## new-ising-class.py

```
# We create a 'master' Ising class, with options to gap the spectrum or use mixed correlator
1
        information.
    import subprocess
2
    import bootstrap
3
    import matplotlib.pyplot as plt
4
    import time, datetime
5
    import datetime
6
7
    import numpy as np
    from matplotlib.backends.backend_pdf import PdfPages
8
9
    sig_defaults = np.arange(0.5, 0.85, 0.05).tolist()
10
    eps_defaults = np.arange(1.0, 2.2, 0.2).tolist()
11
12
13
    class Point(object):
      def __init__(self, sig, eps, kmax, lmax, mmax, nmax, allowed, run_time, cpu_time, CB_time,
14
          CB_cpu, xml_time, xml_cpu, sdp_time, sdp_cpu):
        self.sig = sig
15
16
        self.eps = eps
        self.kmax = kmax
17
18
        self.lmax = lmax
19
        self.mmax = mmax
20
        self.nmax = nmax
        self.allowed = allowed
21
22
        self.run_time = run_time
23
        self.cpu_time = cpu_time
24
        self.CB_time = CB_time
25
        self.CB\_cpu = CB\_cpu
        self.xml_time = xml_time
26
27
        self.xml\_cpu = xml\_cpu
        self.sdp_time = sdp_time
28
29
        self.sdp_cpu = sdp_cpu
30
      # Saves a Point object' data to file named in self.name
31
      def save(self, name):
32
        with open(name + ".py", 'a') as file:
33
          file.write("sig = " + str(self.sig) + "\n")
34
          file.write("eps = " + str(self.eps) + "\n")
35
          file.write("kmax = " + str(self.kmax) + "\n")
36
          file.write("lmax = " + str(self.lmax) + "\n")
37
          file.write("mmax = " + str(self.mmax) + "\n")
38
          file.write("nmax = " + str(self.nmax) + "\n")
39
          file.write("allowed = " + str(self.allowed) + "\n")
40
          file.write("run_time = " + str(self.run_time) + "\n")
41
          file.write("cpu_time = " + str(self.cpu_time) + "\n")
42
          file.write("CB_time = " + str(self.CB_time) + "\n")
43
          file.write("CB_cpu = " + str(self.CB_cpu) + "\n")
44
          file.write("xml_time = " + str(self.xml_time) + "\n")
45
          file.write("xml_cpu = " + str(self.xml_cpu) + "\n")
46
          file.write("sdp_time = " + str(self.sdp_time) + "\n")
47
          file.write("sdp_cpu = " + str(self.sdp_cpu) + "\n")
48
          file.write("self.point_table.append(Point(sig, eps, kmax, lmax, mmax, nmax, allowed,
49
               run_time, cpu_time, CB_time, CB_cpu, xml_time, xml_cpu, sdp_time, sdp_cpu))" + "\n")
50
    class Grid(object):
51
```

```
def __init__(self, kmax, lmax, mmax, nmax, allowed_points, disallowed_points, run_time,
 52
                     cpu_time):
                 self.kmax = kmax
 53
                 self.lmax = lmax
 54
                 self.mmax = mmax
 55
                 self.nmax = nmax
 56
 57
                 self.allowed_points = allowed_points
                 self.disallowed_points = disallowed_points
 58
                 self.run_time = run_time
 59
                 self.cpu_time = cpu_time
 60
 61
              def save(self, name):
 62
 63
                 with open(name + ".py", 'a') as file:
                     file.write("kmax = " + str(self.kmax) + "\n")
 64
                     file.write("lmax = " + str(self.lmax) + "\n")
 65
                     file.write("mmax = " + str(self.mmax) + "\n")
 66
                     file.write("nmax = " + str(self.nmax) + "\n")
 67
                     file.write("allowed_points = " + str(self.allowed_points) + "\n")
 68
                     file.write("disallowed_points = " + str(self.disallowed_points) + "\n")
 69
                     file.write("run_time = " + str(self.run_time) + "\n")
 70
                     file.write("cpu_time = " + str(self.cpu_time) + "\n")
 71
                     file.write("self.grid_table.append(Grid(kmax, lmax, mmax, nmax, allowed_points,
 72
                            disallowed_points, run_time, cpu_time))" + "\n")
 73
 74
          class Ising(object):
              def __init__(self, dim = 3, gap = 3, sig_values = sig_defaults, eps_values = eps_defaults):
 75
                 self.dim = dim
 76
 77
                 self.gap = gap
                 self.sig_values = sig_values
 78
                 self.eps_values = eps_values
 79
                 self.grid_table = []
 80
                 self.grid_file = "grid_saves"
 81
 82
                 # self.name = name
 83
              # For a given set of conformal blocks, set by kmax and lmax, generate a grids for a specified
 84
                     range of mmax and nmax.
