#### Tasks for lecture 4

Recall the least squares problems Pontius and Filip from lecture 2 and 3. We continue the work on these here.

- Solve the exercises from the lecture slides.
- Solve the problems of both datasets with SVD and print relevant information (continuation from lecture 3).
- Perform error estimations of your solutions (create different thresholds than the default and SVD::eps).



## Exercises lecture 4 (+ Mandatory 1 hint)

Design matrix and right hand side vector

Choose sigma (std)

$$\mathbf{A}_{ij} := \mathbf{A}_{ij} / \underbrace{\sigma_i}_{i} \quad i = 1, \dots m, \quad j = 1, \dots n$$

$$\mathbf{b}_i := \mathbf{b}_i / \underbrace{\sigma_i}_{i} \quad i = 1, \dots m$$

The SVD solution 
$$\mathbf{x} = \mathbf{V}\tilde{\mathbf{W}}^{-1}\mathbf{U}^T\mathbf{b}$$

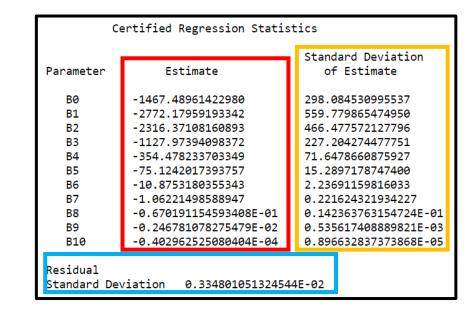
Residual error (std of residuals) < Random fitting

$$\epsilon_{residual} = \frac{\|\mathbf{A}\mathbf{x} - \mathbf{b}\|}{\|\mathbf{b}\|}$$

$$\epsilon_{residual} \simeq \sqrt{\frac{m-n}{m}}$$

Error on parameter estimates (std)

$$[\delta \mathbf{x}]_j \simeq \sqrt{\sum_{i=1}^n \left(\frac{V_{ji}}{w_i}\right)^2} \quad j = 1, \dots, n$$





```
Ex. 2.1 Check if the following vectors are linearly independent 
i) \mathbf{x}_1 = (1, 1, 0); \quad \mathbf{x}_2 = (0, 1, 1); \quad \mathbf{x}_3 = (1, 2, 1)
ii) \mathbf{x}_1 = (1, 1, 0, 0); \quad \mathbf{x}_2 = (0, 1, 1, 0); \quad \mathbf{x}_3 = (0, 0, 1, 1)
iii) \mathbf{x}_1 = (1, 1, 8); \quad \mathbf{x}_2 = (8, 1, -5); \quad \mathbf{x}_3 = (0, 0, 0)
iv) \mathbf{x}_1 = (1, 1, 8, 2, 4); \quad \mathbf{x}_2 = (8, 1, -5, 3, 2); \quad \mathbf{x}_3 = (4, 5, 1, -2, 3); \quad \mathbf{x}_4 = (2, 7, -4, 3, 8); \quad \mathbf{x}_5 = (-4, 9, 2, -21, -8)
```

- 1.  $x_3$  Linear combination of  $x_1$  and  $x_2 \rightarrow$  Linear dependent
- II. No linear combination possible  $\rightarrow$  Linear independent
- III. Definition: Null vector in the set  $\rightarrow$  Linear dependent
- IV. Reduced row echelon form shows linear combination resulting in null vector \(\rightarrow\) Linear dependent

<sup>1.</sup>  $x_3$  Linear combination of  $x_1$  and  $x_2 \rightarrow$  Linear dependent

No linear combination possible → Linear independent

Definition: Null vector in the set → Linear dependent

IV. Reduced row echelon form shows linear combination resulting in null vector → Linear dependent

Ex. 2.2 Assume the columns of a  $3 \times 3$  matrix **A** is given by the vectors in Exercise 2.1 ii). Compute  $\mathbf{A}^T \mathbf{A}$ .



Ex. 3.1 Check if the following vectors are orthogonal, respectively orthonormal

i) 
$$\mathbf{x_1} = (1, 1, 0, 0); \quad \mathbf{x_2} = (0, 0, 1, 1);$$

ii) 
$$\mathbf{x}_1 = (1, 1, 0); \quad \mathbf{x}_2 = (0, 1, 1);$$

iii) 
$$\mathbf{x}_1 = (\frac{\sqrt{3}}{2}, \frac{1}{2}); \quad \mathbf{x}_2 = (-\frac{1}{2}, \frac{\sqrt{3}}{2});$$

iv) 
$$\mathbf{x_1} = (1, 3, 8); \quad \mathbf{x_2} = (0, 0, 0);$$

# Use definition 5 Dot product between vectors

	Orthogonal	Orthonormal
i	Υ	N
ii	N	N
iii	Υ	Υ
iv	Υ	N



**Ex. 3.2** Consider a  $3 \times 3$  rotation matrix **R**. Is this matrix always orthonormal?

$$R_x( heta) = egin{bmatrix} 1 & 0 & 0 \ 0 & \cos heta & -\sin heta \ 0 & \sin heta & \cos heta \end{bmatrix}$$

Definition 6 and 7  $\rightarrow$  Columns always give a dot product of 1



Ex. 6.1 Write a computer program (in any computer language you like) that implements the Gram Schmidt method.

