Colab and Google Drive Setup

```
import os, sys
from google.colab import drive
drive.mount('/content/mnt')
nb path = '/content/notebooks'
os.symlink('/content/mnt/My Drive/Colab Notebooks', nb path)
sys.path.insert(0,nb path)
     Go to this URL in a browser: <a href="https://accounts.google.com/o/oauth2/auth?client_id=947318989803-6bn6qk8qdgf4n4g3pfee649">https://accounts.google.com/o/oauth2/auth?client_id=947318989803-6bn6qk8qdgf4n4g3pfee649</a>
     Enter your authorization code:
     Mounted at /content/mnt
#! pip install mxnet
!pip install --target=$nb path mxnet-cu100mkl
     Collecting mxnet-cu100mkl
        Using cached <a href="https://files.pythonhosted.org/packages/bb/eb/68921d5ffb80fd5cba483ab0dc955ed4aa257acc5c3b00c05dc03e37">https://files.pythonhosted.org/packages/bb/eb/68921d5ffb80fd5cba483ab0dc955ed4aa257acc5c3b00c05dc03e37</a>
     Collecting graphviz<0.9.0,>=0.8.1
       Using cached <a href="https://files.pythonhosted.org/packages/53/39/4ab213673844e0c004bed8a0781a0721a3f6bb23eb8854ee75c23642">https://files.pythonhosted.org/packages/53/39/4ab213673844e0c004bed8a0781a0721a3f6bb23eb8854ee75c23642</a>
     Requirement already satisfied: requests<3,>=2.20.0 in /usr/local/lib/python3.6/dist-packages (from mxnet-cu100mkl) (2
     Requirement already satisfied: numpy<2.0.0,>1.16.0 in /usr/local/lib/python3.6/dist-packages (from mxnet-cu100mkl) (1
     Requirement already satisfied: urllib3<1.25,>=1.21.1 in /usr/local/lib/python3.6/dist-packages (from requests<3,>=2.2
     Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.6/dist-packages (from requests<3,>=2.20.0
     Requirement already satisfied: idna<2.9,>=2.5 in /usr/local/lib/python3.6/dist-packages (from requests<3,>=2.20.0->mx
     Requirement already satisfied: chardet<3.1.0,>=3.0.2 in /usr/local/lib/python3.6/dist-packages (from requests<3,>=2.2
     Installing collected packages: graphviz, mxnet-cu100mkl
       Found existing installation: graphviz 0.10.1
          Uninstalling graphviz-0.10.1:
            Successfully uninstalled graphviz-0.10.1
     Successfully installed graphviz-0.8.4 mxnet-cu100mkl-1.5.1.post0
#!pip install --target=$nb.path --upgrade urllib3==1.24
!pip install --target=$nb.path --upgrade folium==0.2.1
 \Box
```

Help X

```
module
Type:
String form: <module</pre>
File:
              /usr/lib/
Docstring:
OS routines for NT or
This exports:
  - all functions from
  - os.path is either
  - os.name is either
  - os.curdir is a str
  - os.pardir is a str
'..')
  - os.sep is the (or
  - os.extsep is the \epsilon
  - os.altsep is the a
  - os.pathsep is the
  - os.linesep is the
'\r\n')
  - os.defpath is the
  - os.devnull is the
Programs that import \epsilon
portable between diffe
only use functions that
```

→ 1. Import libraries

```
import os
import sys
import numpy as np
import gzip
import pandas as pd
from time import time
print("OS: ", sys.platform)
print("Python: ", sys.version)
# MXnet
import mxnet as mx
from mxnet import nd, autograd
from mxnet import gluon
from mxnet.gluon import nn
print("MXNet version", mx. version ) # Matteo 1.5.1
# Tensorflow
from sklearn.model_selection import train test split
%tensorflow version 2.x
import tensorflow as tf
import tensorflow.keras as keras
import tensorflow.keras.layers as layers
from tensorflow.keras.models import Sequential
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.utils import to categorical
print("Tensorflow version (by Google): ", tf. version )
```

```
OS: linux
   Python: 3.6.9 (default, Nov 7 2019, 10:44:02)
   [GCC 8.3.0]
   MXNet version 1.5.1
   TensorFlow 2.x selected.
   Tensorflow version (by Google): 2.1.0
# Check cuda version
!nvcc --version
   nvcc: NVIDIA (R) Cuda compiler driver
   Copyright (c) 2005-2018 NVIDIA Corporation
   Built on Sat Aug 25 21:08:01 CDT 2018
   Cuda compilation tools, release 10.0, V10.0.130
!nvidia-smi
   Mon Mar 9 07:50:25 2020
    NVIDIA-SMI 440.59
                      Driver Version: 418.67
                                            CUDA Version: 10.1
    -----+
                 Persistence-M | Bus-Id
    GPU Name
                                      Disp.A | Volatile Uncorr. ECC
    Fan Temp Perf Pwr: Usage/Cap | Memory-Usage | GPU-Util Compute M.
    0 Tesla K80
                       Off
                            00000000:00:04.0 Off
    N/A 73C P0
                 75W / 149W | 633MiB / 11441MiB |
                                                       Default
    Processes:
                                                     GPU Memory
     GPU
             PID Type Process name
                                                     Usage
```

