

Social Media Data Analysis 2023/2024 Nearest Neighbors

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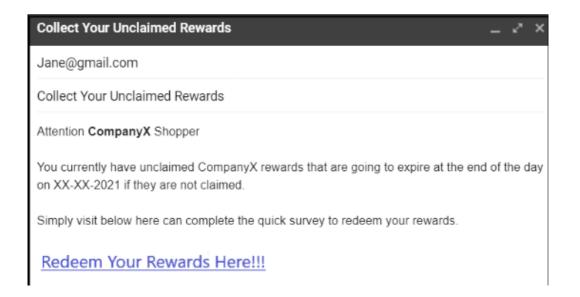
Everyone who enters before MIDNIGHT will have their name entered TWICE to win dinner with me. Please contribute NOW to get your name DOUBLE-ENTERED to win



VS.









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Dear John Smith:

As part of our ongoing effort to provide better services and support, we would like to request your feedback via a short online survey. It should only take about 15 minutes to complete.

The survey is active for a limited time only, so please respond as soon as possible. This survey is hosted by an external company (VendorName), so the link below does not lead to our website. Your responses will be subject to Amazon's Privacy Notice.

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In order to take the survey, please click here: http://www1.vendordomain.com/study/rjyl/index.html?var=2739974

Thank you very much for your time and effort!

Sincerely,

The Kindle Marketing Team

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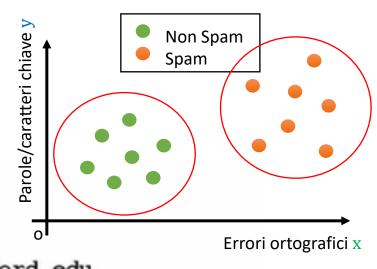
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$$y^{(j)} = f(\boldsymbol{x}^{(j)})$$



From: cheapsales@buystufffromme.com

To: ang@cs.stanford.edu

Subject: Buy now!

Deal of the week! Buy now! Rolex w4tchs - \$100 Medicine (any kind) - \$50 Also low cost M0rgages available.

To: ang@cs.stanford.edu

From: Alfred Ng

Subject: Christmas dates?

Hey Andrew, Was talking to Mom about plans for Xmas. When do you get off work. Meet Dec 22? Alf

