

Optimization Methods in Machine Learning HW2

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1 Theory Tasks

2 Consider Lemma 12 from the lecture notes: Let f be a differentiable, L -smooth function. Then

$$f(x) \leq \underbrace{f(y) + \langle \nabla f(y), x - y \rangle + \frac{L}{2} \|x - y\|^2}_{g(x) :=}$$

for all $x, y \in \mathbb{R}^d$. Find the optimal x that minimizes the upper bound $g(x)$.

Solution

$$\begin{aligned} g(x) &= f(y) + \langle \nabla f(y), x - y \rangle + \frac{L}{2} \|x - y\|^2 \\ &= \langle \nabla f(y), x \rangle + \frac{L}{2} \|x\|^2 - L \langle x, y \rangle + f(y) - \langle \nabla f(y), y \rangle + \frac{L}{2} \|y\|^2 \\ &= \langle \nabla f(y), x \rangle + \frac{L}{2} \langle x, x \rangle - L \langle x, y \rangle + f(y) - \langle \nabla f(y), y \rangle + \frac{L}{2} \|y\|^2 \\ \Rightarrow g(x) &\text{ is quadratic. This implies the function is convex} \\ \Rightarrow dg &= \langle \nabla f(y), dx \rangle + \frac{L}{2} \langle (I_n + I_n^T)x, dx \rangle - L \langle y, dx \rangle \\ &= \langle \nabla f(y), dx \rangle + \frac{L}{2} \langle 2x, dx \rangle - L \langle y, dx \rangle \\ &= \langle \nabla f(y), dx \rangle + L \langle x, dx \rangle - L \langle y, dx \rangle \\ &= \langle \nabla f(y), dx \rangle + L \langle x - y, dx \rangle \\ dg &= \langle \nabla f(y) + L(x - y), dx \rangle \\ \Rightarrow \nabla g(x) &= \nabla f(y) + L(x - y) \\ \Rightarrow x^* &= \frac{yL - \nabla f(y)}{L} \end{aligned}$$

Hence, the optimal value of x that minimizes the upper bound of $g(x)$ is $\frac{yL - \nabla f(y)}{L}$

For convexity,

$$\begin{aligned} d^2g &= d(\langle \nabla f(y) + L(x - y), dx_1 \rangle) = \langle d(\nabla f(y) + L(x - y)), dx_1 \rangle \\ &= \langle LI_n dx, dx_1 \rangle \\ \Rightarrow \nabla^2 g &= LI_n \succ 0 \end{aligned}$$

optimal value,

$$x^* = \frac{yL - \nabla f(y)}{L}$$

3 Consider Theorem 22 and the corresponding proof from the lecture notes. How would the result change if, instead of L -smoothness (implies Lemma 12), the function f satisfies the inequality

$$f(x) \leq f(y) + \langle \nabla f(y), x - y \rangle + \frac{L}{2} \|x - y\|^2 + \delta$$

for all $x, y \in \mathbb{R}^d$ and some $\delta \geq 0$? (Theorem 22 is true when $\delta = 0$. What if $\delta > 0$?)

Solution

From the given inequality and GD update rule $x^{k+1} = x^k - \gamma \nabla f(x^k)$, we have

$$\begin{aligned} f(x^{k+1}) &\leq f(x^k) + \langle \nabla f(x^k), x^{k+1} - x^k \rangle + \frac{L}{2} \|x^{k+1} - x^k\|^2 + \delta \\ \Rightarrow f(x^{k+1}) &\leq f(x^k) - \gamma \|\nabla f(x^k)\|^2 + \frac{L\gamma^2}{2} \|\nabla f(x^k)\|^2 + \delta \\ \Rightarrow f(x^{k+1}) &\leq f(x^k) - \left(\gamma - \frac{L\gamma^2}{2}\right) \|\nabla f(x^k)\|^2 + \delta \end{aligned}$$

For $0 < \gamma \leq \frac{1}{L}$, we have that $\gamma - \frac{L\gamma^2}{2} \leq \frac{\gamma}{2}$, hence,

$$f(x^{k+1}) \leq f(x^k) - \left(\gamma - \frac{L\gamma^2}{2}\right) \|\nabla f(x^k)\|^2 + \delta \leq f(x^k) - \frac{\gamma}{2} \|\nabla f(x^k)\|^2 + \delta$$

Summing the inequality over $k = 0, 1, \dots, T-1$, we get,

$$f(x^T) \leq f(x^0) - \frac{\gamma}{2} \sum_{k=0}^{T-1} \|\nabla f(x^k)\|^2 + T\delta$$

. Let f^* denote the lower bound of f . Then,

$$f^* \leq f(x^T) \leq f(x^0) - \frac{\gamma}{2} \sum_{k=0}^{T-1} \|\nabla f(x^k)\|^2 + T\delta$$

This gives,

$$\begin{aligned} f^* &\leq f(x^0) - \frac{\gamma}{2} \sum_{k=0}^{T-1} \|\nabla f(x^k)\|^2 + T\delta \\ \Rightarrow \frac{\gamma}{2} \sum_{k=0}^{T-1} \|\nabla f(x^k)\|^2 &\leq f(x^0) - f^* + T\delta \\ \Rightarrow \frac{1}{T} \sum_{k=0}^{T-1} \|\nabla f(x^k)\|^2 &\leq \frac{2(f(x^0) - f^*)}{\gamma T} + \frac{2\delta}{\gamma} \end{aligned}$$