1 Module 1

Exercise 1

(a)

The basis vector is a vector that starts from an atom and goes to the closer atom of the same type. For example we can choose the leftmost Na^+ as the origin and we draw a vector until the second Na^+ . The base unit cell is made of a couple $Na^+ + Cl^-$

(b)

Let us take a Na^+ atom at position x and suppose that the chain is infinitely long both at the left and at the right. Each Cl^- atom exerts an attractive force (negative potential) on the Na^+ atom and each other Na^+ exerts a repulsive one (positive potential). Hence, in atomic units

$$V(x) = 2 \cdot \left[\frac{1}{a} - \frac{1}{2a} + \frac{1}{3a} - \dots \right] = \frac{2}{a} \sum_{n=1}^{+\infty} \frac{(-1)^{n+1}}{n} = \frac{2\ln 2}{a}$$

Then the Madelung constant is $M = 2 \ln 2$

(c)

A consequence of the presence of only a finite number of atoms is that symmetry is broken: each atom has now a different number of atoms on its right and left (except for the central one) and this effect becomes smaller as the number of atoms increases (more atoms can be approximated as "centrals"). Remember that the Madelung constant is a geometrical factor related to the energy per molecule in the crystal. One can now proceed in two different ways which will be equivalent in the limit of large N as shown in figure 1.

1. Neglect border effects and consider each atom as "central". This can be reasonable since the Coulomb potential decreases rapidly with the atom index. In this case the total energy of the lattice is approximately $U = NU_i$ where

$$U_i = 2\sum_{n=1}^{N/2} \frac{(-1)^n}{na} = \frac{\alpha}{a}$$

and α is the Madelung constant.

2. Consider the border effects and the fact that not all atoms have the same energy. In this case the value of the Madelung constant would depend on the chosen atom, so we calculate an "average" Madelung constant by calculating the average energy of each molecule in the crystal as $V_{tot}/N_{molecules} = V_{tot}/(N/2)$ and use that expression to evaluate the Madelung constant. The total energy of the system can be computed as a sum over all the particles' interactions. If we begin the chain with a Na^+ atom, the charge of the n-th atom in the chain is in atomic units $(-1)^n$, hence

$$U = \frac{1}{2} \sum_{i \neq j} \frac{(-1)^{i} (-1)^{j}}{r_{ij}} = \frac{1}{2} \sum_{i \neq j} \frac{(-1)^{i+j}}{|i-j|} = \frac{N\alpha}{2a}$$

and this provides an estimation for the Madelung constant α .

The Madelung constant for both models as a function of the number of atoms is plotted in figure 1.

(d)

To simply the calculation we here neglect border effects and calculate the energy of the crystal as the sum of the electrostatic energy and the Pauli repulsion energy (nearest neighbour only). Let us denote with a the interatomic distance of the lattice. Each atom in the center of the crystal has energy equal to

$$U_i(a) = 2\sum_{i \neq j} U_{ij}(a) = 2\left(\lambda e^{-a/\rho} - \sum_{i \neq j} \frac{1}{r_{ij}}\right) = 2\left(\lambda e^{-a/\rho} - \sum_{n=1}^{N/2} \frac{(-1)^n}{n}\right)$$

The equilibrium distance can be obtained by searching the minimum of the energy per atom

$$\frac{\partial U_i}{\partial a} = 0$$

1

The equation can be solved numerically and the tresult is reported in figure 2

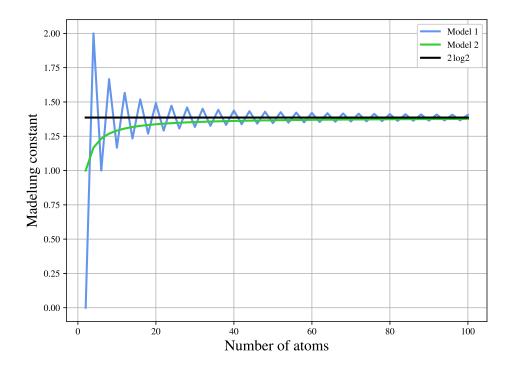


Figure 1: Madelung constant as a function of the number of atoms

Exercise 2

(a)

$$N = 12 \cdot \frac{1}{6} + 2 \cdot \frac{1}{2} + 3 \cdot 1 = 6$$

(b)

Let us consider the tetrahedon composed by two adiacent atoms in the lowest layer, the central atom in the lowest layer and the closest atom in the middle layer. Since the tetrahedon is regular, all the sides are of the same length. The distance x of the projection of the middle layer point to the lowest layer from a vertex of the triangle is

$$x = \frac{a}{2} \frac{1}{\cos \frac{\theta}{2}} = \frac{a}{\sqrt{3}}$$

Hence the height of the middle point is

$$h = \sqrt{a^2 - \frac{a^2}{3}} = \sqrt{\frac{2}{3}}a$$

hence the height of the base cell is $c = 2h = \sqrt{8/3}a$ and the c/a ratio is $\sqrt{8/3}$.

