SIA - TP4

Grupo 7

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Red de Kohonen

Datos (x28):

Country
Area
GDP
Inflation
Life Expectancy
Military Expense
People Growth
Unemployment

Variables:

Epochs (Factor)

RO

R constante o variable

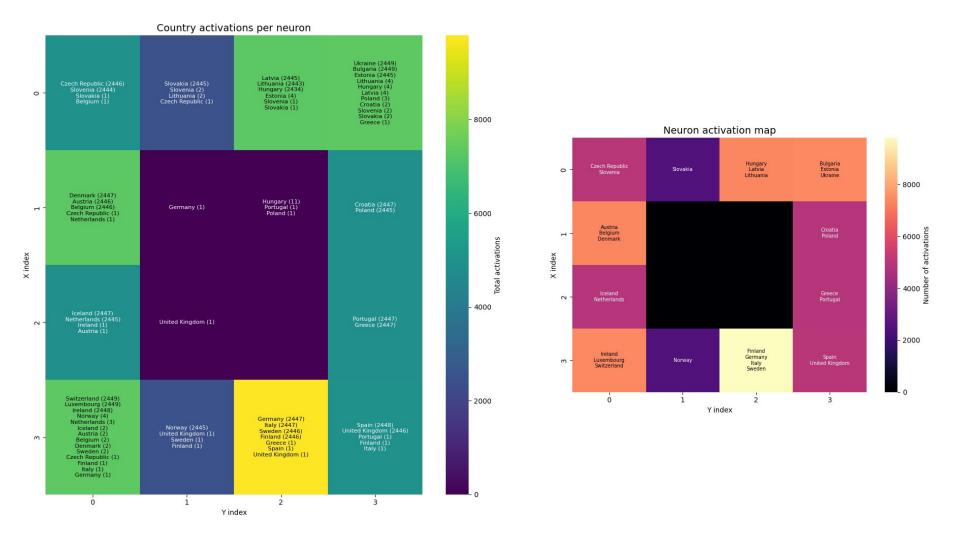
S: Euclídea o Exponencial

K

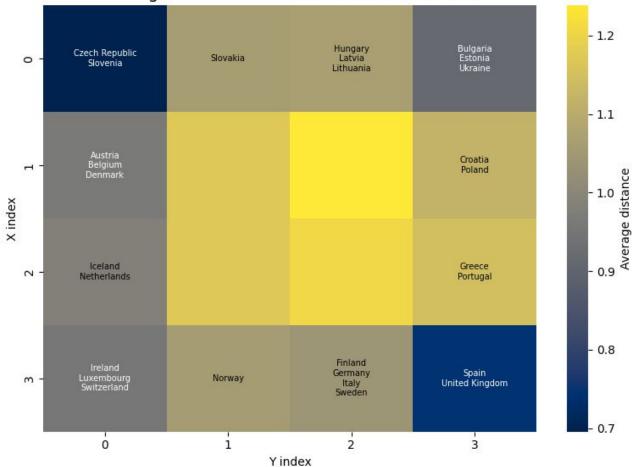
*Learning Rate fijo en 1

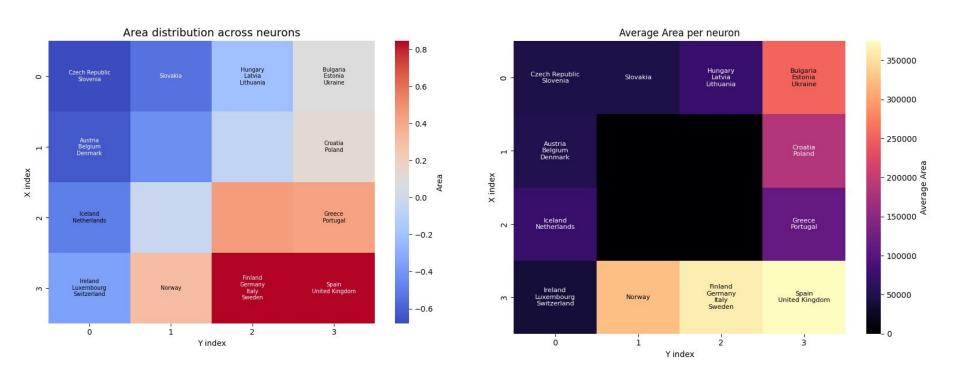
Parámetros:

