

# Week 1 - Dynamic Connectivity

March 4, 2017 1:24 PM

**Union** - connect two objects together

**Connected** - check if two objects are connected

## Applications

When programming, associate objects with integers 0 - N-1

- can insert into an array and access information easily (indexes)
- suppresses details

## Connections

- Reflective
  - p is connected to p
- Symmetric
  - if p is connected to q then q is connected to p
- Transitive
  - if p is connected to q and q is connected to r p is connected to r

## Connective components

- maximal set of objects that are mutually connected
  - {0}{123}{456789}
- can gain efficiency using this method

## Find Query

- check if two objects are in the same components

## Union Command

- Replace components containing two objects with their union

## Union-Find Data Type (API)

- Specification of methods
  - public class UF
    - UF(int N)
    - void union (int p, int q)
    - boolean connected (int p, int q)
    - int find(int p)
    - int count()

## Dynamic-connectivity client

- Check data type API design
- building a client that uses the data type
- read information from standard input and read 2 integers and connect them

# Week 1 - Quick Find

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Eager Algorithm

## Quick-find [eager approach]

Data structure.

- Integer array  $\text{id}[]$  of length  $N$ .
- Interpretation:  $p$  and  $q$  are connected iff they have the same id.

0	1	2	3	4	5	6	7	8	9	
$\text{id}[]$	0	1	1	8	8	0	0	1	8	8

Find. Check if  $p$  and  $q$  have the same id.

$\text{id}[6] = 0; \text{id}[1] = 1$

6 and 1 are not connected

Union. To merge components containing  $p$  and  $q$ , change all entries whose id equals  $\text{id}[p]$  to  $\text{id}[q]$ .

0	1	2	3	4	5	6	7	8	9	
$\text{id}[]$	1	1	1	8	8	1	1	1	8	8

↑                    ↑                    ↑

problem: many values can change

Data structure

- integer array indexed by objects
- interpretation:  $p$  and  $q$  are connected if and only if their entry in the array are the same

To find: check the array value of indexes  $p$  and  $q$  (if they are the same)

To Union: change the entries of  $p \rightarrow q$

- $\text{id}[p] \rightarrow \text{id}[q]$
- problem with large number of objects

Code:

## Quick-find: Java implementation

```
public class QuickFindUF
{
    private int[] id;

    public QuickFindUF(int N)
    {
        id = new int[N];
        for (int i = 0; i < N; i++)
            id[i] = i;
    }

    public boolean connected(int p, int q)
    { return id[p] == id[q]; }

    public void union(int p, int q)
    {
        int pid = id[p];
        int qid = id[q];
        for (int i = 0; i < id.length; i++) ←
            if (id[i] == pid) id[i] = qid;
    }
}
```

Every cell in the array --> different

Implementation of Union trick

- make variables for  $\text{id}[p]$  and  $\text{id}[q]$  before implementing.

Effectiveness:

number of times the code has to access the array

Algorithm	Initialize	Union	Find
Quick Find	N	N	1

Union command too expensive in memory and time.

- not scalable
- quadratic algorithm = bad

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# Week 1 - Quick Union

March 4, 2017 6:08 PM

(Lazy Approach) - avoid doing work until we have to

Same data structure as quick find

Different representation

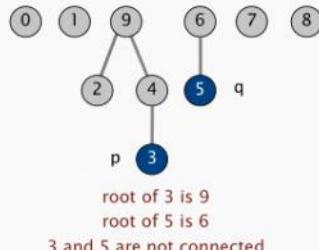
- set of trees called forest
- each entry in the array will contain reference to parent in the tree.

## Quick-union [lazy approach]

### Data structure.

- Integer array  $\text{id}[]$  of length  $N$ .
- Interpretation:  $\text{id}[i]$  is parent of  $i$ .
- Root of  $i$  is  $\text{id}[\text{id}[\dots\text{id}[i]\dots]]$ .

0	1	2	3	4	5	6	7	8	9	
$\text{id}[]$	0	1	9	4	9	6	6	7	8	9

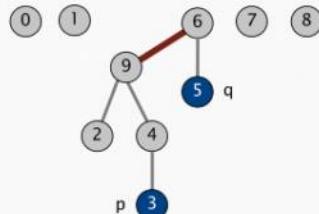


Find. Check if  $p$  and  $q$  have the same root.

Union. To merge components containing  $p$  and  $q$ , set the  $\text{id}$  of  $p$ 's root to the  $\text{id}$  of  $q$ 's root.

0	1	2	3	4	5	6	7	8	9	
$\text{id}[]$	0	1	9	4	9	6	6	7	8	6

↑  
only one value changes



Find: check if  $p$  and  $q$  have the same root

Union: to merge set  $\text{id}$  of  $p$ 's root's to  $\text{id}$  of  $q$

- $\text{id}[\text{p}'s \text{root}] = q$

Code Implementation

## Quick-union: Java implementation

```
public class QuickUnionUF
{
    private int[] id;

    public QuickUnionUF(int N)
    {
        id = new int[N];
        for (int i = 0; i < N; i++) id[i] = i; ← set id of each object to itself
                                                (N array accesses)
    }

    private int root(int i)
    {
        while (i != id[i]) i = id[i]; ← chase parent pointers until reach root
                                                (depth of i array accesses)
        return i;
    }

    public boolean connected(int p, int q)
    {
        return root(p) == root(q); ← check if p and q have same root
                                                (depth of p and q array accesses)
    }

    public void union(int p, int q)
    {
        int i = root(p);
        int j = root(q);
        id[i] = j; ← change root of p to point to root of q
                                                (depth of p and q array accesses)
    }
}
```

follow id[i] until id[i] = I

- private method

### Effectiveness

Algorithm	Initialize	Union	Find
Quick Find	N	N	1
Quick Union	N	N ?	N

- Quick Union - worst case scenario.

### Defect

- trees can get too tall
  - find operation too expensive

# Week 1 - Quick Union Improvements

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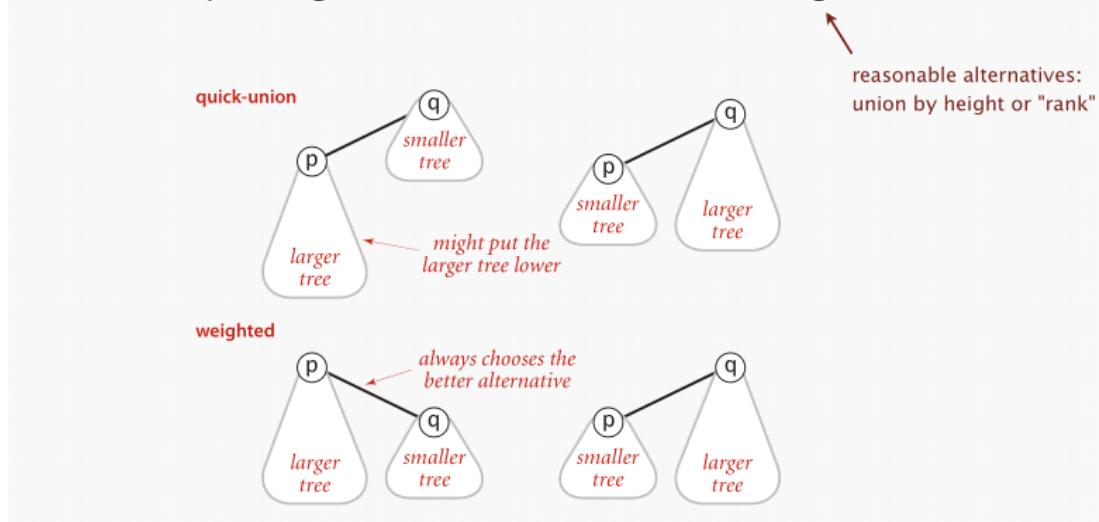
## Weighting

- take steps to avoid having tall trees
- avoid putting the large tree lower
  - keep track of the number of objects in each tree
  - connect the root of the smaller tree to the root of the larger tree
- make the trees flat instead of long
- SMALLER TREE GOES BELOW

## Improvement 1: weighting

### Weighted quick-union.

- Modify quick-union to avoid tall trees.
- Keep track of size of each tree (**number of objects**).
- Balance by linking root of smaller tree to root of larger tree.



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## Java implementation

- same data structure as quick union
- need an extra array to give the number of items rooted at I
- FIND = identical
- UNION = check sizes and then link root of smaller to the larger
  - change the size array

## Weighted quick-union: Java implementation

**Data structure.** Same as quick-union, but maintain extra array  $sz[i]$  to count number of objects in the tree rooted at  $i$ .

**Find.** Identical to quick-union.

```
return root(p) == root(q);
```

**Union.** Modify quick-union to:

- Link root of smaller tree to root of larger tree.
- Update the  $sz[]$  array.

```
int i = root(p);
int j = root(q);
if (i == j) return;
if (sz[i] < sz[j]) { id[i] = j; sz[j] += sz[i]; }
else { id[j] = i; sz[i] += sz[j]; }
```

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### Running time

- find - proportional to depth of the tree
  - depth is  $\lg N - \lg = \log \text{base } 2$

Algorithm	Initialize	Union	Connected
quick-find	N	N	1
quick-union	N	N	N
weighted	N	$\lg N$	$\lg N$

Can improve method - path compression

### Path Compression

- after computing the root of any sub tree, set the id of the sub tree have that root
- one extra line of code
  - second loop to root() to set the id of the selected node to the original root

No such algorithm that can be linear - only algorithms that are linear in practice

# Week 1 - Union-Find Applications

May 15, 2017 3:19 PM

## Percolation

- model for many physical systems
  - nxn grid
  - each square is a site
  - each site has a probability p
  - a system is percolated if the top and the bottom are connected by open sites
    - electricity
      - open conductor closed insulator
    - water flow
    - social network
  - open with a given probability (p)
    - if site vacancy is low then does not percolate
    - if site vacancy is high then it does percolate
    - in the middle - phase transition
      - threshold between percolate and not percolate is sharp
        - ◆ there is a value to determine if a system will or will not percolate  $p^*$
        - ◆ run simulations to determine  $p^*$
  - Monte Carlo simulation
    - the nxn square is all blocked
    - randomly open squares until the system percolates
      - calculate vacancy percentage
      - run many times and find average
  - Dynamic connectivity example with percolation
    - create a virtual top and bottom site
    - to check we check if the virtual top and bottom are connected
  - To open a site connect to all open adjacent squares
    - calls to union

## Steps to developing a usable algorithm

1. Model the problem
2. Find an algorithm to solve
3. Fast and fits in memory?
  - a. if not figure out why
4. Find a way to address the problem
5. Iterate until satisfied

# Week 1 - Programming Assignment Takeaways

June 2, 2017 10:01 PM

Do not redeclare instance variables in the constructor - will overwrite the instance variables.

Backwash - two bottom or top sites are both connected to the bottom virtual site but not to each other.

- connecting them to the virtual site connects them to each other inadvertently

Fix

- make another weighted quick union without the virtual sites - eliminates backwash - only use for isFull()

# Week 1- Analysis of Algorithms- Observations

June 3, 2017 6:52 PM

## 3 Sum problem

- n distinct integers how many triples sum to exactly 0
- runs a loop that checks each triple

How long will this program take to run?

- Empirical analysis
  - Stopwatch class
  - run program and measure running time
- Data analysis
  - Plot running time versus input size
    - can also plot as a log-log plot
      - may yield straight line - get the power
  - Regression will yield run time - get hypothesis
- Effects on runtime
  - what algorithm is being used
  - Input data
- System dependent effects
  - hardware
  - software
  - system

# Week 1- Analysis of Algorithms- Mathematical Models

June 4, 2017 1:12 PM

Total running time = sum of cost x frequency for all operations

- cost depends on machine
- frequency depends on algorithm

In principle accurate mathematical models are plausible

Cost Table - from slides

operation	example	nanoseconds †
integer add	a + b	2.1
integer multiply	a * b	2.4
integer divide	a / b	5.4
floating-point add	a + b	4.6
floating-point multiply	a * b	4.2
floating-point divide	a / b	13.5
sine	Math.sin(theta)	91.3
arctangent	Math.atan2(y, x)	129.0
...	...	...

† Running OS X on Macbook Pro 2.2GHz with 2GB RAM

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operation	example	nanoseconds $\dagger$
variable declaration	<code>int a</code>	$c_1$
assignment statement	<code>a = b</code>	$c_2$
integer compare	<code>a &lt; b</code>	$c_3$
array element access	<code>a[i]</code>	$c_4$
array length	<code>a.length</code>	$c_5$
1D array allocation	<code>new int[N]</code>	$c_6 N$
2D array allocation	<code>new int[N][N]</code>	$c_7 N^2$
string length	<code>s.length()</code>	$c_8$
substring extraction	<code>s.substring(N/2, N)</code>	$c_9$
string concatenation	<code>s + t</code>	$c_{10} N$

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- made from experiments
- some constant
- some operations are proportional to  $N$

Example : 0 sum problem

## Q. How many instructions as a function of input size $N$ ?

```
int count = 0;
for (int i = 0; i < N; i++)
    if (a[i] == 0)
        count++;
```

operation	frequency
variable declaration	2
assignment statement	2
less than compare	$N + 1$
equal to compare	$N$
array access	$N$
increment	$N$ to $2N$

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- may be tedious to get exact counts as algorithms get more complicated

### Simplification 1

- count the ones which are most expensive
  - most expensive or most frequent

### Simplification 2

- ignore low order terms
- only the highest order in a polynomial counts
- as  $N \rightarrow \infty$  low order terms are negligible

### Estimating a discrete sum

- replace sum with integral

**Ex 1.**  $1 + 2 + \dots + N$ .

$$\sum_{i=1}^N i \sim \int_{x=1}^N x dx \sim \frac{1}{2} N^2$$

**Ex 2.**  $1^k + 2^k + \dots + N^k$ .

$$\sum_{i=1}^N i^k \sim \int_{x=1}^N x^k dx \sim \frac{1}{k+1} N^{k+1}$$

**Ex 3.**  $1 + 1/2 + 1/3 + \dots + 1/N$ .

$$\sum_{i=1}^N \frac{1}{i} \sim \int_{x=1}^N \frac{1}{x} dx = \ln N$$

**Ex 4.** 3-sum triple loop.

$$\sum_{i=1}^N \sum_{j=i}^N \sum_{k=j}^N 1 \sim \int_{x=1}^N \int_{y=x}^N \int_{z=y}^N dz dy dx \sim \frac{1}{6} N^3$$

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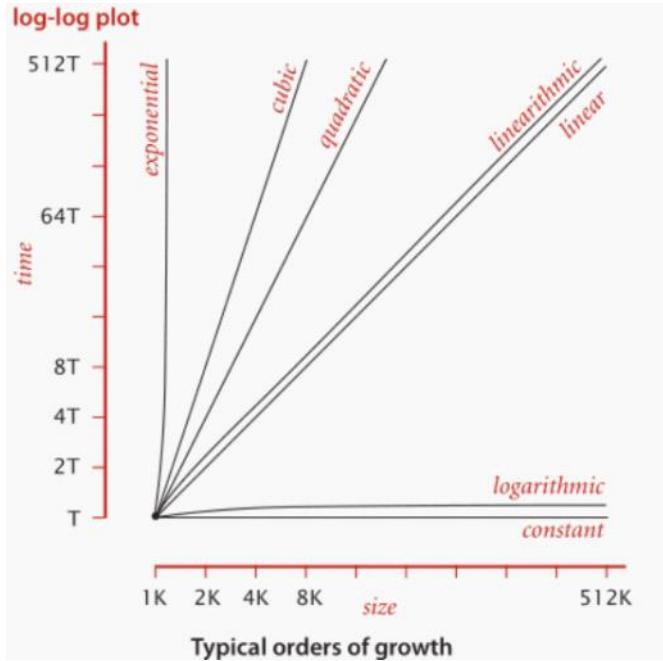
In theory precise mathematical models are possible but practically, approximations are better

# Week- Analysis of Algorithms- Order of Growth Classifications

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Not many different functions in algorithms

- only few functions turn up
- $\log N$ ,  $N$ ,  $N \log N$ ,  $N^2$ ,  $N^3$ ,  $N^3$ ,  $2^N$



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- no leading constant

Make sure no algorithms are quadratic or higher

order of growth	name	typical code framework	description	example	$T(2N) / T(N)$
1	constant	$a = b + c;$	statement	add two numbers	1
$\log N$	logarithmic	<pre>while (N &gt; 1) {   N = N / 2; ... }</pre>	divide in half	binary search	$\sim 1$
$N$	linear	<pre>for (int i = 0; i &lt; N; i++) { ... }</pre>	loop	find the maximum	2
$N \log N$	linearithmic	[see mergesort lecture]	divide and conquer	mergesort	$\sim 2$
$N^2$	quadratic	<pre>for (int i = 0; i &lt; N; i++) for (int j = 0; j &lt; N; j++) { ... }</pre>	double loop	check all pairs	4
$N^3$	cubic	<pre>for (int i = 0; i &lt; N; i++) for (int j = 0; j &lt; N; j++) for (int k = 0; k &lt; N; k++) { ... }</pre>	triple loop	check all triples	8
$2^N$	exponential	[see combinatorial search lecture]	exhaustive search	check all subsets	$T(N)$

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## Binary Search

- sorted array
- given a key - find the key in the array
- compare key against middle entry
  - too small go left
  - too big go right

```
public static int binarySearch(int[] a, int key)
{
    int lo = 0, hi = a.length-1;
    while (lo <= hi)
    {
        int mid = lo + (hi - lo) / 2;
        if      (key < a[mid]) hi = mid - 1;
        else if (key > a[mid]) lo = mid + 1;
        else return mid;
    }
    return -1;
}
```

one "3-way compare"

**Invariant.** If key appears in the array a[], then  $a[lo] \leq key \leq a[hi]$ .

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Since binary search is recursive, the relation is also recurrent

- telescoping

**Proposition.** Binary search uses at most  $1 + \lg N$  key compares to search in a sorted array of size  $N$ .

**Def.**  $T(N) = \# \text{key compares to binary search a sorted subarray of size } \leq N$ .

**Binary search recurrence.**  $T(N) \leq T(N/2) + 1$  for  $N > 1$ , with  $T(1) = 1$ .

↑  
left or right half      ↑  
possible to implement with one  
2-way compare (instead of 3-way)

Pf sketch.

$$\begin{aligned} T(N) &\leq T(N/2) + 1 && \text{given} \\ &\leq T(N/4) + 1 + 1 && \text{apply recurrence to first term} \\ &\leq T(N/8) + 1 + 1 + 1 && \text{apply recurrence to first term} \\ &\dots \\ &\leq T(N/N) + 1 + 1 + \dots + 1 && \text{stop applying, } T(1) = 1 \\ &= 1 + \lg N \end{aligned}$$

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- only holds if  $N$  is a power of 2.
  - can still prove its logarithmic

Better 3 sum algorithm

- sort array
- each pair of numbers - binary search  $-(a[i] + a[j])$
- Makes it  $N^2 \log N$

yields faster programs

- want faster order of growth

# Week 1- Analysis of Algorithms- Theory of Algorithms

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## Type of Analyses

Best Case	Worst Case	Average
easiest input	most difficult input	random input
goal for all inputs	guarantee for all inputs	way to predict performance

Can either:

- design for the worst case
  - ideal
- randomize
  - depend on probability

## Theory of Algorithms

- have a problem
- want to know the difficulty of algorithm

## Approach

- suppress details
  - get to a common factor (one term)
  - focus on worst case design

## Optimal Algorithm

- can guarantee certain performance for any input
- no algorithm can provide a better performance

notation	provides	example	shorthand for	used to
Big Theta	asymptotic order of growth	$\Theta(N^2)$	$\frac{1}{2} N^2$ 10 $N^2$ $5 N^2 + 22 N \log N + 3N$ ⋮	classify algorithms
Big Oh	$\Theta(N^2)$ and smaller	$O(N^2)$	10 $N^2$ 100 $N$ $22 N \log N + 3 N$ ⋮	develop upper bounds
Big Omega	$\Theta(N^2)$ and larger	$\Omega(N^2)$	$\frac{1}{2} N^2$ $N^5$ $N^3 + 22 N \log N + 3 N$ ⋮	develop lower bounds

- Tilde - provide approximate model
  - will focus on tilde in this course

### Example 1- One Sum

#### Goals

- establish difficulty
- develop the optimal algorithm

#### Upper bound ( $O(N)$ )

- brute force
- provides upper bound for run time
- every array entry

#### Lower bound ( $\Omega(N)$ )

- every array entry
  - need to check every square

Therefore, the optimal algorithm has to be the same of upper bound or lower bound

Brute force algorithm for one sum is optimal.

### Example 2 - Three sum

- no one knows the optimal algorithm for 3 sum
- upper bound is known but not lower bound

#### Design Approach

- develop algorithm
- prove lower bound
  - difficult for complex algorithms
- lower upper bound (new algorithm)
- raise lower bound (difficult for complex problems)
  - difficult to prove

# Week 1- Analysis of Algorithms- Memory

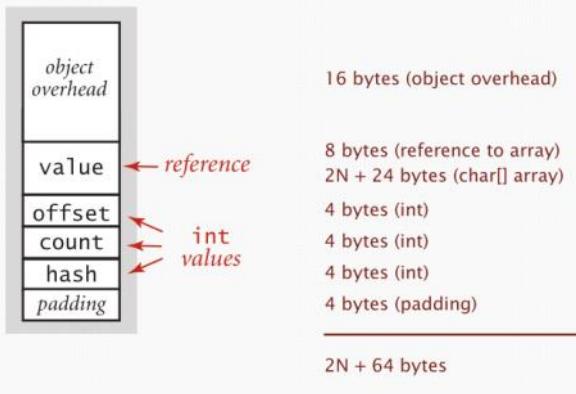
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Current machines are 64 bit with 8 byte pointers

Memory usage of primitive types

Type	Bytes
boolean	1
byte	1
char	2
int	4
float	4
long	8
double	8
char[]	$2N+24$
int[]	$4N+24$
double[]	$8N + 24$
char[]	$\sim 2MN$
int[][]	$\sim 4MN$
double[][]	$\sim 8MN$
Object overhead	16
Reference	8
Padding	8
String	$\sim 2N$

```
public class String
{
    private char[] value;
    private int offset;
    private int count;
    private int hash;
    ...
}
```



Q. How much memory does WeightedQuickUnionUF use as a function of  $N$ ?

Use tilde notation to simplify your answer.

```
public class WeightedQuickUnionUF
{
    private int[] id;
    private int[] sz;
    private int count;

    public WeightedQuickUnionUF(int N)
    {
        id = new int[N];
        sz = new int[N];
        for (int i = 0; i < N; i++) id[i] = i;
        for (int i = 0; i < N; i++) sz[i] = 1;
    }
    ...
}
```

The diagram shows the memory layout for the `WeightedQuickUnionUF` class. It highlights the fields `id` and `sz`. Annotations explain the memory usage:

- For `id`: 16 bytes (object overhead).
- For `sz`: 8 + (4N + 24) each reference + int[] array.
- For `count`: 4 bytes (int).
- At the end: 4 bytes (padding).

A.  $8N + 88 \sim 8N$  bytes.

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# Week 2- Introduction

Tuesday, June 6, 2017 10:15 AM

## Fundamental data types

- Bags ques stacks

>collection of objects that we want to maintain

- Operations
  - Insert
  - Remove
  - Iterate
  - Test if empty
- Stack
  - Takes out the item that was most recently added
  - Last in first out
- Queue
  - Takes out item least recently added
  - First in first out

## Modular Programming

- Completely separate interface and implementation
- Many clients can use the same implementations
  - Modular reusable libraries

# Week 2- Stacks

Tuesday, June 6, 2017 10:20 AM

## 1<sup>st</sup> Implementations

- Linked lists
  - Consists of nodes with strings and references to the next string
  - Push operation
    - New node at the beginning
  - Pop
    - Remove first node

Use inner class:

- Stack class will contain node objects,
  - Contains the string and the reference for another node
- Pop operation
  - Return first item
  - Make the current first node the reference from the returned first item
- Push operation
  - Add a new node at the beginning
  - Make node equal to the old first node
    - This will become the second node
  - Create new node
  - Set the reference to the second node

```
public class LinkedStackOfStrings
{
    private Node first = null;

    private class Node
    {
        String item;
        Node next;
    }

    public boolean isEmpty()
    {   return first == null;   }

    public void push(String item)
    {
        Node oldfirst = first;
        first = new Node();
        first.item = item;
        first.next = oldfirst;
    }

    public String pop()
    {
        String item = first.item;
        first = first.next;
        return item;
    }
}
```

private inner class  
(access modifiers don't matter)

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- Every operation takes constant time in the worst case
- Memory
  - ~40N BYTES

## 2<sup>nd</sup> Implementation

- Array structure
  - Stores N items on stack
- Pop operation
  - Remove string at N
  - Decrement N
- Push operation
  - Add string at N
  - Increment N

```
public class FixedCapacityStackOfStrings
{
    private String[] s;
    private int N = 0;

    public FixedCapacityStackOfStrings(int capacity)
    { s = new String[capacity]; }

    public boolean isEmpty()
    { return N == 0; }

    public void push(String item)
    { s[N++] = item; }

    public String pop()
    { return s[--N]; }
}
```

*a cheat  
(stay tuned)*

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## Stack Considerations

- Pop from empty stack
- Use resizing array for array implementation
- We allow clients to insert null items
- Loitering
  - Have references to something we aren't using
  - When popping objects, make the popped object null
    - Memory considerations
    -

# Week 2- Resizing Arrays

Wednesday, June 7, 2017 11:08 AM

We need a way such that the client does not need to provide the size of the array when initializing the stack

We could resize the array when the client pushes or pops from the stack

- Too expensive
- Need to copy the entire array into the new array
  - Time  $\sim N^2/2$

How to grow array?