→ Set GPU usage

```
# MXNET
gpus = mx.test_utils.list_gpus()
print(gpus)
ctx = [mx.gpu()] if gpus else [mx.cpu(0), mx.cpu(1)]
print(ctx)
```

```
# TENSORFLOW
```

Control reproducibility

The most common form of randomness used in neural networks is the random initialization of the network weights. Although randomness can be used in other areas, here is just a short list:

- Randomness in Initialization, such as weights.
- Randomness in Regularization, such as dropout.
- · Randomness in Layers, such as word embedding.
- · Randomness in Optimization, such as stochastic optimization.

source: https://machinelearningmastery.com/reproducible-results-neural-networks-keras/

```
import random
np.random.seed(42)
random.seed(42)
for computing_unit in ctx:
    mx.random.seed(42, ctx = computing_unit)
tf.random.set_seed(42)
```

→ 2. Read dataset - General Train/Test split

```
.resnape(lengtn, /84) \
                         .reshape(length, 28, 28, 1)
    return features, labels
os.listdir(os.getcwd() + "/notebooks")
[ 'kernel.ipynb',
      'Untitled0.ipynb',
      'Untitled1.ipynb',
      'Untitled2.ipynb',
      'ComparisonOfClusteringMethods (1).ipynb',
      'HierarchicalClustering.ipynb',
      'ComparisonOfClusteringMethods.ipynb',
      'SilhouetteAnalysisIris.ipynb',
      'SilhouetteAnalysis.ipynb',
      'Untitled3.ipynb',
      'CPU - Fundamental Ops - Linear Algebra.ipynb',
      'GPU - Fundamental Ops - Linear Algebra.ipynb',
      'Copy of 0 colab',
      'Copy of 1 data',
      'Copy of 2 keras',
      'Copy of 4 predict',
      'Copy of 3 eager',
      'Teardown - MXnet - TF - Optimization.ipynb',
      'graphviz-0.8.4.dist-info',
      'chardet-3.0.4.dist-info',
      'urllib3',
      'dmlc tracker',
      'urllib3-1.25.8.dist-info',
      'requests',
      'requests-2.23.0.dist-info',
      'numpy',
      'chardet',
      'graphviz',
      'idna',
      'mxnet',
      'mxnet cu100mkl-1.5.1.post0.dist-info',
      'certifi',
      'certifi-2019.11.28.dist-info',
      'idna-2.9.dist-info',
      'numpy-1.18.1.dist-info',
      'bin',
      't10k-labels-idx1-ubyte.gz',
      't10k-images-idx3-ubyte.gz',
      'train-images-idx3-ubyte.gz',
      'train-labels-idx1-ubyte.gz']
#from google.colab import files
#uploaded = files.upload()
```

```
! ls
    mnt notebooks sample data
# LOAD TRAIN AND TEST ALREADY SPLIT
train = {}
test = {}
train['features'], train['labels'] = read mnist('train-images-idx3-ubyte.gz', 'train-labels-idx1-ubyte.gz')
test['features'], test['labels'] = read mnist('t10k-images-idx3-ubyte.gz', 't10k-labels-idx1-ubyte.gz')
print(test['features'].shape[0], '-> # of test images.')
print(train['features'].shape[0], '-> # of training images (train + validation).')
# CREATE TRAIN AND VALIDATION SPLIT
validation = {}
train['features'], validation['features'], train['labels'], validation['labels'] = train test split(train['features'], tr
           ", train['features'].shape[0], '-> # of (actual) training images.')
print("
           ", validation['features'].shape[0], '-> # of validation images.')
print("
   train-images-idx3-ubyte.gz
    t10k-images-idx3-ubyte.gz
    10000 -> # of test images.
    60000 -> # of training images (train + validation).
         48000 -> # of (actual) training images.
         12000 -> # of validation images.
```