(c)

Just substitute a = 2r and calculate directly from the general formula.

Exercise 3

Let us choose a set of parallel planes. From this set we choose the plane closer to the origin. The idea is to calculate the distance between planes as the distance from the origin to this plane. Let us suppose that the plane intersects the x, y, z axes of a cube respectively in positions x_1, x_2, x_3 : the crystal requires

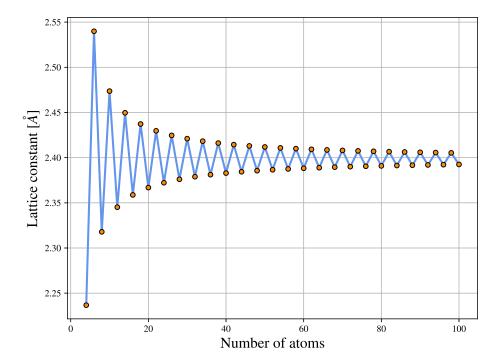


Figure 2

that

$$x_1 = n_1 a$$

$$x_2 = n_2 a$$

$$x_3 = n_3 a$$

where a is the lattice constant.

The Miller indices of the plane are defined as

$$(hkl) \equiv (h,k,l) \equiv C\left(\frac{1}{n_1a},\frac{1}{n_2a},\frac{1}{n_3a}\right)$$

where N is a constant that guarantees that (hkl) is a set of integer numbers (the minimum integers that keeps the reciprocal proportionality). Without loss of generalisation we can assume N to be equal to 1; in fact, otherwise, N would be a common multiple of n_1, n_2, n_3 and we can return to the case above defining $n'_k = n_k/N \quad \forall k$.

If one takes the general equation of a plane

$$ax + by + cz + d = 0$$

it is possible to define the distance of the plane π to a point P via the formula

$$d(P,\pi) = \frac{|ax_p + by_p + cz_p + d|}{\sqrt{a^2 + b^2 + c^2}}$$
(1)

Equation 1 can be rewritten as

$$\frac{x}{c_1} + \frac{y}{c_2} + \frac{y}{c_3} = 1 \tag{2}$$

and in this form the parameters c_1, c_2, c_3 assume the geometrical significance of intercepts of the axes (just check by setting x, y, z equal to 0 in couples). This particularly useful in our case, since we can write the equation of our plane as

$$\frac{x}{n_1 a} + \frac{y}{n_2 b} + \frac{y}{c_3} = 1$$

and using 1 for the origin

$$d(O,\pi) = \frac{1}{\sqrt{(\frac{1}{n_1 a})^2 + (\frac{1}{n_2 a})^2 + (\frac{1}{n_3 a})^2}}$$

or

$$d(O,\pi) = \frac{a}{\sqrt{h^2 + k^2 + l^2}}$$

Exercise 4

(a)

- 1. (010)
- 2. (210)
- 3. (010)
- 4. (120)
- 5. (010)
- 6. (100)

(c) and (d)

Diffraction occurs if the von Laue condition is satisfied, that its

$$2\mathbf{k} \cdot \mathbf{G} + G^2 = 0$$

- 1. if $\mathbf{k} \cdot \mathbf{G} > 0$ the above expression is always positive, hence the result is trivial
- 2. if $\mathbf{k} \cdot \mathbf{G} < 0$ then

$$\mathbf{k} \cdot veG = -k_gG > -\frac{G^2}{2}$$

hence

$$2\mathbf{k} \cdot \mathbf{G} + G^2 > -2\frac{G^2}{2} + G^2 = 0$$

Exercise 7

(a)

Suppose that we have N sites, and n of them are vacancies. Let us calculate the configurational entropy of the system as

$$S = k_B \ln \omega$$

If we imagine the sites as a 1D sequence we can calculate the number of possible ways to combine n objects of type A with N-n objects of type B. In this case

$$\omega(N,n) = \frac{N!}{n!(N-n)!}$$

Let us take the logarithm of this expression and use the Stirling's approximation

$$\ln \omega = \ln(N!) - \ln(n!) - \ln((N-n)!) \approx N \ln N - n \ln n - (N-n) \ln(N-n)$$