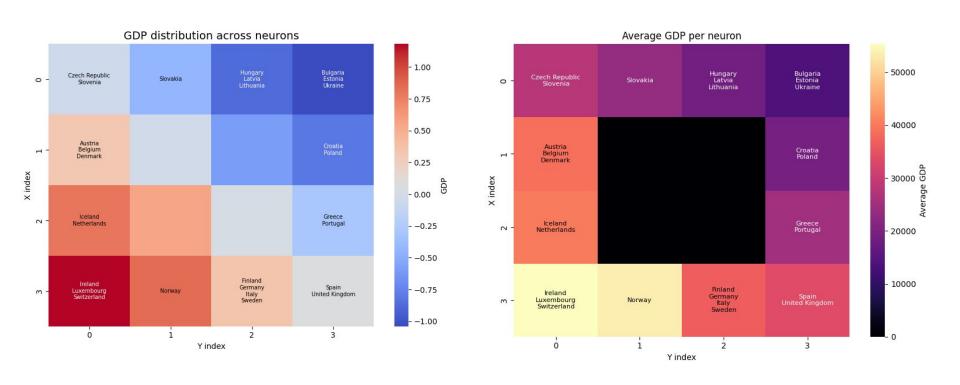
- Epochs factor: 350
- R0: 6
- R variable
- Distancia Euclídea
- K: 4

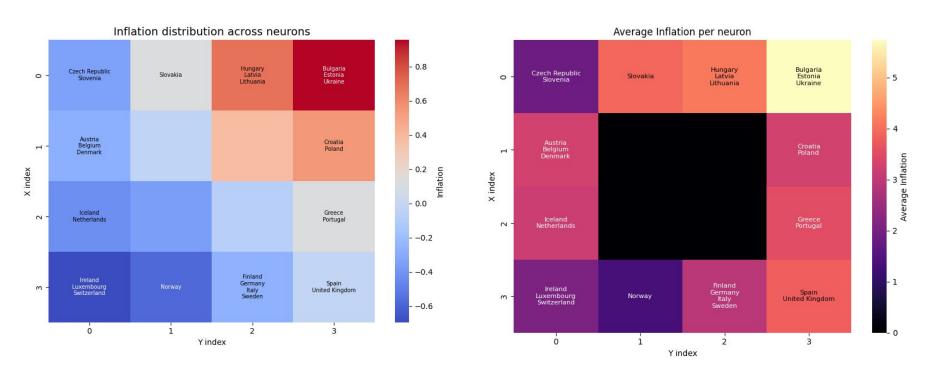


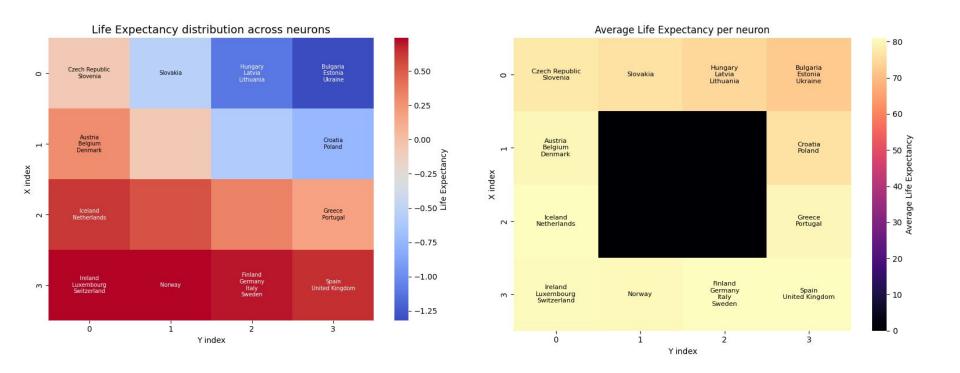
Average Euclidean distance between neurons

