
Cat flap



Agnes & Nabaz - IR sensors

- Created prototype for the sensor

Agnes & Nabaz - IR sensors

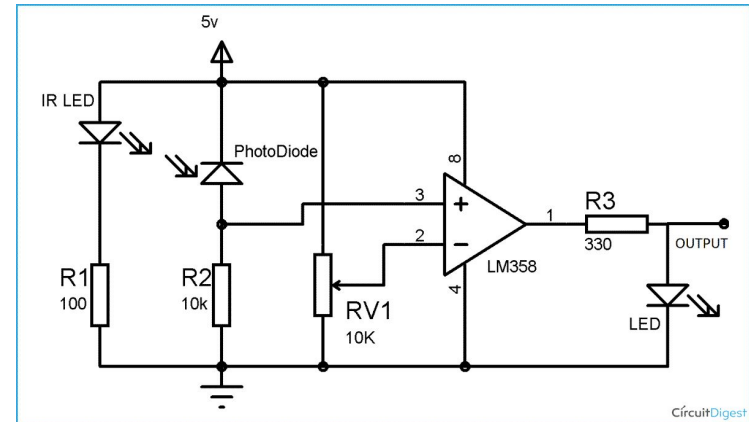
- Created prototype for the sensor
- Measured the output from the receiver

Agnes & Nabaz - IR sensors

- Created prototype for the sensor
- Measured the output from the receiver
- Stolen the sensors from the cat flap, replicated the results from the prototype

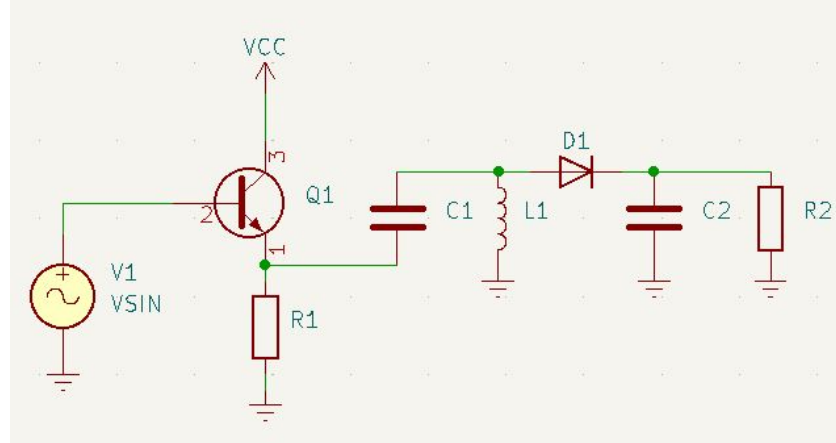
Agnes & Nabaz - IR sensors

- Created prototype for the sensor
- Measured the output from the receiver
- Stolen the sensors from the cat flap, replicated the results from the prototype
- Research and Improvement
 - Sensitivity
 - Energy efficiency



