

# Advanced Modeling for Operations ASSIGNMENT - PART 1



DIPARTIMENTO DI INGEGNERIA GESTIONALE

#### Design of a factory logistics system with autonomous tugger trains

Warehousing and transportation of raw materials, components, and finished products within the factory

Storage and picking of raw materials and components

Transportation of raw materials and components to the production lines

Production of finished goods

Transportation of finished goods to the warehouse

Storage, picking and shipment of finished goods











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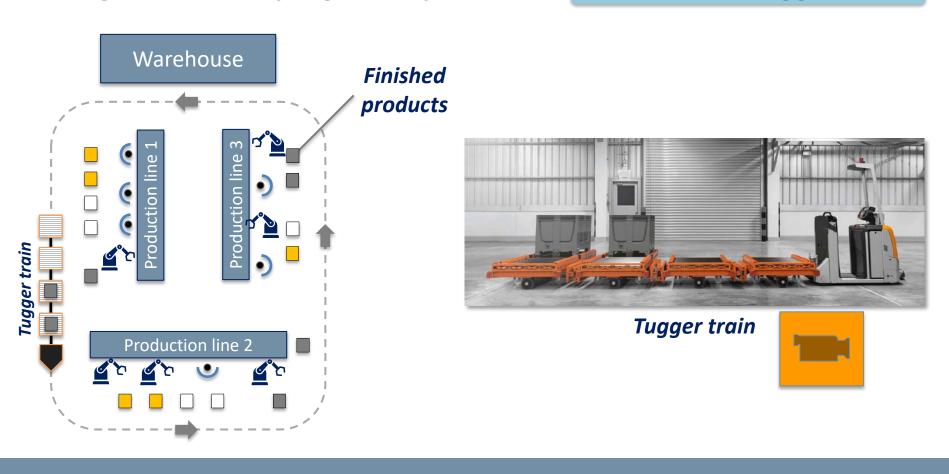
Production of finished goods

Transportation of finished goods to the warehouse

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Focus of the assignment

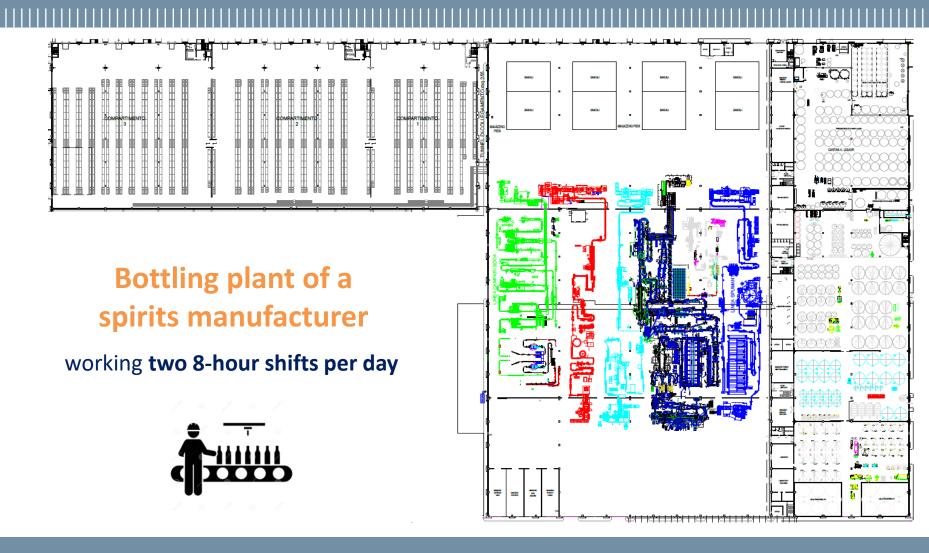
#### Design of a factory logistics system with autonomous tugger trains



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- Each tugger train consists of 1 tugger vehicle and 4 wagons
- ❖ The tugger vehicle is automated (no driver is needed)
- Tugger trains have a maximum loading capacity:
  - 4 unit loads
  - 2 tons (overall weight of the transported unit loads)
- ❖ Tugger vehicles are electric vehicles. Energy is stored in a battery, that needs to be periodically recharged at a charging station

