

Tidy Time Series & Forecasting in R

7. Exponential smoothing



Outline

- 1 Exponential smoothing
- 2 Trend methods
- 3 Lab Session 14
- 4 Seasonal methods
- 5 ETS taxonomy
- 6 Lab Session 15
- 7 Non-Gaussian forecast distributions

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Pharmaceutical Benefits Scheme



Pharmaceutical Benefits Scheme

The Pharmaceutical Benefits Scheme (PBS) is the Australian government drugs subsidy scheme.

- Many drugs bought from pharmacies are subsidised to allow more equitable access to modern drugs.
- The cost to government is determined by the number and types of drugs purchased. Currently nearly 1% of GDP.
- The total cost is budgeted based on forecasts of drug usage.

Pharmaceutical Benefits Scheme

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POLITICS

Opp demands drug price restriction after PBS budget blow-out

The Federal Opposition has called for tighter controls on drug prices after the Pharmaceutical Benefits Scheme (PBS) budget blew out by almost \$800 million.

The money was spent on two new drugs including the controversial anti-smoking aid Zyban, which dropped in price from \$220 to \$22 after it was listed on the PBS.

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Pharmaceutical Benefits Scheme

- In 2001: \$4.5 billion budget, under-forecasted by \$800 million.
- Thousands of products. Seasonal demand.
- Subject to covert marketing, volatile products, uncontrollable expenditure.
- Although monthly data available for 10 years, data are aggregated to annual values, and only the first three years are used in estimating the forecasts.
- All forecasts being done with the FORECAST function in MS-Excel!

Historical perspective

- Developed in the 1950s and 1960s as methods (algorithms) to produce point forecasts.
- Combine a “level”, “trend” (slope) and “seasonal” component to describe a time series.
- The rate of change of the components are controlled by “smoothing parameters”: α , β and γ respectively.
- Need to choose best values for the smoothing parameters (and initial states).
- Equivalent ETS state space models developed in the 1990s and 2000s.

A model for levels, trends, and seasonalities

We want a model that captures the level (ℓ_t), trend (b_t) and seasonality (s_t).

How do we combine these elements?

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Additively?

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Multiplicatively?

$$y_t = \ell_{t-1} b_{t-1} s_{t-m} (1 + \varepsilon_t)$$

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Multiplicatively?

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Perhaps a mix of both?

$$y_t = (\ell_{t-1} + b_{t-1}) s_{t-m} + \varepsilon_t$$

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How do the level, trend and seasonal components evolve over time?

ETS models

General notation

ETS : ExponenTial Smoothing



Error Trend Season

Error: Additive ("A") or multiplicative ("M")

ETS models

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Error Trend Season

Error: Additive ("A") or multiplicative ("M")

Trend: None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

ETS models

General notation

ETS : ExponenTial Smoothing



Error Trend Season

Error: Additive ("A") or multiplicative ("M")

Trend: None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

Seasonality: None ("N"), additive ("A") or multiplicative ("M")

ETS(A,N,N): SES with additive errors

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T$$

Measurement equation

$$y_t = \ell_{t-1} + \varepsilon_t$$

State equation

$$\ell_t = \ell_{t-1} + \alpha \varepsilon_t$$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

ETS(A,N,N): SES with additive errors

Forecast equation

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where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

- “innovations” or “single source of error” because equations have the same error process, ε_t .
- Measurement equation: relationship between observations and states.
- Transition/state equation(s): evolution of state(s) over time.

ETS(M,N,N): SES with multiplicative errors

Forecast equation

$$\hat{y}_{T+h|T} = l_T$$

Measurement equation

$$y_t = l_{t-1}(1 + \varepsilon_t)$$

State equation

$$l_t = l_{t-1}(1 + \alpha\varepsilon_t)$$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

ETS(M,N,N): SES with multiplicative errors

Forecast equation

$$\hat{y}_{T+h|T} = l_T$$

Measurement equation

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State equation

$$l_t = l_{t-1}(1 + \alpha\varepsilon_t)$$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

- Models with additive and multiplicative errors with the same parameters generate the same point forecasts but different prediction intervals.

