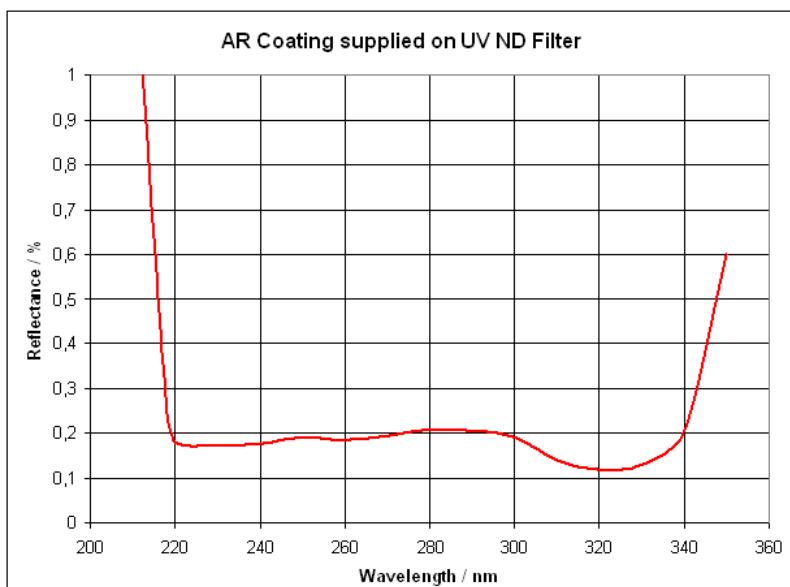
The following diagram shows the measured wavelength dependent loss of the reflective ND filters supplied with the BC106N-UV Camera Beam Profiler.



The BC106N-UV comes also with 3 absorptive AR coated ND filters. These filters are actually not intended for usage in the UV range, however they might be useful in some cases, particularly if operating the BC106N-UV that is operable at wavelengths > 350 nm, is used in this short VIS wavelength range.

4. Wavelength Dependent Reflectance of AR Coating on UV ND Filters

This diagram shows the typical quality of the supplied reflective ND Filters for the UV wavelength range.



