

NB.04.F1

July 23, 2024

1 Proposition

If we have a V -configuration of five points P_1, \dots, P_5 such that the rank of the matrix $\Phi(P_1, \dots, P_5)$ is 9 and such that $\delta_2(P_1, \dots, P_5) = 0$, then the unique ternary cubic determined by the condition that P_1, \dots, P_5 are eigenpoints has also the two other eigenpoints P_6 and P_7 aligned with P_1 .

```
[88]: load("basic_functions.sage")
```

1.1 Case $s_{12} = 0$ and $s_{14} = 0$;

1.1.1 Subcase $P_1 = (1 : 0 : 0)$

```
[89]: P1 = vector(S, (1, 0, 0))
      P2 = vector(S, (0, B2, C2))
      P3 = u1*P1 + u2*P2
      P4 = vector(S, (0, B4, C4))
      P5 = v1*P1 + v2*P4
```

```
[90]: M = condition_matrix([P1, P2, P3, P4, P5], S, standard="all")
```

```
[91]: assert(M[2] == vector([0 for _ in range(10)]))
```

```
[92]: M1 = M.matrix_from_rows([0,1,3,5,6,7,9,10,12,13])
```

```
[93]: M2 = M.matrix_from_rows([0,1,3,5,6,7,9,11,12])
```

```
[94]: G1 = M2.stack(phi((x,y,z), S)[0])
      G2 = M2.stack(phi((x,y,z), S)[1])
      G3 = M2.stack(phi((x,y,z), S)[2])

      g1 = G1.det()
      g2 = G2.det()
      g3 = G3.det()
```

```
[95]: g = P1[2]*g1 - P1[1]*g2 + P1[0]*g3
      assert(g == g3)
```

```
[96]: factors_g = g.factor()
xyz_factors = list(filter(lambda p: p[0].degree(x) > 0 or p[0].degree(y) > 0 or
↪p[0].degree(z) > 0, factors_g))
candidate_line = xyz_factors[-1][0]
```

```
[97]: assert(candidate_line.subs(substitution(P1)).is_zero())
```

1.1.2 Subcase $P_1 = (1 : i : 0)$

```
[98]: P1 = vector(S, (1, ii, 0))
P2 = vector(S, (0, B2, C2))
P3 = u1*P1 + u2*P2
P4 = vector(S, (0, B4, C4))
P5 = v1*P1 + v2*P4
```

```
[99]: M = condition_matrix([P1, P2, P3, P4, P5], S, standard="all")
```

```
[100]: M1 = M.matrix_from_rows([0,2,3,5,6,7,9,10,12,13])
```

```
[101]: M2 = M.matrix_from_rows([0,2,3,5,6,7,9,11,12])
```

```
[102]: G1 = M2.stack(phi((x,y,z), S)[0])
G2 = M2.stack(phi((x,y,z), S)[1])
G3 = M2.stack(phi((x,y,z), S)[2])

g1 = G1.det()
g2 = G2.det()
g3 = G3.det()
```

```
[103]: g = P1[2]*g1 - P1[1]*g2 + P1[0]*g3
```

```
[104]: factors_g = g.factor()
xyz_factors = list(filter(lambda p: p[0].degree(x) > 0 or p[0].degree(y) > 0 or
↪p[0].degree(z) > 0, factors_g))
candidate_line = xyz_factors[-1][0]
```

```
[105]: assert(candidate_line.subs(substitution(P1)).is_zero())
```

1.2 Case $s_{12} = 0$ and $s_{22} = 0$;

This implies that P_2 is on the isotropic conic, so we suppose $P_1 = (1 : 0 : 0)$ and P_2 one of the two intersections of the isotropic conic with the two tangents from P_1 .

```
[123]: P1 = vector(S, (1, 0, 0))
P2 = vector(S, (0, 1, ii))
P3 = u1*P1 + u2*P2
P4 = vector(S, (A4, B4, C4))
P5 = v1*P1 + v2*P4
```

```
[124]: M = condition_matrix([P1, P2, P3, P4, P5], S, standard="all")
```

```
[156]: M2 = M.matrix_from_rows([0,1,3,5,6,9,10,12,13])
```

```
[157]: G1 = M2.stack(phi((x,y,z), S)[0])
G2 = M2.stack(phi((x,y,z), S)[1])
G3 = M2.stack(phi((x,y,z), S)[2])

g1 = G1.det()
g2 = G2.det()
g3 = G3.det()
```

```
[158]: g = P1[2]*g1 - P1[1]*g2 + P1[0]*g3
```

```
[159]: factors_g = g.factor()
xyz_factors = list(filter(lambda p: p[0].degree(x) > 0 or p[0].degree(y) > 0 or
    ↪ p[0].degree(z) > 0, factors_g))
candidate_line = xyz_factors[-1][0]
```

```
[162]: assert(candidate_line.subs(substitution(P1)).is_zero())
```

