

# ECON 4360: Empirical Finance

## Overview and Intro to GMM

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Empirics Lecture #01

# What are we doing today?

- Beginning the Empirical Half of the Course
- Introduction to GMM

# Some Empirical Questions

- Let's look at

$$\begin{aligned}1 &= E_t(m_{t+1}R_{t+1}) \\ m_{t+1} &= \beta \left( \frac{c_{t+1}}{c_t} \right)^{-\gamma}\end{aligned}$$

- What values for  $\beta$  and  $\gamma$  best satisfy our central asset pricing equation?
  - We can use GMM as a statistical criteria to pick these parameters.
- Is the CRRA model a good one for asset prices?
  - Can we reject a null hypothesis that the model is correct?

# Some Empirical Questions

- Now think about linear factor models...
- Recall our expected return-beta representation

$$E(R^i) = \gamma + \beta_{i,a}\lambda_a + \beta_{i,b}\lambda_b + \dots, i = 1 \dots N$$

- Are the pricing errors in linear factor models "large"?
- Which factors provide more accurate prices?

# Overview: Empirical Half of the Course

- The GMM Framework: Formal Statement of Theory and Simple Examples
- Data Issues: Stationarity
- GMM and Robust Standard Errors (HAC)
- Linear Factor Pricing Models
  - Applications to Pricing Stock Market Portfolios, Term Structure of Interest Rates
- Cross-Sectional Factor Pricing Models
  - Linking Stock Returns to Macro Fundamentals
- Estimating and Testing Explicit Factor Pricing Models
  - E.g., CRRA Utility Functions
- H-J Bounds as Tests of Asset Pricing Models
  - 'Exotic' Utility Functions

# Overview of Empirical Framework: GMM

- GMM is a 'moment' based estimator (Partial Information)
  - The alternative is Maximum Likelihood (Full Information)
- The advantage of GMM is that it makes few assumptions about the data
  - The data must be covariance stationary
  - But non-normal distributions, persistence, heteroskedasticity, skewness do not pose problems
- Classic regression theory makes many assumptions about regression residuals. (What are they?)
  - GMM allows us to handle important deviations from these assumptions

# Basic Idea of GMM

- Our central asset pricing equation predicts that

$$E(p_t) = E[m_{t+1}(\text{data}_{t+1}, \text{parameters}) x_{t+1}]$$

- How should we check this prediction?
  - Looks at sample averages:

$$\frac{1}{T} \sum_{t=1}^T p_t \text{ and } \frac{1}{T} \sum_{t=1}^T [m_{t+1}(\text{data}_{t+1}, \text{parameters}) x_{t+1}]$$

- We can then evaluate how well our model performs by looking at how close these sample averages are to each other
  - This is equivalent to examining how large "pricing errors" are

# Basic Idea of GMM

- Say we want to evaluate the consumption-based model assuming CRRA utility.
- Before evaluating the model, we have to first pick the parameters  $\beta$  and  $\gamma$ .

$$m_{t+1} = \beta \left( \frac{c_{t+1}}{c_t} \right)^{-\gamma}$$

- But which parameters should we choose for our model?
  - If we think we have a good model, we want to pick parameters that "give it the best chance". So how do we do this?
- We can use GMM to give us estimates of the parameters  $\beta$  and  $\gamma$  that make the sample averages

$$\frac{1}{T} \sum_{t=1}^T p_t \text{ and } \frac{1}{T} \sum_{t=1}^T [m_{t+1} (\text{data}_{t+1}, \text{parameters}) x_{t+1}]$$

as close to each other as possible.

- Then we can use those parameters to test the model.



# GMM in Explicit Discount Factor Models

- First, we're going to talk about how to estimate the unknown parameters of the model.
- Let's continue our use of the consumption-based model to provide some content to the theory of GMM we're going to build up...
  - We have  $E(p_t) = E[m_{t+1}(\text{data}_{t+1}, \text{parameters}) x_{t+1}]$  with  $m_{t+1} = \beta \left( \frac{c_{t+1}}{c_t} \right)^{-\gamma}$ .
- The discount factor depends on some unknown parameters as well as the data, so we write  $m_{t+1}(b)$ , where

$$b := [\beta \quad \gamma]'$$

- Now,  $b$  is just a vector of parameters to be estimated.
  - And  $x$  and  $p$  are also typically vectors.

# Building GMM Estimates

- Now, we can write

$$E(p_t) = E[m_{t+1}(b) x_{t+1}]$$

in another form

$$E[m_{t+1}(b) x_{t+1} - p_t] = 0.$$

- Equations written in the form  $E(\cdot) = 0$  are easy to work with. Equations like this last equation are the "moment conditions" that we are going to work with.
- This equation should hold in expectation if our model is a good one, so we can think that we might want to minimize the "errors" of this model.
- The errors - from using particular values for  $b$  - can be defined as

$$u_{t+1}(b) = m_{t+1}(b) x_{t+1} - p_t$$

# Building GMM Estimates: First-Stage Estimates

- So a first-stage estimate of  $b$  solves

$$\hat{b}_1 = \arg \min_b g_T(b)' W g_T(b)$$

for some arbitrary matrix  $W$ . (E.g.,  $W = I$ ).