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Holt's linear trend

Additive errors: ETS(A,A,N)

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T + hb_T$$

Measurement equation

$$y_t = \ell_{t-1} + b_{t-1} + \varepsilon_t$$

State equations

$$\ell_t = \ell_{t-1} + b_{t-1} + \alpha\varepsilon_t$$

$$b_t = b_{t-1} + \beta\varepsilon_t$$

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Multiplicative errors: ETS(M,A,N)

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T + hb_T$$

Measurement equation

$$y_t = (\ell_{t-1} + b_{t-1})(1 + \varepsilon_t)$$

State equations

$$\ell_t = (\ell_{t-1} + b_{t-1})(1 + \alpha\varepsilon_t)$$

$$b_t = b_{t-1} + \beta\varepsilon_t$$

Example: Australian population

```
aus_economy <- global_economy %>%  
  filter(Code == "AUS") %>%  
  mutate(Pop = Population / 1e6)  
fit <- aus_economy %>% model(AAN = ETS(Pop))  
report(fit)
```

```
## Series: Pop  
## Model: ETS(A,A,N)  
##   Smoothing parameters:  
##     alpha = 1  
##     beta  = 0.327  
##  
##   Initial states:  
##   l[0]  b[0]  
## 10.1 0.222  
##  
##   sigma^2: 0.0041  
##  
##   AIC  AICc  BIC
```

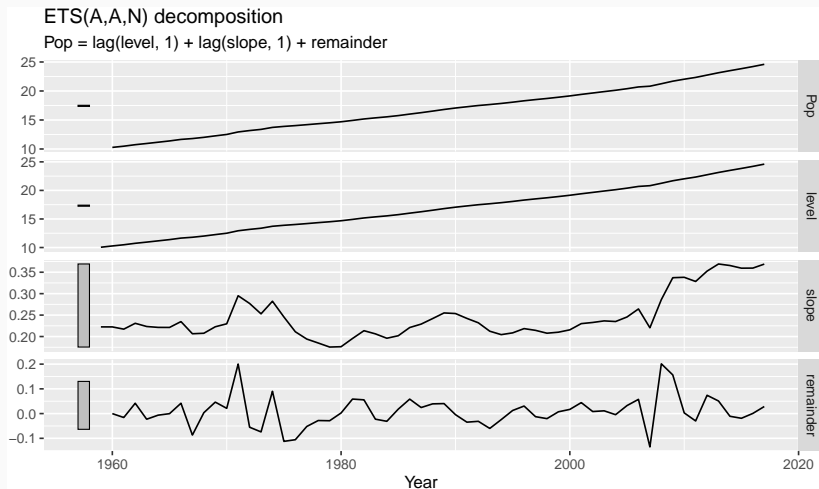

Example: Australian population

```
components(fit)
```

```
## # A dable: 59 x 7 [1Y]
## # Key:      Country, .model [1]
## # :        Pop = lag(level, 1) + lag(slope, 1) + remainder
##   Country   .model Year   Pop level slope remainder
##   <fct>     <chr>  <dbl> <dbl> <dbl> <dbl>      <dbl>
## 1 Australia AAN    1959  NA    10.1 0.222  NA
## 2 Australia AAN    1960  10.3  10.3 0.222 -0.000145
## 3 Australia AAN    1961  10.5  10.5 0.217 -0.0159
## 4 Australia AAN    1962  10.7  10.7 0.231  0.0418
## 5 Australia AAN    1963  11.0  11.0 0.223 -0.0229
## 6 Australia AAN    1964  11.2  11.2 0.221 -0.00641
## 7 Australia AAN    1965  11.4  11.4 0.221 -0.000314
## 8 Australia AAN    1966  11.7  11.7 0.235  0.0418
## 9 Australia AAN    1967  11.8  11.8 0.206 -0.0869
```

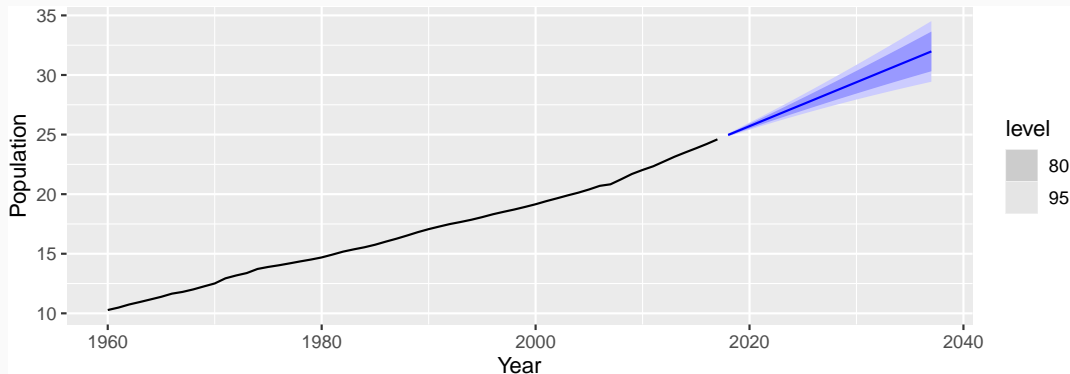
Example: Australian population

```
components(fit) %>% autoplot()
```



