

Monte Carlo Simulation of 2D Ising Model

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Abstract

The aim of this report is to present the results obtained using Monte Carlo simulation for the Ising model and XY model. Two main algorithms have been implemented to simulate the behaviour of the system: the Metropolis Monte Carlo algorithm and the Hoshen-Kopelman cluster finding algorithm. Both algorithms have been used to extrapolate relevant physical quantities, such as the magnetization, the magnetic susceptibility and the specific heat. Finite-size scaling has also been used in order to calculate the critical exponents. Using the Metropolis algorithm we were able to prove the universality of the critical exponents of the Ising model. The Hoshen-Kopelman algorithm is also successfully implemented for the calculation of the helicity modulus.

I. INTRODUCTION

In this report we aim to investigate the physics of the Ising and XY models through the implementation of Monte Carlo algorithms. The Monte Carlo algorithms are a class of algorithms in which "random" numbers play an essential role [1]. This method has been widely and successfully implemented in the past decades to simulate the behaviour of physical systems in order to extrapolate information regarding their static properties.

The Hoshen Kopelman algorithm is a cluster finding algorithm that has been implemented as a non-recursive alternative to the Swendsen-Wang algorithm. It is based on the more famous Union-Find algorithm.

In section II the interaction model and the working principles of the two algorithms are outlined. In section III the numerical results obtained for specific heat, magnetization, magnetic susceptibility, Binder cumulant, finite-size scaling and XY Model.

II. METHODS

While implementing the models and algorithm outlined in this section, we have considered $k_B = 1$, $J = 1$ and a unitary distance between the lattice sites.

I. Ising Model

The Ising Model describes the dynamics of a $L \times L$ lattice of spins which can take values of ± 1 . The Hamiltonian of the system in absence of an external magnetic field is

described by

$$H = -J \sum_{\langle ij \rangle} s_i s_j \quad (1)$$

where s_i represents the spin associated with the i th site. When J is taken to be larger than zero the system favours parallel alignment of adjacent spins (ferromagnetic behaviour). For $J < 0$ anti-parallel alignment is preferable (antiferromagnetic behaviour).

The partition function for the system is given by

$$\mathcal{Z} = \sum_{\{s_i\}} e^{-\beta H(s_i)} \quad (2)$$

which is dependent on the temperature of the system, contained in β .

II. XY Model

The XY Model is a generalization of the Ising model in which the spins can take on any direction in the 2D plane. The Hamiltonian for this model in the absence of a magnetic field can be written as:

$$H = -J \sum_{\langle ij \rangle} \cos(\theta_i - \theta_j) \quad (3)$$

where θ_i is the angle between the direction of the spin of the i -th site and an arbitrarily chosen axis.

The XY model behaviour has been simulated through a Monte Carlo simulation using the Hoshen-Kopelman algorithm, which is described in part IV of this section.

III. Metropolis Monte Carlo Algorithm

The Metropolis Monte Carlo algorithm is an algorithm in which the information regarding different distributions of a system is stored in a Markov chain. In an uncorrelated chain, the probability of occurrence of a certain event is given by the product of the single probabilities lead up to the event itself. In a Markov chain, **(there are a bit too many 'based' starting here :b)** the probability of occurrence for a sequence of events is defined based on the transition probability from one event (in this case, configuration) to another. The Metropolis Monte Carlo method is based on a Markov chain of configurations based on a given stationary distribution, which in our case is represented by the Boltzmann distribution. In order to ensure a correct representation of the phase space, the Markov chain has to be ergodic, which means that the probability of occurrence of a certain configuration **(hmm, ρ , X are not defined before, this is a tad confusing)** $\rho(X, t)$ has to be independent of t when t is large.

Considering the probability of transition between two generic states leads to the *detailed balance solution*

$$T(X \rightarrow X') = \omega_{XX'} A_{XX'} \quad (4)$$

where ω is a symmetric matrix and represent the trial step probability, while $A_{XX'}$ represents the acceptance probability.

