

## 2D Osc: Outer equations

$$\dot{V} = \Omega_1 - \Omega_2 + \Omega_3(T-V) - T - V|V| + A \sin(\Omega t)$$

$$\dot{T} = \Omega_1 - T(1+|V|) + B \sin(\Omega t)$$

For  $A=B=0$ ,  $T_0 = \frac{\Omega_1}{1+|V_0|}$ ,  $0 = \Omega_1 - \Omega_2 + \Omega_3(T_0 - V_0) - T_0 - V_0|V_0|$

Multi-scale:  $\tau = t$ ,  $R = \Omega t$ , assume  $V < 0$  and  $T, V$  are far from axis

$$V_R + \Omega^{-1} V_\tau = \Omega^{-1} (\Omega_1 - \Omega_2 + \Omega_3(T-V) - T + V^2 + A \sin R)$$

$$T_R + \Omega^{-1} T_\tau = \Omega^{-1} (\Omega_1 - T(1-V) + B \sin R)$$

$$V \sim V_0 + \Omega^{-1} V_1 + \dots, T \sim T_0 + \Omega^{-1} T_1$$

$$O(1): V_{0R} = T_{0R} = 0 \rightarrow V_0 = V_0(\tau), T_0 = T_0(\tau)$$

$$O(\Omega^{-1}): V_{1R} + V_{0\tau} = \Omega_1 - \Omega_2 + \Omega_3(T_0 - V_0) - T_0 + V_0^2 + A \sin R$$

$$T_{1R} + T_{0\tau} = \Omega_1 - T_0(1-V_0) + B \sin R$$

Fredholm:  $V_{0\tau} = \Omega_1 - \Omega_2 + \Omega_3(T_0 - V_0) - T_0 + V_0^2$  Same as  $A=B=0$   
 $T_{0\tau} = \Omega_1 - T_0(1-V_0)$

$$V_{1R} = A \sin R, T_{1R} = B \sin R \rightarrow V_1 = X_1(\tau) - A \cos R$$

$$T_1 = Y_1(\tau) - B \cos R$$

$$O(\Omega^{-2}): V_{2R} + V_{1\tau} = \Omega_3(T_1 - V_1) - T_1 + 2V_0 V_1$$

$$T_{2R} + T_{1\tau} = -T_1 + T_1 V_0 + T_0 V_1$$

Fredholm:  $V_{1\tau} = \Omega_3(Y_1 - X_1) - Y_1 + 2V_0 X_1$  equi:  $Y_1 = \frac{T_0 X_1}{-V_0 + 1} \rightarrow X_1 = 0$   
 $T_{1\tau} = -Y_1 + V_0 Y_1 + T_0 X_1 \rightarrow Y_1 = 0$   
 $V_{2R} = (1 - \Omega_3) B \cos R + (\Omega_3 - 2V_0) A \cos R$   
 $T_{2R} = (1 - V_0) B \cos R - T_0 A \cos R$

$$\Rightarrow V_2 \neq X_2(\tau) + [(1 - \Omega_3) B + (\Omega_3 - 2V_0) A] \cos R, T_2 \neq Y_2(\tau)$$

$$V_2 = X_2(\tau) + [(1 - \Omega_3) B + (\Omega_3 - 2V_0) A] \cos R$$

$$T_2 = Y_2(\tau) + [(1 - V_0) B - T_0 A] \cos R$$

## 2D Osc: Outer equations (cont.)

$$O(\Omega^{-3}): V_{3R} + V_{2T} = \Omega_3 (T_2 - V_2) - T_2 + 2V_0 V_2 + V_1^2$$

$$T_{3R} + T_{2T} = -T_2 + T_2 V_0 + T_0 V_2 + T_1 V_1$$

Fredholm: Note  $\frac{1}{2\pi} \int_0^{2\pi} \cos^2 R \, dR = \frac{1}{2}$

$$V_{2T} = \Omega_3 (y_2 - x_2) - y_2 + 2V_0 x_2 + \frac{A^2}{2}$$

$$T_{2T} = -y_2 + V_0 y_2 + T_0 x_2 + \frac{AB}{2}$$

equil:  $y_2 = \frac{T_0 x_2 + \frac{AB}{2}}{1 - V_0} = K_0 x_2 + \frac{AB}{2(1-V_0)} = K_0 x_2 + C$