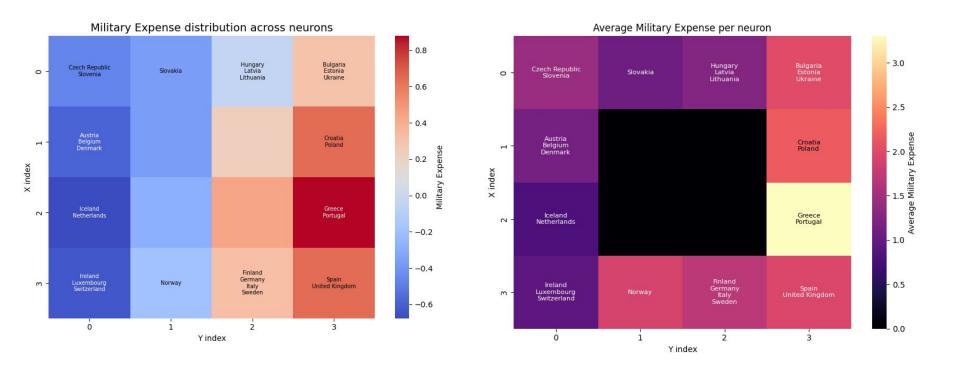


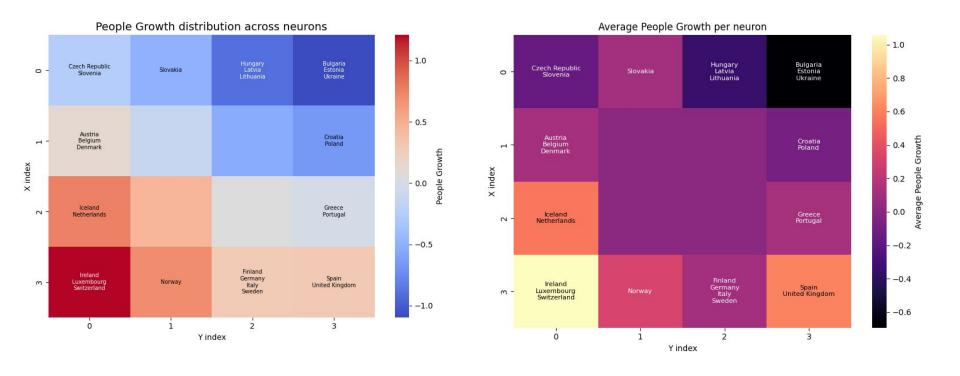


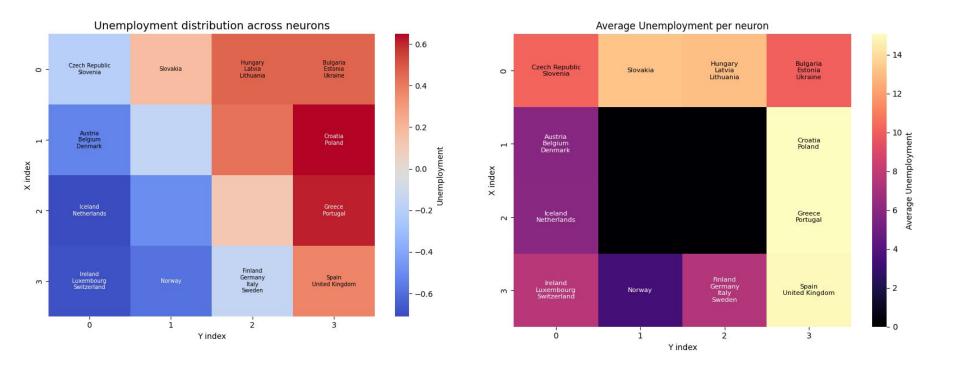




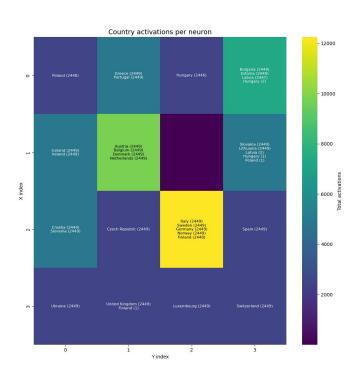


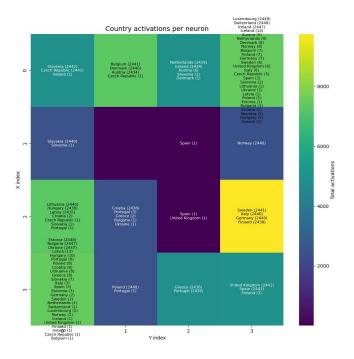






Elección de Radio Inicial: 1.5 vs 12

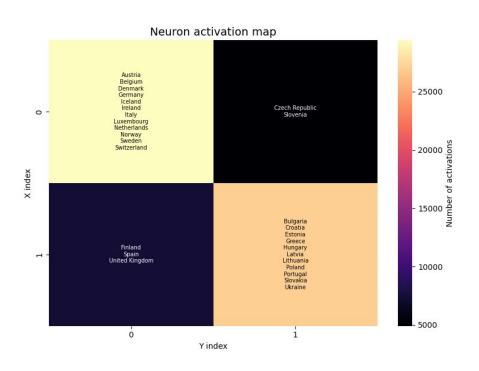


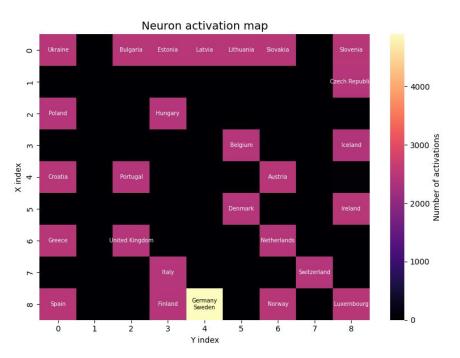


Características encontradas con RO chico:

