

**The machine intelligence of images.**

**MVA 2023**

# The machine intelligence of images – Course Overview

## Course Objectives:

- Dive into the complexity of the design of today's smartphone cameras, which drives most of the technology in the image processing area.
- Understand the gap between the 'academic' image processing algorithms and their integration into a product.
- We will cover:
  - An overview of the smartphone camera industry (hardware and software)
  - The basic and advanced image processing pipelines
  - The hardware implementation constraints
  - The evaluation of the image quality with a visit in DxOMark Labs.
- 8 x 2h of lectures
- 4 x 3h of TPs.
- mini projects, evaluated through an oral presentation.

# The machine intelligence of images – Course Overview

Lectures :

- Introduction to cameras and the industrial ecosystem (F. Guichard / W. Hauser)
- DSLR vs Smartphone – the sensitivity and denoising challenge (F. Guichard / W. Hauser)
- Image Quality Analysis from RAW to Final Image quality (C. Greco / B. Pochon)
- Multi-Images / Multi-Sensors (B. Neveu)
- Color Processing, HDR Format (W. Hauser / B. Pochon)
- Image processing/machine learning implementation constraints (M. Karpushin / W. Hauser)
- IA from cameras to IQ evaluation (S. Ferradans / B. Pochon)

Participants :



Frederic Guichard  
DXOMARK



Claudio Greco  
DXOMARK



Benoit Pochon  
DXOMARK



Sira Ferradans  
DXOMARK



Wolf Hauser  
DxO



Balthazar Neveu  
Xiaomi



Maxim Karpushin  
Xiaomi



FOCUSED ON EXCELLENCE

## **Introduction to cameras and the industrial ecosystem**

The machine intelligence of images.

**F. Guichard / W. Hauser**

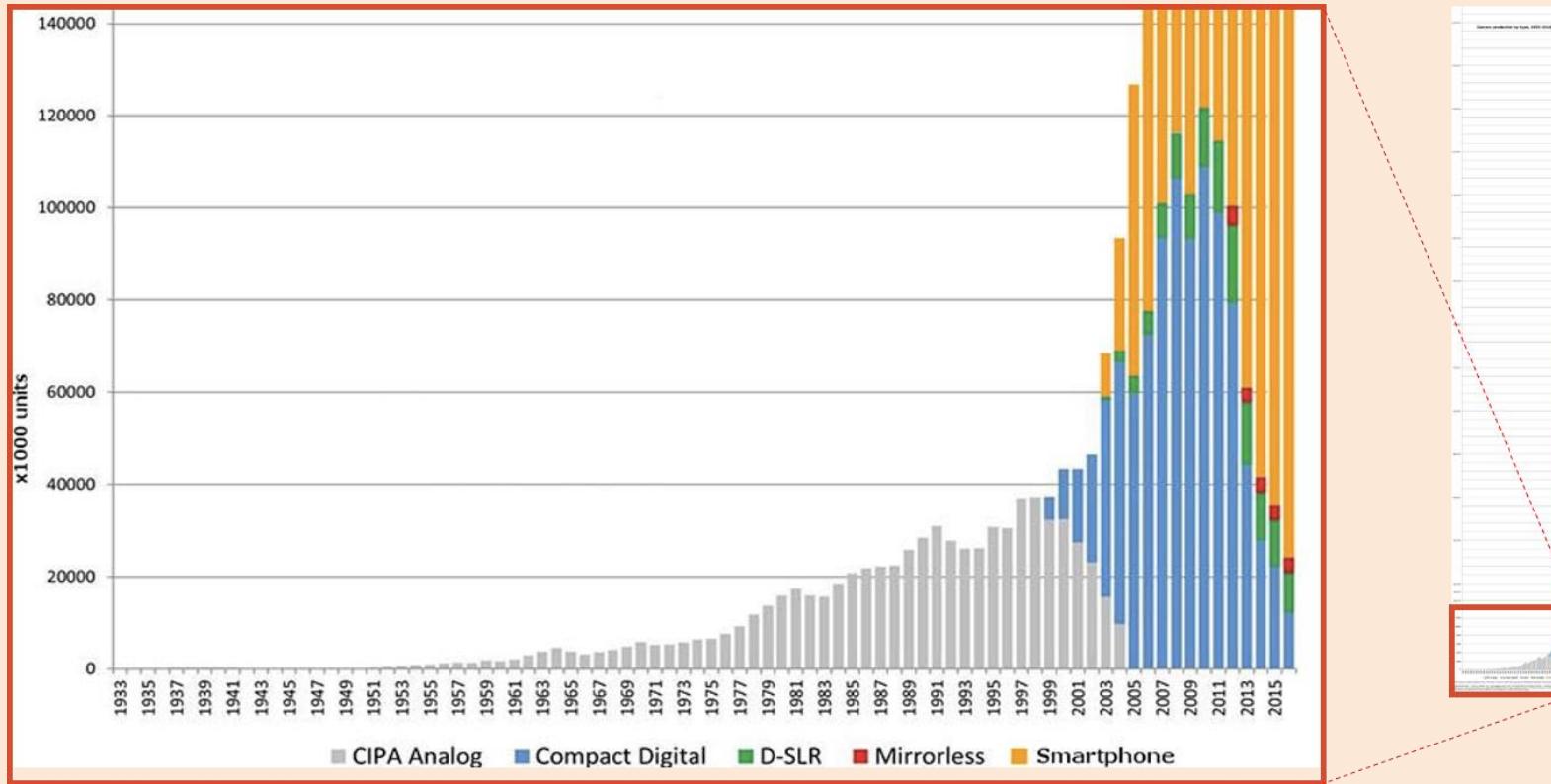
# Cameras are everywhere



# Ingredients of a digital camera



# Camera Industry Trend



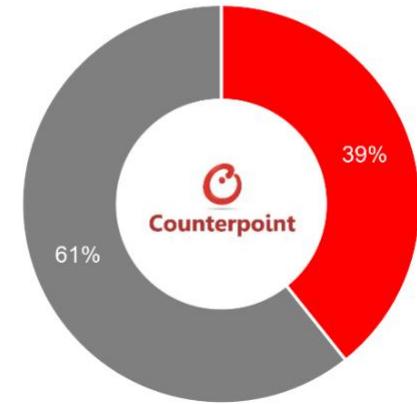
- The smartphones manufacturers
  - Hardware and Software (co-design)
- Post-processing Software



# Smartphones Brands / Vendors / ODM / OEM / EMS

H1 2022 Design Operation Status

■ Outsourced ■ In-House



- **OBM / Brand** : Apple, Samsung, Huawei, Xiaomi, etc...
  - ODM = Original Design Manufacturer : Design and build a product
  - OEM = Original Equipment Manufacturer : Build a product according to specifications given to them
  - EMS = Electronics manufacturing Services : Just manufacture...
  - IDH = Design house : Just does the design, but does not manufacture
- **OEM or ODM model**
  - Apple = OEM model, with Foxconn as OEM/EMS
  - Samsung = OEM model for S series, ODM for low-end series.
  - Crosscall = ODM model, with Hisense as ODM
- Major smartphones ODM/EMS/IDH
  - *Huaqin, Longcheer, Wingtech, Tinno*
- Major smartphones EMS/OEM
  - *Foxconn, Pegatron, ... Quanta, BYD, Flex, Inventec,*

#1	ODM	Shipment share (H1 2022)
1	Huaqin	30%
2	Longcheer	25%
3	Wingtech	20%
4	Tinno	8%
5	CNCE	6%
	others	11%

# Smartphone's Camera ingredients

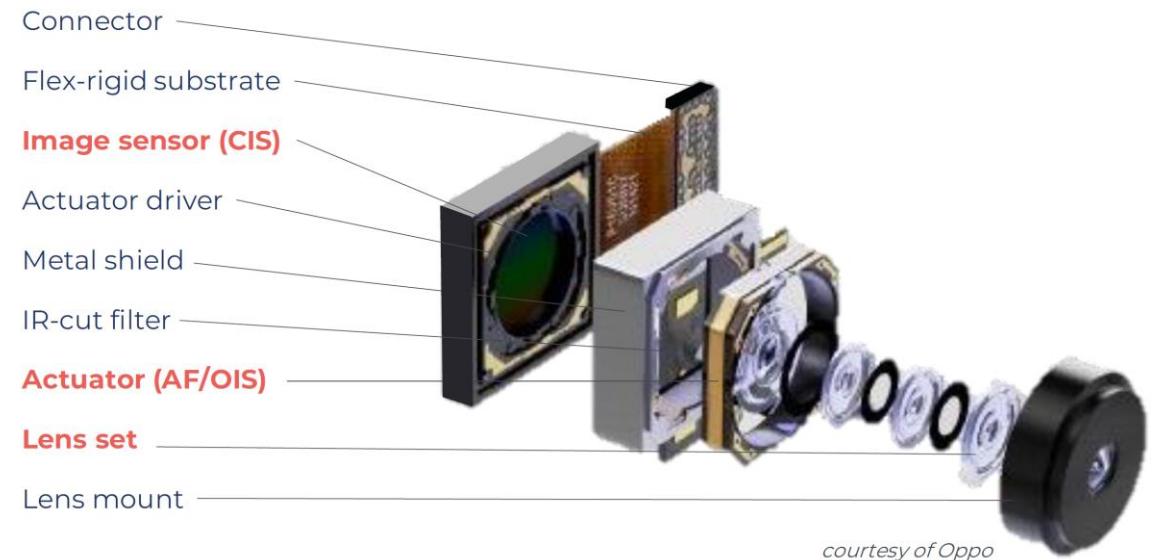


- Camera module(s)  
(and other sensors)
- The image processing

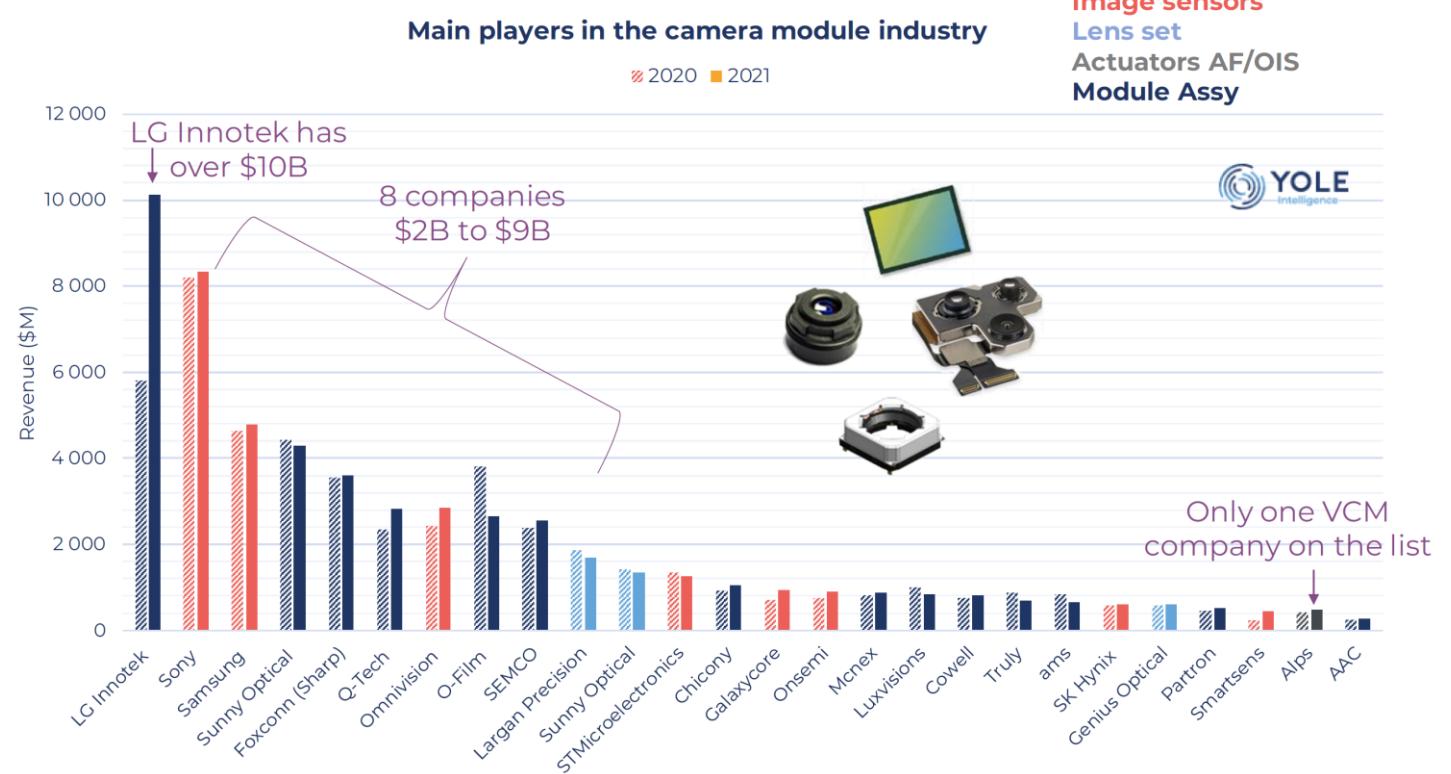
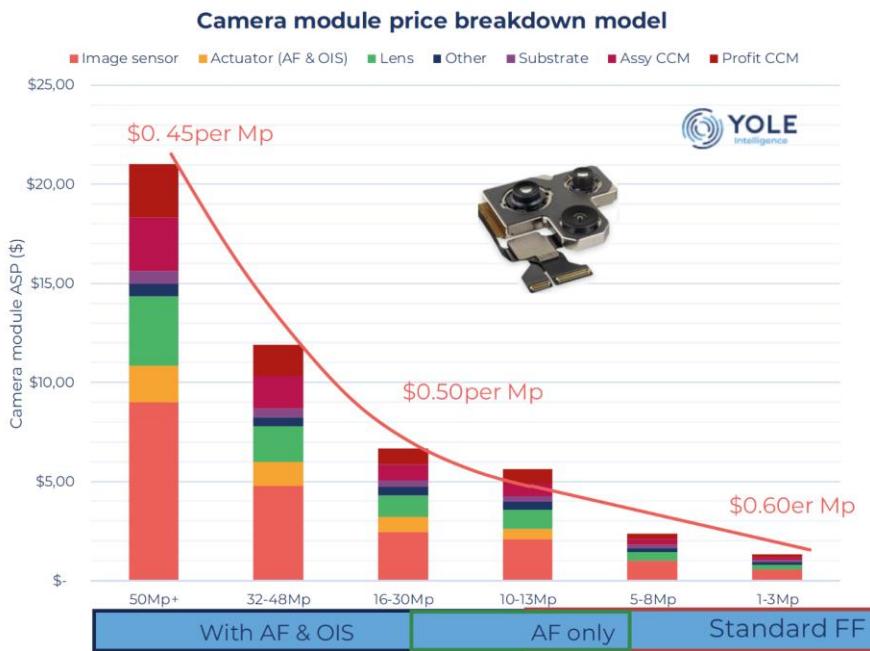
# Inside a Camera Module

- The lens set made of lenses
- The actuators (AF/OIS)
- The image Sensor

All these assembled by some camera modules manufacturers



# The economy of camera modules



# Top OEMs

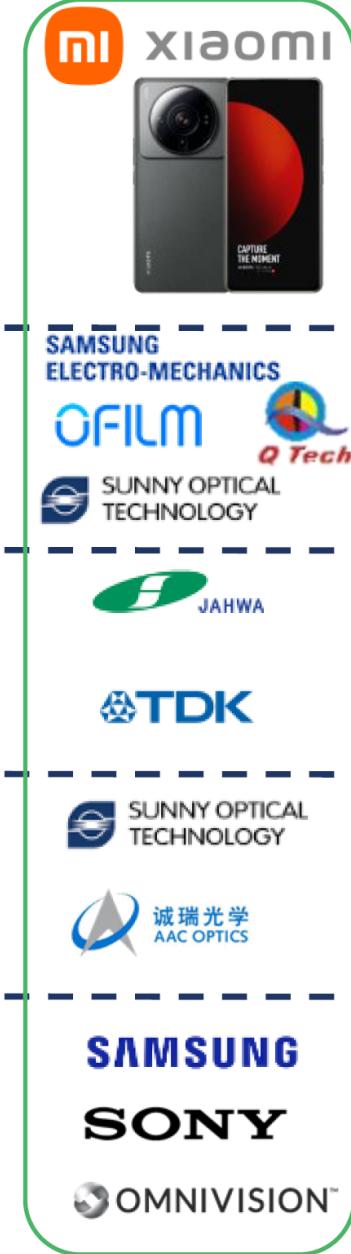
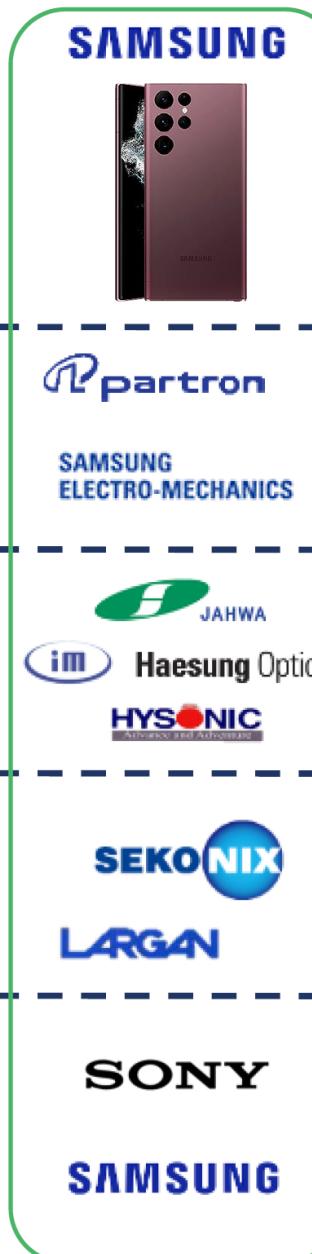
## System OEM

## Module assembly

## AF & OIS VCM

## Optics

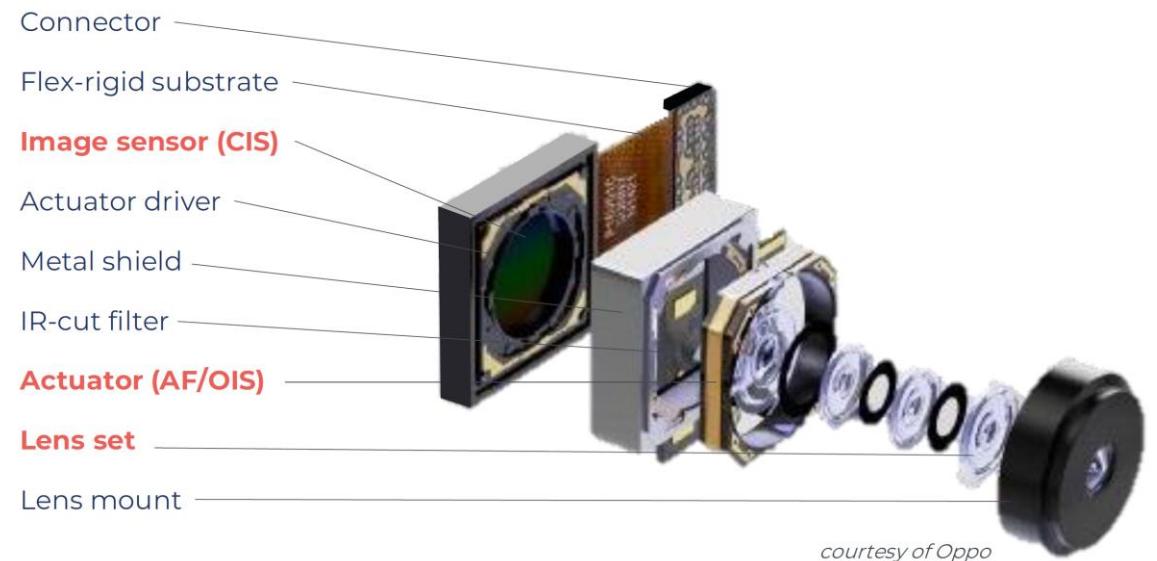
## Image Sensor



# Inside a Camera Module

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All these assembled by some camera modules manufacturers

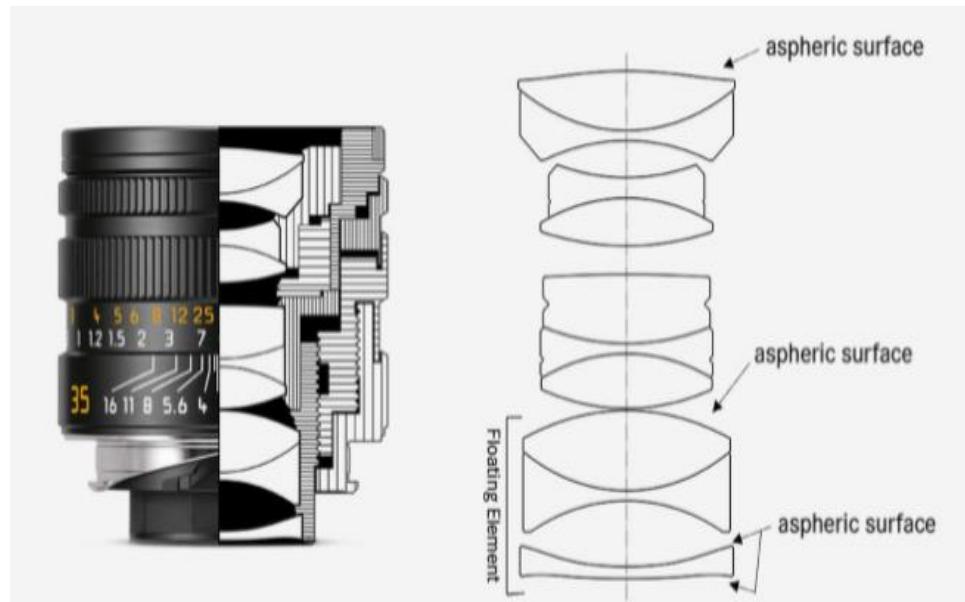


courtesy of Oppo

# Typical lens design (main camera)

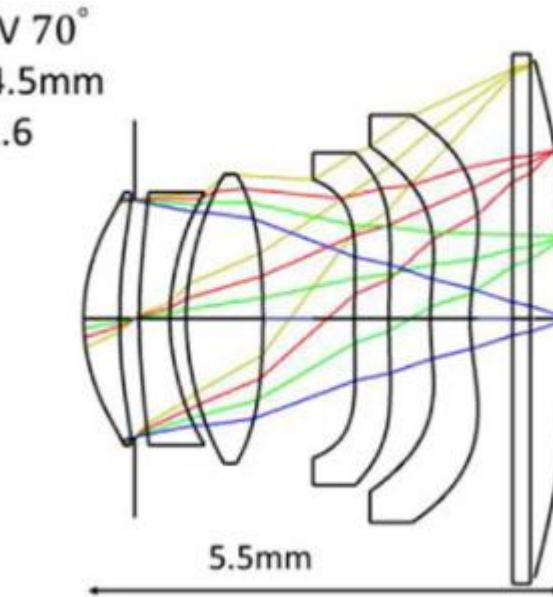
## DSLR Lens

- Between 6 and 18 glass elements
- But mostly spherical



## Smartphone lens (main camera)

- From 6 to 8 elements
  - 1 glass, other plastics – all aspherical
- ➔ The only (real) limits are:  
diffraction & manufacturing



