

## ▼ Colab and Google Drive Setup

```
import os, sys
from google.colab import drive
drive.mount('/content/mnt')
nb_path = '/content/notebooks'
os.symlink('/content/mnt/My Drive/Colab Notebooks', nb_path)
sys.path.insert(0,nb_path)
```

➞ Go to this URL in a browser: [https://accounts.google.com/o/oauth2/auth?client\\_id=947318989803-6bn6qk8qdgf4n4g3pfee649](https://accounts.google.com/o/oauth2/auth?client_id=947318989803-6bn6qk8qdgf4n4g3pfee649)

```
Enter your authorization code:
.....
Mounted at /content/mnt
```

```
#! pip install mxnet
!pip install --target=$nb_path mxnet-cu100mkl
```

➞ Collecting mxnet-cu100mkl  
 Using cached <https://files.pythonhosted.org/packages/bb/eb/68921d5ffb80fd5cba483ab0dc955ed4aa257acc5c3b00c05dc03e37>  
 Collecting graphviz<0.9.0,>=0.8.1  
 Using cached <https://files.pythonhosted.org/packages/53/39/4ab213673844e0c004bed8a0781a0721a3f6bb23eb8854ee75c23642>  
 Requirement already satisfied: requests<3,>=2.20.0 in /usr/local/lib/python3.6/dist-packages (from mxnet-cu100mkl) (2)  
 Requirement already satisfied: numpy<2.0.0,>1.16.0 in /usr/local/lib/python3.6/dist-packages (from mxnet-cu100mkl) (1)  
 Requirement already satisfied: urllib3<1.25,>=1.21.1 in /usr/local/lib/python3.6/dist-packages (from requests<3,>=2.20.0) (1)  
 Requirement already satisfied: certifi<=2017.4.17 in /usr/local/lib/python3.6/dist-packages (from requests<3,>=2.20.0) (1)  
 Requirement already satisfied: idna<2.9,>=2.5 in /usr/local/lib/python3.6/dist-packages (from requests<3,>=2.20.0) (1)  
 Requirement already satisfied: chardet<3.1.0,>=3.0.2 in /usr/local/lib/python3.6/dist-packages (from requests<3,>=2.20.0) (1)  
 Installing collected packages: graphviz, mxnet-cu100mkl  
 Found existing installation: graphviz 0.10.1  
 Uninstalling graphviz-0.10.1:  
 Successfully uninstalled graphviz-0.10.1  
 Successfully installed graphviz-0.8.4 mxnet-cu100mkl-1.5.1.post0

```
#!pip install --target=$nb_path --upgrade urllib3==1.24
!pip install --target=$nb_path --upgrade folium==0.2.1
```

➞

**Type:** module  
**String form:** <module '  
**File:** /usr/lib/  
**Docstring:**  
 OS routines for NT or

This exports:  
 - all functions from  
 - os.path is either  
 - os.name is either  
 - os.curdir is a str  
 '..')  
 - os.pardir is a str  
 '..')  
 - os.sep is the (or  
 - os.extsep is the e  
 - os.altsep is the a  
 - os.pathsep is the  
 - os.linesep is the  
 '\r\n')  
 - os.defpath is the  
 - os.devnull is the

Programs that import a  
 portable between diffe  
 only use functions tha  
 and opendir), and leav  
 (e.g., split and join)

```

Collecting folium==0.2.1
  Downloading https://files.pythonhosted.org/packages/72/dd/75ced7437bfa7cb9a88b96ee0177953062803c3b4cde411a97d98c35a
    |████████████████████| 71kB 3.6MB/s
Collecting Jinja2
  Downloading https://files.pythonhosted.org/packages/27/24/4f35961e5c669e96f6559760042a55b9bcfcdb82b9bdb3c8753dbe042
    |████████████████████| 133kB 16.1MB/s
Collecting MarkupSafe>=0.23
  Downloading https://files.pythonhosted.org/packages/b2/5f/23e0023be6bb885d00ffbefad2942bc51a620328ee910f64abe5a8d18
Building wheels for collected packages: folium
  Building wheel for folium (setup.py) ... done
  Created wheel for folium: filename=folium-0.2.1-cp36-none-any.whl size=79979 sha256=420914a5d822a1020f8c16a467df865
  Stored in directory: /root/.cache/pip/wheels/b8/09/f0/52d2ef419c2aaf4fb149f92a33e0008bdce7ae816f0dd8f0c5
Successfully built folium
Installing collected packages: MarkupSafe, Jinja2, folium
Successfully installed Jinja2-2.11.1 MarkupSafe-1.1.1 folium-0.2.1