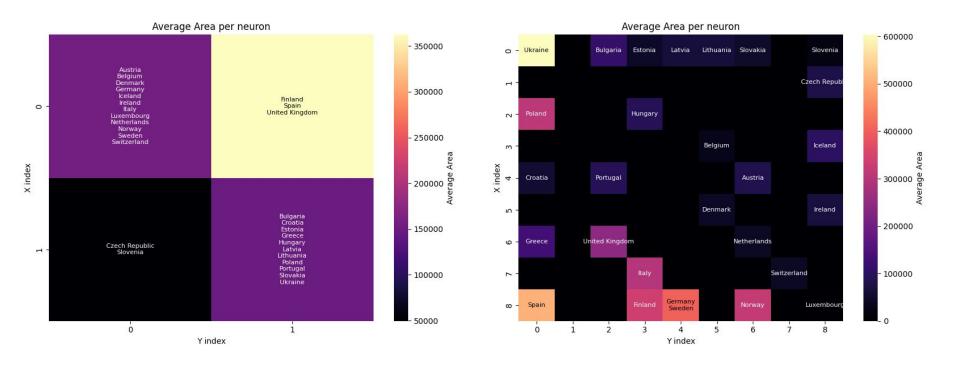
- Convergencia más rápida pero menos generalización
- Los pesos de las neuronas no se ajustan gradualmente
- Aprendizaje local

Elección de K: 2 vs 9





Elección de K: 2 vs 9 (Comparando Var.)



Con K chico:

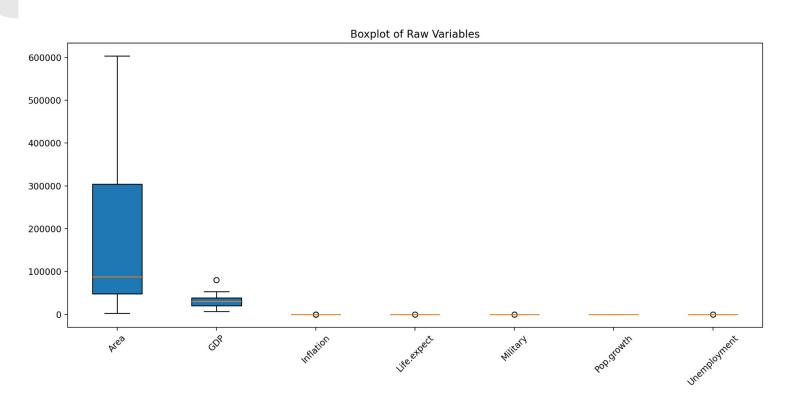
Existe una menor capacidad de discriminación y queda un mapa muy general