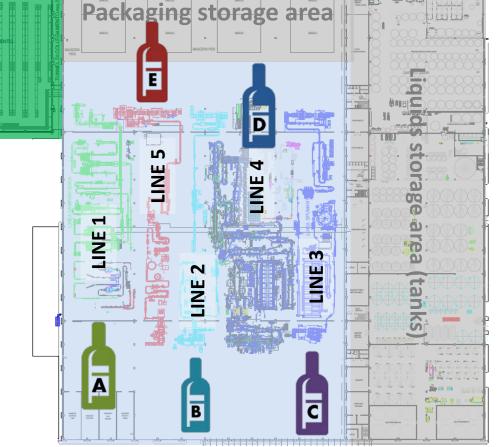


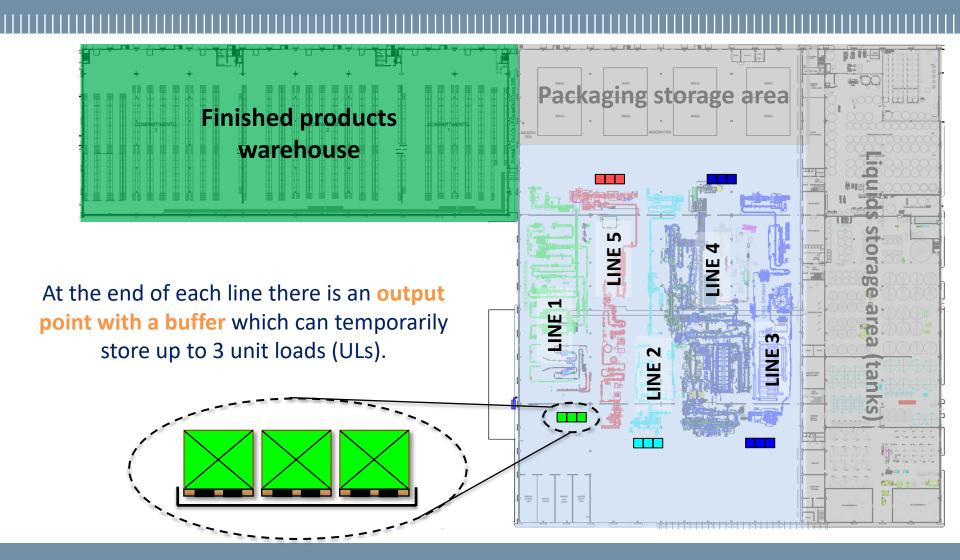


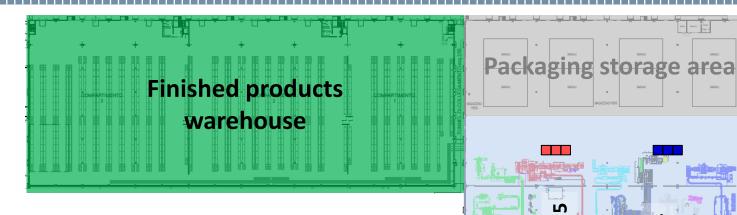
**5 production lines** (bottling lines)

making different products:

Line ID	Product ID
1	Α
2	В
3	С
4	D
5	E







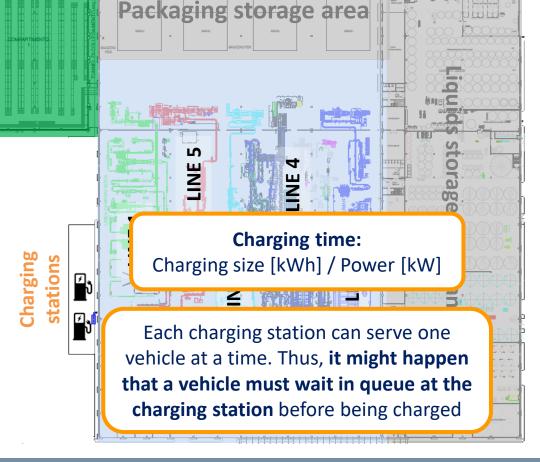
At the end of each line there is an **output** point with a buffer which can temporarily store up to 3 unit loads (ULs).

