Assignment Two

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1 Convolutions

We compute the full valid and same convolution with kernel flipping for the following matrices: [1, 2, 3, 4] * [1, 0, 2]

- The valid convolution is: $[1 \cdot 2 + 2 \cdot 0 + 3 \cdot 1, 2 \cdot 2 + 3 \cdot 0 + 4 \cdot 1] = [5, 8]$
- Likewise the same convolution is: [0, 1, 2, 3, 4, 0] * [1, 0, 2] = [2, 5, 8, 6]
- Finally the full convolution is: [0,0,1,2,3,4,0,0] * [1,0,2] = [1,2,5,8,6,8]

2 Convolutional Neural Networks

Consider a 3-layer CNN. We are given an input of size $3 \times 256 \times 256$. The first layer contains 64×8 kernels using a stride of 2 and no padding. The shape of its output is $64 \times 125 \times 125$ using relationship 6 from [1]:

output length =
$$\left| \frac{256 + 2 \cdot 0 - 8}{2} \right| + 1 = 125$$

The second layer subsamples this using 5×5 non-overlapping max pooling. It is easy to see that the size of its output is $64 \times 25 \times 25$, since $\frac{125}{5} = 25$. The final layer convolves $128 \ 4 \times 4$ kernels with a stride of 1 and a zero-padding of size 1 on each border. Using the formula we have that $\left\lfloor \frac{25+2\cdot 1-4}{1} \right\rfloor + 1 = 24$, and so the output of the last layer has shape $128 \times 24 \times 24$.

- (a) The output of the last layer will be of size: $128 \times 24 \times 24 = 73725$
- (b) Ignoring biases, we would need $64 \times 25 \times 25 \times 128 = 5120000$ weights

3 Kernel configuration for CNNs

We are given an input shape of $3 \times 64 \times 64$ and the output shape is $64 \times 32 \times 32$ for a convolutional layer.

(a) Assuming no dilation and kernel size of 8×8 , we can solve for the stride length s and the padding p by solving the relationship with the given kernel size (setting s=2 for simplicity):

$$\left\lfloor \frac{64 + 2 \cdot p - 8}{2} \right\rfloor + 1 = 32$$
$$32 + p - 4 + 1 = 32$$
$$p = 3$$

Setting 3 padding with 2 stride satisfies the convolution dimensions. Assuming dilatation d = 6 and stride of s = 2, we can use relationship 15 from [1] to get:

$$\left\lfloor \frac{64 + 2 \cdot p - k - (k - 1)(6 - 1)}{2} \right\rfloor + 1 = 32$$
$$\left| \frac{69 + 2 \cdot p - 6 \cdot k}{2} \right| = 31$$

This is satisfied when $69+2\cdot p-6\cdot k=63$. We simplify further to get 2p-6k+6=0, for which one possible solution is: p=3, k=2. Therefore, setting padding to be 3 and kernel size 2×2 satisfies the convolution dimensions.

- (b) Given an input shape of $64 \times 32 \times 32$ and the output shape is $64 \times 8 \times 8$ a configuration assuming no overlapping of pooling windows or padding would have kernel size 4 and stride 1. This is easily seen since $\frac{32}{8} = 4$.
- (c) Without any padding and given input shape $64 \times 32 \times 32$ and kernel of size 8×8 and stride 4 we can use the relation to get:

output length =
$$\left\lfloor \frac{32 + 2 \cdot 0 - 8}{4} \right\rfloor + 1 = 7$$

And so the output size would be 7×7 .

- (d) We are given input shape $64 \times 8 \times 8$ and output $128 \times 4 \times 4$
 - (i) Assuming no padding and no dilation and using the relation above, we can easily solve to get kernel size 4 and stride 2.

- (ii) Assuming dilatation of 1 and padding of 2, kernel size 6 and stride 2 satisfies the input/output dimensions.
- (iii) Assuming padding of 1 and no dilatation, kernel size 4 and stride 2 satisfies the input/output dimensions.

4 Dropout as weight decay

We consider a linear regression problem with input data $X \in \mathbb{R}^{n \times d}$, weights $w \in R^{d \times 1}$ and and targets $y \in R^{n \times 1}$. We also suppose that dropout is being applied to the input units with probability p.

