

Erreur de Hermite

$$\text{gr}(P) = m$$

	x	y	
1	x_1	y_1	
2	x_2	y_2	y_2'
3	x_n	y_n	y_n'
$m+1$			

$$P(x) = a_0 + a_1(x-x_1) + a_2(x-x_1)(x-x_2) + a_3(x-x_1)(x-x_2)^2 + a_m(x-x_1)(x-x_2)^2 \dots (x-x_n)^2$$

$$f(x) - P(x) = \frac{f^{(m+1)}(\xi)}{(m+1)!} W(x)$$

$$W(x) = (x-x_1)^2 \dots (x-x_n)^2 \quad \text{gr}(W) = m+1$$

x	y	y'	y''
0	1	-	-
1	1	2	-4
2	0	-2	

$$\begin{array}{r} 1 \\ 3 \\ 2 \\ \hline 6 \end{array}$$

$$6 = m+1 \quad m=5$$

x	y
0	1
1	0
1	2
1	-2
1	2
2	0
2	0

$$P_5(x) = 1 + 0(x-0) + 2(x-0)(x-1) - 4(x-0)(x-1)^2 + \frac{3}{2}(x-0)(x-1)^3 + \frac{3}{4}(x-0)(x-1)^3(x-2)$$

$$f(x) - P_5(x) = \frac{f^{(6)}(\xi)}{6!} \underbrace{(x-0)(x-1)^3(x-2)^2}_{w(x)}$$

$$y = \alpha + \beta \ln(1+x) + \gamma x^4$$

$$\phi_0(x) = 1$$

$$\phi_1(x) = \ln(1+x)$$

$$\phi_2(x) = x^4$$

$$\bar{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \quad N \times 1$$

$$\Phi = \begin{pmatrix} 1 & \ln(1+x_1) & x_1^4 \\ 1 & \ln(1+x_2) & x_2^4 \\ \vdots & \vdots & \vdots \\ 1 & \ln(1+x_N) & x_N^4 \end{pmatrix} \quad N \times 3$$

$$\begin{matrix} \bar{\Phi}^T & \bar{y} & = & \bar{\Phi}^T & \Phi & \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix} \\ 3 \times N & N \times 1 & & 3 \times N & N \times 3 & 3 \times 1 \\ & & & \underbrace{\hspace{2cm}} & & \\ & & & 3 \times 3 & & \end{matrix}$$

Ec. normales

$$y = a_0 + a_1 x_1 + \dots + a_p x_p$$

$$\vec{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_N \end{pmatrix} \quad \Phi = \begin{pmatrix} 1 & x_{1,1} & x_{1,2} & \dots & x_{1,p} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{N,1} & x_{N,2} & \dots & x_{N,p} \end{pmatrix}$$

$$y = \alpha + \beta x$$

x	y
x_1	y_1
\vdots	\vdots
x_N	y_N

$$\Phi = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{pmatrix} \quad \Phi^T \Phi = \begin{pmatrix} N & \sum x_j \\ \sum x_j & \sum x_j^2 \end{pmatrix}$$