```

## ▼ 1. Import libraries

```

import os
import sys
import numpy as np
import gzip
import pandas as pd
from time import time
print("OS: ", sys.platform)
print("Python: ", sys.version)
# MXnet
import mxnet as mx
from mxnet import nd, autograd
from mxnet import gluon
from mxnet.gluon import nn
print("MXNet version", mx.__version__) # Matteo 1.5.1
# Tensorflow
from sklearn.model_selection import train_test_split
%tensorflow_version 2.x
import tensorflow as tf
import tensorflow.keras as keras
import tensorflow.keras.layers as layers
from tensorflow.keras.models import Sequential
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.utils import to_categorical
print("Tensorflow version (by Google): ", tf.__version__)

```

```
➤ OS:  linux
  Python:  3.6.9 (default, Nov  7 2019, 10:44:02)
  [GCC 8.3.0]
  MXNet version 1.5.1
  TensorFlow 2.x selected.
  Tensorflow version (by Google):  2.1.0
```

```
# Check cuda version
!nvcc --version
```

```
➤ nvcc: NVIDIA (R) Cuda compiler driver
  Copyright (c) 2005-2018 NVIDIA Corporation
  Built on Sat_Aug_25_21:08:01_CDT_2018
  Cuda compilation tools, release 10.0, V10.0.130
```

```
!nvidia-smi
```

```
➤ Mon Mar  9 07:44:29 2020
+-----+
| NVIDIA-SMI 440.59          Driver Version: 418.67          CUDA Version: 10.1          |
+-----+-----+-----+
| GPU   Name                Persistence-M| Bus-Id        Disp.A | Volatile Uncorr. ECC |
| Fan   Temp   Perf    Pwr:Usage/Cap|      Memory-Usage | GPU-Util  Compute M. |
|=====+=====+=====+
|    0   Tesla K80           Off          | 00000000:00:04.0 Off |             0         |
| N/A    73C    P8      35W / 149W |      0MiB / 11441MiB |      0%      Default  |
+-----+-----+-----+

+-----+-----+-----+
| Processes:                                     GPU Memory |
|  GPU       PID    Type    Process name                     Usage      |
|=====+=====+=====+
|   No running processes found                       |
+-----+-----+-----+
```

▼ Set GPU usage

```
# MXNET
gpus = mx.test_utils.list_gpus()
print(gpus)
ctx = [mx.gpu()] if gpus else [mx.cpu(0), mx.cpu(1)]
print(ctx)
```

```
↳ range(0, 1)
   [gpu(0)]
```

```
# TENSORFLOW
```

## ▼ Control reproducibility

The most common form of randomness used in neural networks is the random initialization of the network weights. Although randomness can be used in other areas, here is just a short list:

- Randomness in Initialization, such as weights.
- Randomness in Regularization, such as dropout.
- Randomness in Layers, such as word embedding.
- Randomness in Optimization, such as stochastic optimization.

source: <https://machinelearningmastery.com/reproducible-results-neural-networks-keras/>

```
import random
np.random.seed(42)
random.seed(42)
for computing_unit in ctx:
    mx.random.seed(42, ctx = computing_unit)
tf.random.set_seed(42)
```

