## Master's Thesis Exam Verification of the Blocking and Non-Blocking Michael-Scott Queue Algorithms

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## Overview of the Project and Contributions

#### Outline

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- Proving that the Two-Lock Michael-Scott Queue Satisfies the HOCAP-style Specification
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## Queue Specifications

### Specifications for Queues

#### Assumptions on Queues

- Queues consists of initialize, enqueue, and dequeue
- initialize creates an empty queue: []
- enqueue adds a value, v, to the beginning of the queue  $xs_v$ : v ::  $xs_v$
- dequeue depends on whether queue is empty:
  - If non-empty,  $xs_v ++ v$ , remove v and return Some v
  - If empty, [], return None

#### Nature of Specifications

- Specifications written in Iris, a higher order CSL
- **E**xpressed in terms of *Hoare triples*:  $\{P\}$  e  $\{v.\Phi$   $v\}$
- Hoare triples prove partial correctness of programs, e
- In particular: safety
- Idea: clients can use Hoare triples to prove results about their own code

#### Sequential Specification

#### Definition (Sequential Specification)

```
 \exists \mathsf{isQueue}_{S} : \mathit{Val} \rightarrow \mathit{List} \; \mathit{Val} \rightarrow \mathit{SeqQgnames} \rightarrow \mathsf{Prop}. 
 \{\mathsf{True}\} \; \mathsf{initialize} \; () \; \{v_q. \exists G. \; \mathsf{isQueue}_{S}(v_q, [], G)\} 
 \land \quad \forall v_q, v, xs_v, G. \; \{\mathsf{isQueue}_{S}(v_q, xs_v, G)\} \; \mathsf{enqueue} \; v_q \; v \; \{w. \; \mathsf{isQueue}_{S}(v_q, (v :: xs_v), G)\} 
 \land \quad \forall v_q, xs_v, G. \; \{\mathsf{isQueue}_{S}(v_q, xs_v, G)\} 
 \mathsf{dequeue} \; v_q 
 \left\{ w. \; (xs_v = [] * w = \mathsf{None} * \mathsf{isQueue}_{S}(v_q, xs_v, G)) \lor \\ (\exists v, xs_v'. \; xs_v = xs_v' + + [v] * w = \mathsf{Some} \; v * \mathsf{isQueue}_{S}(v_q, xs_v', G)) \right\}
```

- The proposition isQueue<sub>S</sub>( $v_q$ ,  $x_{s_v}$ , G), states that value  $v_q$  represents the queue, which contains elements  $x_{s_v}$
- ullet  $G \in SeqQgnames$  is a collection of ghost names (depends on specific queue)
- Specification consists of three Hoare triples one for each queue function
- Important: isQueue<sub>S</sub> not required to be persistent!

### Concurrent Specification

#### Definition (Concurrent Specification)

```
\begin{split} \exists \, & \mathsf{isQueue_C} : (\mathit{Val} \to \mathsf{Prop}) \to \mathit{Val} \to \mathit{ConcQgnames} \to \mathsf{Prop}. \\ \forall \Psi : \mathit{Val} \to \mathsf{Prop}. \\ \forall v_q, \, G. \, & \mathsf{isQueue_C}(\Psi, v_q, \, G) \implies \Box \, & \mathsf{isQueue_C}(\Psi, v_q, \, G) \\ \land \quad & \{\mathsf{True}\} \, & \mathsf{initialize} \, () \, \{v_q, \exists G. \, & \mathsf{isQueue_C}(\Psi, v_q, \, G)\} \\ \land \quad & \forall v_q, \, v, \, G. \, \{ \mathsf{isQueue_C}(\Psi, v_q, \, G) * \Psi(v) \} \, & \mathsf{enqueue} \, v_q \, v \, \{w.\mathsf{True}\} \\ \land \quad & \forall v_q, \, G. \, \{ \mathsf{isQueue_C}(\Psi, v_q, \, G) \} \, & \mathsf{dequeue} \, v_q \, \{w.w = \mathsf{None} \, \lor (\exists v. \, w = \mathsf{Some} \, v * \Psi(v)) \} \end{split}
```

## HOCAP-style Specification - Abstract State RA

- Introduce Auth and Frag predicates for tracking abstract state
- **►Show Resource Algebra** ◀

#### Lemmas on the Abstract State RA

$$\vdash \models \exists \gamma. \ \gamma \mapsto_{\bullet} xs_{v} * \gamma \mapsto_{\circ} xs_{v}$$
 (Abstract State Alloc)  
$$\gamma \mapsto_{\bullet} xs'_{v} * \gamma \mapsto_{\circ} xs_{v} \vdash xs_{v} = xs'_{v}$$
 (Abstract State Agree)

 $\gamma \mapsto_{\bullet} \mathit{xs}'_{\mathsf{v}} * \gamma \mapsto_{\circ} \mathit{xs}_{\mathsf{v}} \Rrightarrow \gamma \mapsto_{\bullet} \mathit{xs}''_{\mathsf{v}} * \gamma \mapsto_{\circ} \mathit{xs}''_{\mathsf{v}} \qquad \text{(Abstract State Update)}$ 