Example: Australian population

```
fit %>%  
  forecast(h = 20) %>%  
  autoplot(aus_economy) +  
  ylab("Population") + xlab("Year")
```



ETS(A,Ad,N): Damped trend method

Additive errors

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T + (\phi + \dots + \phi^{h-1})b_T$$

Measurement equation

$$y_t = (\ell_{t-1} + \phi b_{t-1}) + \varepsilon_t$$

State equations

$$\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$$

$$b_t = \phi b_{t-1} + \beta \varepsilon_t$$

ETS(A,Ad,N): Damped trend method

Additive errors

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T + (\phi + \dots + \phi^{h-1})b_T$$

Measurement equation

$$y_t = (\ell_{t-1} + \phi b_{t-1}) + \varepsilon_t$$

State equations

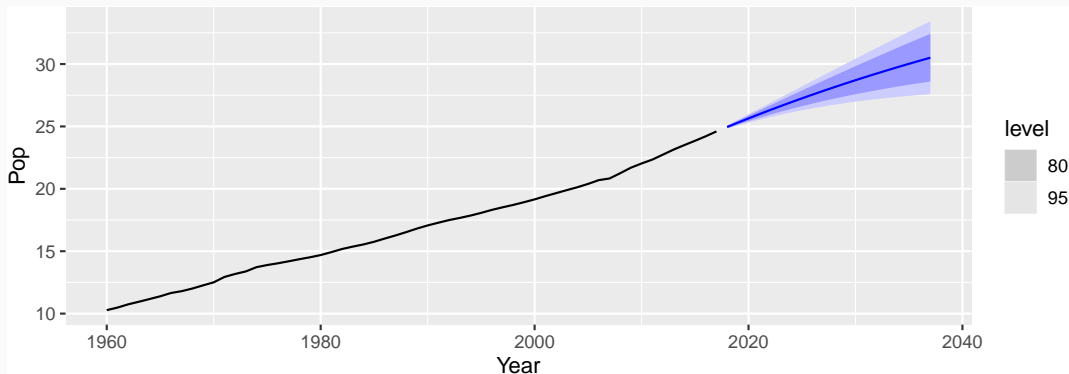
$$\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$$

$$b_t = \phi b_{t-1} + \beta \varepsilon_t$$

- Damping parameter $0 < \phi < 1$.
- If $\phi = 1$, identical to Holt's linear trend.
- As $h \rightarrow \infty$, $\hat{y}_{T+h|T} \rightarrow \ell_T + \phi b_T / (1 - \phi)$.
- Short-run forecasts trended, long-run forecasts constant.

Example: Australian population

```
aus_economy %>%  
  model(holt = ETS(Pop ~ trend("Ad"))) %>%  
  forecast(h = 20) %>%  
  autoplot(aus_economy)
```



Example: National populations

```
fit <- global_economy %>%  
  mutate(Pop = Population / 1e6) %>%  
  model(ets = ETS(Pop))  
fit
```

```
## # A tibble: 263 x 2  
## # Key:   Country [263]  
##   Country                ets  
##   <fct>                 <model>  
## 1 Afghanistan    <ETS(A,A,N)>  
## 2 Albania        <ETS(M,A,N)>  
## 3 Algeria        <ETS(M,A,N)>  
## 4 American Samoa <ETS(M,A,N)>  
## 5 Andorra        <ETS(M,A,N)>  
## 6 Angola         <ETS(M,A,N)>  
## 7 Antigua and Barbuda <ETS(M,A,N)>  
## 8 Arab World     <ETS(M,A,N)>  
## 9 Argentina     <ETS(A,A,N)>  
## 10 Armenia       <ETS(M,A,N)>
```

Example: National populations

```
fit %>%  
  forecast(h = 5)
```

```
## # A tibble: 1,315 x 5 [1Y]  
## # Key:      Country, .model [263]  
##   Country      .model Year      Pop .mean  
##   <fct>        <chr>  <dbl>    <dist> <dbl>  
## 1 Afghanistan ets     2018    N(36, 0.012) 36.4  
## 2 Afghanistan ets     2019    N(37, 0.059) 37.3  
## 3 Afghanistan ets     2020    N(38, 0.16) 38.2  
## 4 Afghanistan ets     2021    N(39, 0.35) 39.0  
## 5 Afghanistan ets     2022    N(40, 0.64) 39.9  
## 6 Albania     ets     2018    N(2.9, 0.00012) 2.87  
## 7 Albania     ets     2019    N(2.9, 6e-04) 2.87  
## 8 Albania     ets     2020    N(2.9, 0.0017) 2.87
```


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Lab Session 14

Try forecasting the Chinese GDP from the `global_economy` data set using an ETS model.