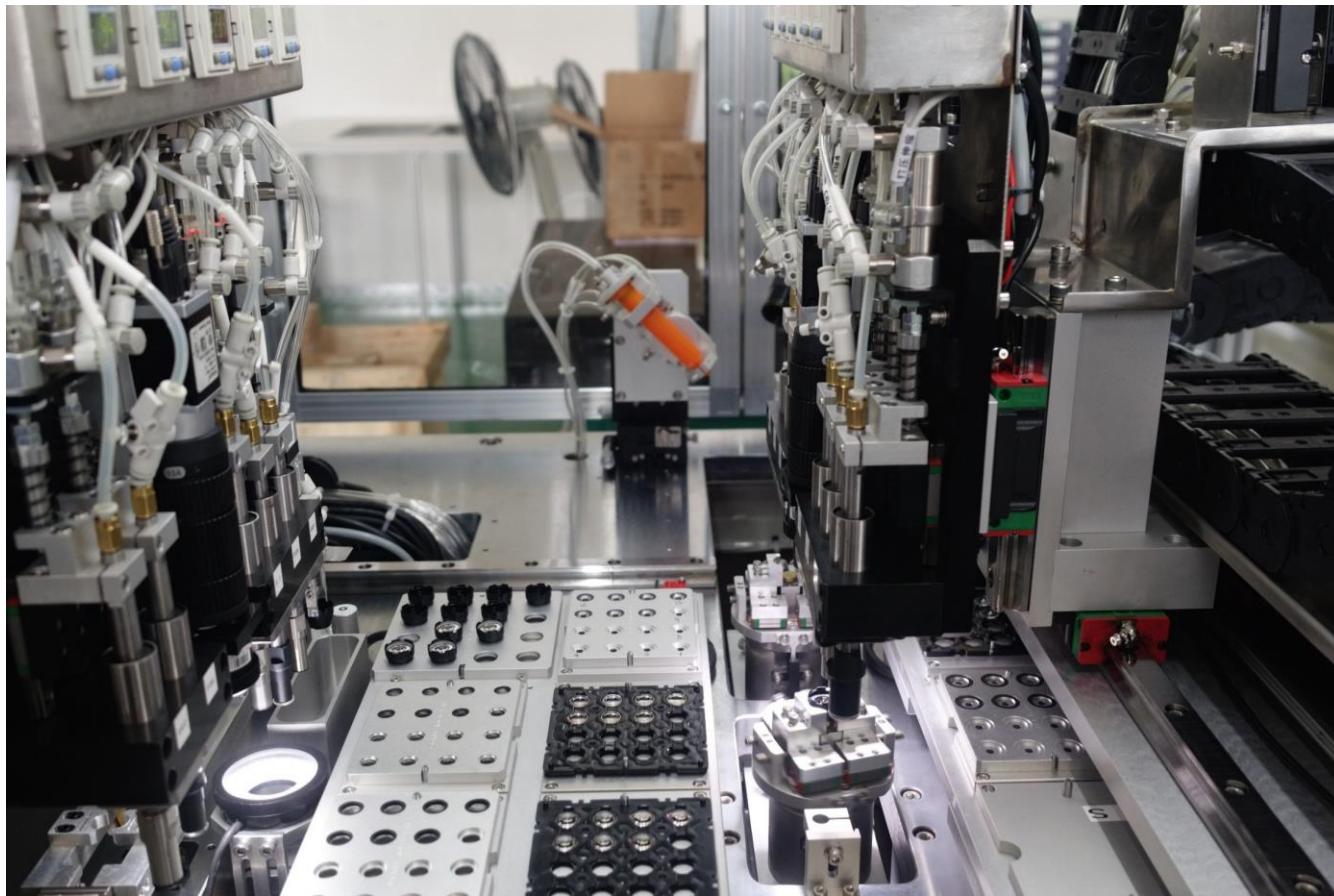
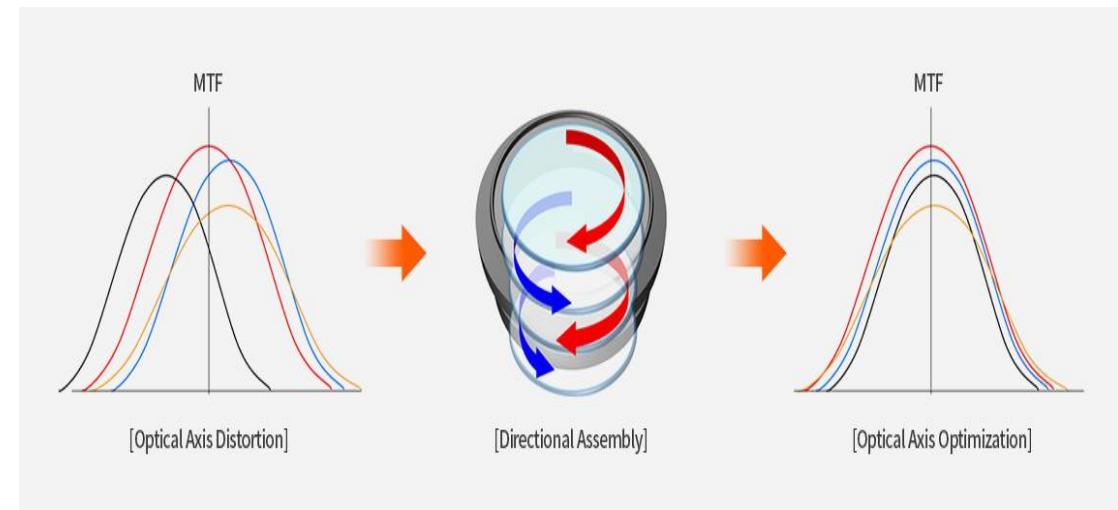
# Lens elements manufacturing

- Molded plastic lenses  
Very sensitive and somehow unpredictable
- Controls every 4hours:  
For each lens elements, each cavity and each mold : surfaces are measured



# Lens elements manufacturing

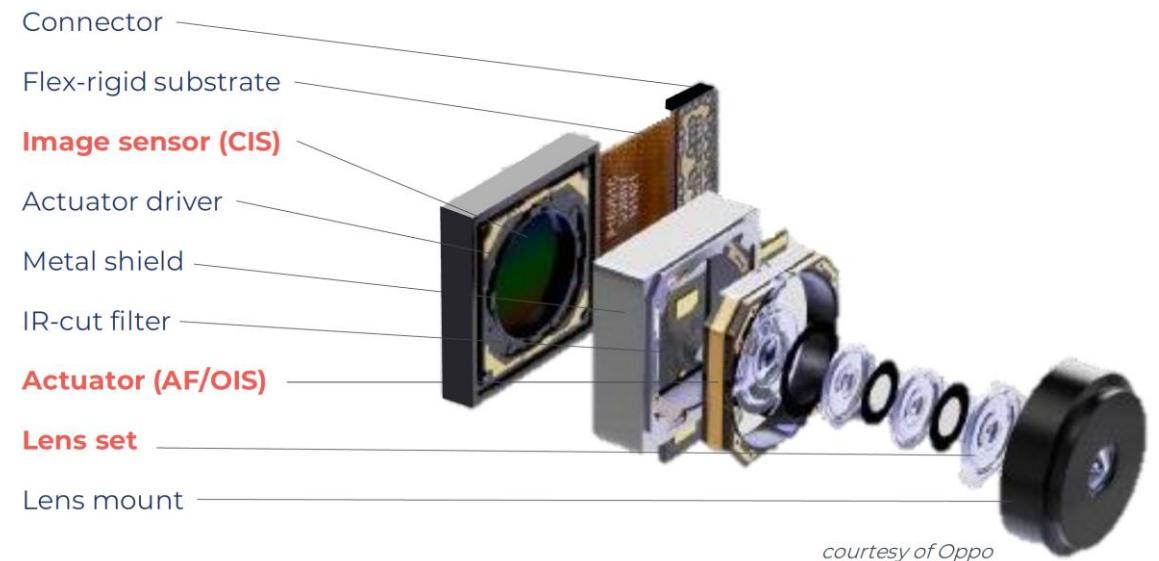
- Molded plastic lenses  
Very sensitive and somehow unpredictable
- Controls every 4hours:  
For each lens elements, each cavity and each mold : surfaces are measured
- Pairing and clocking process decided every 4 hours...  
so that default of one element is compensated by the other elements...



# Inside a Camera Module

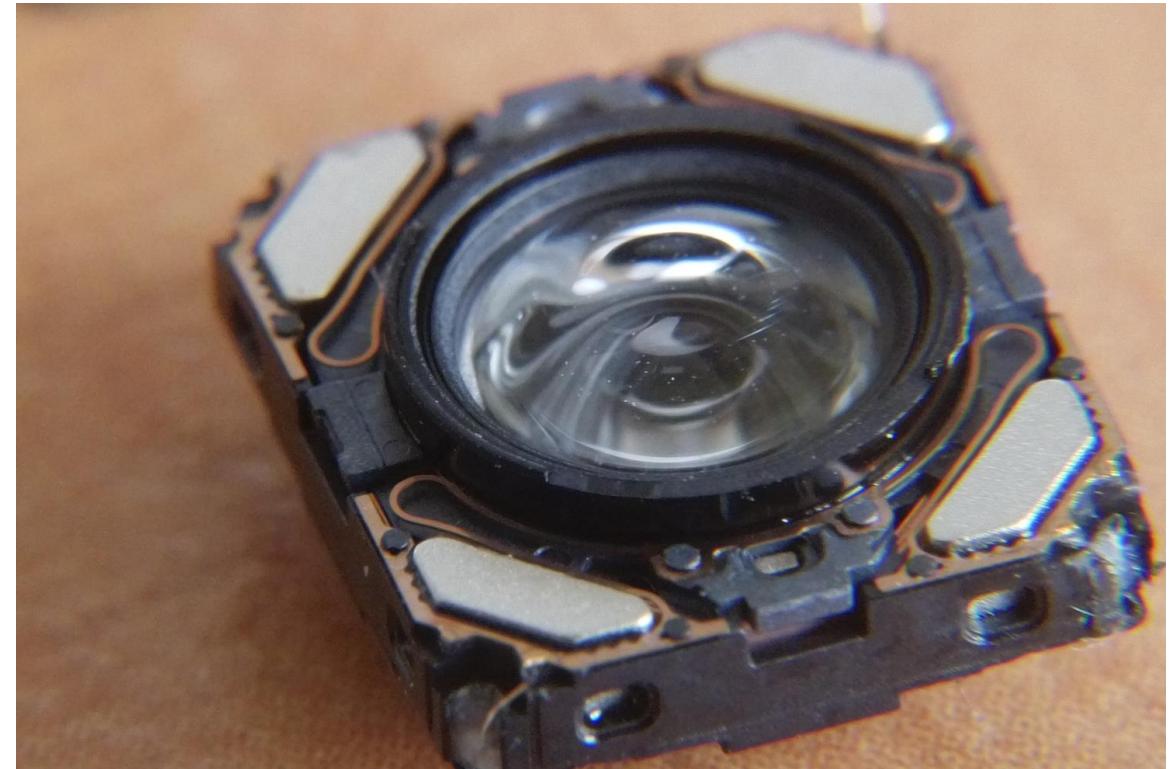
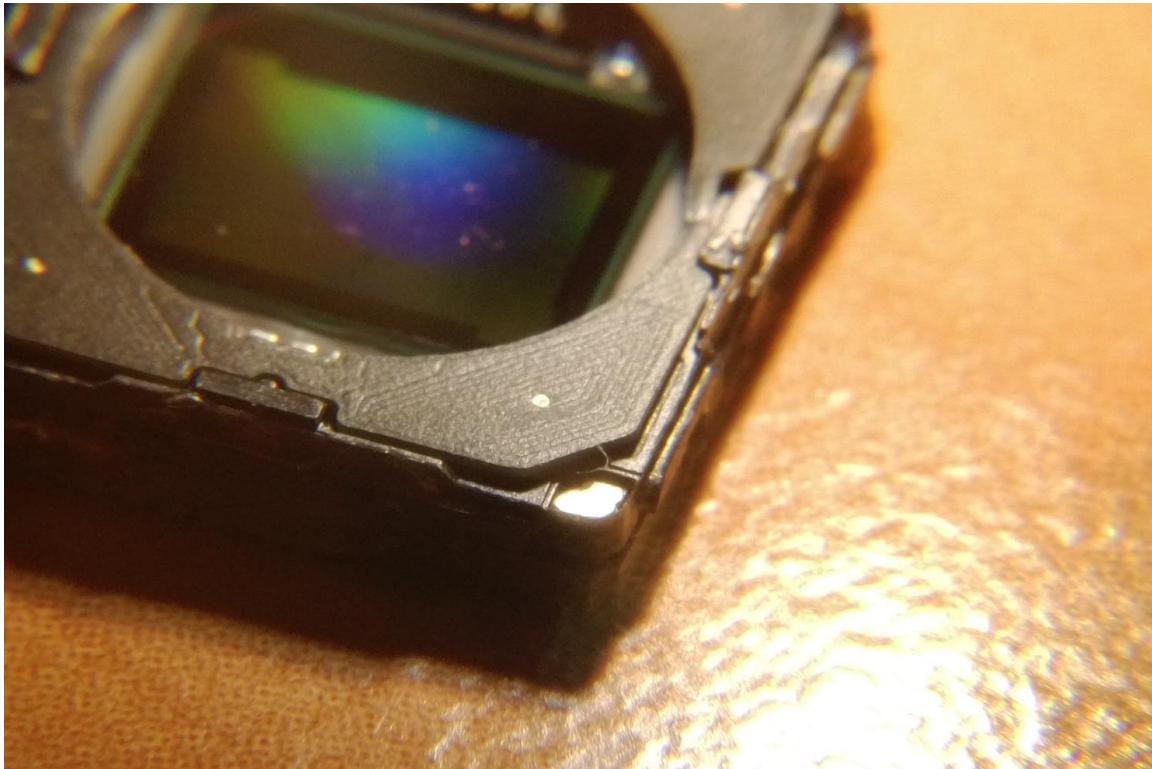
- The lens set made of lenses
- **The actuators (AF/OIS)**
- The image Sensor

All these assembled by some camera modules manufacturers



courtesy of Oppo

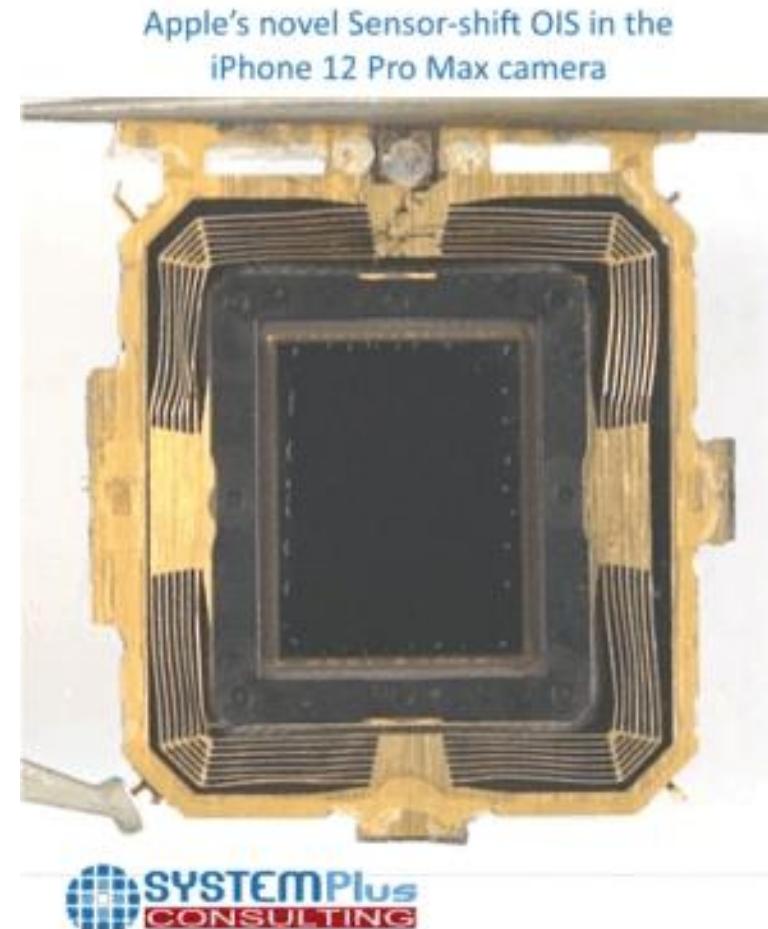
# Camera modules manufacturers – beyond lens technologies



Exemple: iphone7 OIS & AF

# Apple Sensor Shift

<https://www.reverse-costing.com/teardown-notes/apples-novel-sensor-shift-ois-iphone-12-pro-max-ca/>



<https://www.reverse-costing.com/teardown-notes/apples-novel-sensor-shift-ois-iphone-12-pro-max-ca/>

DXOMARK  
D

# Suppliers / other components

- IMU
  - Gyroscope is needed for OIS
    - Accelerometer is needed for AF and to un-bias Gyro
    - Magneto is needed to un-bias accelerometer
    - Temperature and barometric is needed to un-bias magneto
  - 6+ axis system (Gyro+Acc+Magneto+Temp+Baro) @ 10KHz.
- Main actors :
  - Invensense
  - Bosch
  - Alps

# Suppliers / Other components

- TOF (Time Of Flight)
  - For 3D, but also for AF and “bokeh effect”
  - Main actors :
    - ST Micro
    - Espros
    - Infineon
- Flash
  - LED or multi-LED
- Color sensor / Ambiant light
  - Light metering, ambient color (with IR), light flicker detection, etc...
  - Main actors :
    - ST Micro
    - AMS

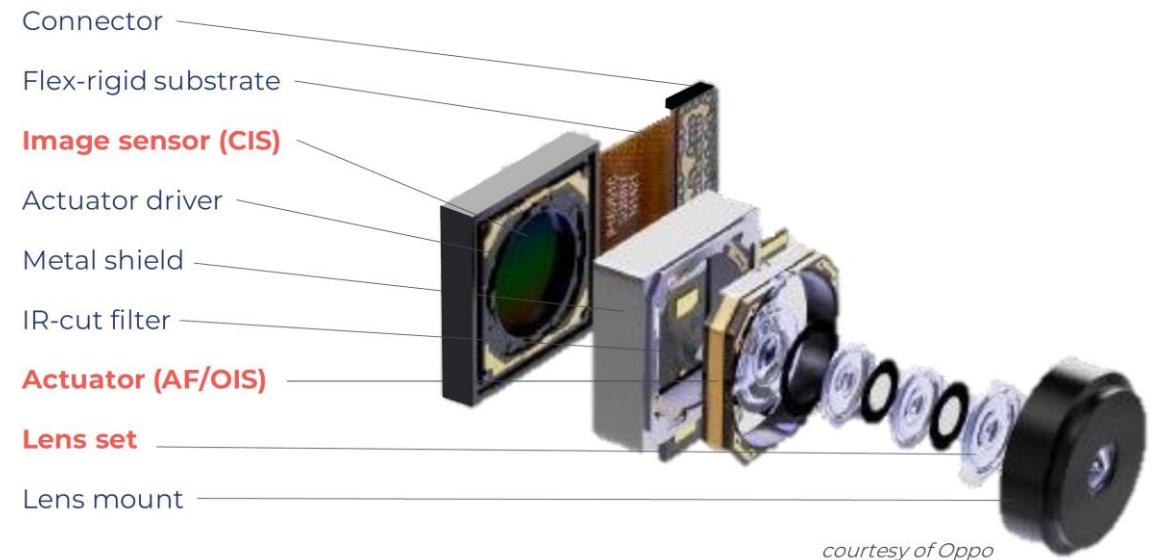


ST VD6281

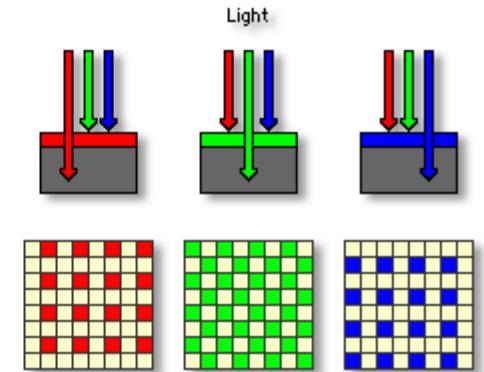
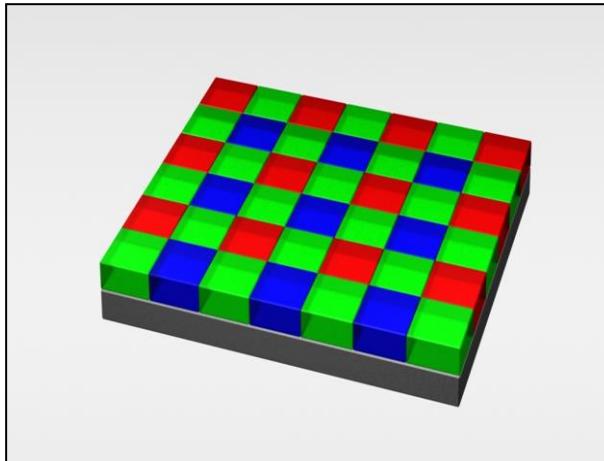
# Inside a Camera Module

- The lens set made of lenses
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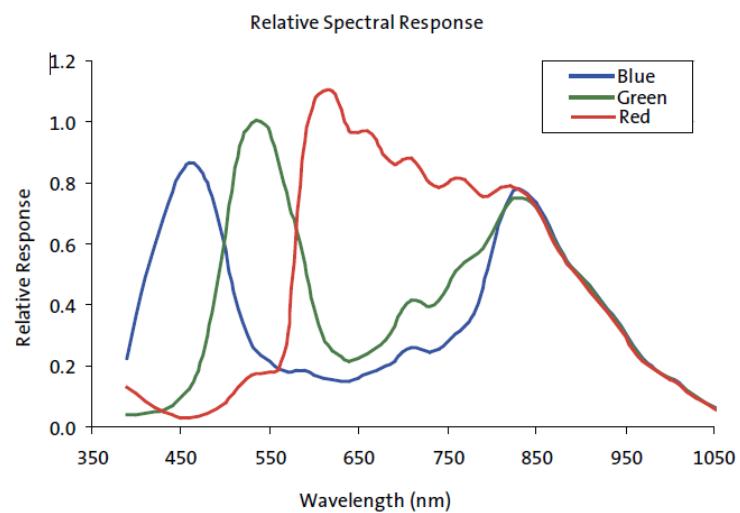
All these assembled by some camera modules manufacturers



# The image sensor

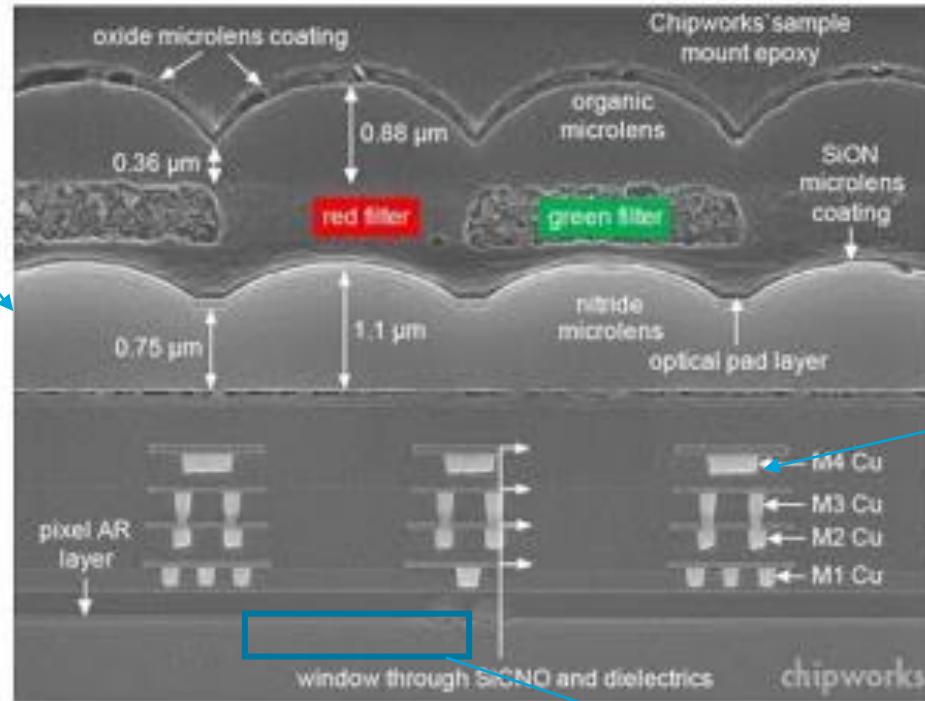
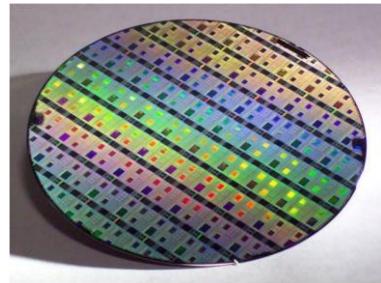


Bayer pattern (Eastman Kodak 1976)



# The image sensor

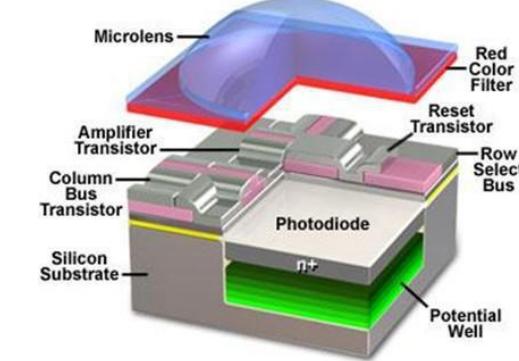
Micro lenses  
Color filters



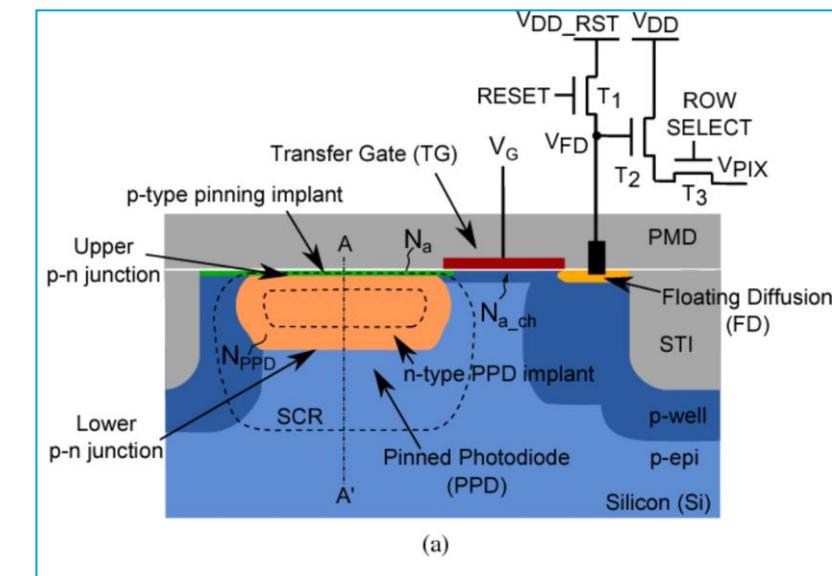
A classic silicon design:

- Photo sensitive area and a full well capacity to store e-
- 4 gates per pixels (4T) to transfer e- to communication lines

Anatomy of the Active Pixel Sensor Photodiode

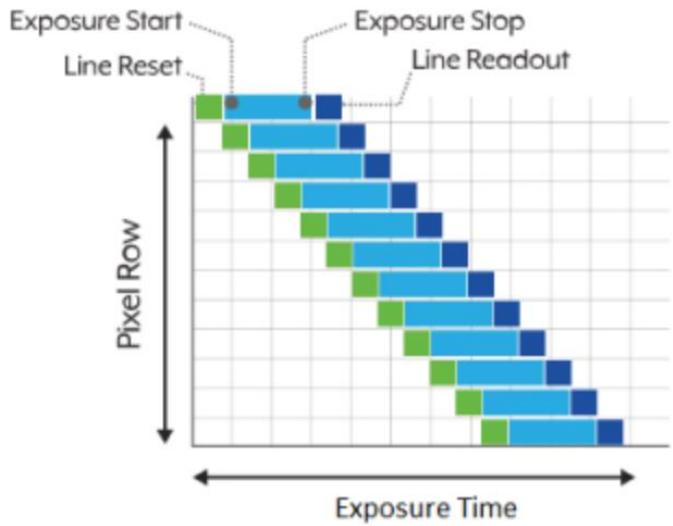


Communication lines



# Pixel read out and electronics rolling shutter

Each row is read one after the other, and on each row:  
each pixel is read one after the other.



