Lecture 13

 $= \frac{1}{4} \frac{1}{4} \frac{x^2 + x_0^2}{x^2 + x_0^2} + \frac{1}{2} \frac{1}{x^2 + x_0^2} + \frac{1}{2}$

 $O=(x_1-x_1+1)^2=0$ X270 × 100 Y X AXX =0 >

: XTAxx=0 iff x=0 => Ag is positive definit

$$e = x - \vec{x}$$
: error

However, small residual r does NOT always imply that error e is also small.

Det a vector norm 11 x11 has the following properties:

2. || dx || = | d| . ||x|| , where d is a scalar 1. 11×11>0 and 11×11=0 : ff x=0

3. ||X+y|| = ||X||+||y|| : triangle inequality

 E_X det $x = (x_1, ..., x_n)^T$

 $\|x\|_{co} = \max_{i=1}^{n} |x_{i}|, i=1,...,n$ $\|x\|_{2} = \left(\sum_{i=1}^{n} |x_{i}|^{2}\right)^{1/2}$

1 X 1 X 1 X:

for norm or as norm

from or 2 norm

f, norm or I norm

$$\|x\|_{\infty} = 0 \iff \max_{i} |x_{i}| = 0 \iff |x_{i}| = 0 \iff x_{i} = 0 \iff x = 0$$

$$\|x\|_{\infty} = 0 \iff \max_{i} |x_{i}| = 0 \iff x_{i} = 0$$

$$\|x\|_{\infty} = 0$$
 (=) max $|x_i| = 0$ (=) $|x_i| = 0$ (=) $x_i = 0$ (=) $|x_i| =$

$$Q = x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \qquad ||x_1|| \frac{\partial u}{\partial x_1} ||x_1 - a x_2|| \quad \text{Can this } ||x_1|| \text{ & a wrn.} \\ x = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \Rightarrow |x_1 - 2x_2| = |2 - 2 \cdot 1| = 0 \text{ but } x \neq 0 \\ \Rightarrow ||x_1|| = |x_1 - 2x_2| \text{ does not } \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_2} = \frac{\partial u}{\partial x_1} = \frac{\partial u}{\partial x_2} = \frac$$

$$x = \begin{pmatrix} 1 \\ 1 \end{pmatrix} : exact tolution$$

$$6 = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$

$$r_1 = 6 - 4\tilde{x}_1 = (-0.02)$$

10.0-

0-x-x-10

4.01

$$r_{2} = 6 - 4 \times 2 = \begin{pmatrix} -0.02 \\ 0.02 \end{pmatrix}$$

11×11×1-1, 11811×1-2

= | 0, = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | × = | ×

6.02

0.0

11.2/100

0.02

C

620 Q what is the relation between relative error IIXII relative residual IIII. University of daho

Det a matrix norm 11 A11 has the following properties:

2. ILAA! - IAI. IIA!!, where & is a scalar 1. 11A11>0 and 11A11=0 144 A=0

3. ||A+B|| <||A|| + ||B|| 4. ||A·B|| <||A|| .||B||

Given a vector norm 11x11, the tubordinate (or induced) matrix norm is defined by

The Subordinate matrix horm has an additional property: 5. 11 AXII 4 11 AII. 11 XII LA all vactors X
$$||A||_{\infty} = \max_{x \neq 0} \frac{||Ax||_{\infty}}{||x||_{\infty}} = 6$$