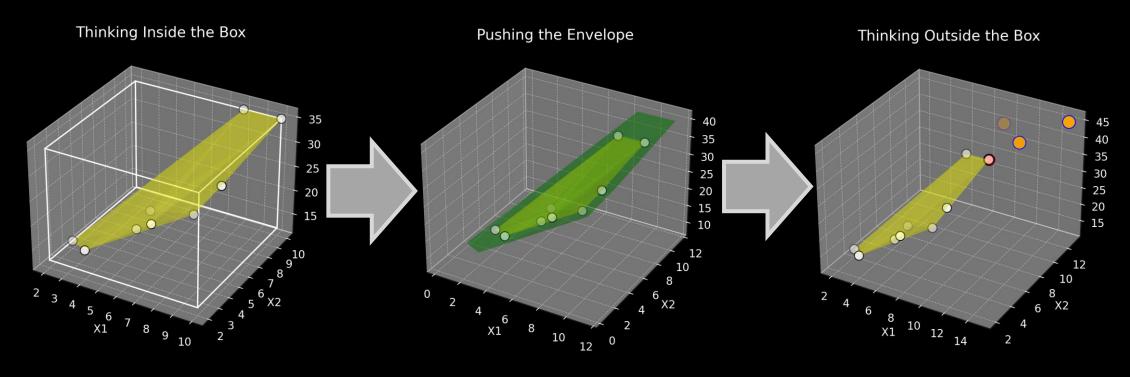
Integrating Predictive & Prescriptive Analytics in R

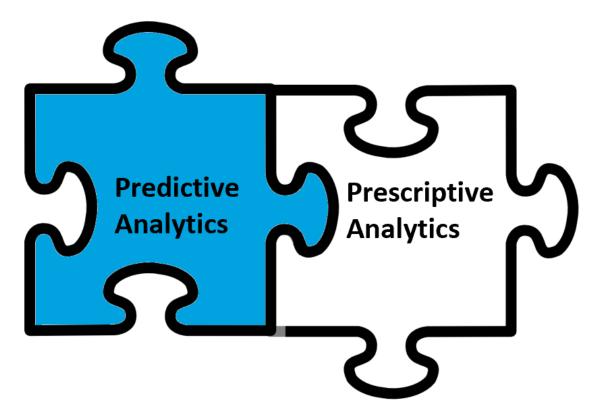




Professor Matthew Lanham
(Former) Academic Director, <u>MS BAIM</u> Program
Associate Director of Student Engagements,
<u>Krenicki Center</u> for Business Analytics & Machine Learning
<u>MatthewALanham.com</u>

There has been a surge integrating prediction with optimization.

• According to Bergman, Huang et al. (2022), "business research practice is witnessing a surge in the integration of predictive modeling and prescriptive analysis."



- Emergen Research (Emergen Research 2021), the global **predictive** and **prescriptive** analytics market is expected to reach \$64B by 2028.
- Emergen's report forecasted growth of the analytics market in nearly every sector:
 - Retail
 - Energy
 - Manufacturing
 - Automotive
 - Defense
 - Healthcare
 - Sports

Bergman, D., et al. (2022). "JANOS: an integrated predictive and prescriptive modeling framework." <u>INFORMS Journal on computing</u> **34**(2): 807-816. Emergen Research (2021) Predictive and Prescriptive Analytics Market.

Today: Predictive to prescriptive modeling considerations (Using R!)

Some of you in the audience may be challenged on where to begin:

- How do I integrate a predictive model into a formal mathematical optimization model?
- Am I making sure I am <u>NOT</u> getting "risky" decision recommendations?
- There are not really a lot of examples in this area, particularly for R folks.



Two-stage design

There are many business problems where a decision-maker wants to make an "optimal" decision using analytical frameworks, methods, and models. Practitioners often use their observational data to:

- 1. Describe what they are seeing
- 2. Predict what might happen in the future
- 3. Then Optimize actions to take

A common modeling design is taking a **two-stage** approach:

- **Stage 1: Predict** what you want to know
- Stage 2: Optimize what actions you should take

$$y = f(X) + \varepsilon$$
 \longrightarrow $\min \hat{y}$ Decision Quality?

What are some ways to try it?

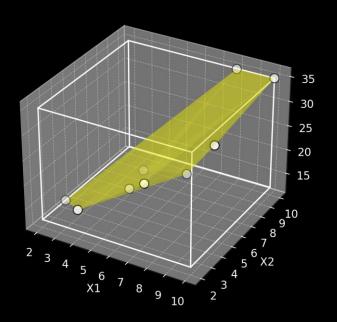
Two-stage designs are the most common way to interface the prediction with the optimization. However, according to *Bertsimas and Kallus* (2020), "it is not clear how to go from a good prediction to a good decision."

$$y = f(X) + \varepsilon \longrightarrow \min \hat{y} \longrightarrow \text{Decision}$$
 $S. t. Z$
Quality?