→ 3. Create a reader for each Framework

```
# GENERAL PARAMETERS
        EPOCHS = 15
        BATCH SIZE = 200
        # MXNET
        # convert from NHWC to NCHW that is used by MXNET
        # https://stackoverflow.com/questions/37689423/convert-between-nhwc-and-nchw-in-tensorflow
        X train mx = mx.ndarray.transpose(mx.nd.array(train['features']), axes=(0, 3, 1, 2))
        y train mx = mx.nd.array(train['labels'])
        X validation mx = mx.ndarray.transpose(mx.nd.array(validation['features']), axes=(0, 3, 1, 2))
        y validation mx = mx.nd.array(validation['labels'])
        X test mx = mx.ndarray.transpose(mx.nd.array(test['features']), axes=(0, 3, 1, 2))
        y test mx = mx.nd.array(test['labels'])
        # create data iterator
        train_data_mx = mx.io.NDArrayIter(X_train_mx.asnumpy(), y_train_mx.asnumpy(), BATCH_SIZE, shuffle=True)
        val_data_mx = mx.io.NDArrayIter(X_validation_mx.asnumpy(), y_validation_mx.asnumpy(), BATCH_SIZE)
         that data may be in any amount and a test may be a test ma
https://colab.research.google.com/drive/1iduFO5cLngJ5OoEKWPj_9zmj_x9POymu#scrollTo=Go8H2cGIi5Pm&printMode=true
```

→ 4. Create models

```
# MXNET -> GLUON
   # IDENTICAL TO LeNet paper: http://yann.lecun.com/exdb/publis/pdf/lecun-01a.pdf
   model mx = nn.HybridSequential()
   model_mx.add(nn.Conv2D(channels=6, kernel_size=5, activation='relu'),
           nn.AvgPool2D(pool size=2, strides=2),
           nn.Conv2D(channels=16, kernel size=3, activation='relu'),
           nn.AvgPool2D(pool size=2, strides=2),
           nn.Flatten(),
           nn.Dense(120, activation="relu"),
           nn.Dense(84, activation="relu"),
           nn.Dense(10))
   # TENSORFLOW -> KERAS
   model tf = keras.Sequential()
   init_tf = tf.keras.initializers.GlorotNormal(seed=1)
   model tf.add(layers.Conv2D(filters=6, kernel size=(5, 5), activation='relu', input shape=(28,28,1), kernel initializer =
   model_tf.add(layers.AveragePooling2D(pool_size=(2, 2), strides=2))
   model tf.add(layers.Conv2D(filters=16, kernel size=(3, 3), activation='relu', kernel initializer = init tf, bias initiali
https://colab.research.google.com/drive/1iduFO5cLngJ5OoEKWPj\_9zmj\_x9POymu\#scrollTo=Go8H2cGIi5Pm\&printMode=true
```

```
model_tf.add(layers.AveragePooling2D(pool_size=(2, 2), strides=2))
model_tf.add(layers.Flatten())
model_tf.add(layers.Dense(units=120, activation='relu', kernel_initializer = init_tf, bias_initializer = init_tf))
model_tf.add(layers.Dense(units=84, activation='relu', kernel_initializer = init_tf, bias_initializer = init_tf))
model_tf.add(layers.Dense(units=10, activation = 'softmax', kernel_initializer = init_tf, bias_initializer = init_tf))
#model.summary()

#help(layers.Dense)
```

Optimization on/off

```
# MXNET
model_mx.hybridize()

# TENSORFLOW
tf.config.optimizer.set_jit(True)
```

→ 5. Train Models

```
%%time
# MXNET

def training_procedure(handwritten_net, train_data):
    global EPOCHS
    global ctx
    handwritten_net.initialize(mx.init.Xavier(), ctx=ctx, force_reinit=True)
    #handwritten_net(init = mx.init.Xavier(), ctx=ctx)
    optim = mx.optimizer.Adam(learning_rate=0.001, beta1=0.9, beta2=0.999, epsilon=1e-08, lazy_update=True)
    trainer = gluon.Trainer(handwritten_net.collect_params(), optim)
# Use Accuracy as the evaluation metric.
    metric = mx.metric.Accuracy()
    softmax_cross_entropy_loss = gluon.loss.SoftmaxCrossEntropyLoss()

for i in range(EPOCHS):
    # Reset the train data iterator.
    train_data_reset()
```