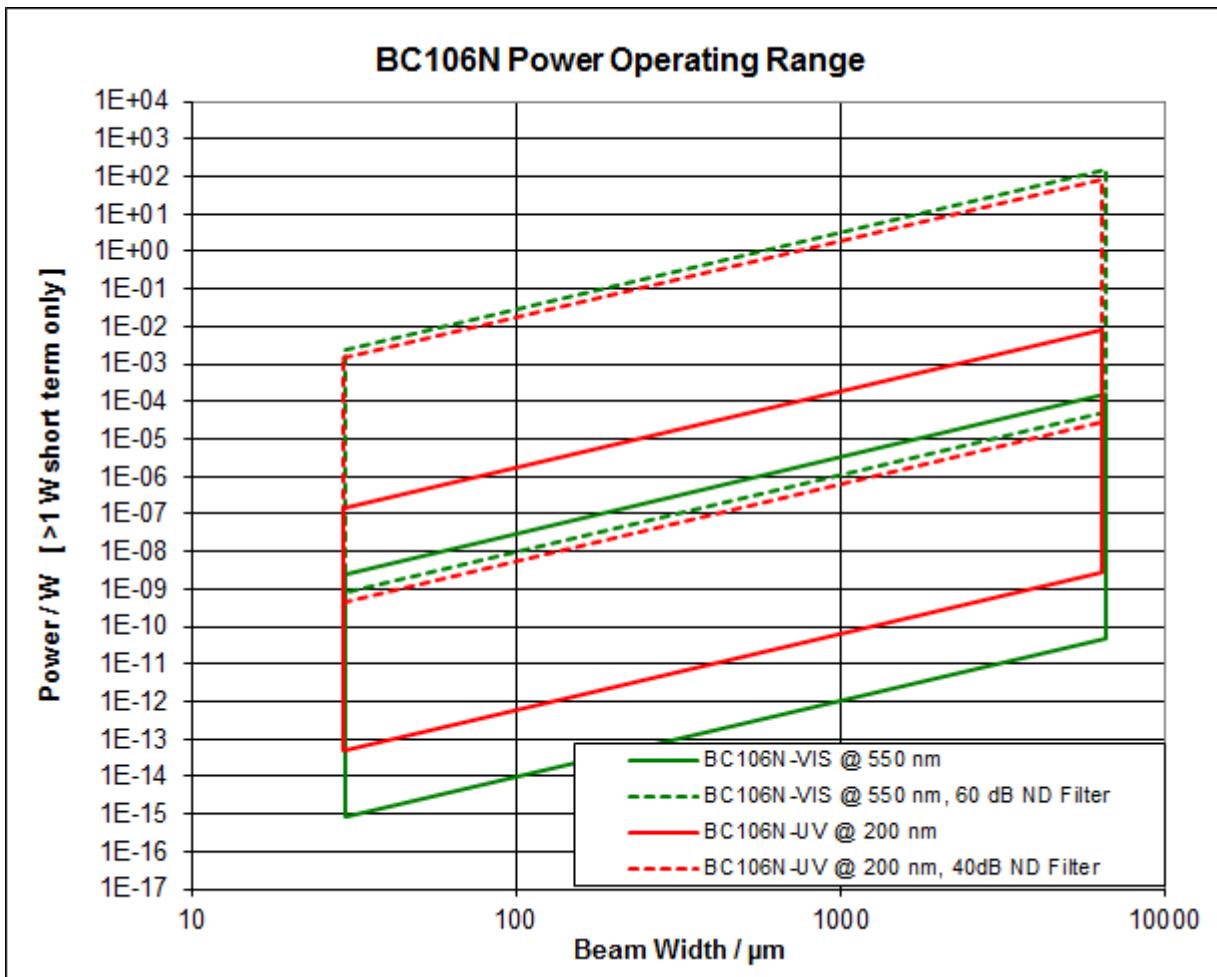
One surface of these reflective type ND Filters is metallized to obtain the 20 dB, 30 dB and 40 dB loss, respectively. The rear side of this fused silica substrate needs to be anti reflective coated to prevent interference effects due to multiple reflections. Therefore, the quality of this AR coating is important for a good image quality.

The displayed curve shows the remaining reflectivity of the AR coating supplied on the fused silica substrate. Between 220 nm and 340 nm is below 0.2 %.

10.5 Power Ranges

The BC106N-VIS and BC106N-UV models offer a different input power range. Maximum and minimum applicable power depends on the beam diameter, the selected optical filter and the wavelength.

The model BC106N-VIS has a maximum responsivity at 550 nm, BC106N-UV at 200 nm. The diagram below refers to these wavelengths.



The range within the unbroken boundary lines indicate the BC106N power range without any filter. The operating power range is shifted towards higher values when a filter is used. The range within the dashed boundary lines stands for the highest attenuation that is available from the filter wheel (40 dB for BC106N-UV; 60 dB for BC106-VIS). With other filter settings, the power range is located between unbroken and dashed lines.

The max. and min. applicable power strongly depends on the actual beam diameter. As for this reason, find first the beam diameter on the horizontal scale read out the power range with respect to the used Beam Profiler model and it's filter setting.