              # If we obtain a grid of entirely dissallowed points, fill in the rest of the grids for that
 85
                     kmax and lmax.
              def iterate_parameters(self, kmax_range, lmax_range, mmax_range, nmax_range):
 86
                 keys = self.generate_keys(kmax_range, lmax_range, mmax_range, nmax_range)
 87
 88
                 while len(keys) > 0:
 89
                     # Used keys will store the keys for which there is already a grid in table.
 90
                     used_keys = []
 91
                     #null_keys = []
 92
 93
                     for key in keys:
 94
                         if self.get_grid_index(key) != -1:
 95
                             used_keys.append(key)
 96
                             continue
 97
                         print("Trying kmax = " + str(key[0]) + ", lmax = " + str(key[1]) + ", mmax = " + str
 98
                                [2]) + ", nmax = " + str(key[3]))
                         self.determine_grid(key)
 99
                         used_keys.append(key)
100
101
                         # If the grid has only disallowed points...
102
                         if self.grid_table[self.get_grid_index(key)].allowed_points == []:
103
                             print ("In the if statement.")
104
```

```
105
                k = key[0]
106
                l = key[1]
                m = key[2]
107
                n = key[3]
108
109
                null_keys = [key for key in keys if key not in used_keys and key[0] == k and key[1] ==
110
                    l and key[2] \Rightarrow m and key[3] \Rightarrow n]
111
                for key in null_keys:
112
                  if self.get_grid_index(key) != -1:
113
                    used_keys.append(key)
114
                    continue
115
                  \#grid = Grid(*key, [], [])
116
                  grid = Grid(*(key + [[], [], 0, 0]))
117
118
                  for sig in self.sig_values:
119
120
                    for eps in self.eps_values:
                      grid.disallowed_points.append((sig, eps))
121
122
123
                  self.grid_table.append(grid)
                  grid.save(self.grid_file)
124
125
                  #self.save_grid(grid, self.name)
126
127
                break
128
           # We remove all keys from the list that we are done with.
129
           keys = [key for key in keys if key not in null_keys and key not in used_keys]
130
131
           null_keys = []
132
133
       ,,,
134
       # Saves the data as an executable file that will repopulate the table attribute.
135
136
       # Note, we now do this as we go, instead of at the end, to avoid loss of mass data.
137
       def save_to_file(self, name):
         with open(name + ".py", 'w') as file:
138
139
            file.write("self.table = []\n")
            for grid in self.table:
140
              file.write("kmax = " + str(grid.kmax) + "\n")
141
              file.write("lmax = " + str(grid.lmax) + "\n")
142
              file.write("mmax = " + str(grid.mmax) + "\n")
143
              file.write("nmax = " + str(grid.nmax) + " \setminus n")
144
              file.write("allowed_points = " + str(grid.allowed_points) + "\n")
145
              file.write("disallowed_points = " + str(grid.disallowed_points) + "\n")
146
              file.write("self.grid_table.append(Grid(kmax, lmax, mmax, nmax, allowed_points,
147
                 disallowed_points))" + "\n")
       ,,,
148
149
       ,,,
150
       def save_grid(self, grid, name):
151
         with open(name + ".py", 'a') as file:
152
           file.write("kmax = " + str(grid.kmax) + " \ ")
153
            file.write("lmax = " + str(grid.lmax) + "\n")
154
           file.write("mmax = " + str(grid.mmax) + "\n")
155
           file.write("nmax = " + str(grid.nmax) + "\n")
156
            file.write("allowed_points = " + str(grid.allowed_points) + "\n")
157
           file.write("disallowed_points = " + str(grid.disallowed_points) + "\n")
158
           file.write("run_time = " + str(grid.run_time) + "\n")
159
            file.write("cpu_time = " + str(grid.cpu_time) + "\n")
160
```

```
file.write("self.grid_table.append(Grid(kmax, lmax, mmax, nmax, allowed_points,
161
               disallowed_points, run_time, cpu_time))" + "\n")
       ,,,
162
       # Recoveres a table stored to a file.
163
       # Loads point_table's and grid_table's.
164
       def load_table(self, file_name):
165
166
         #exec(open(file_name + ".py").read())
         with open(file_name + ".py") as infile:
167
           for line in infile:
168
              exec(line)
169
170
171
172
       \# Searches table of grids for index matching the input key. Returns -1 if not found.
       def get_grid_index(self, key):
173
         for i in range(0, len(self.grid_table)):
174
           if self.grid_table[i].kmax == key[0] and self.grid_table[i].lmax == key[1] and self.