Experiment with the various options in the `ETS()` function to see how much the forecasts change with damped trend, or with a Box-Cox transformation. Try to develop an intuition of what each is doing to the forecasts.

[Hint: use `h=20` when forecasting, so you can clearly see the differences between the various options when plotting the forecasts.]

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ETS(A,A,A): Holt-Winters additive method

Forecast equation

$$\hat{y}_{t+h|t} = \ell_t + hb_t + s_{t+h-m(k+1)}$$

Observation equation

$$y_t = \ell_{t-1} + b_{t-1} + s_{t-m} + \varepsilon_t$$

State equations

$$\ell_t = \ell_{t-1} + b_{t-1} + \alpha \varepsilon_t$$

$$b_t = b_{t-1} + \beta \varepsilon_t$$

$$s_t = s_{t-m} + \gamma \varepsilon_t$$

- $k = \text{integer part of } (h - 1)/m$.
- $\sum_i s_i \approx 0$.
- Parameters: $0 \leq \alpha \leq 1$, $0 \leq \beta^* \leq 1$, $0 \leq \gamma \leq 1 - \alpha$ and $m =$ period of seasonality (e.g. $m = 4$ for quarterly data).

ETS(M,A,M): Holt-Winters multiplicative method

Forecast equation

$$\hat{y}_{t+h|t} = (\ell_t + hb_t)s_{t+h-m(k+1)}$$

Observation equation

$$y_t = (\ell_{t-1} + b_{t-1})s_{t-m}(1 + \varepsilon_t)$$

State equations

$$\ell_t = (\ell_{t-1} + b_{t-1})(1 + \alpha\varepsilon_t)$$

$$b_t = b_{t-1}(1 + \beta\varepsilon_t)$$

$$s_t = s_{t-m}(1 + \gamma\varepsilon_t)$$

- k is integer part of $(h - 1)/m$.
- $\sum_i s_i \approx m$.
- Parameters: $0 \leq \alpha \leq 1$, $0 \leq \beta^* \leq 1$, $0 \leq \gamma \leq 1 - \alpha$ and $m =$ period of seasonality (e.g. $m = 4$ for quarterly data).

Example: Australian holiday tourism

```
holidays <- tourism %>%  
  filter(Purpose == "Holiday")  
fit <- holidays %>% model(ets = ETS(Trips))  
fit
```

```
## # A mable: 76 x 4
```

```
## # Key:      Region, State, Purpose [76]
```

##	Region	State	Purpose	ets
##	<chr>	<chr>	<chr>	<model>
## 1	Adelaide	South Australia	Holiday	<ETS(A,N,A)>
## 2	Adelaide Hills	South Australia	Holiday	<ETS(A,A,N)>
## 3	Alice Springs	Northern Territory	Holiday	<ETS(M,N,A)>
## 4	Australia's Coral Coast	Western Australia	Holiday	<ETS(M,N,A)>
## 5	Australia's Golden Outback	Western Australia	Holiday	<ETS(M,N,M)>
## 6	Australia's North West	Western Australia	Holiday	<ETS(A,N,A)>
## 7	Australia's South West	Western Australia	Holiday	<ETS(M,N,M)>
## 8	Ballarat	Victoria	Holiday	<ETS(M,N,A)>
## 9	Barkly	Northern Territory	Holiday	<ETS(A,N,A)>

Example: Australian holiday tourism

```
fit %>%  
  filter(Region == "Snowy Mountains") %>%  
  report()
```

```
## Series: Trips  
## Model: ETS(M,N,A)  
##   Smoothing parameters:  
##     alpha = 0.157  
##     gamma = 1e-04  
##  
##   Initial states:  
##   l[0] s[0] s[-1] s[-2] s[-3]  
##   142  -61   131 -42.2 -27.7  
##  
##   sigma^2: 0.0388  
##  
##   AIC AICc  BIC  
##   852  854  869
```

Example: Australian holiday tourism

```
fit %>%  
  filter(Region == "Snowy Mountains") %>%  
  components(fit)
```

