
Lab Manual 09

SEMAPHORES

1 WHAT IS A SEMAPHORE ?

1. Dijkstra proposed a significant technique for managing concurrent processes for complex mutual exclusion problems. He introduced a new synchronization tool called Semaphore.
2. Posix Semaphores are Inter Process or Threads synchronization technique, just like mutex.
3. A semaphore is an integer value variable, which can be incremented and unlocked or decremented and locked by threads or processes.

2 POSIX TYPES OF SEMAPHORE

POSIX Semaphores are of 2 types:

1. Named Semaphore
2. Memory-mapped Semaphore

3 UNNAMED SEMAPHORES (MEMORY-BASED SEMAPHORES)

1. No name is associated with these semaphores
2. Provides synchronization between threads and between related processes

3. Placed in a region of main memory that is shared between processes/threads
4. For threads this is done by simply making the semaphore a global variable

4 KINDS OF SEMAPHORES

Depending upon the value a semaphore is made to hold, it can be:

1. Binary semaphore
2. Counting semaphore

5 USES OF SEMAPHORES

Semaphores can be use for synchronization between Threads/Processes. It also provide a way to avoid Dead-locks.

1. **For placing Locks**

Just like mutex (can me binary or counting).

- (a) Counting Semaphores:
Permit a limited number of threads to execute a section of the code.
- (b) Binary Semaphores:
Permit only one thread to execute a section of the code.

2. **Semaphores As Condition Variables**

- (a) Semaphores are also useful when a thread wants to halt its progress waiting for a condition to become true.
- (b) Communicate information about the state of shared data.

6 SEMAPHORES VS MUTEX

1. Mutex can be locked or unlocked, like binary semaphore. Semaphores (counting) can have multiple values.
2. A locked mutex can be unlocked by the thread holding the lock. A locked semaphore can be unlocked by any thread.
3. Semaphore has state (value of semaphore) associated with it.
4. Mutex and condition variables are used together in most scenario. Looking at their functionality, it can be thought as : Semaphore = Mutex + Condition Variable
5. Posix Named Semaphore are kernel persistent. Posix Memory based semaphore, Posix Condition Variable and Posix Mutex are process persistent.

7 SEMAPHORE SYSTEM CALLS

```
#include <semaphore.h>

int sem_init();

int sem_wait();

int sem_trywait();

int sem_post();

int sem_destroy();
```

8 CREATE A SEMAPHORE

```
int sem_init(sem_t *sem, int pshared, unsigned int value)
```

1. **sem:** Target semaphore
2. **pshared:** The pshared argument indicates whether this semaphore is to be shared-between the threads of a process, or between processes.
 - (a) **0:** only threads of the creating process can use the semaphore.
 - (b) **Non-0:** other processes can use the semaphore.
3. **value:** Initial value of the semaphore.

EXAMPLE:

```
#include <semaphore.h>
sem_t s;
sem_init(&s, 0, 1)
```

We declare a semaphore `s` and initialize it to the value 1 by passing 1 in as the third argument. The second argument to `sem_init()` will be set to 0 in all of the examples we'll see; this indicates that the semaphore is shared between threads in the same process.

9 SEMAPHORE OPERATIONS

1. **sem_wait()** decrements (locks) the semaphore pointed to by `sem`.

```
int sem_wait(sem_t *sem)
```

- (a) If the semaphore's value is greater than zero, then the decrement proceeds, and the function returns (gets lock), immediately.

- (b) If the value of the semaphore is negative, the calling thread blocks; one of the blocked threads wakes up when another thread calls `sem_post()`
2. **sem_post()** does not wait for some particular condition to hold like `sem_wait()` does.

```
int sem_post(sem_t *sem)
```

Rather, it simply increments the value of the semaphore and then, if there is a thread waiting to be woken, wakes one of them up.

```
int sem_wait(sem_t*s) {
    decrement the value of semaphore s by one
    wait if value of semaphore s is negative
}

int sem_post(sem_t*s)
    increment the value of semaphore s by one
    if there are one or more threads waiting, wake one
}
```

3. **sem_trywait()** is the version of the `sem_wait()` which does not block.

```
int sem_trywait(sem_t * sem)
```

Decreases the semaphore by one if the semaphore does not equal to zero. If it is zero it does not block, returns zero with error code EAGAIN.

4. **sem_destroy** releases the resources that semaphore has and destroys it

```
int sem_destroy(sem_t * sem)
```

10 EXAMPLES

EXAMPLE 01: SEMAPHORE A BINARY LOCK

```
#include<stdio.h>
#include<stdlib.h>
#include<signal.h>
#include<pthread.h>
#include <semaphore.h>
#include <unistd.h>

// Using semaphore as a Binary lock for IPC/Synchronization

sem_t sem;
void * f1(void *arg){
    sem_wait(&sem);
    printf("Thread with ID:%ld got lock\n",pthread_self());
    sleep(2);
    sem_post(&sem);
    pthread_exit(NULL);
}
```

```

}

int main(){
    pthread_t tid1, tid2;
    sem_init(&sem, 0, 1);
    pthread_create(&tid1, NULL, f1, NULL);
    pthread_create(&tid2, NULL, f1, NULL);
    pthread_exit(NULL);
}

```

EXAMPLE 02: SEMAPHORE A COUNTING VARIABLE

```

#include<stdio.h>
#include<stdlib.h>
#include<signal.h>
#include<pthread.h>
#include <semaphore.h>
#include <unistd.h>
sem_t sem;
void * f1(void *arg)
{
    int i=1,value;
    sem_wait(&sem);
    sem_getvalue(&sem, &value);
    printf("Thread with ID %ld return from wait() and
           Sem state is :%d\n",pthread_self(),value);

    pthread_exit(0);
}
int main()
{
    pthread_t tid[5];
    int value,i;
    sem_init(&sem,0,3);
    for(i=0;i<5;i++){
        pthread_create(&tid[i],NULL,f1,NULL);
    }

    sleep(3);
    printf("Main:Going to Post\n");
    sem_post(&sem);
    sem_getvalue(&sem, &value);
    printf("Main:After Post sem state:%d \n",value);
    sleep(3);
    printf("Main:Going to Post\n");
    sem_post(&sem);
    sem_getvalue(&sem, &value);
    printf("Main:After Post sem state:%d \n",value);

    pthread_exit(0);
}

```

EXAMPLE 03: SEMAPHORE A CONDITIONAL VARIABLE

```

#include<stdio.h>

```

```
#include<stdlib.h>
#include<signal.h>
#include<pthread.h>
#include <semaphore.h>
#include <unistd.h>

// Using semaphore as a condition variable for IPC/Synchronization

sem_t sem;
void * f1(void *arg){
    printf("Child:  begin\n");
    sem_post(&sem);
    printf("Child:  end\n");
    pthread_exit(NULL);
}

int main(){
    pthread_t tid;
    sem_init(&sem,0,0);
    printf("parent:  begin\n");
    pthread_create(&tid ,NULL, f1 ,NULL);
    sem_wait(&sem);
    printf("parent:  end\n");
    pthread_exit(NULL);
}
```