175
               grid_table[i].mmax == key[2] and self.grid_table[i].nmax == key[3]:
              return i
176
         return -1
177
178
       # Plots a single grid, specified by a key. Note grid must be in \mathsf{grid}_{-}\mathsf{table}.
179
       def plot_grid(self, key):
180
         grid = grid_table[self.get_grid_index(key)]
181
         allowed_sig = [points[0] for points in grid.allowed_points]
182
         allowed_eps = [points[1] for points in grid.allowed_points]
183
         disallowed_sig = [points[0] for points in grid.disallowed_points]
184
         disallowed_eps = [points[1] for points in grid.disallowed_points]
185
186
         # Plot a grid.
187
         plt.plot(allowed_sig, allowed_eps, 'r+')
188
         plt.plot(disallowed_sig, disallowed_eps, 'b+')
189
         plt.title('kmax : ' + grid.kmax.__str__() + " " +
190
              'lmax : ' + grid.lmax.__str__() + " " +
191
192
              'mmax : ' + grid.mmax.__str__() + " " +
              'nmax : ' + grid.nmax.__str__())
193
194
       # Plots and saves a series of grids to an output PDF file.
195
       # Takes as input parameter values for which we want plotted grids, and the desired PDF file
196
           name.
       def plot_grids(self, keys, file_name, plots_per_page, grid_size):
197
         #tab = self.generate_table(keys)
198
199
         #table = [grid for grid in tab if grid.run_time != 0]
200
         table = self.grid_table
         pdf_pages = PdfPages(file_name + ".pdf")
201
202
         # Define the number of plots per page and the size of the grid board.
203
         nb_plots = len(table)
204
         # nb_plots_per_page = 6
205
         nb_pages = int(np.ceil(nb_plots / float(plots_per_page)))
206
         # grid_size=(3,2)
207
208
         # This will define which row of the grid we are on.
209
         row_index = 0
210
211
         # We go through each 'grid' in 'grid_table', generating a plot for each.
212
         for i in range(nb_plots):
213
           # To begin, declare a new figure / page if we have exceeded limit of the last page.
214
           if i % plots_per_page == 0:
215
```

```
216
             fig = plt.figure(figsize=(8.27, 11.69), dpi=100)
217
           # Now, add a plot for the current grid on the grid board.
218
           plt.subplot2grid(grid_size, (row_index, i % grid_size[1]))
219
           if i % grid_size[1] == 1:
220
              row_index += 1
221
222
           # Handle our data. Retrieve isolated points for plotting from our input grid_table of Grid
223
               objects.
           allowed_sig = [points[0] for points in table[i].allowed_points]
224
           allowed_eps = [points[1] for points in table[i].allowed_points]
225
           disallowed_sig = [points[0] for points in table[i].disallowed_points]
226
227
           disallowed_eps = [points[1] for points in table[i].disallowed_points]
228
           # Plot a grid.
229
           # if table[i].run_time != 0 and table[i].cpu_time != 0:
230
           plt.plot(allowed_sig, allowed_eps, 'r+')
231
           plt.plot(disallowed_sig, disallowed_eps, 'b+')
232
233
           plt.title('[' + table[i].kmax.__str__() + ", "
                 + table[i].lmax.__str__() + ", "
234
                 + table[i].mmax.__str__() + ", "
235
                  + table[i].nmax.__str__() + ']'
236
                  + "
                          " + time.strftime('%H:%M:%S', table[i].run_time))
237
238
           #else:
           # plt.plot(allowed_sig, allowed_eps, 'r+')
239
           # plt.plot(disallowed_sig, disallowed_eps, 'b+')
240
           # plt.title('[' + table[i].kmax.__str__() + ", "
241
242
                    + table[i].lmax.__str__() + ", "
                    + table[i].mmax.__str__() + ", "
           #
243
                    + table[i].nmax.__str__() + ']'
244
                    + " " + "AUTOFILLED")
245
           #plt.title('kmax : ' + table[i].kmax.__str__() + " " +
246
                'lmax : ' + table[i].lmax.__str__() + " " +
247
           #
           #
                'mmax : ' + table[i].mmax.__str__() + " " +
248
                'nmax : ' + table[i].nmax.__str__())
249
250
           # If we have filled a page, or have reached the end of our plots, tight-pack and save the
251
           if (i + 1) % plots_per_page == 0 or (i + 1) == nb_plots:
252
              plt.tight_layout()
253
              pdf_pages.savefig(fig)
254
255
              row_index = 0
256
257
         pdf_pages.close()