## ▼ 2. Read dataset - General Train/Test split

```
def read_mnist(images_path: str, labels_path: str):
    #mnist_path = "data/mnist/"
    #images_path = mnist_path + images_path
    folder = os.getcwd() + "/notebooks/"
    print(images_path)
    with gzip.open(folder + labels_path, 'rb') as labelsFile:
        labels = np.frombuffer(labelsFile.read(), dtype=np.uint8, offset=8)

    with gzip.open(folder + images_path, 'rb') as imagesFile:
```

```

length = len(labels)
# Load flat 28x28 px images (784 px), and convert them to 28x28 px
features = np.frombuffer(imagesFile.read(), dtype=np.uint8, offset=16) \
            .reshape(length, 784) \
            .reshape(length, 28, 28, 1)
return features, labels

```

```
os.listdir(os.getcwd() + "/notebooks")
```

```

[> ['kernel.ipynb',
    'Untitled0.ipynb',
    'Untitled1.ipynb',
    'Untitled2.ipynb',
    'ComparisonOfClusteringMethods (1).ipynb',
    'HierarchicalClustering.ipynb',
    'ComparisonOfClusteringMethods.ipynb',
    'SilhouetteAnalysisIris.ipynb',
    'SilhouetteAnalysis.ipynb',
    'Untitled3.ipynb',
    'CPU - Fundamental Ops - Linear Algebra.ipynb',
    'GPU - Fundamental Ops - Linear Algebra.ipynb',
    'Copy of 0_colab',
    'Copy of 1_data',
    'Copy of 2_keras',
    'Copy of 4_predict',
    'Copy of 3_eager',
    'Teardown - MXnet - TF - Optimization.ipynb',
    'graphviz-0.8.4.dist-info',
    'chardet-3.0.4.dist-info',
    'urllib3',
    'dmlc_tracker',
    'urllib3-1.25.8.dist-info',
    'requests',
    'requests-2.23.0.dist-info',
    'numpy',
    'chardet',
    'graphviz',
    'idna',
    'mxnet',
    'mxnet_cu100mkl-1.5.1.post0.dist-info',
    'certifi',
    'certifi-2019.11.28.dist-info',
    'idna-2.9.dist-info',
    'numpy-1.18.1.dist-info',
    'bin',
    't10k-labels-idx1-ubyte.gz',
    't10k-images-idx3-ubyte.gz']]

```

```
#from google.colab import files
```

```
#uploaded = files.upload()
```

```
! ls
```

```
📁 mnt notebooks sample_data
```

```
# LOAD TRAIN AND TEST ALREADY SPLIT
```

```
train = {}
```

```
test = {}
```

```
train['features'], train['labels'] = read_mnist('train-images-idx3-ubyte.gz', 'train-labels-idx1-ubyte.gz')
```

```
test['features'], test['labels'] = read_mnist('t10k-images-idx3-ubyte.gz', 't10k-labels-idx1-ubyte.gz')
```

```
print(test['features'].shape[0], '-> # of test images.')
```

```
print(train['features'].shape[0], '-> # of training images (train + validation).')
```

```
# CREATE TRAIN AND VALIDATION SPLIT
```

```
validation = {}
```

```
train['features'], validation['features'], train['labels'], validation['labels'] = train_test_split(train['features'], tr
```

```
print("      ", train['features'].shape[0], '-> # of (actual) training images.')
```

```
print("      ", validation['features'].shape[0], '-> # of validation images.')
```

```
📁 train-images-idx3-ubyte.gz
```

```
  t10k-images-idx3-ubyte.gz
```

```
  10000 -> # of test images.
```

```
  60000 -> # of training images (train + validation).
```

```
    48000 -> # of (actual) training images.
```

```
    12000 -> # of validation images.
```