Note

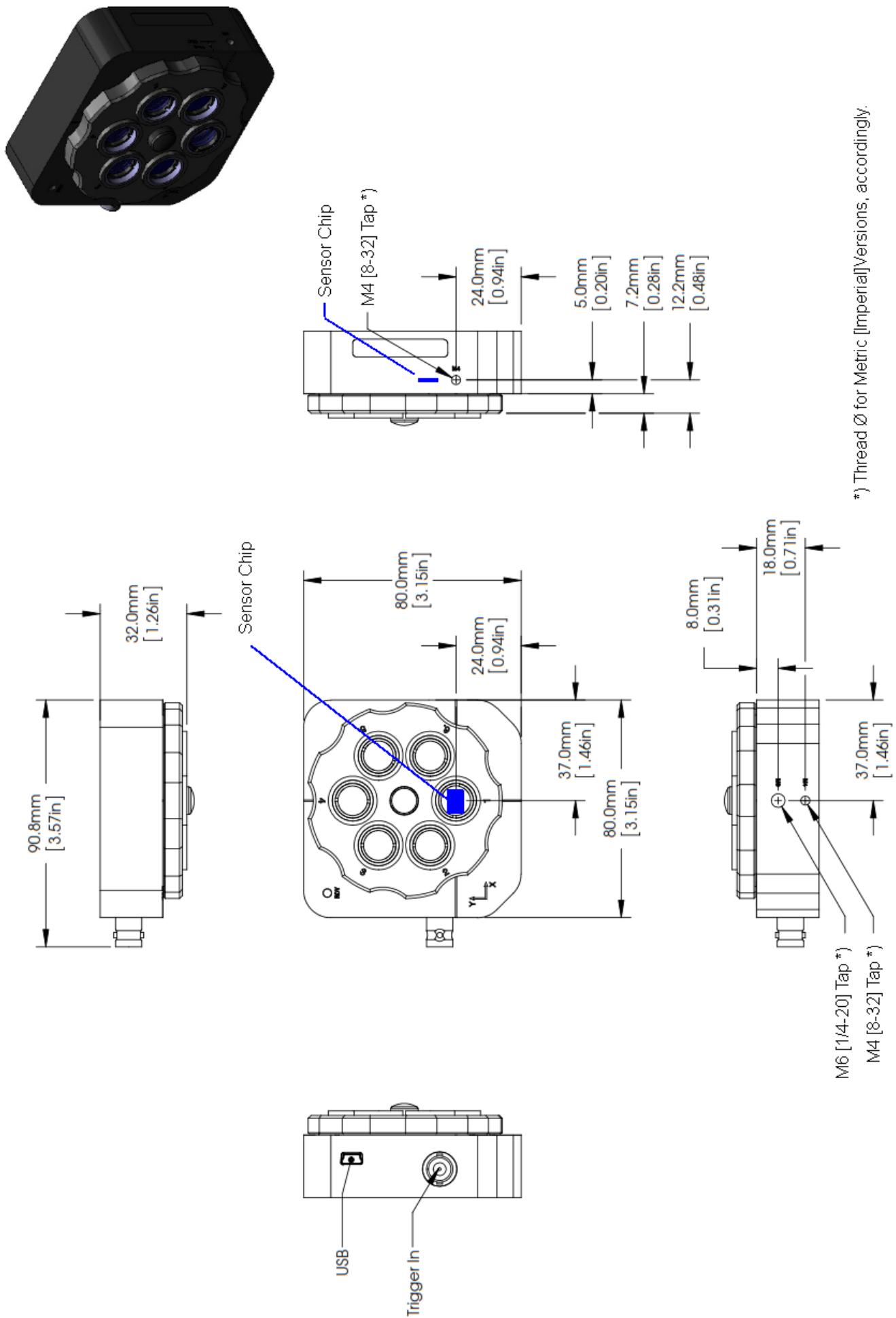
Above diagram represents the operating power range at the wavelength with the highest responsivity of the camera sensor (550 nm for BC106N-VIS and 200 nm for BC106N-UV). For different wavelengths the power range shifts towards higher values and thus, needs to be adopted according to the wavelength depending [response curve of the sensor](#)^[172].