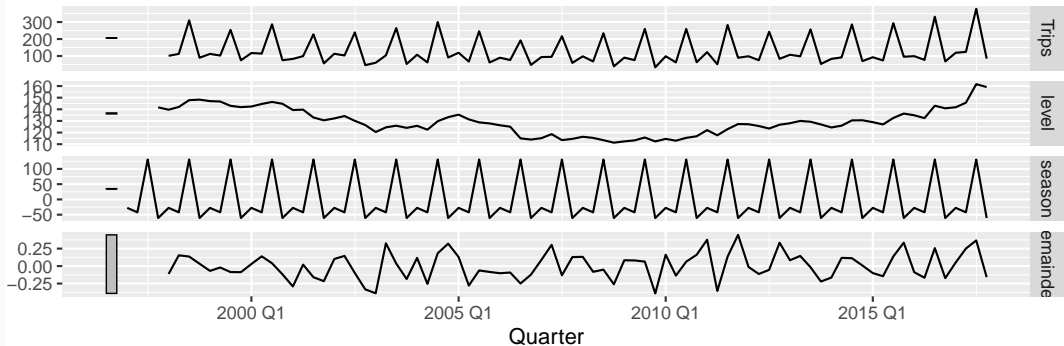
```
## # A dable: 84 x 9 [1Q]  
## # Key:      Region, State, Purpose, .model [1]  
## # :        Trips = (lag(level, 1) + lag(season, 4)) * (1 + remainder)  
##   Region      State Purpose .model Quarter Trips level season remainder  
##   <chr>        <chr> <chr>  <chr>    <qtr>  <dbl>  <dbl>  <dbl>      <dbl>  
## 1 Snowy Mountai~ New ~ Holiday ets    1997 Q1  NA      NA    -27.7    NA  
## 2 Snowy Mountai~ New ~ Holiday ets    1997 Q2  NA      NA    -42.2    NA  
## 3 Snowy Mountai~ New ~ Holiday ets    1997 Q3  NA      NA    131.     NA  
## 4 Snowy Mountai~ New ~ Holiday ets    1997 Q4  NA     142.   -61.0    NA  
## 5 Snowy Mountai~ New ~ Holiday ets    1998 Q1 101.    140.   -27.7   -0.113  
## 6 Snowy Mountai~ New ~ Holiday ets    1998 Q2 112.    142.   -42.2    0.154  
## 7 Snowy Mountai~ New ~ Holiday ets    1998 Q3 310.    148.   131.     0.137  
## 8 Snowy Mountai~ New ~ Holiday ets    1998 Q4  89.8   148.   -61.0    0.0335  
## 9 Snowy Mountai~ New ~ Holiday ets    1999 Q1 112.    147.   -27.7   -0.0687
```


Example: Australian holiday tourism

```
fit %>%  
  filter(Region == "Snowy Mountains") %>%  
  components(fit) %>% autoplot()
```

ETS(M,N,A) decomposition

$\text{Trips} = (\text{lag}(\text{level}, 1) + \text{lag}(\text{season}, 4)) * (1 + \text{remainder})$



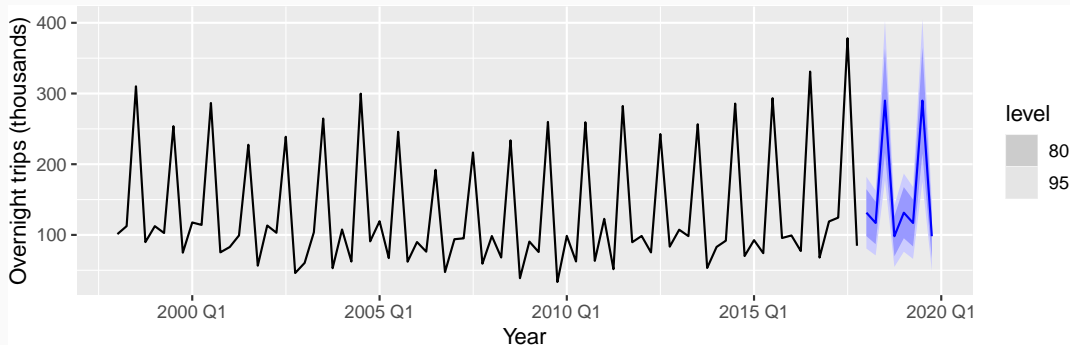
Example: Australian holiday tourism

```
fit %>% forecast()
```

```
## # A tibble: 608 x 7 [1Q]
## # Key:      Region, State, Purpose, .model [76]
##   Region      State      Purpose .model Quarter      Trips .mean
##   <chr>      <chr>      <chr>  <chr>    <qtr>      <dist> <dbl>
## 1 Adelaide    South Australia Holiday ets    2018 Q1 N(210, 457) 210.
## 2 Adelaide    South Australia Holiday ets    2018 Q2 N(173, 473) 173.
## 3 Adelaide    South Australia Holiday ets    2018 Q3 N(169, 489) 169.
## 4 Adelaide    South Australia Holiday ets    2018 Q4 N(186, 505) 186.
## 5 Adelaide    South Australia Holiday ets    2019 Q1 N(210, 521) 210.
## 6 Adelaide    South Australia Holiday ets    2019 Q2 N(173, 537) 173.
## 7 Adelaide    South Australia Holiday ets    2019 Q3 N(169, 553) 169.
## 8 Adelaide    South Australia Holiday ets    2019 Q4 N(186, 569) 186.
## 9 Adelaide Hills South Australia Holiday ets    2018 Q1  N(19, 36)  19.4
## 10 Adelaide Hills South Australia Holiday ets    2018 Q2  N(20, 36)  19.6
## # ... with 598 more rows
```