258
       # Returns a key or list of keys generated by the input parameter ranges.
259
       def generate_keys(self, kmax_range, lmax_range, mmax_range, nmax_range):
260
         if type(kmax_range) == int:
261
           kmax_range = [kmax_range]
262
         if type(lmax_range) == int:
263
           lmax_range = [lmax_range]
264
         if type(mmax_range) == int:
265
266
           mmax_range = [mmax_range]
         if type(nmax_range) == int:
267
268
           nmax_range = [nmax_range]
         keys = []
269
         for kmax in kmax_range:
270
           for lmax in lmax_range:
271
```

```
272
              for mmax in mmax_range:
273
                for nmax in nmax_range:
                  key = [kmax, lmax, mmax, nmax]
274
                  keys.append(key)
275
         return keys
276
277
278
       # Generates a subtable table of desired, already determined grids from main table.
279
       # Gives a warning message if a grid isn't found.
       def generate_table(self, keys):
280
         # table to store the resulting grids.
281
         table = []
282
         for key in keys:
283
284
           if self.get_grid_index(key) == -1:
             print("Grid at kmax = " + str(key[0]) + ", " +
285
                "lmax = " + str(key[1]) + ", " +
286
                "mmax = " + str(key[2]) + ", " +
287
                "nmax = " + str(key[3]) + ", " + "does not exist.")
288
           else:
289
290
              table.append(self.grid_table[self.get_grid_index(key)])
291
         return table
292
293
       # Takes two keys and returns a dictionary with the direction of every point.
294
295
       def changes(self, key1, key2):
         changes = \{\}
296
         allowed_one = self.grid_table[self.get_grid_index(key1)].allowed_points
297
         allowed_two = self.grid_table[self.get_grid_index(key2)].allowed_points
298
299
         for sig in self.sig_values:
300
           for eps in self.eps_values:
301
             if (sig, eps) in allowed_one and (sig, eps) in allowed_two:
302
303
                changes[(sig, eps)] = 0
             if (sig, eps) not in allowed_one and (sig, eps) not in allowed_two:
304
                changes[(sig, eps)] = 0
305
             if (sig, eps) in allowed_one and (sig, eps) not in allowed_two:
306
307
                changes[(sig, eps)] = -1
              if (sig, eps) not in allowed_one and (sig, eps) in allowed_two:
308
                changes[(sig, eps)] = 1
309
         return changes
310
311
       # grid_size is a tuple of (rows, columns).
312
313
       def plot_changes(self, keys, file_name, plots_per_page, grid_size):
         pdf_pages = PdfPages(file_name + ".pdf")
314
315
         # Define the number of plots per page and the size of the grid board.
316
         # We have one less plots than grids.
317
         nb_plots = len(keys)
318
         # nb_plots_per_page = 6
319
         nb_pages = int(np.ceil(nb_plots / float(plots_per_page)))
320
         # grid_size=(3,2)
321
322
         # This will define which row of the grid we are on.
323
         row_index = 0
324
325
326
         # We go through each 'grid' in 'grid_{-}table', generating a plot for each.
         for i in range(nb_plots):
327
           # To begin, declare a new figure / page if we have exceeded limit of the last page.
328
           # 8.27 x 11.69 dimensions of A4 page in inches. DPI - dots per inch (resolution.)
329
```

```
330
           if i % plots_per_page == 0:
331
              fig = plt.figure(figsize=(8.27, 11.69), dpi=100)
332
           # Now, add a plot for the current grid on the grid board.
333
           plt.subplot2grid(grid_size, (row_index, i % grid_size[1]))
334
           if i % grid_size[1] == 1:
335
336
              row_index += 1
337
           # We want the first grid to compare all changes to.
338
           if i == 0:
339
             grid = self.grid_table[self.get_grid_index(keys[i])]
340
             allowed_sig = [points[0] for points in grid.allowed_points]
341
342
             allowed_eps = [points[1] for points in grid.allowed_points]
              disallowed_sig = [points[0] for points in grid.disallowed_points]
343
              disallowed_eps = [points[1] for points in grid.disallowed_points]
