

MotorCmds::MotorCmds

```
graph LR; A[MotorCmds::MotorCmds] --> B[MotorCmds::motor_cmds_callback]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'MotorCmds::MotorCmds'. The right box is gray with a black border and contains the text 'MotorCmds::motor_cmds_callback'.

MotorCmds::motor_cmds
_callback