## 1 Probabilistic Model of Linear Regression

Both ordinary least squares and ridge regression have interpretations from a probabilistic standpoint. In particular, assuming a generative model for our data and a particular noise distribution, we will derive least squares and ridge regression as the maximum likelihood and maximum a-posteriori parameter estimates, respectively. This problem will walk you through a few steps to do that. (Along with some side digressions to make sure you get a better intuition for ML and MAP estimation.)

- (a) Assume that X and Y are both one-dimensional random variables, i.e.  $X, Y \in \mathbb{R}$ . Assume an affine model between X and Y:  $Y = Xw_1 + w_0 + Z$ , where  $w_1, w_0 \in \mathbb{R}$ , and  $Z \sim N(0, 1)$  is a standard normal (Gaussian) random variable. Assume  $w_1, w_0$  are fixed parameters (i.e., they are not random). What is the conditional distribution of Y given X?
- (b) Given n points of training data  $\{(X_1, Y_1), (X_2, Y_2), \ldots, (X_n, Y_n)\}$  generated in an iid fashion by the probabilistic setting in the previous part, derive the maximum likelihood estimator for  $w_1, w_0$  from this training data.
- (c) Now, consider a different generative model. Let Y = Xw + Z, where  $Z \sim U[-0.5, 0.5]$  is a continuous random variable uniformly distributed between -0.5 and 0.5. Again assume that w is a fixed parameter. What is the conditional distribution of Y given X?
- (d) Given n points of training data  $\{(X_1, Y_1), (X_2, Y_2), \dots, (X_n, Y_n)\}$  generated in an i.i.d. fashion in the setting of the part (c) **derive a maximum likelihood estimator of** w. Assume that  $X_i > 0$  for all  $i = 1, \dots, n$ . (Note that MLE for this case need not be unique; but you are required to report only one particular estimate.)
- (e) Take the model Y = Xw + Z, where  $Z \sim U[-0.5, 0.5]$ . Use a computer to simulate n training samples  $\{(X_1, Y_1), (X_2, Y_2), \cdots, (X_n, Y_n)\}$  and illustrate what the likelihood of the data looks like as a function of w after n = 5, 25, 125, 625 training samples. Qualitatively describe what is happening as n gets large.
  - ( You have total freedom in using any python libraries for this problem part. No restrictions. )
- (f) (One-dimensional Ridge Regression) Now, let us return to the case of Gaussian noise. Given n points of training data  $\{(X_1, Y_1), (X_2, Y_2), \cdots, (X_n, Y_n)\}$

generated according to  $Y_i = X_iW + Z_i$ , where  $Z_i \sim N(0,1)$  are iid standard normal random variables. Assume  $W \sim N(0,\sigma^2)$  is also a standard normal and is independent of both the  $Z_i$ 's and the  $X_i$ 's. Use Bayes' Theorem to derive the posterior distribution of W given the training data. What is the mean of the posterior distribution of W given the data?

Hint: Compute the posterior up-to proportionality and try to identify the distribution by completing the square.

- (g) Consider n training data points  $\{(\vec{x}_1, Y_1), (\vec{x}_2, Y_2), \cdots, (\vec{x}_n, Y_n)\}$  generated according to  $Y_i = \vec{w}^\top \vec{x}_i + Z_i$  where  $Y_i \in \mathbb{R}, \vec{w}, \vec{x}_i \in \mathbb{R}^d$  with  $\vec{w}$  fixed, and  $Z_i \sim N(0,1)$  iid standard normal random variables. Argue why the maximum likelihood estimator for  $\vec{w}$  is the solution to a least squares problem.
- (h) (Multi-dimensional ridge regression) Consider the setup of the previous part:  $Y_i = \vec{W}^\top \vec{x}_i + Z_i$ , where  $Y_i \in \mathbb{R}, \vec{W}, \vec{x}_i \in \mathbb{R}^d$ , and  $Z_i \sim N(0,1)$  iid standard normal random variables. Now we treat  $\vec{W}$  as a random vector and assume a prior knowledge about its distribution. In particular, we use the prior information that the random variables  $W_j$  are i.i.d.  $\sim N(0, \sigma^2)$  for  $j = 1, 2, \ldots, d$ . Derive the posterior distribution of  $\vec{W}$  given all the  $\vec{x}_i, Y_i$  pairs. What is the mean of the posterior distribution of the random vector  $\vec{W}$ ?

Hint: Use hints from part (f) and the following identities: For  $\mathbf{X} = \begin{bmatrix} \vec{x}_1^\top \\ \vdots \\ \vec{x}_n^\top \end{bmatrix}$  and  $\vec{Y} = \begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix}$  we have  $\mathbf{X}^\top \mathbf{X} = \sum_{i=1}^n \vec{x}_i \vec{x}_i^\top$  and  $\mathbf{X}^T \vec{Y} = \sum_{i=1}^n \vec{x}_i Y_i$ .

(i) Consider d=2 and the setting of the previous part. Use a computer to simulate and illustrate what the *a-posteriori* probability looks like for the W model parameter space after n=5,25,125 training samples for different values of  $\sigma^2$ . (You have total freedom in using any python libraries for this problem part. No restrictions.)