344
345
             # Plot the arid.
346
              plt.plot(allowed_sig, allowed_eps, 'r+')
347
348
             plt.plot(disallowed_sig, disallowed_eps, 'b+')
             #plt.title('kmax : ' + grid.kmax.__str__() + " " +
349
                  'lmax : ' + grid.lmax.__str__() + " " +
350
                  'mmax : ' + grid.mmax.__str__() + " " +
351
                  'nmax : ' + grid.nmax.__str__())
352
353
              if table[i].run_time != 0 and table[i].cpu_time != 0:
                plt.plot(allowed_sig, allowed_eps, 'r+')
354
                plt.plot(disallowed_sig, disallowed_eps, 'b+')
355
                plt.title('[' + table[i].kmax.__str__() + ", "
356
357
                      + table[i].lmax.__str__() + ",
                      + table[i].mmax.__str__() + ",
358
                      + table[i].nmax.__str__() + ']'
359
                               " + time.strftime('%H:%M:%S', table[i].run_time))
360
             #else:
361
             # plt.plot(allowed_sig, allowed_eps, 'r+')
362
             # plt.plot(disallowed_sig, disallowed_eps, 'b+')
363
             # plt.title('[' + table[i].kmax.__str__() + ", "
364
                      + table[i].lmax.__str__() + ", "
365
                      + table[i].mmax.__str__() + ", "
             #
366
             #
                      + table[i].nmax.__str__() + ']'
367
                      + " " + "AUTOFILLED")
368
369
             y_range = plt.ylim()
370
             x_range = plt.xlim()
371
372
373
           else:
              changes = self.changes(keys[i-1], keys[i])
374
              unchanged_points = []
375
              to_allowed_points = []
376
              to_disallowed_points = []
377
378
              for point in changes:
                if changes[point] == 0:
379
                  unchanged_points.append(point)
380
                if changes[point] == 1:
381
382
                  to_allowed_points.append(point)
383
                if changes[point] == -1:
384
                  to_disallowed_points.append(point)
385
              unchanged_sig = [points[0] for points in unchanged_points]
386
              unchanged_eps = [points[1] for points in unchanged_points]
387
```

```
to_disallowed_sig = [points[0] for points in to_disallowed_points]
388
389
             to_disallowed_eps = [points[1] for points in to_disallowed_points]
             to_allowed_sig = [points[0] for points in to_allowed_points]
390
             to_allowed_eps = [points[1] for points in to_allowed_points]
391
392
             # Plot a grid.
393
394
             plt.plot(to_allowed_sig, to_allowed_eps, 'r+')
             plt.plot(to_disallowed_sig, to_disallowed_eps, 'b+')
395
             plt.xlim(x_range)
396
             plt.ylim(y_range)
397
             plt.title('kmax : ' + self.grid_table[self.get_grid_index(keys[i])].kmax.__str__() + " "
398
399
                  'lmax : ' + self.grid_table[self.get_grid_index(keys[i])].lmax.__str__() + " " +
                  'mmax : ' + self.grid_table[self.get_grid_index(keys[i])].mmax.__str__() + " " +
400
                  'nmax : ' + self.grid_table[self.get_grid_index(keys[i])].nmax.__str__())
401
402
           # If we have filled a page, or have reached the end of our plots, tight-pack and save the
403
               page.
           if (i + 1) % plots_per_page == 0 or (i + 1) == nb_plots:
404
             plt.tight_layout()
405
             pdf_pages.savefig(fig)
406
407
             row_index = 0
408
409
         pdf_pages.close()
410
     class SingleCorrelator(Ising):
411
       bootstrap.cutoff=1e-10
412
413
       def __init__(self, dim = 3, gap = 3, sig_values = sig_defaults, eps_values = eps_defaults):
         self.dim = dim
414
415
         self.gap = gap
         self.sig_values = sig_values
416
417
         self.eps_values = eps_values
         self.grid_table = []
418
419
         self.grid_file = "grid_saves"
420
421
       # Determines allowed and disallowed scaling dimensions for whatever the parameters are.
       def determine_grid(self, key):
422
         #if self.get_grid_index(key) != -1:
423
         start_time=time.time()
424
         start_cpu=time.clock()
425
         tab1 = bootstrap.ConformalBlockTable(self.dim, *key)
426
427
         tab2 = bootstrap.ConvolvedBlockTable(tab1)
428
429
         # Instantiate a Grid object with appropriate input values.
         # grid=Grid(*key, [], [])
430
         grid = Grid(*(key + [[], [], 0, 0]))
431
432
         for sig in self.sig_values:
433
434
           for eps in self.eps_values:
             sdp = bootstrap.SDP(sig, tab2)