Gram-Schmidt program
Set of linear independent vectors
transformed to a set of orthonormal vectors
that span the same space

#### The Gram-Schmidt method:

```
\mathbf{e}_1 := \mathbf{x}_1 / \|\mathbf{x}_1\|
For i := 2, \dots, k do {
\mathbf{e}_i := \mathbf{x}_i - \sum_{j=1}^{i-1} (\mathbf{x}_i \cdot \mathbf{e}_j) \mathbf{e}_j
\mathbf{e}_i := \mathbf{e}_i / \|\mathbf{e}_i\|
}
```

```
function E = Gram Schmidt(X)
    [n,k] = size(X);
    E = zeros(n,k);
    E(:,1) = X(:,1) / norm(X(:,1));
   for i=2:k
        E(:,i) = X(:,i);
        for j=1:i-1
            E(:,i)=E(:,i)-dot(X(:,i),E(:,j))*E(:,j);
        end
        length = norm(E(:,i));
        %disp(length);
        if length > 10^(-15)
            E(:,i) = E(:,i) / norm(E(:,i));
        else
            E(:,i) = zeros(n,1);
        end
    end
    disp("E = ");
    disp(E);
end
```

**Ex. 6.2** Without proof, we can assume that the vectors  $\mathbf{x}_1 = (2, 8, 4, 2, 1)$ ;  $\mathbf{x}_2 = (1, 1, 5, 7, 8)$ ;  $\mathbf{x}_3 = (4, -5, 1, -4, 3)$  are linearly independent vectors in  $\mathbb{R}^5$ . Use the program from Ex. 6.1 to compute an orthonormal basis for the subspace of  $\mathbb{R}^5$  spanned by  $\mathbf{x}_1$ ,  $\mathbf{x}_2$ ,  $\mathbf{x}_3$ .

```
function E = Gram_Schmidt(X)
    [n,k] = size(X);
    E = zeros(n,k);
    E(:,1) = X(:,1) / norm(X(:,1));
    for i=2:k
        E(:,i) = X(:,i);
        for j=1:i-1
            E(:,i)=E(:,i)-dot(X(:,i),E(:,j))*E(:,j);
        end
        length = norm(E(:,i));
        %disp(length);
        if length > 10^(-15)
            E(:,i) = E(:,i) / norm(E(:,i));
        else
            E(:,i) = zeros(n,1);
        end
    end
    disp("E = ");
    disp(E);
end
```

```
x1 =
x2 =
x3 =
    -4
E =
    0.2120
             -0.0161
                         0.6657
             -0.3509
                        -0.1936
    0.8480
    0.4240
             0.2543
                         0.2811
    0.2120
              0.5570
                        -0.5977
                         0.2883
    0.1060
              0.7083
```



- I. Trivial null space due to linear independency  $\mathbf{A} \cdot \mathbf{x} = \mathbf{0}$ .
- II. Range and spanned vector space (rank)

```
Nullspace N(A)
                Matrix 3x0:
Nullity of A: 0
Range B(A)
                Matrix 4x3:
       0.184815
                       0.861674
                                        0.335038
                                         0.71918
       0.567225
                      -0.401294
       0.611814
                       0.258264
                                       -0.338436
      -0.519407
                       0.172573
                                        0.505955
Rank of A: 3
```

Ex. 6.5 Consider the matrix A given as

$$\mathbf{A} = \begin{pmatrix} 2 & 0 & 2 \\ 0 & 4 & 4 \\ 2 & 4 & 4 \\ -1 & -4 & -3 \end{pmatrix}$$

- i) Determine the Null Space  $N(\mathbf{A})$  and an orthonormal basis for  $N(\mathbf{A})$
- ii) Determine the range  $B(\mathbf{A})$  and an orthonormal basis for  $B(\mathbf{A})$

What has all this to do with singular value decomposition? SVD explicitly constructs orthonormal bases for the nullspace and range of a matrix! Specifically, the columns of U whose same-numbered elements  $w_j$  are nonzero are an orthonormal set of basis vectors that span the range; the columns of V whose same-numbered elements  $w_j$  are zero are an orthonormal basis for the nullspace. Our SVD object has methods that return the rank or nullity (integers), and also the range and nullspace, each of these packaged as a matrix whose columns form an orthonormal basis for the respective subspace.

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SVD YT videos of Steve Brunton databookuw.com/

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**Theorem 5** Let  $\mathbf{u}_1 \dots \mathbf{u}_K$  be an arbitrary orthonormal basis for  $B(\mathbf{A})$ . Then the least squares solution  $\mathbf{x}$  that minimizes  $\|\mathbf{A}\mathbf{x} - \mathbf{b}\|$  satisfies

$$\mathbf{A}\mathbf{x} = \sum_{k=1}^{K} (\mathbf{b} \cdot \mathbf{u}_k) \mathbf{u}_k \equiv \mathbf{b}_{LS}$$

Ex. 6.3 Compute the point in the subspace spanned by x<sub>1</sub>, x<sub>2</sub>, x<sub>3</sub> from Ex. 6.2 that is nearest to (5,6,1,2,3) (HINT: Consider the statement in Theorem 5 in the next section and use your result from Ex. 6.2).

```
x1 = [2;8;4;2;1]
x2 = [1;1;5;7;8]
x3 = [4;-5;1;-4;3]
X = [x1,x2,x3];
E = Gram_Schmidt(X);

%6.3
b = [5;6;1;2;3];
b_ls = least_square(E,b);
```

```
b_ls =

2.9391
5.3336
4.0288
1.0129
2.3116
```