Non-spom

$$y = 0$$

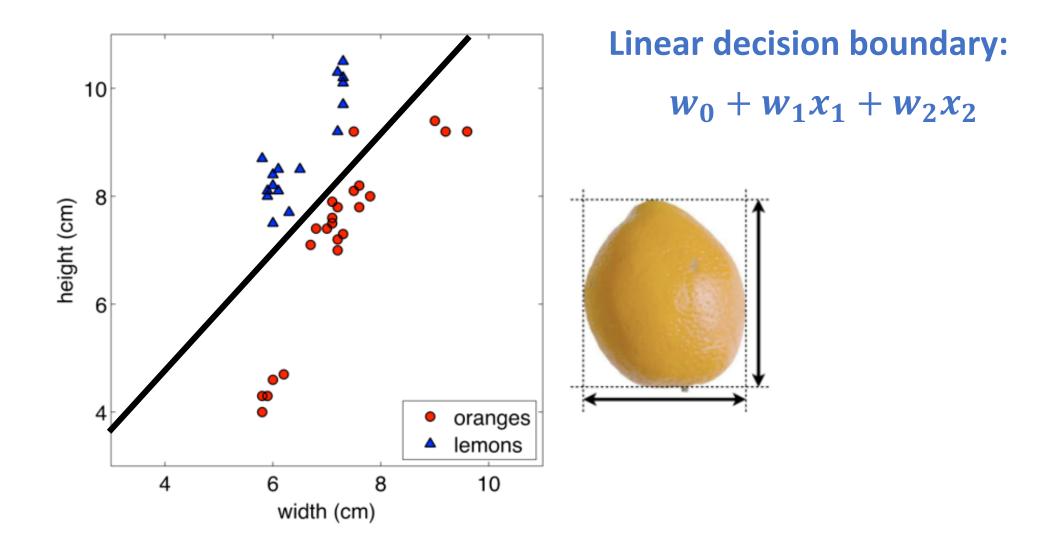
$$y = 1$$

Parametric and Non-parametric models

Parametric and Non-parametric models

- Distance
- Non-linear decision boundaries

Classification: Oranges and Lemons



Classification: non-parametric models

They work for classification or regression problems

Learning amounts to simply storing training data

Test instances classified using similar training instances

Data representation: notation

Examples:
$$(\mathbf{x}^{(j)}, \mathbf{y}^{(j)})_j$$

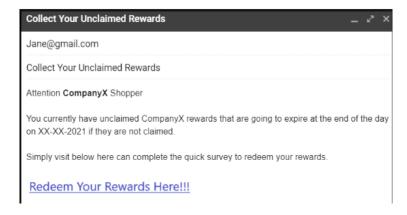
Data points: $x \in \mathbb{R}^n$

Features: $\mathbf{x} = (x_1, \dots, x_n)$

Labels: $y \in \{0, ..., m-1\}$

$$TR = \{(\mathbf{x}^{(j)}, \mathbf{y}^{(j)})\}_j; TE = \{(\mathbf{x}^{(j)}, \mathbf{y}^{(j)})\}_j; VA = \{(\mathbf{x}^{(j)}, \mathbf{y}^{(j)})\}_j$$

Data representation: notation



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Data points: $x \in \Re^{50000}$

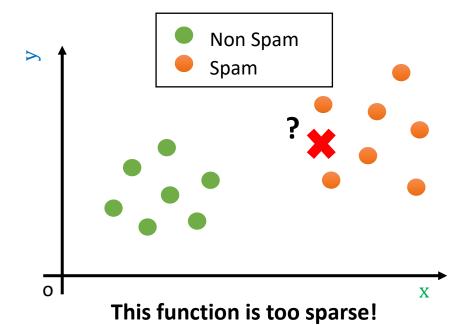
Features: $\mathbf{x} = (x_1, ..., x_{50000})$

Labels: $y \in \{0, 1\}$

Classification By Retrieval: Nearest Neighbor

Idea: The value of the target function for a new query is estimated from the known value(s) of the nearest training example(s)

$$f(x) = y s.t(x, y) \in TR$$

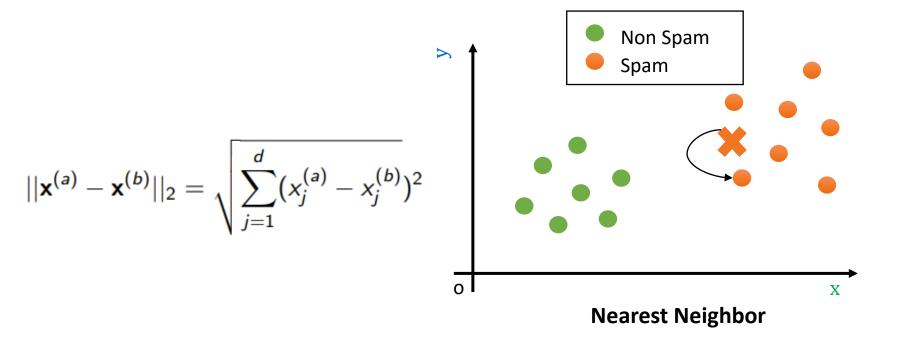




Classification By Retrieval: Nearest Neighbor

Idea: The value of the target function for a new query is estimated from the known value(s) of the nearest training example(s)

