# Rock Paper Scissors

**Gesture Recognition** 









## Goal of the Project

The goal of this project is to develop a classifier able to correctly recognize the gesture among the three of the famous rock paper scissor game. The input is an image

It would be interesting to apply the techniques used in this project for a more noble purpose, for example the recognition of sign language gestures

### Raw Dataset



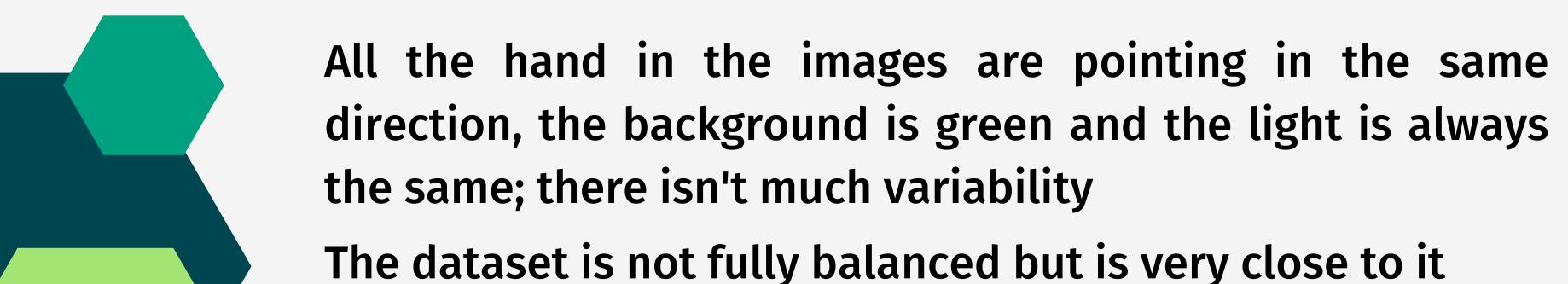
Paper 712 Images



Scissors 750 Images



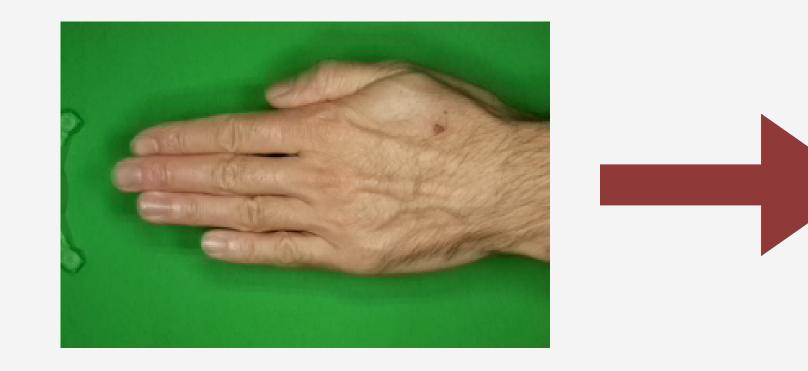
Rock 726 Images



Source: www.kaggle.com/datasets/drgfreeman/rockpaperscissors

## Data Transformation

• Pixel Values as features



200x300 pixels