- If the array is full, create a new array twice the size
- Proportional to  $3N$  not  $1/2N^2$

How to shrink array?

- Don't want array to get too empty
- Half the array every time it gets less than half
- Thrashing
  - If the client push pop push pop
  - Will half the array and then double
  - Quadratic time
- Half the array everytime the array is **one quarter** full

Performance

	best	worst	amortized
construct	1	1	1
push	1	N	1
pop	1	N	1
size	1	1	1

**order of growth of running time  
for resizing stack with N items**

doubling and halving operations

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Resizing array vs Linked List

Resizing Array

- Every operation takes amortized constant time
  - Long time when resizing
- Less wasted space

#### Linked List

- Every operation takes constant time in the worst case
- Extra time and space to deal with links
- slower

# Week 2- Queues

Wednesday, June 7, 2017 11:25 AM

Using the same API as stacks – but different names

Linked List

Need to maintain 2 pointers

- One to the beginning and one to the end

Dequeue

- Same as stack

Enqueue

- Copy old node
- Create new node with new string and null node
- Make old node's pointer the new node

```
public class LinkedQueueOfStrings
{
    private Node first, last;

    private class Node
    { /* same as in StackOfStrings */ }

    public boolean isEmpty()
    { return first == null; }

    public void enqueue(String item)
    {
        Node oldlast = last;
        last = new Node();
        last.item = item;
        last.next = null;
        if (isEmpty()) first = last;
        else          oldlast.next = last;
    }

    public String dequeue()
    {
        String item = first.item;
        first     = first.next;
        if (isEmpty()) last = null;
        return item;
    }
}
```

special cases for  
empty queue

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- If empty then make last node equal to first node

Array Implementation

- Have two pointers: head and tail
  - Insert new nodes at tail
  - Remove nodes at head
- When the array resize, make head at zero

# Week 2 – Generics

Wednesday, June 7, 2017 11:34 AM

Implementations so far have been only good for strings

Attempt one – old approach

- Implement a separate stack class for each type
- Maintaining is difficult

Attempt 2 –

- Use casting
- Make the stack of object
  - Cast the final answer when the client calls for it
- Client's code has to do it
  - Unsatisfactory

Attempt 3- Generics

- Avoid casting in client
- Discover mismatch errors at compile time
- Replace string with generic type name

Linked List:

## Generic stack: linked-list implementation

```
public class LinkedStackOfStrings
{
    private Node first = null;

    private class Node
    {
        String item;
        Node next;
    }

    public boolean isEmpty()
    { return first == null; }

    public void push(String item)
    {
        Node oldfirst = first;
        first = new Node();
        first.item = item;
        first.next = oldfirst;
    }

    public String pop()
    {
        String item = first.item;
        first = first.next;
        return item;
    }
}
```

```
public class Stack<Item>
{
    private Node first = null;

    private class Node
    {
        Item item;
        Node next;
    }

    public boolean isEmpty()
    { return first == null; }

    public void push(Item item)
    {
        Node oldfirst = first;
        first = new Node();
        first.item = item;
        first.next = oldfirst;
    }

    public Item pop()
    {
        Item item = first.item;
        first = first.next;
        return item;
    }
}
```

generic type name

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## Arrays:

- More difficult than linked lists
- We could make generic arrays
  - Java does not allow this
- Create an array of objects
  - Casts these objects to items

(Casting is bad form but in this case, no choice)

- Undesirable feature

## Generic stack: array implementation

the way it is

```
public class FixedCapacityStackOfStrings
{
    private String[] s;
    private int N = 0;

    public ..StackOfStrings(int capacity)
    { s = new String[capacity]; }

    public boolean isEmpty()
    { return N == 0; }

    public void push(String item)
    { s[N++] = item; }

    public String pop()
    { return s[--N]; }
}
```

the way it is

```
public class FixedCapacityStack<Item>
{
    private Item[] s;
    private int N = 0;

    public FixedCapacityStack(int capacity)
    { s = (Item[]) new Object[capacity]; }

    public boolean isEmpty()
    { return N == 0; }

    public void push(Item item)
    { s[N++] = item; }

    public Item pop()
    { return s[--N]; }
}
```

the ugly cast

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- When compiling, will get a warning for unchecked or unsafe operation
  - This is because of the uncheck casts

## Primitive types

- We need to use Java's wrapper type
  - Integer is wrapper type for int
- Autoboxing – automatic cast between primitive type and its wrapper

# Week 2- Iterators

Wednesday, June 7, 2017 11:44 AM

- Makes client code very elegant and compact
- Allow the client to iterate through the objects in the stack
  - Don't want them to know if we're using a linked list or array

## Iteration

- A class that has a method that returns an iterator

## Iterator

- Has methods hasNext() and next() - remove() is bad

If a data structure is inerrable, we can use for each statement

```
Iterable interface
public interface Iterable<Item>
{
    Iterator<Item> iterator();
}

Iterator interface
public interface Iterator<Item>
{
    boolean hasNext();
    Item next();
    void remove(); ← optional; use at your own risk
}

equivalent code (longhand)
Iterator<String> i = stack.iterator();
while (i.hasNext())
{
    String s = i.next();
    StdOut.println(s);
}
```

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## Linked List Iteration

### Implements iterable

- Means that has a method that returns an iterable
- Has to implement hasNext() and next()

### HasNext()

- If we're done returns false
- If not returns true

### Next()

- Give next item in iteration

## Stack iterator: linked-list implementation

```
import java.util.Iterator;

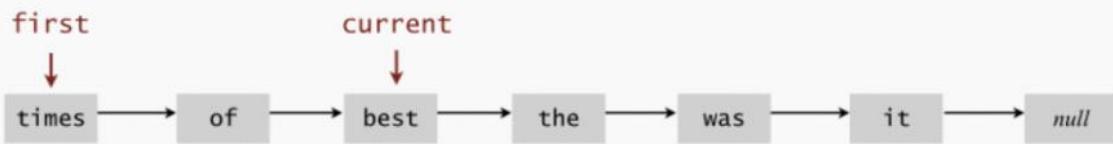
public class Stack<Item> implements Iterable<Item>
{
    ...

    public Iterator<Item> iterator() { return new ListIterator(); }

    private class ListIterator implements Iterator<Item>
    {
        private Node current = first;

        public boolean hasNext() { return current != null; }
        public void remove()    { /* not supported */ }
        public Item next()
        {
            Item item = current.item;
            current = current.next;
            return item;
        }
    }
}
```

throw UnsupportedOperationException  
throw NoSuchElementException  
if no more items in iteration



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### Array Iterator Implementation

- Goes from beginning of stack
  - Need to go from the end of the array to the beginning

## Stack iterator: array implementation

```
import java.util.Iterator;

public class Stack<Item> implements Iterable<Item>
{
    ...

    public Iterator<Item> iterator()
    { return new ReverseArrayIterator(); }

    private class ReverseArrayIterator implements Iterator<Item>
    {
        private int i = N;

        public boolean hasNext() { return i > 0; }
        public void remove()    { /* not supported */ }
        public Item next()      { return s[--i]; }
    }
}
```

	i					N				
s[]	it	was	the	best	of	times	null	null	null	null
	0	1	2	3	4	5	6	7	8	9

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Data structure called a bag

- Adding items to a collection and iterating

## Bag API

Main application. Adding items to a collection and iterating (when order doesn't matter).

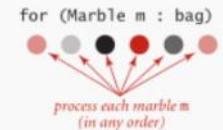
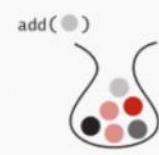
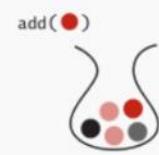
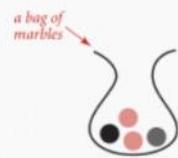
```
public class Bag<Item> implements Iterable<Item>
```

    Bag()                          *create an empty bag*

    void add(Item x)              *insert a new item onto bag*

    int size()                     *number of items in bag*

    Iterable<Item> iterator()    *iterator for all items in bag*



Implementation. Stack (without pop) or queue (without dequeue).

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# Week 2- Introduction to Sorts

June 17, 2017 2:24 PM

Rules to follow

Item = a record to the information that we are going to sort

A piece of the record is called the key

- this is the part that we sort

Goal - Sort any type of data

Callback

- How can sort() know how to compare data of double, string and java.io.file without any information about the type of the key
- call back is a reference to executable code
- the sort function calls back object's compareTo() method
  - the program compares code using the object's compare to method

Comparable Interface

- specification that a type that implements comparable will have a compareTo method

## Callbacks: roadmap

### client

```
import java.io.File;
public class FileSorter
{
    public static void main(String[] args)
    {
        File directory = new File(args[0]);
        File[] files = directory.listFiles();
        Insertion.sort(files);
        for (int i = 0; i < files.length; i++)
            StdOut.println(files[i].getName());
    }
}
```

### object implementation

```
public class File
implements Comparable<File>
{
    ...
    public int compareTo(File b)
    {
        ...
        return -1;
        ...
        return +1;
        ...
        return 0;
    }
}
```

### Comparable interface (built in to Java)

```
public interface Comparable<Item>
{
    public int compareTo(Item that);
}
```

key point: no dependence  
on File data type

### sort implementation

```
public static void sort(Comparable[] a)
{
    int N = a.length;
    for (int i = 0; i < N; i++)
        for (int j = i; j > 0; j--)
            if (a[j].compareTo(a[j-1]) < 0)
                exch(a, j, j-1);
            else break;
}
```

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Total order

A **total order** is a binary relation  $\leq$  that satisfies:

- Antisymmetry: if  $v \leq w$  and  $w \leq v$ , then  $v = w$ .
- Transitivity: if  $v \leq w$  and  $w \leq x$ , then  $v \leq x$ .
- Totality: either  $v \leq w$  or  $w \leq v$  or both.

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## Comparable API

implement compareTo so  $v.compareTo(w)$  is a total order

- if null returns exception

Built in

- integer
- double
- string

Make ourselves

- need to implement Comparable

```
public class Date implements Comparable<Date>
{
    private final int month, day, year;

    public Date(int m, int d, int y)
    {
        month = m;
        day   = d;
        year  = y;
    }

    public int compareTo(Date that)
    {
        if (this.year < that.year) return -1;
        if (this.year > that.year) return +1;
        if (this.month < that.month) return -1;
        if (this.month > that.month) return +1;
        if (this.day < that.day) return -1;
        if (this.day > that.day) return +1;
        return 0;
    }
}
```

only compare dates  
to other dates

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Helper functions - refer to data through compares and exchanges - static  
Only use these functions when sorting to ensure accuracy

- less
  - is  $v$  less than  $w$
- Exchange
  - swamp item in  $a[]$  at  $i$  with  $j$



# Week 2 – Selection Sort

Wednesday, July 5, 2017 4:36 PM

Start out with unsorted array

- Find smallest remaining entry
- Swap  $a[i]$  and  $a[min]$
- Increment  $i$

Invariants – things that are true in the algorithm

- The entries to the left are in ascending order
- No entry to the right of the arrow are smaller than any value on the left side

## Selection sort inner loop

To maintain algorithm invariants:

- Move the pointer to the right.

```
i++;
```



- Identify index of minimum entry on right.

```
int min = i;
for (int j = i+1; j < N; j++)
    if (less(a[j], a[min]))
        min = j;
```



- Exchange into position.

```
exch(a, i, min);
```



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```
public class Selection
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;
        for (int i = 0; i < N; i++)
        {
            int min = i;
            for (int j = i+1; j < N; j++)
                if (less(a[j], a[min]))
                    min = j;
            exch(a, i, min);
        }
    }

    private static boolean less(Comparable v, Comparable w)
    { /* as before */ }

    private static void exch(Comparable[] a, int i, int j)
    { /* as before */ }
}
```

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### Mathematical Analysis

- $N^2/2$  compares and  $N$  exchanges
- Quadratic time – even if input is sorted

Minimal data movement – minimum number of exchanges

# Week 2 – Insertion Sort

Wednesday, July 5, 2017 4:43 PM

Has two variables,  $j$  and  $i$ , exchange to the left until there is no next value or the card is less than  $j$ 's value. ( $j$  is the position of the value being switched while  $i$  is the value of the first value).

## Invariants

- Entries to the left of the arrow are sorted
- Entries to the right have not been seen

### To maintain algorithm invariants:

- Move the pointer to the right.

`i++;`



- Moving from right to left, exchange  $a[i]$  with each larger entry to its left.

```
for (int j = i; j > 0; j--)  
    if (less(a[j], a[j-1]))  
        exch(a, j, j-1);  
    else break;
```



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```

public class Insertion
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;
        for (int i = 0; i < N; i++)
            for (int j = i; j > 0; j--)
                if (less(a[j], a[j-1]))
                    exch(a, j, j-1);
                else break;
    }

    private static boolean less(Comparable v, Comparable w)
    { /* as before */ }

    private static void exch(Comparable[] a, int i, int j)
    { /* as before */ }
}

```

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### Mathematical Analysis

$\frac{1}{4} N^2$  compares

$\frac{1}{4} N^2$  exchanges

- depends on how sorted the original array was sorted
- we can expect each value to be moved half the length of the array

### Best Case

- already sorted
- $N-1$  compares
- 0 exchanges
- validates that the array is sorted

### Worst Case

- In descending order
- every element goes all the way to the front
- $\frac{1}{2} N^2$  compares and exchanges.

### Partially Sorted arrays

- an inversion
  - a pair of keys that are just switched
- if a number of inversions is  $< c*N$  where  $c$  is any constant
- Insertion time is linear time for partially sorted arrays

# Week 2 - Shell sort

July 5, 2017 10:13 PM

With shell sort, we move entries more than one position at a time

h-sorting

- only sorts every h entries
- starts at entry h+1
  - compares with entries h entries back
  - repeats until array is combed through

Use insertion sort, but instead of comparing with the adjacent entry, we compare with the  $h^{\text{th}}$  entry back

Big increment -> small subarray

Small increment -> array will be partially sorted

- can then use insertion sort

Use increments - ie (7,3,1)

- 1 sort is essentially insertion sort

If you g sort an array and then k sort,

- the final array will be both k sorted and g sorted

What increment system should we use?

- powers of 2?
  - does not compare even positions with odd positions
- powers of 2-1
  - ok
- $3x+1$ 
  - easy to compute
- **we find the largest number that is smaller than the array size**

```
public class Shell
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;

        int h = 1;
        while (h < N/3) h = 3*h + 1; // 1, 4, 13, 40, 121, 364, ...
        ← 3x+1 increment sequence

        while (h >= 1)
        { // h-sort the array.
            for (int i = h; i < N; i++)
            {
                for (int j = i; j >= h && less(a[j], a[j-h]); j -= h)
                    exch(a, j, j-h);
            }
            ← insertion sort

            h = h/3;
        }
        ← move to next increment
    }

    private static boolean less(Comparable v, Comparable w)
    { /* as before */ }
    private static void exch(Comparable[] a, int i, int j)
    { /* as before */ }
}
```

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not much difference for partially sorted arrays

#### Mathematical Analysis

- worst case is  $O(N^{3/2})$
- nobody knows an accurate model for shellsort

Very useful in practice

- unless the array size is huge
- not a lot of code

# Week 2 - Shuffling (Sorting application)

July 5, 2017 11:40 PM

## Application of sorting - shuffling

Generate a random real number for each entry

- sort the numbers

Can we have a faster way to shuffle?

- linear time
- pass through array - swap index at  $i$  with a random index  $r$
- only swap cards with already seen indexes
- the values left of  $i$  are shuffled, right of  $i$  are not yet seen
  - Knuth Shuffle

- In iteration  $i$ , pick integer  $r$  between 0 and  $i$  uniformly at random.
- Swap  $a[i]$  and  $a[r]$ .

common bug: between 0 and  $N - 1$   
correct variant: between  $i$  and  $N - 1$

```
public class StdRandom
{
    ...
    public static void shuffle(Object[] a)
    {
        int N = a.length;
        for (int i = 0; i < N; i++)
        {
            int r = StdRandom.uniform(i + 1);           ← between 0 and i
            exch(a, i, r);
        }
    }
}
```

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# Week 2 - Convex Hull (Sorting Application)

July 6, 2017 12:19 AM

For a set of points, the convex hull is the smallest perimeter that can enclose all points.

- vertices need to be points in the set

We want a program that will give us the convex hull of a set of points

- outputs a sequence of vertices in clockwise order

Convex hull application:

- find the shortest path from s to t such that it avoids the polygonal obstacle
- going around - will be the convex hull of the set of points

Second application,

- find the two sets of points furthest from each other
- both points will be on the convex hull

Properties of the convex hull

- can transverse convex hull by only making counter clockwise turns
- the vertices of convex hull appear in increasing order of polar angle with respect to the lowest y component

Graham Scan Algorithm

- choose point p with the smallest y coordinate
- sort points by polar angle
- consider points in order, discard unless it creates a counter clockwise turn.

Implementation Challenges

- point with smallest y coordinate
  - define total order - compare y component
- How to sort points by polar angle
  - define a total order for each point p
  - total order will be in the next lecture
- Determine if a CCW turn - next
- Sorting efficiently
  - merge sort sorts in  $N \log N$  time
  - a good sorting algorithm gives a good convex hull algorithm
- Multiple points on the same line

Implementing CCW turns

- how to determine if a turn is CCW?
- is c to the left of ray a-b
- look at slopes
  - special cases - collinear and infinity/0 slope
- Compute cross product
  - if vector is positive - CCW
  - if vector is negative - clockwise
  - if vector is 0, - they are collinear

## Immutable point data type

```
public class Point2D
{
    private final double x;
    private final double y;

    public Point2D(double x, double y)
    {
        this.x = x;
        this.y = y;
    }

    ...
}

public static int ccw(Point2D a, Point2D b, Point2D c)
{
    double area2 = (b.x-a.x)*(c.y-a.y) - (b.y-a.y)*(c.x-a.x);
    if (area2 < 0) return -1; // clockwise
    else if (area2 > 0) return +1; // counter-clockwise
    else                  return 0; // collinear
}
```

danger of floating-point roundoff error

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## Graham scan: implementation

Simplifying assumptions. No three points on a line; at least 3 points.

```
Stack<Point2D> hull = new Stack<Point>();

Arrays.sort(p, Point2D.Y_ORDER);      ← p[0] is now point with lowest y-coordinate
Arrays.sort(p, p[0].BY_POLAR_ORDER); ← sort by polar angle with respect to p[0]

hull.push(p[0]); ← definitely on hull
hull.push(p[1]); ←
for (int i = 2; i < N; i++) {           ← discard points that would
    Point2D top = hull.pop();           ← create clockwise turn
    while (Point2D.ccw(hull.peek(), top, p[i]) <= 0)
        top = hull.pop();
    hull.push(top);
    hull.push(p[i]); ← add p[i] to putative hull
}
```

Running time.  $N \log N$  for sorting and linear for rest.

Pf.  $N \log N$  for sorting; each point pushed and popped at most once.

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# Week 2 - Programming Assignment

July 10, 2017 7:44 PM

For linked lists - need to bypass the initial null value

- when adding the first node, set first and last to that node
- when removing the last node, set first and last to null

When writing while loops

- what can cause the loop to run forever

Don't just copy their code

# Week 3 - Merge Sort

July 11, 2017 1:41 PM

## How to mergesort

- divide array into two halves
- recursively sort into two halves
- merge two halves

To get two sorted halves into one array (abstract in-place merge)

- keep 3 indices, one at the first of the large array and 2 at the start of the smaller arrays
- compare the two indices in the sub arrays and insert the smallest one where the index in the large array is

## Merging: Java implementation

```
private static void merge(Comparable[] a, Comparable[] aux, int lo, int mid, int hi)
{
    assert isSorted(a, lo, mid);      // precondition: a[lo..mid] sorted
    assert isSorted(a, mid+1, hi);    // precondition: a[mid+1..hi] sorted

    for (int k = lo; k <= hi; k++)
        aux[k] = a[k];                                copy

    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)                  merge
    {
        if      (i > mid)                a[k] = aux[j++];
        else if (j > hi)                a[k] = aux[i++];
        else if (less(aux[j], aux[i]))  a[k] = aux[j++];
        else                            a[k] = aux[i++];
    }

    assert isSorted(a, lo, hi);      // postcondition: a[lo..hi] sorted
}
```



## Assertion

- helps detect logic bug
- test assumption about the program
- documents code

### Assert statement

- throws exception unless boolean condition is true
  - `assert isSorted(a,lo,hi);`

Can enable or disable at runtime

`java -eq MyProgram` // enable assertion

```
java -da MyProgram // disable assertion (default)
```

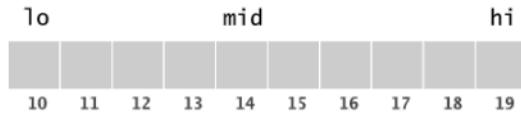
best practice - to test logic not to test inputs

## Mergesort: Java implementation

```
public class Merge
{
    private static void merge(...)
    { /* as before */

    private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
    {
        if (hi <= lo) return;
        int mid = lo + (hi - lo) / 2;
        sort(a, aux, lo, mid);
        sort(a, aux, mid+1, hi);
        merge(a, aux, lo, mid, hi);
    }

    public static void sort(Comparable[] a)
    {
        aux = new Comparable[a.length];
        sort(a, aux, 0, a.length - 1);
    }
}
```



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- don't create aux array in recursive method - takes too much memory

### Running Time

- efficient algorithm
- $N \log N$  time (insertion sort is  $N^2$ )

### Proposition

- uses at most  $N \lg N$  compares and  $6N \lg N$  array accesses with size  $N$  array

### Pf Sketch (recurrence relation)

- the number of compares  $C(N)$  and array access  $A(N)$  to mergesort an array of size  $N$

## Mergesort: number of compares and array accesses

**Proposition.** Mergesort uses at most  $N \lg N$  compares and  $6N \lg N$  array accesses to sort any array of size  $N$ .

Pf sketch. The number of compares  $C(N)$  and array accesses  $A(N)$  to mergesort an array of size  $N$  satisfy the recurrences:

$$C(N) \leq C(\lceil N/2 \rceil) + C(\lfloor N/2 \rfloor) + N \quad \text{for } N > 1, \text{ with } C(1) = 0.$$



$$A(N) \leq A(\lceil N/2 \rceil) + A(\lfloor N/2 \rfloor) + 6N \quad \text{for } N > 1, \text{ with } A(1) = 0.$$

We solve the recurrence when  $N$  is a power of 2. ← result holds for all  $N$

$$D(N) = 2D(N/2) + N, \text{ for } N > 1, \text{ with } D(1) = 0.$$

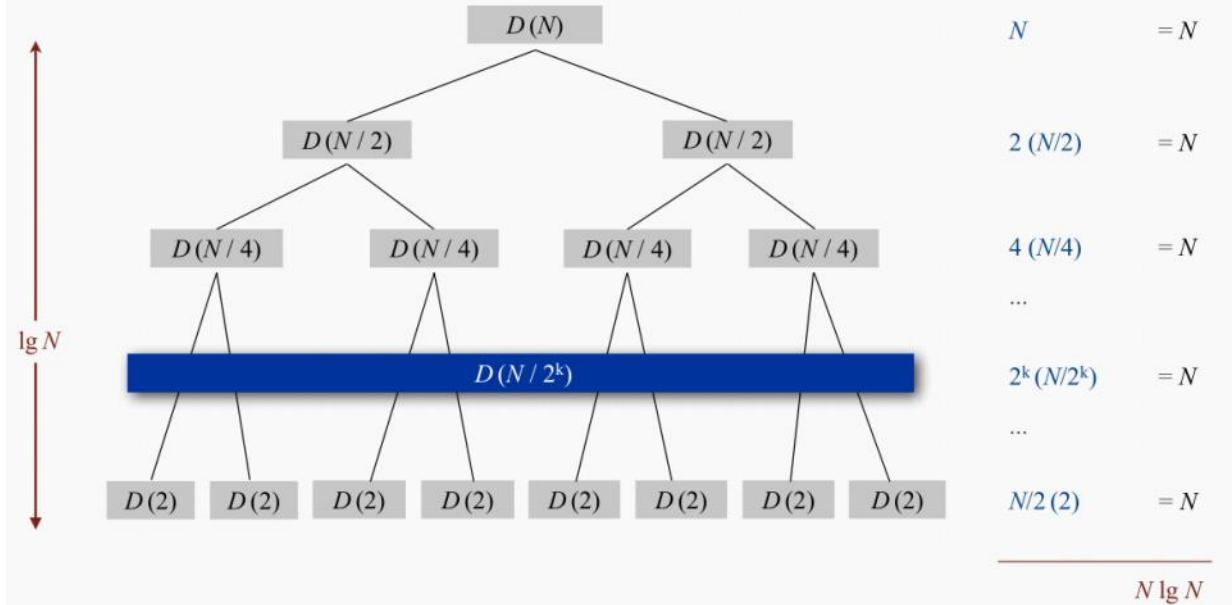
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we can prove by induction

## Divide-and-conquer recurrence: proof by picture

**Proposition.** If  $D(N)$  satisfies  $D(N) = 2 D(N/2) + N$  for  $N > 1$ , with  $D(1) = 0$ , then  $D(N) = N \lg N$ .

