## 2PEM-100A

## PRACTICE 5\_1

## **Energy Consumption Modeling**

#### More information:

https://2pem100a.blogspot.com/

#### More examples:

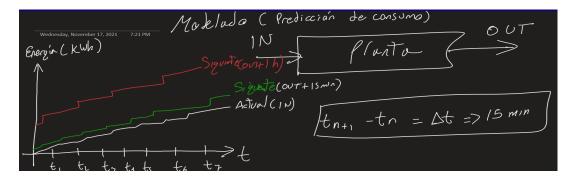
- https://github.com/vasanza/Matlab Code/tree/Electrical-Systems-Simulation
- https://github.com/avbazurt/Simulacion\_Sistemas\_Electricos

#### Dataset:

http://ieee-dataport.org/8630

#### Technical information

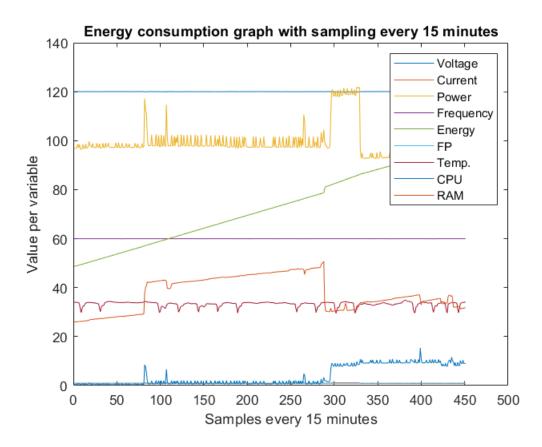
• Sampling frequency: 4Hz (250mSeg)



1- Loading a .mat file with 1sample sampling rate / 15min = 1sample / 900seg

Data (451x9), donde 451x15min=6765min/60min=112.75horas/24=4.69dias

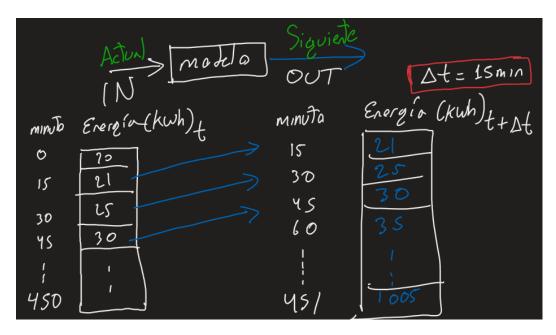
```
clear;%borra el worskpace
clc;%borra el comand windiw
path=fullfile('./datamean.mat');
data=load(path);
data=struct2cell(data);
data=data{1,1};%table
plot(data);%datos originales
title('Energy consumption graph with sampling every 15 minutes');
legend('Voltage','Current','Power','Frequency','Energy','FP','Temp.','CPU','RAM');
xlabel('Samples every 15 minutes');
ylabel('Value per variable');
```



### 2- Separate variables

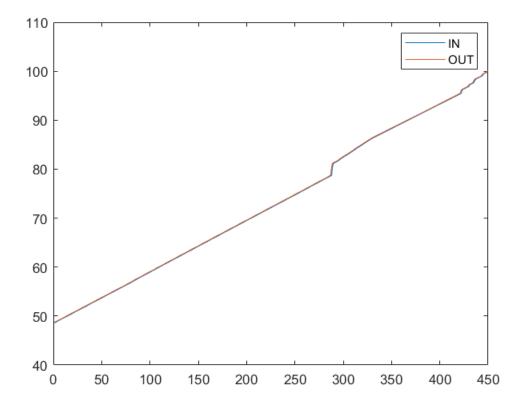
```
Time=(0:1:length(data)-1)'; %Time Vector
Voltaje=[Time data(:,1)];
Corriente=[Time data(:,2)];
Potencia=[Time data(:,3)];
Frecuencia=[Time data(:,4)];
Energia=[Time data(:,5)];
FP=[Time data(:,6)];
Temp=[Time data(:,7)];
CPU=[Time data(:,8)];
RAM=[Time data(:,9)];
```

Example 1: Generate the input (IN) and output (OUT) data of the model



```
% Fila 1 -> Tiempo, Fila 2 -> Variable
IN=Energia(1:length(Energia)-1,2);%Energía actual (t)
OUT=Energia(2:length(Energia),2);%Energia siguiente (f+dT)
Datos=[IN OUT];

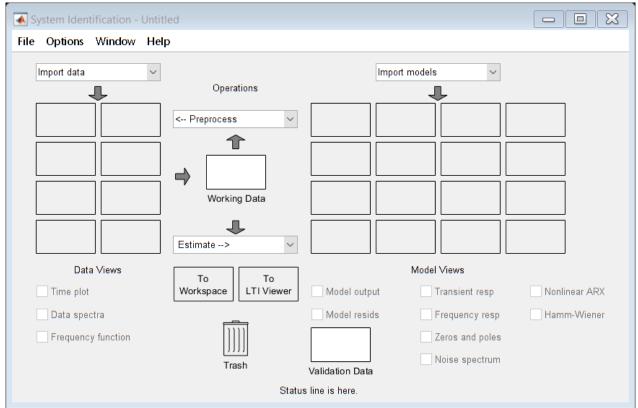
plot(IN);
hold on
plot(OUT);
legend('IN','OUT');
```



## **Ejemple 2: Identificacion System Toolbo**

#### ident

Warning: The "ident" command is obsolete and may be removed in a future release of MATLAB. Use the "systemIdentification" command instead.



# **Ejemple 3: Energy consumption modeling**

```
%% Transfer Function obtained (Method 3)
G=tf(d2c(arxqs));%<---Best FIT Model Modelo con mejor FIT</pre>
num=cell2mat(G.numerator)
num = 1 \times 5
   1.2970
             0.0060
                       0.0000
                                 0.0000
                                           0.0000
den=cell2mat(G.denominator)
den = 1 \times 5
    1.0000
             0.0039
                       0.0000
                                 0.0000
                                           0.0000
FTmotor=tf(num,den)
FTmotor =
 1.297 s^4 + 0.006039 s^3 + 1.509e-05 s^2 + 2.036e-08 s + 1.404e-11
    s^4 + 0.00394 s^3 + 1.052e-05 s^2 + 1.604e-08 s + 1.403e-11
```

```
Time=(0:1:length(IN)-1)'; %Vector de tiempo
y = lsim(G,IN,Time); % system response
figure
plot(y);
hold on;
plot(IN);
plot(OUT);
legend('Estimated Next Value', 'Actual', 'Actual Next Value');
```