20x30 pixels

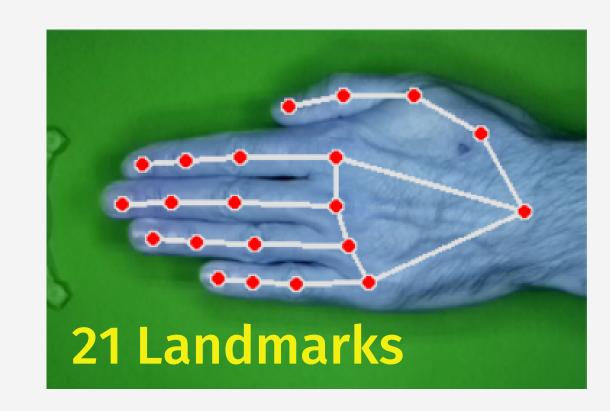
Records: 2188

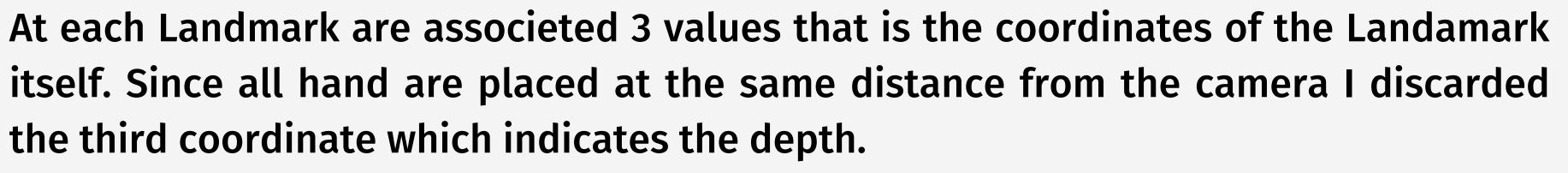
## Data Transformation

Landmarks as features





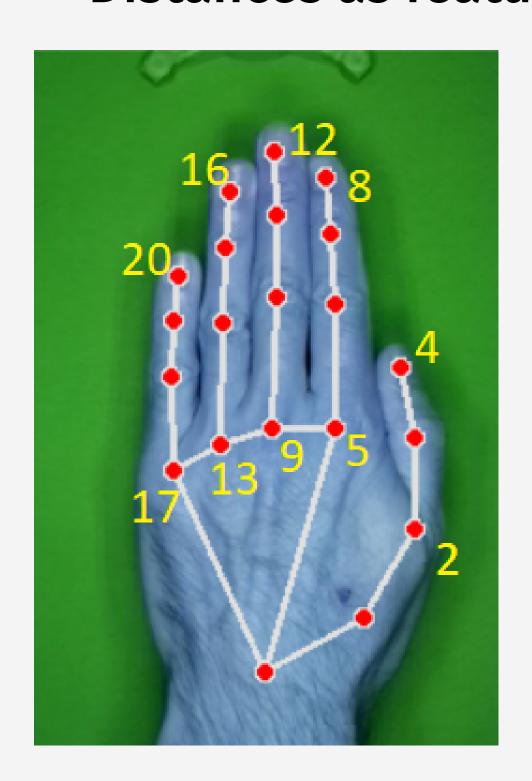




Records: 2091

## Data Transformation

Distances as features



**Euclidian Distance between the landmarks:** 

(4, 2) (5, 8) (9, 12) (13, 16) (17, 20)

Records: 2091

## Data Augmentation

The dataset created with the distances is unaffected by the fact that all the hand, in the images, point in the same direction

A classifier trained on ones of the other two datasets, probabily will not be able to correctly classify an image where the hand is directed in a different way

