# Assignment Four

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## 1 Entropy and Mutual Information

Let X be a discrete random variable on a finite space  $\mathcal{X}$  with  $|\mathcal{X}| = k$ .

1. (a) Prove that the entropy  $H(X) \geq 0$ , with equality only when X is a constant.

PROOF: WLOG we can assume that  $p(x) > 0 \ \forall x \in \mathcal{X}$ , (using that  $0 \cdot log0 = 0$ ). We have that  $H(X) = -\sum_{x} p(x) log p(x) = \sum_{x} p(x) log p(x)^{-1} \ge 0$ , since p(x) > 0 and  $p(x)^{-1} \ge 1$ . If H(X) = 0 then  $\exists \alpha$  such that  $p(\alpha)^{-1} = 1 \Rightarrow p(\alpha) = 1$ . Hence X must be a constant, as needed.

(b) Let  $X \sim p$  and q be the Uniform distribution on  $\mathcal{X}$ . What is the relation between D(p||q) and H(X).

CLAIM: D(p||q) = -H(X) + logkPROOF:

$$D(p||q) = \sum_{x} p(x)log \frac{p(x)}{q(x)}$$

$$= \sum_{x} p(x)log p(x) - \sum_{x} p(x)log q(x)$$

$$= -H(X) + \sum_{x} p(x)log k$$

$$= -H(x) + log k$$

(c) An upper bound for H(X) is log k since  $H(X) = log k - D(p||q) \Rightarrow H(X) \leq log k$ .

We consider a pair of discrete random variables  $(X_1, X_2)$  defined over the finite set  $\mathcal{X}_1 \times \mathcal{X}_2$ . Let  $p_{1,2}$ ,  $p_1$  and  $p_2$  denote respectively the joint distribution, the marginal distribution of  $X_1$  and the marginal distribution of  $X_2$ . Define the mutual information as:

$$I(X_1, X_2) = \sum_{(x_1, x_2) \in \mathcal{X}_1 \times \mathcal{X}_2} p_{1,2}(x_1, x_2) \log \frac{p_{1,2}(x_1, x_2)}{p_1(x_1)p_2(x_2)}$$

We again assume WLOG that  $p(x_1, x_2) > 0 \ \forall (x_1, x_2) \in \mathcal{X}_1 \times \mathcal{X}_2$ 

- 2. (a) CLAIM:  $I(X_1,X_2) \ge 0$  PROOF: Notice that  $I(X_1,X_2) = D(p_{1,2}||p_1p_2) \ge 0$  by the positiveness of
  - (b) We want to express  $I(X_1, X_2)$  as a function of  $H(X_1), H(X_2)$  and  $H(X_1, X_2)$ .

$$\begin{split} I(X_1,X_2) &= \sum_{(x_1,x_2) \in \mathcal{X}_1 \times \mathcal{X}_2} p_{1,2}(x_1,x_2) log \frac{p_{1,2}(x_1,x_2)}{p_1(x_1)p_2(x_2)} \\ &= \sum_{(x_1,x_2) \in \mathcal{X}_1 \times \mathcal{X}_2} p_{1,2}(x_1,x_2) log p_{1,2}(x_1,x_2) - p_{1,2}(x_1,x_2) log p_1(x_1) p_2(x_2) \\ &= -H(X_1,X_2) - \sum_{(x_1,x_2) \in \mathcal{X}_1 \times \mathcal{X}_2} \left( p_1(x_1)p_2(x_2) log p_1(x_1) - p_1(x_1)p_2(x_2) log p_2(x_2) \right) \\ &= -H(X_1,X_2) - \sum_{j=1}^2 \sum_{(x_1,x_2) \in \mathcal{X}_1 \times \mathcal{X}_2} p_1(x_1)p_2(x_2) log p_j(x_j) \\ &= -H(X_1,X_2) - \sum_{j=1}^2 \sum_{x_j \in \mathcal{X}_j} p_j(x_j) log p_j(x_j) \\ &= -H(X_1,X_2) + H(X_1) + H(X_2) \end{split}$$

And so we can represent  $I(X_1, X_2)$  using  $H(X_1), H(X_2)$  and  $H(X_1, X_2)$ , as needed.