1.3 Case $\sigma(P_1, P_2) = 0$ and $\sigma(P_1, P_4) = 0$;

This implies that P_1 cannot be on the isotropic conic, so we can suppose $P_1 = (1 : 0 : 0)$ (indeed, P_1, P_2, P_4 cannot be aligned)

```
[163]: P1 = vector(S, (1, 0, 0))
Qa = vector(S, (0, 1, ii))
Qb = vector(S, (0, 1, -ii))

P2 = m1*P1 + m2*Qa
P4 = l1*P1 + l2*Qb

assert(sigma(P1, P2) == 0)
assert(sigma(P1, P4) == 0)

P3 = u1*P1 + u2*P2
P5 = v1*P1 + v2*P4
```

```
[164]: M = condition_matrix([P1, P2, P3, P4, P5], S, standard="all")
```

```
[165]: M1 = M.matrix_from_rows([0,1,3,5,6,7,9,10,12,13])
```

```
[ ]: M2 = M.matrix_from_rows([0,1,3,5,6,7,9,11,12])
```

In this case the eigenscheme of f is not regular (it contains two lines):

```
[ ]: cb = M2.stack(vector(S, mon)).det()
Ecb = eig(cb)
assert(Ecb.subs({y: -ii*z}) == vector(S, (0, 0, 0)))
assert(Ecb.subs({y: ii*z}) == vector(S, (0, 0, 0)))
```

1.4 Case $P_3 = (s_{14}s_{15}s_{22} - s_{12}^2s_{45})P_1 + s_{12}(s_{11}s_{45} - s_{14}s_{15})P_2$

1.4.1 Subcase $P_1 = (1 : 0 : 0)$

```
[4]: P1 = vector(S, (1, 0, 0))
P2 = vector(S, (A2, B2, C2))
P3 = u1*P1 + u2*P2
P4 = vector(S, (A4, B4, C4))
P5 = v1*P1 + v2*P4
```

```
[6]: d2 = delta2(P1, P2, P3, P4, P5)
U1 = d2.coefficient(u1)
U2 = d2.coefficient(u2)
```

```
[7]: p3 = P3.subs({u1: U2, u2: -U1})
```

```
[8]: M = condition_matrix([P1, P2, p3, P4, P5], S, standard="all")
```

```
[17]: assert(M[2] == vector([0 for _ in range(10)]))
```

```
[20]: M1 = M.matrix_from_rows([0,1,3,4,6,7,9,10,12,13])
```

```
[22]: M2 = M.matrix_from_rows([0,1,3,4,6,7,9,10,12])
```

```
[28]: G1 = M2.stack(phi((x,y,z), S)[0])
G2 = M2.stack(phi((x,y,z), S)[1])
G3 = M2.stack(phi((x,y,z), S)[2])

g1 = G1.det()
g2 = G2.det()
g3 = G3.det()
```

```
[33]: g = P1[2]*g1 - P1[1]*g2 + P1[0]*g3
assert(g == g3)
```

```
[39]: factors_g = g.factor()
xyz_factors = list(filter(lambda p: p[0].degree(x) > 0 or p[0].degree(y) > 0 or
    ↪ p[0].degree(z) > 0, factors_g))
candidate_line = xyz_factors[-1][0]
```

```
[41]: assert(candidate_line.subs(substitution(P1)).is_zero())
```

1.4.2 Subcase $P_1 = (1 : i : 0)$

```
[18]: P1 = vector(S, (1, ii, 0))
      P2 = vector(S, (A2, B2, C2))
      P3 = u1*P1 + u2*P2
      P4 = vector(S, (A4, B4, C4))
      P5 = v1*P1 + v2*P4

[19]: d2 = delta2(P1, P2, P3, P4, P5)
      U1 = d2.coefficient(u1)
      U2 = d2.coefficient(u2)

[20]: p3 = P3.subs({u1: U2, u2: -U1})

[21]: M = condition_matrix([P1, P2, P3, P4, P5], S, standard="all")

[22]: M1 = M.matrix_from_rows([0,1,3,4,6,7,9,10,12,13])

[ ]: M2 = M.matrix_from_rows([0,1,3,4,6,7,9,10,12])

[ ]: G1 = M2.stack(phi((x,y,z), S)[0])
      G2 = M2.stack(phi((x,y,z), S)[1])
      G3 = M2.stack(phi((x,y,z), S)[2])

      g1 = G1.det()
      g2 = G2.det()
      g3 = G3.det()

[27]: g = P1[2]*g1 - P1[1]*g2 + P1[0]*g3

[47]: gtilde = g.quo_rem(matrix([P1, P2, P4]).det()^2)[0]
      gtilde = gtilde.quo_rem(u1^2)[0]
      gtilde = gtilde.quo_rem(u2^2)[0]
      gtilde = gtilde.quo_rem(v1*v2)[0]
      factors_g = gtilde.factor()

[48]: xyz_factors = list(filter(lambda p: p[0].degree(x) > 0 or p[0].degree(y) > 0 or
      ↪p[0].degree(z) > 0, factors_g))

[53]: quadratic_factor = xyz_factors[1][0]

[57]: quadratic_factor = quadratic_factor.subs({u1: U2, u2: -U1})
      xyz_factors = list(filter(lambda p: p[0].degree(x) > 0 or p[0].degree(y) > 0 or
      ↪p[0].degree(z) > 0, quadratic_factor.factor()))

[58]: candidate_line = xyz_factors[-1][0]

[59]: assert(candidate_line.subs(substitution(P1)).is_zero())
```