$\vec{x} \neq \vec{1} \Rightarrow \Phi^T \Phi$ es invertible

$$\sum x_j = \vec{x} \cdot \vec{1}$$

$$\|\vec{1}\|^2 \|\vec{x}\|^2 - (\vec{x} \cdot \vec{1})^2 = \det(\Phi^T \Phi)$$

$$\vec{x} = k \vec{1}$$

x	y
k	y ₁
k	y ₂
k	
k	
k	y _N

$$\sum y_j = N\alpha + \sum x_j \beta$$

$$\sum x_j y_j = \sum x_j \alpha + \sum x_j^2 \beta$$

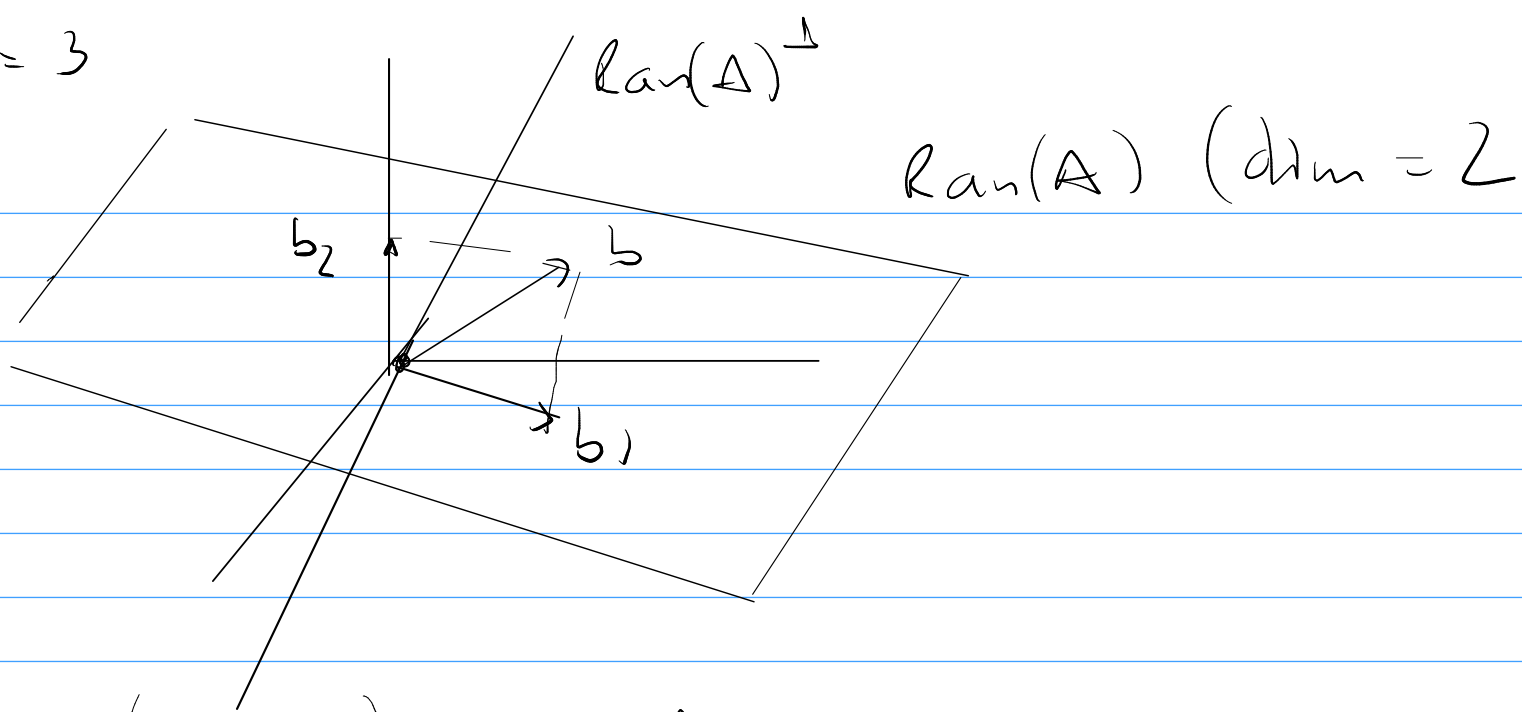
$$\left\{ \begin{array}{l} \sum y_j = N\alpha + Nk\beta \\ k \sum y_j = kN\alpha + k^2 N\beta \end{array} \right\} \downarrow \times$$

∞ soluciones

$$\alpha = \frac{\sum y_j}{N} - k\beta$$

Hay razones para elegir α, β / $\alpha^2 + \beta^2$ sea mínimo

$$M = 3$$



$$A = \begin{pmatrix} \\ \\ \end{pmatrix}$$

$$A \ 3 \times 2$$

$$V \Rightarrow 3 \times 3$$

$$U \rightarrow 2 \times 2$$

$$\bar{\Sigma} \ 3 \times 2$$

$$\tilde{\Sigma} = \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \\ 0 & 0 \end{pmatrix}$$

B simétrica $\lambda_1, \dots, \lambda_n \in \mathbb{R}$

Existen n autovectores $B v_k = \lambda_k v_k$

$$\lambda_k \neq \lambda_j \Rightarrow v_k \perp v_j$$

$$B \text{ semidef} + \Rightarrow \lambda_j \geq 0$$

$$B v_j = \lambda_j v_j \rightarrow A^T A v_j = \lambda_j v_j$$

$$\lambda_1, \dots, \lambda_k > 0 \quad \lambda_{k+1} = 0, \dots, \lambda_n = 0$$

$$v_j = \frac{1}{\sqrt{\lambda_j}} A v_j \quad j = 1, \dots, k$$

$$\begin{aligned} v_j^T \cdot v_l &= \frac{1}{\sqrt{\lambda_j}} v_j^T A^T \frac{1}{\sqrt{\lambda_l}} A v_l = \frac{1}{\sqrt{\lambda_j \lambda_l}} v_j^T (B v_l) \\ &= \frac{\lambda_l}{\sqrt{\lambda_j \lambda_l}} (v_j^T v_l) = \begin{cases} 1 & j=l \\ 0 & j \neq l \end{cases} \end{aligned}$$

