

EdX and its Members use cookies and other tracking technologies for performance, analytics, and marketing purposes. By using this website, you accept this use. Learn more about these technologies in the [Privacy Policy](#).



[Course](#) > [Week 2](#) > [Project...](#) > [p1_sea...](#)

p1_search_q4_a*

Question 4 (3 points): A* search

Implement A* graph search in the empty function `aStarSearch` in `search.py`. A* takes a heuristic function as an argument. Heuristics take two arguments: a state in the search problem (the main argument), and the problem itself (for reference information). The `nullHeuristic` heuristic function in `search.py` is a trivial example.

You can test your A* implementation on the original problem of finding a path through a maze to a fixed position using the Manhattan distance heuristic (implemented already as `manhattanHeuristic` in `searchAgents.py`).

```
python pacman.py -l bigMaze -z .5 -p SearchAgent -a  
fn=astar,heuristic=manhattanHeuristic
```

You should see that A* finds the optimal solution slightly faster than uniform cost search (about 549 vs. 620 search nodes expanded in our implementation, but ties in priority may make your numbers differ slightly). What happens on `openMaze` for the various search strategies?

https:

188x_1%2Fv