Pf 1. [assuming  $N$  is a power of 2]



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- we can also prove by graphical analysis
  - there are  $\lg N$  times you can split  $D(N)$
  - every time you split it is  $N$
  - therefore time takes  $N \lg N$

## Divide-and-conquer recurrence: proof by expansion

**Proposition.** If  $D(N)$  satisfies  $D(N) = 2D(N/2) + N$  for  $N > 1$ , with  $D(1) = 0$ , then  $D(N) = N \lg N$ .

**Pf 2.** [assuming  $N$  is a power of 2]

$$\begin{aligned} D(N) &= 2D(N/2) + N && \text{given} \\ D(N)/N &= 2D(N/2)/N + 1 && \text{divide both sides by } N \\ &= D(N/2)/(N/2) + 1 && \text{algebra} \\ &= D(N/4)/(N/4) + 1 + 1 && \text{apply to first term} \\ &= D(N/8)/(N/8) + 1 + 1 + 1 && \text{apply to first term again} \\ &\dots \\ &= D(N/N)/(N/N) + 1 + 1 + \dots + 1 && \text{stop applying, } D(1) = 0 \\ &= \lg N \end{aligned}$$

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Induction:

## Divide-and-conquer recurrence: proof by induction

**Proposition.** If  $D(N)$  satisfies  $D(N) = 2D(N/2) + N$  for  $N > 1$ , with  $D(1) = 0$ , then  $D(N) = N \lg N$ .

**Pf 3.** [assuming  $N$  is a power of 2]

- Base case:  $N = 1$ .
- Inductive hypothesis:  $D(N) = N \lg N$ .
- Goal: show that  $D(2N) = (2N) \lg (2N)$ .

$$\begin{aligned} D(2N) &= 2D(N) + 2N && \text{given} \\ &= 2N \lg N + 2N && \text{inductive hypothesis} \\ &= 2N(\lg(2N) - 1) + 2N && \text{algebra} \\ &= 2N \lg(2N) && \text{QED} \end{aligned}$$

## Memory

uses space proportional to N

- extra auxiliary array

## Practical Improvements

1. Use insertion sort for small subarrays
  - a. too much overhead for recursive calls
  - b. cutoff to insertion sort for 7 items (insertion sort is efficient for small arrays)

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo + CUTOFF - 1)
    {
        Insertion.sort(a, lo, hi);
        return;
    }
    int mid = lo + (hi - lo) / 2;
    sort (a, aux, lo, mid);
    sort (a, aux, mid+1, hi);
    merge(a, aux, lo, mid, hi);
}
```

2. Stop if already sorted
  - a. The biggest element in the first half is smaller than the smallest item in the second half



```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort (a, aux, lo, mid);
    sort (a, aux, mid+1, hi);
    if (!less(a[mid+1], a[mid])) return;
    merge(a, aux, lo, mid, hi);
}
```

3. Eliminate the copy to the aux array
  - a. switch role of input and aux array in each recursive call

```

private static void merge(Comparable[] a, Comparable[] aux, int lo, int mid, int hi)
{
    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)
    {
        if (i > mid)           aux[k] = a[j++];
        else if (j > hi)       aux[k] = a[i++];
        else if (less(a[j], a[i])) aux[k] = a[j++]; ← merge from a[] to aux[]
        else                     aux[k] = a[i++];
    }
}

private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort (aux, a, lo, mid);
    sort (aux, a, mid+1, hi);           Note: sort(a) initializes aux[] and sets
    merge(a, aux, lo, mid, hi);         aux[i] = a[i] for each i.
}

```

↑  
switch roles of aux[] and a[]

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# Week 3 - Bottom Up Mergesort

July 11, 2017 6:55 PM

Each array is subarrays of sorted arrays of size 1

- merge subarrays of size 1
- repeat for 2,4,8,16.....

No recursion needed

```
public class MergeBU
{
    private static void merge(...)
    { /* as before */

    public static void sort(Comparable[] a)
    {
        int N = a.length;
        Comparable[] aux = new Comparable[N];
        for (int sz = 1; sz < N; sz = sz+sz)
            for (int lo = 0; lo < N-sz; lo += sz+sz)
                merge(a, aux, lo, lo+sz-1, Math.min(lo+sz+sz-1, N-1));
    }
}
```

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- uses extra space proportional to size of array

# Week 3 - Sorting Complexity

July 11, 2017 7:00 PM

Framework to study efficiency of algorithms

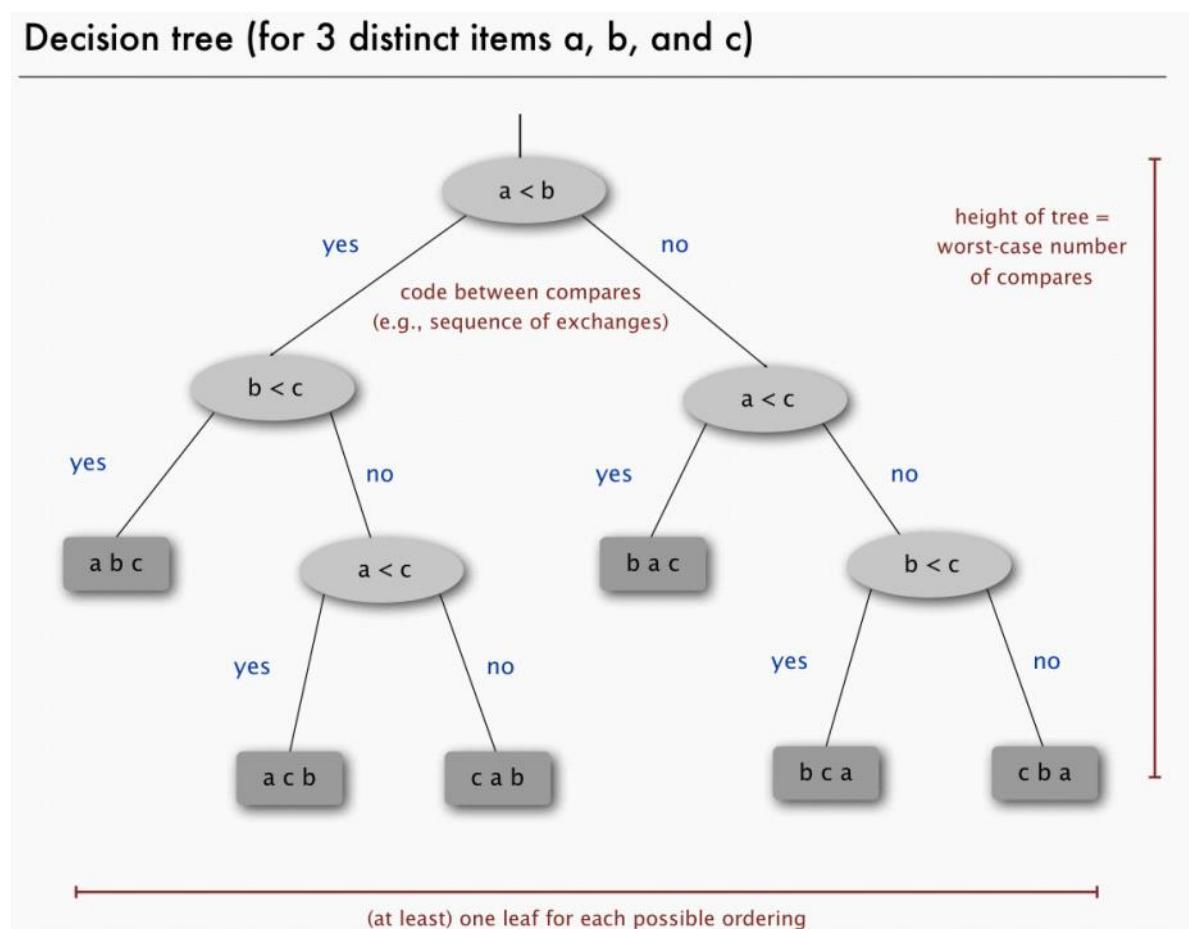
## Model of Computation

- operations that the algorithm performs
- Cost model - operation costs
- Upper bound - guaranteed cost provided by some algorithm
  - known algorithm
- Lower bound - proven limit on cost guaranteed on all algorithms
  - no algorithm can do better
- Optimal algorithm
  - lower bound = upper bound

i.e. Sorting

- decision tree
- all we can use are compares
- number of compares
- mergesort -  $N \lg N$

Decision Tree:

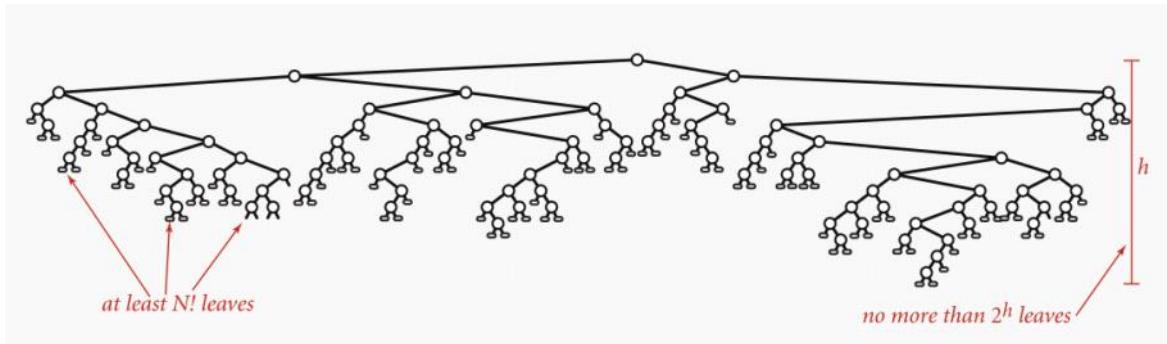


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- Lower bound finds the lowest height of tree possible

Any compare-based sorting algorithm must use at least  $\lg(N!)$  ~  $N \lg N$  compares

- binary tree of height  $h$  has  $2^h$ 
  - no more than  $2^h$
- at least  $N!$  leaves



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$$\begin{aligned} 2^h &\geq \# \text{ leaves} \geq N! \\ \Rightarrow h &\geq \lg(N!) \sim N \lg N \end{aligned}$$

↑  
Stirling's formula

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Therefore the lower bound is  $N \lg N$

- mergesort is the optimal algorithm

Mergesort is optimal to number of compares

- not optimal for memory

### Lessons from sorting complexity

- use theory as guide
  - don't design an algorithm with  $1/2 N \lg N$  compares
    - won't work
- The lower bound is only with one case (using only compares)
  - ie. if the array is partially sorted insertion sort will be linear time

# Week 3 - Comparators

July 11, 2017 9:33 PM

Java's way to compare different values

Comparable interface -> used before

Comparator interface - sort using an alternate order

- can have different keys
  - natural order
  - case insensitive
  - etc

Java system sort

- create comparator object
- Pass as second argument to Arrays.sort()

The diagram shows a snippet of Java code demonstrating various ways to sort an array of strings. Red annotations explain the sorting methods:

- An arrow points from the first line, `String[] a;`, to the text "uses natural order".
- An arrow points from the line `Arrays.sort(a);` to the text "uses alternate order defined by Comparator<String> object".
- An arrow points from the line `Arrays.sort(a, String.CASE_INSENSITIVE_ORDER);` to the same text "uses alternate order defined by Comparator<String> object".
- An arrow points from the line `Arrays.sort(a, Collator.getInstance(new Locale("es")));` to the same text.
- An arrow points from the line `Arrays.sort(a, new BritishPhoneBookOrder());` to the same text.

```
String[] a;
...
Arrays.sort(a);
...
Arrays.sort(a, String.CASE_INSENSITIVE_ORDER);
...
Arrays.sort(a, Collator.getInstance(new Locale("es")));
...
Arrays.sort(a, new BritishPhoneBookOrder());
...
```

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Defining how to sort data can be done separately from when you define the data type

We can change our implementations to support comparators

- use object instead of Comparable
  - Object[] a instead of Comparable[] a
- pass Comparable to sort() and less() and use it in less()

```
public static void sort(Object[] a, Comparator comparator)
{
    int N = a.length;
    for (int i = 0; i < N; i++)
        for (int j = i; j > 0 && less(comparator, a[j], a[j-1]); j--)
            exch(a, j, j-1);
}

private static boolean less(Comparator c, Object v, Object w)
{   return c.compare(v, w) < 0; }

private static void exch(Object[] a, int i, int j)
{   Object swap = a[i]; a[i] = a[j]; a[j] = swap; }
```

## Implementing comparators

```

public class Student
{
    public static final Comparator<Student> BY_NAME = new ByName();
    public static final Comparator<Student> BY_SECTION = new BySection();
    private final String name;
    private final int section;
    ...
        one Comparator for the class

    private static class ByName implements Comparator<Student>
    {
        public int compare(Student v, Student w)
        { return v.name.compareTo(w.name); }
    }

    private static class BySection implements Comparator<Student>
    {
        public int compare(Student v, Student w)
        { return v.section - w.section; }
    }
}

```

this technique works here since no danger of overflow

## Example: Comparator for 2d points (CCW polar angles)

```

public class Point2D
{
    public final Comparator<Point2D> POLAR_ORDER = new PolarOrder();
    private final double x, y;
    ...
        one Comparator for each point (not static)

    private static int ccw(Point2D a, Point2D b, Point2D c)
    { /* as in previous lecture */ }

    private class PolarOrder implements Comparator<Point2D>
    {
        public int compare(Point2D q1, Point2D q2)
        {
            double dy1 = q1.y - y;
            double dy2 = q2.y - y;

            if (dy1 == 0 && dy2 == 0) { ... } ← p, q1, q2 horizontal
            else if (dy1 >= 0 && dy2 < 0) return -1; ← q1 above p; q2 below p
            else if (dy2 >= 0 && dy1 < 0) return +1; ← q1 below p; q2 above p
            else return -ccw(Point2D.this, q1, q2); ← both above or below p
        }
    }
}

```

to access invoking point from within inner class

- the compare() method returns a positive value if obj 1 is greater than obj2

- 0 for equal
- negative for obj2 greater than obj1

# Week 3 - Stability

July 11, 2017 10:14 PM

A stable sort preserves the relative order of items with equal keys

Which sorts are stable?

- insertion
- merge

Not stable

- selection
- shell

**What makes sorts stable?**

- equal items never move past each other

Long distance exchanges often makes sorts unstable

Mergesort's stability depends on its merge() method

- if the two keys are equal will take from the lower array - items will remain sorted

# Week 3 - Quicksort

July 12, 2017 11:51 AM

Quicksort is the Java sort for primitive data types

## Quicksort

- Recursive method
- shuffle the array
- partition such that a value will be in place
  - no value left of it is greater than the value
  - no value right of it is less than the value
- sort each side recursively

## Demo

1. randomly select the partition
2. have 2 pointers i,j
  - a. scan from left to right for i
    - i. stop if the value is greater than the partition value
  - b. scan from right to left for j
    - i. stop if the value is smaller than the partition value
  - c. when both i and j are stopped, exchange i and j
3. exchange j with the partition element

The screenshot shows a Java code editor with the following code:

```
private static int partition(Comparable[] a, int lo, int hi)
{
    int i = lo, j = hi+1;
    while (true)
    {
        while (less(a[++i], a[lo]))           find item on left to swap
            if (i == hi) break;

        while (less(a[lo], a[--j]))           find item on right to swap
            if (j == lo) break;

        if (i >= j) break;                  check if pointers cross
        exch(a, i, j);                   swap
    }

    exch(a, lo, j);                  swap with partitioning item
    return j;                        return index of item now known to be in place
}
```

Below the code are three diagrams illustrating the state of the array at different stages:

- before:** An array with elements  $v$ ,  $\leq v$ ,  $\geq v$ . The index  $lo$  is at the start of the  $\leq v$  segment, and  $hi$  is at the end of the  $\geq v$  segment.
- during:** The array has been partially sorted. The  $v$  element is highlighted. The  $\leq v$  segment starts at index  $lo$ , contains the element  $v$ , and ends at index  $i$ . The  $\geq v$  segment starts at index  $j$  and ends at  $hi$ . The  $v$  element is currently at index  $j$ .
- after:** The array is fully sorted. The  $\leq v$  segment starts at index  $lo$  and ends at index  $j$ . The  $v$  element is at index  $j$ . The  $\geq v$  segment starts at index  $j+1$  and ends at index  $hi$ .

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```

public class Quick
{
    private static int partition(Comparable[] a, int lo, int hi)
    { /* see previous slide */ }

    public static void sort(Comparable[] a)
    {
        StdRandom.shuffle(a);
        sort(a, 0, a.length - 1);
    }

    private static void sort(Comparable[] a, int lo, int hi)
    {
        if (hi <= lo) return;
        int j = partition(a, lo, hi);
        sort(a, lo, j-1);
        sort(a, j+1, hi);
    }
}

```

← shuffle needed for performance guarantee (stay tuned)

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### Implementation Details

- partitions in place - doesn't take extra space
- testing when pointers cross is trickier - duplicate keys
- ( $j == lo$ ) is redundant -  $j$  will hit the partitioning element
- ( $i=hi$ ) is not redundant - there is room for  $i$  to run off the array

### Preserving randomness

- shuffling is needed for performance guarantee

### Equal keys

- when the pointers hit values that are equal to the partition, they stop

### Running Time

- faster than mergesort
- Best Case
  - divides everything by half
    - $N \lg N$
- Worst Case
  - when the partition is the first value
    - $1/2 N^2$
    - unlikely to happen
- Average case

Pf.  $C_N$  satisfies the recurrence  $C_0 = C_1 = 0$  and for  $N \geq 2$ :

$$C_N = (N+1) + \left( \frac{C_0 + C_{N-1}}{N} \right) + \left( \frac{C_1 + C_{N-2}}{N} \right) + \dots + \left( \frac{C_{N-1} + C_0}{N} \right)$$

partitioning      left      right  
↓                  ↓      ↓  
                            ↑  
                            partitioning probability

- Multiply both sides by  $N$  and collect terms:

$$NC_N = N(N+1) + 2(C_0 + C_1 + \dots + C_{N-1})$$

- Subtract this from the same equation for  $N-1$ :

$$NC_N - (N-1)C_{N-1} = 2N + 2C_{N-1}$$

- Rearrange terms and divide by  $N(N+1)$ :

$$\frac{C_N}{N+1} = \frac{C_{N-1}}{N} + \frac{2}{N+1}$$

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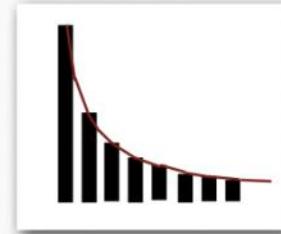
- Repeatedly apply above equation:

$$\begin{aligned} \frac{C_N}{N+1} &= \frac{C_{N-1}}{N} + \frac{2}{N+1} \\ &= \frac{C_{N-2}}{N-1} + \frac{2}{N} + \frac{2}{N+1} \quad \leftarrow \text{substitute previous equation} \\ &= \frac{C_{N-3}}{N-2} + \frac{2}{N-1} + \frac{2}{N} + \frac{2}{N+1} \\ &= \frac{2}{3} + \frac{2}{4} + \frac{2}{5} + \dots + \frac{2}{N+1} \end{aligned}$$

← previous equation

- Approximate sum by an integral:

$$\begin{aligned} C_N &= 2(N+1) \left( \frac{1}{3} + \frac{1}{4} + \frac{1}{5} + \dots + \frac{1}{N+1} \right) \\ &\sim 2(N+1) \int_3^{N+1} \frac{1}{x} dx \end{aligned}$$



- Finally, the desired result:

$$C_N \sim 2(N+1) \ln N \approx 1.39N \lg N$$

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- 39% more compares than mergesort
- faster because of less data movement
- shuffle guarantees against worst case
- easily understandable mathematically

## Practical Improvements

- insertion sort for small subarrays
  - cutoff ~ 10 items (10-20 also works)

- another option is to leave small subarrays until the end and then run a insertion sort on the sub arrays
- Take the median
  - sample the items
  - estimate median of samples
    - take the median of 3 random items

# Week 3 - Selection

July 12, 2017 3:18 PM

Goal - given an array of N items - find the kth largest

## Use theory as a guide

- we can solve selection in  $N \lg N$ 
  - sort the array - find the kth
- If k is small - proportional to N
  - for  $k = 0$  just find min
  - for  $k = 1$  need to run through twice
- Lower bound is N - must look at all items

## Quick-Select

Partition array such that

- $a[j]$  is in place
- no entry smaller left
- no entry larger right
- repeat in one subarray depending on the values of k and j
  - if k is larger than j - only look at right subarray
  - if k is smaller than j - only look at left subarray
  - if equal - found the kth digit

## Mathematical Analysis

- only takes linear time on average

### Pf sketch.

- Intuitively, each partitioning step splits array approximately in half:  
 $N + N/2 + N/4 + \dots + 1 \sim 2N$  compares.
- Formal analysis similar to quicksort analysis yields:

$$C_N = 2N + 2k \ln(N/k) + 2(N-k) \ln(N/(N-k))$$

  
 $(2 + 2 \ln 2)N$  to find the median

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## Quick Select is only on average linear time

There is an algorithm that is worst case linear time

- takes too much memory to be practical
- still worthwhile to find a practical linear time algorithm

# Week 3 - Duplicate Keys

July 12, 2017 3:26 PM

The purpose of sorting is often to bring keys of equal keys together

## Quicksort

- goes quadratic time unless partition stops on equal keys

Mistake: put all items equal to partition items on one side

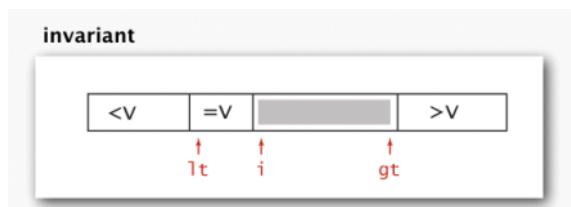
- if all the keys are equal
  - then the algorithm will become quadratic
- if you stop when keys are equal
  - divides the array in half
  - $N \lg N$  compares
- If put all items in place
  - desirable

## 3 way partitioning

- partition array into three parts
- 1 array smaller than partition
- 1 array equal to partition
- 1 array larger than partition

## 3 constants

- lt - less than partitioning element
- gt - greater than partitioning element
- i - everything right of i we haven't seen yet
- between lt and i - equal to v

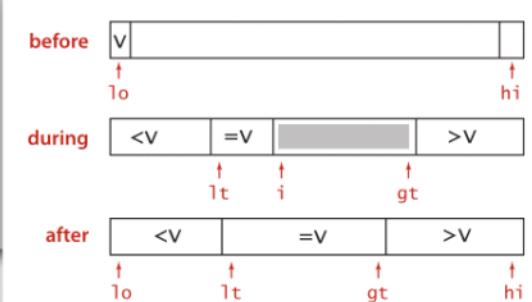


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- i scans from left to right
  - if i is less than partition, swap i and lt - increment i and lt
  - if i is greater than partition, swap i and gt - decrement gt
  - if i is equal to partition increment i
  - stop with i and gt cross

## 3-way quicksort: Java implementation

```
private static void sort(Comparable[] a, int lo, int hi)
{
    if (hi <= lo) return;
    int lt = lo, gt = hi;
    Comparable v = a[lo];
    int i = lo;
    while (i <= gt)
    {
        int cmp = a[i].compareTo(v);
        if      (cmp < 0) exch(a, lt++, i++);
        else if (cmp > 0) exch(a, i, gt--);
        else                i++;
    }
    sort(a, lo, lt - 1);
    sort(a, gt + 1, hi);
}
```



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## Sorting Lower Bound

**Sorting lower bound.** If there are  $n$  distinct keys and the  $i^{\text{th}}$  one occurs  $x_i$  times, any compare-based sorting algorithm must use at least

$$\lg \left( \frac{N!}{x_1! x_2! \cdots x_n!} \right) \sim - \sum_{i=1}^n x_i \lg \frac{x_i}{N}$$

$N \lg N$  when all distinct;  
linear when only a constant number of distinct keys

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- number of compares is equal to lower bound
- depends on the distribution of keys
  - entropy optimal
- when using 3 way partitioning
  - many applications when run times become linear

# Week 3 - System Sorts

July 12, 2017 3:41 PM

## Applications

Java - arrays.sort()

- with primitive type
- implements comparable and comparator

Another implementation that does not require making the array random

- Tukey's ninther
  - Median of the median of 3 samples each of 3 entries
  - approximates the median of 9 values with only 12 compares
  - don't like change of state and also less costly

What is the most important sorting algorithm?