If temperature and pressure are constant, then the equilibrium state of the system is the one that minimizes the free energy

$$G = H - TS = U + pV - TS$$

Since the free energy of the lattice without vacancies is a constant, we can restrict the analysis to minimize the vacancies contribution only which practically means that we can minimize

$$(\Delta G)_{\text{vac}} = G_{\text{tot}} - G_{\text{no vacancies}}$$

If we assume pressure and temperature constant the expression becomes

$$\Delta G = nE_f + npV_f - T\Delta S$$

where E_f is the energy required to remove a site and V_f is the volume of a site. We can search for the minimum in this way

$$0 = \frac{d\Delta G}{dn} = E - f + pV_f - k_B \ln\left(\frac{N-n}{n}\right)$$

$$\frac{E_f}{k_B T} = \ln\left(\frac{N-n}{n}\right)$$

or

$$\frac{n}{N-n} = \exp\left(-\frac{E_f}{k_B T}\right) \, \exp\left(-\frac{p V_f}{k_B T}\right)$$

and if $n \ll N$

$$c_v = \frac{n}{N} = e^{-E_f/k_B T} e^{-pV/k_B T}$$
 (3)

Pressure is just a particular case of the stress (it is just the case in which the force is orthogonal to the surface). Hence equation 3 can be generalised to an applied stress with module σ

$$c_v = \frac{n}{N} = e^{-E_f/k_B T} e^{-\sigma V/k_B T}$$

(b)

The formation energy is the energy required to move an atom from the site to the surface of the lattice and in equation 3 is represented by E_f . When an atom is removed the lattice get deformed and it generates an internal stress. The deformation causes a variation in the volume and the difference between the final state of the system (after moving the atom) and the initial state is the formation volume.

2 Module 2

I start with a brief review of useful concepts to go trough Kittel's book

General information about waves

Let us consider the wave equation

$$\frac{\partial^2 u(x,t)}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 u(x,t)}{\partial t^2}$$

One solution is the function

$$u(x,t) = Ae^{i(kx - \omega t)} \tag{4}$$

where k and ω are two numbers such that $v^2 = \omega^2/k^2$ and the minus sign at the exponent is purely conventional.

One first important consideration is that

$$u(x - vt, 0) = Ae^{i(kx - kvt)} = Ae^{i(kx - \omega t)} = u(x, t)$$

this means that the value of the function u at position x at time t is equal to the value of the function t seconds before, in a position traslated from x to the same distance that a particle with velocity v would cover in the time t. In other words, these types of solutions are rigid waves that traslates in time and space without deforming with velocity v. If at time t the point of a wave is at position x_1 where do we find it at time $t_2 = t + t_0$? From what just said the same point will be at position $x(t_2) = x(t) + vt_0$. In general a wave point motion equation is $x(t) = x(0) + vt = x(0) + \frac{\omega}{k}t$ so it moves with a velocity v (called $phase\ velocity$).

Since the wave equation is a linear equation (derivatives do not "mix"), a linear combination of functions of the previous form is still a solution. Hence, chosen k_1, \ldots, k_N and $\omega_1, \ldots, \omega_n$ such that $\omega_i/k_i = v$, the function

$$u(x,t) = \sum_{n=1}^{N} A(k_n)e^{i(k_n x - \omega(k_n)t)}$$

is still a solution of the equation (can be verified by direct substitution and imposing polynomials identity). In particular we can take a "continous" linear combination such that

$$u(x,t) = \int_{-\infty}^{+\infty} A(k)e^{i(kx - \omega(k)t)} dk$$
 (5)

This function can be viewed as the Fouries transform of a function $u(k,t) = A(k)e^{ikx}$. Every function (wave) A(k) sufficiently regular can be written in terms of a linear combination of sines and cosines

(indeformable waves).

Now suppose that A(k) is peaked around a value k_0 so that we can expand $\omega(k)$ at first order

$$\omega(k) \simeq \omega(k_0) + \frac{d\omega(k)}{dk}(k - k_0)$$

Equation 5 can be rewritten as

$$u(x,y) \simeq A(k_0)e^{i(k_0x-w(k_0)t)} \int_{-\infty}^{+\infty} e^{i(\omega'(k)(k-k_0))t} dk \equiv f(x,t) \cdot g(t)$$

The first factor $f(x,t) = A(k_0)e^{i(k_0x - w(k_0)t)}$ is a plane wave with phase velocity $\omega_0 \equiv \omega(k_0)$, while the second factor $g(t) = \int_{-\infty}^{+\infty} e^{i(\omega'(k)(k-k_0))t} dk$ modulates the wave in time as an envelope that moves with velocity $\omega'(k)$, called the *group velocity*.

Phonons and quantization

Phonons

Let us consider a lattice with monoatomic base. The force acting on the n-th atom in the chain is

$$F_n = C(x_{n+1} + x_{n-1} - 2x_n)$$

where x_k indicates the displacement of the k-th particle with respect to its equilibrium position. We are interested in solutions of the type

$$x_n(t) = A \exp(i(nka - \omega_n t))$$

that is waves of the form as in 4. By popping this expression into the Newton motion equation for the n-th particle, we get out that in order to satisfy the equality the following relation must hold

$$\omega(k) = 2\sqrt{\frac{C}{M}} \left| \sin\left(\frac{ka}{2}\right) \right|$$

this is called the dispersion relation and (intuitively) indicates the relationship between the time periodicity (ω) and space periodicity (k).