## Data Augmentation







300x300



Rotation



Rotation





Records: 2188

Features: 600



Records: 8752

Features: 625



Records: 2091

Features: 42



Records: 4219

## Data Augmentation



**Pixels** 

Landmarks

**Distances** 

Records: 2188

Records: 2091

Records: 2091

Features: 600

Features: 42

Features: 5



Data Augmentation



Aug. Pixels

Aug. Landmarks

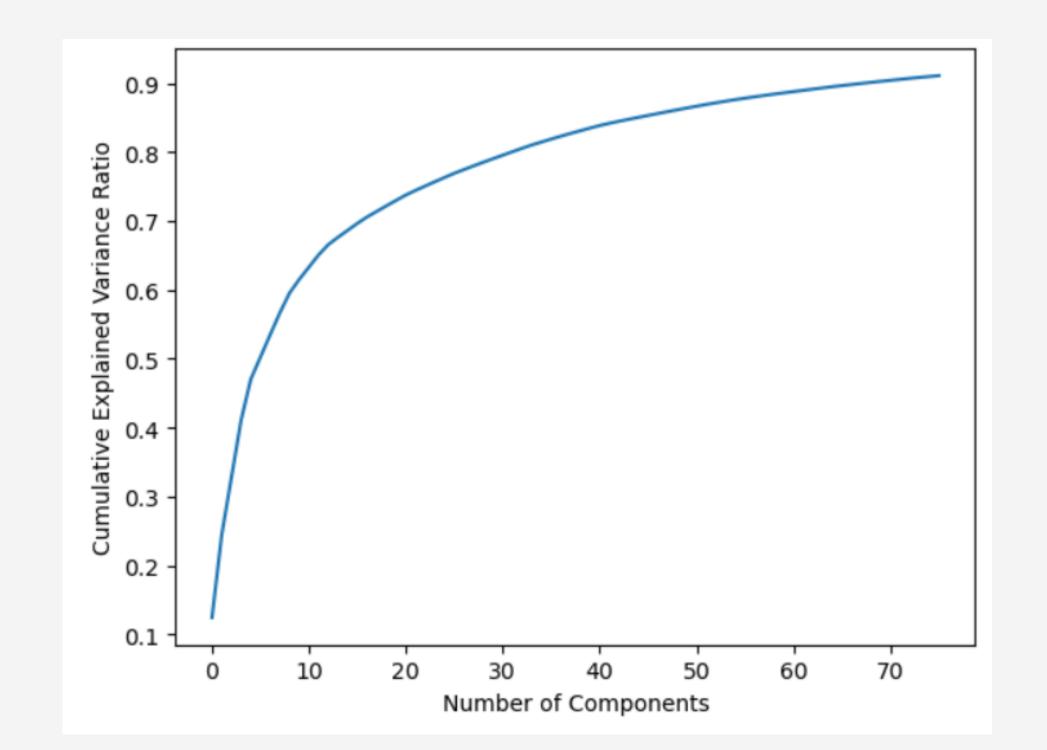
Records: 8752

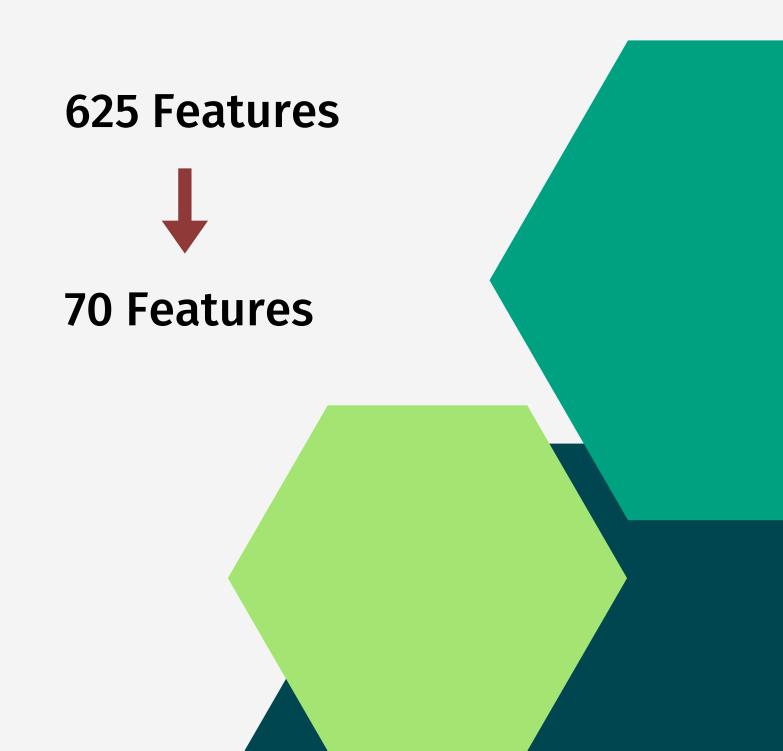
Records: 4219

Features: 625

## PCA

In the dataset that have the pixel values as features, the number of features is too high. I decide to performe Principal Component Analysis in order to reduce it