435
             # SDPB will naturally try to parallelize across 4 cores / slots.
436
             # To prevent this, we set its 'maxThreads' option to 1.
437
             # See 'common.py' for the list of SDPB option strings, as well as their default values.
438
             sdp.set_option("maxThreads", 1)
439
             sdp.set_bound(0, float(self.gap))
440
             sdp.add_point(0, eps)
441
             result = sdp.iterate()
442
             if result:
443
```

```
444
               grid.allowed_points.append((sig, eps))
445
             else:
               grid.disallowed_points.append((sig, eps))
446
447
         # Now append this grid object to the IsingGap grid_table.
448
         # Note we will need to implement a look up table to retrieve desired data.
449
450
         end_time=time.time()
         end_cpu=time.clock()
451
         run_time=end_time-start_time
452
         cpu_time=end_cpu-start_cpu
453
         run_time = datetime.timedelta(seconds = int(end_time - start_time))
454
         cpu_time = datetime.timedelta(seconds = int(end_cpu - start_cpu))
455
456
         grid.run_time = run_time
457
         grid.cpu_time = cpu_time
458
459
         self.grid_table.append(grid)
460
         grid.save(self.grid_file)
         #self.save_grid(grid, self.name)
461
462
     # For mixed correlator, we pass pairs of external scaling dimensions to the SDP.
463
     # We copy the content of the triples entering the SDP from the tutorial, same case.
464
     # We want to scan over all possible [sig, eps], assuming only one relevant Z2-even and Z2-odd
465
         operator.
     # Use a protoype to use the same basis for all SDPs, so we don't need to recaculate bases.
466
     # Dump the ConformalBlockTable objects once we have used them to save memory.
467
     # Set dualThresholdError to 1e-15.
468
     # Use 16 cores for all SDP runs - set maxThreads = 16, speed up the SDP.
469
470
     class MixedCorrelator(Ising):
       bootstrap.cutoff=0
471
472
       def _{-init_{-}}(self, dim = 3):
         self.dim = dim
473
474
         self.point_table = []
475
         self.grid_table = []
476
         self.grid_file = "grid_saves"
         self.point_file = "point_saves"
477
478
       # Determines allowed and disallowed scaling dimensions for whatever the parameters are.
479
       def determine_points(self, key, row):
480
       # Will be called with a given row_lists[i]
481
         # row = row_lists[row_index]
482
         reference_sdp = None
483
         blocks_initiated = False
484
         for i in range(len(row[0])):
485
           sig = row[0][i]
486
           eps = row[1][i]
487
488
489
           qlobal start_time
           start_time = time.time()
490
491
           global start_cpu
           start_cpu = time.clock()
492
           # Generate three conformal block tables, two of which depend on the dimension differences.
493
           # They need only be calculated once for any given diagonal. They remain constant along this
494
                line.
           # Uses the function above to return the 5 ConvolvedConformalBlocks we need.
495
           # The ConvolvedConformalBlock objects inherits the dimension differences from
496
               ConformalBlockTable.
           # We set odd_spins = True for odd those ConvolvedConformalBlocks appearing in odd-sector-
497
               odd-spins.
```

```
# We set symmetric = True where required.
498
499
                  if blocks_initiated == False:
                      g_tab1 = bootstrap.ConformalBlockTable(self.dim, *key)
500
                     g_tab2 = bootstrap.ConformalBlockTable(self.dim, *(key + [eps-sig, sig-eps, "odd_spins =
501
                      g_{tab} = bootstrap.ConformalBlockTable(self.dim, *(key + [sig-eps, sig-eps, "odd_spins = bootstrap.ConformalBlockTable(self.dim, sig-eps, sig-ep
502
                           True"]))
                     tab_list = self.convolved_table_list(g_tab1, g_tab2, g_tab3)
503
                      for tab in [g_tab1, g_tab2, g_tab3]:
504
                         tab.dump("tab_" + str(tab.delta_12) + "_" + str(tab.delta_34))
505
                         del tab
506
                     blocks_initiated = True
507
508
                  global now
                  global now_clock
509
                  global CB_time
510
                  global CB_cpu
511
512
                  now = time.time()
                  now_clock = time.clock()
513
514
                  CB_time = datetime.timedelta(seconds = int(now - start_time))
                  CB_cpu = datetime.timedelta(seconds = int(now_clock - start_cpu))
515
                  print("The calculation of the required conformal blocks has successfully completed.")