Lets see some practical modeling considerations....

Thinking Inside the Box

Thinking Inside the Box





Professor Matthew Lanham
(Former) Academic Director, <u>MS BAIM</u> Program
Associate Director of Student Engagements,
<u>Krenicki Center</u> for Business Analytics & Machine Learning
<u>MatthewALanham.com</u>

A good starting point begins with a good problem

First, lets focus on the linear regression model, which falls under the general umbrella of statistical learning and parametric models.

- 1. y is the target variable in our predictive model y: $\{y \in \mathbb{R}\}$
- 2. X are the input features of the predictive model; numeric x: $\{x \in \mathbb{R}\}$ or binary x: $\{x \in 0,1\}$
- 3. ε is the predictive model error term $\varepsilon \sim N(0, \sigma)$

Equation 1: Predictive model

$$y = f(X) + \varepsilon$$

Now consider cases where the predictive model has been estimated and the firm must identify what actions would lead to the best outcome.

Equation 2: Prescriptive (i.e., optimization) model

$$\min \hat{y}$$
 $s.t.Z$

Equation 2 might be to minimize our prediction (say, of cost) subject to some constraints Z.

Stage 1: estimate the relationship

Consider fitting a linear regression model having numeric features, then formulating an optimization model using those estimated parameter coefficients to identify "optimal" decision recommendations.

Example: sample carpet data

$$x_1 \in (2,4,4,5,7,7,9,8,10)$$

 $x_2 \in (4,8,2,5,7,3,6,10,10)$
 $y \in (12.5,13.3,16.9,16.4,17.8,23.7,27.8,35,35.1)$

If an OLS model is fit to this data, it would yield an estimated predictive model of:

$$\hat{y} = 2.674 + 2.685x_1 + 0.437x_2$$

This would create the following plane shown through three-dimensional space.

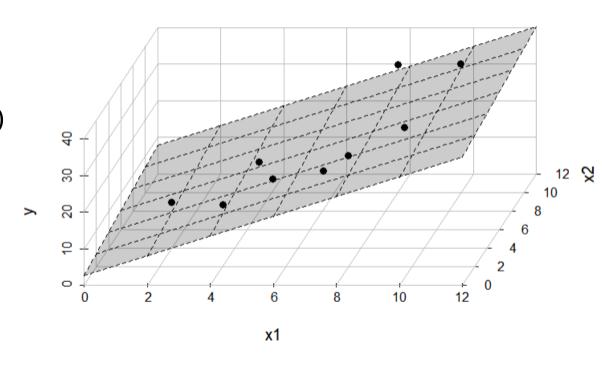


Figure 4: OLS best fit plane

Stage 2: predictive model part of optimization model

You might then take the estimated predictive model and formulate it into an optimization model to obtain the "best" solution or decision.

Assumptions:

- Target variable y in the predictive model is a business performance measure that a decision-maker is seeking to improve (e.g., "quality")
- You might decide to formulate the predictive model into the optimization as either:
 - 1) the objective function, or
 - 2) as a constraint

- Expected quality must be greater than or equal to 29
- Total budgetary cost is \$225

Model formulation 1: Maximize quality

```
max y = 2.674 + 2.685x_1 + 0.437x_2 [1]

s.t.
2.674 + 2.685x_1 + 0.437x_2 \ge 29 [2] ("quality constraint")
\$10x_1 + \$20x_2 \le \$225 [3] ("budgetary constraint")
x_i \ge 0 [4] ("non-negativity")
```

No constraints can lead to extrapolations

After solving the problem, we find the suggested optimal decision is:

- $x_1^* = 22.5$ and $x_2^* = 0$
- leads to an E[y] = 63.09 (quality estimate) and an E[Cost] = \$225.

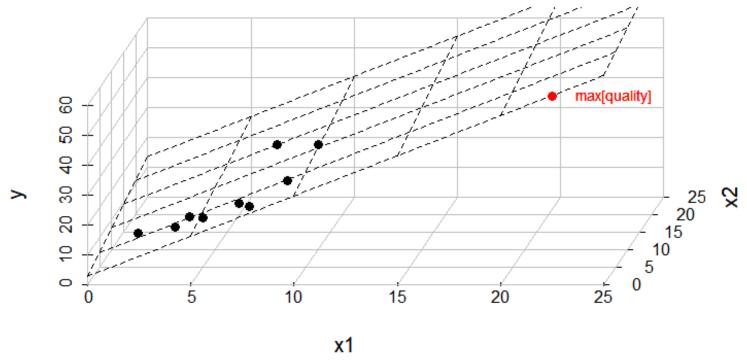


Figure 5: Suggested optimal decision for maximizing quality

When developing a predictive model to eventually support decision-making, are you thinking and designing with the end decision support in mind?