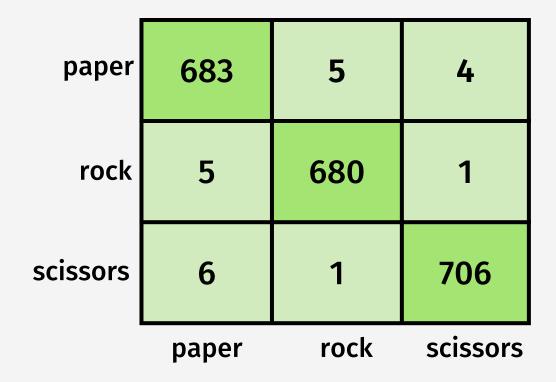


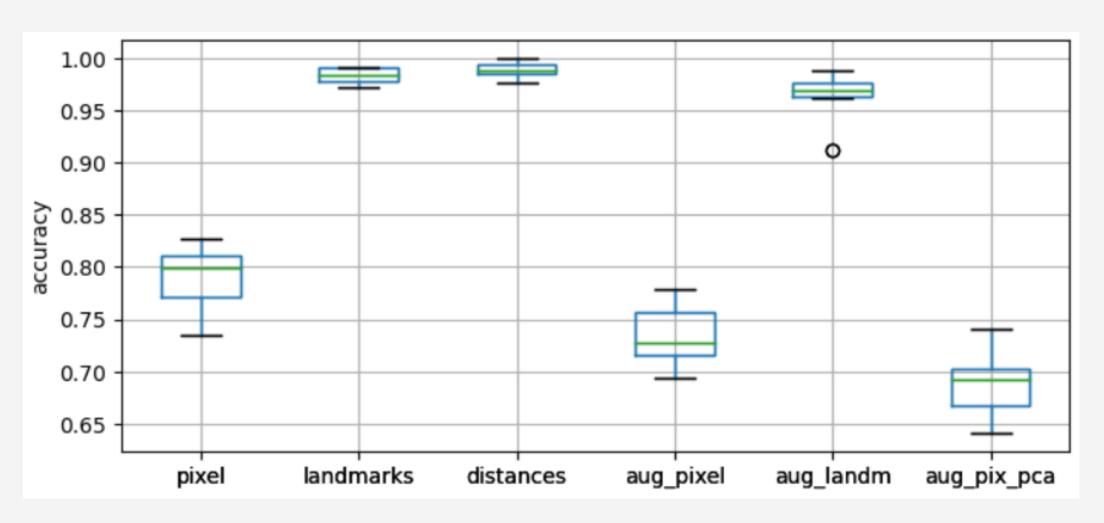


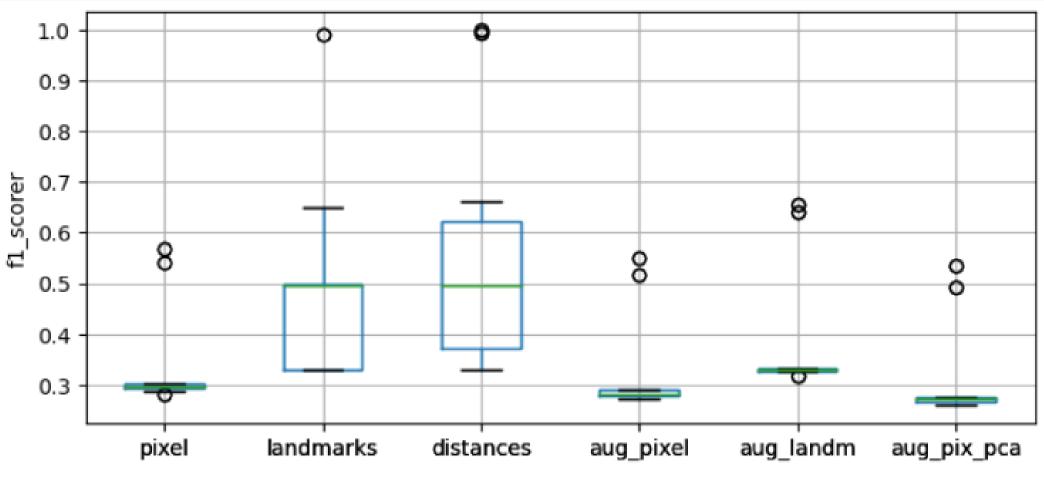
#### **Decision Tree**

(criterion: gini)