From top to bottom → delay

This delay decreases with pixels throughput increase  
@1Gpixels/s delay is about 20ms for a 48Mpix sensor.

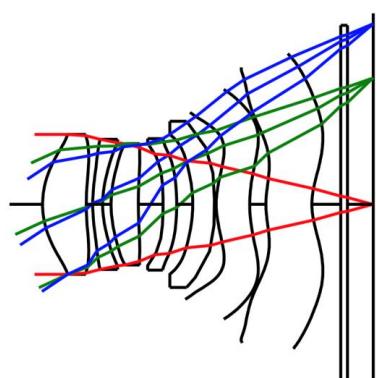
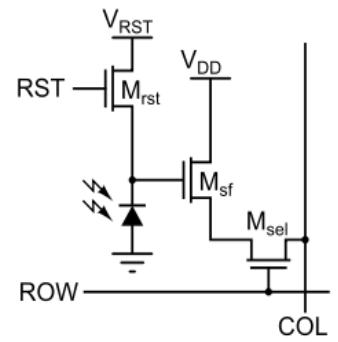
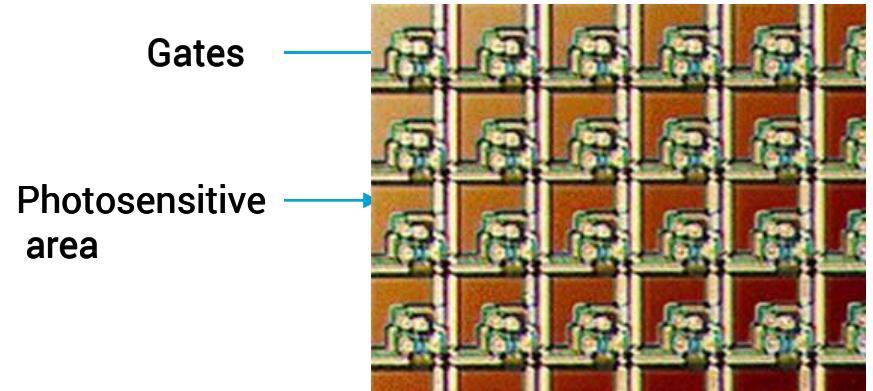
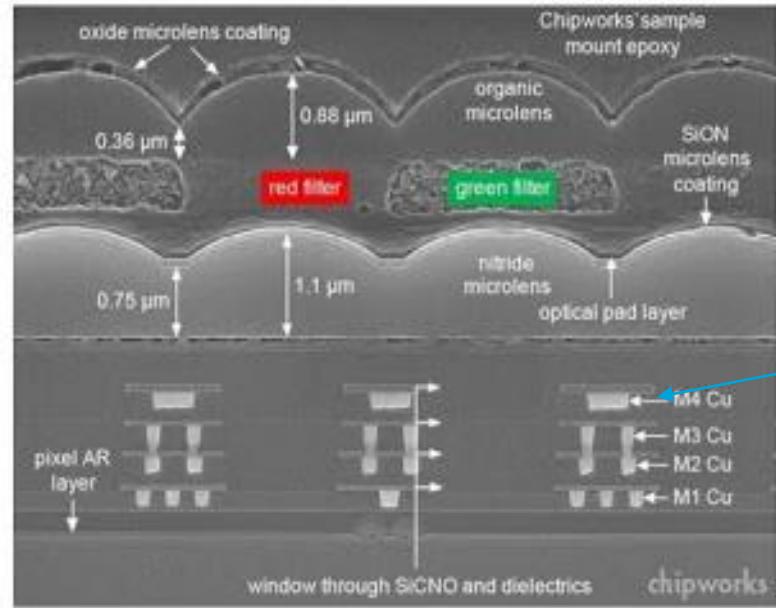


# Pixel technologies

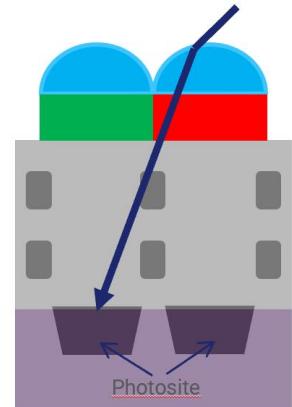
Photo sensitive area and Gates at the same layer

Communication lines are above and make “shadows” (or diffraction)

This makes **pixel pitch reduction** a nightmare...



Large incident angles



Crosstalk



Color Lens Shading

# Pixel technologies

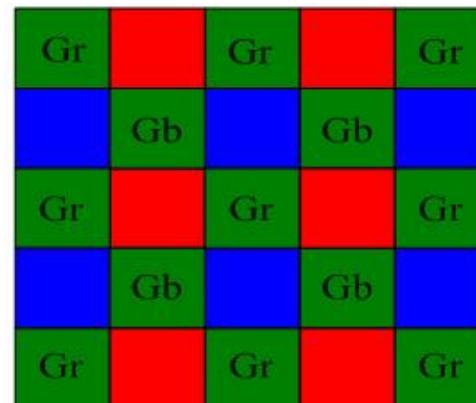
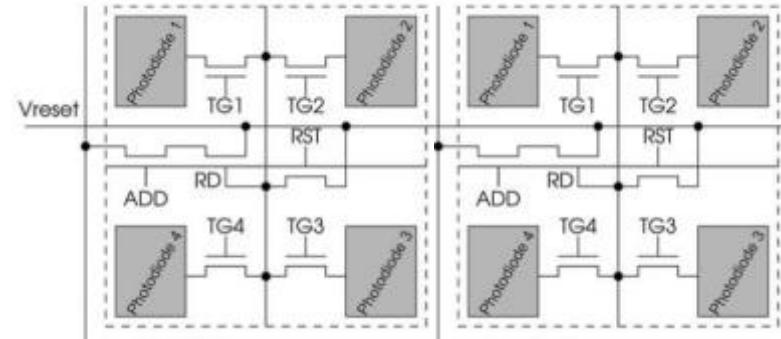
→ Share communication lines and some gates → 1.75T

Increase photosensitive part ☺

Smaller pixel pitch allowed (even below 1um) ☺

Asymmetrical pixels.

Gr and Gb : different spectral response! ☹

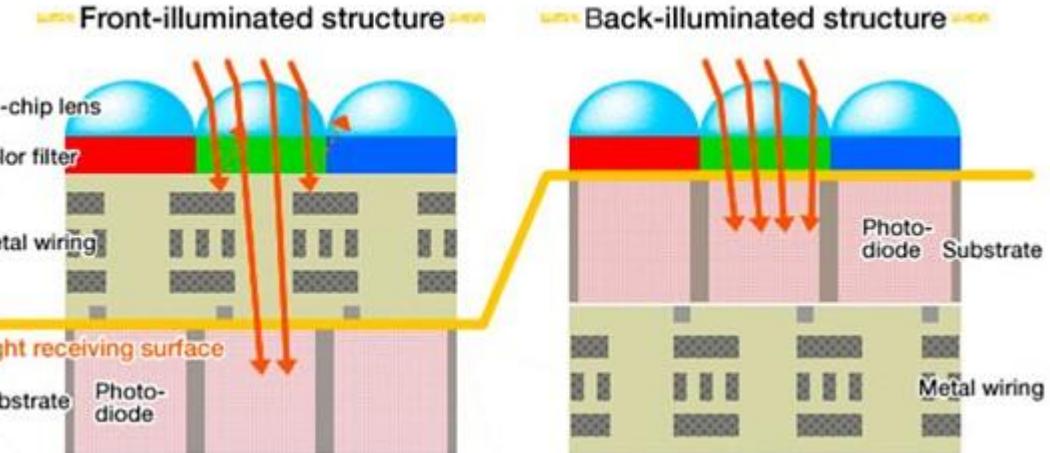


<https://blog.csdn.net/gbmaotai>

# Front Side Illuminated / Back Side Illuminated / stacked

- From FSI to BSI (2012)

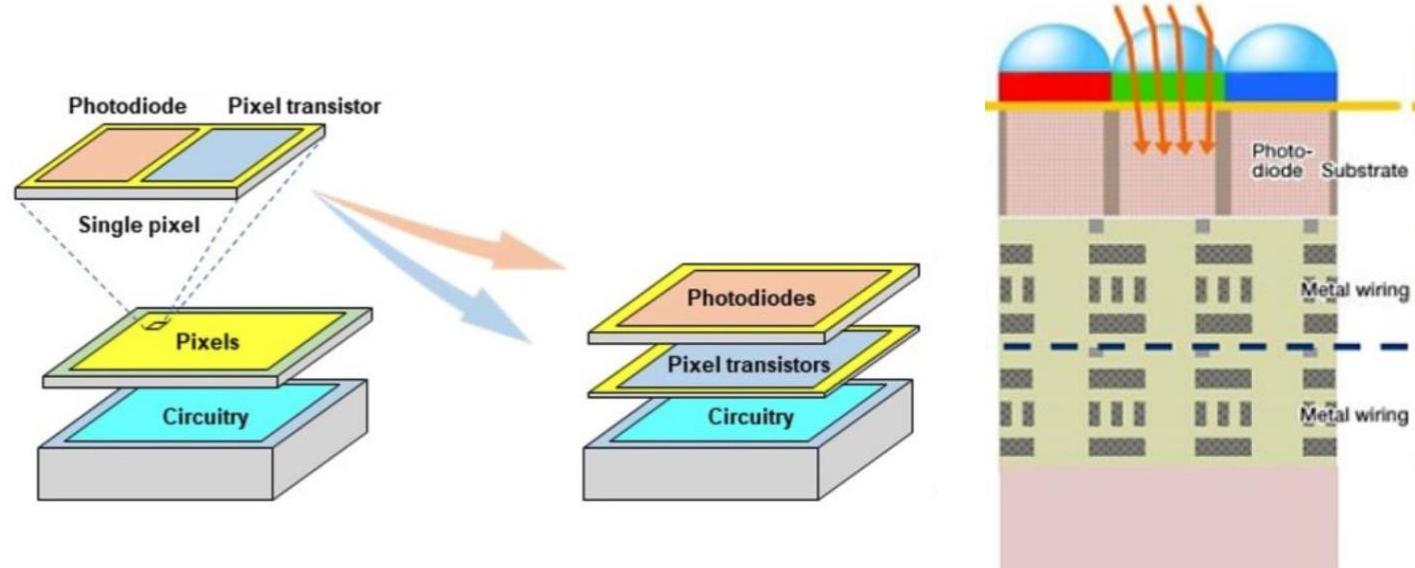
Metal layers are not an issue any-longer



- From BSI to Stacked BSI

Global shutter possible. (by adding a memory layer)

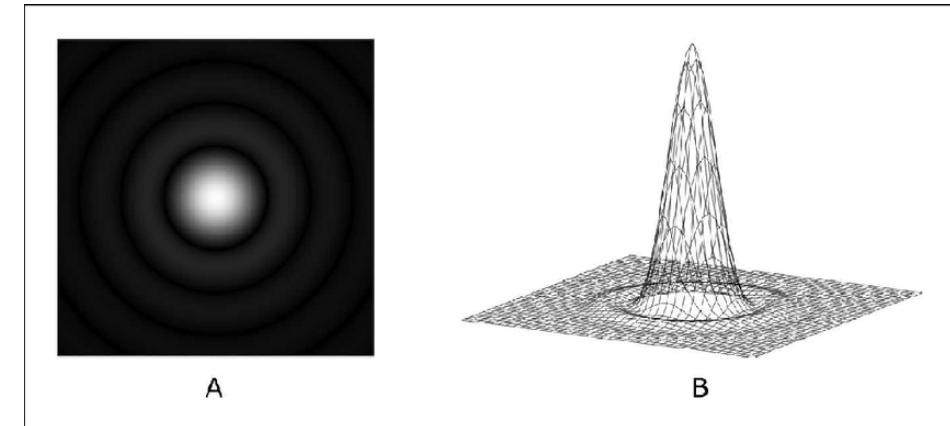
One day : single gate per pixel! → more sensitivity



# Note : Pixel pitch and diffraction limit

- Diffraction :  $r = 1.22 \lambda f\# = \sim 0.65 f\#$

Aperture	Wave length cut-off ( $\mu\text{m}$ ) at 530nm
2.8	1.82*2
2.0	1.3*2
1.4	0.9*2

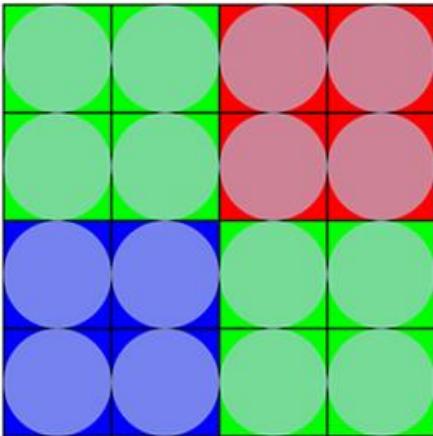


→ Aperture must be very wide for small pixels

# Bayer variants...

Quad structure

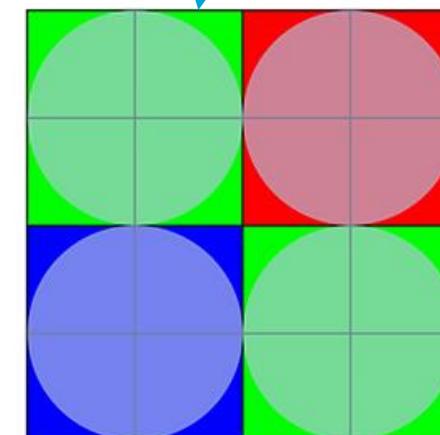
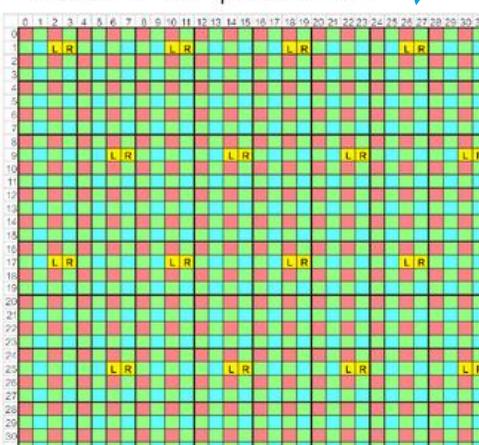
Back to bayer when used half resolution.



Masking or specific micro lenses for AF statistics  
“Phase pixels” or “dual pixels”

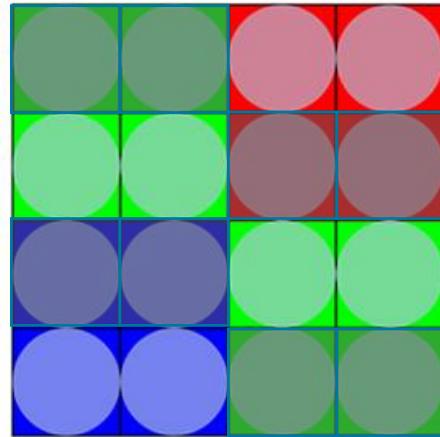
Bayer	Quad
Structure	Shield On chip lens Color filter Shield Photo diode
Density	1.5%

1Block = 32 pixel x 32

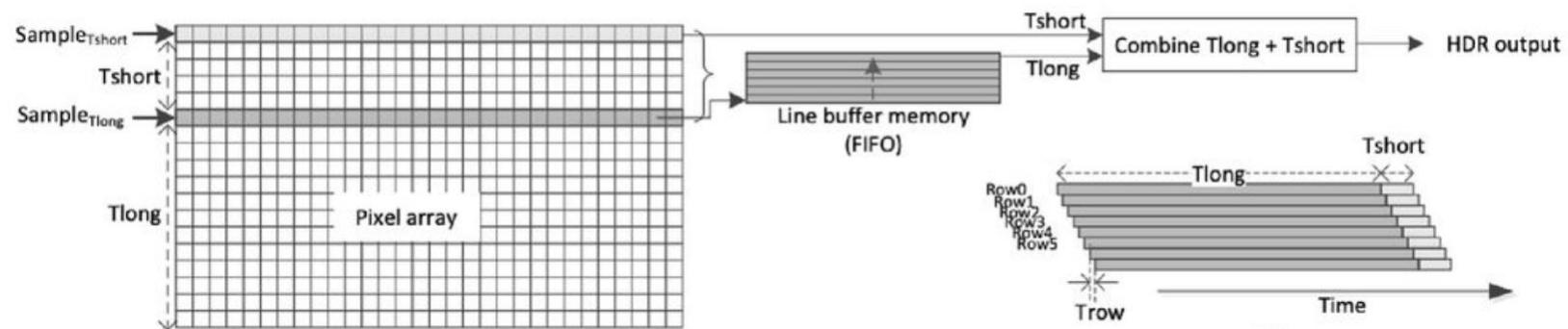


# Bayer variants... and HDR

Q-HDR  
(quad structure with various sensitivities)



Staggered HDR  
(dual read out)

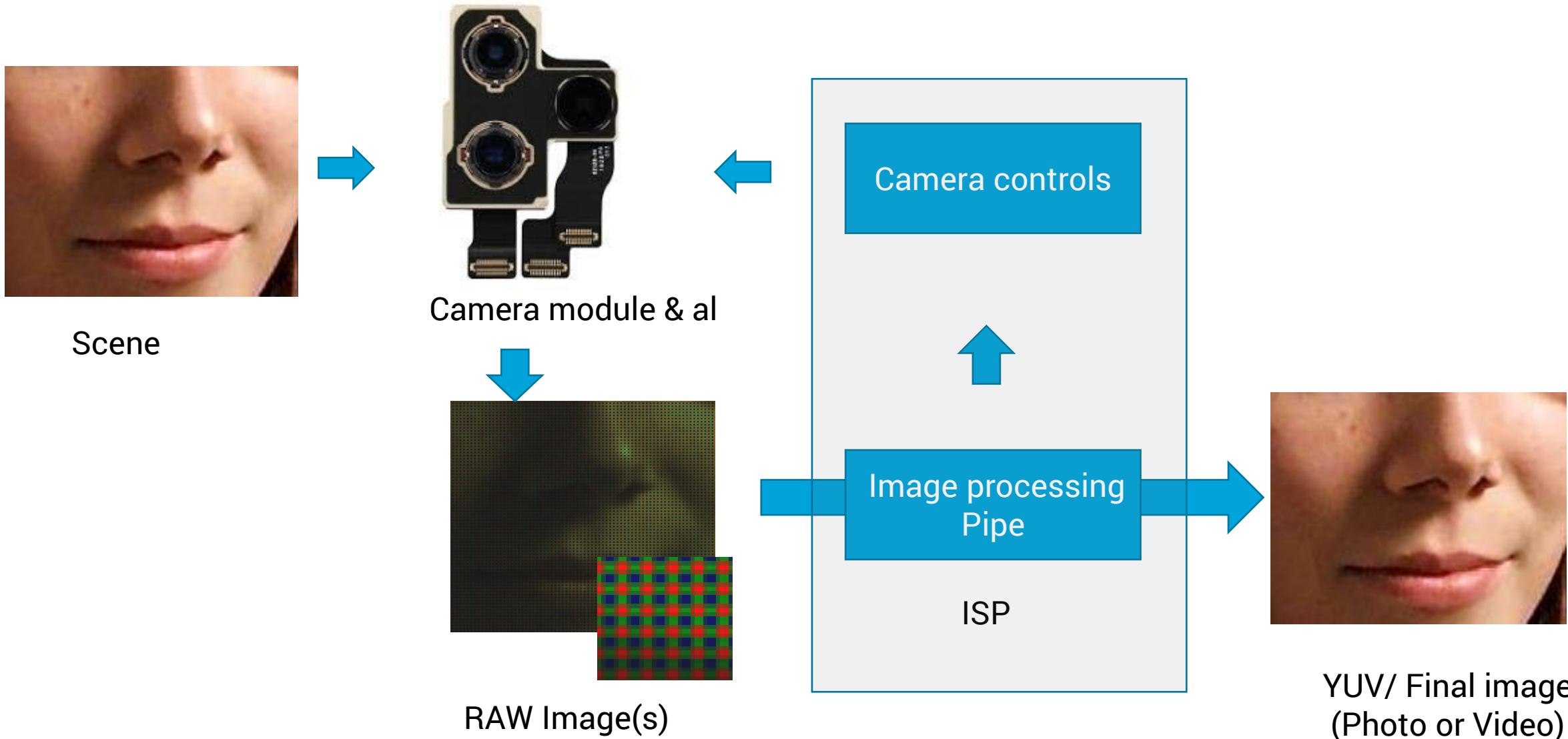


# Smartphone's Camera ingredients



- Camera module(s)  
(and other sensors)
- **The image processing**
  - Introduction (chipset/SW)
  - Camera controls
  - The “image pipe”
  - Architecture

# RAW → RGB



# Suppliers / Chipset

- Proprietary solutions:

- Apple (A series)
- Samsung (Exynos)
- Huawei Hisilicon (Kirin)

- Off the shelves:

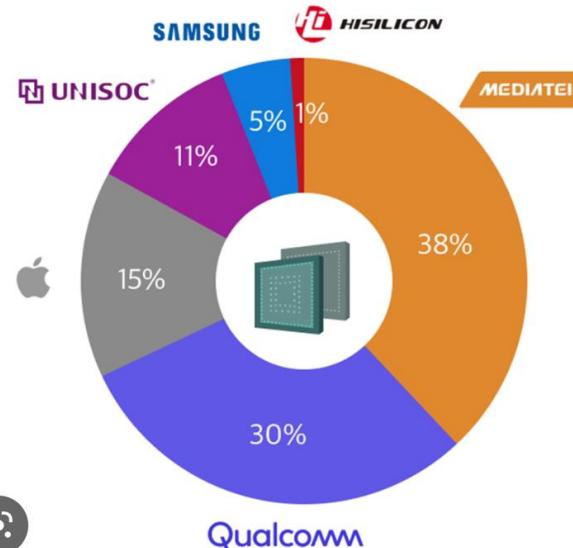
- Qualcomm (QTI Snapdragon)
- Mediatek (MTK Dimensity)
- Unisoc

- Kind of mixed:

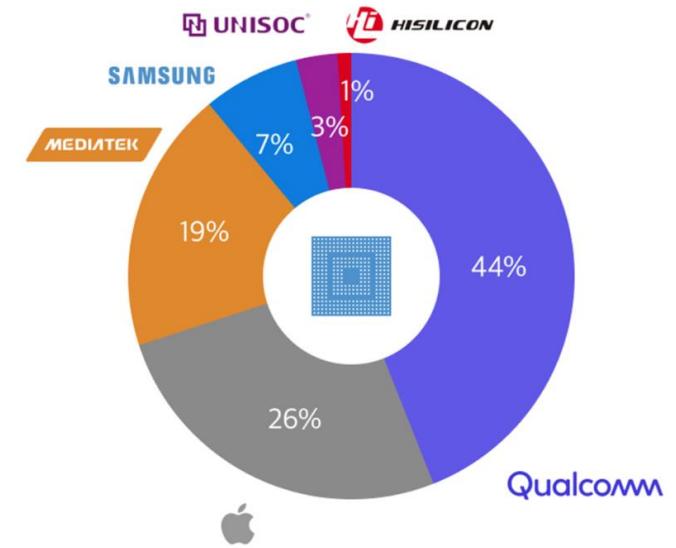
- Google : QTI + Tensor
- Oppo : QTI or MTK + Marisilicon

Global Smartphone AP Market Share by Shipments

Q1 2022



Global Smartphone AP Market Share by Revenue



# An example : Snapdragon 8gen2



## Artificial Intelligence

Qualcomm® Adreno™ GPU

Qualcomm® Kryo™ CPU

Qualcomm® Hexagon™ Processor

- Fused AI Accelerator Architecture
- Hexagon Tensor Accelerator
- Hexagon Vector eXtensions
- Hexagon Scalar Accelerator
- Hexagon Direct Link
- Support for mix precision (INT8+INT16)
- Support for all precisions (INT4, INT8, INT16, FP16)
- Micro Tile Inferencing

Qualcomm® Sensing Hub

- Dual AI Processors for audio and sensors
- Always-Sensing camera

## 5G Modem-RF System

Qualcomm® X70 5G Modem-RF System

- 5G mmWave and sub-6 GHz, standalone (SA) and non-standalone (NSA) modes, standalone mmWave and mmWave-sub6 dual connectivity, FDD, TDD
- mmWave: 8 carriers, 2x2 MIMO
- Sub-6 GHz: 4x4 MIMO
- Qualcomm® 5G AI Suite
- Qualcomm® AI-Enhanced Signal Boost
- Qualcomm® 5G PowerSave Gen 3

## Camera

Qualcomm Spectra™ Image Signal Processor

- Cognitive ISP, Triple 18-bit ISPs
- Up to 36 MP triple camera @ 30 FPS with Zero Shutter Lag
- Up to 64+36 MP dual camera @ 30 FPS with Zero Shutter Lag
- Up to 108 MP single camera @ 30 FPS with Zero Shutter Lag
- Up to 200 Megapixel Photo Capture

AI-based face detection, auto-focus, and auto-exposure

Rec. 2020 color gamut photo and video capture

Up to 10-bit color depth photo and video capture

8K HDR Video Capture + 64 MP Photo Capture

10-bit HEIF: HEIC photo capture, HEVC video capture

Video Capture HDR Formats: HDR10+, HDR10, HLG, Dolby Vision

8K HDR Video Capture @ 30 FPS

4K Video Capture @ 120 FPS

Slow-mo video capture at 720p @ 960 FPS

8K Video Playback @ 60 FPS

Engine for Visual Analytics 3.0

## CPU

Kryo CPU

- 64-bit Architecture
- 1 Prime core, up to 3.2 GHz<sup>2</sup>
  - Arm Cortex-X3 technology
- 4 Performance cores, up to 2.8 GHz
- 3 Efficiency cores, up to 2.0 GHz

## Visual Subsystem

Adreno GPU

- Real-time Hardware Accelerated Ray Tracing
- Snapdragon Game Post Processing Accelerator
- HDR gaming (10-bit color depth, Rec. 2020 color gamut)
- Snapdragon Shadow Denoiser
- API Support: OpenGL® ES 3.2, OpenCL™ 2.0 FP, Vulkan® 1.3
- Hardware-accelerated H.265 and VP9 decoder
- HDR Playback Codec support for HDR10+, HDR10, HLG, and Dolby Vision

## Security

Platform Security Foundations, Trusted Execution

Environment & Services, Secure Processing Unit (SPU)

Trust Management Engine

Qualcomm® wireless edge services (WES) and

ISP : ~3G pixels per second, @ 10K+ ops/pixels → 30 Tops/s

GPU : ~1280 Alu(FP32x3) @ 700Mhz → ~2.7 Tops/s

Made possible thx to 4nm node.

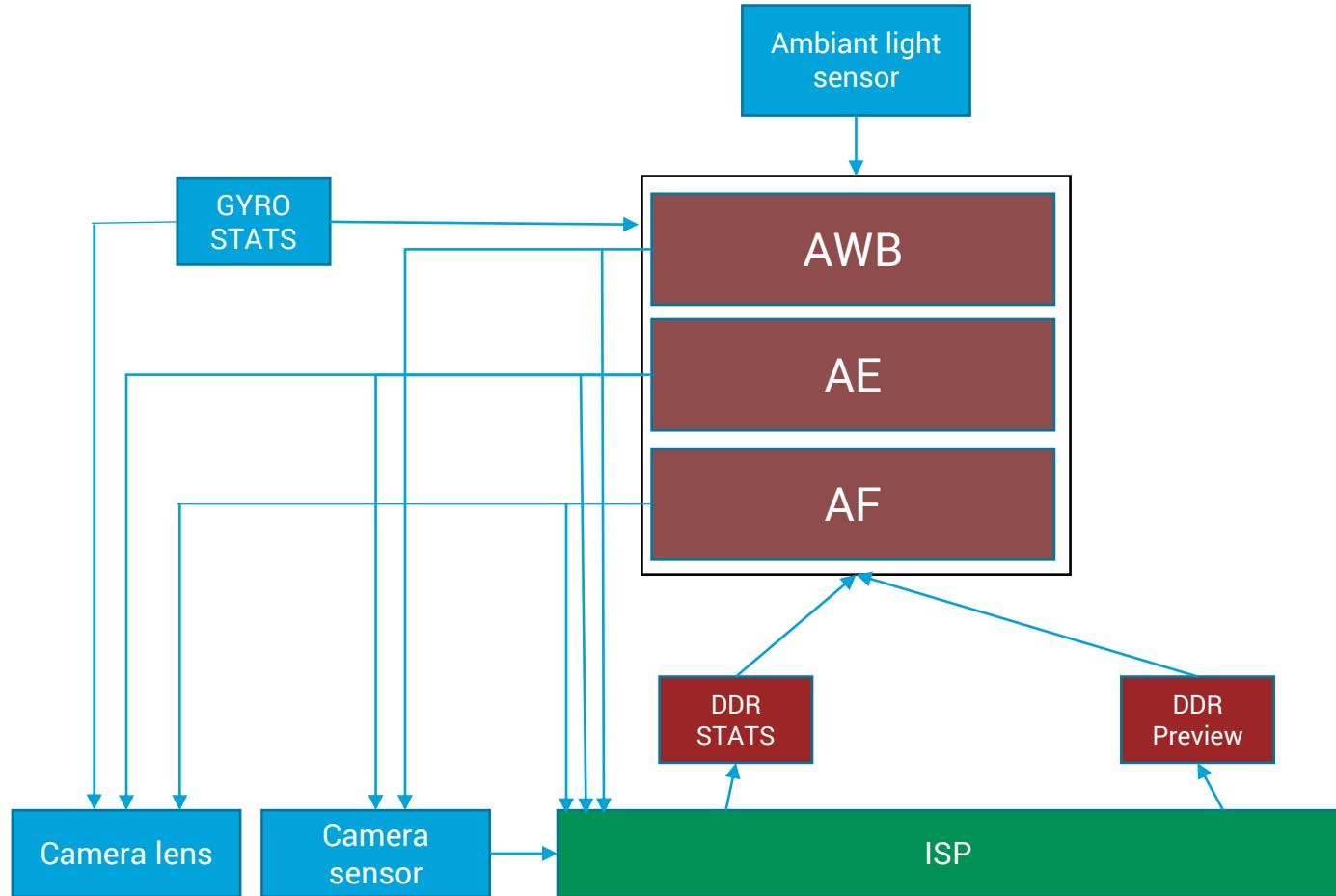
# Smartphone's Camera ingredients



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(and other sensors)
- **Chipset (ISP)**
  - Introduction (chipset/SW)
  - **Camera controls**
  - The “image pipe”
  - Architecture

# Camera Controls or “3A”

- Auto Exposure
- Auto Focus
- Auto White Balance



# Auto Exposure

## Inputs:

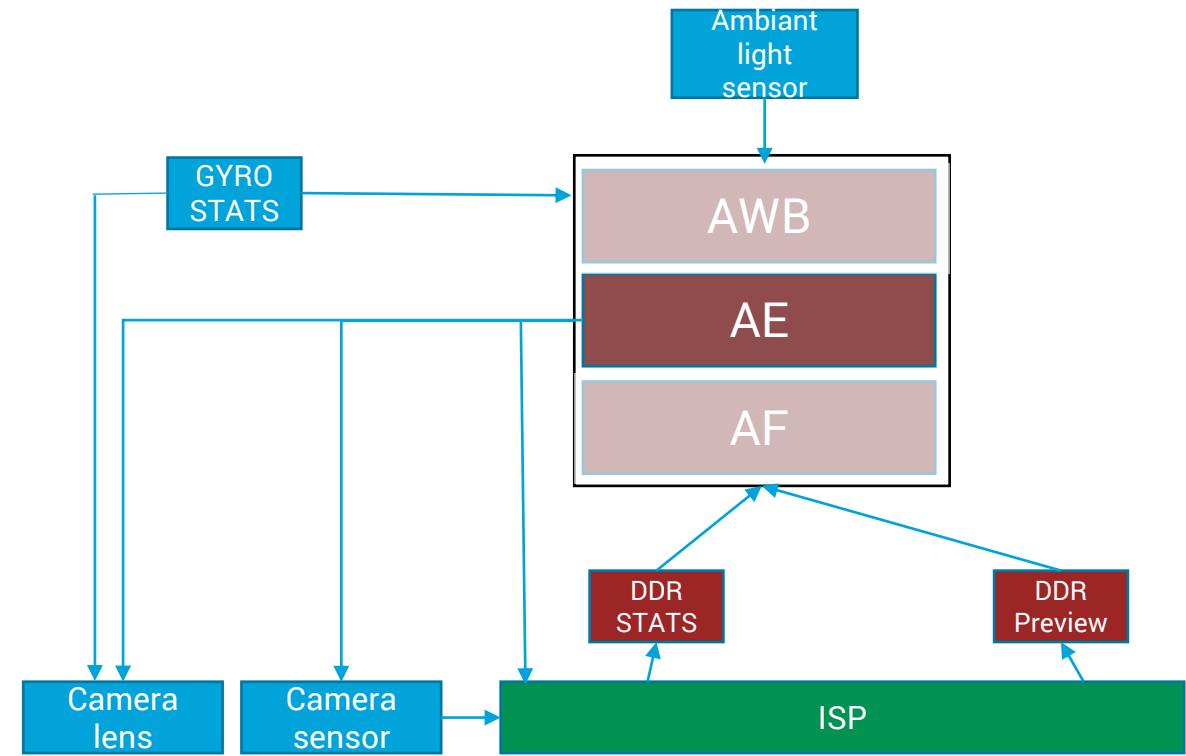
- Image statistics (histogram)
- Ambiant light statistics (flicker)
- Gyro data (camera motion)
- Image preview analysis (face detection, scene motion etc...)

## Outputs:

- Time exposure (sensor)
- Iris (if any to the lens)
- ISO (digital&analog gains green channel)
- Flash control
- Switch to HDR mode with exposures bracketing strategy
- Switch to night mode

## Objectives:

- Tradeoff between SNR, bright clipping and motion blur
- No light flicker



# Auto Exposure

## Inputs:

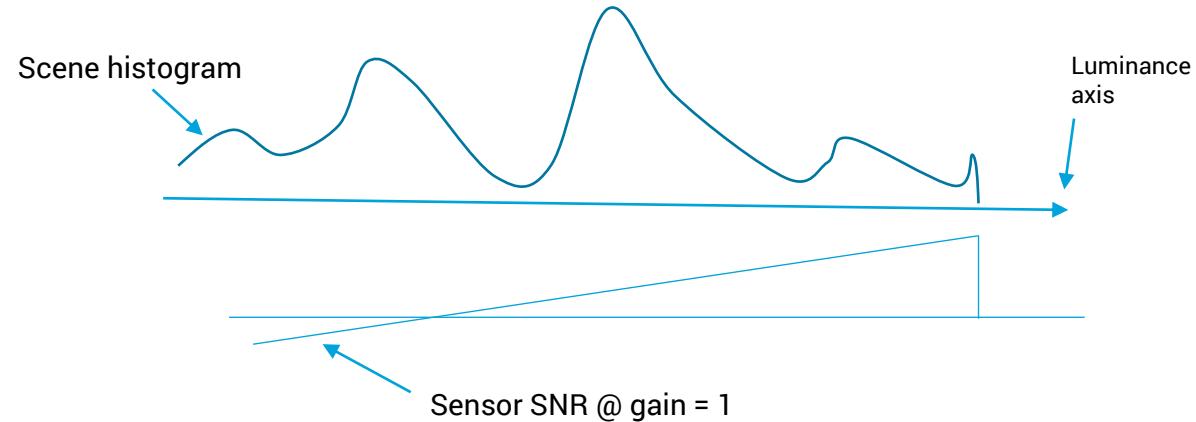
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## Objectives:

- Tradeoff between SNR, bright clipping and motion blur
- No light flicker



#1 : Exposure time adjusted at saturation  
→ No clipped areas. ☺ but... image too dark and  
SNR too low for most part → impossible to digitally relight the  
picture

# Auto Exposure

## Inputs:

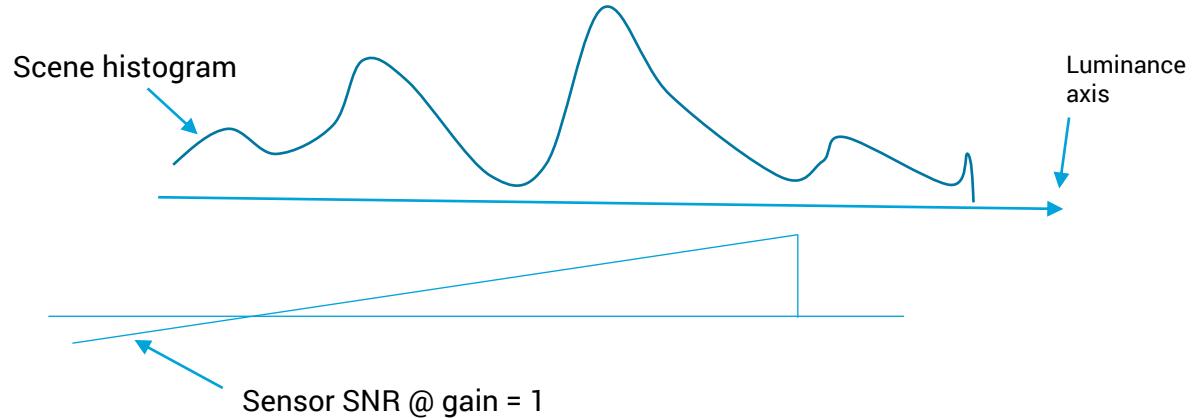
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## Objectives:

- Tradeoff between SNR, bright clipping and motion blur
- No light flicker



#2 : Exposure time adjusted for the main part:

→ Overall good exposure and SNR but  
High-light are clipped. Information lost, impossible to recover.

# Auto Exposure

## Inputs:

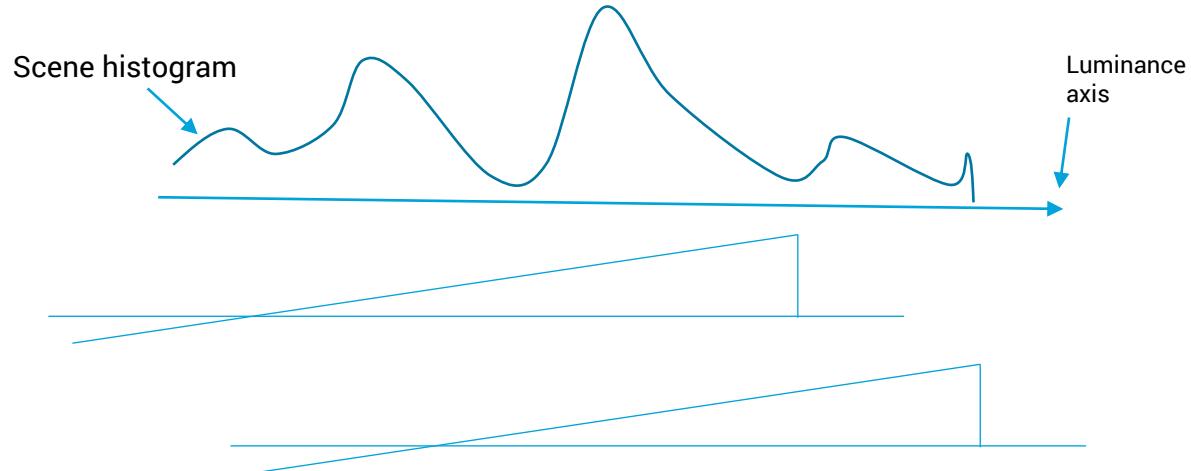
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## Outputs:

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- ISO (digital&analog gains green channel)
- Flash control
- Switch to HDR mode with exposures bracketing strategy
- Switch to night mode

## Objectives:

- Tradeoff between SNR, bright clipping and motion blur
- No light flicker



#3 : Switch to HDR strategy with two exposures.

→ All parts are captured with reasonable SNR  
But, two images to fuse, with possible motion in between...

# Auto Exposure

## Inputs:

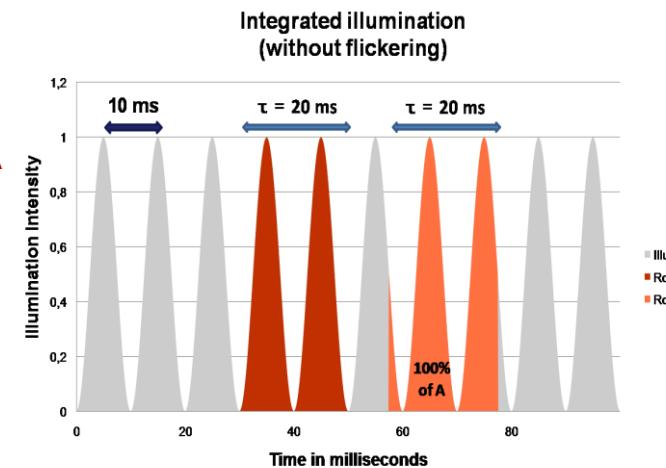
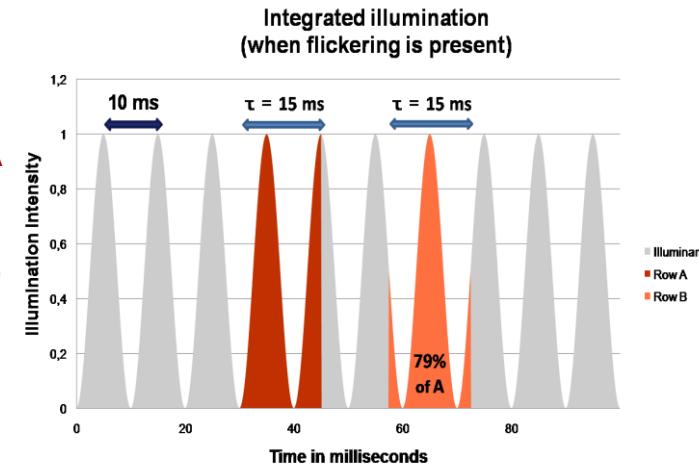
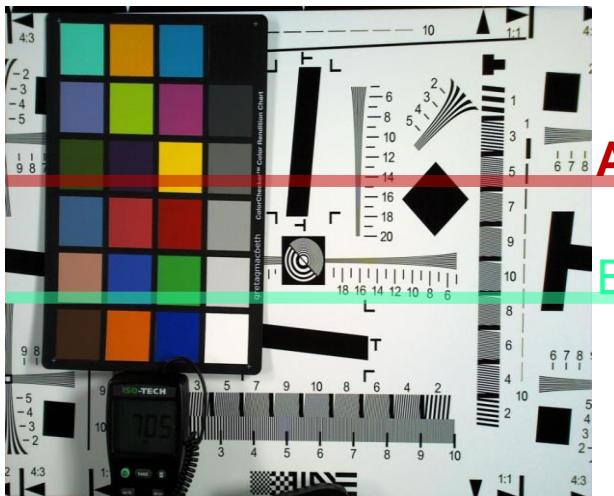
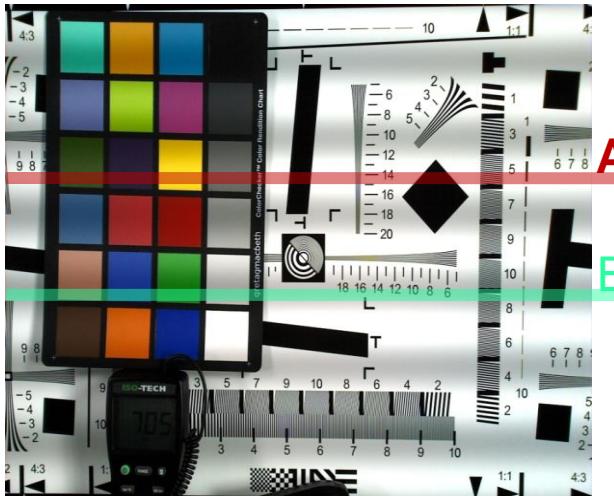
- Image statistics (histogram)
- Ambiant light statistics (flicker)
- Gyro data (camera motion)
- Image preview analysis (face detection, scene motion etc...)