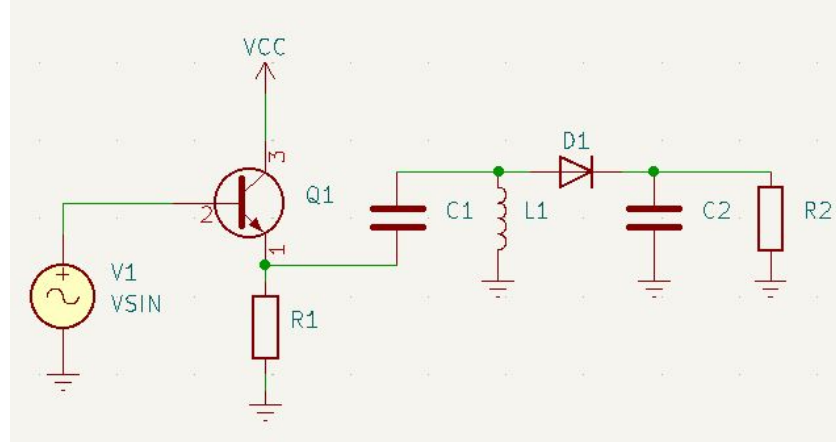
Jakob & Arvid - Antenna

- Gained enough understanding RFID to start working on the new design



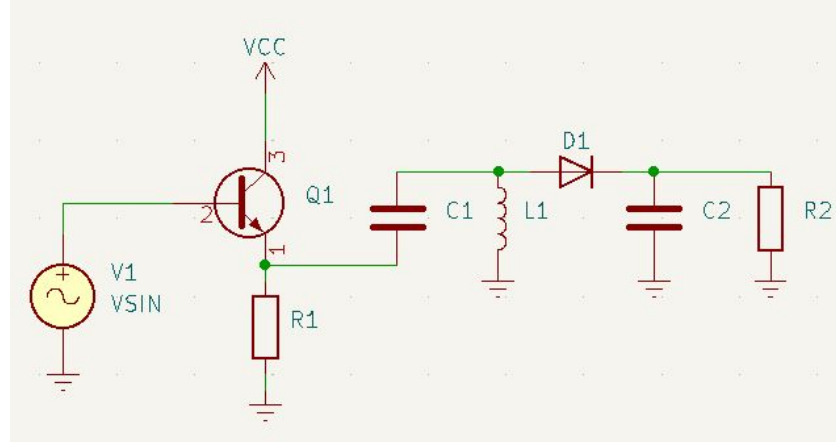
Jakob & Arvid - Antenna

- Gained enough understanding RFID to start working on the new design
- Measured the signal of the pet microchip and antenna for further analysis



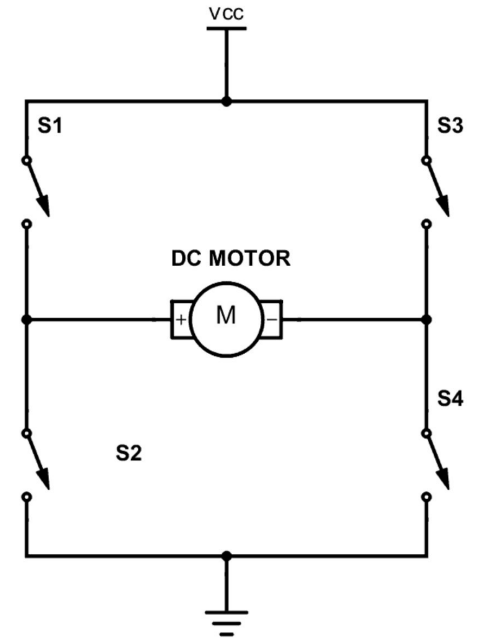
Jakob & Arvid - Antenna

- Gained enough understanding RFID to start working on the new design
- Measured the signal of the pet microchip for further analysis
- Have started simulating on a preliminary design



Matilda & Anders - Motor

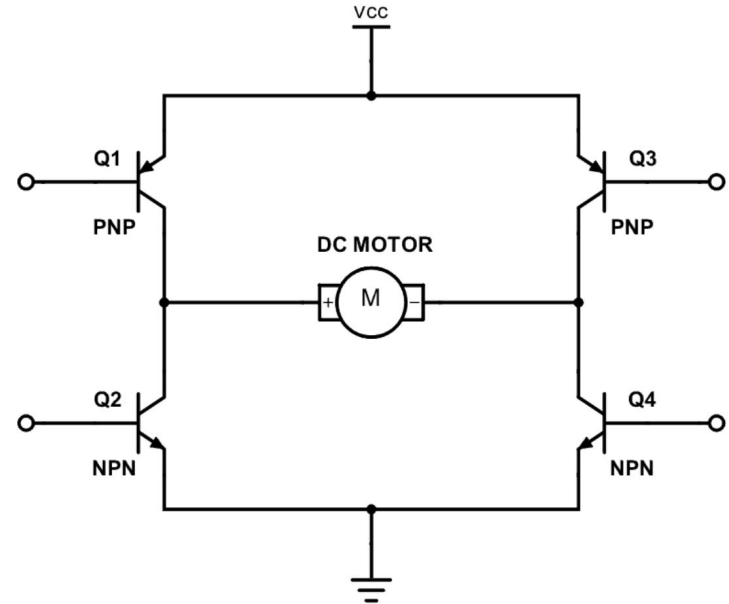
- H-bridge to control the direction of the motor