Example: Australian holiday tourism

```
fit %>%  
  forecast() %>%  
  filter(Region == "Snowy Mountains") %>%  
  autoplot(holidays) +  
  xlab("Year") + ylab("Overnight trips (thousands)")
```



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Exponential smoothing models

Additive Error

		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
Trend Component	N (None)	A,N,N	A,N,A	A,N,M
	A (Additive)	A,A,N	A,A,A	A,A,M
	A _d (Additive damped)	A,A _d ,N	A,A _d ,A	A,A_d,M

Multiplicative Error

		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
Trend Component	N (None)	M,N,N	M,N,A	M,N,M
	A (Additive)	M,A,N	M,A,A	M,A,M
	A _d (Additive damped)	M,A _d ,N	M,A _d ,A	M,A _d ,M

Estimating ETS models

- Smoothing parameters α , β , γ and ϕ , and the initial states ℓ_0 , b_0 , s_0 , s_{-1} , \dots , s_{-m+1} are estimated by maximising the “likelihood” = the probability of the data arising from the specified model.
- For models with additive errors equivalent to minimising SSE.
- For models with multiplicative errors, **not** equivalent to minimising SSE.

Model selection

Akaike's Information Criterion

$$AIC = -2 \log(L) + 2k$$

where L is the likelihood and k is the number of parameters & initial states estimated in the model.

Model selection

Akaike's Information Criterion

$$AIC = -2 \log(L) + 2k$$

where L is the likelihood and k is the number of parameters & initial states estimated in the model.

Corrected AIC

$$AIC_c = AIC + \frac{2k(k+1)}{T-k-1}$$

which is the AIC corrected (for small sample bias).

Model selection

Akaike's Information Criterion

$$\text{AIC} = -2 \log(L) + 2k$$

where L is the likelihood and k is the number of parameters & initial states estimated in the model.

Corrected AIC

$$\text{AIC}_c = \text{AIC} + \frac{2k(k+1)}{T-k-1}$$

which is the AIC corrected (for small sample bias).

Bayesian Information Criterion

$$\text{BIC} = \text{AIC} + k(\log(T) - 2).$$

Minimizing the AIC assuming Gaussian residuals is asymptotically equivalent to minimizing one-step time series cross validation MSE.

Automatic forecasting

From Hyndman et al. (IJF, 2002):

- 1 Apply each model that is appropriate to the data. Optimize parameters and initial values using MLE.
 - 2 Select best method using AICc.
 - 3 Produce forecasts using best method.
 - 4 Obtain forecast intervals using underlying state space model.
- Method performed very well in M3 competition.
 - Used as a benchmark in the M4 competition.

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Lab Session 15

Find an ETS model for the Gas data from `aus_production`.

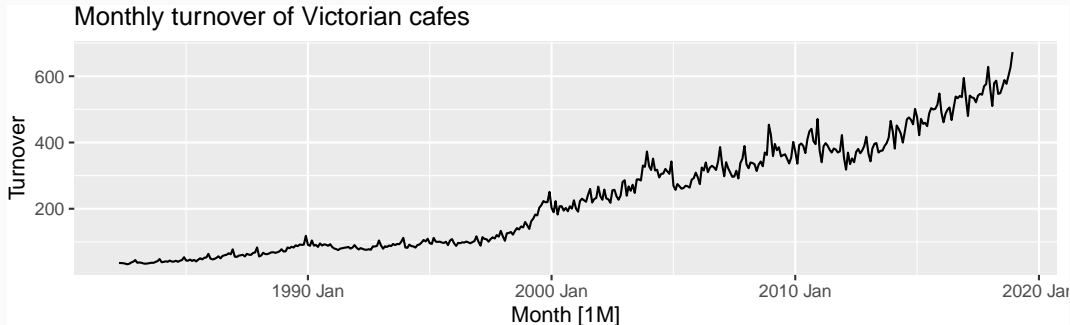
- Why is multiplicative seasonality necessary here?
- Experiment with making the trend damped. Does it improve the forecasts?