## Outputs:

- **Time exposure** (sensor)
- Iris (if any to the lens)
- ISO (digital&analog gains green channel)
- Flash control
- Switch to HDR mode with exposures bracketing strategy
- Switch to night mode

## Objectives:

- Tradeoff between SNR, bright clipping and motion blur
- **No light flicker**



# Auto White Balance

## Inputs:

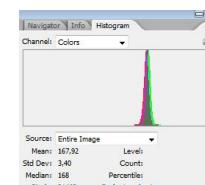
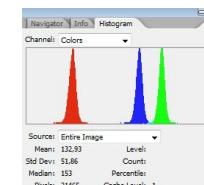
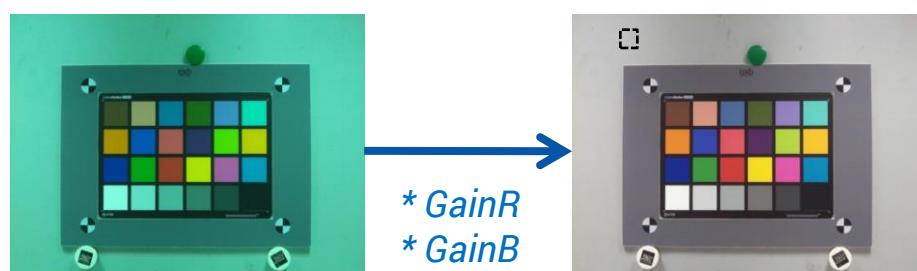
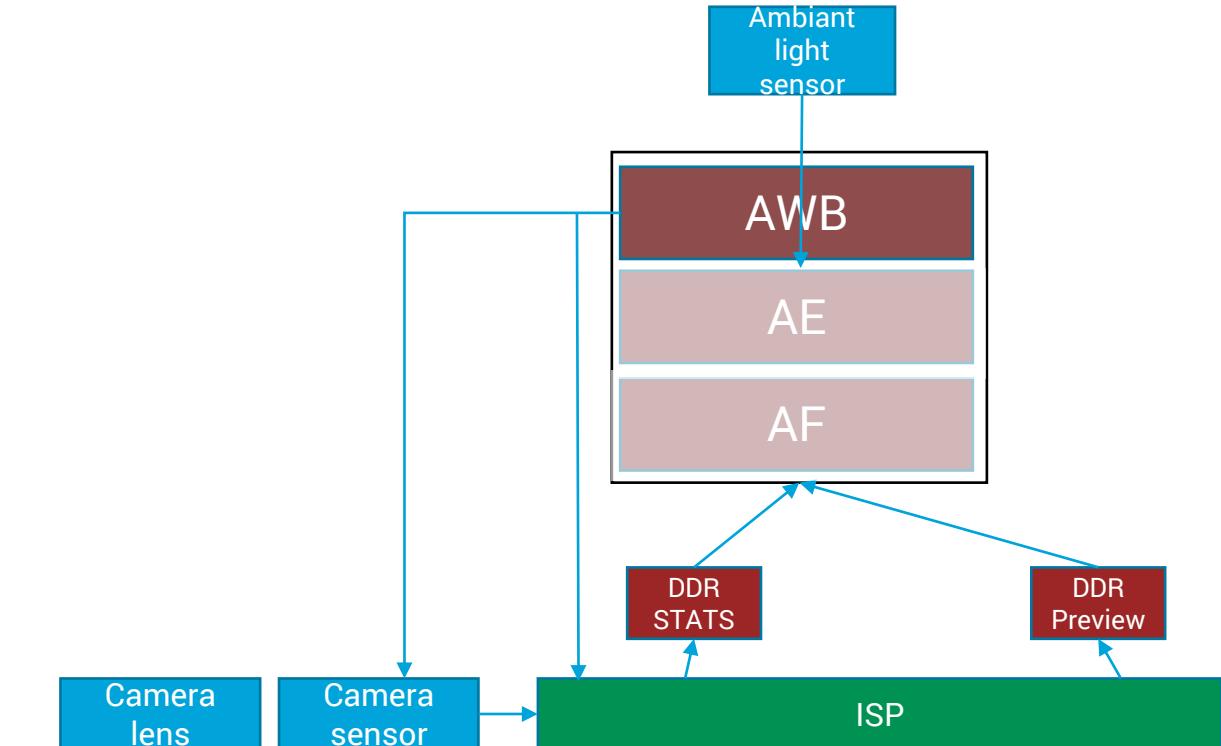
- Image statistics (histogram)
- Ambiant light statistics
- Image preview analysis (face detection, content analysis, etc...)

## Outputs:

- 2 gains : Blue and Red gain (vs Green one)
- (additional option : color rendering maps)

## Objective:

- “Get the colors right”

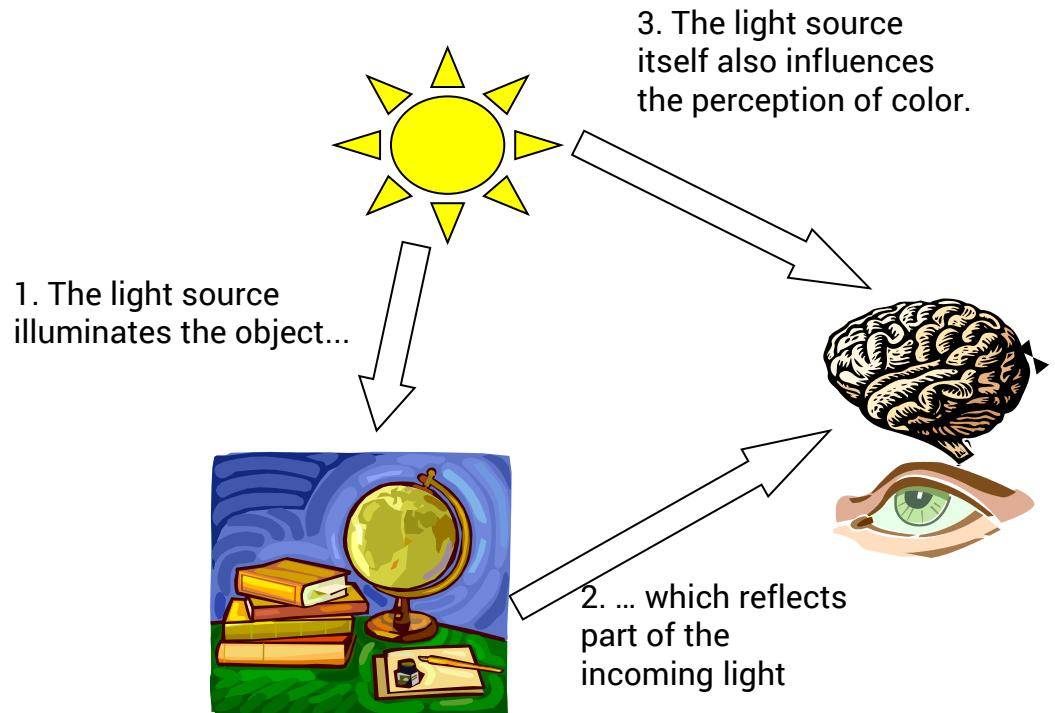


# Auto White balance

## The « triangle of color »

(Perceived) color of an object is the result of an interaction between :

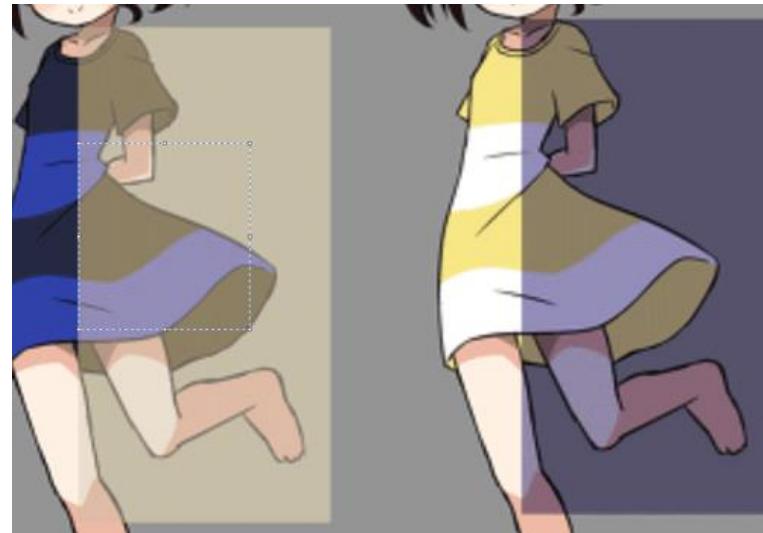
the light source,  
the object and...  
the human visual system.



### White balance objective:

Get rendered colors by the camera to be independent from the illumination conditions

→ Illuminant should be determined.



# Auto White balance - which illuminant ?



Shade

D65

D60



D55

Fluo40

Tungsten

# Auto White Balance

## Inputs:

- Image statistics (histogram)
- Ambiant light statistics
- Image preview analysis (face detection, content analysis, etc...)

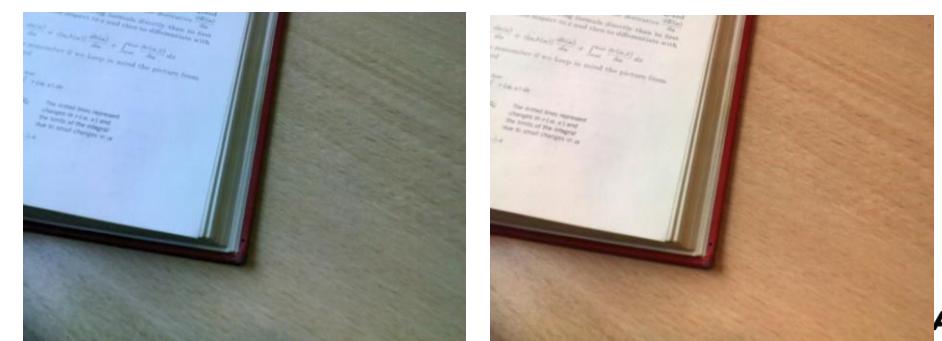
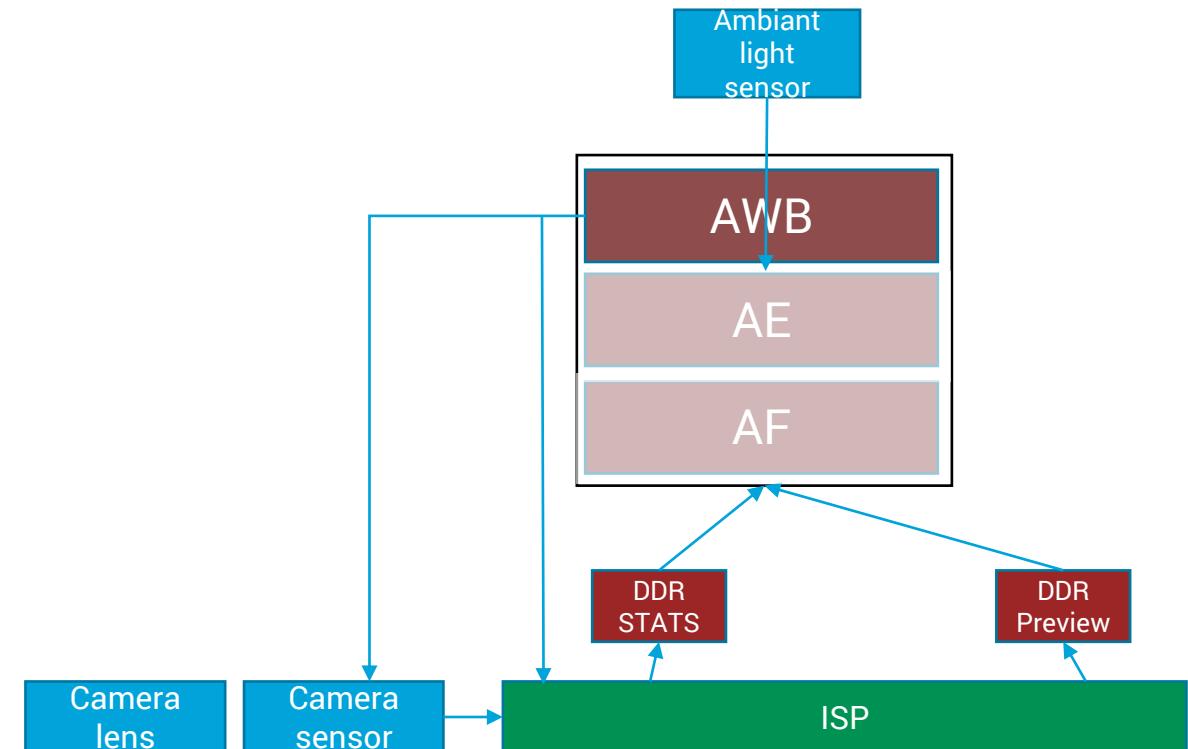
## Outputs:

- 2 gains : Blue and Red gain (vs Green one)
- (additional option : color rendering maps)

## Objective:

- “Get the colors right”

Not so simple and partly subjective...



# Auto Focus

## Inputs:

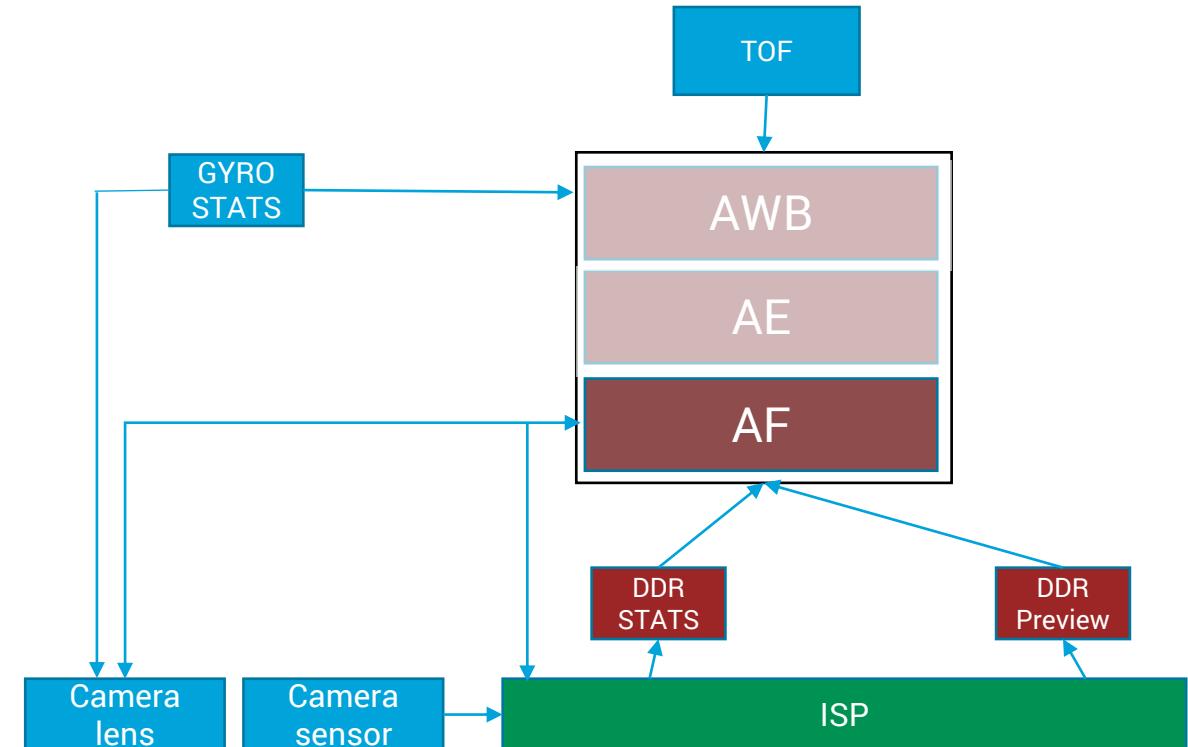
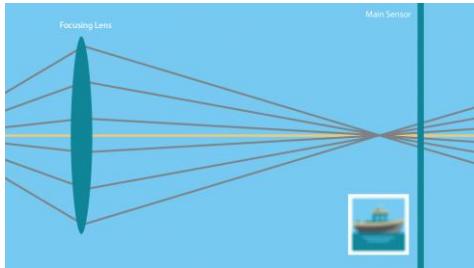
- Image statistics, dual/phase pixels data.
- Image preview analysis (face detection...)
- TOF data
- Hall sensor data from lens' AF actuator or Gyro data (accelerometer)

## Outputs:

- **Focus position for lens**
- Magnification factor for ISP

## Objectives:

- Important part of the scene should be in focus.



# Auto Focus

## Inputs:

- Image statistics, **dual/phase pixels data**.
- Image preview analysis (face detection...)
- TOF data
- Hall sensor data from lens' AF actuator or Gyro data (accelerometer)

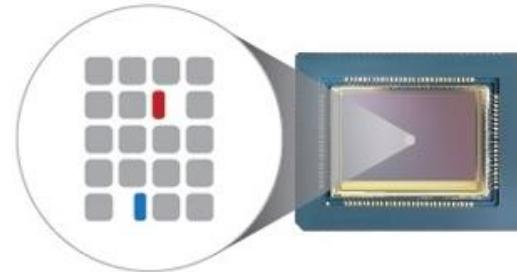
## Outputs:

- **Focus position for lens**
- Magnification factor for ISP

## Objectives:

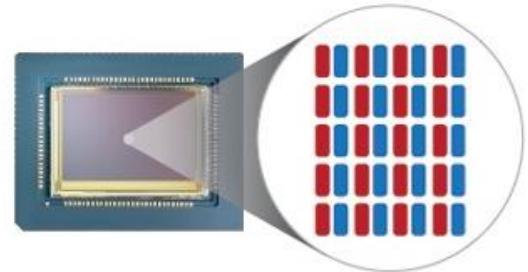
- Important part of the scene should be in focus.

Traditional Phase Detection  
Autofocus Sensor

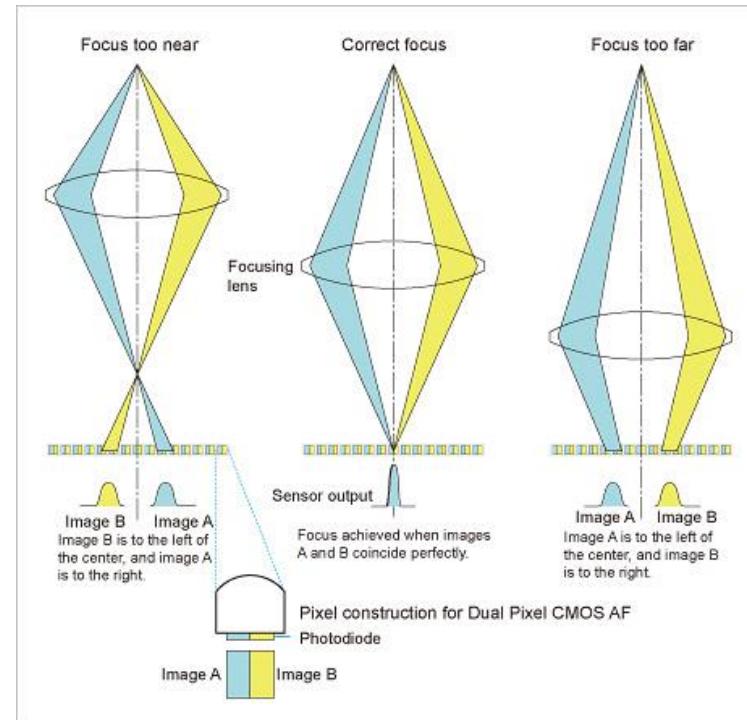


Less than 5% of the pixels are for phase-detection autofocus

Dual Pixel Sensor



100% of the pixels are for phase-detection autofocus

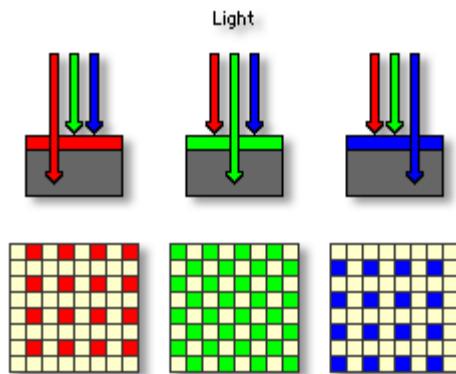
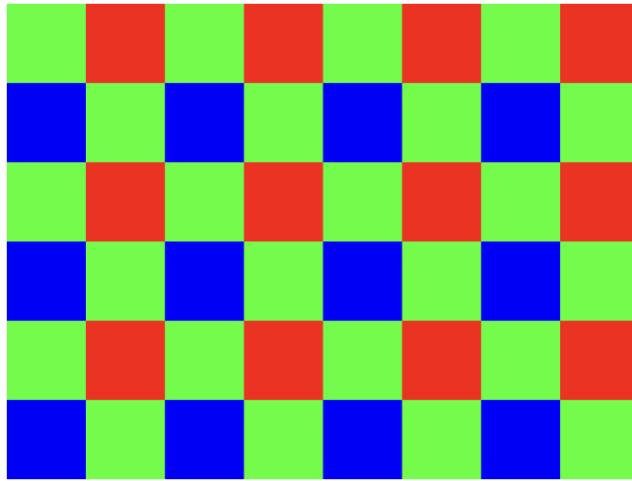


# Smartphone's Camera ingredients

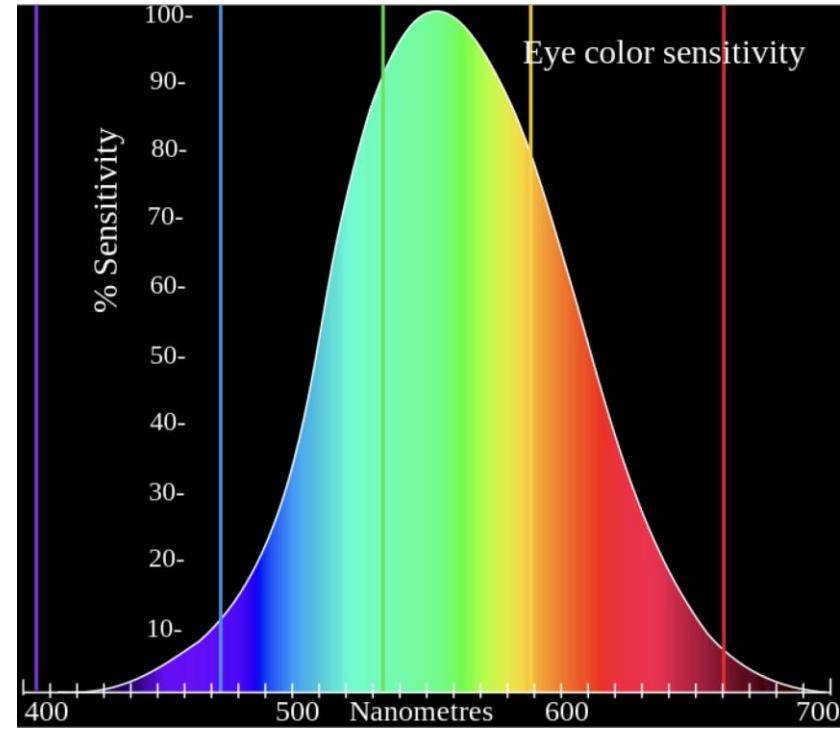


- Camera module(s)  
(and other sensors)
- **Chipset (ISP)**
  - introduction
  - Camera controls
  - **The “image pipe”**
  - Architecture

# Color filter mosaic and demosaicing

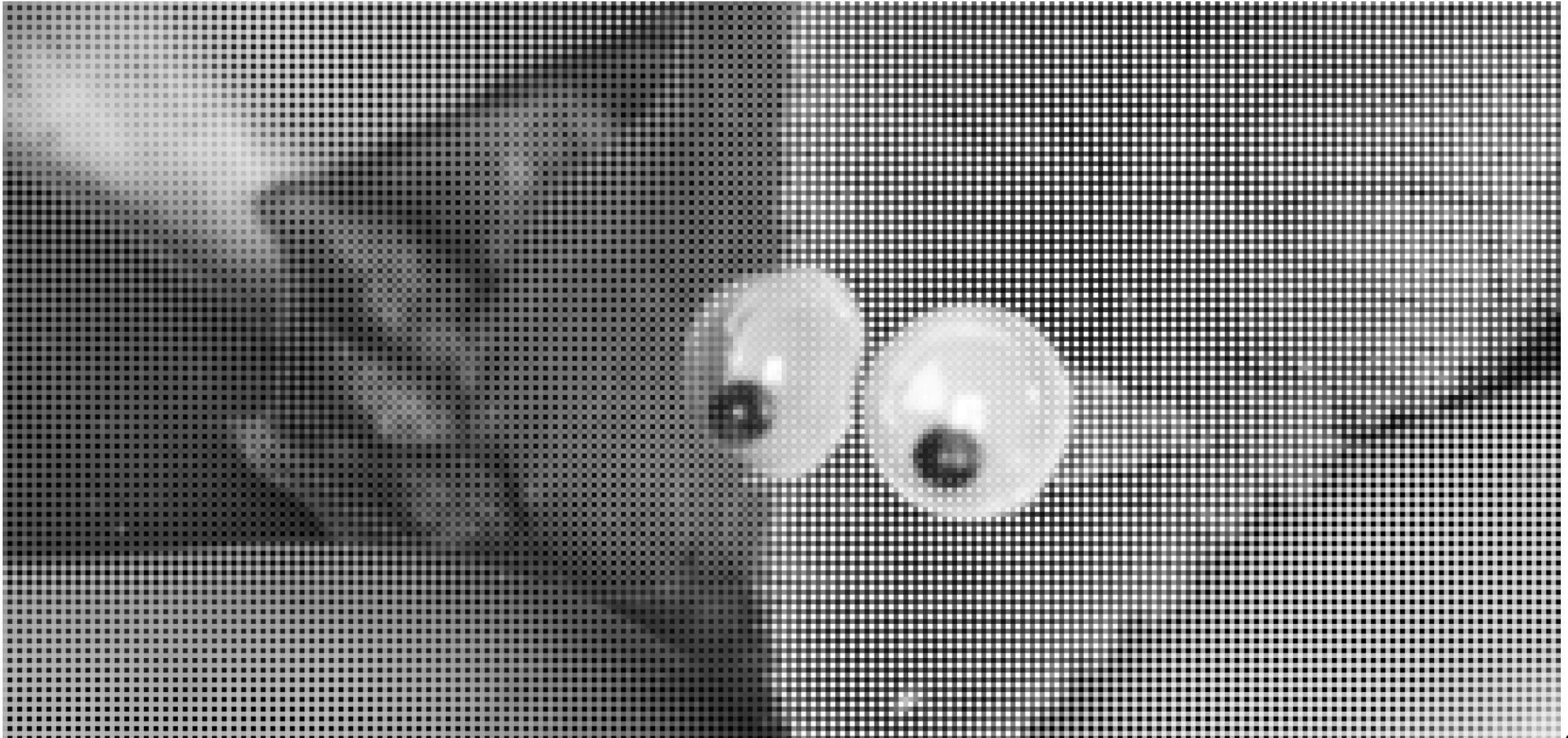


Bayer pattern (Eastman Kodak 1976)