## **HOCAP-style Specification**

#### Definition (HOCAP Specification)

 $\exists$  isQueue :  $Val \rightarrow Qgnames \rightarrow Prop.$ 

```
\forall v_{q}, G. \text{ isQueue}(v_{q}, G) \implies \Box \text{ isQueue}(v_{q}, G)
\land \quad \{\text{True}\} \text{ initialize } () \{v_{q}.\exists G. \text{ isQueue}(v_{q}, G) * G.\gamma_{\text{Abst}} \mapsto_{\circ} []\}
\land \quad \forall v_{q}, v, G, P, Q. \quad (\forall xs_{v}. G.\gamma_{\text{Abst}} \mapsto_{\bullet} xs_{v} * P \Rightarrow_{\mathcal{E} \setminus \mathcal{N}.i\uparrow} \triangleright G.\gamma_{\text{Abst}} \mapsto_{\bullet} (v :: xs_{v}) * Q) \twoheadrightarrow \{\text{isQueue}(v_{q}, G) * P\} \text{ enqueue } v_{q} \ v \ \{w.Q\}
\land \quad \forall v_{q}, G, P, Q.
\begin{pmatrix} (xs_{v} = [] * G.\gamma_{\text{Abst}} \mapsto_{\bullet} xs_{v} * Q(\text{None})) \\ \forall (G.\gamma_{\text{Abst}} \mapsto_{\bullet} xs'_{v} * Q(\text{Some } v)) \end{pmatrix}
\{\text{isQueue}(v_{q}, G) * P\} \text{ dequeue } v_{q} \{w.Q(w)\}
```

#### Queue Client - A PoC Client

- Idea: a minimal client complex enough to require HOCAP specification
- Concurrent, so sequential specification insufficient
- Relies on dequeues not returning None, so concurrent specification insufficient
- HOCAP specification supports consistency and allows us to track queue contents, allowing us to exclude cases where dequeue returns None

```
unwrap w \triangleq \mathsf{match} \ w \ \mathsf{with} \ \mathsf{None} \Rightarrow () \ () \ | \ \mathsf{Some} \ v \Rightarrow v \ \mathsf{end}
\mathsf{enqdeq} \ \ v_q \ c \triangleq \mathsf{enqueue} \ \ v_q \ c; \mathsf{unwrap}(\mathsf{dequeue} \ \ v_q)
\mathsf{queueAdd} \ \ a \ b \triangleq \\ \mathsf{let} \ \ v_q = \mathsf{initialize} \ () \ \mathsf{in} \\ \mathsf{let} \ \ p = (\mathsf{enqdeq} \ \ v_q \ a) \ || \ (\mathsf{enqdeq} \ \ v_q \ b) \ \mathsf{in} \\ \mathsf{fst} \ p + \mathsf{snd} \ p
```

## Queue Client - A PoC Client (continued)

#### Lemma (QueueAdd Specification)

$$\forall a, b \in \mathbb{Z}. \{ \textit{True} \} \text{ queueAdd } a \ b \{ v.v = a + b \}$$

- Proof idea: Create invariant capturing possible states of queue contents
- Tokens are used to reason about which state we are in

#### Definition (Invariant for QueueAdd)

$$\begin{split} I_{QA}(G,Ga,a,b) &\triangleq G.\gamma_{\mathrm{Abst}} \mapsto_{\circ} [] * \mathsf{TokD1} \ \mathit{Ga} * \mathsf{TokD2} \ \mathit{Ga} \lor \\ & G.\gamma_{\mathrm{Abst}} \mapsto_{\circ} [a] * \mathsf{TokA} \ \mathit{Ga} * (\mathsf{TokD1} \ \mathit{Ga} \lor \mathsf{TokD2} \ \mathit{Ga}) \lor \\ & G.\gamma_{\mathrm{Abst}} \mapsto_{\circ} [b] * \mathsf{TokB} \ \mathit{Ga} * (\mathsf{TokD1} \ \mathit{Ga} \lor \mathsf{TokD2} \ \mathit{Ga}) \lor \\ & G.\gamma_{\mathrm{Abst}} \mapsto_{\circ} [a;b] * \mathsf{TokA} \ \mathit{Ga} * \mathsf{TokB} \ \mathit{Ga} \lor \\ & G.\gamma_{\mathrm{Abst}} \mapsto_{\circ} [b;a] * \mathsf{TokB} \ \mathit{Ga} * \mathsf{TokA} \ \mathit{Ga} \lor \end{split}$$

The Two-Lock Michael-Scott Queue

Implementation: initialize

Implementation: enqueue

Implementation: dequeue

## Observations on Behaviour of the Two-Lock M&S Queue

Proving that the Two-Lock Michael-Scott Queue Satisfies the HOCAP-style Specification

Invariant

### The isLL Predicate

## Queue Predicate

### Proof of Initialise

## Proof of ▶enqueue xor dequeue◀

The Lock-Free Michael-Scott Queue

Implementation: initialize

Implementation: enqueue

Implementation: dequeue

## **Prophecies**

#### The Lock-and-CC-Free Michael-Scott Queue

#### ▶format ◀

```
initialize ≜
  let node = ref (None, ref (None)) in
  ref (ref (node), ref (node))
enqueue Q value ≜
  let node = ref (Some value, ref (None)) in
  (rec loop_ =
     let tail = !(snd(! Q)) in
     let next = !(snd(! tail)) in
     if next = None then
       if CAS (snd(! tail)) next node then
         CAS (snd(! Q)) tail node
       else loop ()
     else CAS (snd(! Q)) tail next; loop ()
  )()
dequeue Q \triangleq
  (rec loop_ =
     let head = !(fst(! Q)) in
     let tail = !(snd(!Q)) in
     let next = !(snd(! head)) in
     if head = tail then
       if next = None then
         None
       else
         CAS(snd(! Q)) tail next; loop ()
     else
       let value = fst(! next) in
       if CAS (fst(! Q)) head next then
          value
```

Proving that the Lock-and-CC-Free Michael-Scott Queue Satisfies the HOCAP-style Specification

## Reachability

Invariant

## Queue Predicate

# In Coq!

