$$A \times_{A} = \begin{pmatrix} 4 \\ 4 \end{pmatrix}$$

N

||X 4|||

$$A \times_2 = \begin{pmatrix} 5 \\ 5 \end{pmatrix}$$

$$\begin{pmatrix} 2 \\ 4 \end{pmatrix}$$

N

$$||A||_{\infty} = \max_{i} \sum_{j=1}^{n} |a_{ij}|$$
 (1)

9

11 Ax1(8 1141(20 = 1

 $|(Ax)| = |\sum_{j=1}^{n} a_{ij} \cdot x_{j}| \leq \sum_{j=1}^{n} |a_{ij}| \cdot |x_{j}| \leq ||x||_{\omega} \cdot \sum_{j=1}^{n} |a_{ij}|$ 240 X40

Stept

 $x \rightarrow (Ax)$ ;  $| \leq ||x||_{\infty} \cdot max \geq |a_{ij}|$ ,  $||Ax||_{\infty} \leq ||x||_{\infty} \cdot max \geq |a_{ij}|$ in component

6 max 2 lajil M AXIL <u>8</u> ×

11411 5 max 2 19ji

Aside

[2] 2 |-5|

Step 2  
Suppose max 
$$\sum_{i=1}^{n} |a_{ij}| = \sum_{j=1}^{n} |a_{pj}|$$
  
Suppose  $y = (y_{11...}, y_{n})^{T}$  with  $y_{ij} = 1$ , it  $a_{pj} < 0$ 

$$\|A\|_{\infty} = \|Ax\|_{\infty} = \|Ay\|_{\infty} = \|Ay\|_{\infty} > \|(Ay)\|_{\infty} > \|Ay\|_{\infty} > \|Ay\|_{\infty}$$

Œ

Note 
$$\frac{Nofp}{4}$$
.  $\|x\|_{L^{2}} = (\frac{n}{2} |x|^{2})^{1/2} = (x^{2} \cdot x)^{1/2}$ 

& ATA Y

$$\|A\|_{t} = \max_{x \neq 0} \frac{1}{\|x\|_{t}} = \max_{i \geq 1} \frac{1}{2} |a_{ij}|$$
 ("max column orn")

Let A le invertible, 
$$Ax=6$$
  
 $x: exact solution;  $\widetilde{x}: approximation$   
 $e=x-\widetilde{x}: error; r=6-A\widetilde{x}: rebidual$$ 

The z

||e|| 
$$K(A) = ||X||$$
 || ||x|| || ||x|| || ||x|| ||x|

relative to norm 11.11, ie. relative error 11.61 is bounded by K(A) times relative residual.

Recall (1.01 0.99)
$$A = \begin{pmatrix} 1.01 & 0.99 \\ 0.99 & 1.01 \end{pmatrix}$$

11 A 11 A 11 A

$$A^{-1} = \begin{pmatrix} 25.26 & -24.75 \\ -24.75 & 25.26 \end{pmatrix}$$

$$\frac{\lambda^{0+x}}{\lambda} + \frac{\lambda^{x-x}}{\lambda^{x-x}} = \frac{\lambda^$$

X

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$$2. \ A \times = 6$$

$$2. \ A \times = 6$$

$$3. \ A \times = 6$$

$$4 \times = 6$$

$$4 \times = 6$$

2. 
$$Ax=6$$

$$||x-\tilde{x}|| \leq k(A) \cdot \frac{||A-\tilde{A}||}{||X||}$$

$$||\tilde{A}\tilde{X}|| \leq k(A) \cdot \frac{||A-\tilde{A}||}{||A||}$$
Proof of A follows from thin, proof of  $2 - kw$  (?)

Recall

$$K_{\infty}(E_1A) \sim \frac{1}{\varepsilon^2} \Rightarrow \tilde{\chi} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$E_1P_1A = \begin{pmatrix} 1 & 1 \\ 0 & 1-E \end{pmatrix}$$

$$K_{DG}($$

$$K_{L}(E_1P_1A) \sim 4 \Rightarrow \tilde{X}=\begin{pmatrix} 1 \\ 1 \end{pmatrix}$$
because  $K(A^{(E)}) >> KC$ 

Gaussian elimination is unstable because K(A(K))>> K(A). Perturbations of A<sup>(K)</sup> due to roundoft errors are amplified by K(A<sup>(K)</sup>) instead of K(A).

Gaussian elimination with partial pivoting is stable  $\kappa(A^{(k)}) \sim \kappa(A)$ . because

Iterative Methods

Ax=8 (=) X=Bx+C

Xktl - BXk+C

B. Heration matrix

C: coustant recta