- (a) We can let $\tilde{X} = P \odot X$ where $P_{ij} \sim Bernoulli(p)$
- (b) The cost function of this would be

$$\mathbb{E}_{P}\left\{\|y - \tilde{X}w\|^{2}\right\} = \mathbb{E}_{P}\left\{(y - \tilde{X}w)^{T}(y - \tilde{X}w)\right\} \\
= y^{T}y - 2w^{T}\mathbb{E}_{P}\left\{\tilde{X}^{T}\right\}y + \mathbb{E}_{P}\left\{w^{T}\tilde{X}^{T}\tilde{X}w\right\} \\
= y^{T}y - 2pw^{T}X^{T}y + \left(p^{2}(Xw)^{T}(Xw) - p^{2}(Xw)^{T}(Xw)\right) + \mathbb{E}_{P}\left\{w^{T}\tilde{X}^{T}\tilde{X}w\right\} \\
= \|y - pXw\|^{2} + \mathbb{E}_{P}\left\{w^{T}\tilde{X}^{T}\tilde{X}w\right\} - p^{2}(Xw)^{T}(Xw) \\
= \|y - pXw\|^{2} + \mathbb{E}_{P}\left\{w^{T}\tilde{X}^{T}\tilde{X}w\right\} - \mathbb{E}_{P}\left\{(\tilde{X}w)^{T}(\tilde{X}w)\right\} \\
= \|y - pXw\|^{2} + w^{T}\left(\mathbb{E}_{P}\left\{\tilde{X}^{T}\tilde{X}\right\} - \mathbb{E}_{P}\left\{\tilde{X}\right\}^{T}\mathbb{E}_{p}\left\{\tilde{X}\right\}\right)w$$

We evaluate the matrix in the rightmost term:

$$\mathbb{E}_{P}\left\{\tilde{X}^{T}\tilde{X}\right\} - \mathbb{E}_{P}\left\{\tilde{X}\right\}^{T} \mathbb{E}_{p}\left\{\tilde{X}\right\} = \left[\sum_{k} \mathbb{E}\left\{p_{ki}p_{kj}\right\} x_{ki}x_{kj} - \mathbb{E}\left\{p_{ki}\right\} \mathbb{E}\left\{p_{kj}\right\} x_{ki}x_{kj}\right] \\ = \sum_{k} Cov(p_{ki}, p_{kj}) x_{ki}x_{kj} \\ = \begin{cases} \sum_{k} p(1-p)x_{ki}^{2} & \text{if } i=j \\ 0 & \text{o.w.} \end{cases} \\ = Diag(X^{T}X)p(1-p)$$

Inserting this into the cost function gives us:

$$\mathbb{E}_{P} \left\{ \|y - \tilde{X}w\|^{2} \right\} = \|y - pXw\|^{2} + p(1-p)w^{T}Diag(X^{T}X)w$$
$$= \|y - pXw\|^{2} + p(1-p)\|\Gamma w\|^{2}$$

Where $\Gamma = Diag(X^T X)^{\frac{1}{2}}$

(c) We show that applying dropout to the linear regression problem can be seen as using L2 regularization in the loss function. Let $\tilde{w} = pw$. The optimal value of the cost function is:

$$\frac{\partial}{\partial \tilde{w}} \left(\|y - X\tilde{w}\|^2 + \frac{1-p}{p} \|\Gamma \tilde{w}\|^2 \right) = -2X^T y + 2X^T X\tilde{w} + 2\frac{1-p}{p} \Gamma^2 \tilde{w}$$

And setting this to zero yields:

$$\frac{1-p}{p}\Gamma^2 \tilde{w} + X^T X \tilde{w} = X^T y$$

$$\Rightarrow \left(\frac{1-p}{p}\Gamma^2 + X^T X\right) \tilde{w} = X^T y$$

$$\Rightarrow \tilde{w} = \left(\lambda \Gamma^2 + X^T X\right)^{-1} X^T y$$

where $\lambda = \frac{1-p}{p}$. Notice that the solution to the regularized least squares problem is identical except the $\lambda\Gamma^2$ term is replaced by λI . In dropout, the Γ term adds additional cost to weights which are in directions where the data varies, wheras in ordinary L2 regularized least squares, the directions are penalized by the same amount.

5 Dropout as Geometric Ensemble

We show that weight scaling with a factor of 0.5 corresponds exactly to the inference of a conditional probability distribution proportional to the geometric mean over all dropout masks:

$$p_{\mathrm{ens}}(y=j|v) \propto \left(\prod_{i=1}^{N} \hat{y}_{j}^{(i)}\right)^{rac{1}{N}}$$