- (What is  $g_T(b)$ ?)
- These estimates  $\hat{b}_1$  are:
  - Consistent
  - and Asymptotically Normal.
- (We could just stop here. But we won't...)

# Building GMM Estimates: The Weighting Matrix

- Let's think about our weighting matrix,  $W = I...$
- What does a weighting matrix do?
  - It directs GMM to emphasize some moments (or linear combinations of moments) at the expense of other moments.
- What does it mean if you start with  $W = I$ ?

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- What does it mean if you start with  $W = I$ ?
  - GMM is trying to price all assets equally well. When would we want to do this? ...

# Building GMM Estimates: The Weighting Matrix

- Think about a sample mean  $g_T = E_T (m_t R_t - 1)$ . When would you expect it to be an accurate measurement of the population mean  $E (mR - 1)$ ?

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- Idea: We want to pay more attention to things we think might be priced more accurately.
  - This means downweighting things with higher variance.

# Building GMM Estimates: The Weighting Matrix

- Think about a weighting matrix that might do this.
  - If we were to replace the 1's in the weighting matrix  $W = I$  with  $1 / (\text{var} [E_T (m_t R_t - 1)])$ , that would do it.
  - Think about what would happen if the  $u'_t$ 's are uncorrelated over time  $E_t (u_t u'_{t-j}) = 0$ , then

$$\text{var} \left( \frac{1}{T} \sum_{t=1}^T u_{t+1} \right) = \frac{1}{T} E (u u') = \frac{\text{var} (u)}{T}$$

- This is just a formula for the variance of a sample mean!
- But we actually know more...
  - We know that asset returns are correlated, so if we use a form of the covariance matrix of  $[E_T (m_t R_t - 1)]$ , it will also pay more attention to linear combinations of moments about which the data set has the most information.

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    - What that means is that the covariances can depend on *the interval*  $j$ , but not on *where you are at*  $t$ , e.g.,  $E(u_1 u_2') = E(u_t u_{t+1}')$

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- Note that since  $\text{cov}(Y_t, Y_{t-j}) = E[(Y_t - EY_t)(Y_{t-j} - EY_{t-j})]$ , if the time-series has mean zero, this simplifies to  $\text{cov}(Y_t, Y_{t-j}) = E(Y_t, Y_{t-j})$

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- Now, at  $T \rightarrow \infty$ ,  $(T-j)/T \rightarrow 1$ , so

$$\text{var}(g_T) \rightarrow \frac{1}{T}\sum_{j=-\infty}^{\infty} E(u_t u'_{t-j}) = \frac{1}{T}S$$

where

$$S = \sum_{j=-\infty}^{\infty} E(u_t u'_{t-j})$$

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- Hansen (1982) shows that  $W = S^{-1}$  is the statistically optimal weighting matrix. What does that mean?
  - It produces estimates with the lowest asymptotic variance.

# Building GMM Estimates: Second-Stage Estimates

- Now, from our first-stage estimate of  $b$  from

$$\hat{b}_1 = \arg \min_b g_T(b)' W g_T(b)$$

- We can use  $\hat{b}_1$  to form an estimate of  $\hat{S}$

$$\hat{S} = \Sigma_{j=-\infty}^{\infty} E \left[ u_t(\hat{b}_1) u_{t-j}(\hat{b}_1)' \right]$$

- Next, we can form second-stage estimates according to

$$\hat{b}_2 = \arg \min_b g_T(b)' \hat{S}^{-1} g_T(b)$$



- Estimates for  $\hat{b}_2$  are
  - Consistent
  - Asymptotically Normal
  - and, now, also Asymptotically Efficient
    - Where efficient means that it has the smallest variance-covariance matrix among all estimators that set linear combinations of  $g_T(b)$  equal to zero or all choices of weighting matrices  $W$ .

# First- and Second-Stage Estimates

- The estimates we have done should remind you of standard linear regression models.
- The first-stage estimates are *like* OLS.
  - For OLS, if the errors are not i.i.d., OLS estimates are consistent, but not efficient.
- To get efficient estimates, we can use the OLS estimates to construct a series of residuals to estimate a variance-covariance matrix of the residuals to then use for GLS.
  - GLS is also consistent, but more efficient (meaning the sampling variation in the estimated parameters is lower).

# Does the Weighting Matrix Matter?

- It Depends.

# Two Cases of GMM

- Case 1: We have the same number of moment conditions as parameters.
  - The parameters are exactly identified.
  - We can set all of the moment conditions equal to zero (exactly).
  - The weighting matrix:
    - is irrelevant for solving the minimization problem.
    - is needed for inference
    - can be constructed after solving for the parameters.