In the simulation of the Ising model with the Metropolis Algorithm,

$$\omega_{XX'} = \frac{1}{L^2} \quad \text{if } X \text{ and } X' \text{ differ by one spin} \quad (5)$$

$$\omega_{XX'} = 0 \quad \text{otherwise} \quad (6)$$

A spin, or more than one, are then selected at random and flipped. The difference in energy between the two configurations is then calculated. if the results is bigger than zero, the new configuration is accepted with probability $e^{-\beta\Delta E}$, while if $\Delta E < 0$, the new state is always adopted.

IV. Hoshen-Kopelman Algorithm

Before applying the Hoshen-Kopelman algorithm it is necessary to find the links between lattice sites. For each link, we consider two possible cases; in the first one, the spins are opposite and the interaction is deleted; if the spins are equal the interaction is deleted with probability $e^{2\beta J}$ and frozen with probability $1 - e^{-2\beta J}$. In the simulation, determining whether a link is frozen or not implies generating a "random" number, which means that the overall **hmm, simulation doesnt really seem like the right word here...** simulation still belongs to the Monte Carlo family of algorithms.

Once the links are found, one can apply the Hoshen-Kopelman cluster finding algorithm, which can be divided in two steps. The first one consists in checking the links to the left and upwards for each site of the lattice. If there is a link between two sites, they are assigned to the same cluster. **This second step is not very clear to me. do you mean the boundary check?** The second step consists in

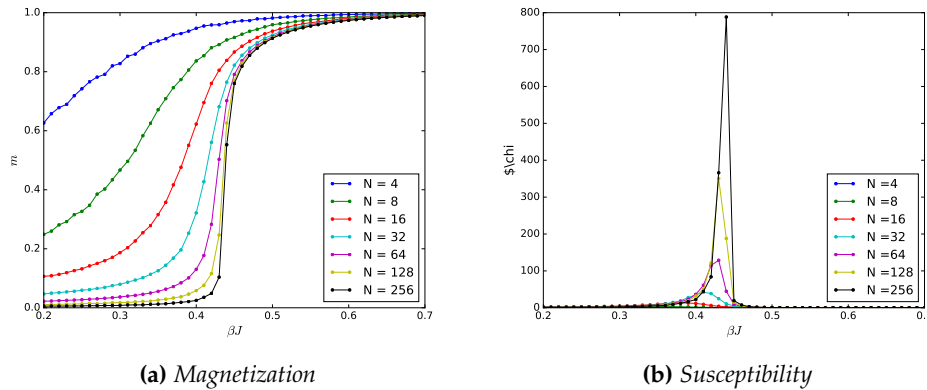


Figure 1: Behaviour of the magnetization and susceptibility calculated with the Hoshen-Kopelman algorithm

going over all the sites once more and checking all their links to make sure that the clusters are correctly identified. To generate random configurations, a new random spin value is then assigned to each cluster and the properties of the specific configuration are calculated.

IV.1 Applying the HK algorithm to XY model

(to be written)

III. RESULTS

The results obtained with the Hoshen-Kopelman algorithm for magnetization, susceptibility specific heat and Binder cumulant are presented in the first four parts of this section **WE should specify we're simulating the regular ising model with $j>0$ here.** In section V we present the results obtained with finite-size scaling when also considering second neighbours with both ferromagnetic and anti-ferromagnetic behaviour. In order to consider higher interaction order, the Metropolis algorithm as been used. In section VI we reported the results obtained for the XY model through the Hoshen-Kopelman algorithm.

It should be noted that we follow the convention found in [1], where $k_B = 1$ and the distance between sites is taken to be unitary.

I. Magnetization

In the Ising model the magnetization is defined as:

$$m = \frac{1}{L^2} \left\langle \sum_i s_i \right\rangle \quad (7)$$

The spin flipping operations taking place in the Hoshen-Kopelman algorithm cause this quantity to oscillate considerably; for this reason, the magnetization can be better described as:

$$m = \frac{1}{L^2} \left\langle \left| \sum_i s_i \right| \right\rangle \quad (8)$$

In Figure 1a it is possible to see the behaviour of the magnetization as a function of temperature. We can clearly see a phase transition around $\beta J = 0.44$, as predicted by the theory. The exact value found for the critical point is reported in section III.V.