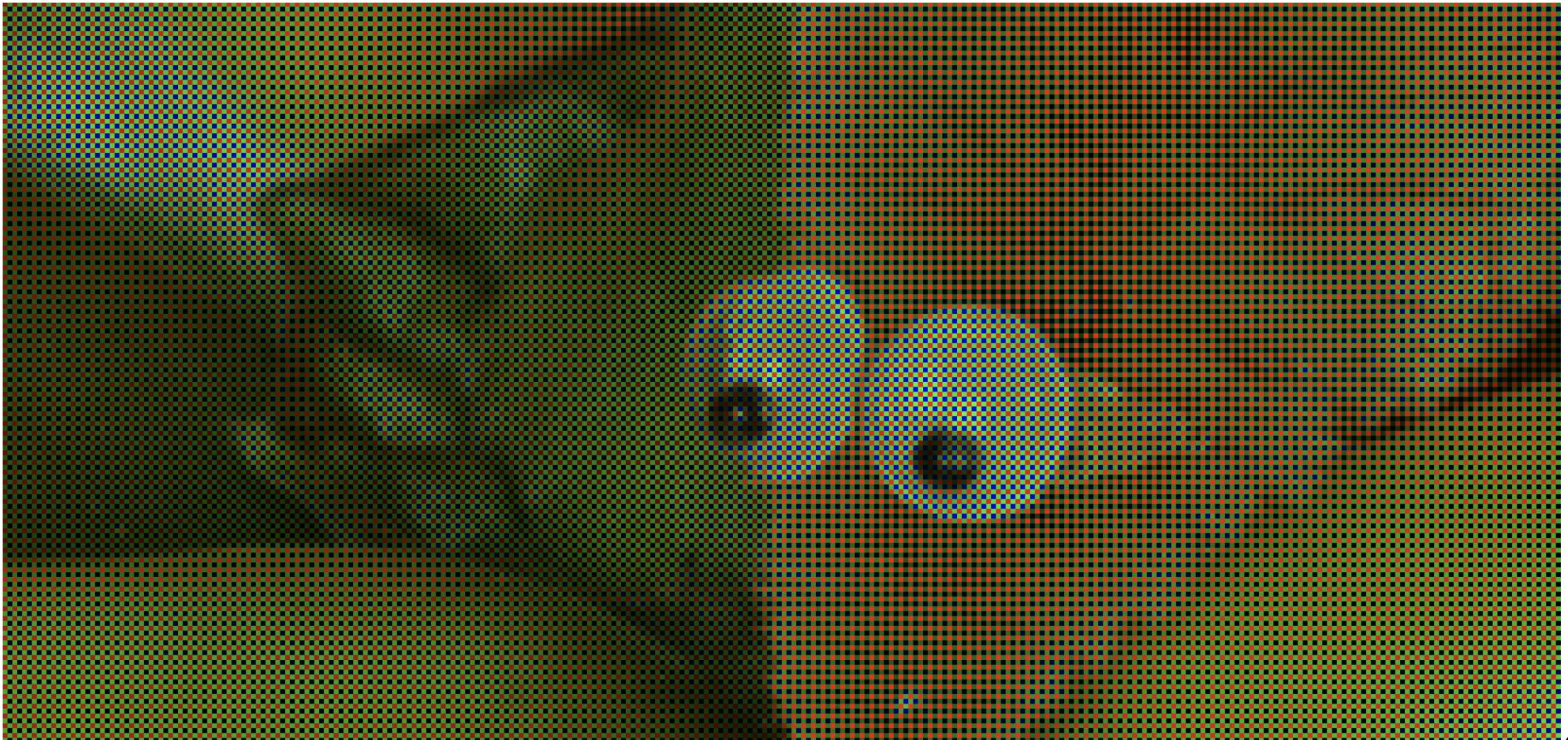


Spectral sensitivity of the human eye

# Sensor output (gray levels)



# Sensor output (color mosaic)



# Demosaiced (Adams Hamilton 1996)



# Color matrix



$$\begin{pmatrix} R' \\ G' \\ B' \end{pmatrix} = \underbrace{\begin{pmatrix} m_{RR} & m_{GR} & 1 - m_{RR} - m_{GR} \\ m_{RG} & m_{GG} & 1 - m_{RG} - m_{GG} \\ m_{RB} & m_{GB} & 1 - m_{RB} - m_{GB} \end{pmatrix}}_{\text{Color management}} \underbrace{\begin{pmatrix} \lambda_R & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \lambda_B \end{pmatrix}}_{\text{White balance}} \gamma \underbrace{\begin{pmatrix} R \\ G \\ B \end{pmatrix}}_{\text{Exposure}}$$

9 DoF    =    6 DoF    +    2 DoF    +    1 DoF

# Exposure



$\times 2$   
+ 1 EV



$\times 2$   
+ 1 EV



# White balance

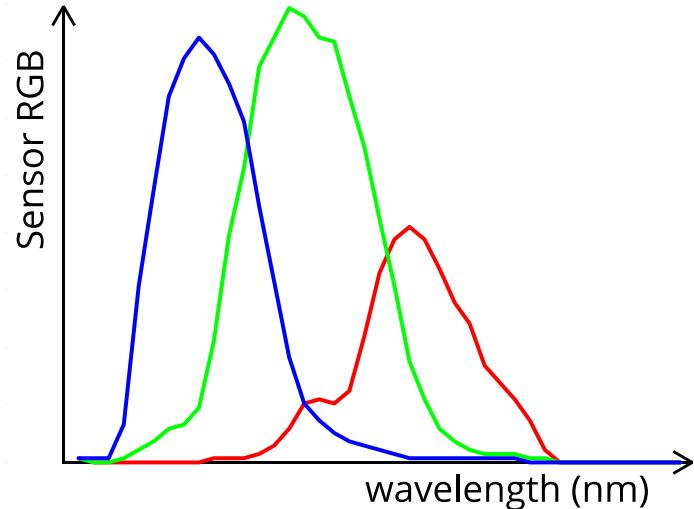


Tungsten

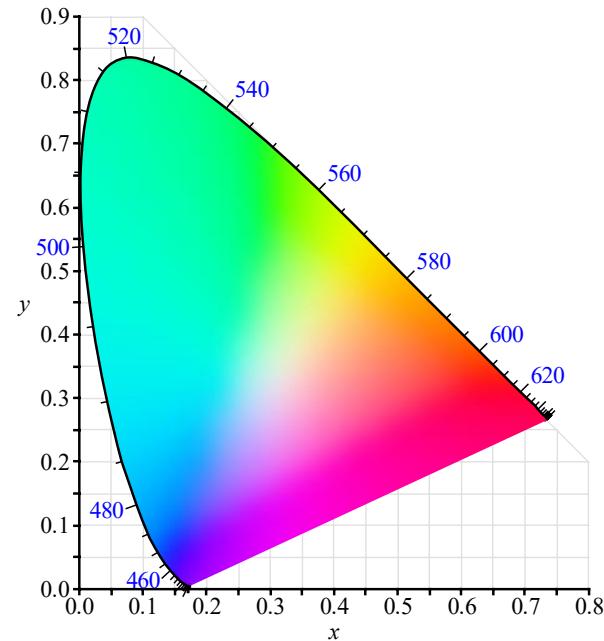


Cloudy daylight

# Color management

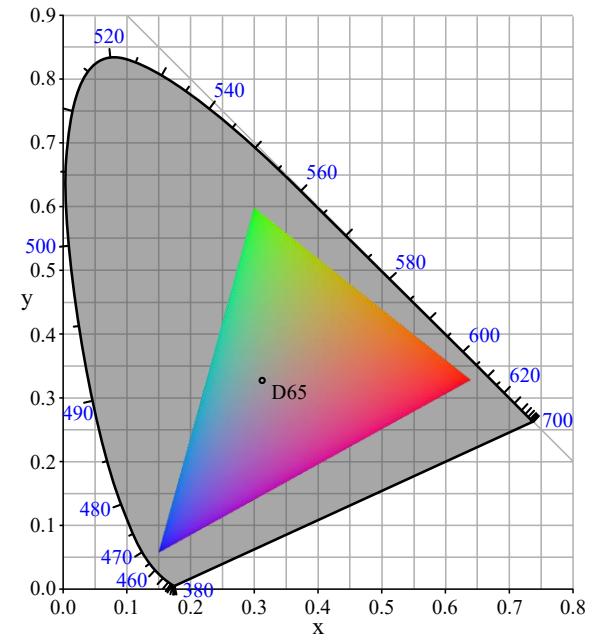


Source  
RGB



Profile connection  
space

Device independent



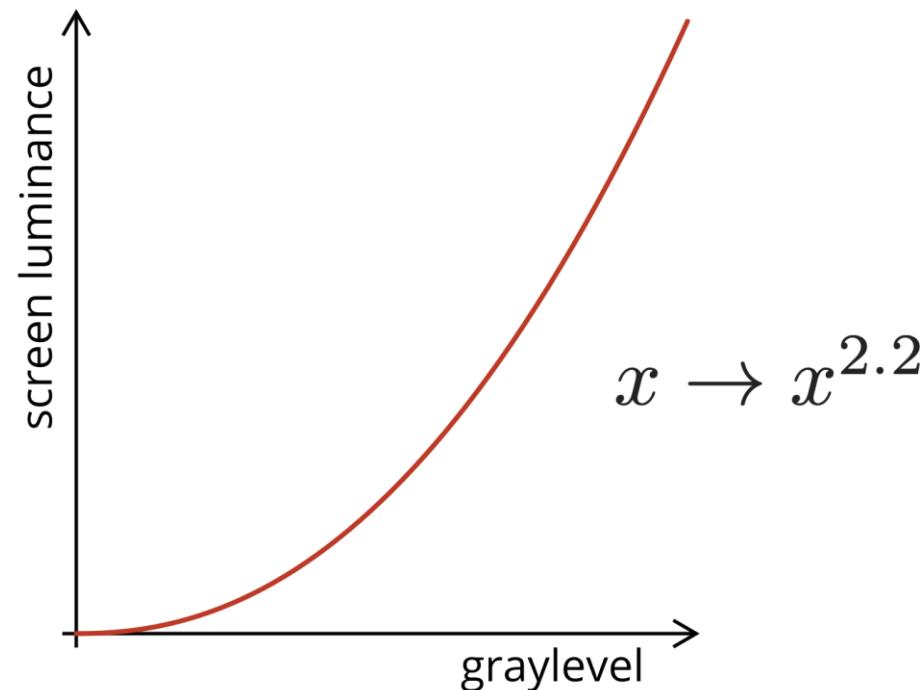
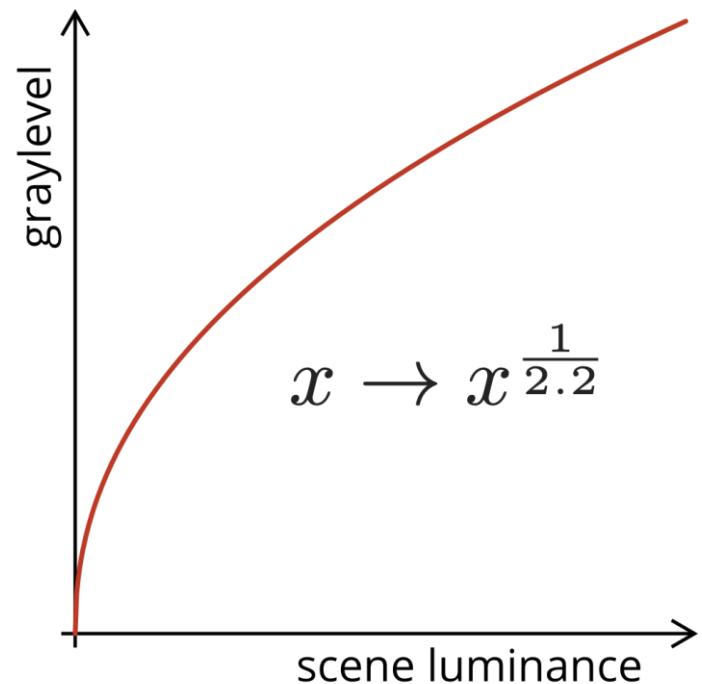
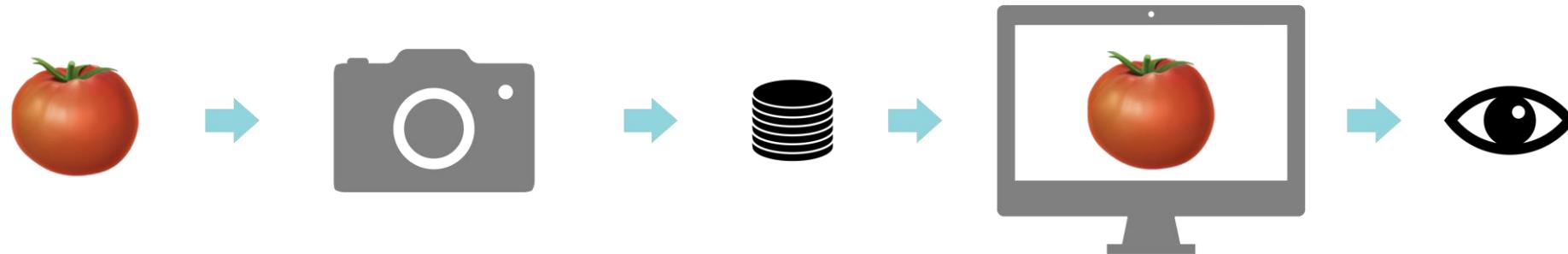
Target  
RGB



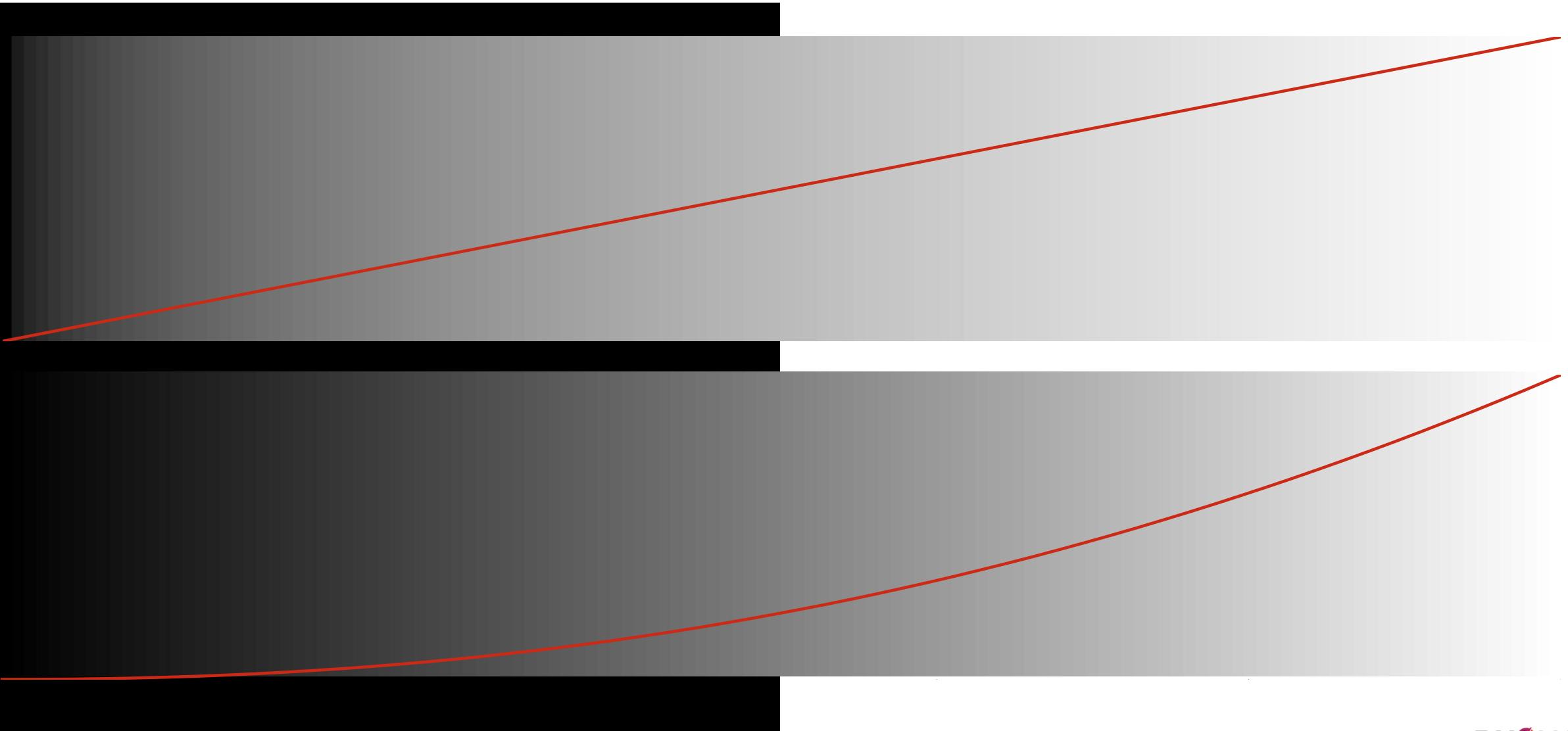
# Color management



# Gamma correction



# Gamma correction



# Lens corrections – Distortions



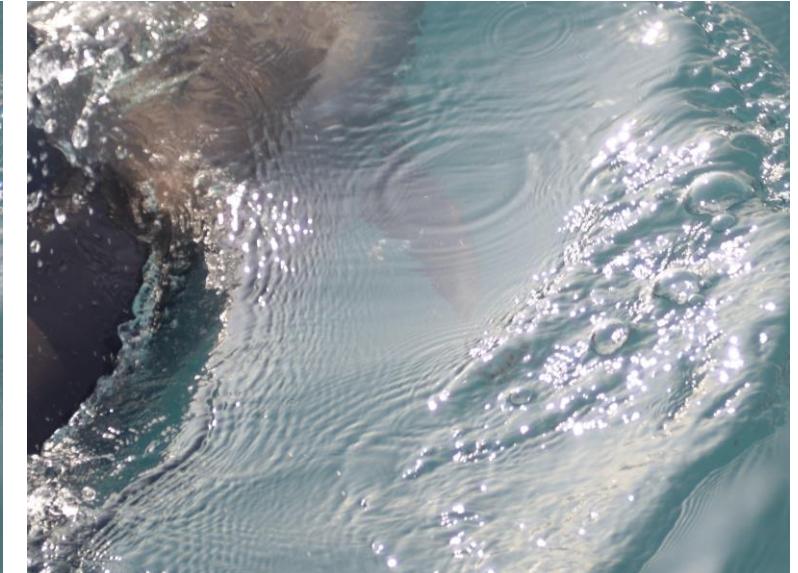
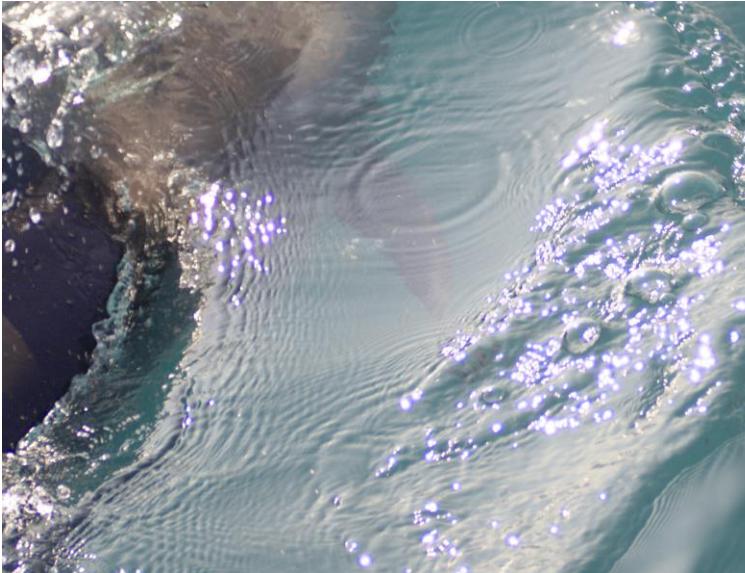
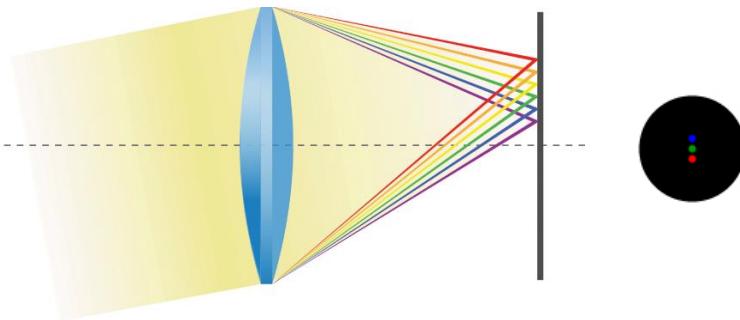
Photo: Hugo Uyttersprot

# Lens corrections – Vignetting aka Lens shading

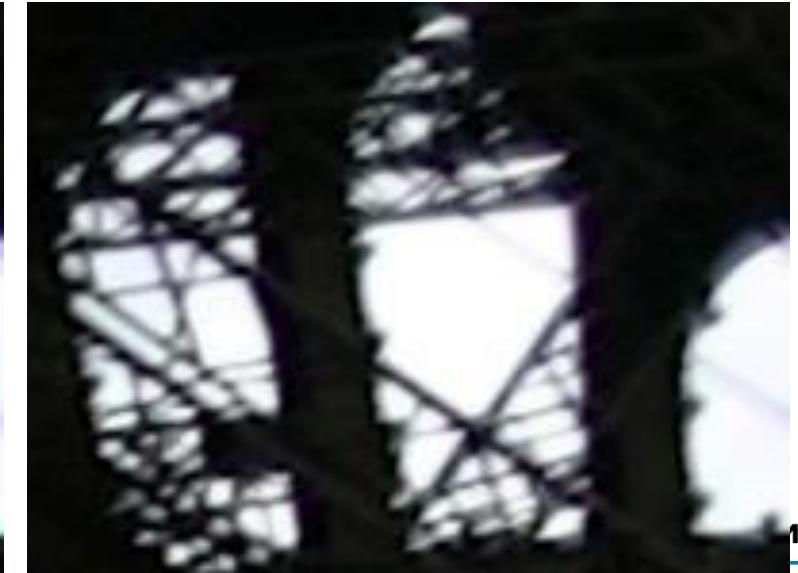
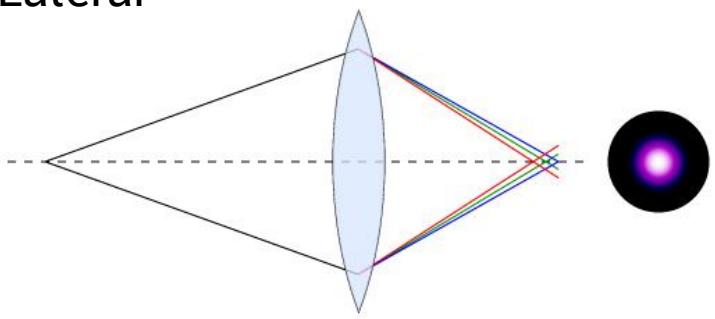


