Elementos de Cálculo Numérico/Cálculo Numérico

Clase 7

Primer Cuatrimestre 2021

Proceso de ortonormalización

 $\{m u_1,\dots,m u_d\}$ base del subespacio S $\{m v_1,\dots,m v_d\}$ base ortonormal $\{m u_1,\dots,m u_k\}$ y $\{m v_1,\dots,m v_k\}$ generan el mismo subespacio

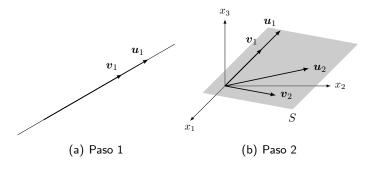


Fig.: Proceso de ortonormalización.

Método de Gram-Schmidt

Paso 1
$$oldsymbol{v}_1 = oldsymbol{u}_1/\|oldsymbol{u}_1\|$$

Paso 2

$$\tilde{\boldsymbol{v}}_2 = \boldsymbol{u}_2 - (\boldsymbol{v}_1.\boldsymbol{u}_2)\boldsymbol{v}_1 \quad \Longrightarrow \tilde{\boldsymbol{v}}_2 \perp \boldsymbol{v}_1$$

$$oldsymbol{v}_2 = ilde{oldsymbol{v}}_2/\| ilde{oldsymbol{v}}_2\|$$

Paso 3

$$\tilde{\boldsymbol{v}}_3 = \boldsymbol{u}_3 - (\boldsymbol{v}_1.\boldsymbol{u}_3)\boldsymbol{v}_1 - (\boldsymbol{v}_2.\boldsymbol{u}_3)\boldsymbol{v}_2 \quad \Longrightarrow \tilde{\boldsymbol{v}}_3 \perp \boldsymbol{v}_1, \tilde{\boldsymbol{v}}_3 \perp \boldsymbol{v}_2$$

$$\boldsymbol{v}_3 = \tilde{\boldsymbol{v}}_3 / \|\tilde{\boldsymbol{v}}_3\|$$

Paso k

$$\tilde{\boldsymbol{v}}_k = \boldsymbol{u}_k - \sum_{j=1}^{k-1} (\boldsymbol{v}_j.\boldsymbol{u}_3) \boldsymbol{v}_j \implies \tilde{\boldsymbol{v}}_k \perp \boldsymbol{v}_j, \quad j = 1, \dots, k-1$$

$$oldsymbol{v}_k = ilde{oldsymbol{v}}_k / \| ilde{oldsymbol{v}}_k\|$$

Método de Gram-Schmidt modificado

Definimos
$$\boldsymbol{u}_{j}^{(0)}=\boldsymbol{u}_{j},\,j=1,\ldots,d$$

Paso 1: para $j = 2, \ldots, d$

$$lackbox{u}_1^{(1)} = oldsymbol{u}_1^{(0)} / \|oldsymbol{u}_1^{(0)}\|$$

$$oldsymbol{u}_j^{(1)} \perp oldsymbol{u}_1^{(1)} = 0$$
 para $j = 2, \dots, d$

Paso 2: para $j = 3, \ldots, d$

$$oldsymbol{u}_i^{(2)} \perp oldsymbol{u}_2^{(2)} = 0$$
 para $j = 3, \dots, d$

Cambio de base

$$\{m u_1,\dots,m u_k\}$$
 y $\{m v_1,\dots,m v_k\}$ generan el mismo subespacio $1\le k\le d$ Existen coeficientes $\{r_{i,j}:j=1,\dots,d\quad i=1,\dots,j\}$
$$m u_1=r_{1,1}\,m v_1$$

$$\boldsymbol{u}_d = r_{1,d} \, \boldsymbol{v}_1 + \dots + r_{d,d} \, \boldsymbol{v}_d$$

$$[m{u}_1 \; m{u}_2 \; \cdots \; m{u}_d] = [m{v}_1 \; m{v}_2 \; \cdots \; m{v}_d] \left[egin{array}{cccc} r_{1,1} & r_{1,2} & \dots & r_{1,d} \ 0 & r_{2,2} & \dots & r_{2,d} \ dots & dots & \ddots & dots \ 0 & 0 & \dots & r_{d,d} \end{array}
ight]$$

Descomposición QR

 $A = [a_1 \cdots a_n]$ inversible,

$$\{a_1,\ldots,a_n\}$$
 columnas de A forman una base $\{q_1,\ldots,q_n\}$ base ortonormal obtenida por G-S $A=Q.R$ $Q=[q_1\ \cdots\ q_n]$ (matriz ortogonal)
$$R=\begin{bmatrix}r_{1,1}&r_{1,2}&\ldots&r_{1,n}\\0&r_{2,2}&\ldots&r_{2,n}\\\vdots&\vdots&\ddots&\vdots\\0&0&\ldots&r_{n,n}\end{bmatrix}$$
 (matriz triangular superior)