II. Susceptibility

The susceptibility is defined as

$$\chi = \frac{dm}{dh} \quad (9)$$

This definition is modified in order to account for the cluster spin flips taking place in the Hoshen-Kopelman algorithm. The resulting equation is:

$$\chi = \frac{1}{L^2} \left[\left\langle \left(\sum_i s_i \right)^2 \right\rangle - \left\langle \left| \sum_i s_i \right| \right\rangle^2 \right] \quad (10)$$

The results obtained for the susceptibility are shown in Figure 1b. As expected, the susceptibility presents a peak close to the phase transition and is equal to zero everywhere else.

III. Heat capacity

The heat capacity can be directly related to the system's energy fluctuations. From [1]:

$$C_v = \frac{\langle E^2 \rangle - \langle E \rangle^2}{L^2 T} \quad (11)$$

The obtained results are show in Figure 2a.

IV. Binder cumulant

The Binder cumulant Q is defined as:

$$Q = 1 - \frac{\langle (\sum_i s_i)^4 \rangle}{3 \langle (\sum_i s_i)^2 \rangle^2} \quad (12)$$

The behaviour of the Binder cumulant is shown in Figure 2b. It can be shown that Q has a universal value at the critical point [2]. Therefore one can estimate βJ_c by determining the intersection point of Q for different lattice sizes. Since intersection point is depends very weakly on the lattice size, one can an accurate estimate for critical point by interpolating the curves for the highest values of N and determining the intersection. This procedures yields $\beta J_c \approx 0.4409$, which is very close to the exact value of $\beta J_c = 0.44068...$

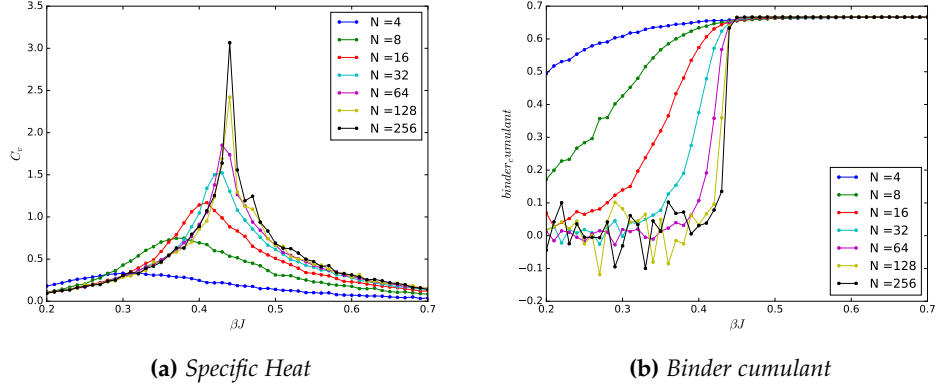


Figure 2: Behaviour of the specific heat and Binder cumulant calculated with the Hoshen-Kopelman algorithm

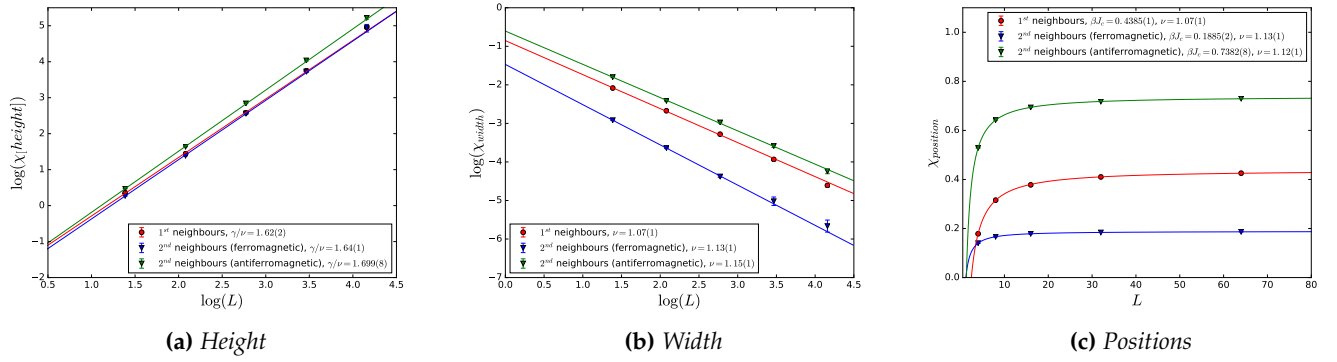


Figure 3: Scaling behaviour .