#### **Confusion Matrix:**





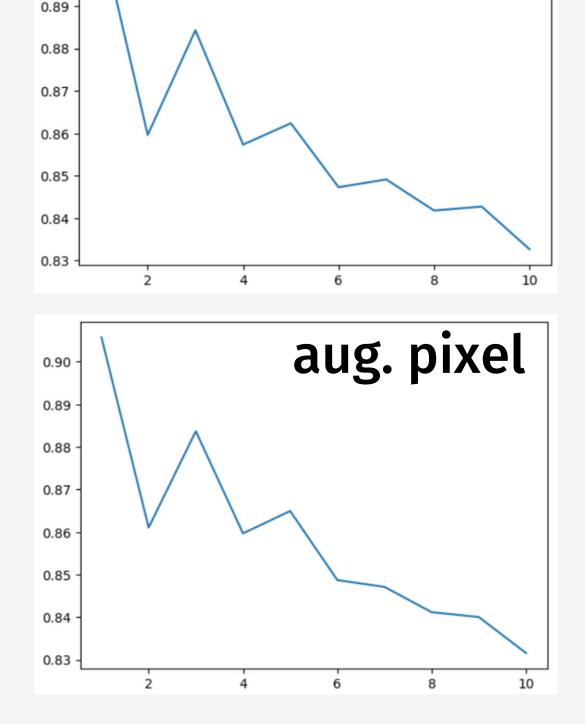


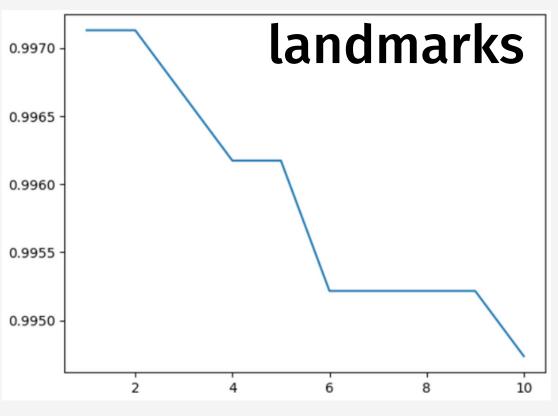
0.91

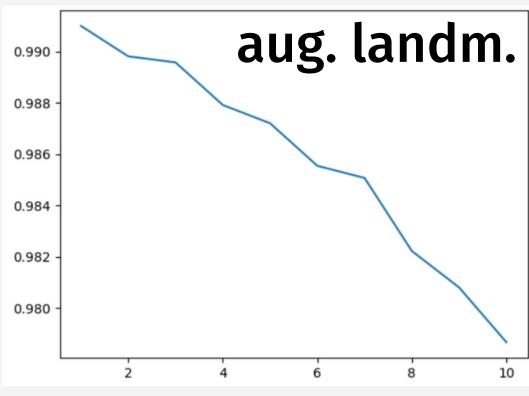
0.90

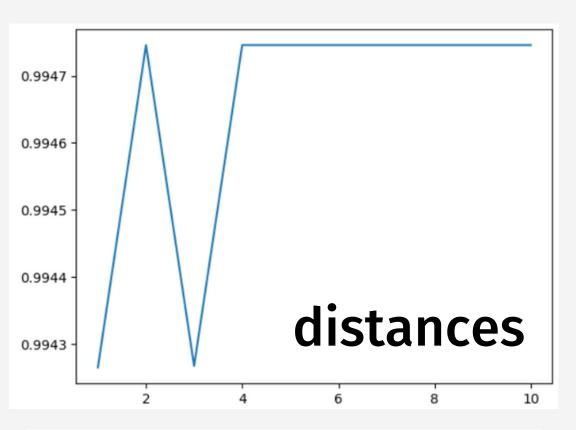
K-Nearest Neighbor (k = 1 ÷ 10)

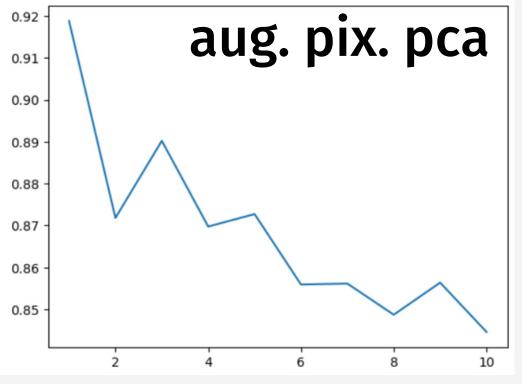
pixel











	•	
D	<b>IXe</b>	
	IVC	L

#### Landmarks

Classifier		
Decision Tree (gini)		
Decision Tree (entropy)		
K-Nearest Neighbor		
Naive Bayesian		
Random Forest (50)		
Random Forest (100)		

Accuracy	F1	Score time
0.791	0.346	0.0197
0.797	0.348	0.0205
0.908	0.394	0.1922
0.763	0.335	0.0410
0.902	0.377	0.0420
0.914	0.380	0.0555

Accuracy	F1	Score time
0.983	0.494	0.0107
0.985	0.528	0.0086
0.997	0.798	0.0484
0.944	0.531	0.0116
0.994	0.664	0.0253
0.993	0.698	0.0402

#### **Distances**

#### Aug. Pixel

Score

time

0.0096

0.0226

0.0375

0.0109

0.0239

0.0389

Classifier	Accuracy	F1
Decision Tree (gini)	0.989	0.563
Decision Tree (entropy)	0.989	0.578
K-Nearest Neighbor	0.994	0.714
Naive Bayesian	0.991	0.564
Random Forest (50)	0.992	0.647
Random Forest (100)	0.992	0.664

Accuracy	F1	Score time
0.732	0.331	0.0344
0.735	0.332	0.0356
0.905	0.394	2.4051
0.649	0.299	0.0986
0.894	0.375	0.0792
0.903	0.377	0.1212

#### Aug. Landmarks

A		
ΛΠσ	DIVA	DI A
Aug.		LFLA
<i>-</i> 3-	, .,	· · · · ·

Classifier		
Decision Tree (gini)		
Decision Tree (entropy)		
K-Nearest Neighbor		
Naive Bayesian		
Random Forest (50)		
Random Forest (100)		

Accuracy	F1	Score time
0.966	0.391	0.0104
0.968	0.408	0.0096
0.990	0.614	0.1582
0.793	0.348	0.0141
0.985	0.530	0.0281
0.985	0.630	0.0408

Accuracy	F1	Score time
0.687	0.318	0.0624
0.681	0.314	0.0543
0.918	0.381	0.5829
0.693	0.316	0.0680
0.857	0.364	0.0850
0.865	0.366	0.1196