# Two Cases of GMM

- Case 2: We have more moment conditions than parameters.
  - The parameters are over-identified.
  - We cannot set all of the moment conditions equal to zero.
  - The weighting matrix is key to solving the minimization problem.
  - The weighting matrix is needed for estimating the parameters, yet it depends on the parameters
  - So we solve the minimization problem numerically on a computer:
    - Start with any weighting matrix, e.g.,  $W = I$  to find  $\hat{b}_1$
    - Use  $\hat{b}_1$  to construct  $\hat{S}_1$
    - Find  $\hat{b}_2$  using  $\hat{S}_1$
    - Continue until  $\hat{b}_{i+1} \approx \hat{b}_i$

# GMM Estimator: Formal Statement

- Let  $\bar{Y}_T$  be a matrix of data with  $T$  time-series observations, and let  $b$  be a vector of parameters to be estimated.
- Let  $f(Y_t, b)$  denote the moment condition that relates the data and parameters.
  - And let  $g_T(\bar{Y}_T, b) = (1/T) \sum_{t=1}^{\infty} f(Y_t, b)$  denote the sample average of  $f(Y_t, b)$
- The GMM estimate for  $b$  solves the following minimization problem

$$\hat{b}_{GMM} = \arg \min_b g_T(\bar{Y}_T, b)' \hat{S}^{-1} g_T(\bar{Y}_T, b)$$

- where  $\hat{S}$  is a weighting matrix defined as

$$\hat{S} = \sum_{j=-\infty}^{\infty} E \left[ f(Y_{t,b}) f(Y_{t-j}, b)' \right]$$

- And  $\hat{b}_{GMM} \overset{a}{\sim} N \left[ b, \frac{1}{T} \left( d \hat{S}^{-1} d' \right)^{-1} \right]$ , where  $d$  is just the derivative of the moment condition w.r.t.  $b$ ,  $d = \frac{\partial g(\bar{Y}_T, b)}{\partial b}$

# The Standard Errors

- What is  $d$ ?
  - Recall that we're trying to find estimates of  $b$ , and we know that the GMM estimates are distributed asymptotically normal.
- Recall, the Delta Method:
  - It's easy to see in the univariate case. Basically, if we have

$$\sqrt{n} [X_n - \theta] \rightarrow N(0, \sigma^2)$$

then

$$\sqrt{n} [h(X_n) - h(\theta)] \rightarrow N(0, [h'(\theta)]^2 \sigma^2)$$

- So think of  $\text{var}(\hat{b}_2) = \frac{1}{T} (d\hat{S}^{-1}d')^{-1}$  as just an application of the delta method, where

$$\begin{aligned} d &= \frac{\partial g(\bar{Y}_T, b)}{\partial b} \\ &= E_T \left[ \frac{\partial}{\partial b} (m_{t+1}(b) x_{t+1} - p_t) \right] \Big|_{b=\hat{b}} \end{aligned}$$

# Testing

- We now have all the pieces we need to test if a parameter or group of parameters is equal to zero.
- Since we have the asymptotic distribution,

$$\hat{b}_{GMM} \overset{a}{\sim} N \left[ b, \frac{1}{T} \left( d\hat{S}^{-1}d' \right)^{-1} \right]$$

- We just use, for an individual parameter,

$$\frac{\hat{b}_i}{\sqrt{\text{var}(\hat{b})_{ii}}} \sim N(0, 1)$$

or, for a group,

$$\hat{b}_j \left[ \text{var}(\hat{b})_{jj} \right]^{-1} \hat{b}_j \sim \chi^2 \left( \dim(\hat{b}_j) \right)$$

where  $b_j$  is a subvector of  $b$ , and  $\text{var}(b)_{jj}$  is a submatrix of the variance matrix  $\frac{1}{T} \left( d\hat{S}^{-1}d' \right)^{-1}$



# What Else Can We Do? The J Test

- Now, we've used GMM to estimate parameters to make the model fit the best it possibly can. But how well does the *model* fit?
  - We're going to now look at the pricing errors and see if they are "large"
- $J_T$  Test: If the model is true, how often should we see a weighted sum of squared pricing errors as big as what we got?
  - If the answer is "not too often", then the model is rejected.
- The  $J_T$  test is also called a *test of overidentifying restrictions*

$$TJ_T = T \left[ g_T \left( \hat{b}_{GMM} \right)' S^{-1} g_T \left( \hat{b}_{GMM} \right) \right] \sim \chi^2 (\# \text{ mom's} - \# \text{ par's})$$

and recall that  $S$  is the variance-covariance matrix for  $g_T$ , where this statistic is the minimized pricing errors divided by their variance-covariance matrix.

# Interpreting GMM

- So what have we done?
- We've constructed  $g_T(b)$  and interpreted it as a pricing error.
- We've used GMM to pick parameters that minimize a weighted sum of squared pricing errors.
  - First and second stage estimates of the parameters are like OLS and GLS regressions - the second stage estimates pick the linear combinations of pricing errors that are 'best measured', interpreted as having the smallest variation in the sample.
- We've constructed the asymptotic distribution of the parameters through an application of the delta method for use in testing parameters.
- We've developed the  $J_T$  test as a test of the overall model.

# End of Today's Lecture.

- That's all for today. Today's material corresponds roughly to 10 in Cochrane (2005).