- has diverse attributes
  - stability
  - parallel
  - equal keys
  - key types
  - large or small items
  - guaranteed vs random performance

**System sort is usually good enough but not always**

	inplace?	stable?	worst	average	best	remarks
selection	✓		$N^2 / 2$	$N^2 / 2$	$N^2 / 2$	$N$ exchanges
insertion	✓	✓	$N^2 / 2$	$N^2 / 4$	$N$	use for small $N$ or partially ordered
shell	✓		?	?	$N$	tight code, subquadratic
merge		✓	$N \lg N$	$N \lg N$	$N \lg N$	$N \log N$ guarantee, stable
quick	✓		$N^2 / 2$	$2 N \ln N$	$N \lg N$	$N \log N$ probabilistic guarantee fastest in practice
3-way quick	✓		$N^2 / 2$	$2 N \ln N$	$N$	improves quicksort in presence of duplicate keys
???	✓	✓	$N \lg N$	$N \lg N$	$N$	holy sorting grail

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# Week 3 programming assignment

July 20, 2017 12:26 PM

- watch for null values
- careful with pointers in arrays - at the end of array
  - double check every time you call pointers - what happens with them at the end of arrays

# Week 4 - APIs and Elementary Implementations

July 21, 2017 4:05 PM

## Priority Queues

- like sorting but more flexibility

### Priority Queue

- remove the largest or smallest item

API:

Key must be Comparable (bounded type parameter)	
public class MaxPQ<Key extends Comparable<Key>>	
MaxPQ()	<i>create an empty priority queue</i>
MaxPQ(Key[] a)	<i>create a priority queue with given keys</i>
void insert(Key v)	<i>insert a key into the priority queue</i>
Key delMax()	<i>return and remove the largest key</i>
boolean isEmpty()	<i>is the priority queue empty?</i>
Key max()	<i>return the largest key</i>
int size()	<i>number of entries in the priority queue</i>

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## Items must be comparable

Lots of applications:

- event driven simulation
- numerical computation
- data compression
- graph searching
- etc

Example: Store the largest M values in a very large N

- memory restrictions
- (credit card fraud detection - only want to look at largest amounts)

To keep the largest M,

- add a transaction
- then delete the lowest value if there are more values than M in the queue

## Compared to other methods:

implementation	time	space
sort	$N \log N$	$N$
elementary PQ	$M N$	$M$
binary heap	$N \log M$	$M$
best in theory	$N$	$M$

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- this technique too slow
  - binary heap is better(future lesson)

## Two ways to set up a prioritized queue

- ordered stack
  - easy to remove
  - hard to add
- unordered stack
  - opposite

## Unordered Example:

```
public class UnorderedMaxPQ<Key extends Comparable<Key>>
{
    private Key[] pq; // pq[i] = ith element on pq
    private int N; // number of elements on pq

    public UnorderedMaxPQ(int capacity)
    { pq = (Key[]) new Comparable[capacity]; } ← no generic array creation

    public boolean isEmpty()
    { return N == 0; }

    public void insert(Key x)
    { pq[N++] = x; }

    public Key delMax()
    {
        int max = 0;
        for (int i = 1; i < N; i++)
            if (less(max, i)) max = i;
        exch(max, N-1);
        return pq[--N]; ← null out entry to prevent loitering
    }
}
```

← less() and exch()  
similar to sorting methods

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## Running Time

**order of growth of running time for priority queue with N items**

implementation	insert	del max	max
unordered array	1	N	N
ordered array	N	1	1
goal	log N	log N	log N

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# Week 4 - Binary Heaps

July 21, 2017 7:17 PM

## Binary Tree

- empty or node with links to left and right binary tree

## Complete Tree

- perfectly balanced except for bottom level
- height of tree with N nodes is floor of  $\lg N$

## Binary Heap

- array implementation of a heap ordered binary tree
  - keys in nodes
  - Parent's key no smaller than children's keys
- indices start at one
- nodes in level order
  - no explicit links needed
- $a[1]$  will be the largest key
- parent of node  $k$  is at  $k/2$
- children of node  $k$  are at  $2k$  and  $2k+1$

## Promotion

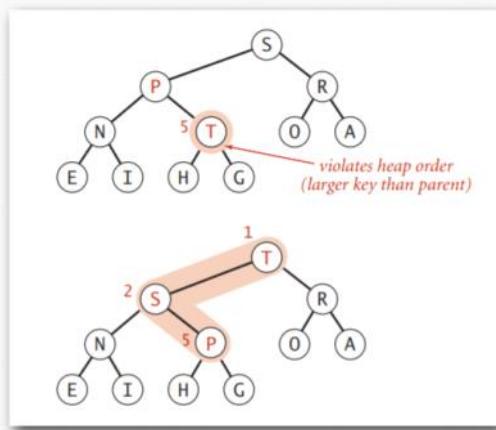
- violates invariants above but then fixes it later
- if a child's key becomes larger than its parent's
  - a value change
- exchange the keys in parent and child
  - keep moving up the tree until the invariant is restored

code (the child swims to the top)

- Repeat until heap order restored.

```
private void swim(int k)
{
    while (k > 1 && less(k/2, k))
    {
        exch(k, k/2);
        k = k/2;
    }
}
```

parent of node at  $k$  is at  $k/2$



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This allows us to insert an element in the heap

- add a new element
- let the element swim up

## Demotion

- if a parent is smaller than its children
- swap with the larger child
- keep moving until invariant is restored

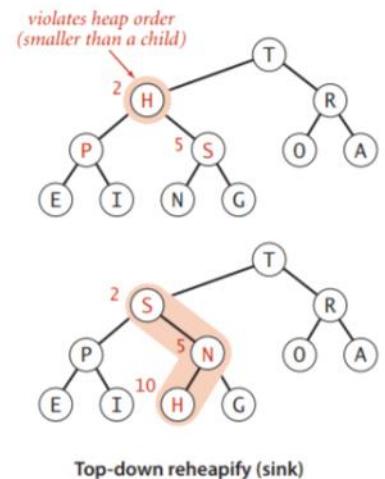
code (the parent sinks to the bottom)

```

private void sink(int k)
{
    while (2*k <= N)
    {
        int j = 2*k;
        if (j < N && less(j, j+1)) j++;
        if (!less(k, j)) break;
        exch(k, j);
        k = j;
    }
}

```

children of node at k  
are  $2k$  and  $2k+1$



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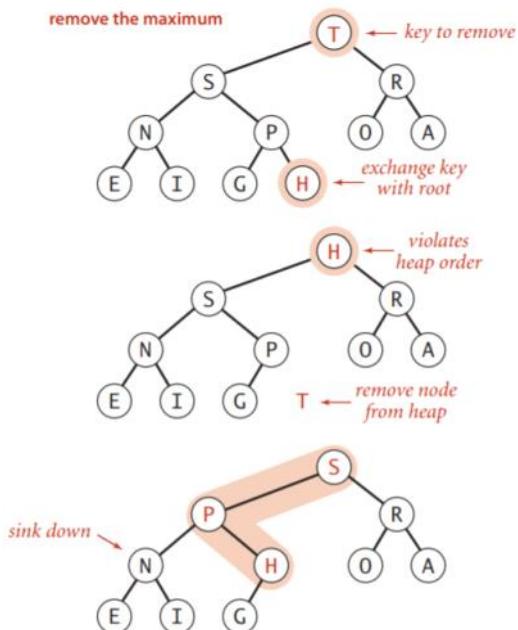
Delete the maximum in a heap

- exchange root with node at end - let it sink down

```

public Key delMax()
{
    Key max = pq[1];
    exch(1, N--);
    sink(1);
    pq[N+1] = null; ← prevent loitering
    return max;
}

```



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## Complete Implementation

```

public class MaxPQ<Key extends Comparable<Key>>
{
    private Key[] pq;
    private int N;

    public MaxPQ(int capacity)
    {   pq = (Key[]) new Comparable[capacity+1]; } ← fixed capacity (for simplicity)

    public boolean isEmpty() ← PQ ops
    {   return N == 0;   }
    public void insert(Key key)
    public Key delMax()
    {   /* see previous code */ }

    private void swim(int k)
    private void sink(int k) ← heap helper functions
    {   /* see previous code */ }

    private boolean less(int i, int j)
    {   return pq[i].compareTo(pq[j]) < 0;   }
    private void exch(int i, int j) ← array helper functions
    {   Key t = pq[i]; pq[i] = pq[j]; pq[j] = t;   }
}

```

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## Cost Summary

**order-of-growth of running time for priority queue with N items**

implementation	insert	del max	max
unordered array	1	N	N
ordered array	N	1	1
binary heap	$\log N$	$\log N$	1
d-ary heap	$\log_d N$	$d \log_d N$	1
Fibonacci	1	$\log N$ †	1
impossible	1	1	1

← why impossible?

† amortized

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## Heap Considerations

- Immutability of keys
  - assuming that client does not change keys while they're using the priority queue
    - **use immutable keys**
- Underflow and Overflow
  - throw exception if deleting from empty PQ
  - add resizing array
- minimum oriented priority queue
- Other options
  - remove arbitrary options
  - Change the priority of an item

### Immutability

- everything in java is a data type
- immutable - can't change the data type once created

### Example:

```

public final class Vector {
    private final int N;
    private final double[] data;

    public Vector(double[] data) {
        this.N = data.length;
        this.data = new double[N];
        for (int i = 0; i < N; i++)
            this.data[i] = data[i];
    }

    ...
}

```

The code snippet shows a class `Vector` with private final instance variables `N` and `data`. A vertical line separates the declaration from the constructor. Several annotations with arrows point to specific parts of the code:

- An arrow points to the `final` keyword in the class declaration with the text "can't override instance methods".
- An arrow points to the `private` and `final` keywords in the variable declarations with the text "all instance variables private and final".
- An arrow points to the assignment in the constructor's loop with the text "defensive copy of mutable instance variables".
- An arrow points to the `final` keyword in the class declaration with the text "instance methods don't change instance variables".

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### Advantages:

- simplifies debugging
- Safer in presence in hostile code

### Disadvantages

- need to create a new object for each data type value

# Week 4 - Heapsort

July 21, 2017 11:08 PM

## Heapsort

- have n keys in array
  - build a max heap
- remove the largest value
- in place sort

## Heap construction

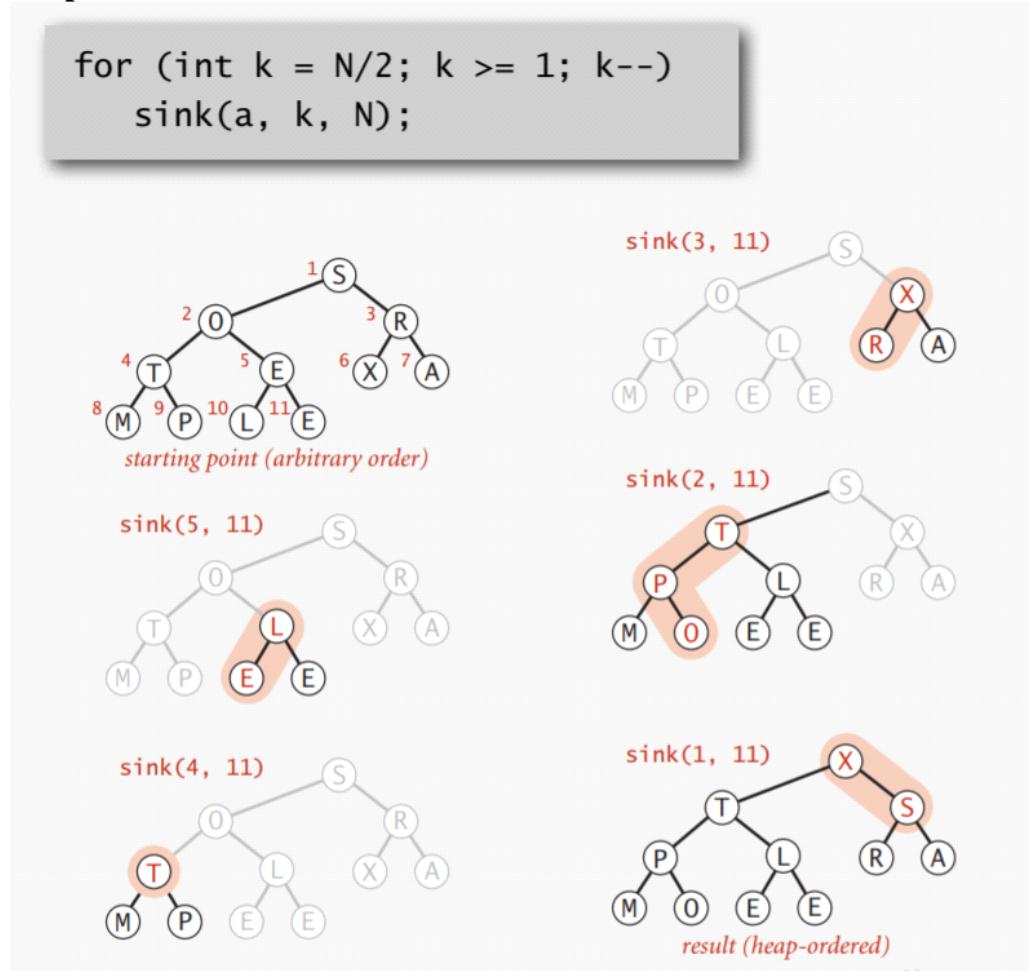
- bottom up construction
  - Start with 1 node heaps at bottom
  - sink the parent of the two nodes at the bottom
  - repeat till you reach the top of the heap

## Sort with heaps

- exchange first and last element
- sink the new first element
- keep going until heap is emptied

## Heap Construction Code

```
for (int k = N/2; k >= 1; k--)  
    sink(a, k, N);
```



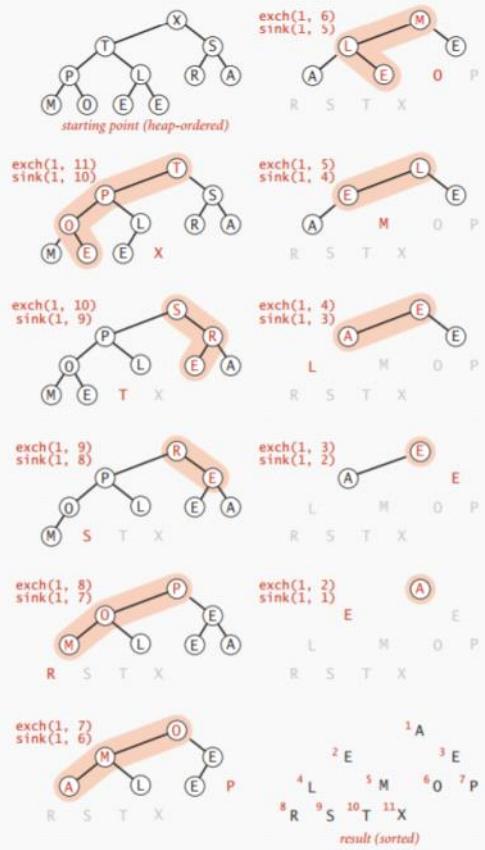
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## Removing the maximum

## Second pass.

- Remove the maximum, one at a time.
- Leave in array, instead of nulling out.

```
while (N > 1)
{
    exch(a, 1, N--);
    sink(a, 1, N);
}
```



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## Total java Implementation

```
public class Heap
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;
        for (int k = N/2; k >= 1; k--)
            sink(a, k, N);
        while (N > 1)
        {
            exch(a, 1, N);
            sink(a, 1, --N);
        }
    }

    private static void sink(Comparable[] a, int k, int N)
    { /* as before */ }

    private static boolean less(Comparable[] a, int i, int j)
    { /* as before */ }

    private static void exch(Comparable[] a, int i, int j)
    { /* as before */ }
}

but convert from
1-based indexing to
0-base indexing
```

## Mathematical Analysis

- construction uses  $2N$  compares and exchanges
- sort uses  $2N\lg N$  compares and exchanges

First in place sorting algorithm with  $N\lg N$  compares in the worst case

Heapsort is optimal for time and space BUT

1. inner loop is longer than quicksort
2. poor use in cache memory
  - a. accesses information far away - quicksort will access information closer
3. not stable

## Summary

	inplace?	stable?	worst	average	best	remarks
selection	x		$N^2 / 2$	$N^2 / 2$	$N^2 / 2$	$N$ exchanges
insertion	x	x	$N^2 / 2$	$N^2 / 4$	N	use for small $N$ or partially ordered
shell	x		?	?	N	tight code, subquadratic
quick	x		$N^2 / 2$	$2N \ln N$	$N \lg N$	$N \log N$ probabilistic guarantee fastest in practice
3-way quick	x		$N^2 / 2$	$2N \ln N$	N	improves quicksort in presence of duplicate keys
merge		x	$N \lg N$	$N \lg N$	$N \lg N$	$N \log N$ guarantee, stable
heap	x		$2N \lg N$	$2N \lg N$	$N \lg N$	$N \log N$ guarantee, in-place
???	x	x	$N \lg N$	$N \lg N$	$N \lg N$	holy sorting grail

# Week 4 - Symbol Table APIs

July 22, 2017 12:25 AM

## Symbol Tables

- insert a value with a specific key
- given a key, search for the corresponding value
  - key-value pair

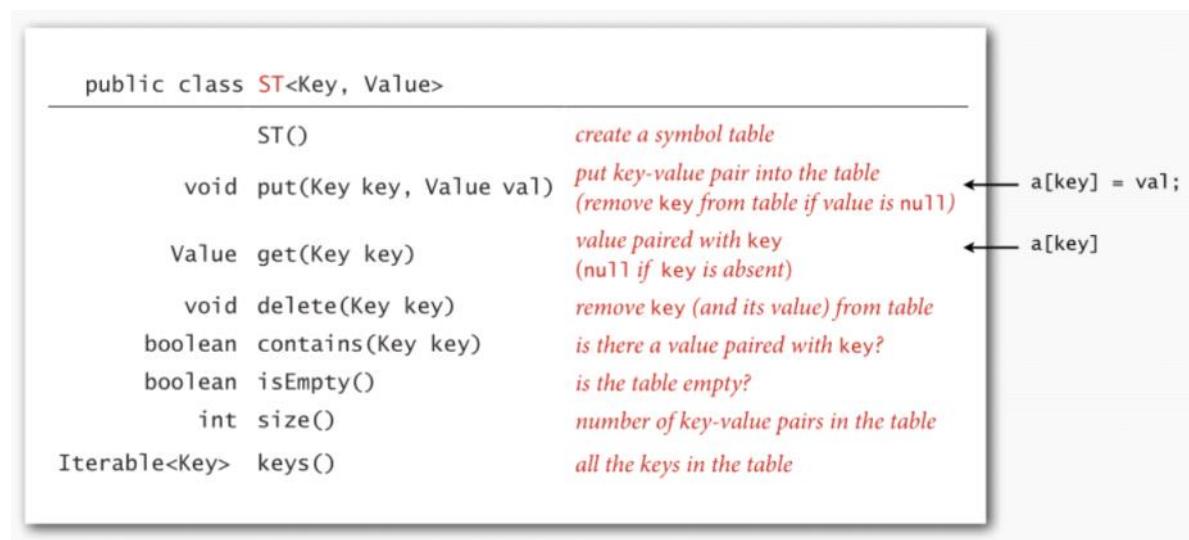
Ex.

DNS lookup.

- insert URL with IP address
- Given URL find the IP address

## Basic Symbol Table API

- associative array abstraction
- Associate one value with each key
  - the key is the index - value is the value
    - key may not be an integer however - it is generic in our case



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## Conventions:

- Values are not null
- get() returns null if key not present
- put() overwrites old value with new value
- makes it so the contains() is the same
  - return get(key) != null
- implement lazy version of delete()
  - put(key,null)

Values: any generic type

## Key: - natural assumptions

- are comparable
- if can't be comparable
  - any generic type - use equals() to test equality
    - use hash code to scramble key (stay tuned)

## Best Practice

- immutable types for symbol table keys

## Equality test

- all Java classes inherit a method equals()
- in Java this method is defaulted to is the references equal
  - not practical for general uses

**Java requirements.** For any references x, y and z:

- Reflexive: `x.equals(x)` is true.
- Symmetric: `x.equals(y)` iff `y.equals(x)`.
- Transitive: if `x.equals(y)` and `y.equals(z)`, then `x.equals(z)`.
- Non-null: `x.equals(null)` is false.

} equivalence relation

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## Implementation

Seems easy, but requires some care.

typically unsafe to use equals() with inheritance  
(would violate symmetry)

```
public final class Date implements Comparable<Date>
{
    private final int month;
    private final int day;
    private final int year;
    ...

    public boolean equals(Object y)
    {
        if (y == this) return true;           ← optimize for true object equality

        if (y == null) return false;         ← check for null

        if (y.getClass() != this.getClass())
            return false;                  ← objects must be in the same class
                                              (religion: getClass() vs. instanceof)

        Date that = (Date) y;
        if (this.day != that.day) return false;
        if (this.month != that.month) return false;   ← cast is guaranteed to succeed
        if (this.year != that.year) return false;       ← check that all significant
                                                       fields are the same
        return true;
    }
}
```

must be Object.  
Why? Experts still debate.

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## Equals Design (same as picture above)

- optimization for reference
- check against null
- two objects are the same type and cast
- Compare each significant field
  - if field is primitive type use `==`
  - if it is an object use `equals()`
    - apply rule recursively
  - array

- i. apply to each entry

## Best Practices

- fields that are most likely to differ compare first
- make compareTo() comply with equals()

## Implementation - indexing client

Build ST by associating value  $i$  with  $i^{th}$  string from standard input.

```
public static void main(String[] args)
{
    ST<String, Integer> st = new ST<String, Integer>();
    for (int i = 0; !StdIn.isEmpty(); i++)
    {
        String key = StdIn.readString();
        st.put(key, i);
    }
    for (String s : st.keys())
        StdOut.println(s + " " + st.get(s));
}
```

	output
A	8
C	4
E	12
H	5
L	11
M	9
P	10
R	3
S	0
X	7

keys	S	E	A	R	C	H	E	X	A	M	P	L	E
values	0	1	2	3	4	5	6	7	8	9	10	11	12

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## Frequency Client

- read a sequence of strings from standard input
  - print the one that occurs with highest frequency

```
public class FrequencyCounter
{
    public static void main(String[] args)
    {
        int minlen = Integer.parseInt(args[0]);
        ST<String, Integer> st = new ST<String, Integer>(); ← create ST
        while (!StdIn.isEmpty())
        {
            String word = StdIn.readString();
            if (word.length() < minlen) continue; ← ignore short strings
            if (!st.contains(word)) st.put(word, 1);
            else st.put(word, st.get(word) + 1);
        }
        String max = "";
        st.put(max, 0);
        for (String word : st.keys())
            if (st.get(word) > st.get(max))
                max = word;
        StdOut.println(max + " " + st.get(max));
    }
}
```

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# Week 4 - Elementary Symbol Table Implementations

July 23, 2017 1:51 PM

1. Maintain an unordered linked list of key value pairs
  - a. Search: Scan through all keys to find a match
  - b. Insert: Scan through all keys to find a match - if no match add to front
2. Binary search in an ordered array
  - a. Have parallel arrays of keys and values
  - b. maintain keys in ordered order
    - i. get index via binary search and use the index to get value
  - c. Rank help function
    - i. how many keys are less than k?
  - d. Code:

```
public Value get(Key key)
{
    if (isEmpty()) return null;
    int i = rank(key);
    if (i < N && keys[i].compareTo(key) == 0) return vals[i];
    else return null;
}

private int rank(Key key)                                number of keys < key
{
    int lo = 0, hi = N-1;
    while (lo <= hi)
    {
        int mid = lo + (hi - lo) / 2;
        int cmp = key.compareTo(keys[mid]);
        if      (cmp < 0) hi = mid - 1;
        else if (cmp > 0) lo = mid + 1;
        else if (cmp == 0) return mid;
    }
    return lo;
}
```

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- rank is binary search
- to insert a key we need to shift everything over
  - anything you do with the key array has to be done with the vals array

## Summary of the two methods:

ST implementation	worst-case cost (after N inserts)		average case (after N random inserts)		ordered iteration?	key interface
	search	insert	search hit	insert		
sequential search (unordered list)	N	N	N / 2	N	no	equals()
binary search (ordered array)	log N	N	log N	N / 2	yes	compareTo()

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- we need an efficient implementation of both sort and insert

# Week 4 - Ordered Operations

July 23, 2017 3:51 PM

When keys are comparable and ordered

- has more operations available

## Wider Interface:

public class ST<Key extends Comparable<Key>, Value>	
ST()	<i>create an ordered symbol table</i>
void put(Key key, Value val)	<i>put key-value pair into the table (remove key from table if value is null)</i>
Value get(Key key)	<i>value paired with key (null if key is absent)</i>
void delete(Key key)	<i>remove key (and its value) from table</i>
boolean contains(Key key)	<i>is there a value paired with key?</i>
boolean isEmpty()	<i>is the table empty?</i>
int size()	<i>number of key-value pairs</i>
Key min()	<i>smallest key</i>
Key max()	<i>largest key</i>
Key floor(Key key)	<i>largest key less than or equal to key</i>
Key ceiling(Key key)	<i>smallest key greater than or equal to key</i>
int rank(Key key)	<i>number of keys less than key</i>
Key select(int k)	<i>key of rank k</i>
void deleteMin()	<i>delete smallest key</i>
void deleteMax()	<i>delete largest key</i>
int size(Key lo, Key hi)	<i>number of keys in [lo..hi]</i>
Iterable<Key> keys(Key lo, Key hi)	<i>keys in [lo..hi], in sorted order</i>
Iterable<Key> keys()	<i>all keys in the table, in sorted order</i>

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## Costs of all the operations:

	sequential search	binary search
search	N	$\lg N$
insert / delete	N	N
min / max	N	1
floor / ceiling	N	$\lg N$
rank	N	$\lg N$
select	N	1
ordered iteration	$N \lg N$	N

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- sequential search is linked list

We need a faster way to insert/delete values - Binary Search Trees

# Week 4 - Binary Search Trees

July 23, 2017 4:03 PM

Allows us to perform efficient symbol table operations

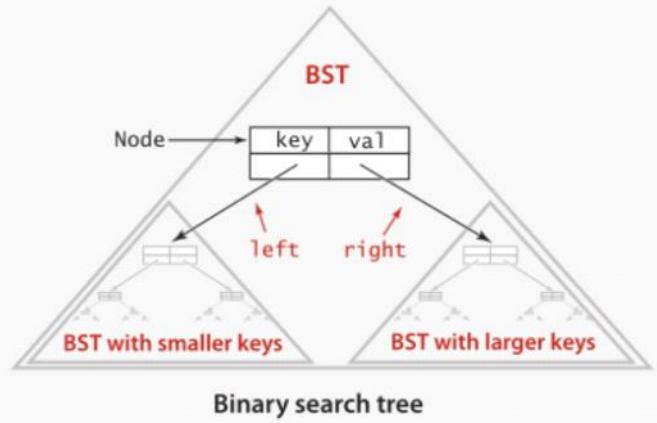
## Binary Search Tree

- explicit tree structure (implicit is for example, heap trees)
- binary tree in symmetric order
  - each node has a key and every node's key is
    - larger than all keys in its left subtree
    - smaller than all the keys in its right subtree
  - the parent is the value in-between each subtree

## Representation in Java

- extend linked list implementation
  - BST is a reference to a root node
    - key
    - value
    - reference to a right and left subtree

```
private class Node
{
    private Key key;
    private Value val;
    private Node left, right;
    public Node(Key key, Value val)
    {
        this.key = key;
        this.val = val;
    }
}
```



Key and Value are generic types; Key is Comparable

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- left and right nodes are initialized as null

## Implementation:

```
public class BST<Key extends Comparable<Key>, Value>
{
    private Node root;                                ← root of BST

    private class Node
    { /* see previous slide */ }

    public void put(Key key, Value val)
    { /* see next slides */ }

    public Value get(Key key)
    { /* see next slides */ }

    public void delete(Key key)
    { /* see next slides */ }

    public Iterable<Key> iterator()
    { /* see next slides */ }

}
```

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### Search (get()):

- if less go left
- if more go right
- if equal then the search is complete
- for an unsuccessful search,
  - no more tree
    - search miss

### Insert

- search tree until you get to the null link
  - replace null link with the inserted node

### Get Implementation:

```

public Value get(Key key)
{
    Node x = root;
    while (x != null)
    {
        int cmp = key.compareTo(x.key);
        if      (cmp < 0) x = x.left;
        else if (cmp > 0) x = x.right;
        else if (cmp == 0) return x.val;
    }
    return null;
}

```

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### Put:

- if key is in tree - reset value
- if key is not in tree - add new node
- Recursive implementation
  - as you go down the tree, return a link to higher up in the tree
  - to fix the links

```

public void put(Key key, Value val)
{   root = put(root, key, val);  }

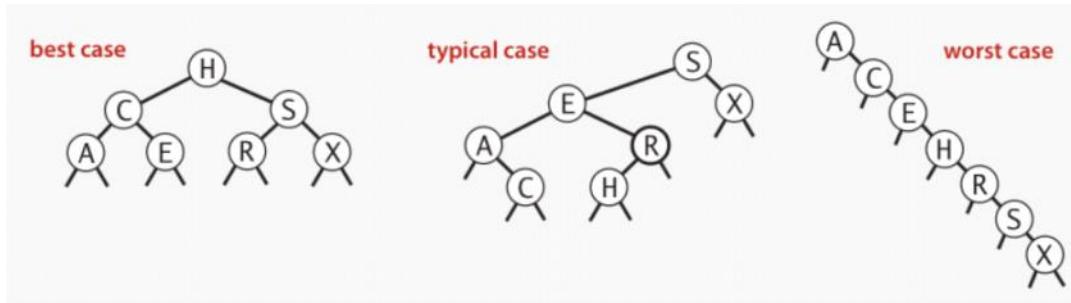
private Node put(Node x, Key key, Value val)
{
    if (x == null) return new Node(key, val);
    int cmp = key.compareTo(x.key);
    if      (cmp < 0)
        x.left = put(x.left,  key, val);
    else if (cmp > 0)
        x.right = put(x.right, key, val);
    else if (cmp == 0)
        x.val = val;
    return x;
}

```

concise, but tricky,  
recursive code;  
read carefully!