$$0 = \Omega_3 (K_0 x_2 + C - x_2) - K_0 x_2 - C + 2V_0 x_2 + \frac{A^2}{2}$$

$$\Rightarrow x_2 = \frac{\frac{AB}{2(1-V_0)} - \Omega_3 \frac{AB}{2(1-V_0)} - \frac{A^2}{2}}{\Omega_3 K_0 - \Omega_3 - K_0 + 2V_0} = \frac{(1-V_0) \left( \frac{AB}{2} - \Omega_3 \frac{AB}{2} - \frac{A^2}{2}(1-V_0) \right)}{\Omega_3 \Omega_1 - \Omega_1 + 2V_0(1-V_0)^2 - \Omega_3(1-V_0)^2}$$

$$V \sim V_0 - \Omega^{-1} A \cos R + \Omega^{-2} \left( \frac{(1-V_0) \left( \frac{AB}{2} - \Omega_3 \frac{AB}{2} - \frac{A^2}{2}(1-V_0) \right)}{\Omega_3 \Omega_1 - \Omega_1 + (2V_0 - \Omega_3)(1-V_0)^2} + [(1-\Omega_3)B + (\Omega_3 - 2V_0)A] \sin R \right)$$

$$T \sim T_0 - \Omega^{-1} B \cos R + \Omega^{-2} \left( \frac{\Omega_1 \left( \frac{AB}{2} - \Omega_3 \frac{AB}{2} - \frac{A^2}{2}(1-V_0) \right)}{(\Omega_3 \Omega_1 - \Omega_1)(1-V_0) + (2V_0 - \Omega_3)(1-V_0)^2} + \frac{AB}{2(1-V_0)} + [(1-V_0)B - T_0 A] \sin R \right)$$

Need to perform a local analysis but first need to find the scales of the local problem.

Recall,  $(V, T, \Omega_2) = (0, \Omega_1, \Omega_1, \Omega_3)$  is the non-smooth Bif.

## Two D Scale Analysis

$$V = \varepsilon X, \quad T = \Omega_1 + \gamma y, \quad \Omega_2 = \Omega_1 \cdot \Omega_3 + \xi m$$

$$\begin{aligned} \varepsilon \dot{X} &= -\xi m + \Omega_3(\gamma y - \varepsilon x) - \gamma y - \varepsilon^2 x|x| + A \sin(\Omega t) \\ \gamma \dot{y} &= -\Omega_1 \varepsilon |x| - \varepsilon \gamma |x| y - \gamma y + B \sin(\Omega t) \end{aligned}$$

Multiple Scales:  $T = t, \quad R = \Omega t$

$$\begin{aligned} \varepsilon \Omega X_R + \varepsilon X_T &= -\xi m + \Omega_3(\gamma y - \varepsilon x) - \gamma y - \varepsilon^2 x|x| + A \sin R \\ \gamma \Omega y_R + \gamma y_T &= -\Omega_1 \varepsilon |x| - \varepsilon \gamma |x| y + B \sin R \end{aligned}$$

To see the dynamics communicate,  $\gamma = \varepsilon$ :

$$\begin{aligned} X_R + \Omega^{-1} X_T &= \Omega^{-1} \left( -\frac{\xi m}{\varepsilon} + \Omega_3(y - x) - y - \varepsilon x|x| + \frac{A}{\varepsilon} \sin R \right) \\ y_R + \Omega^{-1} y_T &= \Omega^{-1} \left( -\Omega_1 |x| - y - \varepsilon |x| y + \frac{B}{\varepsilon} \sin R \right) \end{aligned}$$

To get sin terms to give  $X_R \sim \sin R$ ,  $\varepsilon = \Omega^{-1}$ :

$$\begin{aligned} X_R + \Omega^{-1} X_T &= \Omega^{-1} \left( -\xi \Omega m + \Omega_3(y - x) - y - \Omega^{-1} x|x| \right) + A \sin R \\ y_R + \Omega^{-1} y_T &= \Omega^{-1} \left( -\Omega_1 |x| - y - \Omega^{-1} |x| y \right) + B \sin R \end{aligned}$$