### ▼ 3. Create a reader for each Framework

```
# GENERAL PARAMETERS
```

```
EPOCHS = 15
```

```
BATCH_SIZE = 200
```

```
# MXNET
```

```
# convert from NHWC to NCHW that is used by MXNET
```

```
# https://stackoverflow.com/questions/37689423/convert-between-nhwc-and-nchw-in-tensorflow
```

```
X_train_mx = mx.ndarray.transpose(mx.nd.array(train['features']), axes=(0, 3, 1, 2))
```

```
y_train_mx = mx.nd.array(train['labels'])
```

```
X_validation_mx = mx.ndarray.transpose(mx.nd.array(validation['features']), axes=(0, 3, 1, 2))
```

```
y_validation_mx = mx.nd.array(validation['labels'])
```

```
X_test_mx = mx.ndarray.transpose(mx.nd.array(test['features']), axes=(0, 3, 1, 2))
```

```
y_test_mx = mx.nd.array(test['labels'])
```

```
# create data iterator
```

```
train_data_mx = mx.io.NDArrayIter(X_train_mx.asnumpy(), y_train_mx.asnumpy(), BATCH_SIZE, shuffle=True)
```

```
val_data_mx = mx.io.NDArrayIter(X_validation_mx.asnumpy(), y_validation_mx.asnumpy(), BATCH_SIZE)
test_data_mx = mx.io.NDArrayIter(X_test_mx.asnumpy(), y_test_mx.asnumpy(), BATCH_SIZE)
```

```
X_train_mx.shape
```

```
↳ (48000, 1, 28, 28)
```

```
type(X_train_mx.asnumpy())
```

```
↳ numpy.ndarray
```

```
# TENSORFLOW
# convert in multiple output for tensorflow
X_train_tf, y_train_tf = train['features'], to_categorical(train['labels'])
X_validation_tf, y_validation_tf = validation['features'], to_categorical(validation['labels'])
# create data generator
train_generator_tf = ImageDataGenerator().flow(X_train_tf, y_train_tf, batch_size=BATCH_SIZE)
validation_generator_tf = ImageDataGenerator().flow(X_validation_tf, y_validation_tf, batch_size=BATCH_SIZE)
```

```
X_train_tf.shape
```

```
↳ (48000, 28, 28, 1)
```

## ▼ 4. Create models

```
# MXNET -> GLUON
# IDENTICAL TO LeNet paper: http://yann.lecun.com/exdb/publis/pdf/lecun-01a.pdf
model_mx = nn.HybridSequential()
model_mx.add(nn.Conv2D(channels=6, kernel_size=5, activation='relu'),
             nn.AvgPool2D(pool_size=2, strides=2),
             nn.Conv2D(channels=16, kernel_size=3, activation='relu'),
             nn.AvgPool2D(pool_size=2, strides=2),
             nn.Flatten(),
             nn.Dense(120, activation="relu"),
             nn.Dense(84, activation="relu"),
             nn.Dense(10))
```

```
# TENSORFLOW -> KERAS
model_tf = keras.Sequential()
init_tf = tf.keras.initializers.GlorotNormal(seed=1)
model_tf.add(layers.Conv2D(filters=6, kernel_size=(5, 5), activation='relu', input_shape=(28,28,1), kernel_initializer =
model_tf.add(layers.AveragePooling2D(pool_size=(2, 2), strides=2))
```

```

model_tf.add(layers.AveragePooling2D(pool_size=(2, 2), strides=2))
model_tf.add(layers.Conv2D(filters=16, kernel_size=(3, 3), activation='relu', kernel_initializer = init_tf, bias_initializer = init_tf))
model_tf.add(layers.AveragePooling2D(pool_size=(2, 2), strides=2))
model_tf.add(layers.Flatten())
model_tf.add(layers.Dense(units=120, activation='relu', kernel_initializer = init_tf, bias_initializer = init_tf))
model_tf.add(layers.Dense(units=84, activation='relu', kernel_initializer = init_tf, bias_initializer = init_tf))
model_tf.add(layers.Dense(units=10, activation = 'softmax', kernel_initializer = init_tf, bias_initializer = init_tf))
#model.summary()

#help(layers.Dense)