10.6 Initial Settings

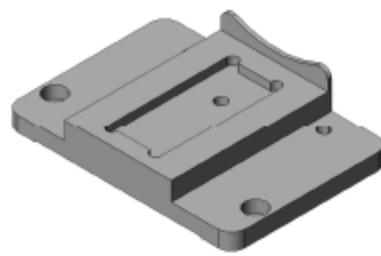
When the BC106N is used first time with the BEAM software, the following initial settings are applied:

Parameter	Default value
Region Of Interest	Full Size
Tab Beam Profiler Parameter	
Wavelength	635nm
Filter Wheel Selection [dB]	No Filter (0 dB)
Auto Exposure Control	ON
Gain	1.0 (minimum)
AD Precision mode	FAST (8 bit data)
Tab Corrections	
Hot Pixel Correction	ON
Power Correction	OFF, factory calibration active
Ambient Light Correction	OFF
Tab Trigger	
No Trigger	(selected)
Software Trigger	OFF, 50% min AD saturation
Hardware Trigger	OFF, Rising Edge
Single Pulse	100ms Target Delay
Repetitive Pulses	1.000kHz Rep. Rate

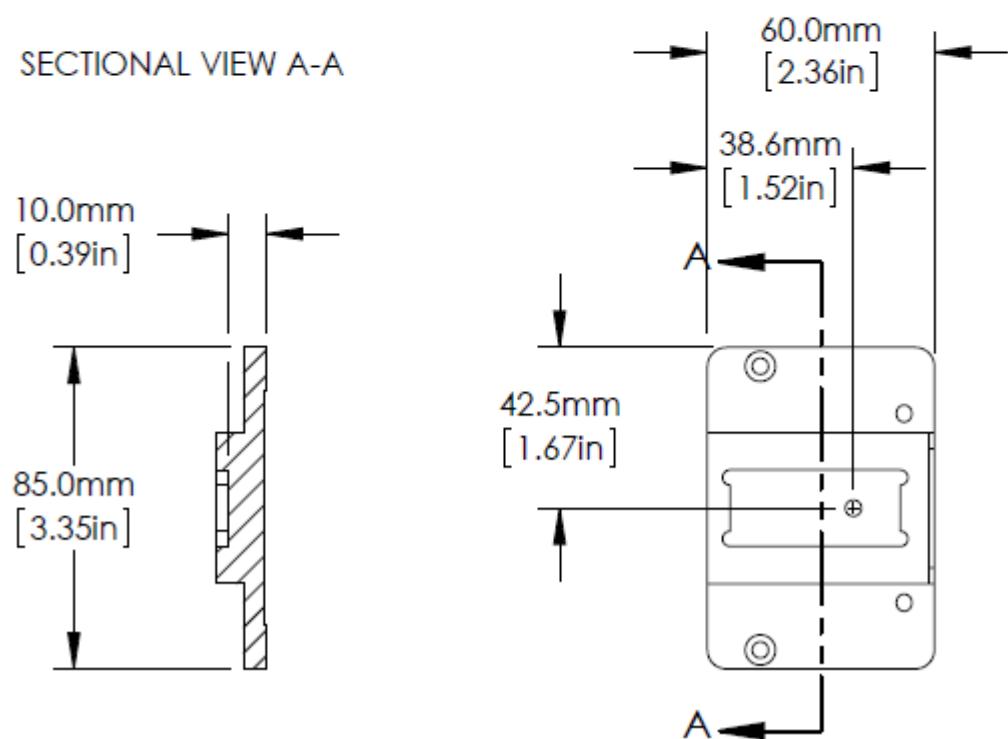
10.7 Drawing BC106N



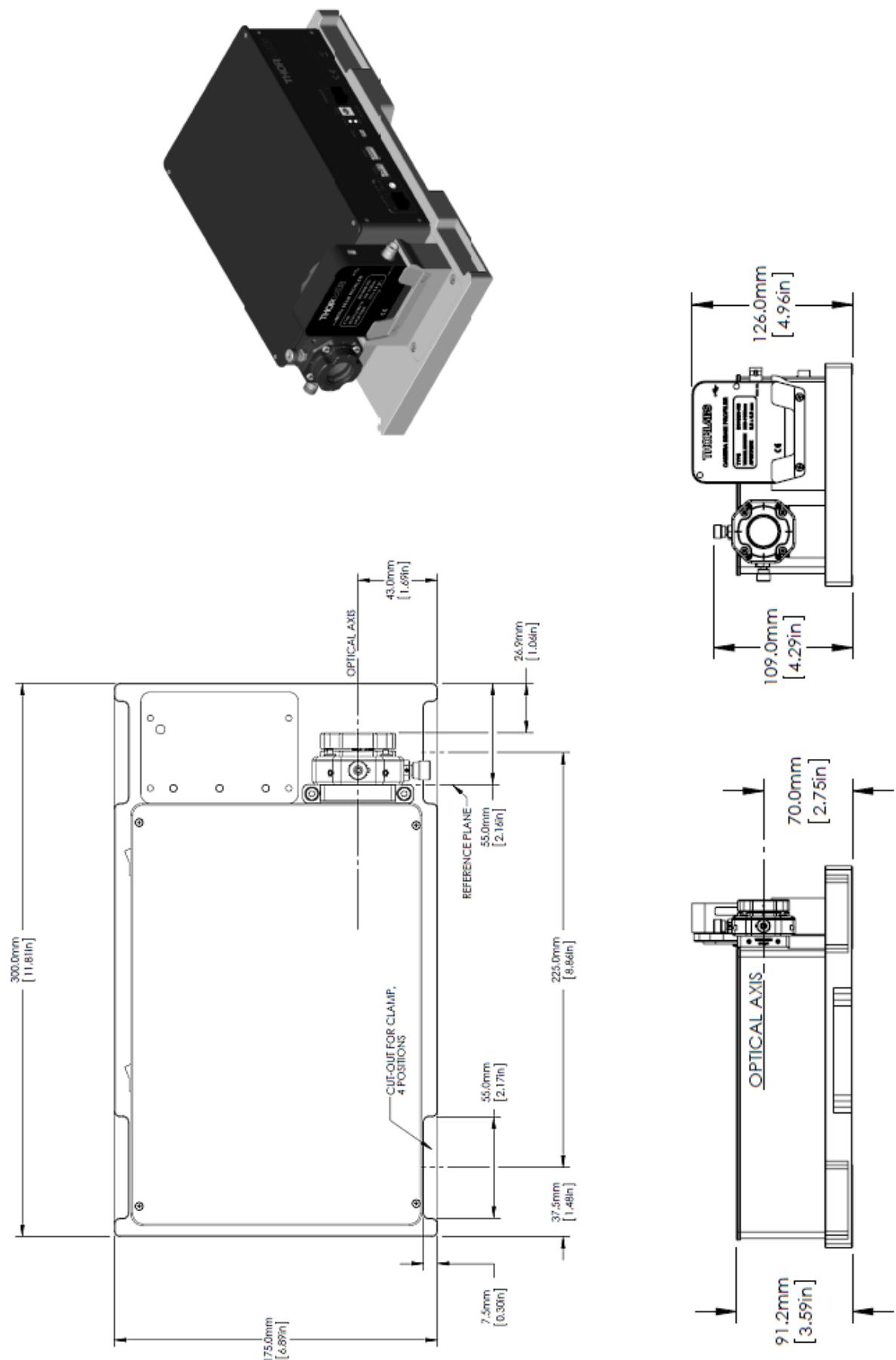
10.8 Drawing BC106 Mounting Adapter



SECTIONAL VIEW A-A



10.9 Drawing M2MS-BC106



10.10 Compatibility with Older Hardware

The Beam software is downwards compatible with the following discontinued hardware components:

- BP104-UV, BP104-VIS, BP104-IR, BP104-IR2 (Slit Beam Profiler with 4 mm aperture)
- BP109-UV, BP109-VIS, BP109-IR, BP109-IR2 (Slit Beam Profiler with 9 mm aperture)
- BC106-UV, BC106-VIS (Camera Beam Profiler)
- BP1M2-50, BP1M2-150, BP1M2-300 (Linear translation stages with adapter for BP10x Slit Beam Profilers)
- BC1M2-150, BC1M2-300 (Linear translation stages with adapter for BC106 Camera Beam Profilers)
- M2SET-VIS, M2SET-IR (M² Meter Sets with BP109 Slit Beam Profiler, Linear Translation Stage and various optical components)

Electrical connections, particularly of the used older VT-80 linear translation stages, and mechanical setup should be carried out as described in the appropriate documentation to this hardware, while operation is described in the manual on hand.