Resolución de sistema usando descomposición QR

 $\mathbf{A} \in \mathbb{R}^{n \times n}$ inversible

Sistema: A.x = b

 $Q.R.\boldsymbol{x} = \boldsymbol{b}$

Q.y = b, R.x = y

Q ortogonal $\Longrightarrow y = Q^T.\boldsymbol{b}$

R triangular: R.x = y (eliminación recursiva)

Matrices ortogonales

 $Q \in \mathbb{R}^{n \times n}$, son equivalentes:

- Las columnas de Q forman una base ortonormal
- Las filas de Q forman una base ortonormal
- $Q^T = Q^{-1}$
- $\|\mathbf{Q}.\boldsymbol{x}\|_2 = \|\boldsymbol{x}\|_2$
- $\quad \blacksquare \ (\mathbf{Q}.\boldsymbol{x}).(\mathbf{Q}.\boldsymbol{y}) = \boldsymbol{x}.\boldsymbol{y}$

En este caso $Q \in \mathbb{R}^{n \times n}$ es ortogonal

Matrices ortogonales

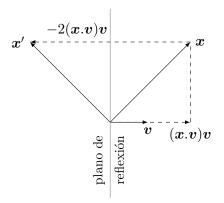
 $\mathbf{Q} \in \mathbb{R}^{n \times n}$ ortogonal

- $det(Q) = \pm 1$
- $||Q||_2 = 1$
- $\kappa_2(Q) = 1$
- lacksquare λ autovalor $\Longrightarrow |\lambda| = 1$
- Ejemplo: Q rotación $\Longrightarrow det(Q) = 1$
- Ejemplo: Q reflexión $\Longrightarrow det(Q) = -1$

Reflexiones

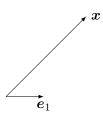
Si $\| {m v} \| = 1$, la transformación ${m x} \mapsto {m x} - 2({m v}.{m x}){m v}$ es ortogonal:

$$\|\boldsymbol{x} - 2(\boldsymbol{v}.\boldsymbol{x})\boldsymbol{v}\|_{2}^{2} = \|\boldsymbol{x}\|_{2}^{2} - 4(\boldsymbol{v}.\boldsymbol{x})^{2} + 4(\boldsymbol{v}.\boldsymbol{x})^{2} = \|\boldsymbol{x}\|_{2}^{2}$$



$$e_1 = (1 \ 0 \dots 0) \in \mathbb{R}^n$$

$$egin{aligned} ilde{oldsymbol{v}} &= oldsymbol{x} + \|oldsymbol{x}\|oldsymbol{e}_1 & ext{si } x_1 \geq 0 \quad ilde{oldsymbol{v}} &= oldsymbol{x} - \|oldsymbol{x}\|oldsymbol{e}_1 \ & oldsymbol{v} &= ilde{oldsymbol{v}} / \| ilde{oldsymbol{v}}\| \ & oldsymbol{x}' = oldsymbol{x} - 2\left(oldsymbol{v}.oldsymbol{x}
ight) oldsymbol{v} = \pm \|oldsymbol{x}\| oldsymbol{e}_1 \end{aligned}$$



Si
$$A \in \mathbb{R}^{n \times n}$$
, $A = [\boldsymbol{a}_1 \boldsymbol{a}_2 \dots \boldsymbol{a}_n]$

Definimos:
$$oldsymbol{v} \in \mathbb{R}^n$$
, $ilde{oldsymbol{v}} = oldsymbol{a}_1 \pm \|oldsymbol{a}_1\|oldsymbol{e}_1$, $oldsymbol{v} = ilde{oldsymbol{v}}/\| ilde{oldsymbol{v}}\|$

$$Q_1.a_1 = a_1 - 2(a_1.v)v = \alpha_1 e_1$$

$$\mathbf{Q}_{1}.\mathbf{A} = \begin{bmatrix} \alpha_{1} \mathbf{e}_{1} \mathbf{a}_{2}' \dots \mathbf{a}_{n}' \end{bmatrix} = \begin{bmatrix} \alpha_{1} & a_{1,2}' & a_{1,3}' & \dots & a_{1,n}' \\ 0 & a_{2,2}' & a_{3,3}' & \dots & a_{3,n}' \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & a_{n,2}' & a_{n,3}' & \dots & a_{n,n}' \end{bmatrix} \begin{bmatrix} \alpha_{1} \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

