

COMP3702 Artificial Intelligence

Tutorial 1: Introduction

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CREATE CHANGE

Dimensions of complexity in agent design

From P&M Ch 1.5:

Dimension	Values
Modularity:	flat, modular, hierarchical
Planning horizon:	non-planning, finite stage, indefinite stage, infinite stage
Representation:	states, features, relations
Computational limits:	perfect rationality, bounded rationality
Learning:	knowledge is given, knowledge is learned
Sensing uncertainty:	fully observable, partially observable
Effect uncertainty:	deterministic, stochastic
Preference:	goals, complex preferences
Number of agents:	single agent, multiple agents
Interaction:	offline, online

Agent Design

To solve an **agent design problem**, the following components are required:

- Action Space (A): The set of all possible actions the agent can perform (sometimes
 called the action set in the discrete case). An action is denoted a ∈ A.
- Percept Space (P): The set of all possible things the agent can perceive.
- State Space (S): The set of all possible configurations of the world the agent is operating
 in (sometimes called the set of states in discrete state systems). A state is denoted s ∈ S.
- World Dynamics/Transition Function (T: S × A → S'): A function that specifies how
 the world changes when the agent performs actions in it; a system model. We sometimes
 write T(s, a) = s'.
- **Perception Function** $(Z: S \rightarrow P)$: A function that maps a world state to a perception.
- Utility Function $(U: S \to \mathbb{R})$: A function that maps a state (or a sequence of states) to a real number, indicating how desirable it is for the agent to occupy that state/sequence of states. We sometimes write U(s) = some cost or reward.

Exercise 1.1 - Tic-Tac-Toe

- Action Space Place element in position $\{i \mid i \in Z, i \in [0,9)\}$
- Percept Space All placed elements
- State Space All combinations of elements placed
- Transition Function Given a state S and performing an action A results in a new state S'. e.g. $S(000000000) \times A(X,(1,1)) = S'(0000X0000)$
- Utility Function
 - Can be 0 random
 - Can be the number of ways we can still win

Exercise 1.2 - Navigation App

- Action Space Given a set of all roads, select road and tell user direction
- Percept Space Map data, not traffic or pedestrians
- State Space (x,y) coordinates where $x, y \in R$
- Transition Function $S(x,y) \times Direction(\overrightarrow{x'},\overrightarrow{y'}) = S'(x',y')$
- Utility Function Each state (x,y) euclidean distance from destination, so utility function is –(distance to destination). This is informed search, more in coming tutorials.

Exercise 1.2 - Navigation App

- Agent can be discrete or continuous
 - Intersections Discrete
 - Real world coordinates Continuous
- Agent is non-deterministic, the agent can only 'tell' the driver what to do, there is no guarantee the driver will do it:P
- GPS gives fully observable map data traffic and pedestrians are not observable
- Agent is dynamic There are external processes operating on the agent

Exercise 1.3 - Web Crawler

- Action Space Find links and crawl
- Percept Space Text within the set of all links collected
- State Space All the links on the internet
- Transition Function Given a new link, select it, finding new links and adding them to collection
- Utility Function +1 for new link found

Exercise 1.4 - Poker Bot

- Action Space Check, Call, Raise, Fold
- Percept Space The agents 2 cards and the cards shown in each stage
- State Space It can get complicated, try all the following
 - All combinations of cards for each player including shown cards
 - All combinations of current and previous bets from all players
 - All combinations of total chips for each player and in pot
- Transition Function Given current state S of (cards,chips,bets..etc), perform action (Check, Call, Raise, Fold), to arrive to a new state S', where everyone folds and you win all the chips.
- Utility Function
 - +X for winning where X is the total pot
 - ullet +5 for an opponent that folds
 - $\bullet\ +10$ for hitting a card that improves your hand