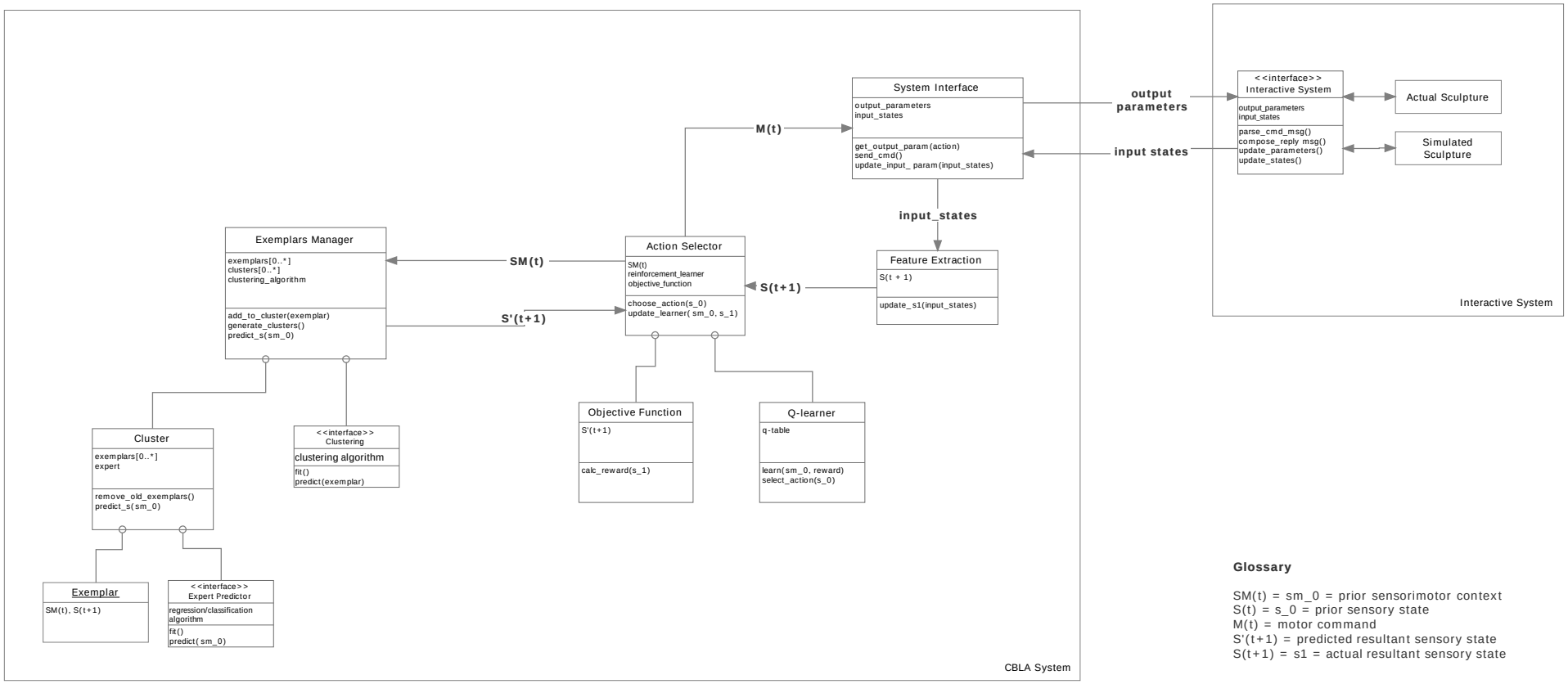
CBLA Software Architecture



Glossary

SM(t) = sm_0 = prior sensorimotor context
S(t) = s_0 = prior sensory state
M(t) = motor command
S'(t+1) = predicted resultant sensory state
S(t+1) = s1 = actual resultant sensory state