Existe $Q' \in \mathbb{R}^{(n-1)\times(n-1)}$

$$\mathbf{Q'}.\begin{bmatrix} a'_{2,2} & a'_{2,3} & \dots & a'_{2,n} \\ a'_{3,2} & a'_{3,3} & \dots & a'_{3,n} \\ \vdots & \vdots & \ddots & \vdots \\ a'_{n,2} & a'_{n,3} & \dots & a'_{n,n} \end{bmatrix} = \begin{bmatrix} \alpha_2 & a''_{2,3} & \dots & a''_{2,n} \\ 0 & a''_{3,3} & \dots & a''_{3,n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & a''_{n,3} & \dots & a''_{n,n} \end{bmatrix}$$

Existe $Q_2 \in \mathbb{R}^{n \times n}$ ortogonal

$$Q_2.Q_1.A = \begin{bmatrix} 1 & 0 \\ 0 & Q' \end{bmatrix}.Q_1.A = \begin{bmatrix} \alpha_1 & a'_{1,2} & a'_{1,3} & \dots & a'_{1,n} \\ 0 & \alpha_2 & a''_{2,3} & \dots & a''_{2,n} \\ 0 & 0 & a''_{3,3} & \dots & a''_{3,n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & a''_{n,3} & \dots & a''_{n,n} \end{bmatrix}$$

Existen $Q_1, \dots Q_{n-1}$ ortogonales y R triangular superior:

$$Q_{n-1}.Q_{n-2}...Q_2.Q_1.A = R$$

El sistema A.x = b es equivalente a:

$$Q_{n-1}.Q_{n-2}...Q_2.Q_1.A.x = R.x$$

Se obtiene: $R.\boldsymbol{x} = Q_{n-1}.Q_{n-2}...Q_2.Q_1.\boldsymbol{b}$

Descomposición QR por matrices de Householder

Ejemplo: $A \in \mathbb{R}^{3 \times 3}$, $\boldsymbol{b} \in \mathbb{R}^3$, $A.\boldsymbol{x} = \boldsymbol{b}$

$$\mathbf{A} = \begin{bmatrix} 2.31378 & -0.80272 & -2.53906 \\ 1.12035 & -5.84402 & -1.16536 \\ 5.46919 & 4.91904 & -3.19922 \end{bmatrix}, \ \boldsymbol{b} = \begin{bmatrix} 3.83421 \\ 3.99835 \\ -5.24273 \end{bmatrix}$$

Paso 1:

$$\mathbf{a}_1 = (2.31378, 1.12035, 5.46919), \|\mathbf{a}_1\| = 6.04324$$

 $\tilde{\mathbf{v}}_1 = (8.35702, 1.12035, 5.46919), \mathbf{v}_1 = (0.83153, 0.11148, 0.54419)$

$$\mathrm{Q}_1 = \left[\begin{array}{cccc} -0.382\,87 & -0.185\,39 & -0.905\,01 \\ -0.185\,39 & 0.975\,15 & -0.121\,33 \\ -0.905\,01 & -0.121\,33 & 0.407\,72 \end{array} \right]$$

Descomposición QR por matrices de Householder

Paso 1:

$$\mathbf{Q}_1.\mathbf{A} = \left[\begin{array}{ccc} -6.043\,24 & -3.061\,02 & 4.083\,50 \\ 0.0 & -6.146\,77 & -0.277\,54 \\ 0.0 & 3.441\,11 & 1.134\,87 \end{array} \right]$$

Paso 2:

$$\boldsymbol{a}_2 = (-6.14677, 3.44111), \ \|\boldsymbol{a}_2\| = 7.04443$$

$$\tilde{\boldsymbol{v}}_2 = (0., 0.89766, 3.44111), \ \boldsymbol{v}_2 = (0., 0.25242, 0.96762)$$

$$Q_2 = \left[\begin{array}{ccc} 1.0 & 0.0 & 0.0 \\ 0.0 & 0.872\,57 & -0.488\,49 \\ 0.0 & -0.488\,49 & -0.872\,57 \end{array} \right]$$

Descomposición QR por matrices de Householder

Paso 2:

$$R = Q_2.Q_1.A = \left[\begin{array}{cccc} -6.043\,24 & -3.061\,02 & 4.083\,50 \\ 0.0 & -7.044\,43 & -0.796\,54 \\ 0.0 & 0.0 & -0.854\,68 \end{array} \right]$$

Resolución: R. $\boldsymbol{x} = Q_2.Q_1.\boldsymbol{b}$

$$\begin{bmatrix} -6.04324 & -3.06102 & 4.08350 \\ 0.0 & -7.04443 & -0.79654 \\ 0.0 & 0.0 & -0.85468 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2.53546 \\ 6.31312 \\ 3.44821 \end{bmatrix}$$

$$\mathbf{x} = (-2.92287, -0.43999, -4.03452)$$