$m \times n$

4×3

$k=2$

$$\underbrace{(v_1, v_2, v_3, v_4)}_V$$

V

$$\Sigma = \begin{pmatrix} \lambda_1^{1/2} & 0 & 0 \\ 0 & \lambda_2^{1/2} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \underbrace{(v_1, v_2, v_3)}_{U^T}$$

$$U = (U_1 \ U_2 \ \dots \ U_n)$$

$$A \cdot U = (A \cdot U_1 \ A \cdot U_2 \ \dots \ A \cdot U_n) = \begin{pmatrix} \lambda_1^{1/2} \sigma_1 & & & \\ & \lambda_k^{1/2} \sigma_k & 0 & \dots & 0 \end{pmatrix}$$

$$\underbrace{\begin{pmatrix} \sigma_1 & \sigma_2 & & \sigma_k & \sigma_{k+1} & & \sigma_m \end{pmatrix}}_V \underbrace{\begin{pmatrix} \lambda_1^{1/2} & & & & & & \\ & \lambda_2^{1/2} & & & & & \\ & & \ddots & & & & \\ & & & \lambda_k^{1/2} & & & \\ & & & & 0 & & \\ & & & & & \ddots & \\ & & & & & & 0 \end{pmatrix}}_{\Sigma}$$

$$V \Sigma = A U \rightarrow \boxed{V \Sigma U^T = A}$$

$$A = V \Sigma U^T$$

$$A^T A x = A^T b$$

$$A^T = U \Sigma^T V^T$$

$$A^T A = U \Sigma^T \underbrace{V^T V}_{I_m} \Sigma U^T = U \Sigma^T \Sigma U^T = U \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & 0 \end{pmatrix} U^T = U \Sigma^T V^T$$

$$\tilde{\Sigma} = \begin{pmatrix} \lambda_1^{1/2} & & & \\ & \lambda_2^{1/2} & & \\ & & 0 & \\ 0 & 0 & 0 & \end{pmatrix} \quad \tilde{\Sigma}^T = \begin{pmatrix} \lambda_1^{1/2} & 0 & 0 & 0 \\ 0 & \lambda_1^{1/2} & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\tilde{\Sigma}^T \tilde{\Sigma} = \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$U \tilde{A} \underbrace{U^T X}_Y$$

$$A = V \tilde{\Sigma} U^T \quad A^T = U \tilde{\Sigma}^T V^T$$

$$\cancel{U} \tilde{\Sigma}^T \underbrace{\tilde{\Sigma} U^T X}_Y = \cancel{U} \tilde{\Sigma}^T V^T b$$

$$\tilde{\Sigma} = \begin{pmatrix} \gamma_1 & & & \\ & \gamma_k & & \\ & & \lambda_1 & \\ & & & \lambda_2 & \\ & & & & \lambda_k \\ & & & & & 0 \\ 0 & & & & & 0 \end{pmatrix}$$

$$\tilde{\Sigma} \gamma = V b$$

$$\underbrace{\gamma_1 - \gamma_k}_{\text{fijos}}$$

$$\underbrace{\gamma_{k+1} - \gamma_m}_{\text{arbitrarios}}$$

$$\| \gamma \|^2 = \underbrace{\gamma_1^2 + \dots + \gamma_k^2}_{\text{fijos}} + \underbrace{\gamma_{k+1}^2 + \dots + \gamma_m^2}_{\text{arbitrarios}}$$

A^+ pseudo-inverse (Moore-Penrose)

$$A \in \mathbb{R}^{m \times n}$$

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2 \quad / \quad \|x\|_2 \min$$

$$x = \underbrace{A^+}_{\neq} b \quad b \longrightarrow x$$

Si $m = n$ A invertible $\Rightarrow A^+ = A^{-1}$

$$m > n \quad \text{rg}(A) = n$$

$$A^+ = \underbrace{(A^T A)^{-1}}_{n \times n} \underbrace{A^T}_{n \times m}$$