



UNDERSTANDING DEEP LEARNING REQUIRES RETHINKING GENERALIZATION

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Introduction

Main Question

What distinguishes Neural Networks that generalize well from those that don't?

- Capacity ?
- Regularization ?
- How we train the model?

Questions

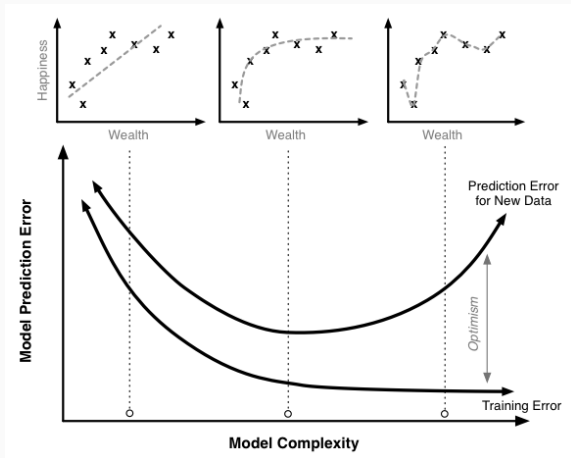


Figure 1: Traditional view of generalization. Image taken from [1]

Why do we care about the problem?

- Make neural networks more interpretable
- May lead to more principled and reliable model architecture design

Background

Statistical Learning Theory gives bounds on the Generalization Error using:

- VC Dimension
- Rademacher Complexity
- Uniform Stability

Theory suggests that some regularization helps (including Early Stopping)

In 2016 Hardt et al. gives an Upper bound on Generalization error on model using SGD using uniform stability [2]

BUT

Uniform stability is a property of a learning algorithm and is not affected by the labelling of the training data.

Main Message

Statistical Learning Theory is insufficient in that it cannot distinguish between neural networks with dramatically different generalization performance.

This is demonstrated in the paper [3]. The central finding:

Deep neural networks easily fit random labels

Results

Setup: trained several standard architectures on the data with various modifications:

1. True labels → No modifications
2. Random labels → randomly changed some labels
3. shuffled pixels → apply some fixed permutation of pixels to all images
4. Random pixels → apply some random permutation of pixels to all images
5. Gaussian → Generate pixels for all images from a Gaussian

Main Results

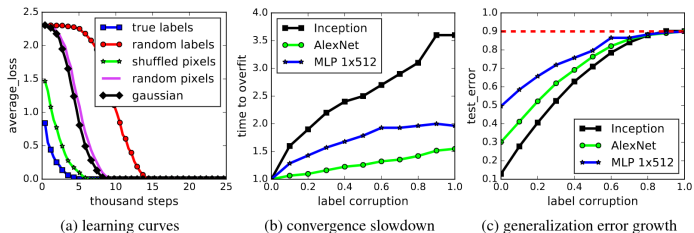


Figure 2: Fitting random labels and random pixels on CIFAR10.

In most cases, the training error went to zero while test error was high

Notice:

the model capacity, hyperparameters, and the optimizer remained the same!

Explicit regularization may improve generalization performance, but is neither necessary nor by itself sufficient for controlling generalization error

Table 4: Results on fitting random labels on the CIFAR10 dataset with weight decay and data augmentation.

| Model | Regularizer | Training Accuracy |
|-----------|------------------------------|--------------------|
| Inception | Weight decay | 100% |
| Alexnet | | Failed to converge |
| MLP 3x512 | | 100% |
| MLP 1x512 | | 99.21% |
| Inception | Random Cropping ¹ | 99.93% |
| | Augmentation ² | 99.28% |

Technical dive

Theorem

There exists a two-layer neural network with ReLU activations and $2n + d$ weights that can represent any function on a sample of size n in d dimensions.

Lemma 1

For any two interleaving sequences of n real numbers

$b_1 < x_1 < b_2 < x_2 \cdots < b_n < x_n$, the $n \times n$ matrix

$A = [\max\{x_i - b_j, 0\}]_{ij}$ has full rank. Its smallest eigenvalue is $\min_i \{x_i - b_i\}$

For weight vectors $w, b \in R^n$ and $a \in R^d$, consider the function $c : R^n \rightarrow R$,

$$c(x) = \sum_{j=1} w_j \max\{a^T x - bj, 0\}$$

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- This can be done trivially with a depth 2 neural network with relu.

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- Now, fixing a sample $S = z_1, \dots, z_n$ of size n and a target vector $y \in R_n$. We need to find weights a, b, w so that $y_i = c(z_i)$ for all $i \in \{1, \dots, n\}$

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- First, choose a and b such that with $x_i = a_i^T z_i$ we have the interleaving property $b_1 < x_1 < b_2 < \dots < b_n < x_n$. Next, consider the set of n equations in the n unknowns w ,

$$y_i = c(z_i), i \in \{1, \dots, n\}$$

We have $c(z_i) = Aw$, where $A = [\max\{x_i b_j, 0\}]_{ij}$ is the matrix of Lemma 1.

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- We chose a and b so that the lemma applies and hence A has full rank. We can now solve the linear system $y = Aw$ to find suitable weights w .

Discussion

Some Thoughts...

1. Our favourite papers are the ones that shed light on truths that are taken for granted.
2. Its obvious that randomizing the labels would eliminate generalizability, but finding precise mathematical statements about this is not!
3. The paper doesn't really make many conclusions of its own.
4. Models used in practice have the capability of memorizing the training data. Is it somehow easier not to?
5. The interplay between generalization and ease of optimization seems like an interesting thing to explore...

-  D. Sowinski, “What is generalization in machine learning?.” Post.
-  M. Hardt, B. Recht, and Y. Singer, “Train faster, generalize better: Stability of stochastic gradient descent,” *CoRR*, vol. abs/1509.01240, 2015.
-  C. Zhang, S. Bengio, M. Hardt, B. Recht, and O. Vinyals, “Understanding deep learning requires rethinking generalization,” *CoRR*, vol. abs/1611.03530, 2016.