# **Generalization Bounds**Theoretical Foundations of Deep Learning

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December 17, 2024



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### Introduction

Introduction

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## Why Study Generalization?

► Core Question: How can models trained on limited data perform reliably on unseen scenarios?

Classical Bounds

- ► **Generalization** is a fundamental goal in machine learning: ensuring models extend their learned patterns to new, unseen data.
- ► A poorly generalized model risks:
  - Overfitting: Performing well on training data but poorly on unseen data.
  - Underfitting: Failing to capture the underlying patterns of the data.

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## **Defining Generalization**

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- ▶ **Supervised Learning**: Learn a function  $f: X \to Y$  from labeled training data.
- ► **Challenge**: The learned function must perform well *beyond* the training set.
- ▶ **Evaluation**: We assess generalization by comparing model performance on training data versus a separate *testing* dataset representing unseen scenarios. This helps us understand how well the model will perform in the real world.

# **Overfitting**

#### Objective:

Introduction

► Show how increasing model complexity (polynomial degree) leads to overfitting.

#### Dataset

 Using the scikit-learn **Diabetes** dataset with a single feature (BMI) and a quantitative response variable indicating disease progression (Target)<sup>[1]</sup>.

#### Approach:

- 1. Fit polynomial regression models of varying degrees.
- 2. Visualize polynomial fits on the training data.
- **3.** Examine the fits' residuals to see how errors behave.
- 4. Plot training vs. test errors to highlight overfitting.

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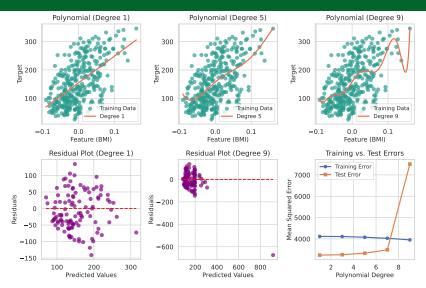


Figure 1: Overfitting Phenomenon in Polynomial Regression

Introduction

Modern machine learning introduces a fascinating twist: Double Descent, where increasing model complexity can lead to improved generalization after an initial overfitting phase.

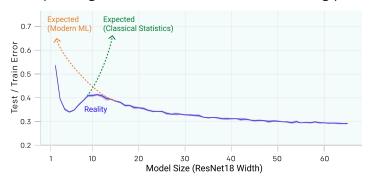


Figure 2: Double Descent phenomenon in a Residual Neural Network<sup>[2]</sup>

#### **Classical Bounds**

- ► Goal: Predict a model's performance on unseen data.
- ► **Generalization Bounds** provide theoretical guarantees, linking:
  - ► **Generalization Error**: Error on unseen data.
  - **Empirical Risk**: Error on training data.
  - ► Model Complexity: Model's flexibility.
- ▶ Why They Matter: They help understand the trade-offs between:
  - ► **Accuracy**: How well the model fits the data.
  - **Complexity**: Ability to model intricate patterns.
  - ▶ Data Size: Amount of data needed for reliable learning.

## Hoeffding's Inequality

- ► What it is: A probabilistic tool that helps estimate how well a model will generalize.
- ► Focus: Quantifies the difference between empirical risk (training error) and generalization error (true error) for a single, fixed model.

## **Hoeffding's Inequality: The Math**

► Expression<sup>[3]</sup>:

$$P(|R(h) - R_{\sf emp}(h)| > \varepsilon) \le 2 \exp(-2n\varepsilon^2)$$

- Breakdown:
  - ▶ R(h): The **true risk** of hypothesis h, defined as the expected loss over the data distribution:  $R(h) = \mathbb{E}_{x,y \sim D}[\ell(h(x), y)]$ .
  - ►  $R_{\text{emp}}(h)$ : The **empirical risk** of hypothesis h, defined as the average loss over the training dataset S of size n:  $R_{\text{emp}}(h) = \frac{1}{n} \sum_{i=1}^{n} \ell(h(x_i), y_i)$ .
  - $\triangleright$   $\varepsilon$ : Error tolerance.
  - n: Dataset size.

## Hoeffding's Inequality: Convergence

- Rate of Convergence: Simulating biased coin flips to show the rate at which sample mean approaches the true probability.
- ▶ **Hoeffding's Bound**, derived from the  $\exp(-2n\varepsilon^2)$  term, shows **faster convergence** as *n* increases.

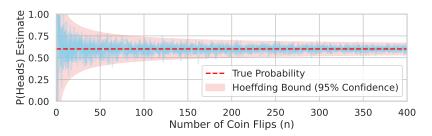


Figure 3: Convergence to True Probability with Hoeffding Bounds

## Hoeffding's Inequality: Interpretation

- ► The probability of a large difference between the true risk (generalization error) and the empirical risk (training error) decreases **exponentially** with:
  - Larger datasets (n).
  - ▶ Smaller error tolerance  $(\varepsilon)$ .
- Note: Hoeffding's inequality applies more generally to the difference between the sample average and the expectation of any bounded random variable. We have shown a special application of the inequality.
- ▶ Limitations: We usually pick the best model from many, not just one. Hoeffding doesn't account for how complex the model class is.

#### **Union Bound**

- ▶ What it does: Extends bounds like Hoeffding's to work when choosing from many models (a hypothesis space H).
- ▶ **Main Idea**: Considers the chance that *at least one* model in  $\mathcal{H}$  has a large difference between training and true error.