Con K grande:

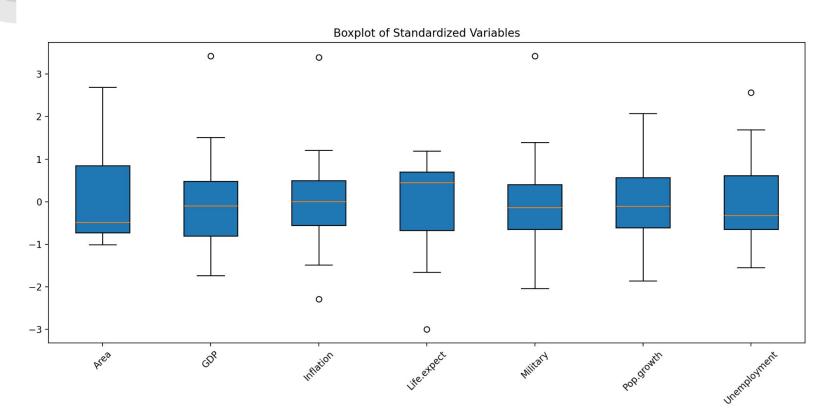
Hay más neuronas muertas y suele memorizar ejemplos individuales

Modelo de Oja

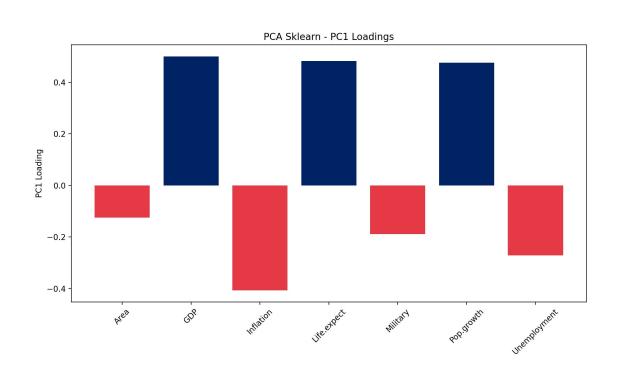
Variables sin estandarizar



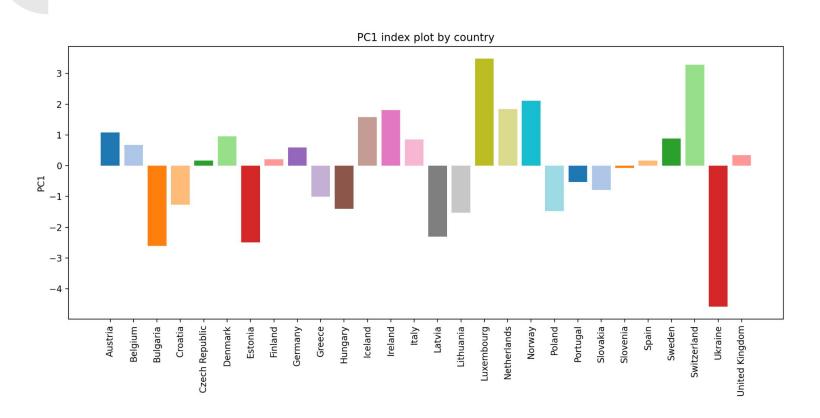
Variables estandarizadas



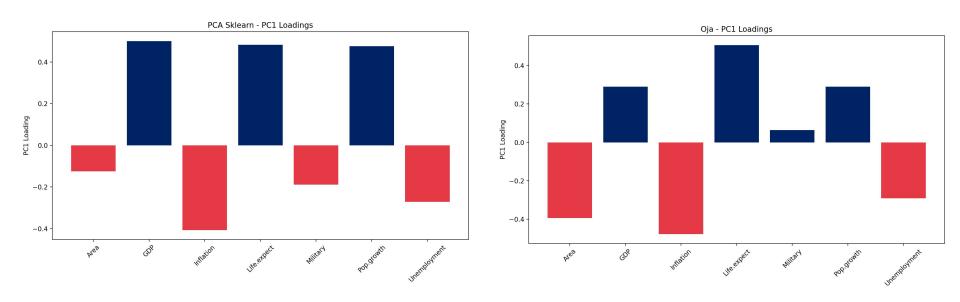
Interpretación de PC1 (SKlearn)



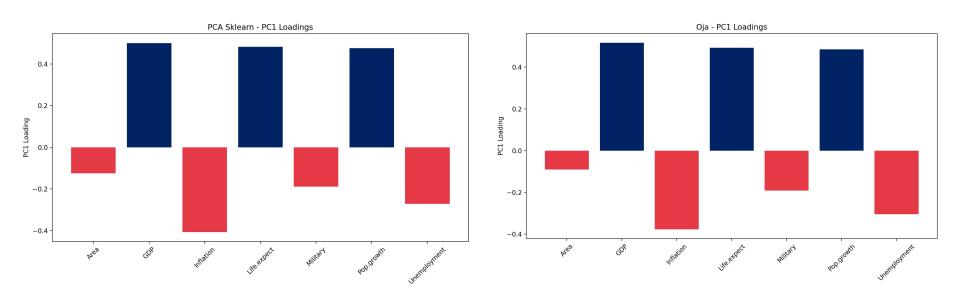
Índice



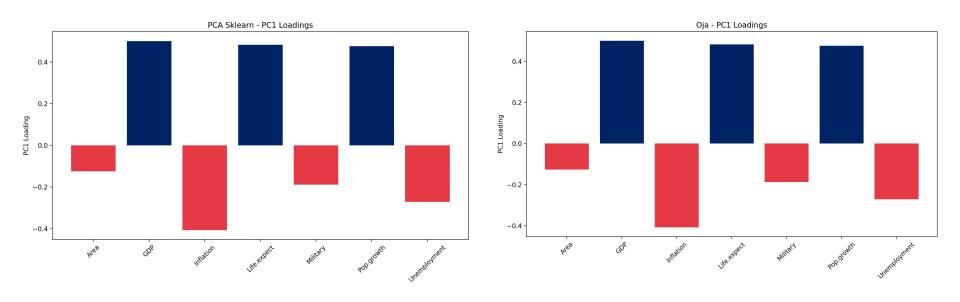
η =0.1 Epochs=100 E=0.22



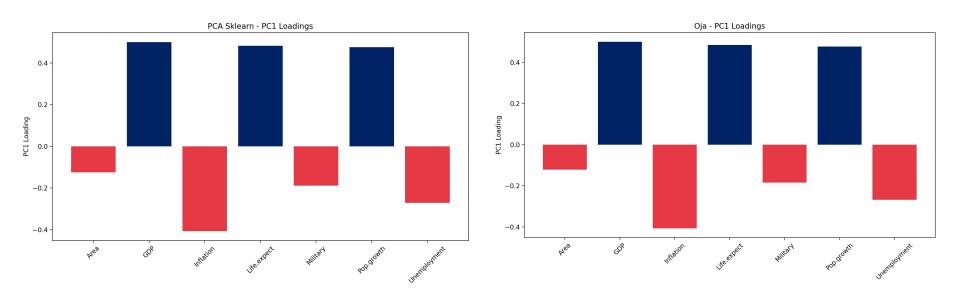










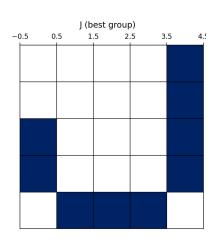


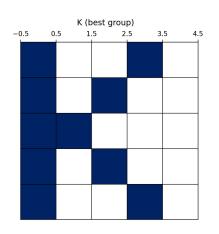
Conclusiones

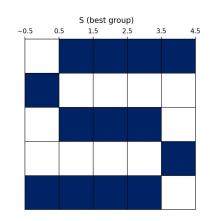
- El PC1 puede ser considerado una medida del bienestar social.
- Las variables que más impactan de forma positiva son el GDP, la expectativa de vida y la tasa de crecimiento poblacional.
- La variable negativa con mayor magnitud es la inflación, mientras que la variable con menor magnitud es el área.
- Oja aproxima el PC1 de mejor forma con valores menores de η .
- Con valores muy altos de η Oja puede no converger nunca.
- Con valores muy bajos de η tarda mucho en converger.

