1.A. Canonical Correlation Analysis:

Given the problem,

leads to an optimization problem.

1. Pormolate the Kogzangian fru -

$$\mathcal{L} = \omega_{\mathcal{H}}^{T} (\lambda_{y} \omega_{y} - \frac{\lambda_{x}}{2} (\omega_{x}^{T} (\lambda_{x} \omega_{x-1}) - \frac{\lambda_{y}}{2} (\omega_{y}^{T} (y_{y} \omega_{y}^{-1}))$$

2. Taking differentials and silve VS=0

3. Given the consteaints.

wing for makinaly coulding components; In= 1 y= 1.

Chywy =
$$\lambda (\gamma_{\chi} \omega_{\chi})$$
 ($\gamma_{\chi} \omega_{\chi} = \lambda (\gamma_{\chi} \omega_{\chi})$ ($\gamma_{\chi} \omega_{\chi} = \lambda (\gamma_{\chi} \omega_{\chi})$) ($\gamma_{\chi} \omega_{\chi} = \lambda (\gamma_{\chi} \omega_{\chi})$

System of equation, (cyn o) [wy] = > [(un o) [wy].

1 K Show

Solution to CEA is the eigenvector amounted with largest eigenvalue to,

1. eigenide repeths the Maximus possible coeuletai betien the projection of x and 4.

2. CEA for High Binemend Data.

To show that optical solubin war, wy for cear as a linear combination of data matries X and V.

Note cert finds linear projection wx, wy men that coccelation between projected date Nwn and Ywy is maxim

1. Repusat was , wy in pany dala.

Ket us prone tet w x 2 X x y are optical when .

- Projection of aleta. onto we i uryan.

Xwn z X (xx) 2 (XX) X2.

Ywy z Y (Yxy) 2 (YT4) Xy.

Coerelhis can be experted inters of Xn/xy.

- Openality.

Decorpose w, wy who composents:

" Span : they are in spang data natrices X & Y.

· Onlygood ! There are orlingood to data natives .

YT wy = 0.

Jus,

w= = w= + w= (n) , w= = X xx w= wy = wy (n) + wy (n) wy (s) = Yxy.

In the original problem,

replace who won & XXn, YXy.

given (XXn) T Chy (YXy) maximine.

with (XXn) T Chi (XXn) = 1

(YQj) T Cyy (YXy) = 1

given. X Ty Byy Ky naxuming

With X Ty Byy Ky = 1

X Ty Byy Ky = 1

More: same structure, e as original CEA.

Tollowy same as Excurse, ne got the engenture probles

[O 4xy] = 1 (4xy) [dxy]

O Byy O [dxy].

c. Some as 1b, multipry both sides of eigenetic by (x n xy) T and find the point that hereinness the obsjeche is the one with highest eigenvelock.

1) wa = X da

so we can compute war, by with dandy

sheet06-programming

November 25, 2024

Exercises for the course Machine Learning for Data Science Winter Semester 2024/25

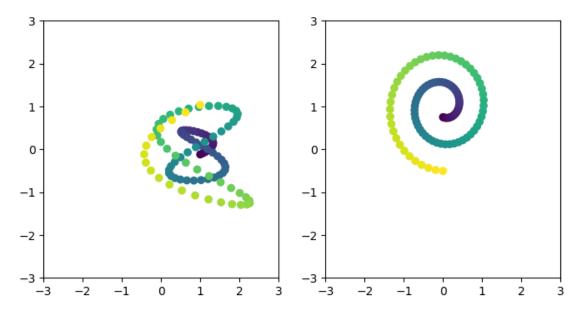
G. Montavon Institute of Computer Science Department of Mathematics and Computer Science Freie Universität Berlin

Exercise Sheet 6 (programming part)

In this exercise, we consider canonical correlation analysis (CCA) on two simple problems, one in low dimensions and one in high dimensions. The goal is to implement the original CCA procedure, and the CCA variant for high-dimensional data, in order to handle both cases. The first dataset consists of two trajectories in two dimensions. The dataset is extracted and plotted below. The first data points are shown in dark blue, and the last ones are shown in yellow.

```
[1]: import numpy
  import matplotlib
  %matplotlib inline
  from matplotlib import pyplot as plt
  import utils

X,Y = utils.getdata()
  p1,p2 = utils.plotdata(X,Y)
```



For these two trajetories, that can be understood as two different modalities of the same data, we would like determine under which projections they appear maximally correlated.