516
517
                  print("Time taken: " + str(CB_time))
                  print("CPU_time: " + str(CB_cpu))
518
                  # N.B vec3 & vec2 are 'raw' quads, which will be converted to 1x1 matrices automatically.
519
                  # Third vector: 0, 0, 1 * table4 with one of each dimension, -1 * table2 with only pair[0]
520
                        dimensions, 1 * table3 with only pair[0] dimensions
                  vec3 = [[0, 0, 0, 0], [0, 0, 0, 0], [1, 4, 1, 0], [-1, 2, 0, 0], [1, 3, 0, 0]]
521
522
                  \# Second vector: 0, 0, 1 * table4 with one of each dimension, 1 * table2 with only pair[0]
                        dimensions, -1 * table3 with only pair[0] dimensions
                  vec2 = [[0, 0, 0, 0], [0, 0, 0, 0], [1, 4, 1, 0], [1, 2, 0, 0], [-1, 3, 0, 0]]
523
                  # The first vector has five components as well but they are matrices of quads, not just the
524
                          quads themselves.
                  m1 = [[[1, 0, 0, 0], [0, 0, 0, 0]], [[0, 0, 0, 0], [0, 0, 0, 0]]]
525
                  m2 = [[[0, 0, 0, 0], [0, 0, 0, 0]], [[0, 0, 0, 0], [1, 0, 1, 1]]]
526
                  m3 = [[[0, 0, 0, 0], [0, 0, 0, 0]], [[0, 0, 0, 0], [0, 0, 0, 0]]]
527
                  m4 = [[[0, 0, 0, 0], [0.5, 0, 0, 1]], [[0.5, 0, 0, 1], [0, 0, 0, 0]]]
528
                  m5 = [[[0, 1, 0, 0], [0.5, 1, 0, 1]], [[0.5, 1, 0, 1], [0, 1, 0, 0]]]
529
                  vec1 = [m1, m2, m3, m4, m5]
530
531
                  # The first rep must be the singlet even channel, where the unit operator resides.
532
                  # After this, the order doesn't matter.
533
                  # Spins for these again go even, even, odd.
534
                  # The Z2 even sector has only even spins, Z2 odd sector runs over even and odd spins.
535
                  info = [[vec1, 0, "z2-even-l-even"], [vec2, 0, "z2-odd-l-even"], [vec3, 1, "z2-odd-l-odd"]]
536
537
                  # We instantiate the SDP object, inputting our vectorial sum info.
538
                  # dim_list, convolved_block_table_list, vector_types (how they combine to compose sum rule)
539
                  # We use the first calculated SDP object as a prototype for all the rest.
540
                  # This is because some bounds remain unchanged, no need to recalculate basis.
541
                  # Basis is independent of external scaling dimensions, cares only of the bounds on
542
                        particular operators.
543
                  # sdp = bootstrap.SDP([sig, eps], tab_list, vector_types = info)
544
                  if reference_sdp == None:
                      sdp = bootstrap.SDP([sig, eps], tab_list, vector_types = info)
545
                      reference_sdp = sdp
546
                  else:
547
                      sdp = bootstrap.SDP([sig, eps], tab_list, vector_types = info, prototype = reference_sdp)
548
```

```
549
550
           # We assume the continuum in both Z2 odd / even sectors begins at the dimension=3.
           sdp.set_bound([0, "z2-even-l-even"], self.dim)
551
           sdp.set_bound([0, "z2-odd-l-even"], self.dim)
552
553
           # Except for the two lowest dimension scalar operators in each sector.
554
555
           sdp.add_point([0, "z2-even-l-even"], eps)
           sdp.add_point([0, "z2-odd-l-even"], sig)
556
557
           # We expect these calculations to be computationally intensive.
558
           # We set maxThreads=16 to parallelise SDPB for all runs.
559
           # See 'common.py' for the list of SDPB option strings, as well as their default values.
560
           sdp.set_option("maxThreads", 16)
561
           sdp.set_option("dualErrorThreshold", 1e-15)
562
           sdp.set_option("maxIterations", 1000)
563
564
           # Run the SDP to determine if the current operator spectrum is permissable.
565
           print("Testing point " + "(" + sig.__str__() + ", " + eps.__str__() +")...")
566
567
           result = sdp.iterate()
           end_time = time.time()
568
           end_cpu = time.clock()
569
570
           global sdp_time
           global sdp_cpu
571
572
           sdp_time = datetime.timedelta(seconds = int(end_time - bootstrap.now2))
           sdp_cpu = datetime.timedelta(seconds = int(end_cpu - bootstrap.now2_clock))
573
           run_time = datetime.timedelta(seconds = int(end_time - start_time))
574
           cpu_time = datetime.timedelta(seconds = int(end_cpu - start_cpu))
575
576
           print("The SDP has finished running.")