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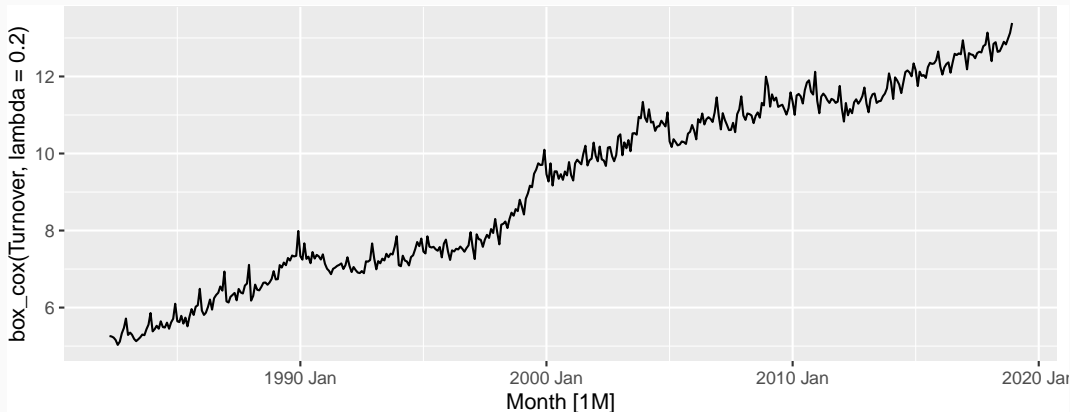
Non-Gaussian forecast distributions

```
vic_cafe <- tsibbledata::aus_retail %>%  
  filter(State == "Victoria",  
         Industry == "Cafes, restaurants and catering services") %>%  
  select(Month, Turnover)  
vic_cafe %>%  
  autoplot(Turnover) + ggtitle("Monthly turnover of Victorian cafes")
```



Forecasting with transformations

```
vic_cafe %>% autoplot(box_cox(Turnover, lambda = 0.2))
```



Forecasting with transformations

```
fit <- vic_cafe %>%  
  model(ets = ETS(box_cox(Turnover, 0.2)))  
fit
```

```
## # A mable: 1 x 1  
##           ets  
##      <model>  
## 1 <ETS(A,A,A)>
```

```
(fc <- fit %>% forecast(h = "3 years"))
```

```
## # A fable: 36 x 4 [1M]  
## # Key:      .model [1]  
##   .model    Month      Turnover .mean  
##   <chr>     <mth>      <dist> <dbl>  
## 1 ets      2019 Jan  t(N(13, 0.02)) 608.  
## 2 ets      2019 Feb  t(N(13, 0.028)) 563.  
## 3 ets      2019 Mar  t(N(13, 0.036)) 629.  
## 4 ets      2019 Apr  t(N(13, 0.044)) 615.
```

Forecasting with transformations

```
fit <- vic_cafe %>%  
  model(ets = ETS(box_cox(Turnover, 0.2)))  
fit
```

```
## # A mable: 1 x 1  
##           ets  
##      <model>  
## 1 <ETS(A,A,A)>
```

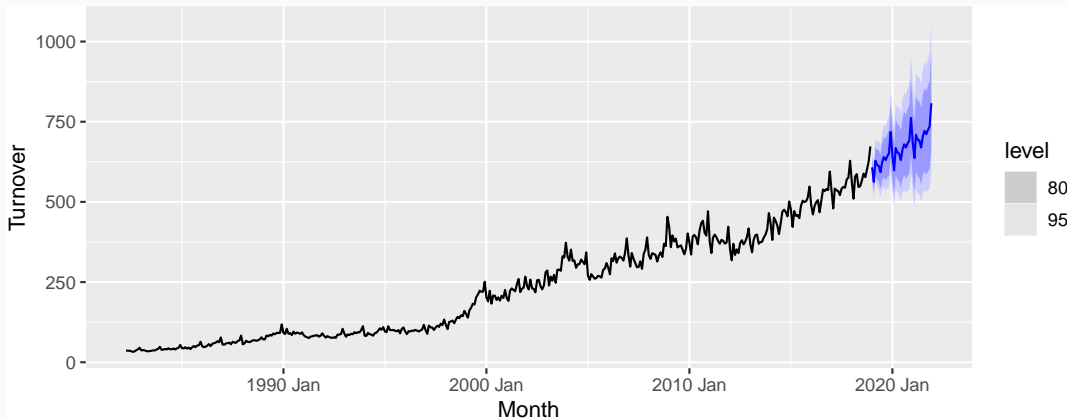
```
(fc <- fit %>% forecast(h = "3 years"))
```

```
## # A fable: 36 x 4 [1M]  
## # Key:      .model [1]  
##   .model   Month      Turnover .mean  
##   <chr>    <mth>      <dist> <dbl>  
## 1 ets     2019 Jan   t(N(13, 0.02)) 608.  
## 2 ets     2019 Feb   t(N(13, 0.028)) 563.  
## 3 ets     2019 Mar   t(N(13, 0.036)) 629.  
## 4 ets     2019 Apr   t(N(13, 0.044)) 615.
```