C→

```
# Loop over the train data iterator.
        for batch in train data:
           # Splits train data into multiple slices along batch axis
           # and copy each slice into a context.
           data = gluon.utils.split and load(batch.data[0], ctx list=ctx, batch axis=0)
           # Splits train labels into multiple slices along batch axis
           # and copy each slice into a context.
           label = gluon.utils.split and load(batch.label[0], ctx list=ctx, batch axis=0)
           outputs = []
           # Inside training scope
           with autograd.record():
                for x, y in zip(data, label):
                   z = handwritten net(x)
                   # Computes softmax cross entropy loss.
                   loss = softmax cross entropy loss(z, y)
                   # Backpropogate the error for one iteration.
                   loss.backward()
                   outputs.append(z)
           # Updates internal evaluation
           metric.update(label, outputs)
           # Make one step of parameter update. Trainer needs to know the
           # batch size of data to normalize the gradient by 1/batch_size.
           trainer.step(batch.data[0].shape[0])
        # Gets the evaluation result.
        name, acc = metric.get()
        # Reset evaluation result to initial state.
       metric.reset()
        print('training acc at epoch %d: %s=%f'%(i, name, acc))
    return handwritten net
trained model mx = training procedure(model mx, train data mx)
```

```
training acc at epoch 0: accuracy=0.877375
    training acc at epoch 1: accuracy=0.967458
    training acc at epoch 2: accuracy=0.977187
    training acc at epoch 3: accuracy=0.983583
    training acc at epoch 4: accuracy=0.986229
    training acc at epoch 5: accuracy=0.987563
    training acc at epoch 6: accuracy=0.991250
    training acc at epoch 7: accuracy=0.991521
    training acc at epoch 8: accuracy=0.992771
    training acc at epoch 9: accuracy=0.994062
    training acc at epoch 10: accuracy=0.993708
    training acc at epoch 11: accuracy=0.993729
    training acc at epoch 12: accuracy=0.995271
    training acc at epoch 13: accuracy=0.995313
    training acc at epoch 14: accuracy=0.995146
    CPU times: user 25.5 s, sys: 5.1 s, total: 30.6 s
    Wall time: 21.3 s
%%time
# TENSORFLOW
chosen tf optimizer = keras.optimizers.Adam(learning rate=0.001, beta 1=0.9, beta 2=0.999, amsgrad=False)
model tf.compile(loss=keras.losses.categorical crossentropy, optimizer=chosen tf optimizer, metrics=['accuracy'])
steps_per_epoch = X_train_tf.shape[0]//BATCH SIZE
validation steps = X validation tf.shape[0]//BATCH SIZE
model_tf.fit_generator(train_generator_tf, steps_per_epoch=steps_per_epoch, epochs=EPOCHS,
                    validation data=validation generator tf, validation steps=validation steps,
                    shuffle=True, callbacks=[])
```

 \Box

```
WARNING: tensorflow: sample weight modes were coerced from
to
['...']
WARNING: tensorflow: sample weight modes were coerced from
to
['...']
Train for 240 steps, validate for 60 steps
Epoch 1/15
Epoch 2/15
Epoch 3/15
Epoch 4/15
Epoch 5/15
Epoch 6/15
Epoch 7/15
Epoch 8/15
Epoch 9/15
Epoch 10/15
Epoch 11/15
Epoch 12/15
Epoch 13/15
Epoch 14/15
Epoch 15/15
CPU times: user 50.4 s, sys: 4.65 s, total: 55.1 s
Wall time: 40.3 s
```

→ 6. Evaluate models

```
# MXNET
# TEST THE NETWORK
metric = mx.metric.Accuracy()
# Reset the test data iterator.
test data mx.reset()
# Loop over the test data iterator.
for batch in test data mx:
    # Splits test data into multiple slices along batch axis
    # and copy each slice into a context.
    data = gluon.utils.split and load(batch.data[0], ctx list=ctx, batch axis=0)
    # Splits validation label into multiple slices along batch axis
    # and copy each slice into a context.
    label = gluon.utils.split and load(batch.label[0], ctx list=ctx, batch axis=0)
    outputs = []
    for x in data:
        outputs.append(model_mx(x))
    # Updates internal evaluation
    metric.update(label, outputs)
print('MXnet - Test %s : %f'%metric.get())
assert metric.get()[1] > 0.90
   MXnet - Test accuracy: 0.984900
    CPU times: user 188 ms, sys: 30.5 ms, total: 218 ms
    Wall time: 151 ms
%%time
# TENSORFLOW
score = model tf.evaluate(test['features'], to categorical(test['labels']), verbose=0)
#print('Test loss:', score[0])
print('TensorFlow - Test accuracy:', score[1])
assert score[1] > 0.90
TensorFlow - Test accuracy: 0.9864
    CPU times: user 1.25 s, sys: 192 ms, total: 1.44 s
    Wall time: 1.19 s
```