# Lens corrections – Chromatic aberrations

Longitudinal



Lateral



# Denoising



# Color saturation enhancement



# Contrast enhancement (global)



## Contrast enhancement (local)



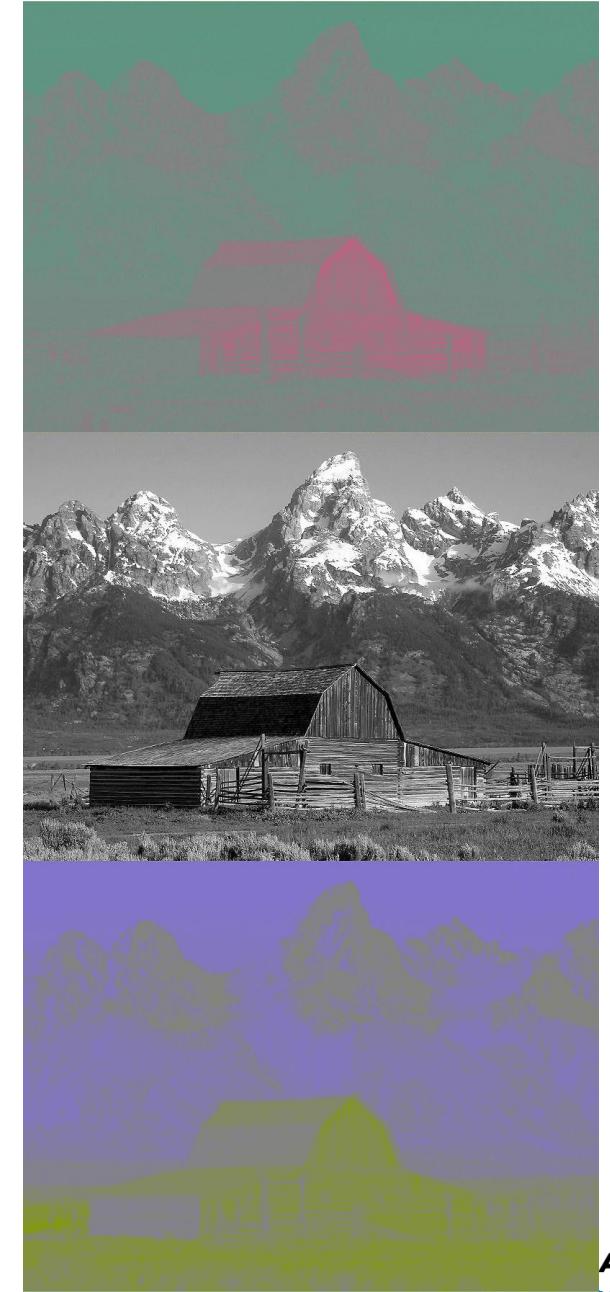
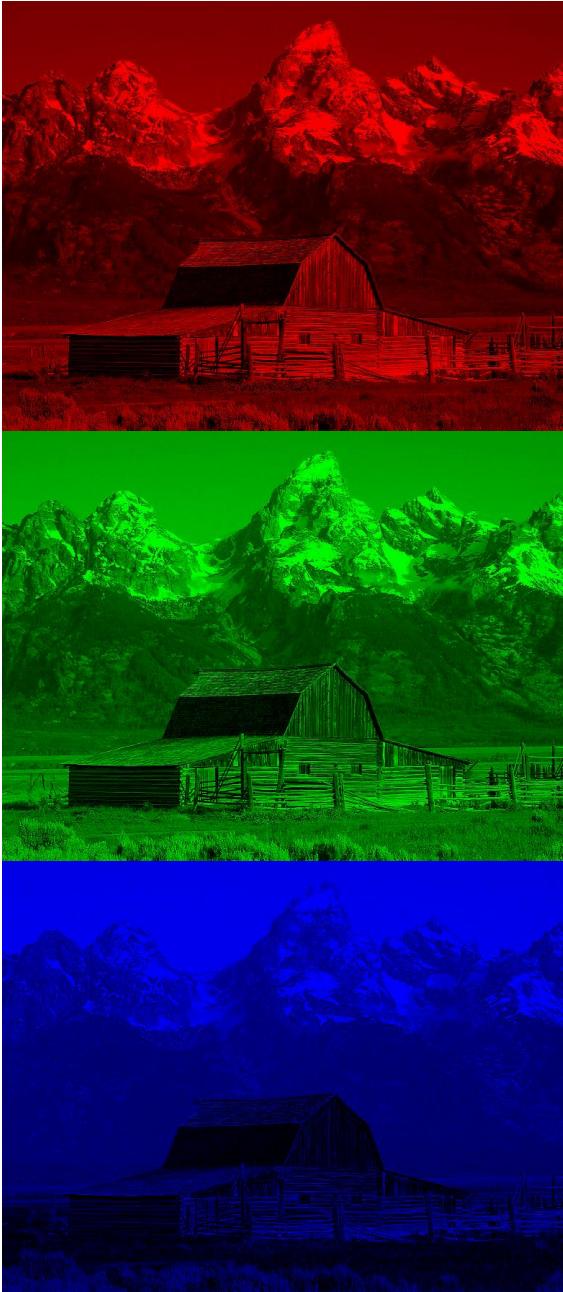
# Sharpness enhancement



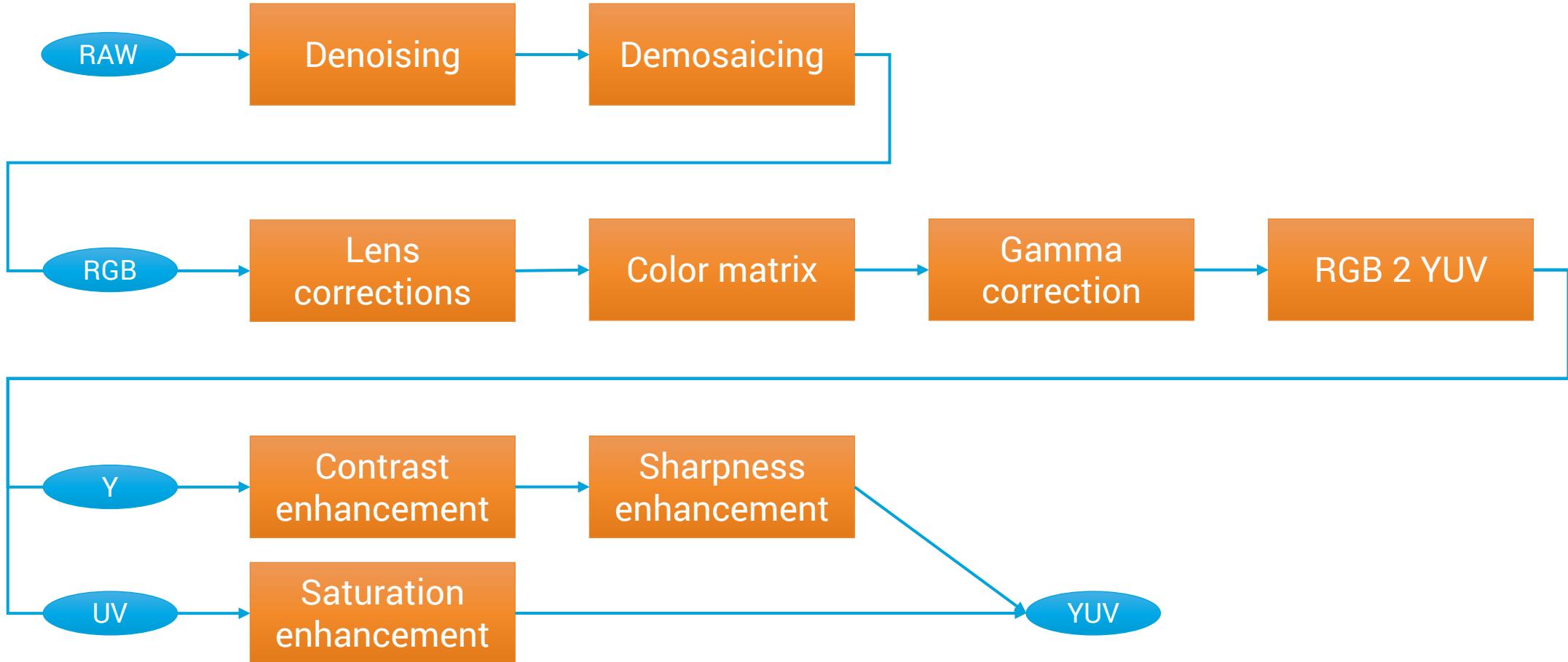
# Chroma – Luma



Source: <https://en.wikipedia.org/wiki/YCbCr>



# Pipeline example



# Smartphone's Camera ingredients



- Camera module(s)  
(and other sensors)
- **Chipset (ISP)**
  - introduction
  - Camera controls
  - The “image pipe”
  - **Architecture**

# ISP – a typical architecture (simplified)

ISP block

HW signal processing block, 1 pixel in, 1 pixel out. Local access only. Same story for all pixels.

CSID

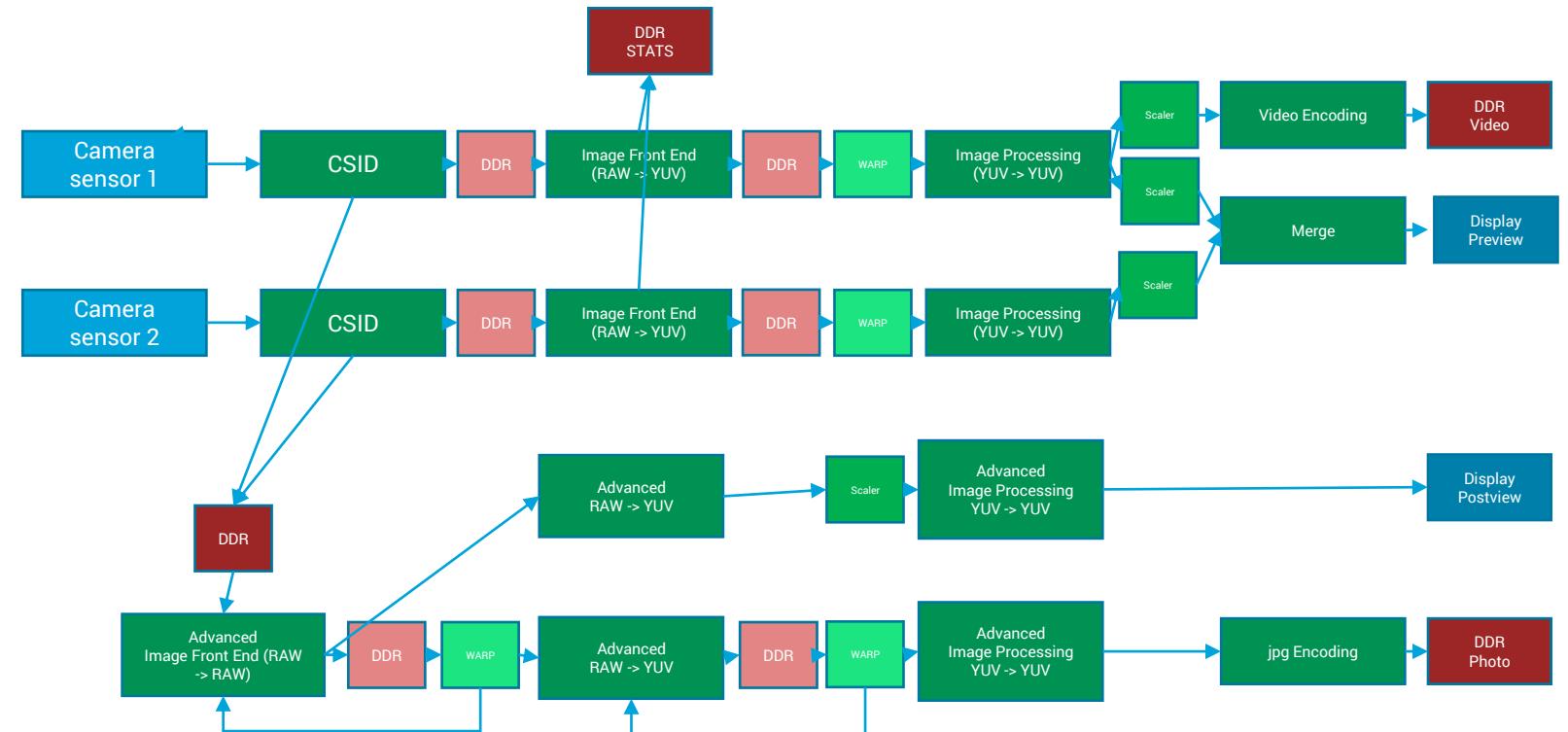
Camera Serial Interface decoder

DDR

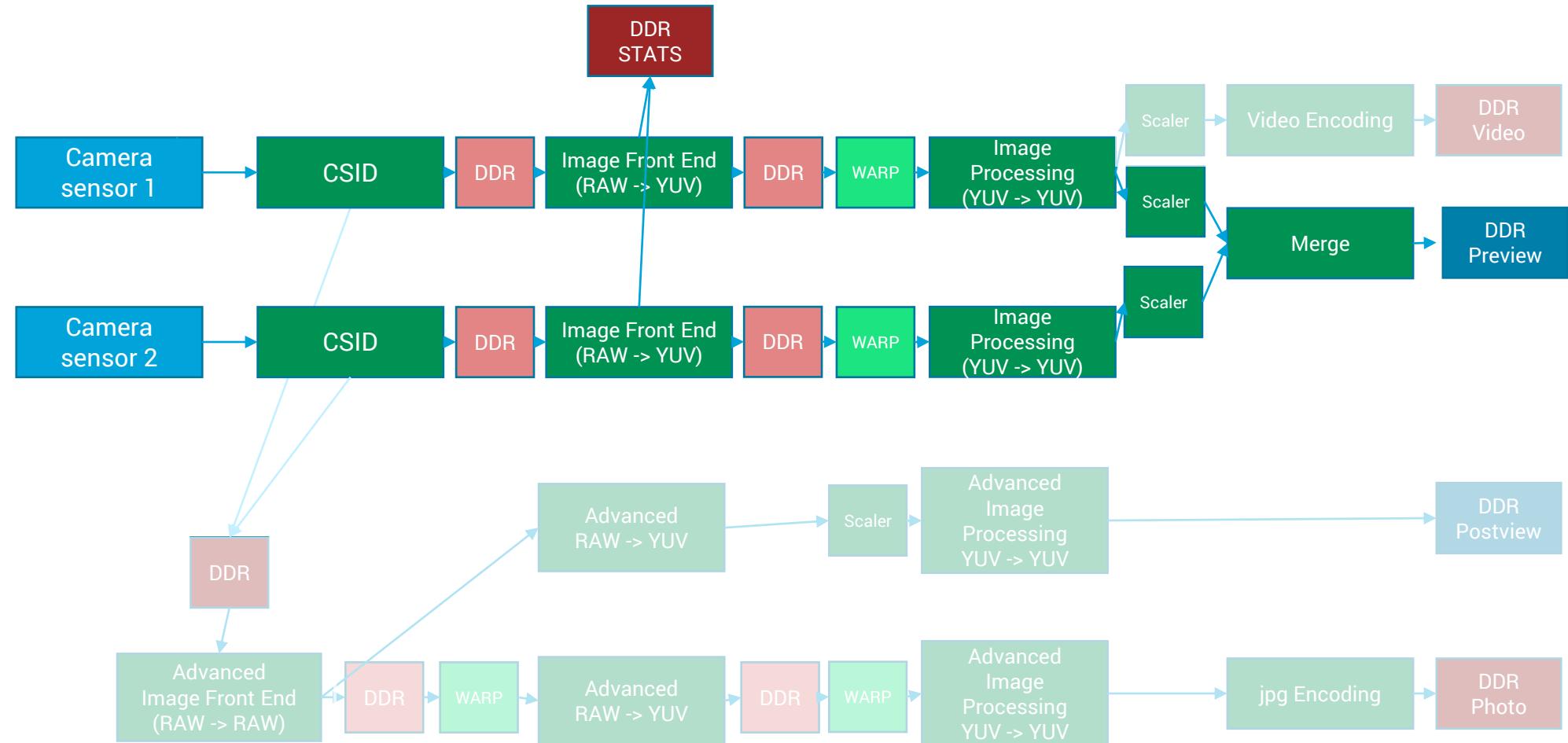
(Optional) back to RAM. Allow buffering and/or additional CPU/GPU processing. But... costly.

Warp/scaler

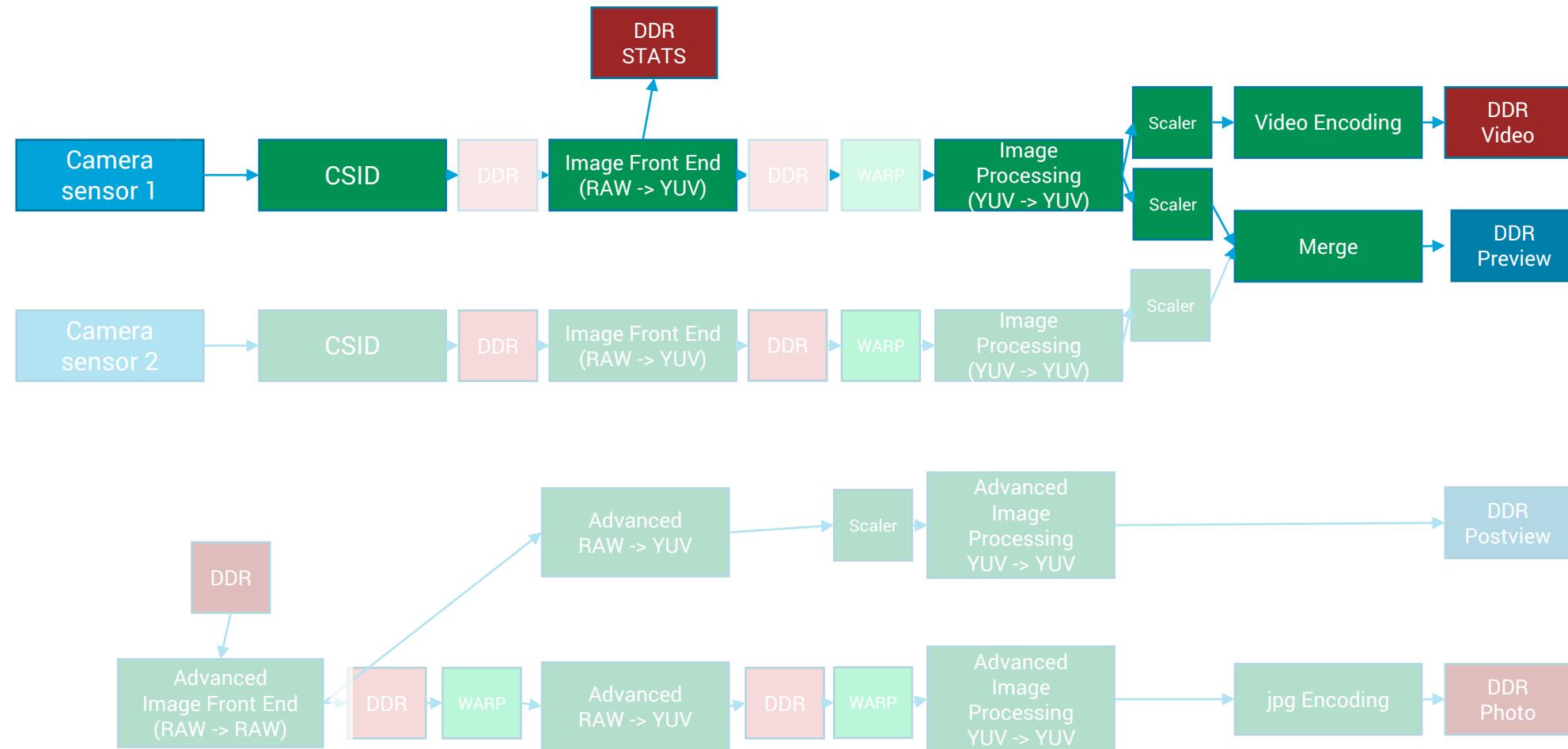
Things that can not be performed by an ISP block...