0.1 Exercise 3: Implementing CCA (25 P)

As stated in the lecture, the CCA problem in its original form consists of maximizing the cross-correlation objective:

$$J(w_x,w_y) = w_x^\top C_{xy} w_y$$

subject to autocorrelation constraints $w_x^{\top} C_{xx} w_x = 1$ and $w_y^{\top} C_{yy} w_y = 1$. Using the method of Lagrange multipliers, this optimization problem can be reduced to finding the first eigenvector of the generalized eigenvalue problem:

$$\begin{bmatrix} 0 & C_{xy} \\ C_{yx} & 0 \end{bmatrix} \begin{bmatrix} w_x \\ w_y \end{bmatrix} = \lambda \begin{bmatrix} C_{xx} & 0 \\ 0 & C_{yy} \end{bmatrix} \begin{bmatrix} w_x \\ w_y \end{bmatrix}$$

Your first task is to write a function that solves this generalized eigenvalue problem. The function you need to implement receives two matrices X and Y of size $d1 \times N$ and $d2 \times N$ respectively. It should return two vectors of size d1 and d2 corresponding to the projections associated to the modalities X and Y. (Hint: Note that the data matrices X and Y have not been centered yet.)

```
[2]: import numpy as np
     def CCA(X, Y):
         # Center the data
         X_centered = X - np.mean(X, axis=1, keepdims=True)
         Y_centered = Y - np.mean(Y, axis=1, keepdims=True)
         # Covariance matrices
         C xx = np.cov(X centered)
         C_yy = np.cov(Y_centered)
         C_xy = np.cov(X_centered, Y_centered)[:X.shape[0], X.shape[0]:]
         # Form the generalized eigenvalue problem matrix
         C = np.block([[np.zeros_like(C_xx), C_xy],
                       [C_xy.T, np.zeros_like(C_yy)]])
         D = np.block([[C_xx, np.zeros_like(C_xy)],
                       [np.zeros_like(C_xy.T), C_yy]])
         # Solve the generalized eigenvalue problem
         eigvals, eigvecs = np.linalg.eig(np.linalg.pinv(D) @ C)
         # Extract the first eigenvector (corresponding to the largest eigenvalue)
         idx = np.argmax(eigvals)
```

```
w = eigvecs[:, idx]

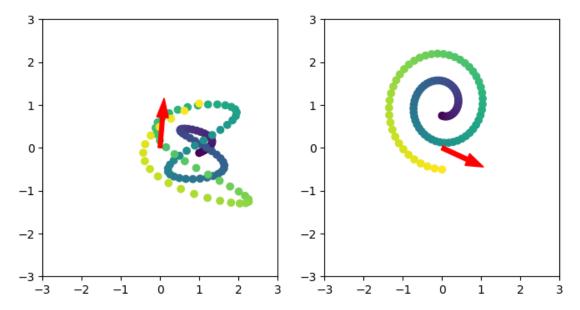
# Separate the eigenvector into projections for X and Y
wx = w[:X.shape[0]]
wy = w[X.shape[0]:]

return wx, wy
```

The function can now be called with our dataset. The learned projection vectors w_x and w_y are plotted as red arrows.