#### **Union Bound: The Math**

► Expression<sup>[4]</sup>:

$$P\left(\sup_{h\in\mathcal{H}}|R(h)-R_{\mathsf{emp}}(h)|>\epsilon\right)\leq\sum_{h\in\mathcal{H}}P\left(|R(h)-R_{\mathsf{emp}}(h)|>\epsilon\right)$$

- Breakdown:
  - ightharpoonup R(h): True risk (expected loss).
  - $ightharpoonup R_{emp}(h)$ : Empirical risk (average training loss).
  - ightharpoonup sup<sub> $h \in \mathcal{H}$ </sub>: Account for the worst-case scenario across all hypotheses, considering the largest deviation between true and empirical risk.
  - ▶  $\sum_{h \in \mathcal{H}}$ : Sums up probabilities of large error differences for each model in the hypothesis space  $\mathcal{H}$ .

## **Union Bound: Interpretation**

► Larger Model Space: The more models we consider, the looser the bound becomes.

Table 1: Trade-off: Hypothesis Space vs. Bound & Capacity

Hypothesis Space Size	Bound	Model Capacity
Small	Tighter	Limited
Large	Looser	Higher

## **Moving Forward**

- ► **Challenge**: Real-world model spaces are often infinite or too large.
- ► **Solution**: We need ways to measure model complexity that go beyond counting.
- ▶ **Next**: Exploring **complexity measures** for more practical generalization bounds.

#### **Advanced Bounds**

## Why Advanced Bounds?

- ► Classical Bounds give us a good starting point, but they can be loose.
- ► **Goal**: Tighter bounds that better reflect real-world performance.
- ► **How?**: By measuring model complexity in more sophisticated ways.

- ▶ **Growth Function**  $(\Pi_{\mathcal{H}}(n))$ : How many ways can a model class  $(\mathcal{H})$  label n data points?
  - ► More ways = more complex.
  - For small n,  $\Pi_{\mathcal{H}}(n) = 2^n$ .
- ▶ **Shattering**: A model class *shatters* a dataset if it can label it in *every possible way*.

### **VC** Dimension: Definition

- **VC Dimension**  $(d_{VC})$ : The size of the *largest* dataset a model class can shatter.
- **Example**: Linear classifiers in 2D have  $d_{VC} = 3$ . They can shatter 3 points but not 4 (in all configurations).

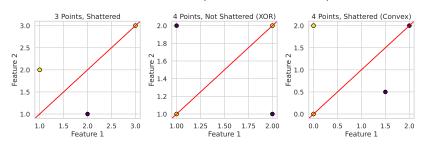


Figure 4: VC Dimension of Linear Classifiers in 2D

#### VC Generalization Bound: The Math

Expression<sup>[5]</sup>:

$$R(h) \leq R_{\mathsf{emp}}(h) + \sqrt{\frac{8d_{\mathsf{VC}}\left(\ln\left(\frac{2n}{d_{\mathsf{VC}}}\right) + 1\right) + 8\ln\left(\frac{4}{\delta}\right)}{n}}$$

Classical Bounds

- Breakdown:
  - R(h): True risk (expected loss).
  - R<sub>emp</sub>(h): Empirical risk (average training loss).
  - d<sub>VC</sub>: VC dimension.
  - n: Dataset size.
  - $\triangleright$   $\delta$ : Confidence parameter.

## **VC** Generalization Bound: Interpretation

- Higher VC Dimension:
  - More complex model, looser bound, higher risk of overfitting.
- Larger Dataset:
  - Tighter bound, better generalization.

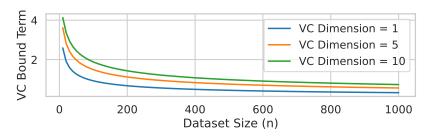


Figure 5: Approximation of the VC Generalization Bound

- **VC** theory often considers the *worst-case* scenario.
- New Idea: Use information about the data distribution for tighter bounds.
- **Example**: Support Vector Machines (SVMs).
  - ► Margin: Distance from the decision boundary to the nearest data points.
  - ► Larger margin = better generalization.
- ▶ **Benefit**: More realistic bounds reflecting real-world performance.

## More Measures of Complexity

- ▶ Why?: VC dimension can be too pessimistic.
- ► **Goal**: More nuanced measures, especially for things like neural networks.

**Table 2:** Further ways to measure complexity<sup>[6]</sup>

Measure	Description	Key Idea
Covering Numbers	How many "balls" cover the hypothesis space?	Smaller = simpler = tighter bounds
Rademacher Complexity	How well can the model fit random noise?	Lower = less prone to overfitting

## **Conclusions**

## Key Takeaways I

- ▶ Generalization is crucial: We want models to work on unseen data, not just the training set.
- Overfitting is a risk: More complex models can memorize the training data but fail to generalize.
- Classical Bounds highlight the importance of:
  - Dataset size: More data leads to better generalization.
  - Model complexity: Simpler models (smaller hypothesis spaces) are safer.

## Key Takeaways II

- Advanced Bounds offer a refined view:
  - ► VC Dimension: Measures a model's ability to shatter data. Higher VC dimension means more complexity.
  - Distribution-Based: Leverage data properties for tighter bounds.
- ▶ **The Goal**: Balance model expressiveness with the risk of overfitting by controlling complexity and leveraging insights from the data distribution.

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