Section 1: Introduction to probability

ARE 210

August 29, 2017

- Introduction (10 min)
- A few tips (10 min)
- Practice questions (30 min)

The section notes are available on the section Github at github.com/johnloeser/are210 in the "section1" folder.

1 Definitions

- A probability space is a triple (Ω, \mathbf{F}, P)
 - The sample space Ω is a set
 - * $A \in \Omega$ is an **event**
 - $\mathbf{F} \subseteq 2^{\Omega}$ is a σ -algebra
 - * A set **F** is a σ -algebra if
 - 1. $\emptyset \in \mathbf{F}$
 - 2. $A \in \mathbf{F} \Rightarrow A^c \in \mathbf{F}$
 - 3. $A_1, A_2, \ldots \in \mathbf{F} \Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathbf{F}$
 - The **probability measure** $P : \mathbf{F} \to [0, 1]$ such that
 - 1. $P(\Omega) = 1$
 - 2. A_1, A_2, \ldots pairwise disjoint $\Rightarrow P(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$
- A measurable space is a 2-tuple (Ω, \mathbf{F}) , where Ω is a set and \mathbf{F} is a σ -algebra over Ω
 - Common measurable spaces are $(\Omega, 2^{\Omega})$ and $(\mathbf{R}^k, \mathbf{B}^k)$ (where **B** is the **Borel** σ -algebra, the smallest σ -algebra containing all open sets in **R**)
- A partition of Ω is a set of disjoint sets whose union is Ω
- The probability of A conditional on B is $P(A|B) = \frac{P(A \cap B)}{P(B)}$
- Bayes rule is $P(A|B) = \frac{P(B|A)P(A)}{P(B)}$
- $\{A_i\}_{i=1}^N$ are mutually independent if $\forall I \subseteq \{1,\ldots,N\}, P(\cap_{i\in I}A_i) = \prod_{i\in I}P(A_i)$
- A random variable $X:(\Sigma, \mathbf{F}) \to (E, \mathbf{E})$, where X is a measurable function, and (Σ, \mathbf{F}) and (E, \mathbf{E}) are measurable spaces
 - Typically, $(E, \mathbf{E}) = (\mathbf{R}^k, \mathbf{B}^k)$

2 Some useful tips for the homework

- Set logic
 - $-a \in A \cup B \Leftrightarrow a \in A \lor a \in B$
 - $-a \in A \cap B \Leftrightarrow a \in A \land a \in B$
 - $-a \in A^c \Leftrightarrow a \notin A$
 - $-A = B \Leftrightarrow (a \in A \Rightarrow a \in B) \land (a \in B \Rightarrow a \in A)$
- Let C be a set of sets, and $\sigma(C)$ be the smallest σ -algebra over Ω containing C. It's useful to conceptualize $\sigma(C)$ as countable unions of the smallest partition of Ω which can be used to construct any element of C by countable union.
- $\bullet \ \ a \in X^{-1}(A) \Leftrightarrow X(a) \in A$

Also worth noting - Lecture 1 covered sufficient material to answer questions 1 through 5, while Lecture 2 covered sufficient material to answer questions 6 through 8. If any questions seem difficult to you, I recommend coming to office hours to discuss why it seemed tough. If the questions seemed easy, it might be useful to wait to complete the problem set after we've covered all the relevant material as a refresher.

3 Some example questions

- 1) Conditional independence: Define A_1 and A_2 to be independent conditional on B if $P(A_1 \cap A_2|B) = P(A_1|B)P(A_2|B)$. Show that independence conditional on each event in a partition of the sample space implies independence.
- 2) Practice constructing counterexamples: Recall our formula for Bayesian updating, $P(A|B) = \frac{P(B|A)P(A)}{P(B)}$. Suppose we observe the events B_1, B_2, \ldots, B_N . Consider calculating $P(A|\cap_{i=1}^N B_i)$ via batch Bayesian updating and sequential Bayesian updating. Define the batch Bayesian updating approach by

$$P(A|\cap_{i=1}^{N} B_i) = \frac{P(\cap_{i=1}^{N} B_i|A)P(A)}{P(\cap_{i=1}^{N} B_i)}$$

Define the sequential Bayesian updating approach recursively by

$$P(A|B_1) = \frac{P(B_1|A)P(A)}{P(B_1)}$$

$$P(A|\cap_{i=1}^K B_i) = \frac{P(B_K|A)P(A|\cap_{i=1}^{K-1} B_i)}{P(B_K)}$$

- a) Propose two sufficient conditions for the two approaches to yield the same answer. Which approach do you think is "correct"?
- b) For N=2, construct an example where the two approaches yield different answers, but the first condition is violated.
- c) For N=2, construct an example where the two approaches yield different answers, but the second condition is violated.