$$f(\overline{x}) = \arg_{y} \min\{d(\overline{x}, x) | (x, y) \in TR\}$$

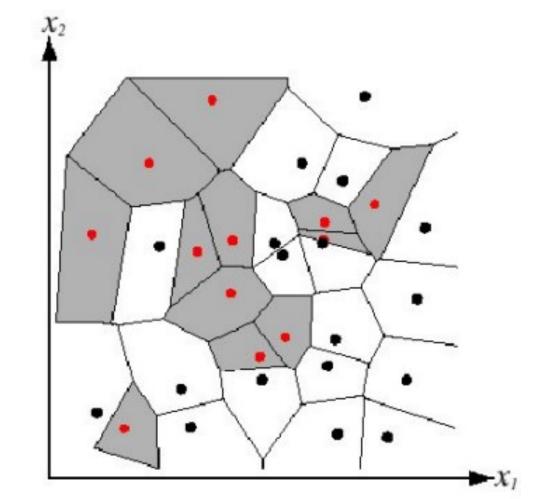


Nearest Neighbor: Decision Boundaries

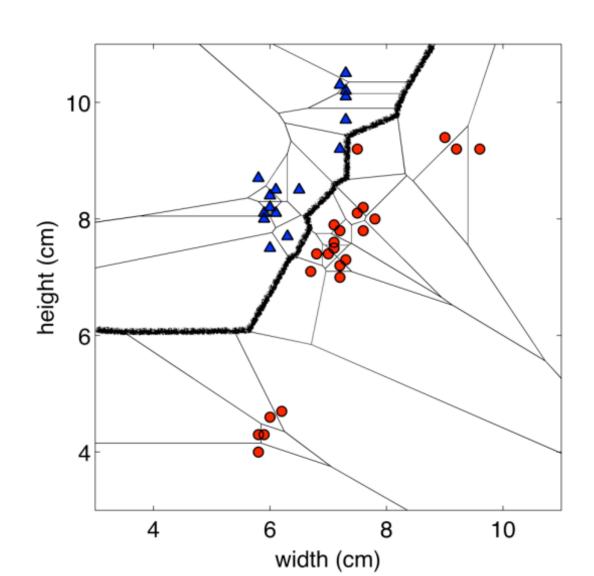
It does not explicitly compute decision boundaries, but these can be

inferred

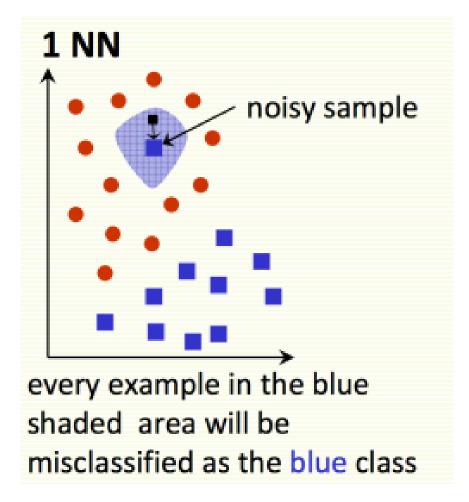
Voronoi Diagram visualization:



Nearest Neighbors: Decision Boundaries

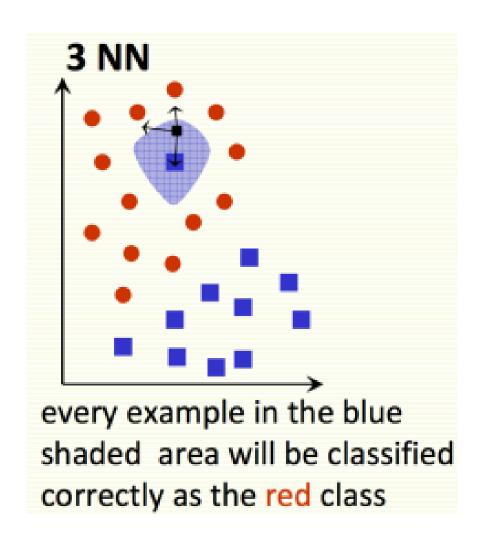


Nearest Neighbors

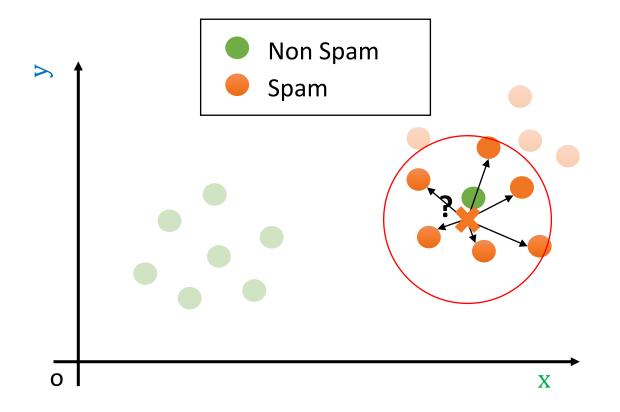


Nearest neighbors is sensitive to mis-labeled data ("class noise"). Solution?

