

# Context-Aware-VR

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## context-extraction

Context characteristics:

- ▶ Eye tracking
- ▶ Position tracking

# Why reinforcement learning

## Supervised learning

- ▶ needs data to increase performance
- ▶ can never become better than the quality of the data

# Why reinforcement learning

## Reinforcement learning

- ▶ provides a way to have an agent learn completely by itself (without requiring data)
- ▶ agents can become better than the 'best' players

# Reinforcement learning

## Policy Network

- ▶ transforms the input to the possible actions

## Policy Gradients

- ▶ method to train a policy network

# Policy Gradients

- ▶ starts off from a completely random network

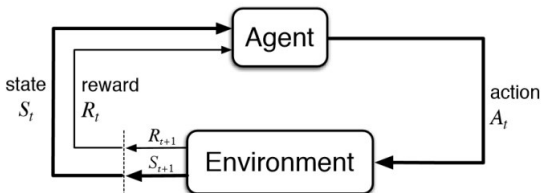


Figure 1: The principle of RL

- ▶ calculate for each possible action a probability
- ▶ agent will choose an action and get feedback (reward)
- ▶ the goal of the agent is to receive as much reward as possible

# Policy Gradients

How does it improve the Policy network?

- ▶ In the first generations it will miserably fail, until the agent gets lucky (received a good reward)
- ▶ this successful series of actions now need to be more preferred over other ones
- ▶ when receiving a good reward we multiply the probability with a positive gradient
- ▶ when receiving a bad reward we multiply the probability with the same negative gradient

## "Troubles in paradise"

Unfortunately there are also downsides:

- ▶ *Credit assignment problem*: punished hard for small mistakes
- ▶ Not appropriate in complex environments