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- Many different binary search trees that have the same keys
  - depend on the order of insertions



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### Binary search tree and quicksort partitioning

- 1-1 correspondence if no duplicates
  - same as quicksort
- worst case =  $4\ln N$ 
  - **keep in mind that worst case for binary search is N**
    - no random

implementation	guarantee		average case		ordered ops?	operations on keys
	search	insert	search hit	insert		
sequential search (unordered list)	N	N	N/2	N	no	equals()
binary search (ordered array)	$\lg N$	N	$\lg N$	$N/2$	yes	compareTo()
BST	N	N	$1.39 \lg N$	$1.39 \lg N$	next	compareTo()

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- next refers to next few lectures

# Week 4 - Ordered Operations in Binary Search Trees

July 23, 2017 4:39 PM

## Minimum Key

- the most left key

## Maximum Key

- the most right key

## Floor/ Ceiling (same concept)

**Case 1.** [ $k$  equals the key at root]

The floor of  $k$  is  $k$ .

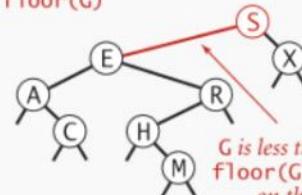
**Case 2.** [ $k$  is less than the key at root]

The floor of  $k$  is in the left subtree.

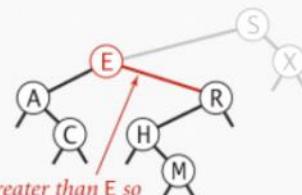
**Case 3.** [ $k$  is greater than the key at root]

The floor of  $k$  is in the right subtree  
(if there is any key  $\leq k$  in right subtree);  
otherwise it is the key in the root.

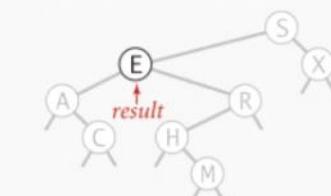
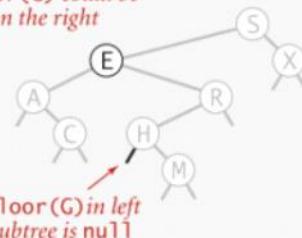
**finding floor( $G$ )**



*G is less than S so  
floor(G) must be  
on the left*



*G is greater than E so  
floor(G) could be  
on the right*



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**Code:**

```

public Key floor(Key key)
{
    Node x = floor(root, key);
    if (x == null) return null;
    return x.key;
}
private Node floor(Node x, Key key)
{
    if (x == null) return null;
    int cmp = key.compareTo(x.key);

    if (cmp == 0) return x;

    if (cmp < 0) return floor(x.left, key);

    Node t = floor(x.right, key);
    if (t != null) return t;
    else return x;
}

```

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## Rank/Select

- subtree counts
  - keep a field which is the number of subtrees that it contains (including itself)
- size - count at root

## Implementation (subtree count):

```

private class Node
{
    private Key key;
    private Value val;
    private Node left;
    private Node right;
    private int count;
}

```

number of nodes in subtree

```

public int size()
{   return size(root);  }

private int size(Node x)
{
    if (x == null) return 0;
    return x.count;      ok to call
                        when x is null
}

```

```

private Node put(Node x, Key key, Value val)
{
    if (x == null) return new Node(key, val, 1);
    int cmp = key.compareTo(x.key);
    if (cmp < 0) x.left = put(x.left, key, val);
    else if (cmp > 0) x.right = put(x.right, key, val);
    else if (cmp == 0) x.val = val;
    x.count = 1 + size(x.left) + size(x.right);
    return x;
}

```

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## Rank with subtree counts

- recursive algorithm
- to find number of keys less than k
  - if key is equal to key at current node
    - size of left subtree
  - if key is less than the root
    - return the rank of the left subtree
  - if key is greater
    - return 1+ size of left subtree and the rank of the right subtree

```
public int rank(Key key)
{  return rank(key, root);  }

private int rank(Key key, Node x)
{
    if (x == null) return 0;
    int cmp = key.compareTo(x.key);
    if      (cmp < 0) return rank(key, x.left);
    else if (cmp > 0) return 1 + size(x.left) + rank(key, x.right);
    else if (cmp == 0) return size(x.left);
}
```

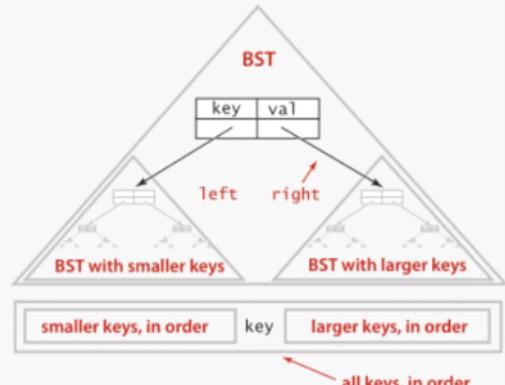
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## Iteration (inorder traversal)

- traverse left subtree
- enqueue key
- Traverse right subtree

```
public Iterable<Key> keys()
{
    Queue<Key> q = new Queue<Key>();
    inorder(root, q);
    return q;
}

private void inorder(Node x, Queue<Key> q)
{
    if (x == null) return;
    inorder(x.left, q);
    q.enqueue(x.key);
    inorder(x.right, q);
}
```



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## Summary

	sequential search	binary search	BST
search	N	$\lg N$	$h$
insert	N	N	$h$
min / max	N	1	$h$
floor / ceiling	N	$\lg N$	$h$
rank	N	$\lg N$	$h$
select	N	1	$h$
ordered iteration	$N \log N$	N	N

$h = \text{height of BST}$   
 (proportional to  $\log N$   
 if keys inserted in random order)

#### order of growth of running time of ordered symbol table operations

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# Week 4 - Deletion in Binary Search Tables

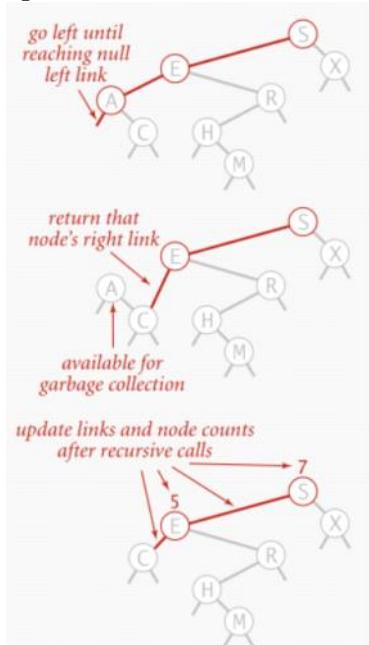
July 23, 2017 6:20 PM

## Deletion : Lazy Approach

- set value to null
- leave key in tree to guide searches
- will keep insert search and delete logarithmic
- memory overload

## Deleting the Minimum

- go left until a node with a null left link
- replace that node with its right link
- update counts



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## Code:

```
public void deleteMin()
{   root = deleteMin(root);  }

private Node deleteMin(Node x)
{
    if (x.left == null) return x.right;
    x.left = deleteMin(x.left);
    x.count = 1 + size(x.left) + size(x.right);
    return x;
}
```

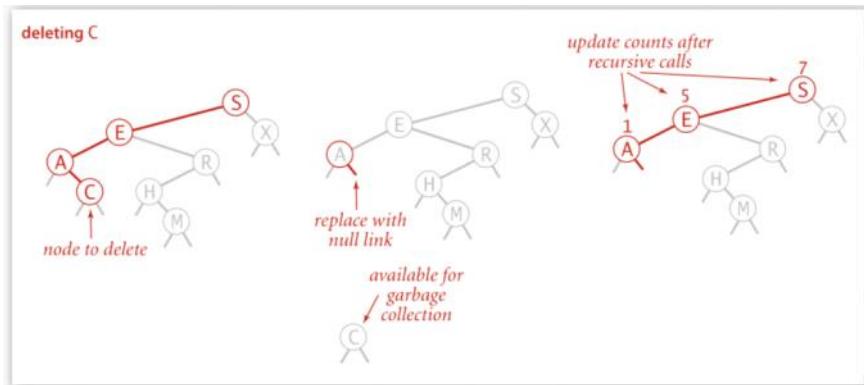
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- also works for max

## Hibbard Deletion

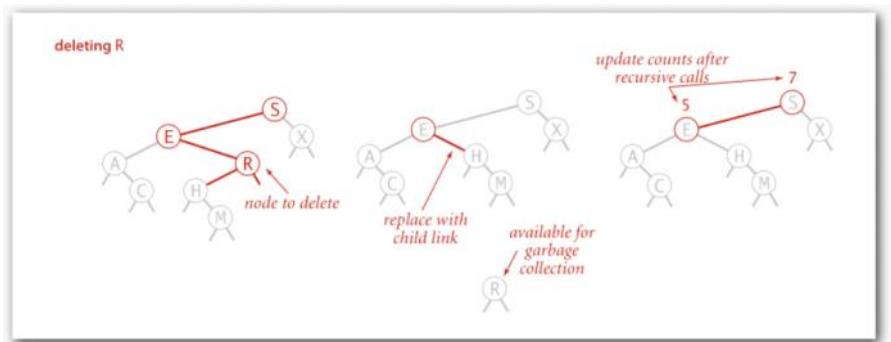
- to delete node with key k
  - search for node t containing k

- Case 1 : 0 Children
  - delete t by setting the link to it to null
  - update counts



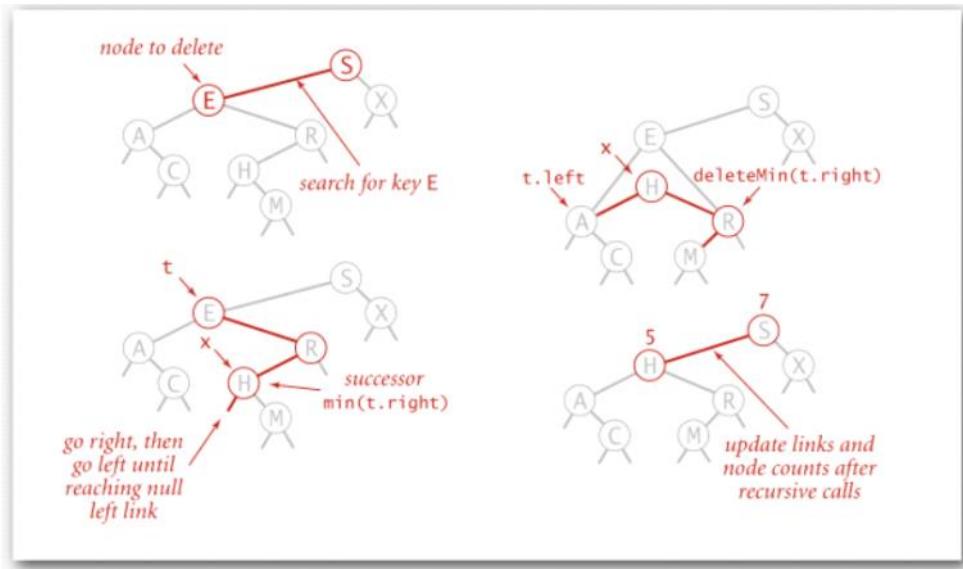
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- Case 2: 1 Child
  - replace parent link
    - bypass the node by setting the link to the child to t's child instead of t
  - update counts



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- Case 3: 2 Children
  - Find the next smallest node in the right subtree
    - (x)
      - store the value of the next smallest node
      - delete that node
      - replace t with that node
  - Update counts



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### Code:

```

public void delete(Key key)
{   root = delete(root, key);  }

private Node delete(Node x, Key key) {
    if (x == null) return null;
    int cmp = key.compareTo(x.key);
    if      (cmp < 0) x.left  = delete(x.left,  key);           ← search for key
    else if (cmp > 0) x.right = delete(x.right, key);
    else {
        if (x.right == null) return x.left;                      ← no right child
        if (x.left  == null) return x.right;                     ← no left child
        Node t = x;
        x = min(t.right);
        x.right = deleteMin(t.right);
        x.left = t.left;                                       ← replace with successor
    }
    x.count = size(x.left) + size(x.right) + 1;             ← update subtree counts
    return x;
}

```

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### Disadvantages:

- the trees become not balanced
  - because we are only taking from the right
- after a long sequence of removes and inserts
  - height becomes  $\sqrt{N}$

### Summary:

implementation	guarantee			average case			ordered iteration?	operations on keys
	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	N	N	N	N/2	N	N/2	no	equals()
binary search (ordered array)	lg N	N	N	lg N	N/2	N/2	yes	compareTo()
BST	N	N	N	1.39 lg N	1.39 lg N	✓N	yes	compareTo()


 other operations also become  $\sqrt{N}$   
 if deletions allowed

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# Week 4- Programming Assignment

July 25, 2017 5:14 PM

- when a method returns an iterable object
  - array list or linkedlist
    - array list is better for searching - not as good for when adding or removing a lot of elements
    - linked list is better for removing and adding elements but not for searching
- when working with size() in a for loop make sure the size stays consistent or store the size in a value beforehand

# Week 5 - Balanced Search Trees

July 28, 2017 9:40 PM

Binary search trees are average logarithmic

- we want a data structure that is guaranteed logarithmic
  - 2-3 trees
  - left leaning red-black BST
  - B-trees

## 2-3 Tree

- allow 1 or 2 keys per node
  - two node - one key two children
  - three node - two key three children
    - less
    - between
    - greater
- Perfect Balance
  - every path from root to the null link has the same length
- Symmetric Order
  - in order transversal yields keys in ascending order

## Search

- compare search key against keys in node
- find interval containing search key
- follow associated link

## Insert (2- node at bottom)

- search for key
- replace two node with three node

## Insert (3- node at bottom)

- add new key to 3-node to make temp 4-node
- move middle key in 4- node into parent
  - leaving two 2-nodes
- If the node at the root is a 3-node add to make 4-node and split into three 2-nodes
  - the middle value in the 4-node becomes the root of a 2-node
  - height of tree increases by 1

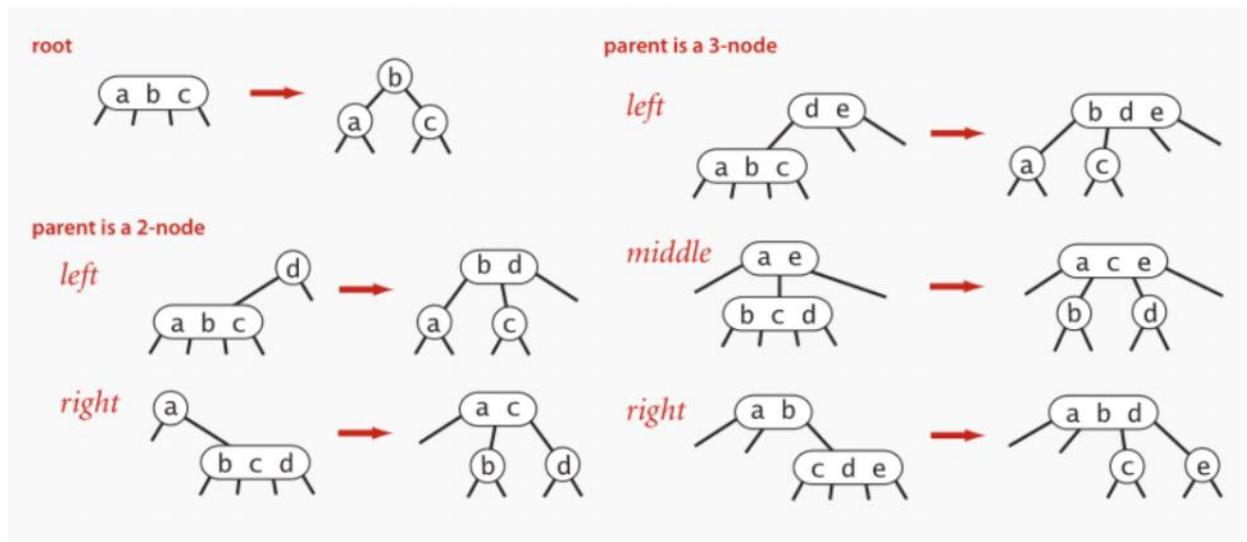
## Local Transformations

- splitting a 4-node is a local transformation
  - constant number of operations
- we don't touch anything above or below the nodes that are undergoing the transformation

## Global Properties

- Invariants
  - maintains symmetric order and perfect balance
  - all operations maintains symmetric order and perfect balance

## All Operations:



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All operations have time proportional to the height of the tree - since the height is the same for all nodes,

- we have guaranteed logarithmic performance for search and insert

Summary:

implementation	worst-case cost (after N inserts)			average case (after N random inserts)			ordered iteration?	key interface
	search	insert	delete	search hit	insert	delete		
sequential search (unordered list)	N	N	N	N/2	N	N/2	no	equals()
binary search (ordered array)	$\lg N$	N	N	$\lg N$	N/2	N/2	yes	compareTo()
BST	N	N	N	$1.39 \lg N$	$1.39 \lg N$	?	yes	compareTo()
2-3 tree	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	$c \lg N$	yes	compareTo()

*constants depend upon implementation*

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Implementation:

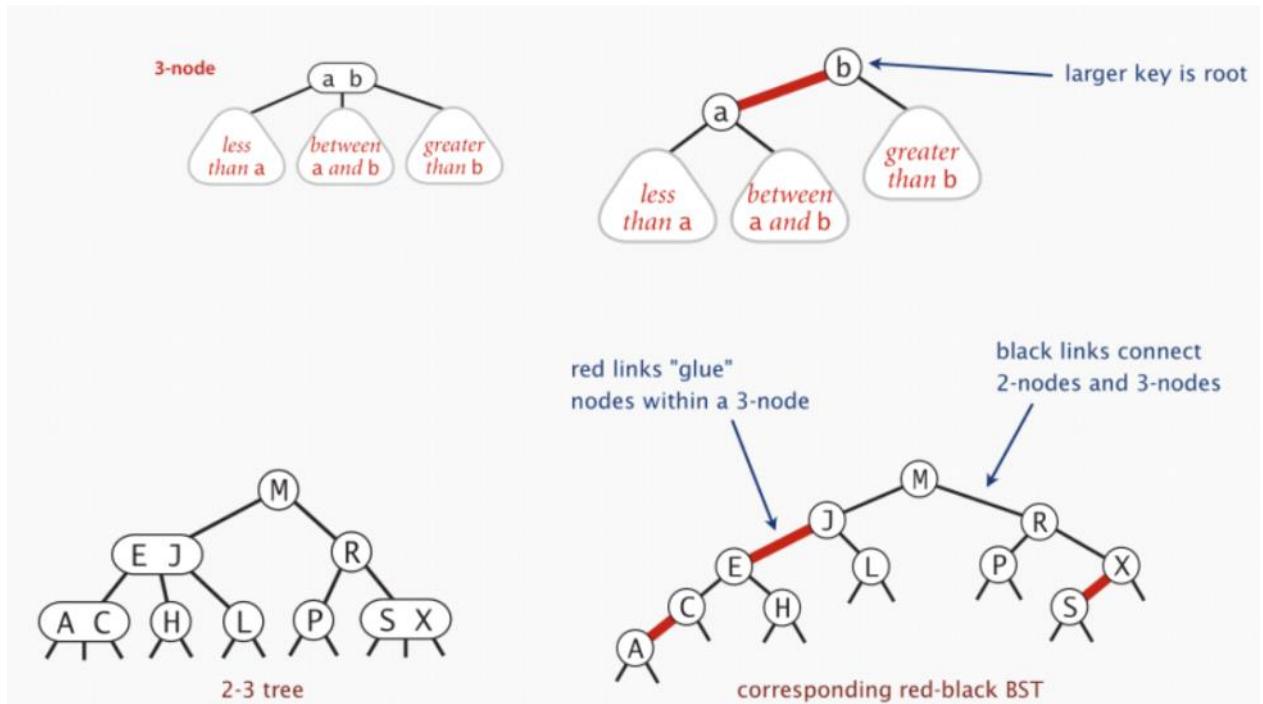
- direct implementation is complicated
  - lots of cases to consider
- possible but much easier way is possible
- is used as a model

# Week 5 - Red Black BST's

July 29, 2017 11:22 AM

Allows us to implement 2-3 trees using existing binary search tree code

- represent 2-3 tree BST
  - left leaning
- need simple representation for 3-nodes
  - use internal left leaning links as "glue" for 3-nodes



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## Definition:

- no node has two red links
- every path from root has same amount of black links
  - perfect black balance
- red links lean left

## Search

- search is the same as elementary BST
  - ignore color
  - runs faster because of better balance

```
public Val get(Key key)
{
    Node x = root;
    while (x != null)
    {
        int cmp = key.compareTo(x.key);
        if      (cmp < 0) x = x.left;
        else if (cmp > 0) x = x.right;
        else if (cmp == 0) return x.val;
    }
    return null;
}
```

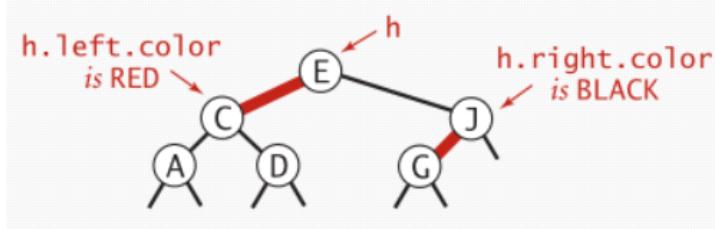
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Most of the operations are the same for elementary BST

- but runs faster because of balance

### Red-Black Representation

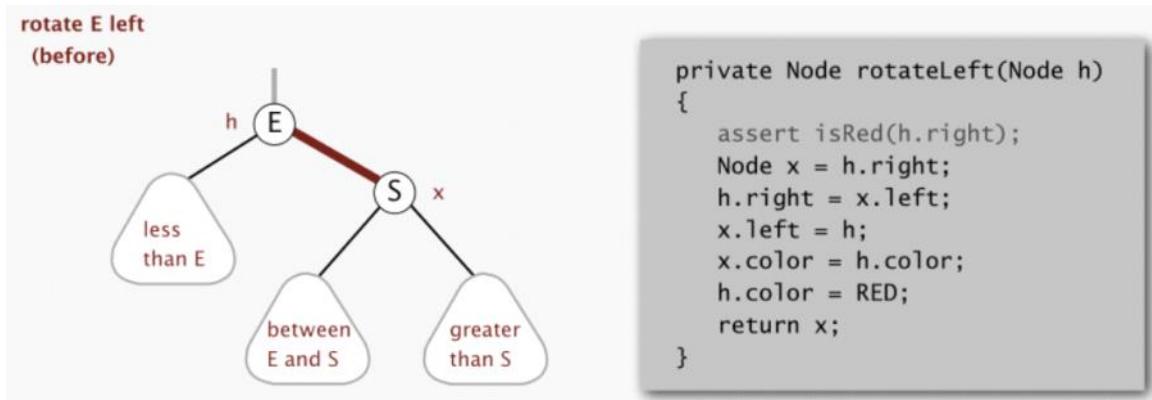
- each node is pointed by one link from its parent
- can encode color in the child node
- null links are black