K-Nearest Neighbors



K-Nearest Neighbors



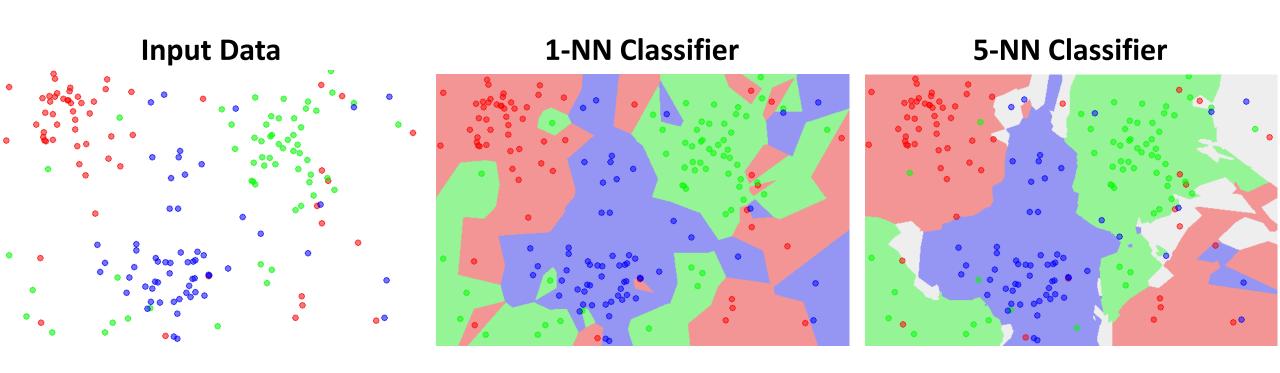
$$N(\overline{x}; TR, \epsilon) = \{(x, y) \in TR \mid d(\overline{x}, x) \leq \epsilon\}$$

$$\epsilon_K(\overline{x}; TR, K) = \max\{\epsilon \text{ s. t. } |\{d(\overline{x}, x) \leq \epsilon\}| \leq K, \forall \epsilon \in \Re\}$$

$$N(\overline{x}; TR, K) = \{(x, y) \in TR \mid d(\overline{x}, x) \leq \epsilon_K(\overline{x}; TR, K)\}$$

$$f(\overline{x}) = mode\{y | (x, y) \in N(\overline{x}; TR, K)\}$$

Classification Map/Decision Boundary



NN is Powerful!

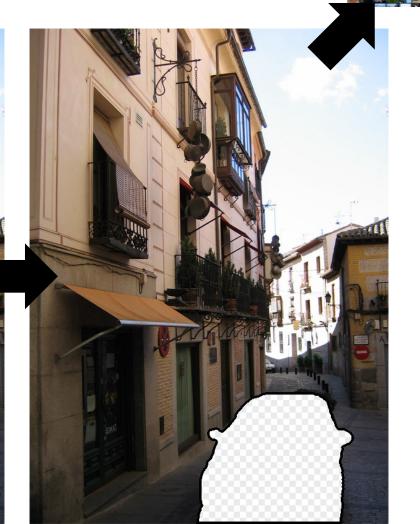


Image Collection



Classification: Evaluating Performance

Ground truth labels: $Y = \{y^{(i)}\}_i$

Predicted labels $\hat{Y} = \{\hat{y}^{(i)}\}_{i} = \{f(\mathbf{x}^{(i)})\}_{i}$

Performance measure: $P(Y, \hat{Y}) \rightarrow \Re$

Accuracy

$$Accuracy(Y, \hat{Y}) = \frac{\left|\{i \mid y^{(i)} = \hat{y}^{(i)}\}\right|}{|Y|}$$

not good for imbalanced datasets (example)

Confusion Matrix

Type 1: False Positives (FP)

Type 2: False Negatives (FN)

True Positives (TP)

True Negatives (TN)