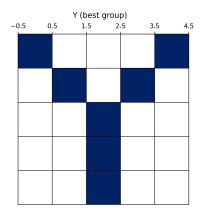
Red de Hopfield



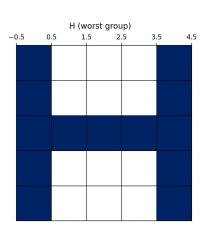


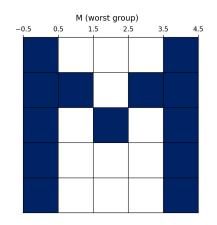


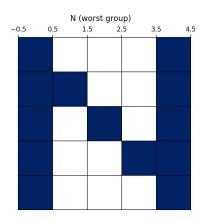


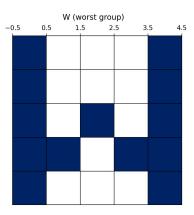






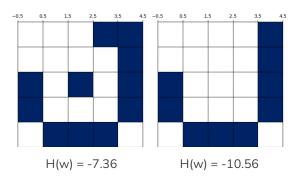


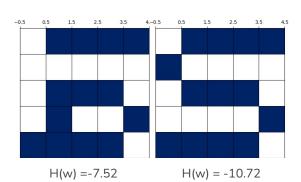


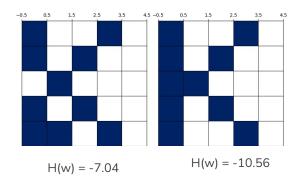


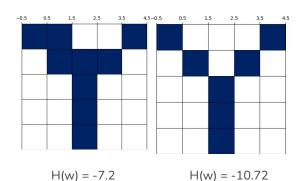
Análisis de convergencia según el ruido

 $\mu = 0.1$



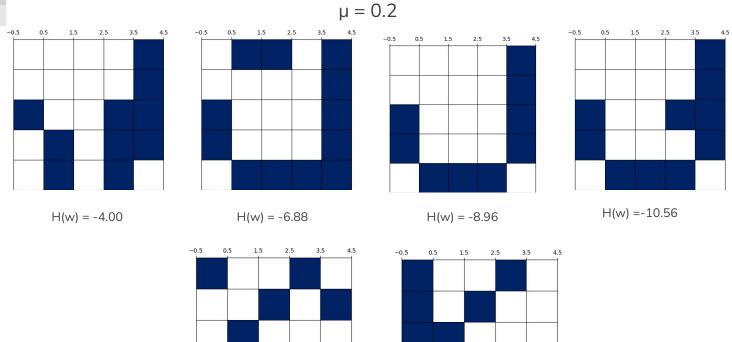






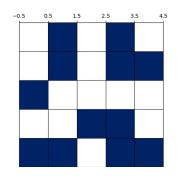
Análisis de convergencia según el ruido

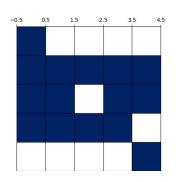


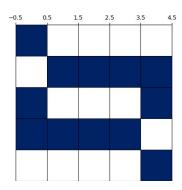


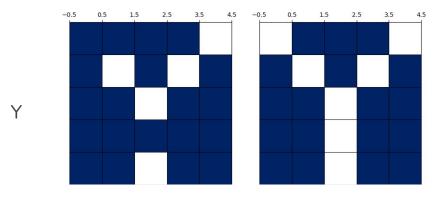
Análisis de convergencia según el ruido

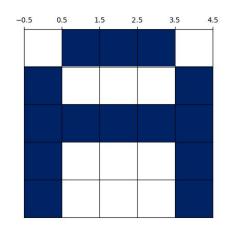
 $\mu = 0.6$



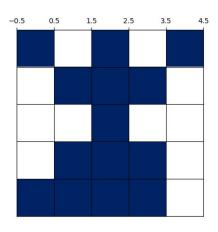




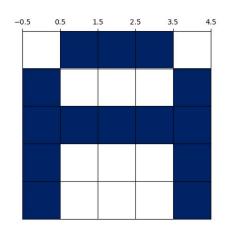




patrón almacenado

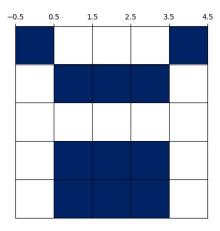


noise = 0.9



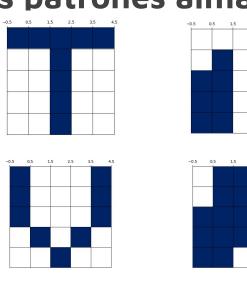
patrón almacenado

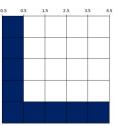
$$H(w) = -11.52$$

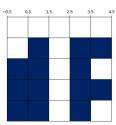


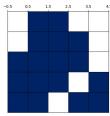
patrón espurio obtenido

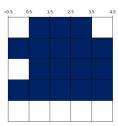
$$H(w) = -11.52$$

