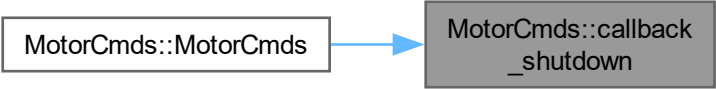


MotorCmds::MotorCmds



```
graph LR; A[MotorCmds::MotorCmds] --> B[MotorCmds::callback_shutdown]
```

The diagram consists of two rectangular boxes connected by a blue arrow. The left box is white with a black border and contains the text 'MotorCmds::MotorCmds'. The right box is gray with a black border and contains the text 'MotorCmds::callback_shutdown' on two lines. A blue arrow points from the right side of the left box to the left side of the right box.

MotorCmds::callback
_shutdown