CONFUSION MATRIX		PREDICTED LABELS	
		POSITIVE	NEGATIVE
TRUE LABELS	POSITIVE	TP	FN
	NEGATIVE	FP	TN

$$Accuracy = \frac{TP + TN}{TP + FN + FP + TN}$$

more informative with imbalanced datasets

Precision and Recall

CONFUSION MATRIX		PREDICTED LABELS	
		POSITIVE	NEGATIVE
TRUE LABELS	POSITIVE	TP	FN
	NEGATIVE	FP	TN

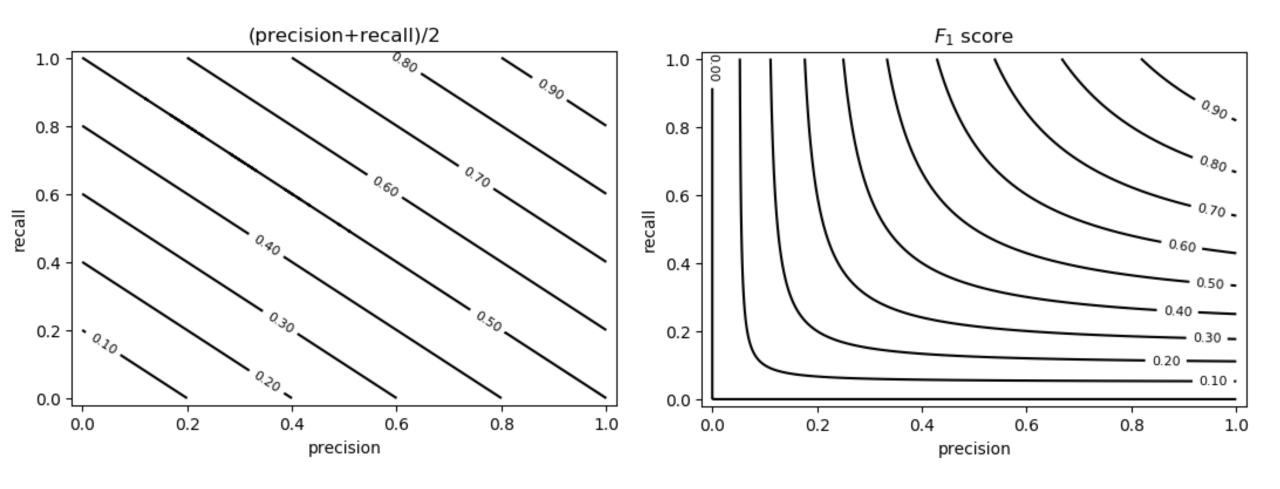
$$Precision = \frac{TP}{TP + FP}$$

$$Recall = \frac{TP}{TP + FN}$$

summarizes the confusion matrix

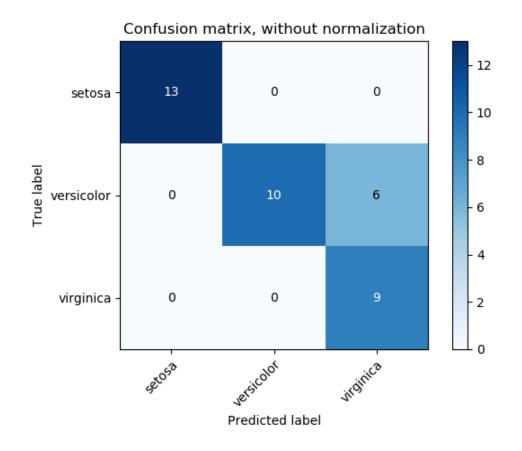
F_1 Score

$$F_1 = 2 \cdot \frac{precision \cdot recall}{precision + recall}$$



Confusion Matrix for Multi-Class Classification

 M_{ij} : number of elements of class i classified as belonging to class j



References/Optional Readings

- Nearest Neighbor: Section 2.5.2 of [1]
- Evaluation Measures for Classifcation: <u>https://en.wikipedia.org/wiki/Precision_and_recall</u>

[1] Bishop, Christopher M. *Pattern recognition and machine learning*. springer, 2006. https://www.microsoft.com/en-us/research/uploads/prod/2006/01/Bishop-Pattern-Recognition-and-Machine-Learning-2006.pdf