```

## ▼ Optimization on/off

```

# MXNET
#model_mx.hybridize()

# TENSORFLOW
#tf.config.optimizer.set_jit(True)

```

## ▼ 5. Train Models

```

%%time
# MXNET
def training_procedure(handwritten_net, train_data):
    global EPOCHS
    global ctx
    handwritten_net.initialize(mx.init.Xavier(), ctx=ctx, force_reinit=True)
    #handwritten_net(init = mx.init.Xavier(), ctx=ctx)
    optim = mx.optimizer.Adam(learning_rate=0.001, beta1=0.9, beta2=0.999, epsilon=1e-08, lazy_update=True)
    trainer = gluon.Trainer(handwritten_net.collect_params(), optim)
    # Use Accuracy as the evaluation metric.
    metric = mx.metric.Accuracy()
    softmax_cross_entropy_loss = gluon.loss.SoftmaxCrossEntropyLoss()

    for i in range(EPOCHS):

```



```

# Reset the train data iterator.
train_data.reset()
# Loop over the train data iterator.
for batch in train_data:
    # Splits train data into multiple slices along batch_axis
    # and copy each slice into a context.
    data = gluon.utils.split_and_load(batch.data[0], ctx_list=ctx, batch_axis=0)
    # Splits train labels into multiple slices along batch_axis
    # and copy each slice into a context.
    label = gluon.utils.split_and_load(batch.label[0], ctx_list=ctx, batch_axis=0)
    outputs = []
    # Inside training scope
    with autograd.record():
        for x, y in zip(data, label):
            z = handwritten_net(x)
            # Computes softmax cross entropy loss.
            loss = softmax_cross_entropy_loss(z, y)
            # Backpropagate the error for one iteration.
            loss.backward()
            outputs.append(z)
    # Updates internal evaluation
    metric.update(label, outputs)
    # Make one step of parameter update. Trainer needs to know the
    # batch size of data to normalize the gradient by 1/batch_size.
    trainer.step(batch.data[0].shape[0])
# Gets the evaluation result.
name, acc = metric.get()
# Reset evaluation result to initial state.
metric.reset()
print('training acc at epoch %d: %s=%f'%(i, name, acc))
return handwritten_net

