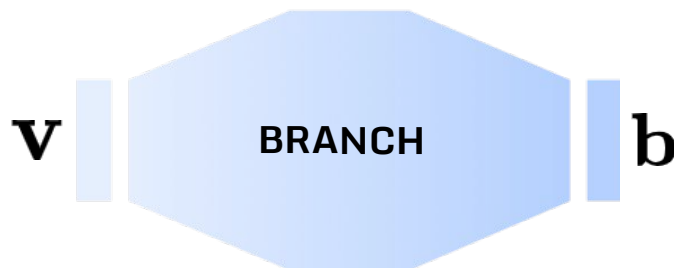
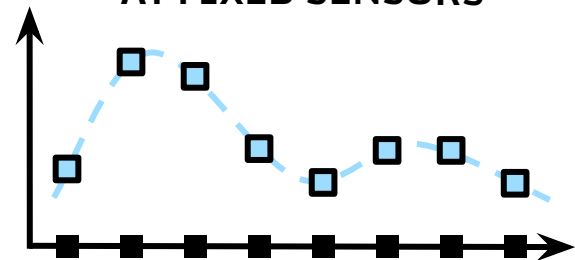
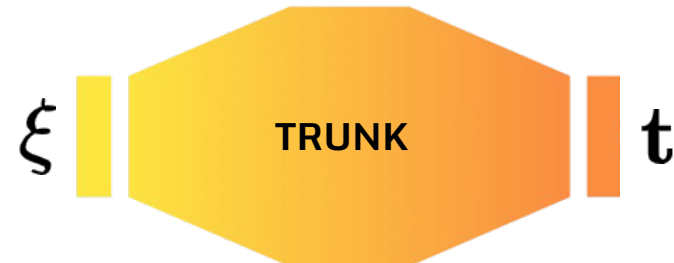
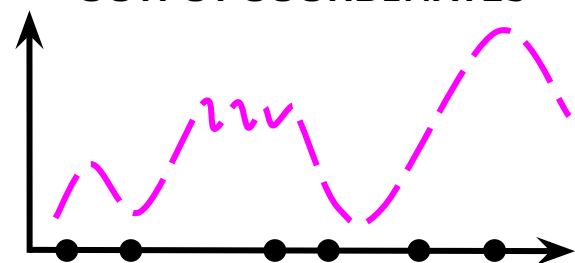


INPUT FUNCTION  
AT FIXED SENSORS



OUTPUT COORDINATES



$\mathbf{b}$



$\mathbf{t}$

$$G(\mathbf{v})(\xi) = \mathbf{b}(\mathbf{v}) \cdot \mathbf{t}(\xi)$$