The parameter should also communicate  $\Rightarrow \xi = \Omega^{-1}$

$$\begin{aligned} X_R + \Omega^{-1} X_T &= \Omega^{-1} \left( -m + \Omega_3(y - x) - y - \Omega^{-1} x|x| \right) + A \sin R \\ y_R + \Omega^{-1} y_T &= \Omega^{-1} \left( -\Omega_1 |x| - y - \Omega^{-1} |x| y \right) + B \sin R \end{aligned}$$

$$V = \Omega^{-1} X, \quad T = \Omega_1 + \Omega^{-1} y, \quad \Omega_2 = \Omega_1 \Omega_3 + \Omega^{-1} m$$



## Two D inner equations

$$\begin{aligned}\dot{x} &= -m + \mu_3(y-x) - y - \Omega^{-1}x|x| + \Omega A \sin(\Omega t) \\ \dot{y} &= -\mu_1|x| - y - \Omega^{-1}|x|y + \Omega B \sin(\Omega t)\end{aligned}$$

Multiple scales:  $t = \tau$ ,  $R = \Omega t$

$$\begin{aligned}X_R + \Omega^{-1}X_\tau &= \Omega^{-1}(-m + \mu_3(y-x) - y - \Omega^{-1}x|x|) + A \sin R \\ Y_R + \Omega^{-1}Y_\tau &= \Omega^{-1}(-\mu_1|x| - y - \Omega^{-1}|x|y) + B \sin R\end{aligned}$$

Expansions:  $X \sim X_0 + \Omega^{-1}X_1 + \dots$ ,  $y \sim y_0 + \Omega^{-1}y_1 + \dots$

$$\begin{aligned}O(1): X_{0R} &= A \sin R \rightarrow X_0 = P_0(\tau) - A \cos R \\ Y_{0R} &= B \sin R \rightarrow Y_0 = Q_0(\tau) - B \cos R\end{aligned}$$

$$\begin{aligned}O(\Omega^{-1}) X_{1R} + X_{0\tau} &= -m + (\mu_3 - 1)Y_0 - \mu_3 X_0 \\ Y_{1R} + Y_{0\tau} &= -\mu_1 |X_0| - Y_0\end{aligned}$$

$$\begin{aligned}\text{Fredholm: } X_{0\tau} &= -m + (\mu_3 - 1)Q_0 - \mu_3 P_0 \quad (1) \\ Y_{0\tau} &= -\frac{\mu_1}{2\pi} \int_0^{2\pi} |P_0(\tau) - A \cos R| dR - Q_0 \quad (2)\end{aligned}$$

Equil:

$$\Rightarrow Q_0 = -\frac{\mu_1}{2\pi} \int_0^{2\pi} |P_0(\tau) - A \cos R| dR \stackrel{\text{1D osc.}}{=} -\frac{2\mu_1}{\pi} \left( \sin^{-1}\left(\frac{P_0}{A}\right) + \sqrt{A^2 - P_0^2} \right)$$

$$\text{Taylor approx: } Q_0 \approx -\frac{2\mu_1 |A|}{\pi} - \frac{\mu_1}{\pi |A|} P_0^2 = -c - a P_0^2$$

$$\xrightarrow{\text{Equil}} \textcircled{1} \quad 0 = a(1 - \mu_3) P_0^2 - \mu_3 P_0 + c(1 - \mu_3) - m$$

$$\Rightarrow P_0 = \frac{\mu_3}{2a(1 - \mu_3)} \pm \frac{1}{2a(1 - \mu_3)} \sqrt{\mu_3^2 - 4a(1 - \mu_3)[c(1 - \mu_3) - m]}$$

$$\rightarrow \mu_{\text{osc}} = \frac{2\mu_1(1 - \mu_3)}{\pi |A|} - \frac{\pi |A| \mu_3^2}{4\mu_1(1 - \mu_3)} \Rightarrow \mu_{\text{osc}} = \mu_1 \mu_3 + \Omega^{-1} \mu_{\text{osc}}$$