577
           print("Time taken: " + str(sdp_time))
578
           print("CPU_time: " + str(sdp_cpu))
579
           print("See point file for more information. Check the times are consistent")
580
581
           point = Point(*([sig, eps] + key + [result, run_time, cpu_time, CB_time, CB_cpu, bootstrap.
582
               xml_time, bootstrap.xml_cpu, sdp_time, sdp_cpu]))
           self.point_table.append(point)
583
           point.save(self.point_file)
584
           #self.save_point(point, self.name)
585
586
       # Determines a full grid of Points.
587
       # Appends the Points to point_table and the Grid to qrid_table.
588
       def determine_grid(self, key):
589
         #if self.get_grid_index(key) != -1:
590
591
         #start_time=time.time()
         #start_cpu=time.clock()
592
593
594
         grid = Grid(*(key + [[], [], 0, 0]))
595
596
         self.determine_points(key)
597
         # end_time=time.time()
598
         # end_cpu=time.clock()
599
         # run_time = datetime.timedelta(seconds = int(end_time - start_time))
600
         # cpu_time = datetime.timedelta(seconds = int(end_cpu - start_cpu))
601
602
         points = [points for points in self.point_table if [points.kmax, points.lmax, points.mmax,
603
             points.nmax] == key]
         for point in points:
604
```

```
605
           grid.run_time += point.run_time
           grid.cpu_time += point.cpu_time
606
           if point.allowed == True:
607
             grid.allowed_points.append((point.sig, point.eps))
608
           else:
609
             grid.disallowed_points.append((point.sig, point.eps))
610
611
         # grid.run_time = run_time
612
         # grid.cpu_time = cpu_time
613
         self.grid_table.append(grid)
614
         # self.save_grid(grid, self.name)
615
616
617
       # A method for composing a whole grid from a set of 'raw' points.
       # Allows more flexability - can choose sets of disparate points or use parallelization.
618
       def make_grid(self, key):
619
         grid = Grid(*(key + [[], [], 0, 0]))
620
         points = [points for points in self.point_table if [points.kmax, points.lmax, points.mmax,
621
             points.nmax] == key]
622
         for point in points:
           grid.run_time += point.run_time
623
           grid.cpu_time += point.cpu_time
624
625
           if point.allowed == True:
             grid.allowed_points.append((point.sig, point.eps))
626
627
           else:
             grid.disallowed_points.append((point.sig, point.eps))
628
629
       # A function used for the multi-correlator 3D Ising example.
630
631
       # Note default is antisymmetrised convolved conformal blocks.
       def convolved_table_list(self, tab1, tab2, tab3):
632
         f_tabla = bootstrap.ConvolvedBlockTable(tab1)
633
         f_tab1s = bootstrap.ConvolvedBlockTable(tab1, symmetric = True)
634
         f_tab2a = bootstrap.ConvolvedBlockTable(tab2)
635
         f_tab2s = bootstrap.ConvolvedBlockTable(tab2, symmetric = True)
636
         f_tab3 = bootstrap.ConvolvedBlockTable(tab3)
637
         return [f_tabla, f_tabls, f_tab2a, f_tab2s, f_tab3]
638
639
       # Returns the number of points that will be calculated for given sig,eps ranges and step sizes.
640
       def points(self):
641
         return ((self.sig_range[1] - self.sig_range[0])/self.sig_step) * ((self.eps_range[1] - self.
642
             eps_range[0])/self.eps_step)
643
       # Saves a Point object' data to file named in self.name
644
       def save_point(self, point, name):
645
         with open(name + ".py", 'a') as file:
646
           file.write("kmax = " + str(point.kmax) + "\n")
647
           file.write("lmax = " + str(point.lmax) + "\n")
648
           file.write("mmax = " + str(point.mmax) + " \ n")
649
           file.write("nmax = " + str(point.nmax) + "\n")
650
           file.write("sig = " + str(point.sig) + "\n")
651
           file.write("eps = " + str(point.eps) + "\n")
652
           file.write("allowed = " + str(point.allowed) + "\n")
653
           file.write("run_time = " + str(point.run_time) + "\n")
654
           file.write("cpu_time = " + str(point.cpu_time) + "\n")
655
           file.write("self.point_table.append(Point(kmax, lmax, mmax, nmax, sig, eps, run_time,
656
               cpu_time))" + "\n")
657
       # Recoveres a table of Point objects stored to a file.
658
       def recover_points(self, file_name):
659
```

```
with open(file_name + ".py") as infile:
for line in infile:
    exec(line)
#exec(open(file_name + ".py").read())
```