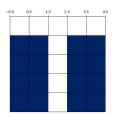


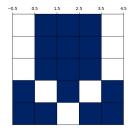


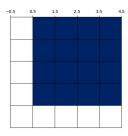












$$sign(h_i^{\nu}) = \xi_i^{\nu}$$

$$h_i^{\nu} = \sum_{j} w_{ij} \xi_j^{\nu} = \frac{1}{N} \sum_{j} \sum_{\mu} \xi_i^{\mu} \xi_j^{\mu} \xi_j^{\nu}$$

$$h_i^{\nu} = \frac{1}{N} \sum_{j} \sum_{\mu \neq \nu} \xi_i^{\mu} \xi_j^{\mu} \xi_j^{\nu} + \frac{1}{N} \sum_{j} \xi_i^{\nu} \xi_j^{\nu} \xi_j^{\nu} h_i^{\nu} = \frac{1}{N} \sum_{j} \sum_{\mu \neq \nu} \xi_i^{\mu} \xi_j^{\mu} \xi_j^{\nu} + \frac{1}{N} \xi_i^{\nu}$$

$$sign(h_i^{\nu}) = \xi_i^{\nu}$$

$$-\xi^{\nu} = (-\xi_1^{\nu}, -\xi_2^{\nu}, ..., -\xi_n^{\nu})$$

$$sign(h_i) = -\xi_i^{\nu}$$

$$h_i = \sum_j w_{ij}(-\xi_j^{\nu}) = \frac{1}{N} \sum_j \sum_{\mu} \xi_i^{\mu} \xi_j^{\mu}(-\xi_j^{\nu})$$

$$h_{i} = -\frac{1}{N} \sum_{j} \sum_{\mu} \xi_{i}^{\mu} \xi_{j}^{\mu} \xi_{j}^{\nu}$$

$$h_i = -\frac{1}{N} \sum_j \sum_{\mu} \xi_i^{\mu} \xi_j^{\mu} \xi_j^{\nu}$$

$$h_i = -\left(\frac{1}{N} \sum_{j} \sum_{\mu \neq \nu} \xi_i^{\mu} \xi_j^{\mu} \xi_j^{\nu} + \frac{1}{N} \sum_{j} \xi_i^{\nu} \xi_j^{\nu} \xi_j^{\nu}\right)$$

$$h_i = -(\frac{1}{N} \sum_{j} \sum_{\mu \neq \nu} \xi_i^{\mu} \xi_j^{\mu} \xi_j^{\nu} + \frac{1}{N} \xi_i^{\nu})$$

$$sign(h_i) = -\xi_i^{\nu}$$