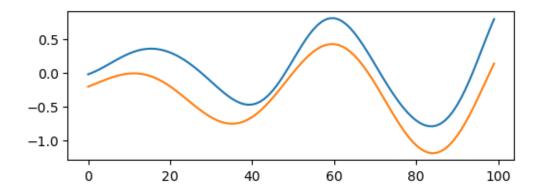
```
[3]: wx,wy = CCA(X,Y)

p1,p2 = utils.plotdata(X,Y)
p1.arrow(0,0,1*wx[0],1*wx[1],color='red',width=0.1)
p2.arrow(0,0,1*wy[0],1*wy[1],color='red',width=0.1)
plt.show()
```



In each modality, the arrow points in a specific direction (note that the optimal CCA directions are defined up to a sign flip of both w_x and w_y). Furthermore, we can verify CCA has learned a meaningful solution by projecting the data on it.

```
[4]: plt.figure(figsize=(6,2))
  plt.plot(wx.dot(X))
  plt.plot(wy.dot(Y))
  plt.show()
```



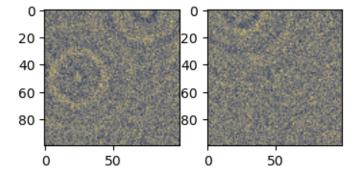
Clearly, the data is correlated in the projected space.

0.2 Exercise 4: Implementing CCA for High Dimensions (25 P)

In the second part of the exercise, we consider the case where the data is high dimensional (with $d \gg N$). Such high-dimensionality occurs for example, when input data are images. We consider the scenario where sources emit spatially, and two (noisy) receivers measure the spatial field at different locations. We would like to identify the signal that is common to the two measured locations, e.g. a given source emitting at a given frequency. We first load the data and show one example.

```
[5]: X,Y = utils.getHDdata()

utils.plotHDdata(X[:,0],Y[:,0])
plt.show()
```



Several sources can be perceived, however, there is a significant level of noise. Here again, we will use CCA to find subspaces where the two modalities are maximally correlated. In this example, because there are many more dimensions than there are data points, it is more advantageous to solve the alternate formulation of CCA in terms of the weightings α_x and α_y . Your task is to implement the latter CCA solver. Like the original CCA solver, it receives two data matrices of size $\mathtt{d1} \times \mathtt{N}$ and $\mathtt{d2} \times \mathtt{N}$ respectively as input, and should return the associate CCA directions (two

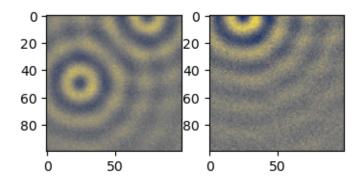
vectors of respective sizes d1 and d2).

```
[6]: import numpy as np
     from utils import getHDdata, plotHDdata
     def CCA_HD(X, Y):
         n n n
         Canonical Correlation Analysis for high-dimensional data.
         Optimized for d \gg N.
         11 11 11
         # Center the data
         X_centered = X - np.mean(X, axis=0, keepdims=True)
         Y_centered = Y - np.mean(Y, axis=0, keepdims=True)
         # Perform SVD on X centered and Y centered to reduce dimensionality
         U_x, S_x, V_x = np.linalg.svd(X_centered, full_matrices=False)
         U_y, S_y, V_y = np.linalg.svd(Y_centered, full_matrices=False)
         # Reduce the data to the span of the largest singular vectors
         X_reduced = np.diag(S_x) @ V_x
         Y_reduced = np.diag(S_y) @ V_y
         # Compute the cross-covariance matrix in the reduced space
         C_xy = X_reduced @ Y_reduced.T / (X.shape[0] - 1)
         # Solve the eigenvalue problem in the reduced space
         U, S, V = np.linalg.svd(C_xy)
         # The top singular vector corresponds to the optimal directions
         alpha_x = U[:, 0]
         alpha_y = V[0, :]
         # Convert alpha_x and alpha_y back to original dimensions
         wx = U_x @ alpha_x
         wy = U_y @ alpha_y
         return wx, wy
```

We now call the function we have implemented with a training sequence of 100 pairs of images. Because the returned solution is of same dimensions as the inputs, it can be rendered in a similar fashion.

```
[7]: wx,wy = CCA_HD(X,Y)

utils.plotHDdata(wx,wy)
plt.show()
```



Here, we can clearly see a common factor that has been extracted between the two fields, specifically a point source emitting at a particular frequency. The sequence of image pairs can now be projected on these two filters:

```
[8]: plt.figure(figsize=(6,2))
  plt.plot(wx.dot(X))
  plt.plot(wy.dot(Y))
  plt.show()
```