(c) From the previous result we have that  $I(X_1, X_2) \geq 0 \Rightarrow H(X_1) + H(X_2) \geq H(X_1, X_2)$ , and so the maximal entropy of  $(X_1, X_2)$  is  $H(X_1) + H(X_2)$ . By definition this only occurs when  $I(X_1, X_2) = 0$ , which only occurs if  $p_{1,2}(x_1, x_2) = p_1(x_1)p_2(x_2) \ \forall x_1, x_2 \in \mathcal{X}_1 \times \mathcal{X}_2$ . This can be seen directly from the definition of I and using the strict positivity of  $p(x_1, x_2)$ .

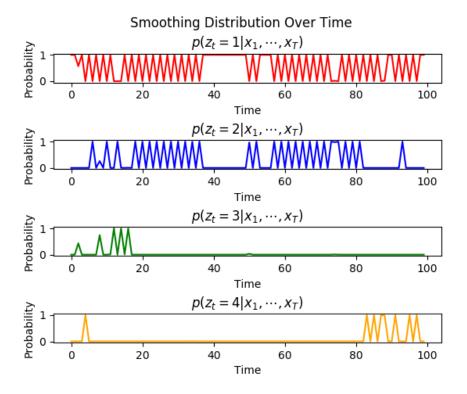


Figure 2.1: The smoothing distribution for the first 100 time points.

## 2 HMM - Implementation

We use an HMM model to account for the possible temporal structure of some data. We consider the following HMM model: the chain  $(z_t)_{t=1}^T$  has K=4 possible states, with an initial probability distribution  $\pi \in \Delta_4$  and a probability transition matrix  $A \in \mathbb{R}^{4\times 4}$  where  $A_{ij} = p(z_t = i|z_{t-1} = j)$  and conditionally on the current state  $z_t$ , we have observations obtained from Gaussian emission probabilities  $x_t|(z_t = k) \sim N(x_t|\mu_k, \Sigma_k)$ .

### 2.1 Fake Parameters Inference

We computed the vectors  $\alpha(z_t) = p(z_t, x_{1:t})$  and  $\beta(z_t) = p(x_{(t+1):T}|z_t)$  on the test set from Assignment 3 using the following parameters:  $\pi_k = \frac{1}{4}$ ,  $A_{ii} = \frac{1}{2}$  and  $A_{ij} = \frac{1}{6}$ ,  $i \neq j$ , and  $\mu_k, \Sigma_k$  as defined in the homework. We used these to compute the posterior of the latent variable over time  $p(z_t \mid x_1, \dots, x_T)$ . We plotted the first 100 datapoints in figure 2.1.

### 2.2 M-Step Derivation

We now derive the M-Step for the Hidden Markov Model. Let  $\theta^{(s)}=(\pi^{(s)},A^{(s)},\mu_1^{(s)},\cdots,\mu_K^{(s)},\Sigma_1^{(s)},\cdots,\Sigma_K^{(s)})$  be the ML parameters learned during

step s of EM. Let  $\gamma_{tk} = P(z_t = k|x_{1:T})$  and  $\xi_{tlm} = P(z_t = l, z_{t+1} = m|x_{1:T})$  - which are the quantities that were computed in the E-Step using  $\theta^{(s)}$ . The Expected Complete Data Log-Likelihood (at step s+1) is:

$$Q(\theta, \theta^{(s)}) = \sum_{k=1}^{K} \gamma_{tk} log \pi_k + \sum_{t=1}^{T} \sum_{k=1}^{K} \gamma_{tk} P(\bar{x}_t | \mu_k, \Sigma_k) + \sum_{t=1}^{T-1} \sum_{l=1}^{K} \sum_{m=1}^{K} \xi_{tlm} log A_{lm}$$
 (2.1)

To solve for  $\pi_k$  we look for stationary points, subject to the constraint  $\sum_{k=1}^K \pi_k = 1$ 

$$\frac{\partial}{\partial \pi_k} Q(\theta, \theta^{(s)}) - \lambda \left( \sum_{k=1}^K \pi_k - 1 \right) = \frac{\gamma_{1k}}{\pi_k} - \lambda = 0 \tag{2.2}$$

$$\Rightarrow \pi_k = \frac{\gamma_{1k}}{\lambda} \tag{2.3}$$

And using that  $\sum_{k=1}^{K} \pi_k = 1$  we have that:

$$\pi_k^{(s+1)} = \frac{\gamma_{1k}}{\sum_{l=1}^K \gamma_{1l}} \tag{2.4}$$

To solve for  $A_{lm}$  we look for stationary points, subject to the constraint  $\sum_{l=1}^{K} A_{lm} = 1$ 