- $t(N)$ denotes a transformed normal distribution.
- back-transformation and bias adjustment is done automatically.

Forecasting with transformations

```
fc %>% autoplot(vic_cafe)
```



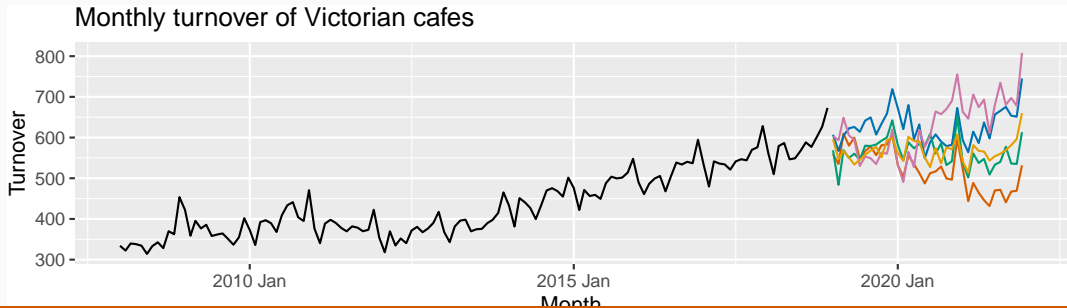
Bootstrapped forecast distributions

```
sim <- fit %>% generate(h = "3 years", times = 5, bootstrap = TRUE)
sim
```

```
## # A tsibble: 180 x 4 [1M]
## # Key:           .model, .rep [5]
##   .model      Month .rep   .sim
##   <chr>       <mth> <chr> <dbl>
## 1 ets        2019 Jan 1     559.
## 2 ets        2019 Feb 1     535.
## 3 ets        2019 Mar 1     610.
## 4 ets        2019 Apr 1     580.
## 5 ets        2019 May 1     600.
## 6 ets        2019 Jun 1     547.
## 7 ets        2019 Jul 1     566.
## 8 ets        2019 Aug 1     578.
## 9 ets        2019 Sep 1     557.
## 10 ets       2019 Oct 1     581.
## # ... with 170 more rows
```

Bootstrapped forecast distributions

```
vic_cafe %>%  
  filter(year(Month) >= 2008) %>%  
  ggplot(aes(x = Month)) +  
  geom_line(aes(y = Turnover)) +  
  geom_line(aes(y = .sim, colour = as.factor(.rep)), data = sim) +  
  ggtitle("Monthly turnover of Victorian cafes") +  
  guides(col = FALSE)
```



Bootstrapped forecast distributions

```
fc <- fit %>% forecast(h = "3 years", bootstrap = TRUE)
fc
```

```
## # A fable: 36 x 4 [1M]
## # Key:      .model [1]
##   .model      Month      Turnover .mean
##   <chr>       <mth>      <dist> <dbl>
## 1 ets        2019 Jan t(sample[5000]) 608.
## 2 ets        2019 Feb t(sample[5000]) 563.
## 3 ets        2019 Mar t(sample[5000]) 628.
## 4 ets        2019 Apr t(sample[5000]) 614.
## 5 ets        2019 May t(sample[5000]) 613.
## 6 ets        2019 Jun t(sample[5000]) 592.
## 7 ets        2019 Jul t(sample[5000]) 624.
## 8 ets        2019 Aug t(sample[5000]) 640.
## 9 ets        2019 Sep t(sample[5000]) 631.
## 10 ets       2019 Oct t(sample[5000]) 642.
## # ... with 26 more rows
```

Bootstrapped forecast distributions

```
fc %>% autoplot(vic_cafe) +  
  ggtitle("Monthly turnover of Victorian cafes")
```