Older documentation can be downloaded from the Thorlabs Manual Archive at www.thorlabs.com/manuals.cfm. Open this page and enter the desired item number; be careful about correct spelling (e.g., "BP104-IR2/M" or "M2SET-VIS").

10.11 List of Acronyms

The following acronyms and abbreviations are used in this manual:

2D	<u>2</u> Dimensional
3D	<u>3</u> Dimensional
ADC	<u>A</u> nalog to <u>D</u> igital <u>C</u> onverter
AL	<u>A</u> luminum
AR	<u>A</u> nti <u>R</u> eflection
BC	<u>B</u> eam <u>P</u> rofiler <u>C</u> amera
CA	<u>C</u> alculation <u>A</u> rea
cw	<u>C</u> ontinuous <u>W</u> ave (constant power source)
GUI	<u>G</u> raphical <u>User <u>I</u>nterface</u>
ND	<u>N</u> eutral <u>D</u> ensity
PC	<u>P</u> ersonal <u>C</u> omputer
FPS	<u>F</u> rames <u>P</u> er <u>S</u> econd
ROI	<u>R</u> egion <u>O</u> f <u>I</u> nterest
USB	<u>U</u> niversal <u>S</u> erial <u>B</u> us
UV	<u>U</u> ltra <u>V</u> iolet (wavelength range)
VIS	<u>V</u> ISeble (wavelength range)

10.12 Thorlabs 'End of Life' Policy (WEEE)

As required by the WEEE (Waste Electrical and Electronic Equipment Directive) of the European Community and the corresponding national laws, Thorlabs offers all end users in the EC the possibility to return "end of life" units without incurring disposal charges.

This offer is valid for Thorlabs electrical and electronic equipment

- sold after August 13th 2005
- marked correspondingly with the crossed out "wheelie bin" logo (see figure below)
- sold to a company or institute within the EC
- currently owned by a company or institute within the EC
- still complete, not disassembled and not contaminated

As the WEEE directive applies to self contained operational electrical and electronic products, this "end of life" take back service does not refer to other Thorlabs products, such as

- pure OEM products, that means assemblies to be built into a unit by the user (e. g. OEM laser driver cards)
- components
- mechanics and optics
- left over parts of units disassembled by the user (PCB's, housings etc.).

Waste treatment on your own responsibility

If you do not return an "end of life" unit to Thorlabs, you must hand it to a company specialized in waste recovery. Do not dispose of the unit in a litter bin or at a public waste disposal site.

WEEE Number (Germany) : DE97581288

Ecological background

It is well known that waste treatment pollutes the environment by releasing toxic products during decomposition. The aim of the European RoHS Directive is to reduce the content of toxic substances in electronic products in the future.

The intent of the WEEE Directive is to enforce the recycling of WEEE. A controlled recycling of end-of-life products will thereby avoid negative impacts on the environment.



*Crossed out
"Wheelie Bin" symbol*

10.13 List of Symbols

The following symbols appear on the BC106N Beam Profiler or within this manual:

Symbol	Meaning
	Universal Serial Bus (USB), a serial bus standard to interface devices to a host computer.
	The CE mark is a mandatory conformity mark on many products placed on the single market in the European Economic Area (EEA). By affixing the CE marking, the manufacturer asserts that the item meets all the essential requirements of the relevant European Directive(s). It does not certify that a product has met EU consumer safety, health or environmental requirements.
	Crossed out "Wheelie Bin" symbol. Waste Electrical and Electronic Equipment (WEEE) is a loose description of surplus, obsolete, broken or discarded electrical or electronic devices. See Thorlabs 'End of Life' Policy (WEEE) [182].