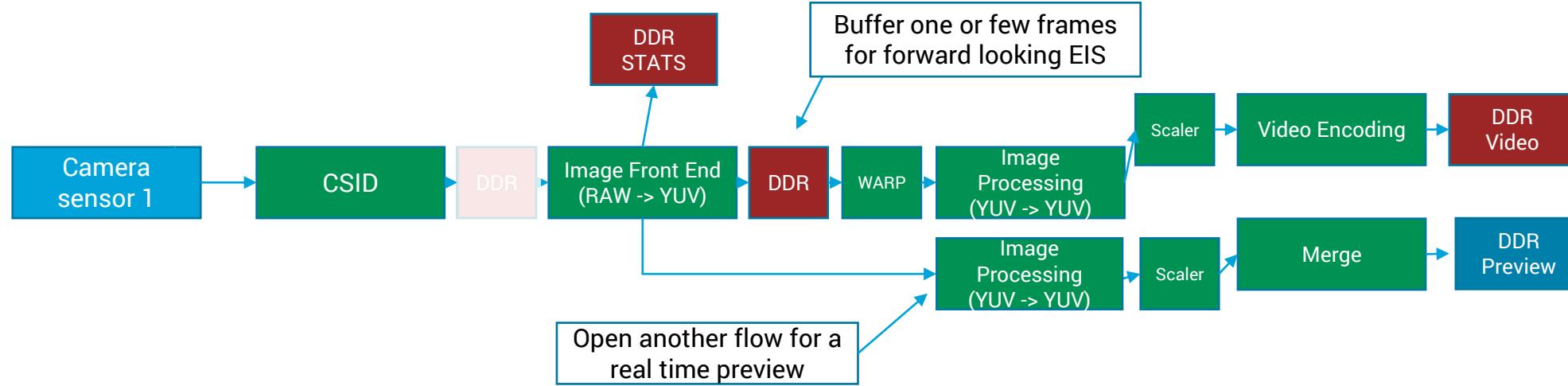
# ISP – During Preview



# ISP – During video recording, without EIS



# ISP – During video recording, with forward looking EIS

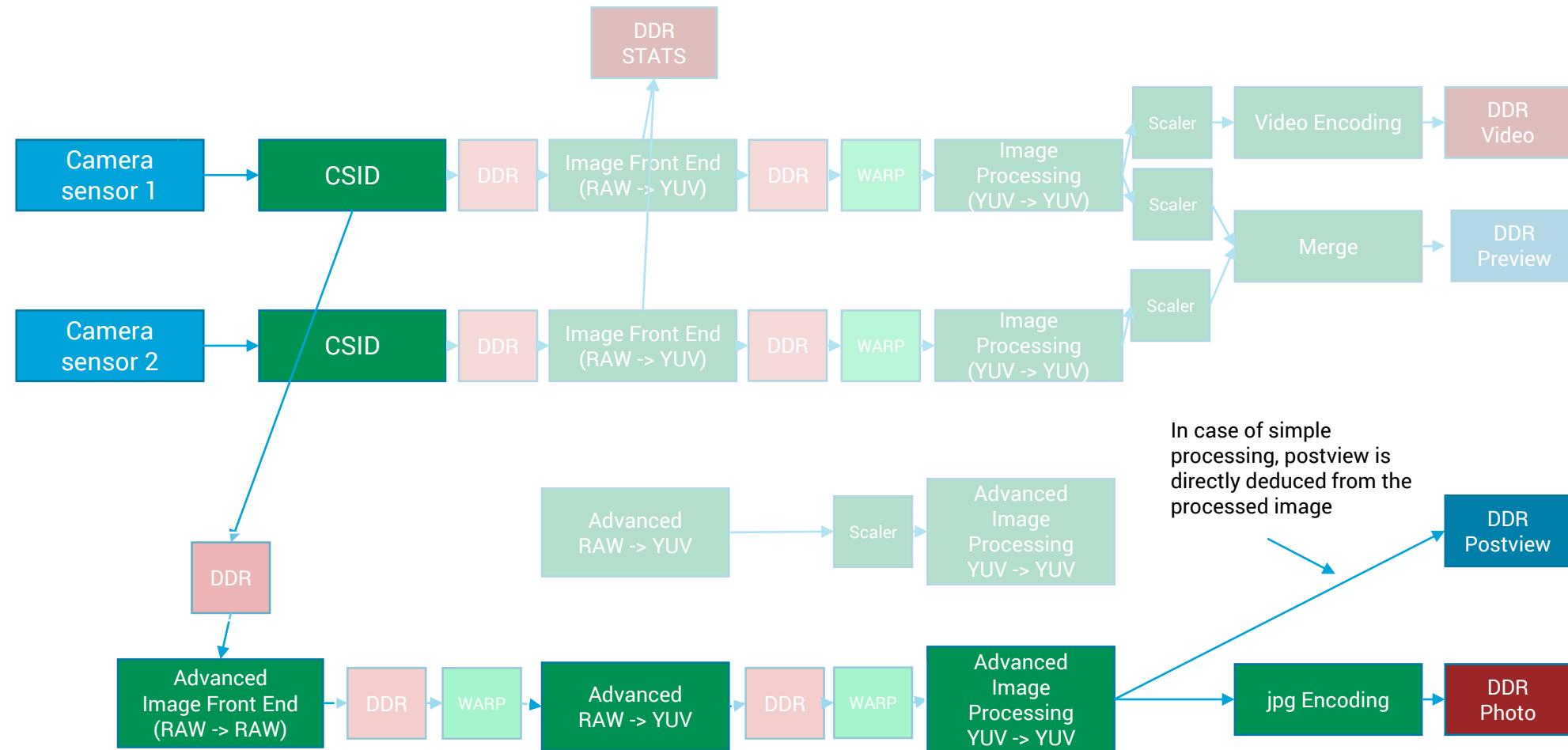


**“Forward looking EIS”** = a better video stabilization is obtained if we know the future motion of the camera.

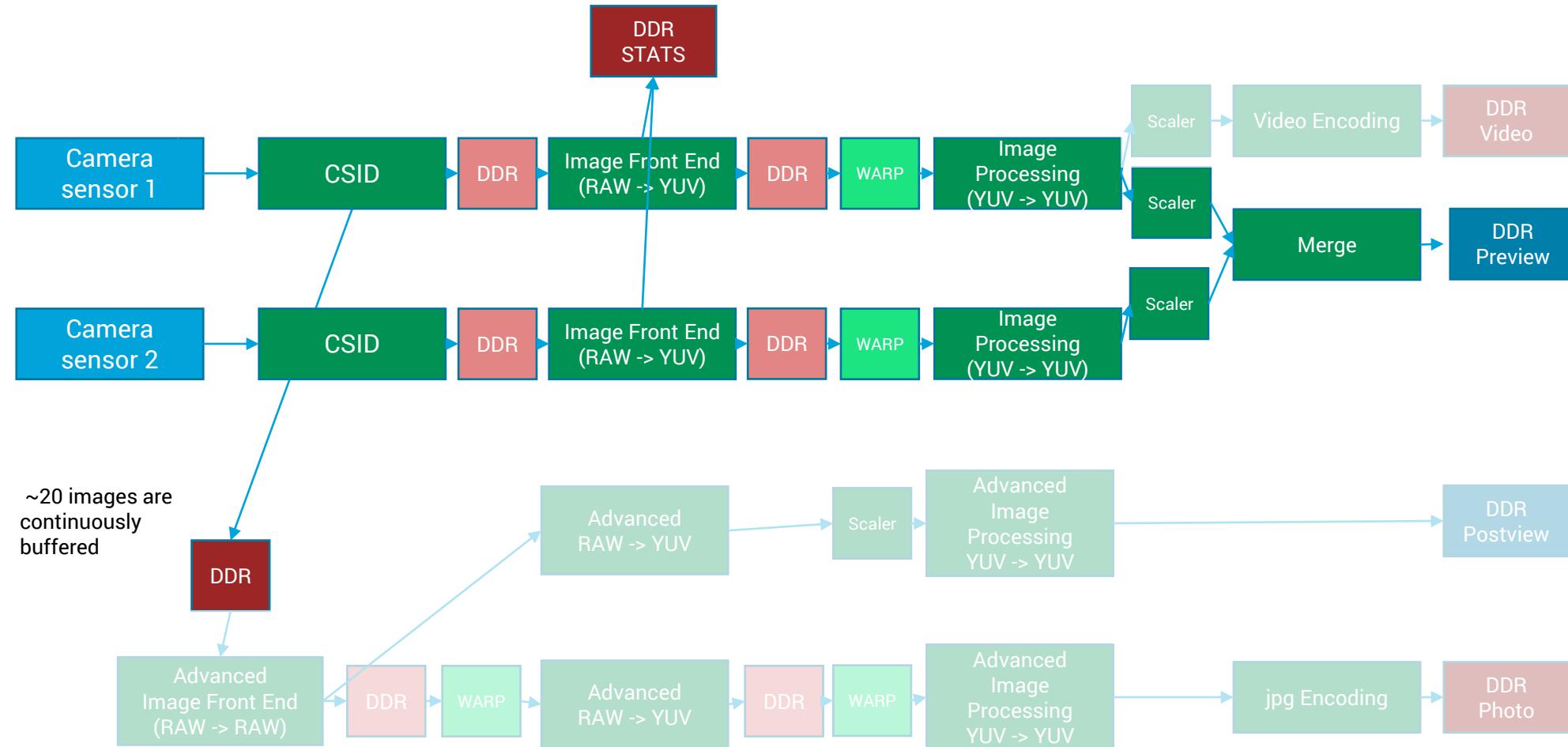
Idea = **buffer several frames** in DDR, delay accordingly the processing/encoding.

In order to keep a real time preview, open another processing pipe, quickly processing the just captured frame just for preview.

# ISP – Case 1: photo capture. Single image captured after trigger

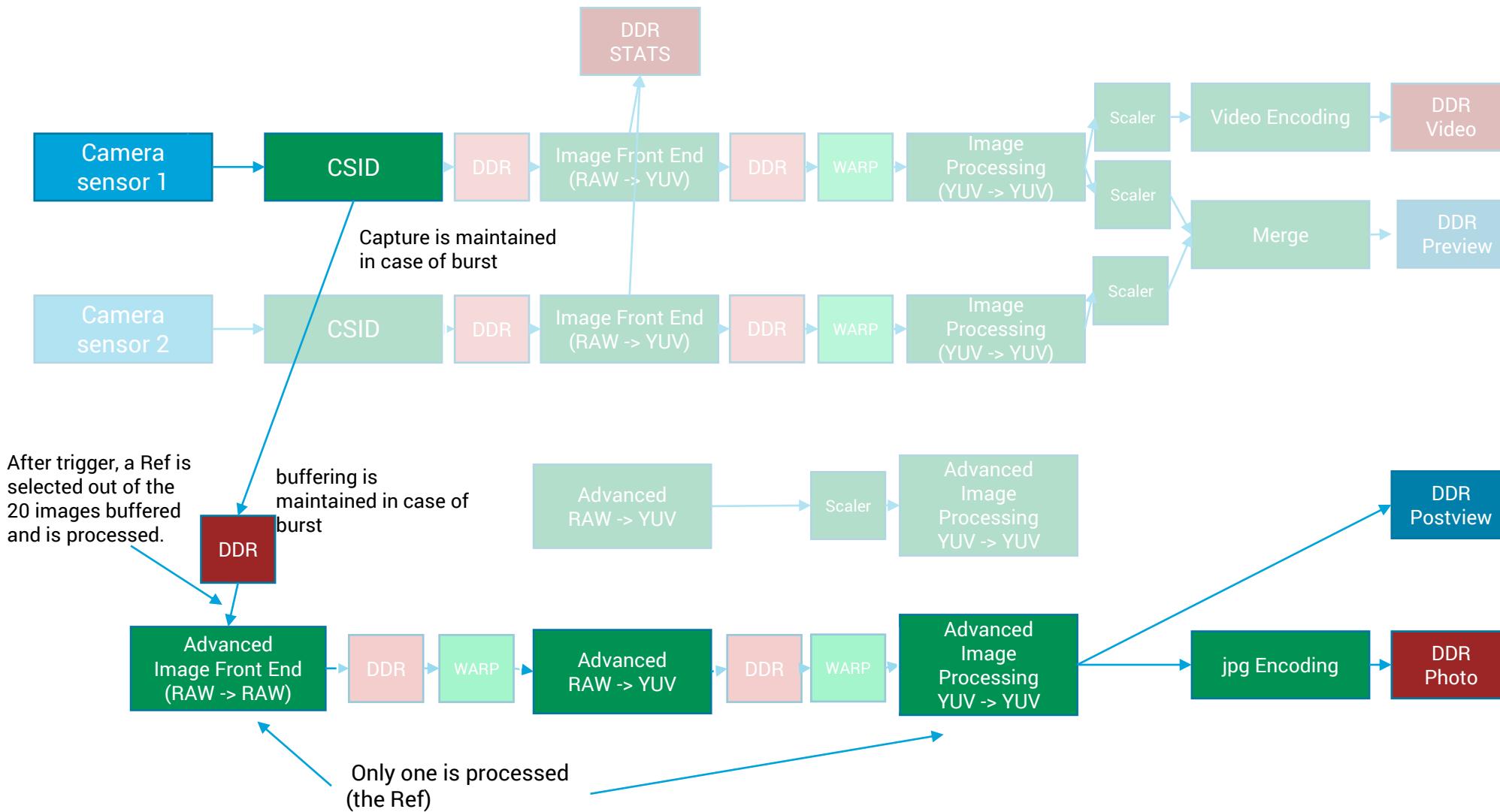


# ISP – Case 2 : Zero shutter lag. “before trigger”

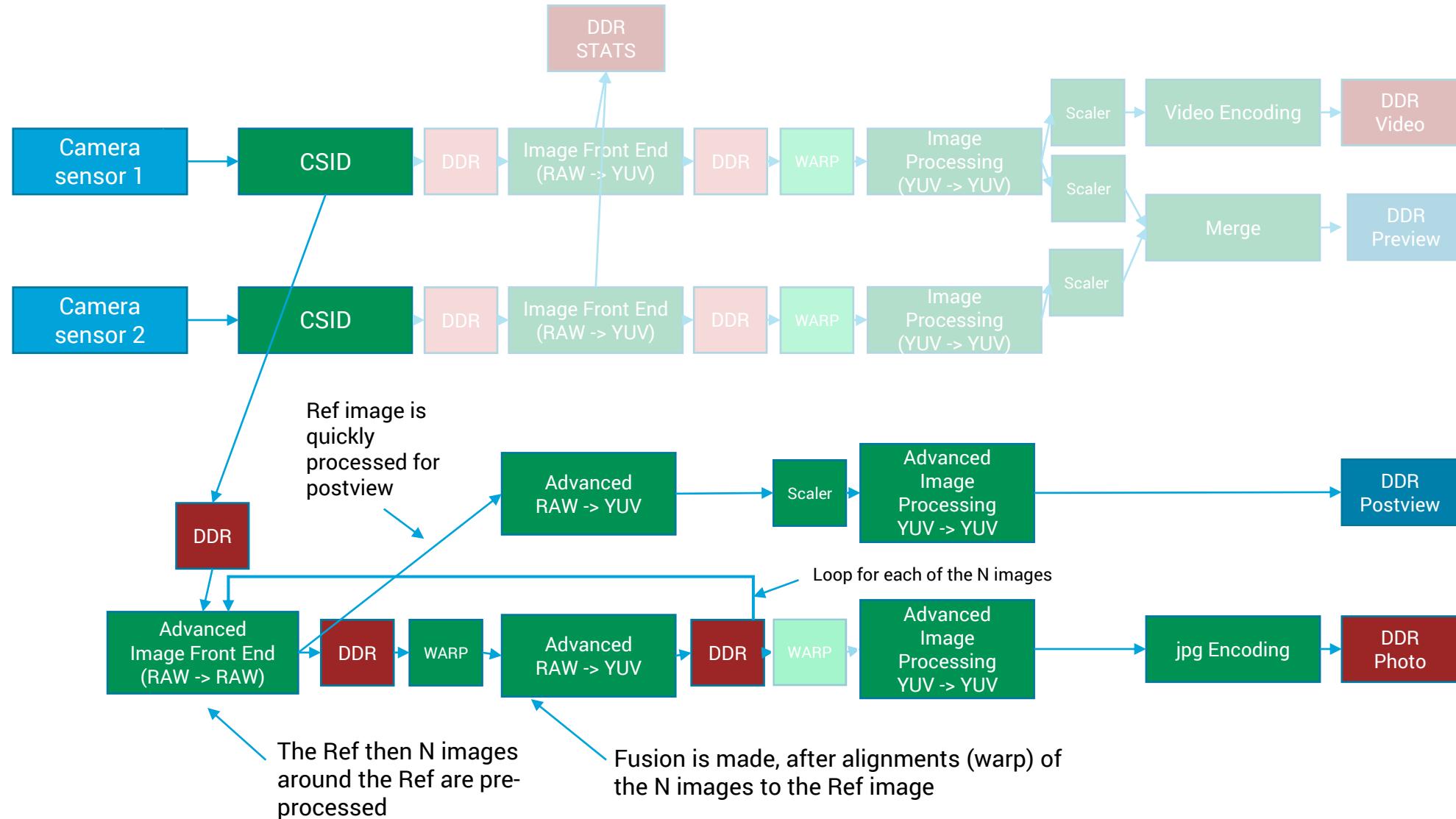


# ISP – case 2 : Zero shutter lag – “after trigger”

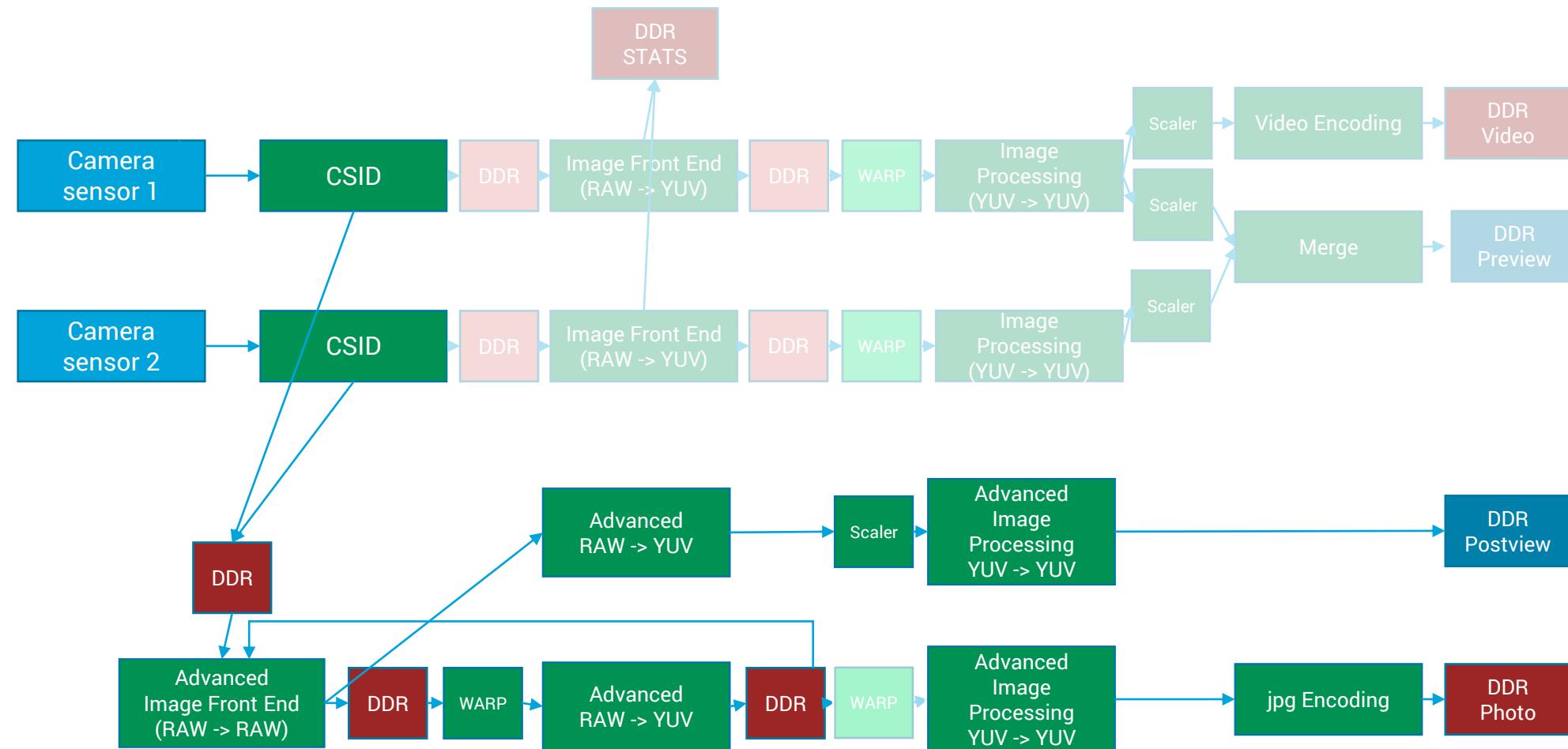
(single image, simple processing)



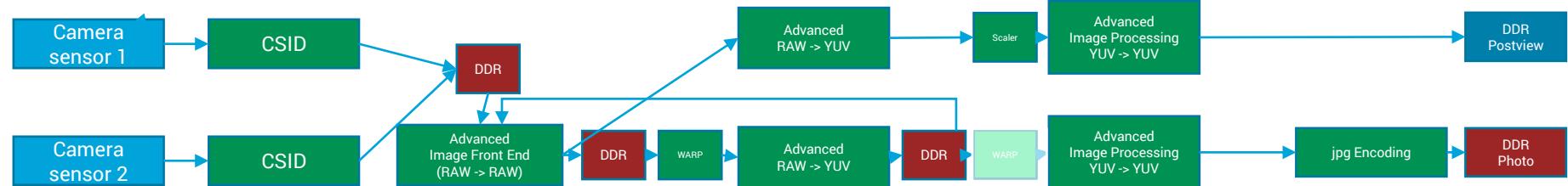
# ISP – case 3 : Zero shutter lag, multi images



# ISP – Case 4, ZSL, Multi images, multi cameras.



# ISP – HW or SW processing ?



HW : 30 T Ops/s, low power consumption, but... fixed processing.

SW : about 2.7T Ops/s.  
Not enough to handle 4K60 video.  
But... enough to handle photo processing.

SW in background processing, can take time

Real time appearance made thanks to HW generated Postview.

## Artificial Intelligence

Qualcomm® Adreno™ GPU

Qualcomm® Kryo™ CPU

Qualcomm® Hexagon™ Processor

- Fused AI Accelerator Architecture
- Hexagon Tensor Accelerator
- Hexagon Vector eXtensions
- Hexagon Scalar Accelerator
- Hexagon Direct Link
- Support for mix precision (INT8+INT16)
- Support for all precisions (INT4, INT8, INT16, FP16)
- Micro Tile Inferencing

Qualcomm® Sensing Hub

- Dual AI Processors for audio and sensors
- Always-Sensing camera

## 5G Modem-RF System

Snapdragon® X70 5G Modem-RF System

- 5G mmWave and sub-6 GHz, standalone (SA) and non-standalone (NSA) modes, standalone mmWave and mmWave-sub6 dual connectivity, FDD, TDD
- mmWave: 8 carriers, 2x2 MIMO
- Sub-6 GHz: 4x4 MIMO
- Qualcomm® 5G AI Suite
- Qualcomm® AI-Enhanced Signal Boost
- Qualcomm® 5G PowerSave Gen 3

## Camera

Qualcomm Spectra™ Image Signal Processor

- Cognitive ISP, Triple 18-bit ISPs
- Up to 36 MP triple camera @ 30 FPS with Zero Shutter Lag
- Up to 64+36 MP dual camera @ 30 FPS with Zero Shutter Lag
- Up to 108 MP single camera @ 30 FPS with Zero Shutter Lag
- Up to 200 Megapixel Photo Capture

AI-based face detection, auto-focus, and auto-exposure

Rec. 2020 color gamut photo and video capture

Up to 10-bit color depth photo and video capture

8K HDR Video Capture + 64 MP Photo Capture

10-bit HEIF: HEIC photo capture, HEVC video capture

Video Capture HDR Formats: HDR10+, HDR10, HLG, Dolby Vision

8K HDR Video Capture @ 30 FPS

4K Video Capture @ 120 FPS

Slow-mo video capture at 720p @ 960 FPS

8K Video Playback @ 60 FPS

Engine for Visual Analytics 3.0

## CPU

Kryo CPU

- 64-bit Architecture
- 1 Prime core, up to 3.2 GHz<sup>2</sup>
  - Arm Cortex-X3 technology
- 4 Performance cores, up to 2.8 GHz
- 3 Efficiency cores, up to 2.0 GHz

## Visual Subsystem

Adreno GPU

- Real-time Hardware Accelerated Ray Tracing
- Snapdragon Game Post Processing Accelerator
- HDR gaming (10-bit color depth, Rec. 2020 color gamut)
- Snapdragon Shadow Denoiser
- API Support: OpenGL® ES 3.2, OpenCL™ 2.0 FP, Vulkan® 1.3
- Hardware-accelerated H.265 and VP9 decoder
- HDR Playback Codec support for HDR10+, HDR10, HLG, and Dolby Vision

## Security

Platform Security Foundations, Trusted Execution

Environment & Services, Secure Processing Unit (SPU)

Trust Management Engine

Qualcomm® wireless edge services (WES) and

# Conclusion : Smartphone's Camera ingredients - Conclusion



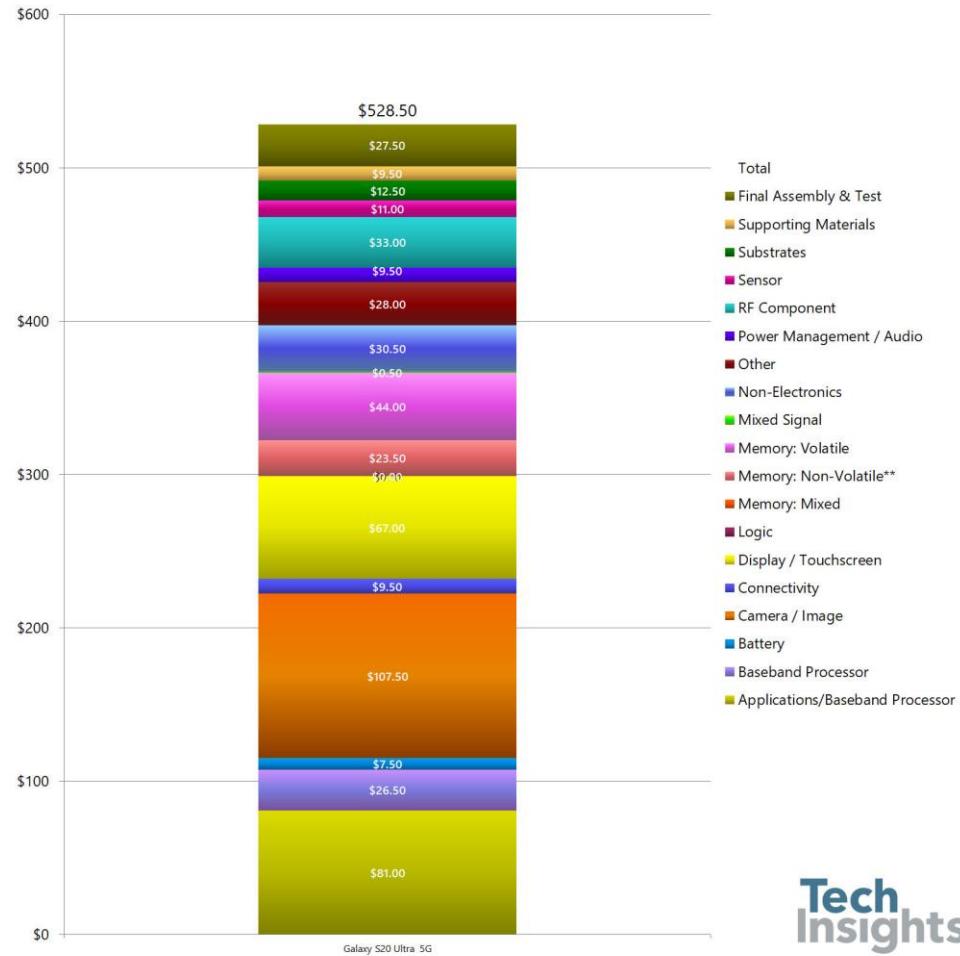
- **Camera module(s)  
(and other sensors)**
- **Chipset (ISP)**

# Conclusion : Smartphone camera = not so simple

Camera = a significant part of the BOM

- Chipset: 15%
- Screen: 12%
- Camera: 22%
- Memory : 13%
- Comm: 9%
- Substrates+ID : 12%
- Assembly and Tests: 5%
- Battery: 2%
- Audio: 1%
- Others stuff : 10-%

Also a significant part of the R&D costs...



Tech  
Insights

A large, semi-transparent watermark of the DXOMARK logo is positioned on the left side of the image. The logo consists of the word "DXOMARK" in a bold, sans-serif font. The letter "O" is stylized with a circular arrow graphic. The entire logo is surrounded by three concentric circles.

**DXOMARK**

THANK YOU !