$$\frac{\partial}{\partial A_{lm}}Q(\theta,\theta^{(s)}) - \lambda \left(\sum_{l=1}^{K} A_{lm} - 1\right) = \sum_{t=1}^{T-1} \frac{\xi_{tlm}}{A_{lm}} - \lambda = 0$$
(2.5)

$$\Rightarrow A_{lm} = \frac{\sum_{t=1}^{T-1} \xi_{tlm}}{\lambda} \tag{2.6}$$

And using that  $\sum_{l=1}^{K} A_{lm} = 1$  we have that:

$$A_{lm}^{(s+1)} = \frac{\sum_{t=1}^{T-1} \xi_{tlm}}{\sum_{t=1}^{K} \sum_{t=1}^{T-1} \xi_{tlm}}$$
(2.7)

To solve for  $\mu_k$  we look for stationary points

$$\frac{\partial}{\partial \mu_k} Q(\theta, \theta^{(s)}) = \sum_{t=1}^{T} \frac{\partial}{\partial \mu_k} \frac{-\gamma_{tk}}{2} (\bar{x}_t - \mu_k)^T \Sigma_k^{-1} (\bar{x}_t - \mu_k)$$
(2.8)

$$= \sum_{t=1}^{T} \frac{-\gamma_{tk}}{2} (\bar{x}_t - \mu_k) \Sigma_k^{-1} = 0$$
 (2.9)

$$\Rightarrow \sum_{t=1}^{T-1} \gamma_{tk} (\bar{x}_t - \mu_k) = 0 \tag{2.10}$$

$$\Rightarrow \mu_k^{(s+1)} = \frac{\sum_{t=1}^{T} \gamma_{tk} \bar{x}_t}{\sum_{t=1}^{T-1} \gamma_{tk}}$$
 (2.11)

To solve for  $\Sigma_k$  we look for stationary points. As in assignment 1, we take the derivative w.r.t  $\Sigma_k^{-1}$ 

$$\frac{\partial}{\partial \Sigma_k^{-1}} Q(\theta, \theta^{(s)}) = \sum_{t=1}^T \frac{\partial}{\partial \mu_k} \left( \frac{-\gamma_{tk}}{2} log |\Sigma_k| - \frac{\gamma_{tk}}{2} \left( \bar{x}_t - \mu_k^{(s+1)} \right)^T \Sigma_k^{-1} \left( \bar{x}_t - \mu_k^{(s+1)} \right) \right)$$
(2.12)

Differentiating the first term yields

$$\frac{\partial}{\partial \Sigma_k^{-1}} \frac{-\gamma_{tk}}{2} log|\Sigma_k| = \frac{\partial}{\partial \Sigma_k^{-1}} \frac{\gamma_{tk}}{2} log|\Sigma_k^{-1}|$$
 (2.13)

$$=\frac{\gamma_{tk}}{2}\Sigma_k\tag{2.14}$$

Differentiating the second term yields

$$\frac{\partial}{\partial \Sigma^{-1}} \frac{\gamma_{tk}}{2} \left( \bar{x}_t - \mu_k^{(s+1)} \right)^T \Sigma_k^{-1} \left( \bar{x}_t - \mu_k^{(s+1)} \right) \tag{2.15}$$

$$= \frac{\partial}{\partial \Sigma^{-1}} \frac{\gamma_{tk}}{2} tr\left(\left(\bar{x}_t - \mu_k^{(s+1)}\right) \left(\bar{x}_t - \mu_k^{(s+1)}\right)^T \Sigma_k^{-1}\right)$$
(2.16)

$$= \frac{\gamma_{tk}}{2} \left( \bar{x}_t - \mu_k^{(s+1)} \right) \left( \bar{x}_t - \mu_k^{(s+1)} \right)^T$$
 (2.17)

Where (2.15) and (2.16) come from results proved in class and on Homework 1. After substituting (2.14) and (2.17) into (2.12) and equating to 0 we have that:

$$\sum_{t=1}^{T} \gamma_{tk} \Sigma_k = \sum_{t=1}^{T} \gamma_{tk} \left( \bar{x}_t - \mu_k^{(s+1)} \right) \left( \bar{x}_t - \mu_k^{(s+1)} \right)^T$$
 (2.18)

$$\Rightarrow \Sigma_k^{(s+1)} = \frac{\sum_{t=1}^T \gamma_{tk} (\bar{x}_t - \mu_k^{(s+1)}) (\bar{x}_t - \mu_k^{(s+1)})^T}{\sum_{t=1}^T \gamma_{tk}}$$
(2.19)