```

```
trained_model_mx = training_procedure(model_mx, train_data_mx)
```



```
training acc at epoch 0: accuracy=0.877583
training acc at epoch 1: accuracy=0.967208
training acc at epoch 2: accuracy=0.976396
training acc at epoch 3: accuracy=0.983000
training acc at epoch 4: accuracy=0.986604
training acc at epoch 5: accuracy=0.987417
training acc at epoch 6: accuracy=0.989854
training acc at epoch 7: accuracy=0.991729
training acc at epoch 8: accuracy=0.992167
training acc at epoch 9: accuracy=0.993396
training acc at epoch 10: accuracy=0.994979
training acc at epoch 11: accuracy=0.994208
training acc at epoch 12: accuracy=0.995000
training acc at epoch 13: accuracy=0.995146
training acc at epoch 14: accuracy=0.996687
CPU times: user 34.8 s, sys: 7.5 s, total: 42.3 s
Wall time: 29.5 s
```

```
%%time
# TENSORFLOW
chosen_tf_optimizer = keras.optimizers.Adam(learning_rate=0.001, beta_1=0.9, beta_2=0.999, amsgrad=False)
model_tf.compile(loss=keras.losses.categorical_crossentropy, optimizer=chosen_tf_optimizer, metrics=['accuracy'])
steps_per_epoch = X_train_tf.shape[0]//BATCH_SIZE
validation_steps = X_validation_tf.shape[0]//BATCH_SIZE
model_tf.fit_generator(train_generator_tf, steps_per_epoch=steps_per_epoch, epochs=EPOCHS,
                      validation_data=validation_generator_tf, validation_steps=validation_steps,
                      shuffle=True, callbacks=[])
```



```

WARNING:tensorflow:From <timed exec>:8: Model.fit_generator (from tensorflow.python.keras.engine.training) is depreca
Instructions for updating:
Please use Model.fit, which supports generators.
WARNING:tensorflow:sample_weight modes were coerced from
...
to
['...']
WARNING:tensorflow:sample_weight modes were coerced from
...
to
['...']
Train for 240 steps, validate for 60 steps
Epoch 1/15
240/240 [=====] - 9s 38ms/step - loss: 0.7762 - accuracy: 0.8675 - val_loss: 0.1144 - val_ac
Epoch 2/15
240/240 [=====] - 2s 10ms/step - loss: 0.0921 - accuracy: 0.9716 - val_loss: 0.0810 - val_ac
Epoch 3/15
240/240 [=====] - 2s 10ms/step - loss: 0.0641 - accuracy: 0.9804 - val_loss: 0.0695 - val_ac
Epoch 4/15
240/240 [=====] - 2s 10ms/step - loss: 0.0493 - accuracy: 0.9851 - val_loss: 0.0610 - val_ac
Epoch 5/15
240/240 [=====] - 2s 10ms/step - loss: 0.0392 - accuracy: 0.9879 - val_loss: 0.0622 - val_ac
Epoch 6/15
240/240 [=====] - 2s 10ms/step - loss: 0.0325 - accuracy: 0.9896 - val_loss: 0.0542 - val_ac
Epoch 7/15
240/240 [=====] - 2s 10ms/step - loss: 0.0280 - accuracy: 0.9912 - val_loss: 0.0497 - val_ac
Epoch 8/15
240/240 [=====] - 2s 10ms/step - loss: 0.0241 - accuracy: 0.9922 - val_loss: 0.0563 - val_ac
Epoch 9/15
240/240 [=====] - 2s 10ms/step - loss: 0.0217 - accuracy: 0.9928 - val_loss: 0.0466 - val_ac
Epoch 10/15
240/240 [=====] - 2s 10ms/step - loss: 0.0205 - accuracy: 0.9936 - val_loss: 0.0567 - val_ac
Epoch 11/15
240/240 [=====] - 2s 10ms/step - loss: 0.0168 - accuracy: 0.9946 - val_loss: 0.0485 - val_ac
Epoch 12/15
240/240 [=====] - 2s 10ms/step - loss: 0.0149 - accuracy: 0.9950 - val_loss: 0.0600 - val_ac
Epoch 13/15
240/240 [=====] - 2s 10ms/step - loss: 0.0151 - accuracy: 0.9949 - val_loss: 0.0517 - val_ac
Epoch 14/15
240/240 [=====] - 2s 10ms/step - loss: 0.0107 - accuracy: 0.9967 - val_loss: 0.0499 - val_ac
Epoch 15/15
240/240 [=====] - 2s 10ms/step - loss: 0.0171 - accuracy: 0.9944 - val_loss: 0.0519 - val_ac
CPU times: user 47.8 s, sys: 6.16 s, total: 54 s
Wall time: 42.8 s

```

## ▼ 6. Evaluate models

```

%%time
# MXNET
# TEST THE NETWORK
metric = mx.metric.Accuracy()
# Reset the test data iterator.
test_data_mx.reset()
# Loop over the test data iterator.
for batch in test_data_mx:
    # Splits test data into multiple slices along batch_axis
    # and copy each slice into a context.
    data = gluon.utils.split_and_load(batch.data[0], ctx_list=ctx, batch_axis=0)
    # Splits validation label into multiple slices along batch_axis
    # and copy each slice into a context.
    label = gluon.utils.split_and_load(batch.label[0], ctx_list=ctx, batch_axis=0)
    outputs = []
    for x in data:
        outputs.append(model_mx(x))
    # Updates internal evaluation
    metric.update(label, outputs)
print('MXnet - Test %s : %f'%metric.get())
assert metric.get()[1] > 0.90

```

```

↳ MXnet - Test accuracy : 0.984900
   CPU times: user 188 ms, sys: 30.5 ms, total: 218 ms
   Wall time: 151 ms

```

```

%%time
# TENSORFLOW
score = model_tf.evaluate(test['features'], to_categorical(test['labels']), verbose=0)
#print('Test loss:', score[0])
print('TensorFlow - Test accuracy:', score[1])
assert score[1] > 0.90

```

```

↳ TensorFlow - Test accuracy: 0.9864
   CPU times: user 1.25 s, sys: 192 ms, total: 1.44 s
   Wall time: 1.19 s

```