Matilda & Anders - Motor



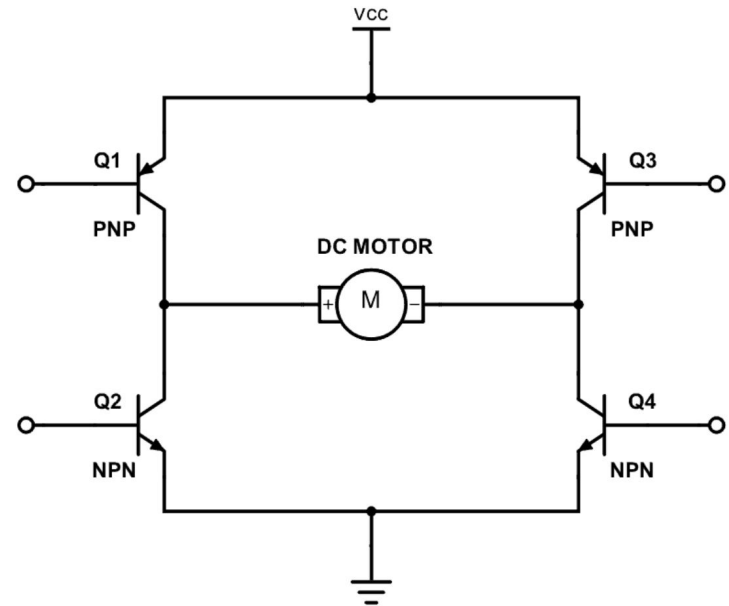
- H-bridge to control the direction of the motor
- NPN and PNP transistors



Matilda & Anders - Motor



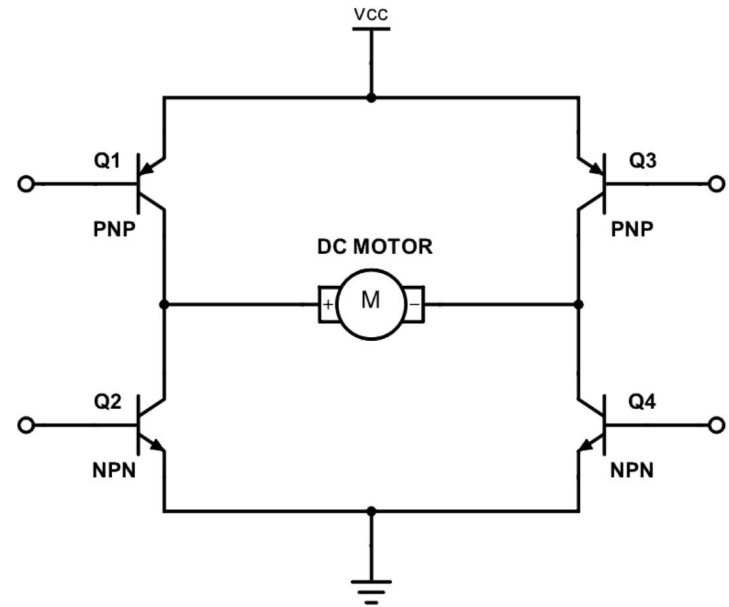
- H-bridge to control the direction of the motor
- NPN and PNP transistors
- Played around!



Matilda & Anders - Motor



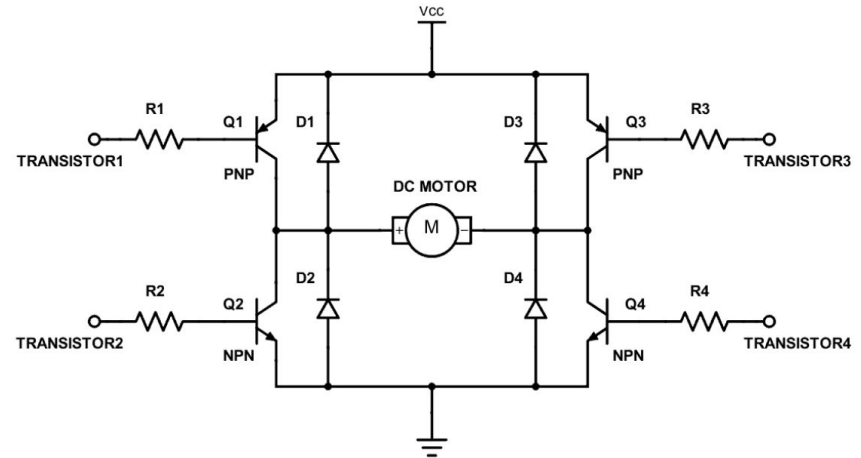
- H-bridge to control the direction of the motor
- NPN and PNP transistors
- Played around!
- Choices (DVR8837) + report



Matilda & Anders - Motor



- H-bridge to control the direction of the motor
- NPN and PNP transistors
- Played around!
- Choices (DVR8837) + report
- Proper electric circuit →





Questions?

