Paw on Pi - instructions:

1) Setup Raspbian on your Pi

2) Installing Python PyUSB libraries

To be able to control your USB device you will need the Python PyUSB libraries. The PyUSB libraries have been written in collaboration with a team of 'open-source' volunteers.

To download them, open the Midori web browser and visit: goo.gl/5GBcD This will give you the option to save the pyusb-1.0.0-a2.tar.gz into the Downloads folder.

In the Terminal window or command line – Type:

cd Downloads

Then expand the compressed tarball file:

tar xvf pyusb-1.0.0-a2.tar.gz

List the files and directories by typing 'ls'. You should see a new directory called "pyusb-1.0.0-a2".

Change directory by typing:

cd pyusb-1.0.0-a2

Type 'ls' again to see the contents of the directory.

Type

sudo python setup.py install'

- 3) Copy the example Python file into you working folder (or make a new one)
- 4) Plug your FlowPaw via USB into the Raspberry Pi

(Note that on Model A and B there isn't much USB power so you may have to disconnect the keyboard and mouse or use Bluetooth for these, Model B+ has the fixed usb power so should work just fine.

5) In order to gain the low level access you need to run the Python file form the Terminal Window or Command Line:

Type:

sudo python MyExampleFile.py (eg: sudo python PawPiTest2.py)

and the program should run.