Where N is the number of dropout masks, $\hat{y}_j^{(i)} = softmax (W^T(m_i \odot v) + b)_j$ and m_i is a dropout mask configuration, for which there are N of. We expand the geometric mean:

$$p_{\text{ens}}(y = j | v) \propto \left(\prod_{i=1}^{N} softmax \left(W^{T}(m_{i} \odot v) + b \right)_{j} \right)^{\frac{1}{N}}$$

$$= \left(\prod_{i=1}^{N} \frac{\exp \left\{ W^{T}(m_{i} \odot v) + b \right\}_{j}}{\sum_{j'} \exp \left\{ W^{T}(m_{i} \odot v) + b \right\}_{j'}} \right)^{\frac{1}{N}}$$

$$= \frac{\left(\prod_{i=1}^{N} \exp \left\{ W^{T}(m_{i} \odot v) + b \right\}_{j} \right)^{\frac{1}{N}}}{\left(\prod_{i=1}^{N} \sum_{j'} \exp \left\{ W^{T}(m_{i} \odot v) + b \right\}_{j'} \right)^{\frac{1}{N}}}$$

$$\propto \left(\prod_{i=1}^{N} \exp \left\{ W^{T}(m_{i} \odot v) + b \right\}_{j} \right)^{\frac{1}{N}}$$

$$= \exp \left\{ \frac{1}{N} \sum_{i=1}^{N} W^{T}(m_{i} \odot v) + b \right\}_{j}$$

$$= \exp \left\{ \frac{1}{N} \sum_{i=1}^{N} W^{T}(m_{i} \odot v) + b \right\}_{j}$$

6 Normalization

We investigate Weight Normalization (WN). We decouple the weight vector into two terms :

 $w = \frac{g}{\|u\|}u$

where $g \in \mathbb{R}$ is a scaling factor. Doing so has similar effects as implementing Batch Normalization (BN), but has a lower computational overhead.

(a) We consider the simplest model, where we only have one single output layer conditioned on one input feature x. Additionally, we assume $\mathbb{E}\{x\} = 0$, $Var\{x\} = 1$. We show that in this simple case WN is equivalent to BN (ignoring the learned scale and shift terms) that normalizes the linearly transformed feature $a = w^T x + b$. From 8.35 of [2] we have that:

$$BN(a) = \frac{a - \mathbb{E}\left\{a\right\}}{\sqrt{Var\left\{a\right\}}} = \frac{w^T x}{\|w\|}$$

since $\mathbb{E}\left\{w^Tx\right\} = w^T\mathbb{E}\left\{x\right\} = 0$ and $Var\left\{w^Tx\right\} = w^TVar\left\{x\right\}w = w^Tw = \|w\|^2$. Ignoring the scale and shift terms, we see that this is equivalent to weight normalization.

(b) Show that the gradient of a loss function L with respect to the new parameters u can be expressed in the form $sW^*\nabla_w L$, where s is a scalar and W^* is the orthogonal complement projection matrix. We compute the gradient. Using the multivariate chain rule:

$$\nabla_u L = \nabla_u w \nabla_w L$$

$$= g \nabla_u \frac{u}{\|u\|} \nabla_w L$$

$$= \frac{g}{\|u\|} \left(I - \frac{u u^T}{\|u\|^2} \right) \nabla_w L$$

Since

$$\frac{\partial w_i}{\partial u_j} = \frac{\partial}{\partial u_j} \frac{u_i}{\|u\|} = \frac{1_{i=j} - \frac{u_j}{\|u\|^2} u_i}{\|u\|}$$

And so multiplying and dividing the matrix by $g^2 = ||w||^2$ gives us

$$\nabla_u L = \frac{g}{\|u\|} \left(I - \frac{ww^T}{\|w\|^2} \right) \nabla_w L$$
$$= sW^* \nabla_w L$$

Where $s = \frac{g}{\|w\|}$ and $W^* = \left(I - \frac{ww^T}{\|w\|^2}\right)$ is a projection matrix that projects onto the complement of w.

(c) The effect in the figure is a consequence of (b). Let $u' = u + \alpha \nabla_u L$, which is standard gradient descent with α learning rate. Since W^* projects $\nabla_u L$ orthogonal to w, we have that $w \perp \nabla_u L$ and so $u \perp \nabla_u L$ (since $u \propto w$). Let $c = \frac{\|\nabla_u L\|}{\|u\|}$. We can use Pythagorean theorem (due to the orthogonality of u and $\nabla_u L$) to get that

$$||u'|| = ||u + \alpha \nabla_u L|| = \sqrt{||u||^2 + \alpha^2 ||\nabla_u L||^2}$$

$$= \sqrt{||u||^2 + \alpha^2 c^2 ||u||^2}$$

$$= \sqrt{1 + \alpha^2 c^2} ||u||$$

$$\ge ||u||$$

We see that ||u|| grows monotonically, and this growth is proportional to α . This explains what is happening in the graph.

References

- [1] V. Dumoulin and F. Visin, "A guide to convolution arithmetic for deep learning.," CoRR, vol. abs/1603.07285, 2016.
- [2] I. Goodfellow, Y. Bengio, and A. Courville, *Deep Learning*. MIT Press, 2016.