V. Finite size scaling

As a system approaches a critical phase transition, the behaviour of its physical quantities is described by power laws. The exponents corresponding to these power laws are called the *critical exponents*. For the Ising model we can write:

$$\chi \sim |T - T_c|^{-\gamma} \quad (13)$$

$$C_v \sim |T - T_c|^{-\alpha} \quad (14)$$

$$\xi \sim |T - T_c|^{-\nu} \quad (15)$$

$$m \sim |T - T_c|^\beta \quad (16)$$

The exact values for the critical exponents are given by:

$$\gamma = \frac{7}{4} \quad (17)$$

$$\alpha = 0 \quad (18)$$

$$\nu = 1 \quad (19)$$

$$\beta = \frac{1}{2} \quad (20)$$

These exponents are said to be *universal* due to the fact that they remain invariant changes in the Hamiltonian that do not affect the system size or its order. Systems governed by different Hamiltonians but with the same critical exponents are said to belong to the same *universality class*.

It is important to note that analytical exponents are actually obtained by taking the system size $L \times L$ to be infinite. The thermodynamic quantities will be smooth functions of temperature for a finite system, which means that we will not see a divergence at the critical point, but a smooth peak. As we increase the system size we observe that height, width and position of this peak change according to a set of equations, called *scaling laws*. Suppose we have a thermodynamic quantity A with critical exponent σ (i.e. $A \sim |T - T_c|^{-\sigma}$ close to T_c): it can be shown that the peak height of A as a function of T (or βJ , in our case) scales as $L^{\sigma/\nu}$, while its position and width scale as $L^{-\nu}$.

These three quantities were tracked for the magnetic susceptibility χ for different values of L by fitting the peaks to a Gaussian function. Besides the system described by (1), we considered two other Hamiltonians:

$$H_2 = -J \sum_{\langle ij \rangle} s_i s_j - J \sum_{\langle\langle ij \rangle\rangle} s_i s_j \quad (21)$$

$$H_3 = -J \sum_{\langle ij \rangle} s_i s_j + 0.3J \sum_{\langle\langle ij \rangle\rangle} s_i s_j \quad (22)$$

where $\sum_{\langle ij \rangle}$ and $\sum_{\langle\langle ij \rangle\rangle}$ denote sums over first and second neighbours respectively and J is taken to be positive. These two equations take into account the interaction with second neighbours: in equation 21, the added contribution is ferromagnetic, while the second neighbour interaction in equation 22 is weakly anti-ferromagnetic.

The results obtained for the critical exponents through finite-size scaling are shown in Figure 3 and reported in Table 1. The critical exponents were found to be very close to the exact results for the 2D Ising model ($\frac{\gamma}{\nu} = 1.75$, $\nu = 1$). Furthermore one also sees that although both systems exhibit different critical temperatures the critical exponents are very similar, indicating that both systems belong to the same universality class.

Interaction order	βJ_c	$\nu(\chi_{height})$	$\nu(\chi_{position})$	γ/ν
1 st	0.4385(1)	1.07(1)	1.07(1)	1.62(2)
2 nd (ferromagnetic)	0.1885(2)	1.13(1)	1.13(1)	1.64(1)
2 nd (antiferromagnetic)	0.7382(8)	1.15(1)	1.12(1)	1.699(8)

One can also study the behaviour the magnetization at T_c which is expected to satisfy the following scaling relation [3]:

$$m(T_c) \propto L^{\beta/\nu} \quad (23)$$

In figure 4 the magnetization at the critical temperature is plotted as function of the system size for a system with nearest neighbour ferromagnetic interactions (Hamiltonian in (1))¹. The critical exponent obtained from the slope of the line $\beta = 0.115(3)$ is close to the exact value of $\beta = 0.125$.

¹Next nearest neighbour interactions were not considered due to the fact that they were implemented using the Metropolis algorithm, which suffers from critical slowing down. As such, it is computationally very taxing to obtain good estimates for $m(T_c)$.