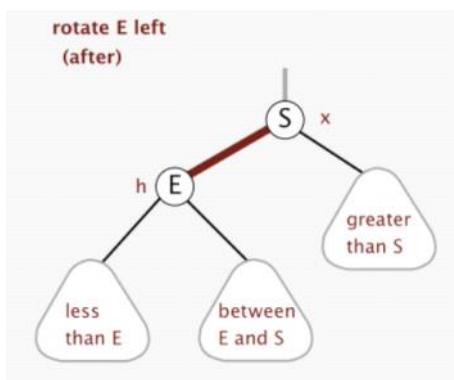
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Rotations:

- sometimes red links lean in the wrong direction(right)
  - we need to perform a left rotation
  - make a right leaning red to a left leaning



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- all local transformations

### Right Leaning Rotations

We may sometimes need to take a left leaning link and make it lean right

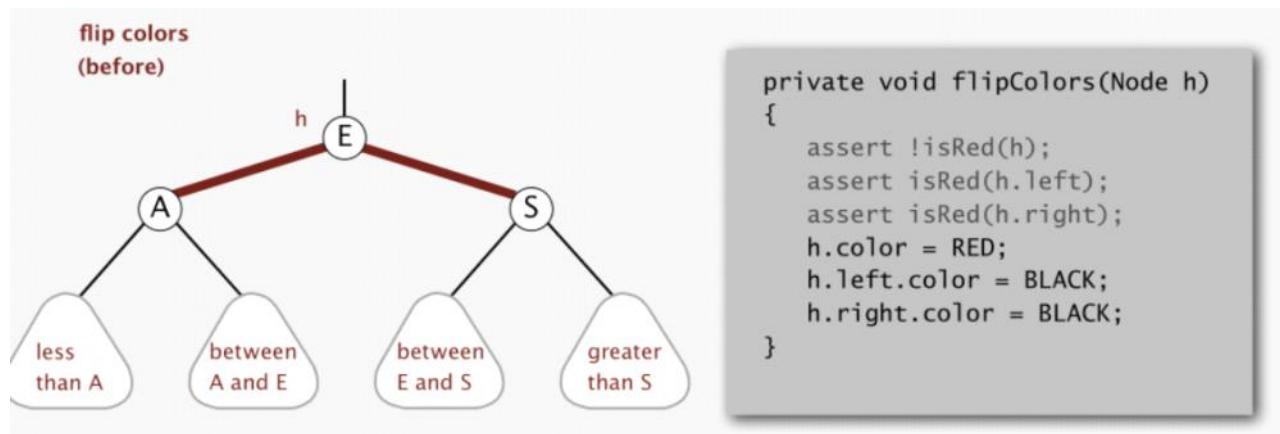
- temporarily for insertion

```
private Node rotateRight(Node h)
{
    assert isRed(h.left);
    Node x = h.left;
    h.left = x.right;
    x.right = h;
    x.color = h.color;
    h.color = RED;
    return x;
}
```

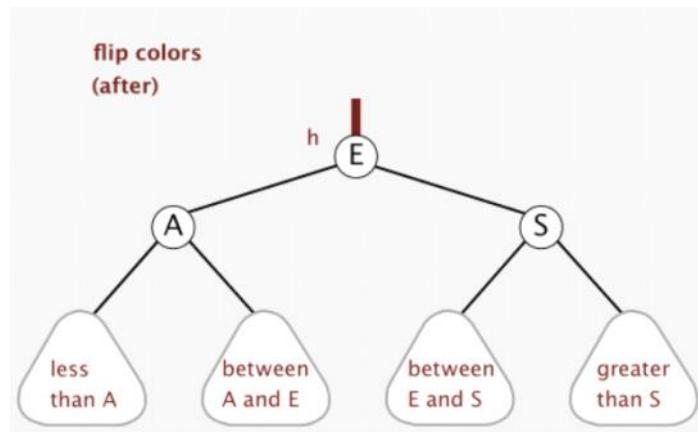
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### Color Flip

- node with two red links
  - temporary 4-node
- split and pass center node to the root
- only change colors



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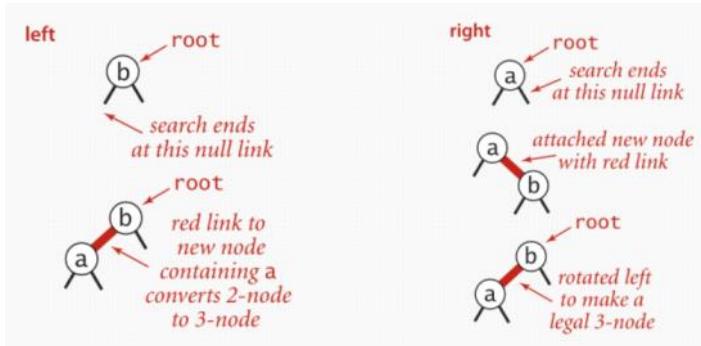
### Basic Strategy

- maintain 1-1 correspondence with 2-3 trees by applying red black BST operations(above)

## Insert

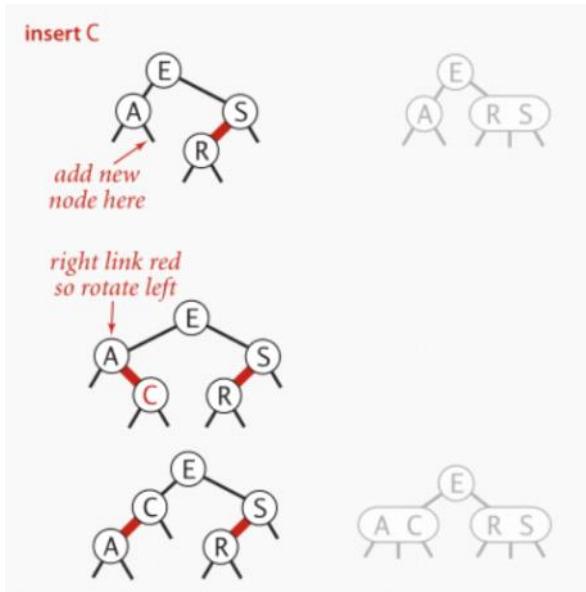
When inserting, we insert with red link to the parent

### Insert into tree with only one node



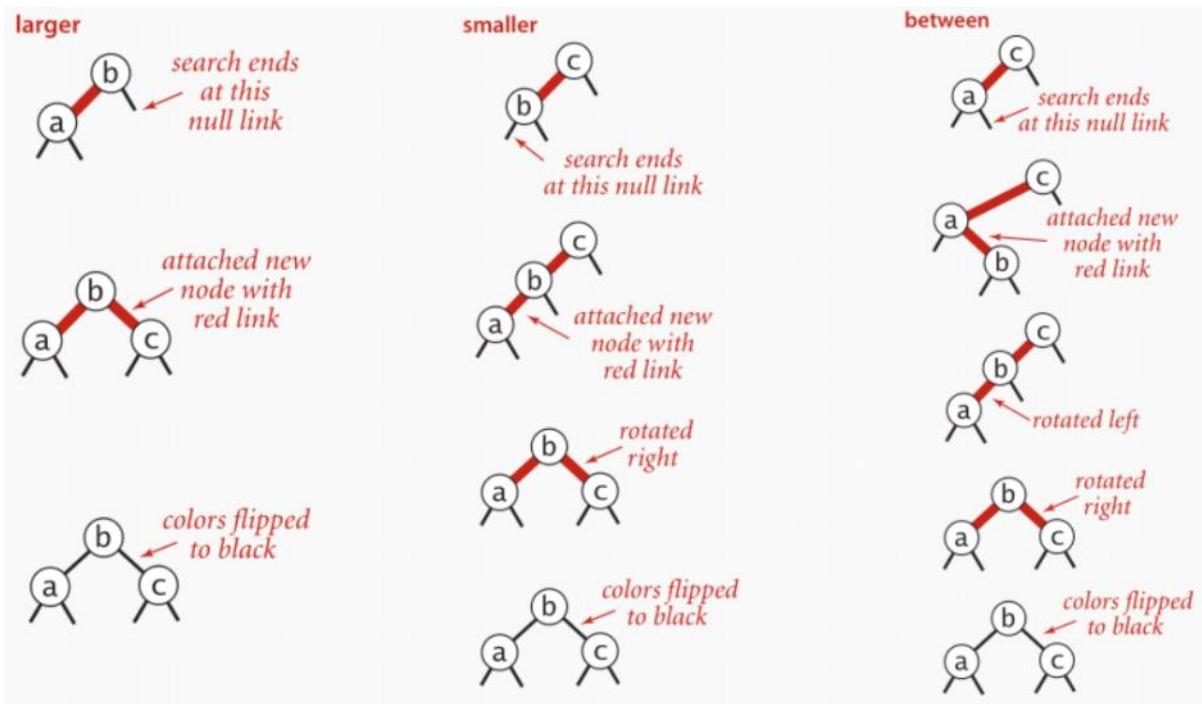
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### Insert into a 2-node at bottom



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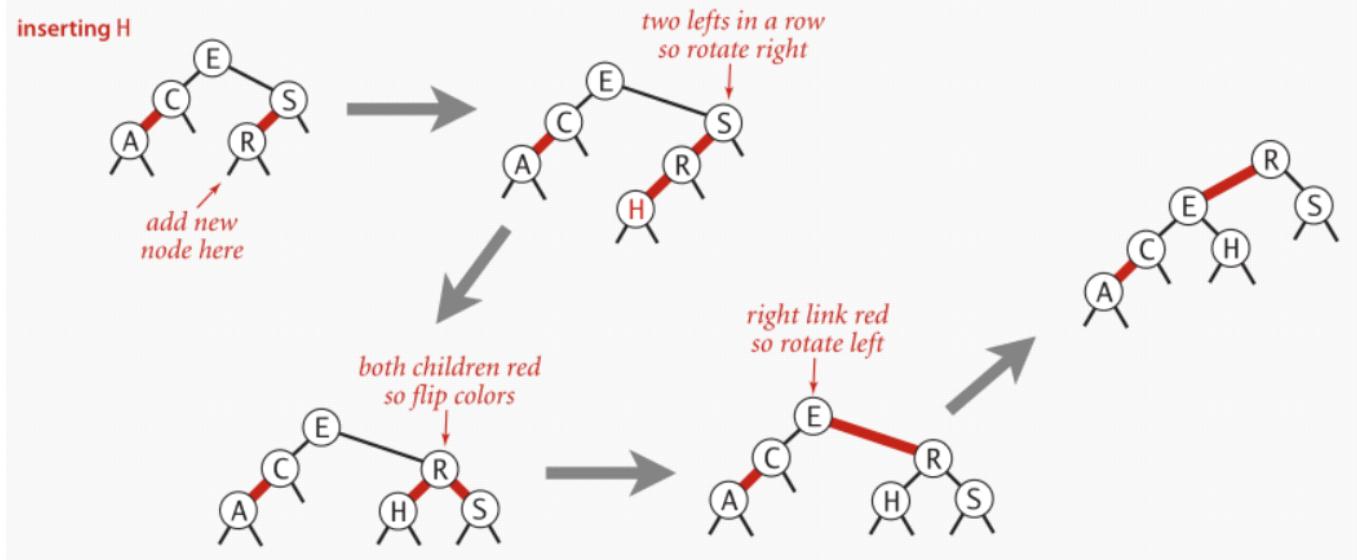
### Insert into tree with 2 nodes



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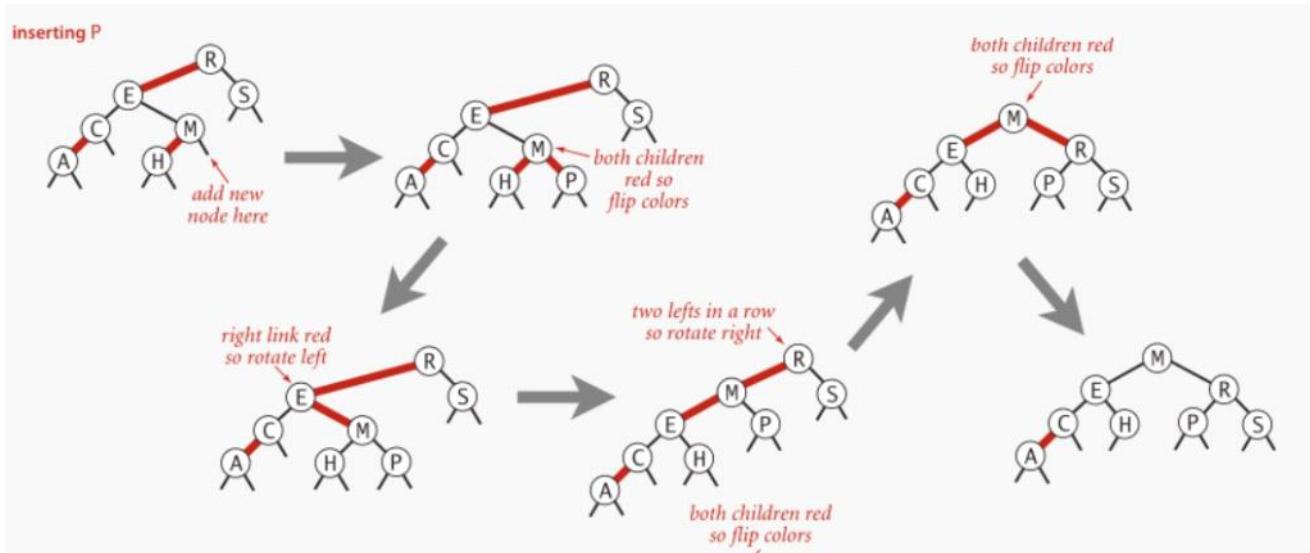
### Insert into a 3 node at bottom

- standard BST insert (red link)
- rotate to balance 4-node (if needed)
- flip colors to pass red link
- rotate to make lean left (if needed)
- We passed a red link up
  - repeat case 1 or 2 up the tree (if needed)
    - (passing a red link up into a 3-node)



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Passing red links up in the tree



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### Insert Implementation

- Same code handles all cases
  - right child red, left child black
    - rotate left
  - left child red, left left grandchild red
    - rotate right
  - both children red
    - flip

```
private Node put(Node h, Key key, Value val)
{
    if (h == null) return new Node(key, val, RED);
    int cmp = key.compareTo(h.key);
    if (cmp < 0) h.left = put(h.left, key, val);
    else if (cmp > 0) h.right = put(h.right, key, val);
    else if (cmp == 0) h.val = val;

    if (isRed(h.right) && !isRed(h.left)) h = rotateLeft(h);
    if (isRed(h.left) && isRed(h.left.left)) h = rotateRight(h);
    if (isRed(h.left) && isRed(h.right)) flipColors(h);

    return h;
}
```

only a few extra lines of code provides near-perfect balance

insert at bottom  
(and color it red)

lean left

balance 4-node

split 4-node

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Height of tree is guaranteed  $2\lg N$  in the worst case

- height of tree is  $\sim \lg N$  in typical applications

### Summary

implementation	worst-case cost (after N inserts)			average case (after N random inserts)			ordered iteration?	key interface
	search	insert	delete	search hit	insert	delete		
sequential search (unordered list)	N	N	N	N/2	N	N/2	no	equals()
binary search (ordered array)	lg N	N	N	lg N	N/2	N/2	yes	compareTo()
BST	N	N	N	1.39 lg N	1.39 lg N	?	yes	compareTo()
2-3 tree	c lg N	c lg N	c lg N	c lg N	c lg N	c lg N	yes	compareTo()
red-black BST	2 lg N	2 lg N	2 lg N	1.00 lg N <sup>*</sup>	1.00 lg N <sup>*</sup>	1.00 lg N <sup>*</sup>	yes	compareTo()

\* exact value of coefficient unknown but extremely close to 1

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# Week 5 - B trees (red black applications)

July 29, 2017 2:35 PM

## B-trees

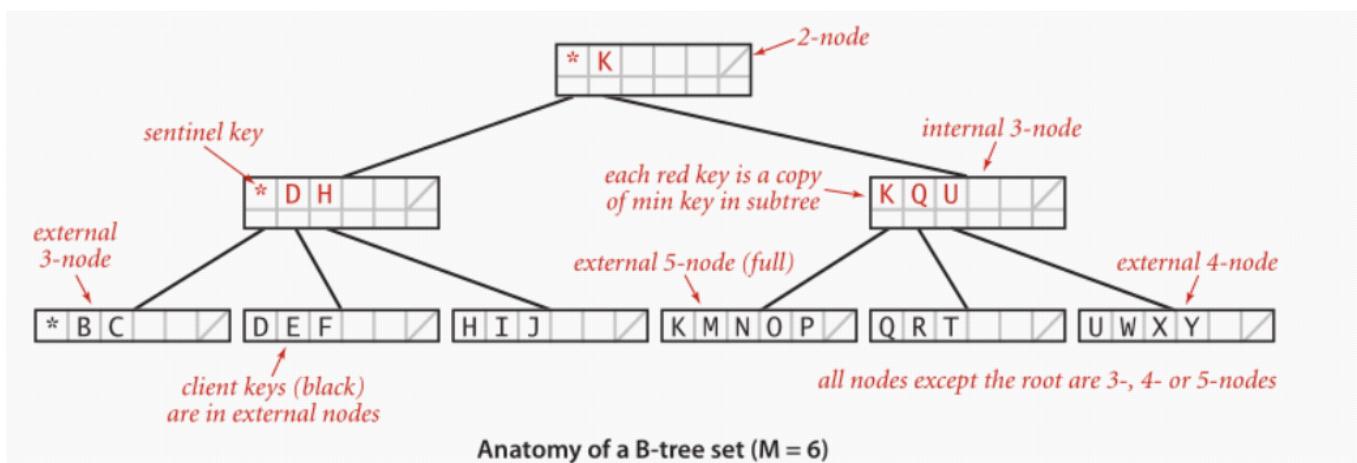
- general version

## File System

- we have large data files
- Probing in the hard drive is the bottleneck operation
  - once first accessed we can access information in the page very fast
- the cost model is based on the number of probes
- the goal of file systems is to access data using minimum number of probes

## B-Tree

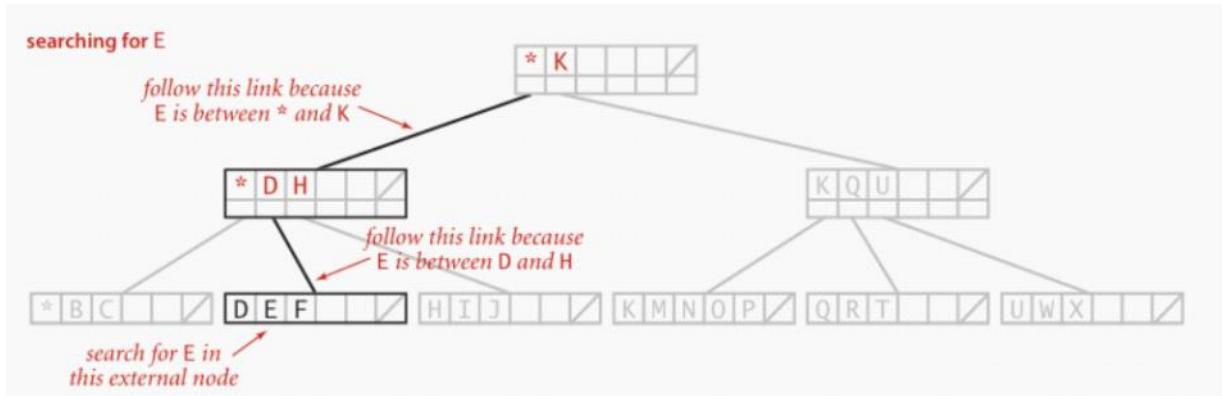
- generalize 2-3 trees by allowing  $M-1$  key link pairs per node
  - at least 2 key link pairs at root
  - at least  $M/2$  key link pairs in other nodes
  - external nodes contain client keys
    - sorted order
    - when inserting into a full external node the node splits
      - splits in two -  $M/2 - M$  link pairs
  - internal nodes contain copies of keys to guide search



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## Search

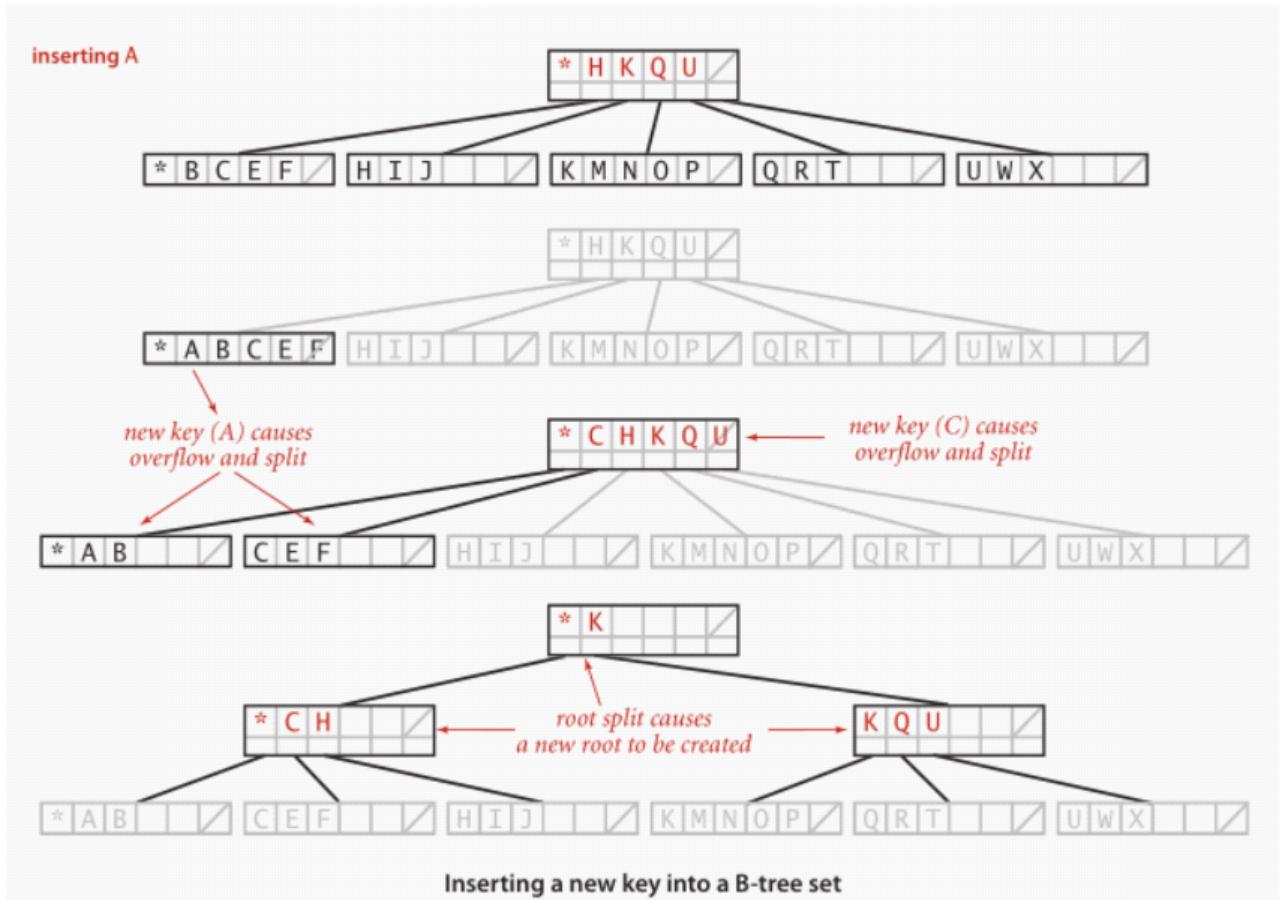
- start at root
- find interval and follow link
- search terminates at an external node



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## Insert

- search for new key
- insert at bottom
- split nodes with M keys on the way up the tree



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## Balance in B-trees

- a search or insertion in a B tree with order M with N keys requires between  $\log_M(N)$  and  $\log_{M/2}(N)$
- all internal nodes have between  $M/2$  and  $M-1$  links
- In practice, max probes are 4 or 5

# Week 5 - 1d Range Search

July 29, 2017 3:07 PM

Intersections among geometric objects

- how many points in rectangle
- how many intersections between rectangles
- etc

**Binary search trees and more are very efficient solutions**

**Extension of ordered symbol table**

- insert key-value pair
- search for key k
- delete key k
- Range search
  - find all keys between  $k_1$  and  $k_2$
- Range count
  - number of keys between  $k_1$  and  $k_2$

**Geometric Interpretation**

- keys are points on line
  - find/count points on the line

Keep keys in a BST

- use rank function
  - we can compute how many keys between  $k_1$  and  $k_2$

```
public int size(Key lo, Key hi)
{
    if (contains(hi)) return rank(hi) - rank(lo) + 1;
    else               return rank(hi) - rank(lo);
}
```