10.14 Certifications and Compliances

Category	Standards or description	
EC Declaration of Conformity - EMC	Meets intent of Directive 2004/108/EC ¹ for Electromagnetic Compatibility. Compliance was demonstrated to the following specifications as listed in the Official Journal of the European Communities:	
	EN 61326:1997 +A1:1998 +A2:2001 +A3:2003	Electrical equipment for measurement, control and laboratory use – EMC requirements: Immunity: complies with immunity test requirements for equipment intended for use in industrial locations ² . Emission: complies with EN 55011 Class B Limits ² , IEC 61000-3-2 and IEC 61000-3-3.
	IEC 61000-4-2	Electrostatic Discharge Immunity (Performance criterion B)
	IEC 61000-4-3	Radiated RF Electromagnetic Field Immunity (Performance Criterion A)
	IEC 61000-4-4	Electrical Fast Transient / Burst Immunity (Performance Criterion A)
EC Declaration of Conformity - Low Voltage	Compliance was demonstrated to the following specification as listed in the Official Journal of the European Communities: Low Voltage Directive 2006/95/EC ³	
	EN 61010-1:2001	Safety requirements for electrical equipment for measurement, control and laboratory use.

¹ Replaces 89/336/EEC

² Compliance demonstrated using a high-quality shielded USB cable shorter than 3 meters.

³ Replaces 73/23/EEC, amended by 93/68/EEC

10.15 Warranty

Thorlabs warrants material and production of the BC106N for a period of 24 months starting with the date of shipment. During this warranty period Thorlabs will see to defaults by repair or by exchange if these are entitled to warranty.

For warranty repairs or service the unit must be sent back to Thorlabs. The customer will carry the shipping costs to Thorlabs, in case of warranty repairs Thorlabs will carry the shipping costs back to the customer.

If no warranty repair is applicable the customer also has to carry the costs for back shipment.

In case of shipment from outside EU duties, taxes etc. which should arise have to be carried by the customer.

Thorlabs warrants the hard- and/or software determined by Thorlabs for this unit to operate fault-free provided that they are handled according to our requirements. However, Thorlabs does not warrant a fault free and uninterrupted operation of the unit, of the software or firmware for special applications nor this instruction manual to be error free. Thorlabs is not liable for consequential damages.

Restriction of Warranty

The warranty mentioned before does not cover errors and defects being the result of improper treatment, software or interface not supplied by us, modification, misuse or operation outside the defined ambient stated by us or unauthorized maintenance.

Further claims will not be consented to and will not be acknowledged. Thorlabs does explicitly not warrant the usability or the economical use for certain cases of application.

Thorlabs reserves the right to change this instruction manual or the technical data of the described unit at any time.

10.16 Exclusion of Reliability and Copyright

Thorlabs has taken every possible care in preparing this document. We however assume no liability for the content, completeness or quality of the information contained therein. The content of this document is regularly updated and adapted to reflect the current status of the hardware and/or software. We furthermore do not guarantee that this product will function without errors, even if the stated specifications are adhered to.

Under no circumstances can we guarantee that a particular objective can be achieved with the purchase of this product.

Insofar as permitted under statutory regulations, we assume no liability for direct damage, indirect damage or damages suffered by third parties resulting from the purchase of this product. In no event shall any liability exceed the purchase price of the product.

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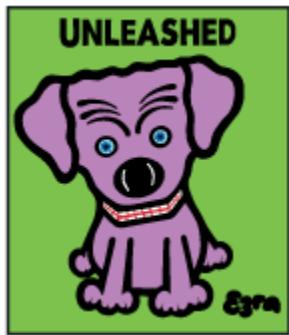
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