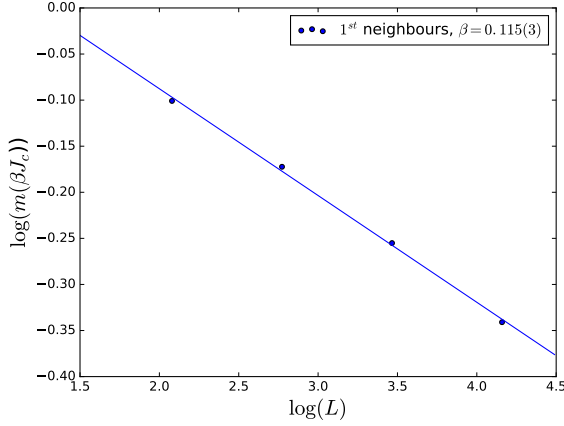


Figure 4: Scaling behaviour of the magnetization at the critical temperature $m(T_c)$.

VI. XY Model

The XY model undergoes a phase transition (known as the Kosterlitz-Thouless transition) from bound vortex-antivortex pairs at low temperatures to unpaired vortices and anti-vortices.

The helicity modulus Γ (helicity modulus) quantifies the free energy needed to 'twist' the spins and can be expressed as:

$$\Gamma = \frac{J}{2L^2} \left\{ \left\langle \sum_{\langle ij \rangle} \cos(\theta_i - \theta_j) \right\rangle - \frac{J}{k_B T} \left\langle \left[\sum_i \sin(\theta_i - \theta_{i+\vec{e}_x}) \right]^2 \right\rangle \right. \\ \left. - \frac{J}{k_B T} \left\langle \left[\sum_i \sin(\theta_i - \theta_{i+\vec{e}_y}) \right]^2 \right\rangle \right\} \quad (24)$$

For infinite systems Γ drops to zero at the KT critical temperature T_{KT} . It can be shown [1] that Γ has a universal value of $2k_B T_{KT} / \pi$ at the KT transition.

Γ/J is plotted in figure 5 as a function of temperature. The line $\Gamma/J = 2k_B T / (J\pi)$ is also shown in order to determine T_{KT} .

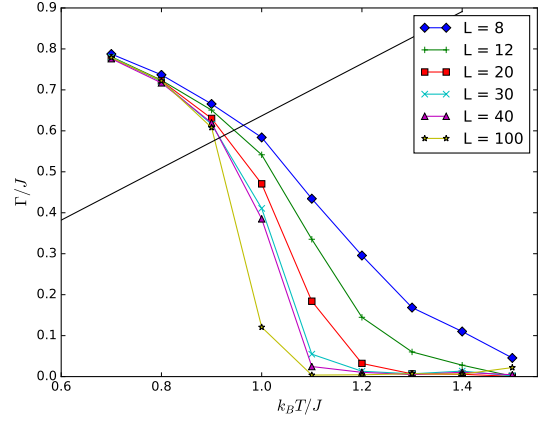


Figure 5: The helicity modulus in units of the coupling constant J of the XY model vs. the inverse coupling constant in units of $k_B T$. The intersection with the straight line gives the critical temperature T_{KT} .

The results are similar to those obtained by Thijssen [1]. We can note that, as the system size increases, the slope of the curves becomes steeper and its behaviour becomes non-analytic close to the critical temperature.

By checking the intersection of the line with the results $L = 100$ we can obtain a rough estimate for critical temperature. We find $\beta_{KT} \approx 1.121$ which is very close to the value of $\beta_{KT} \approx 1.120(1)$ reported in [4].

IV. CONCLUSION

In this paper, we presented the results obtained through the Monte Carlo simulation of the Ising model and the XY Model. The behaviour of the magnetization, susceptibility, binder cumulant and specific heat was found thanks to the Hoshen-Kopelman algorithm and resembles closely the theoretical prediction. Using finite-size scaling, we were able to calculate some of the critical exponent, obtaining accurate values for all the interaction orders we considered and consequently proving their universality. In the simulation of the XY model, we found an estimate for the helicity modulus, showing how the Monte Carlo algorithms can be used to predict the behaviour of a variety of physical systems in a reasonably accurate manner.

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