↑ number of keys < hi

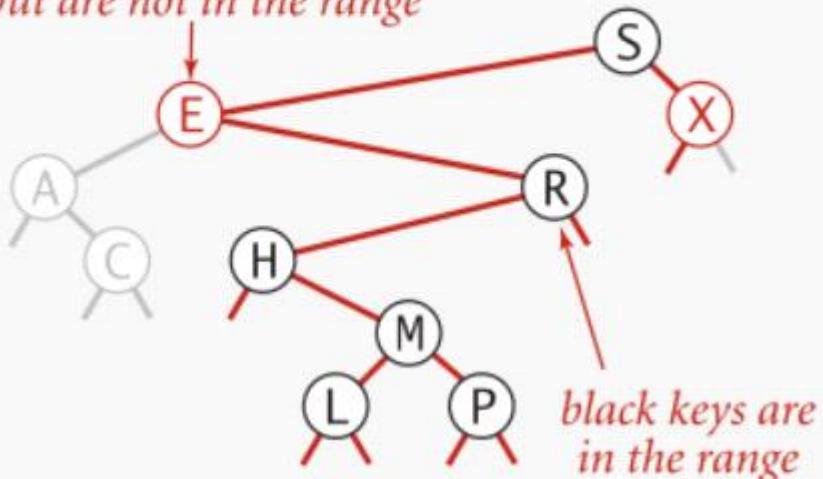
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**1d Range search**

- find all keys between  $lo$  and  $hi$ 
  - recursively find all keys in left subtree(if any fall in range)
  - check key in current node
  - recursively find all keys in right subtree( if any fall in range)

## searching in the range [F..T]

*red keys are used in compares  
but are not in the range*



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**proportional to  $R + \log N$**

# Week 5 - Line Segment Intersection

July 29, 2017 3:54 PM

## Orthogonal Line Segment Intersection Search

- all lines are either vertical or horizontal
- find all places where they intersect

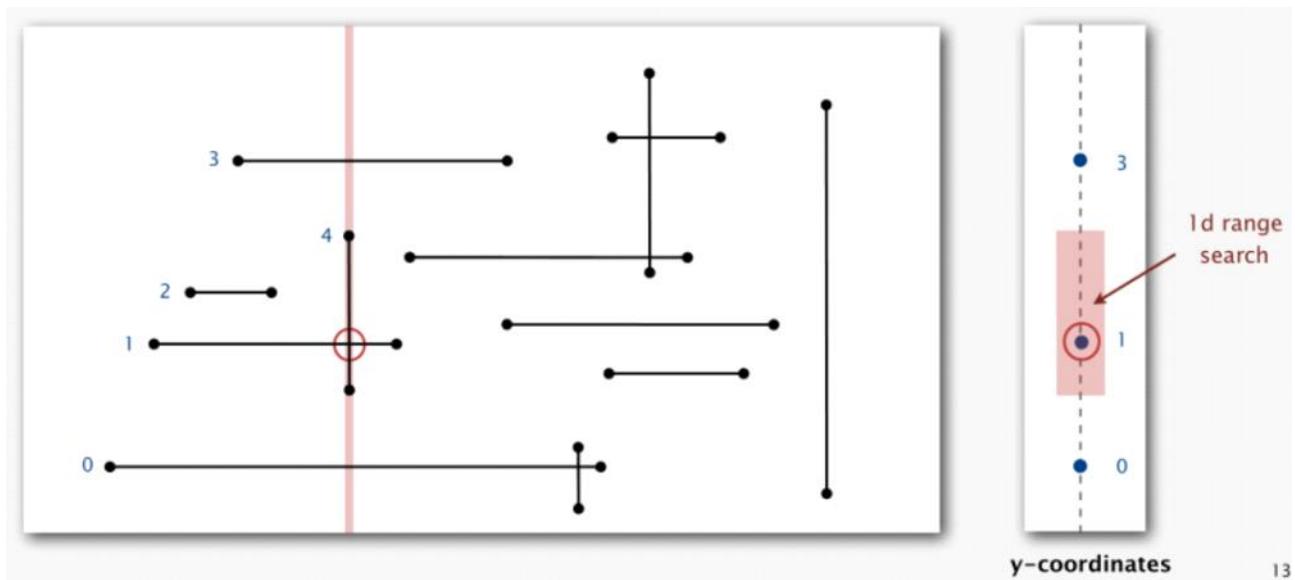
Brute force - quadratic algorithm

- check all pairs of line segments for intersections

\*Assumption! all x and y coordinates are distinct

## Sweep Line Algorithm

- sweep vertical line from left to right
  - x- coordinates define events
  - horizontal segment(left endpoint)
    - insert y coordinate into BST
  - horizontal segment(right endpoint)
    - remove y coordinate from BST
  - vertical segment
    - range search for y endpoints



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# Week 5 - kd Trees

July 29, 2017 4:07 PM

## 2-d Orthogonal range search

- insert a 2d key
- search for a 2d key
- range search
- range count

## Geometric Interpretation

- keys are points
- find/count points in a h-v rectangle

## Grid Implementation

- divide space into  $M \times M$  grid of squares
- create list of points contained in each square
- 2d array to directly index square
- add(x,y) to the corresponding square
- Range search examine only squares that intersect 2d range query
  - deal only with the perimeter of the rectangle
  - all squares fully inside will be counted as in range
- Space -  $M^2 + N$
- Time  $1 + N/M^2$ 
  - per square
- We need to manage the size of M
  - $M = \sqrt{N}$

## Running Time (assuming data is random)

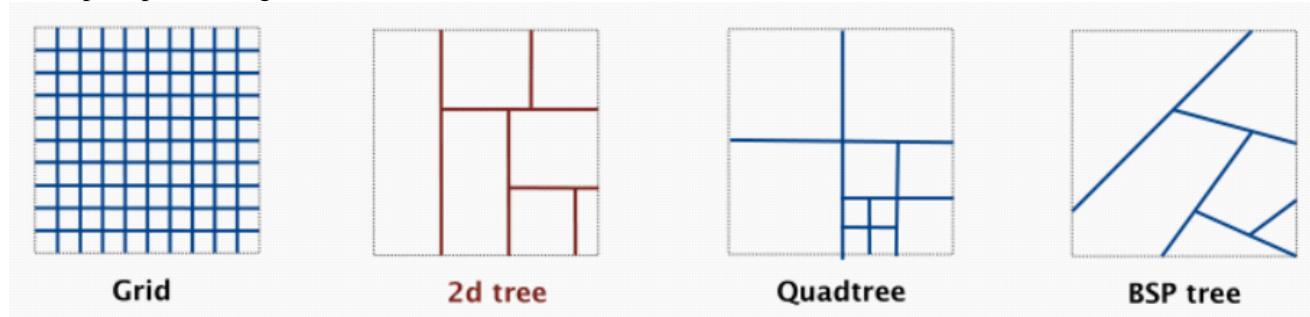
- initialize -  $N$
- Insert - 1
- Range Search - 1 per point in range

## Good although often times the points are clustered

- list of points in each square will be too big

Use a tree to represent a recursive subdivision of 2d space

- space partitioning trees



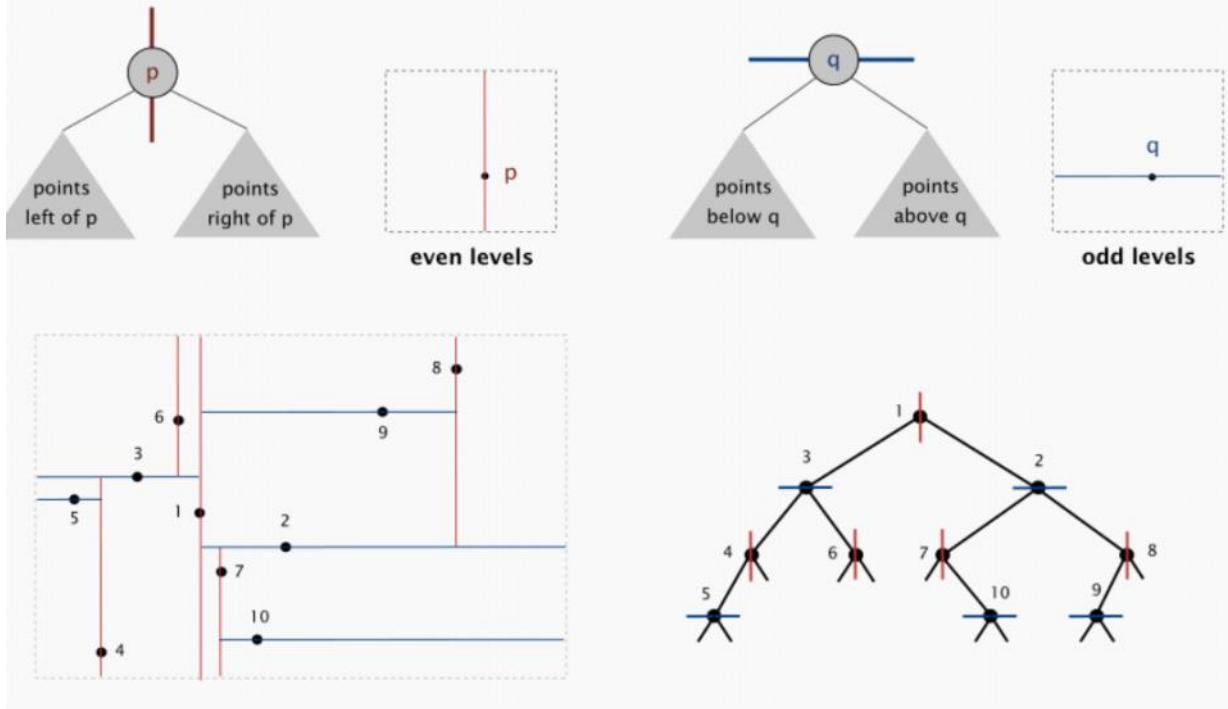
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## 2d Tree

- recursively partitioning the plane
- all the points to the left(tree wise) of a point are left/below(geometrically) and vice versa
- The first node is vertically partitioned
  - 2nd level is horizontally partitioned
    - odd = vertical even = horizontal

**Left/below = left child ----- Right/above = right child**

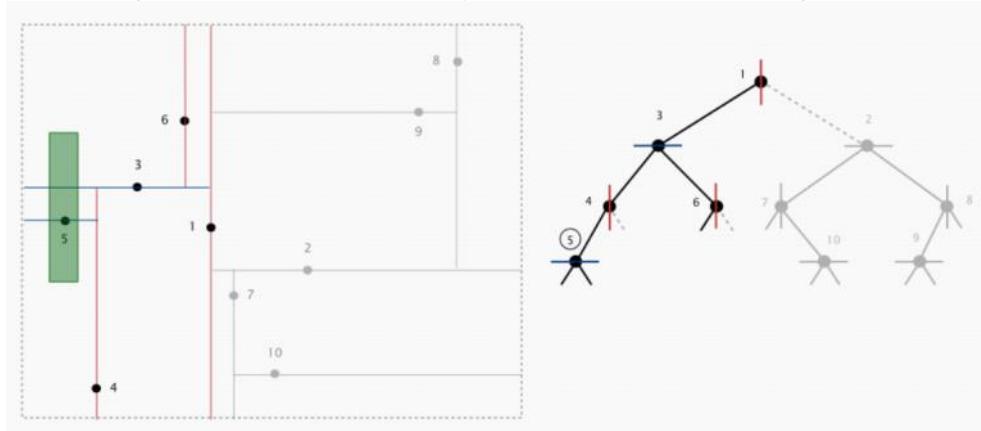
- Search gives rectangle containing point.
- Insert further subdivides the plane.



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### Range Search

- check if point in node lies in rectangle
- recursively search left/bottom
- recursively search right/top
- If the rectangle **does not intersect** a partitioning line (given by the points)
  - we move down the tree
    - if the rectangle is in the area left, we move to the left child
    - if to the right, we move to the right child
- If the rectangle **does intersect** a partitioning line,
  - we have to search both subtrees (start with left)
  - goes down the tree recursively until hits null links following the rules above



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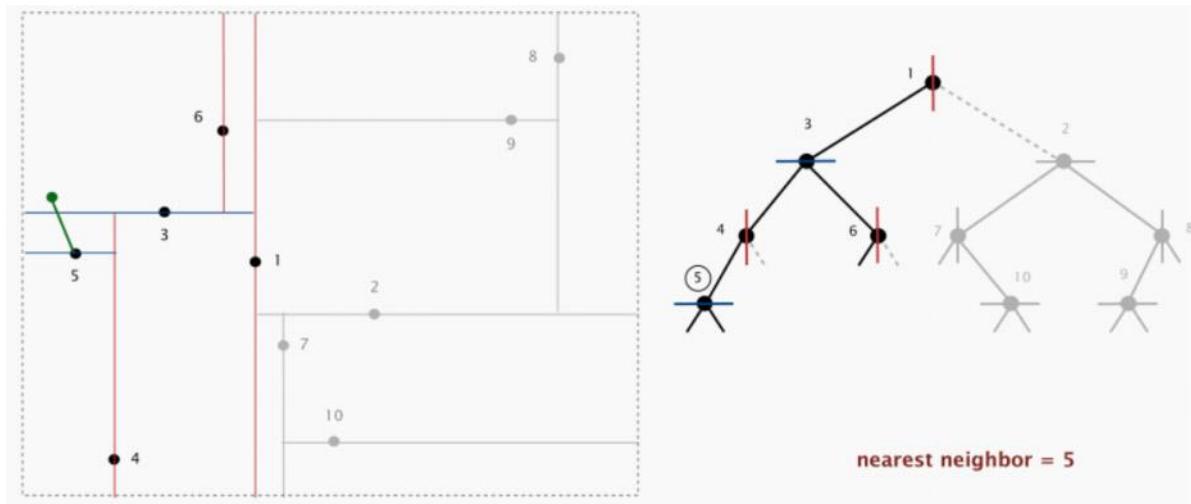
### Running Time

- proportional to  $R + \log N$  (typically)
- $R + \sqrt{N}$  (worst case)

### Nearest Neighbor Search

- find closest point to query point

- check distance from point to query point
- recursively search left/bottom
- recursively search right/top
- method begins by searching for query point
- we move toward the query point first
- if a new closest point is found
  - it becomes the new "champion"



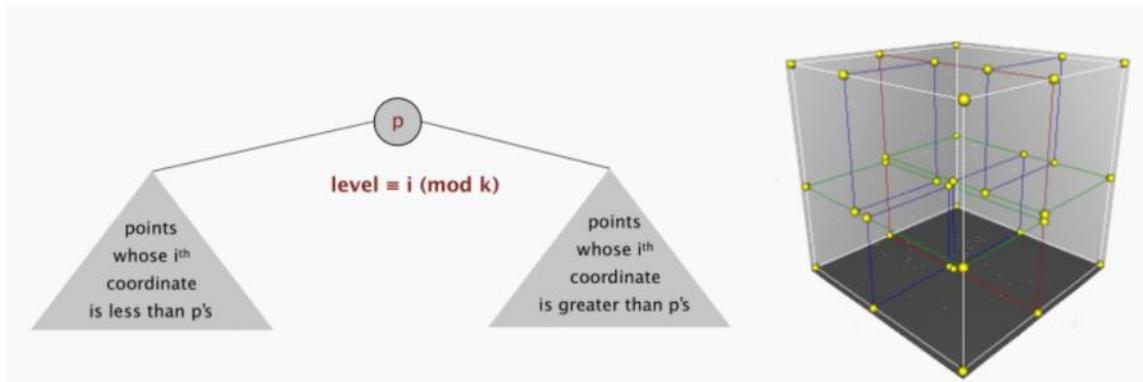
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#### Running Time

- Typical Case
  - $\log N$
- Worst Case
  - $N$

Expands to multiple dimensions (kd tree - k dimensions)

- partition k dimensions
  - 1 dimension at a time



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# Week 5 - Interval Search Trees

July 29, 2017 7:01 PM

## 1d Interval search

- instead of point objects we have intervals

We need to support the operations:

- insert
- search
- delete
- interval intersection query
  - given an interval find all intervals that intersects that interval

\*Assumption!

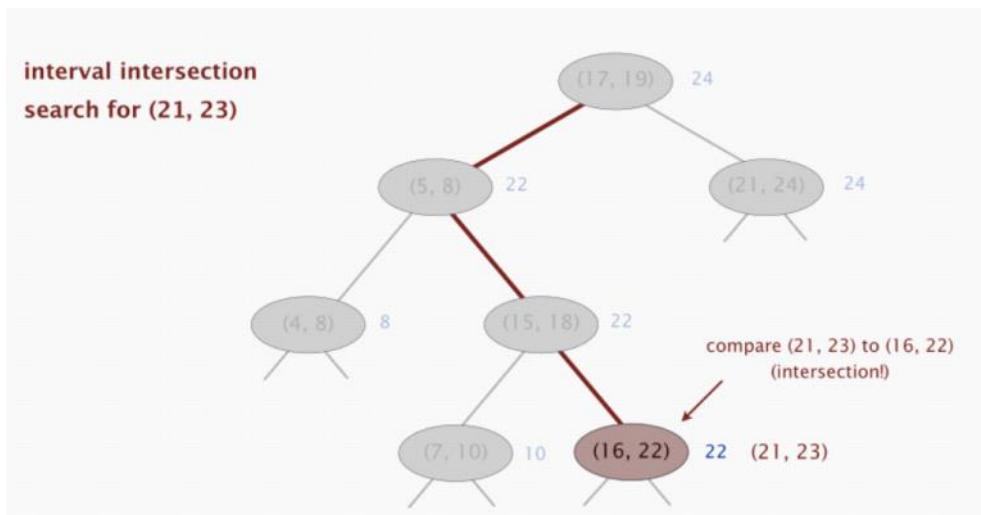
- no two intervals have the same left endpoint

## Search Tree Data Structure

- use left endpoint as BST key
- store max endpoint in subtree rooted at node

## Insert

- insert using lo as key
- update max in each node



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## Search (any interval that intersects query)

- if interval in node intersects query interval
  - return
- if left subtree is null go right
- if max endpoint in left subtree is less than lo go right
- else go left
- until hit null at right

## Implementation

```

Node x = root;
while (x != null)
{
    if      (x.interval.intersects(lo, hi)) return x.interval;
    else if (x.left == null)                  x = x.right;
    else if (x.left.max < lo)                x = x.right;
    else                                      x = x.left;
}
return null;

```

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Analysis - use red black to guarantee performance

operation	brute	interval search tree	best in theory
insert interval	1	$\log N$	$\log N$
find interval	N	$\log N$	$\log N$
delete interval	N	$\log N$	$\log N$
find <b>any one</b> interval that intersects $(lo, hi)$	N	$\log N$	$\log N$
find <b>all</b> intervals that intersects $(lo, hi)$	N	$R \log N$	$R + \log N$

**order of growth of running time for N intervals**

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# Week 5- Rectangle Intersection

July 29, 2017 7:16 PM

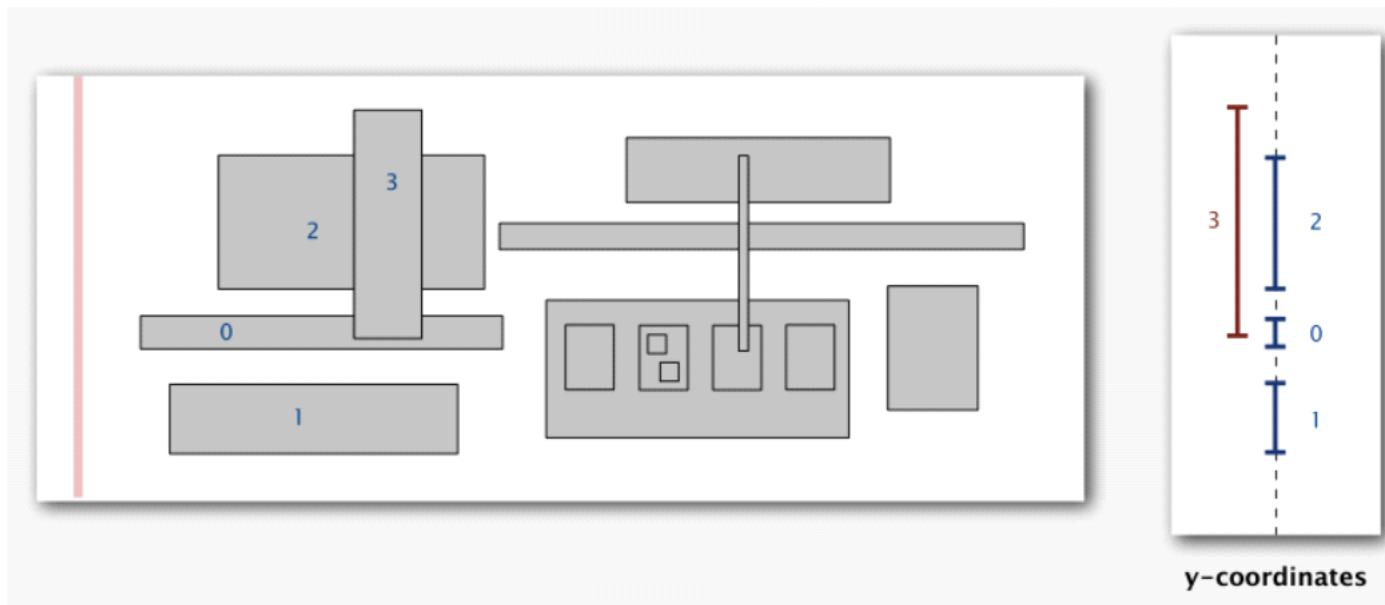
**Goal:** find all intersections among a set of N orthogonal rectangles

- Brute force
  - quadratic

\*Assumption! - all coordinates are distinct

## Sweep vertical line from left to right

- x coordinate of interval defines events
- maintain set of rectangles that intersect the sweep line in an interval search tree (using y coordinate)
- left endpoint (vertical line)
  - interval search for y-interval of rectangle
  - insert y-interval
- right endpoint (vertical line)
  - remove y-interval



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## Analysis

Pf.

- Put x-coordinates on a PQ (or sort).  $\leftarrow N \log N$
- Insert y-intervals into ST.  $\leftarrow N \log N$
- Delete y-intervals from ST.  $\leftarrow N \log N$
- Interval searches for y-intervals.  $\leftarrow N \log N + R \log N$

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# Week 5 - Programming assignment

August 3, 2017 11:19 AM

in kdtree if we define being colinear as greater, make sure to make this consistent through the program

- in this case it was the put method

check for an already existing point being inserted again

# Week 6 - Hash Tables

August 4, 2017 12:13 PM

## Way to implement symbol tables

- we can do better than R-B tree
  - different access
  - no ordered operations

## Hashing

- Save items in a key indexed table (index is a function of the key)
- Hash function - method for computing array from key

## Issues

- computing the hash function
- equality test - method for checking whether two keys are equal
- Collision Resolution
  - two values hash to the same array index

## Implementation

- ideally
  - scramble keys uniformly to produce a table index
- efficiently computable
- each table equally likely for each key
- need a different approach for each key type
- all java classes have a method hashCode()
  - returns a 32 bit int
- REQUIREMENT
  - if  $e.equals(y)$  then  $(x.hashCode() == y.hashCode())$
- Highly Desirable
  - if  $\neg e.equals(y)$  then  $(x.hashCode() \neq y.hashCode())$
- Default implementation
  - Memory address

Implementing Hash Code: integers, booleans and doubles

### Java library implementations

```
public final class Integer
{
    private final int value;
    ...

    public int hashCode()
    { return value; }
}
```

```
public final class Boolean
{
    private final boolean value;
    ...

    public int hashCode()
    {
        if (value) return 1231;
        else      return 1237;
    }
}
```

```
public final class Double
{
    private final double value;
    ...

    public int hashCode()
    {
        long bits = doubleToLongBits(value);
        return (int) (bits ^ (bits >> 32));
    }
}
```

convert to IEEE 64-bit representation;  
xor most significant 32-bits  
with least significant 32-bits

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### Java library implementation

```
public final class String
{
    private final char[] s;
    ...

    public int hashCode()
    {
        int hash = 0;
        for (int i = 0; i < length(); i++)
            hash = s[i] + (31 * hash);
        return hash;
    }
}
```

char	Unicode
...	...
'a'	97
'b'	98
'c'	99
...	...