For $|k| < \pi/a$ we say that we are in the Brillouin zone of the crystal: the border's values $k = \pm \pi/a$ represents the maximum value for $\omega(k)$ and between this range all possible values of $\omega(k)$ are covered: in fact it is easy to see that $\omega(k) = \omega(2k + N\pi/a)$, $N \in \mathbb{N}$ (see plots on Kittel for better intuition). Remeber that $2N\pi/a$ is a reciprocal lattice vector! The particualr significance of the borders of the Brillouin zone is that the wave is standing: there is no space dependence (we will examin this point later better, but for a visual understanding see https://www.khanacademy.org/science/high-school-physics/waves-and-sound/standing-waves-2/v/standing-waves-on-strings). Just note that in this case $x_n(t) = (-1)^n A \exp(i\omega_0 t)$ and

$$x_{n+1}(t)/x_n(t) = -1$$

or, in other words, each atom moves in the opposite direction of the one before: this implies that the center of mass of the chain stays fixed (and explains why phonons do not carry physical momentum).

Quantization

Let us consider an infinitesimal volume dV centered in \mathbf{r} of a monoatomic crystal and let us consider a standing wave of the type

$$u(t) = u_0 \cos(kx) \cos(\omega t) \tag{6}$$

Stationarity requires that $nKa = \pi$ where a is the lattice constant.

Now let us use the quantum virial theorem to calculate

$$\left(n + \frac{1}{2}\right)\hbar\omega = \langle H \rangle = \langle T \rangle + \langle V \rangle = 2 \langle T \rangle$$

To estimate $\langle T \rangle$ we can use the energy density of the crystal (Ehrenfest theorem allows us to use classical expression for QM expectation value). Given an infinitesimal volume dV at position \mathbf{r} whose displacement from equilibrium position is given by 6 its kinetic energy is

$$d\left\langle T\right\rangle =\frac{1}{2}\rho(\mathbf{r})\dot{u}^{2}(t)\,dV=\frac{1}{2}u_{0}^{2}\omega^{2}\cos^{2}(kx)\sin^{2}(\omega t)\,dV$$

Hence the kinetic energy of the crystal is

$$\langle T \rangle = \frac{1}{2} \rho(\mathbf{r}) \dot{u}^2(t) \, dV = \frac{1}{2} u_0^2 \omega^2 \sin^2(\omega t) \int_0^{N_z a_z} \int_0^{N_y a_y} \int_0^{N_x a_x} \rho(\mathbf{r}) \cos^2(kx) \, dx dy dz \tag{7}$$

Now, supposing that $N_x a_x = N_y a_y = N_z a_z$ and noting that

$$\int_0^{Na} \cos^2(kx) \, dx = \int_0^{Nka} \cos^2 t \, dt = \frac{1}{2}$$

because $Nka = \pi$, expression 7 becomes

$$\langle T \rangle = \frac{1}{4} M u_0^2 \omega^2 \sin^2(\omega t)$$

and averaging over time

$$\langle T \rangle = \frac{1}{8} M u_0^2 \omega^2 \tag{8}$$

and inserting back into 2, rearrangin terms

$$u_0^2 = 4\left(n + \frac{1}{2}\right) \frac{\hbar}{M\omega}$$

For each value of n we say that the wave is oscillating with one precise mode of oscillation: for some misterious reasons one can associate to an oscillating wave with energy $E_n = (n+1/2) \hbar \omega n$ quanta (particles) called phonons.

Density of states

The total energy of the system can be written as

$$U = \sum_{p} \sum_{k} \langle n_{k,p} \rangle \, \hbar \omega_p \tag{9}$$

where $\langle n_{k,p} \rangle$ is the average number of phonons per mode of polarization p and wavevector k. In particular this last factor is given by the Planck distribution (canonical ensemble) and it is

$$\langle n \rangle = \frac{1}{\exp(\beta \hbar \omega) - 1}$$

which allows us to rewrite 9 as

$$\sum_{p} \sum_{k} \frac{\hbar \omega_{k,p}}{exp(\hbar \omega_{k,p}/T) - 1} = \sum_{p} \int d\omega \ D_{p}(\omega) \frac{\hbar \omega_{k,p}}{exp(\hbar \omega_{k,p}/T) - 1}$$

for a suitable choice of the function $D_p(\omega)$ which we call density of states. The interesting point is how to compute this function (see exercise 2).

Exercise 1

(a)

Let us consider a chain of N atom ... bla bla bla ...