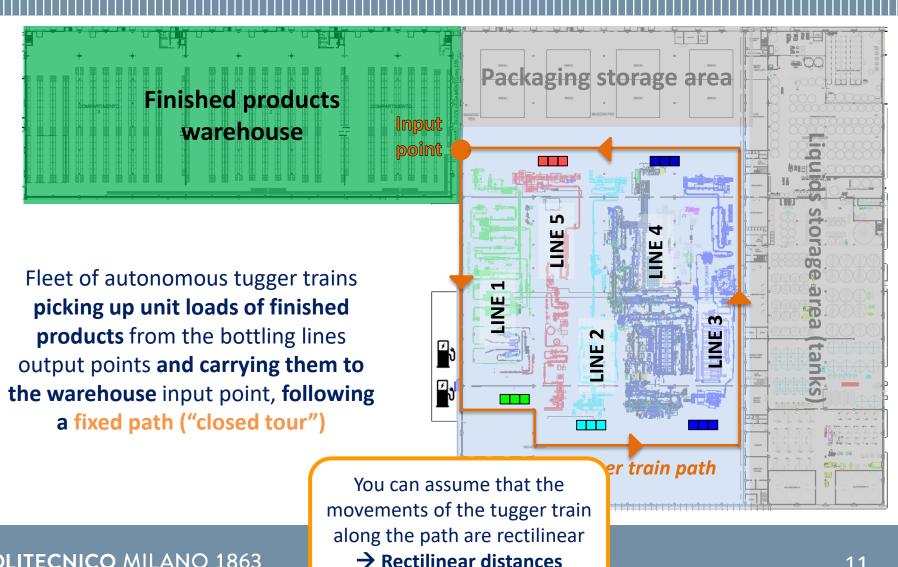
If the buffer is full, the line must stop. As soon as at least one UL is removed from the buffer, the line can resume its production activities.

The **idle time** of a line indicates the time during which the line is not producing (since the buffer is full)



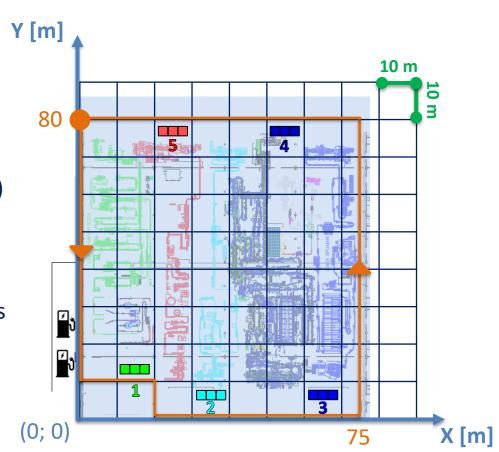
- 2 **charging stations** to recharge the vehicles' batteries:
  - Power supplied by a charging station: 4.9 kW
- ❖ Battery size of a vehicle: 4.8 kWh
- Energy usage during the travel and the loading/unloading operations





Each tugger train follows a fixed path ("closed tour"):

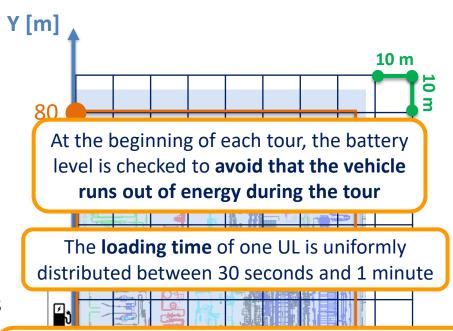
- 1. It starts at the warehouse input point
- 2. (It goes to a charging station, if needed)
- 3. It passes by all the lines output points, checking if there are ULs to be picked up. If so, and if the train still has some capacity left, it picks up one or more ULs
  - 4. It goes back to the warehouse input point, where it unloads the ULs



The coordinates of the lines output points, together with the cycle times, are reported in the file "lines\_info.csv"

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The **unloading time** of ULs at the warehouse input point has a fixed component (30 seconds to stop the vehicle in the right position) and a variable component (uniformly distributed between 30 s and 1 min per UL)

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