

Inner core convection with aspect

How to run a simulation

```
#!/bin/ksh
#SBATCH --job-name=g10000P2
#SBATCH --output=o.g10000P2.%j
#SBATCH --error=e.g10000P2.%j
#SBATCH --ntasks=100
#SBATCH --time=08:00:00
aprun -n 100 ../../../../aspect inner_core_traction.prm
```

To run : "sbatch name-of-bashscript".

Governing parameters

In order to explore the different regimes of the inner core dynamic, two parameters have to be changed, the Rayleigh number Ra , and the phase change number P . The Rayleigh number can directly be changed by adjusting the magnitude of the gravity:

```
# The gravity has its maximum value at the boundary of inner and
# outer core, and decreases approximately linearly to zero towards
# the center of the core.
# The Rayleigh number used in the model is given by the magnitude
# of the gravity at the inner core/outer core boundary.
subsection Gravity model
  set Model name = radial linear

  subsection Radial linear
    set Magnitude at surface = 2      # <-- Ra
  end
end
```

The phase change number is implemented as part of the material model, and as a function that can depend on the spatial coordinates and/or on time:

```
subsection Material model
  set Model name = inner core material

  # The 'inner core material' model also contains a function that
  # represents the resistance to melting/freezing at the inner core
  # boundary.
  # For  $P \rightarrow \infty$ , the boundary is a free slip boundary, and for
  #  $P \rightarrow 0$ , the boundary is an open boundary (with zero normal stress).
  subsection Inner core
    subsection Phase change resistance function
      set Variable names = x,y,z
      set Function expression = 1e-2      # <-- P
    end
  end
end
```

Mesh refinement

In the particular case of translation for the inner core convection, a mesh that is finer in the outer boundary is appropriated. For translation and stable simulations I used:

```

subsection Mesh refinement
  set Initial global refinement      = 1
  set Initial adaptive refinement   = 5
  set Strategy                      = minimum refinement function
  set Time steps between mesh refinement = 0

  subsection Minimum refinement function
    set Variable names = depth, phi, theta
    set Function expression = if(depth>0.1,if(depth>0.2,1,5),6)
  end
end

```

For plume convection simulations :

```

subsection Mesh refinement
  set Initial global refinement      = 2
  set Initial adaptive refinement   = 5
  set Strategy                      = minimum refinement function
  set Time steps between mesh refinement = 0

  subsection Minimum refinement function
    set Variable names = depth, phi, theta
    set Function expression = if(depth>0.1,if(depth>0.1,2,6),7)
  end
end

```

The sum of the "Initial global refinement" and the "Initial adaptative refinement" is always the maximum refinement of the model. In order to have a finest mesh with a refinement of 6 (like for the exemple above), the sum of those two parameters should be 6. The "Initial global refinement" is used to start with an uniform mesh, and then it does a number of mesh refinement step equal to the "Initial adaptive refinement". That means that if the Initial adaptive refinement is setted to 0, the mesh will always be uniform, no matter what is specified elsewhere. Also, in every mesh refinement step, the mesh is only refined or coarsened by one level, respectively. That means that if for example, the start is from an Initial global refinement of 5, the Initial adaptive refinement should be 2, so that refinement levels of 5,6 and 7 are possible (as it's specified in the minimum refinement function). It's also possible to change the fraction of the sphere you want to better define. This can be achieve by changing the first term in the paranthesis, which corresponds to the pourcentage of the sphere you want to define.

Next step : Use adaptative mesh refinement for the plume convection cases.

Restart from a previous run

Some simulations can be very heavy (3D calculations) and thus long. In the particular case of using a server, you could run only limited time simulations and thus need to restart from a previous state.

In order to restart from a previous run:

```

%At the beginning of the input file
set Resume computation          = true
%
subsection Checkpointing
  set Steps between checkpoint = 100
  set Time between checkpoint = 0
end

```

For the first run, "set Resume computation" has to be false and then true if you want to restart from it. Checkpointing files will be created and the number of steps between every checkpoint has to be adjusted.

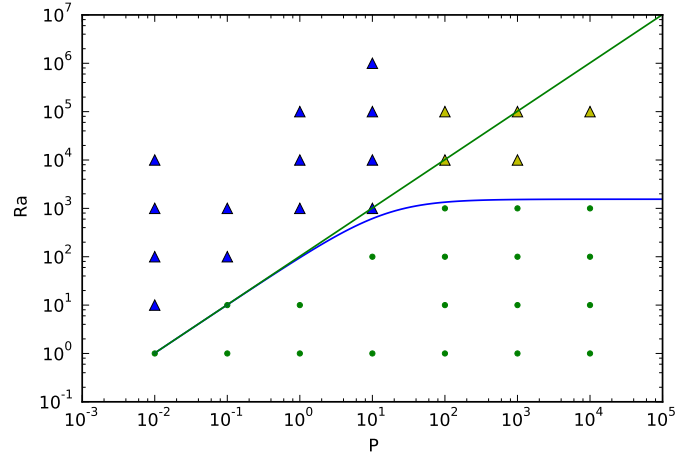


Figure 1: Stability diagram for convection in a sphere with phase change at its outer boundary. The stability curves for the first unstable mode ($l=1$) and the translation are obtained from [?]. Triangles are for the convective regimes with, in blue, the translation mode and in yellow, the plume convection mode; points are for the stable cases.

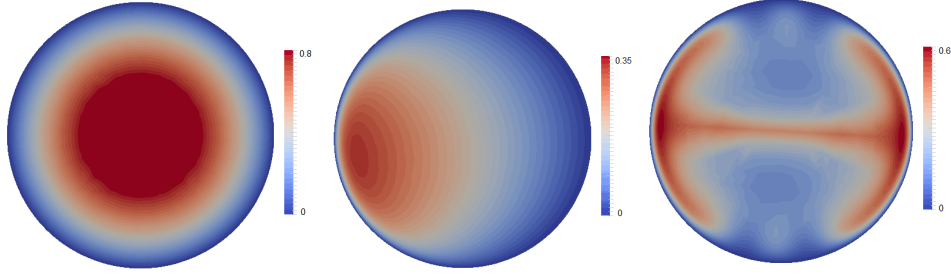


Figure 2: Convection regimes in the inner core for different values of Ra and \mathcal{P} . From left to right: no convection ($Ra = 1, \mathcal{P} = 1$), translation ($Ra = 10^2, \mathcal{P} = 10^{-1}$), plume convection ($Ra = 10^5, \mathcal{P} = 10^4$).

Some results

Simulations shown on the Figure 1 have been performed with the parameters used above. All of them reached a stationary state. The regime to which they belong was determined using the paraview visualization tool. A simulation example for each regime is shown on the Figure 2.