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- treats string as large number
- Horner's method
  - $h = s[0] * 31^{L-1} + \dots + s[L-3] * 31^2 + s[L-2] * 31 + s[L-1] * 31^0$
- you want to involve all the characters in the string
- if the object is immutable, store the value as an instance variable
  - don't have to recomputed

## Example of User defined types

```

public final class Transaction implements Comparable<Transaction>
{
    private final String who;
    private final Date when;
    private final double amount;

    public Transaction(String who, Date when, double amount)
    { /* as before */ }

    ...

    public boolean equals(Object y)
    { /* as before */ }

    public int hashCode()
    {
        int hash = 17;           ← nonzero constant
        hash = 31*hash + who.hashCode(); ← for reference types,
                                         use hashCode()
        hash = 31*hash + when.hashCode(); ← for primitive types,
                                         use hashCode() of wrapper type
        hash = 31*hash + ((Double) amount).hashCode(); ← of wrapper type
        return hash;
    }
}

```

typically a small prime

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- standard recipe
  - 31x+y rule to compute fields
  - if primitive use wrapper type hashCode()
  - null - return 0
  - reference type - use hashCode() - applies the method recursively
  - array - use Arrays.deepHashCode()

In theory, - universal hash functions exist

- equal chance of each position

**Basic Rule** - Need to use the whole key to compute hashCode

- consult an expert for state of the art codes

### Modular Hashing

- hash code gives an integer from -2<sup>31</sup> and (2<sup>31</sup>)-1
- a hash function needs an int from 0 - M-1 (for table sized M)
  - M is typically a power of 2 or a prime number
  - this is because how we get a hash function from a hash code is to do mod(M)
    - need to take abs(hashCode) - can't have a negative array index
    - still has a bug

```
private int hash(Key key)
{   return key.hashCode() % M; }
```

bug

```
private int hash(Key key)
{   return Math.abs(key.hashCode()) % M; }
```

1-in-a-billion bug

hashCode() of "polygenelubricants" is -2<sup>31</sup>

```
private int hash(Key key)
{   return (key.hashCode() & 0xffffffff) % M; }
```

correct

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- use hashCode make positive and then mod - abs value has a small bug

### Uniform Hashing Assumption

- each key is equally likely to hash to an integer between 0 - M-1
- able to come close to this

### Bins and Balls Example

- throw balls uniformly at random into M bins
- Birthday problem
  - subset of this problem
  - expect two balls in the same bin after  $\sqrt{\pi M/2}$  tosses
- Coupon Collector
  - expect every bin to have at least 1 ball after  $M \ln M$  tosses
- Load Balancing
  - after  $M$  tosses most loaded bin has  $(\log M / \log(\log M))$  balls

# Week 6 - Separate Chaining

August 4, 2017 3:29 PM

## Collision Resolution

- Collision - two distinct keys hashing to the same index
- Birthday problem- we will have collisions

The challenge is to deal with challenges efficiently

## Separate Chaining

- build a linked list for each of the table positions
  - hash - map key to integer  $i$  between  $0-(M-1)$
  - Insert put in front of  $i^{\text{th}}$  chain
  - search - only need to search the  $i^{\text{th}}$  chain

## Implementation

```
public class SeparateChainingHashST<Key, Value>
{
    private int M = 97;                      // number of chains
    private Node[] st = new Node[M];          // array of chains

    private static class Node
    {
        private Object key; ← no generic array creation
        private Object val; ← (declare key and value of type Object)
        private Node next;
        ...
    }

    private int hash(Key key)
    {   return (key.hashCode() & 0xffffffff) % M;   }

    public Value get(Key key) {
        int i = hash(key);
        for (Node x = st[i]; x != null; x = x.next)
            if (key.equals(x.key)) return (Value) x.val;
        return null;
    }

}
```

array doubling and  
halving code omitted

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- another possibility is to make the hash table bigger as more values get inserted
  - simple implementation
  - not discussed here

## Insertion Implementation

```

public void put(Key key, Value val) {
    int i = hash(key);
    for (Node x = st[i]; x != null; x = x.next)
        if (key.equals(x.key)) { x.val = val; return; }
    st[i] = new Node(key, val, st[i]);
}

```

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## Analysis

- using uniform hashing assumption,
  - number of keys in list is within a constant factor of  $N/M$ 
    - extremely close to 1
- Make  $M = N/5$ 
  - $M$  too large - too many empty chains
  - $M$  too small - chains too long

## Summary

implementation	worst-case cost (after $N$ inserts)			average case (after $N$ random inserts)			ordered iteration?	key interface
	search	insert	delete	search hit	insert	delete		
sequential search (unordered list)	$N$	$N$	$N$	$N/2$	$N$	$N/2$	no	<code>equals()</code>
binary search (ordered array)	$\lg N$	$N$	$N$	$\lg N$	$N/2$	$N/2$	yes	<code>compareTo()</code>
BST	$N$	$N$	$N$	$1.38 \lg N$	$1.38 \lg N$	?	yes	<code>compareTo()</code>
red-black tree	$2 \lg N$	$2 \lg N$	$2 \lg N$	$1.00 \lg N$	$1.00 \lg N$	$1.00 \lg N$	yes	<code>compareTo()</code>
separate chaining	$\lg N^*$	$\lg N^*$	$\lg N^*$	$3-5^*$	$3-5^*$	$3-5^*$	no	<code>equals()</code> <code>hashCode()</code>

\* under uniform hashing assumption

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# Week 6 - Linear Probing

August 5, 2017 3:05 AM

- another popular collision detection method
- open addressing
  - when a new key collides find next empty slot and put it there
  - array size will need to be larger than the amount of keys

## Insert

- put at table index i if free
  - if not try i+1, i+2, etc
  - until hit empty position
- if run to the end of the array
  - run off to index 0

## Search

- search table index i
  - if free search hit
  - if not try i+1 i+2 etc
  - until hit empty position

## Array size must be greater than the number of key-value pairs

- need array resizing
- at least twice as big

Implementation

```

public class LinearProbingHashST<Key, Value>
{
    private int M = 30001;
    private Value[] vals = (Value[]) new Object[M];
    private Key[] keys = (Key[]) new Object[M];
}

private int hash(Key key) { /* as before */ }

public void put(Key key, Value val)
{
    int i;
    for (i = hash(key); keys[i] != null; i = (i+1) % M)
        if (keys[i].equals(key))
            break;
    keys[i] = key;
    vals[i] = val;
}

public Value get(Key key)
{
    for (int i = hash(key); keys[i] != null; i = (i+1) % M)
        if (key.equals(keys[i]))
            return vals[i];
    return null;
}
}

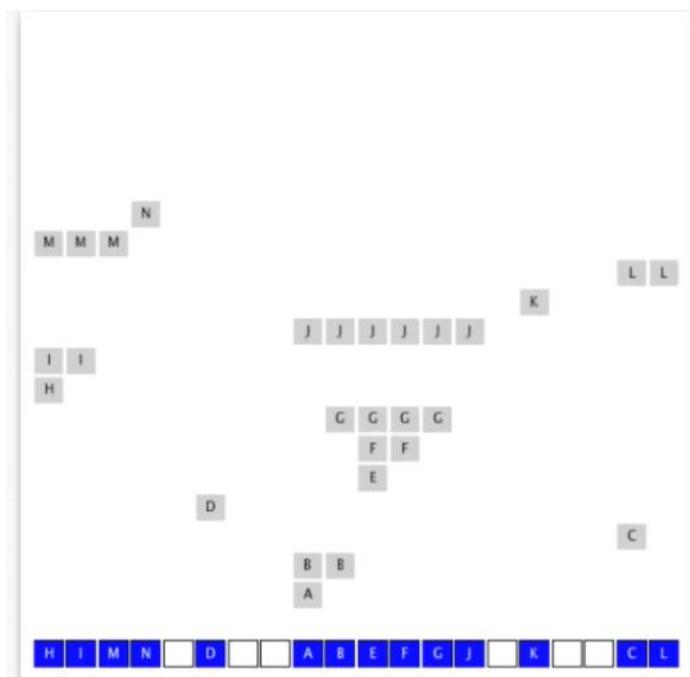
```

array doubling and  
halving code omitted

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## Cluster

- new keys likely to hash into middle of big clusters



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- as more values are inserted, large clusters form and clusters merge together

## Knuth's parking problem

cars show up at random times to find a spot- if they can not find one, they look to the next spot (models clustering)

- with  $M/2$  spaces mean displacement is  $3/2$
- $M$  cars mean displacement is  $\sqrt{\pi(m)/8}$

**Proposition.** Under uniform hashing assumption, the average # of probes in a linear probing hash table of size  $M$  that contains  $N = \alpha M$  keys is:

$$\begin{array}{ll} \sim \frac{1}{2} \left( 1 + \frac{1}{1-\alpha} \right) & \sim \frac{1}{2} \left( 1 + \frac{1}{(1-\alpha)^2} \right) \\ \text{search hit} & \text{search miss / insert} \end{array}$$

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typical choice alpha =  $N/M = 0.5$

## Summary

implementation	worst-case cost (after $N$ inserts)			average case (after $N$ random inserts)			ordered iteration?	key interface
	search	insert	delete	search hit	insert	delete		
sequential search (unordered list)	$N$	$N$	$N$	$N/2$	$N$	$N/2$	no	<code>equals()</code>
binary search (ordered array)	$\lg N$	$N$	$N$	$\lg N$	$N/2$	$N/2$	yes	<code>compareTo()</code>
BST	$N$	$N$	$N$	$1.38 \lg N$	$1.38 \lg N$	?	yes	<code>compareTo()</code>
red-black tree	$2 \lg N$	$2 \lg N$	$2 \lg N$	$1.00 \lg N$	$1.00 \lg N$	$1.00 \lg N$	yes	<code>compareTo()</code>
separate chaining	$\lg N^*$	$\lg N^*$	$\lg N^*$	$3-5^*$	$3-5^*$	$3-5^*$	no	<code>equals()</code> <code>hashCode()</code>
linear probing	$\lg N^*$	$\lg N^*$	$\lg N^*$	$3-5^*$	$3-5^*$	$3-5^*$	no	<code>equals()</code> <code>hashCode()</code>

\* under uniform hashing assumption

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# Week 6 - Hash Table Context

August 5, 2017 3:40 AM

- originally in java, they only used every 8th key when computing the hash function
  - makes it easier to hash long strings
  - great potential for bad collision patterns
  - some strings have the same character every 8th character (ie. URLs)

```
http://www.cs.princeton.edu/introcs/13loop>Hello.java
http://www.cs.princeton.edu/introcs/13loop>Hello.class
http://www.cs.princeton.edu/introcs/13loop>Hello.html
http://www.cs.princeton.edu/introcs/12type/index.html
↑   ↑   ↑   ↑   ↑   ↑   ↑   ↑
```

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## Important to use every character when computing hash functions

### Uniform hashing assumption is important when we need to guarantee performance

- sometimes R-B search trees is better if you can't guarantee uniform hashing assumptions
- hackers can DDOS attack your service
  - if they know your hash code - they can exploit cracks in your hash function

key	hashCode()
"Aa"	2112
"BB"	2112

key	hashCode()
"AaAaAaAa"	-540425984
"AaAaAaBB"	-540425984
"AaAaBBAa"	-540425984
"AaAaBBBB"	-540425984
"AaBBAAaAa"	-540425984
"AaBBAaBB"	-540425984
"AaBBBBAA"	-540425984
"AaBBBBBB"	-540425984

key	hashCode()
"BBAaAaAa"	-540425984
"BBAaAaBB"	-540425984
"BBAaBBAa"	-540425984
"BBAaBBBB"	-540425984
"BBBBAAaAa"	-540425984
"BBBBAAaBB"	-540425984
"BBBBBBAA"	-540425984
"BBBBBBBB"	-540425984

**2<sup>N</sup> strings of length 2N that hash to same value!**

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## One way hash functions

- "hard" to find a key that will hash to a desired value (or two keys to the same value)

```

String password = args[0];
MessageDigest sha1 = MessageDigest.getInstance("SHA1");
byte[] bytes = sha1.digest(password);

/* prints bytes as hex string */

```

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## Separate Chaining vs Linear Probing

Separate Chaining	Linear Probing
easier to implement delete	less wasted space
performance degrades gracefully	better cache performance
clustering less sensitive to poorly designed hash function	

## Improved Versions

- two probe hashing
  - hash to two positions - insert in shorter of the two chains
  - reduces expected length of the longest chain to  $\log \log N$
- double hashing
  - linear probing - skip a variable amount
    - wipes out clustering
  - can allow table to become nearly full
  - more difficult to implement delete
- cuckoo hashing
  - hash to two positions
    - insert key into either position
      - if occupied reinsert displaced key into its alternative position
  - constant worst time for search

## Hash Tables vs Balanced Search Trees

Hash Tables	Balanced Search Trees
Simpler to code	Stronger performance guarantee
no effective alternative for unordered keys	Support for ordered ST operations
faster for simple keys (simple arithmetic vs $\log N$ compares)	Easier to implement compareTo than equals and hashCode
better system support in Java for strings	

## Java includes Both

- R-B search trees
  - `java.util.TreeMap`
  - `java.util.TreeSet`
- Hash Tables
  - `java.util.HashMap`
  - `java.util.IdentityHashMap`

# Week 6 - Symbol Table Applications - Sets

August 5, 2017 4:00 AM

## Mathematical Set

- collection of distinct keys

## API

public class SET<Key extends Comparable<Key>>	
SET()	<i>create an empty set</i>
void add(Key key)	<i>add the key to the set</i>
boolean contains(Key key)	<i>is the key in the set?</i>
void remove(Key key)	<i>remove the key from the set</i>
int size()	<i>return the number of keys in the set</i>
Iterator<Key> iterator()	<i>iterator through keys in the set</i>

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## Implementation

- take symbol table implementation
  - remove anything that deals with values

## Examples of Sets

- Exception Filter
  - read in a list of words from one file
    - print out all words from standard input that are not in(or in) the list
  - whitelist
    - prints all the words that are in the list
  - black list
    - prints the words not in the list

application	purpose	key	in list
spell checker	identify misspelled words	word	dictionary words
browser	mark visited pages	URL	visited pages
parental controls	block sites	URL	bad sites
chess	detect draw	board	positions
spam filter	eliminate spam	IP address	spam addresses
credit cards	check for stolen cards	number	stolen cards

## Implementation (whitelist)

```
public class WhiteList
{
    public static void main(String[] args)
    {
        SET<String> set = new SET<String>(); ← create empty set of strings

        In in = new In(args[0]);
        while (!in.isEmpty())
            set.add(in.readString()); ← read in whitelist

        while (!StdIn.isEmpty())
        {
            String word = StdIn.readString();
            if (set.contains(word))
                StdOut.println(word); ← print words not in list
        }
    }
}
```

- whitelist prints all words that are in the exceptional list

## Implementation(blacklist)

```
public class BlackList
{
    public static void main(String[] args)
    {
        SET<String> set = new SET<String>(); ← create empty set of strings

        In in = new In(args[0]);
        while (!in.isEmpty())
            set.add(in.readString()); ← read in whitelist

        while (!StdIn.isEmpty())
        {
            String word = StdIn.readString();
            if (!set.contains(word))
                StdOut.println(word); ← print words not in list
        }
    }
}
```

- black list prints all words that are not in the exceptional list

# Week 6 - Symbol Table Applications - Dictionary Client

August 5, 2017 4:10 AM

## Command line arguments

- CSV file
- key field
- value field

### Ex 1. DNS lookup.

```
domain name is key IP is value  
% java LookupCSV ip.csv 0 1  
adobe.com  
192.150.18.60  
www.princeton.edu  
128.112.128.15  
ebay.edu  
Not found  
  
domain name is value  
IP is key  
% java LookupCSV ip.csv 1 0  
128.112.128.15  
www.princeton.edu  
999.999.999.99  
Not found
```

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### Ex. 2 Amino Acids

```
codon is key name is value  
% java LookupCSV amino.csv 0 3  
ACT  
Threonine  
TAG  
Stop  
CAT  
Histidine
```

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### Ex. 3 Class List

```
first name  
login is key is value  
% java LookupCSV classlist.csv 4 1  
eberl  
Ethan  
nwebb  
  
section  
login is key is value
```

```
% more ip.csv  
www.princeton.edu,128.112.128.15  
www.cs.princeton.edu,128.112.136.35  
www.math.princeton.edu,128.112.18.11  
www.cs.harvard.edu,140.247.50.127  
www.harvard.edu,128.103.60.24  
www.yale.edu,130.132.51.8  
www.econ.yale.edu,128.36.236.74  
www.cs.yale.edu,128.36.229.30  
espn.com,199.181.135.201  
yahoo.com,66.94.234.13  
msn.com,207.68.172.246  
google.com,64.233.167.99  
baidu.com,202.108.22.33  
yahoo.co.jp,202.93.91.141  
sina.com.cn,202.108.33.32  
ebay.com,66.135.192.87  
adobe.com,192.150.18.60  
163.com,220.181.29.154  
passport.net,65.54.179.226  
tom.com,61.135.158.237  
nate.com,203.226.253.11  
cnn.com,64.236.16.20  
daum.net,211.115.77.211  
blogger.com,66.102.15.100  
fastclick.com,205.180.86.4  
wikipedia.org,66.230.200.100  
rakuten.co.jp,202.72.51.22  
...
```

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```
% more classlist.csv  
13,Berl,Ethan Michael,P01,eberl  
12,Cao,Phillips Minghua,P01,pcao  
11,Chehoud,Christel,P01,cchehoud  
10,Douglas,Malia Morioka,P01,malia  
12,Haddock,Sara Lynn,P01,shaddock  
12,Hantman,Nicole Samantha,P01,nhantman  
11,Hesterberg,Adam Classen,P01,ahesterb  
13,Hwang,Roland Lee,P01,rhwang  
13,Hyde,Gregory Thomas,P01,ghyde  
13,Kim,Hyunmoon,P01,hktwo  
12,Korac,Damjan,P01,dkorac  
11,MacDonald,Graham David,P01,gmacdona  
10,Michal,Brian Thomas,P01,bmichal  
12,Nam,Seung Hyeon,P01,seungnam  
11,Nastasescu,Maria Monica,P01,mnastase  
11,Pan,Di,P01,dpan  
12,Perez,Jessica,P01,jperez
```

```

eberl
Ethan
nwebb
Natalie
          section
          login is key  is value
          ↓
% java LookupCSV classlist.csv 4 3
dpan
P01

```

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```

12,Nam,Seung Hyeon,P01,seungnam
11,Nastasescu,Maria Monica,P01,mnastase
11,Pan,Di,P01,dpan
12,Partridge,Brenton Alan,P01,bpartrid
13,Rilee,Alexander,P01,arilee
13,Roopakalu,Ajay,P01,aroopaka
11,Sheng,Ben C,P01,bsheng
12,Webb,Natalie Sue,P01,nwebb
:

```

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## Implementation

```

public class LookupCSV
{
    public static void main(String[] args)
    {
        In in = new In(args[0]);
        int keyField = Integer.parseInt(args[1]);
        int valField = Integer.parseInt(args[2]);
        ← process input file

        ST<String, String> st = new ST<String, String>();
        while (!in.isEmpty())
        {
            String line = in.readLine();
            String[] tokens = line.split(",");
            String key = tokens[keyField];
            String val = tokens[valField];
            st.put(key, val);
        }
        ← build symbol table

        while (!StdIn.isEmpty())
        {
            String s = StdIn.readString();
            if (!st.contains(s)) StdOut.println("Not found");
            else
                StdOut.println(st.get(s));
        }
    }
}
        ← process lookups
        with standard I/O

```

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# Week 6 - Symbol Table Applications - Indexing Clients

August 5, 2017 4:17 AM

We may need to index our pc

- allows us to search files in our computer

**Goal:** Given a list of files specified, create an index so that you can efficiently find all files containing a given query string

```
% ls *.txt
aesop.txt magna.txt moby.txt
sawyer.txt tale.txt

% java FileIndex *.txt

freedom
magna.txt moby.txt tale.txt

whale
moby.txt

Tamb
sawyer.txt aesop.txt
```

```
% ls *.java
BlackList.java Concordance.java
DeDup.java FileIndex.java ST.java
SET.java WhiteList.java

% java FileIndex *.java

import
FileIndex.java SET.java ST.java

Comparator
null
```

**Solution.** Key = query string; value = set of files containing that string.

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## Implementation

```
import java.io.File;
public class FileIndex
{
    public static void main(String[] args)
    {
        ST<String, SET<File>> st = new ST<String, SET<File>>(); ← symbol table

        for (String filename : args) {
            File file = new File(filename);
            In in = new In(file);
            while (!in.isEmpty())
            {
                String key = in.readString();
                if (!st.contains(key))
                    st.put(key, new SET<File>());
                SET<File> set = st.get(key);
                set.add(file);
            }
        }

        while (!StdIn.isEmpty())
        {
            String query = StdIn.readString();
            StdOut.println(st.get(query)); ← process queries
        }
    }
}
```

list of file names from command line

for each word in file, add file to corresponding set

process queries

## Concordance

- get context for words before and after search word (in books and text)  
ie

```
% java Concordance tale.txt  
cities  
tongues of the two *cities* that were blended in  
  
majesty  
their turnkeys and the *majesty* of the law fired  
me treason against the *majesty* of the people in  
of his most gracious *majesty* king george the third  
  
princeton  
no matches
```

## Implementation

```
public class Concordance  
{  
    public static void main(String[] args)  
    {  
        In in = new In(args[0]);  
        String[] words = in.readAllStrings();  
        ST<String, SET<Integer>> st = new ST<String, SET<Integer>>();  
        for (int i = 0; i < words.length; i++)  
        {  
            String s = words[i];  
            if (!st.contains(s))  
                st.put(s, new SET<Integer>());  
            SET<Integer> set = st.get(s);  
            set.add(i);  
        }  
  
        while (!StdIn.isEmpty())  
        {  
            String query = StdIn.readString();  
            SET<Integer> set = st.get(query);  
            for (int k : set)  
                // print words[k-4] to words[k+4]  
            }  
        }  
    }
```

← read text and build index

← process queries and print concordances

# Week 6 - Symbol Table Applications - Sparse Vectors

August 5, 2017 4:26 AM

Matrix- Vector Multiplication

- standard implementation:

a[][]	x[]	b[]	
$\begin{bmatrix} 0 & .90 & 0 & 0 \\ 0 & 0 & .36 & .36 & .18 \\ 0 & 0 & 0 & .90 & 0 \\ .90 & 0 & 0 & 0 & 0 \\ .47 & 0 & .47 & 0 & 0 \end{bmatrix}$	$\begin{bmatrix} .05 \\ .04 \\ .36 \\ .37 \\ .19 \end{bmatrix}$	$=$	$\begin{bmatrix} .036 \\ .297 \\ .333 \\ .045 \\ .1927 \end{bmatrix}$

```
...
double[][] a = new double[N][N];
double[] x = new double[N];
double[] b = new double[N];
...
// initialize a[][] and x[]
...
for (int i = 0; i < N; i++)
{
    sum = 0.0;
    for (int j = 0; j < N; j++)
        sum += a[i][j]*x[j];
    b[i] = sum;
}
```

nested loops  
( $N^2$  running time)

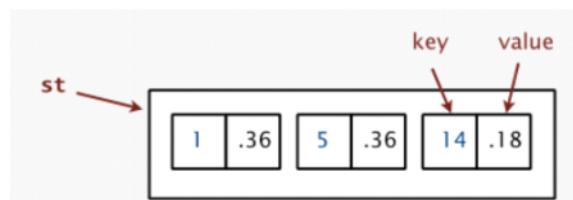
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This implementation is fine for full/almost full matrices but not efficient for sparse matrices(because of the nested for loop)

Symbol tables solve this

Standard implementation of vectors

- array of size N - where N is the dimensions of the vector
- instead, symbol table representation
  - key = index, value = entry
  - efficient iterator
  - space proportional to number of nonzero



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Implementation:

```
public class SparseVector
{
    private HashST<Integer, Double> v; ← HashST because order not important

    public SparseVector()
    { v = new HashST<Integer, Double>(); } ← empty ST represents all 0s vector

    public void put(int i, double x)
    { v.put(i, x); } ← a[i] = value

    public double get(int i)
    {
        if (!v.contains(i)) return 0.0;
        else return v.get(i); } ← return a[i]

    public Iterable<Integer> indices()
    { return v.keys(); }

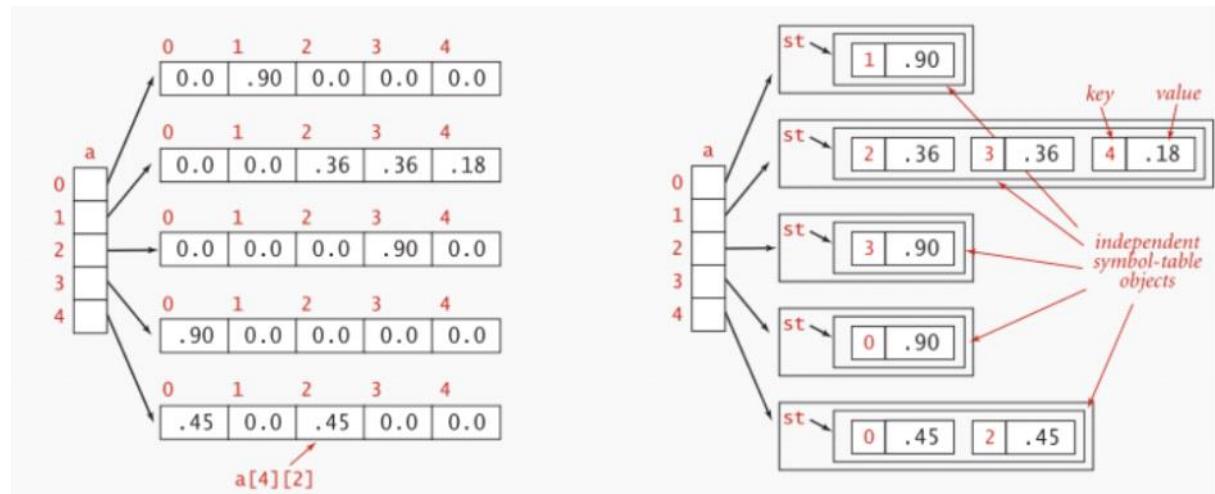
    public double dot(double[] that)
    {
        double sum = 0.0; ← dot product is constant time for sparse vectors
        for (int i : indices())
            sum += that[i]*this.get(i);
        return sum;
    }
}
```

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Normal matrix representation - 2D array

Sparse matrix representation

- each row is a sparse vector



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- more efficient running time for matrix multiplication

```
..  
SparseVector[] a = new SparseVector[N];  
double[] x = new double[N];  
double[] b = new double[N];  
...  
// Initialize a[] and x[]  
...  
for (int i = 0; i < N; i++)  
    b[i] = a[i].dot(x);
```

linear running time  
for sparse matrix

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