Is predictive modeling process aligned with the decision modeling process?

Say one of the variables x_2 is not statistically significant. Do you leave it in or remove it?

Example:

$$\hat{y} = 2.674 + 2.685x_1 + 0.437x_2$$

MODEL INFO:

Observations: 9

Dependent Variable: y

Type: OLS linear regression

MODEL FIT:

$$F(2,6) = 12.07, p = 0.01$$

 $R^2 = 0.80$

 $Adj. R^2 = 0.73$

Standard errors: OLS

	Est.	2.5%	97.5%	t val.	р
(Intercept) x1 x2	2.69	-7.93 0.88 -1.21	4.49	0.62 3.63 0.65	0.56 0.01 0.54

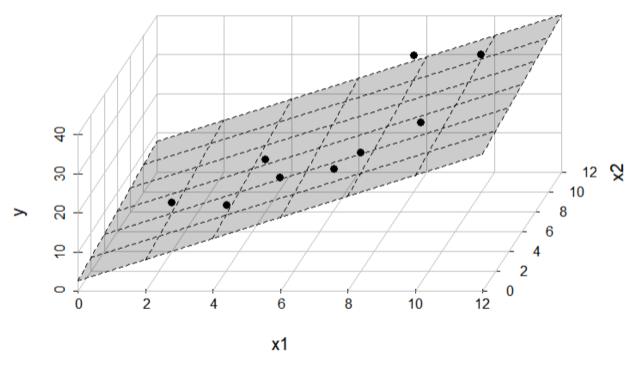


Figure: OLS best fit plane

Keep the end in mind..

Observations:

- 1. Suggested decision recommendations may deviate significantly from historical data. Is that okay?
- 2. Severe extrapolation don't overlook possible implicit predictive modeling assumptions.
- 3. What if decision variables are removed because they are statistically insignificant? Consider in this problem that x_1 and x_2 are manufacturing process settings.
- 4. Prediction error
 - Adjusted $R^2 = 0.7347$
 - "Expected quality" level of E[y] = 63

The recommended decision has error directly from the predictive model. Are you aware and accounting for this error in stage 2?

Stage 1: Prediction

$$\hat{y} = 2.674 + .685x_1 + 0.437x_2$$



$$\max y = 2.674 + 2.685x_1 + 0.437x_2$$
 [1] s.t.

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$\$10x_1 + \$20x_2 \le \$225 \tag{3}$$

$$x_i \ge 0 \tag{4}$$





Curtailing extrapolation risk using data-driven constraints

How could we make "less risky" data-supported decision recommendations?

Model formulation 2: Maximize quality with min-max constraints (a.k.a. "box constraints")

max y =
$$2.674 + 2.685x_1 + 0.437x_2$$
 [1] subject to:

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$\$10x_1 + \$20x_2 \le \$225 \tag{3}$$

$$\min(x_1) \le x_1 \le \max(x_1) \tag{4}$$

$$\min(x_2) \le x_2 \le \max(x_2) \tag{5}$$

$$x_i \ge 0 \tag{6}$$

•
$$x_1^* = 10.0; x_2^* = 6.25$$

•
$$E[y] = 32.26$$
 (previously $E[y] = 63.09$)

•
$$E[Cost] = $225$$
 (same as before)

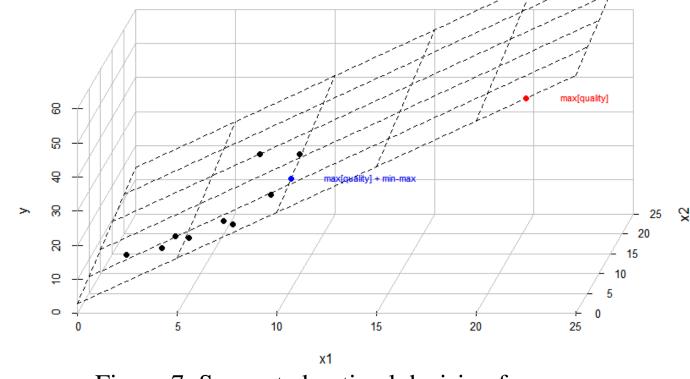


Figure 7: Suggested optimal decision for maximizing quality with min-max constraints

Min-max constraints

In our new solution using min-max constraints, the business requirements of quality and costs are still satisfied.

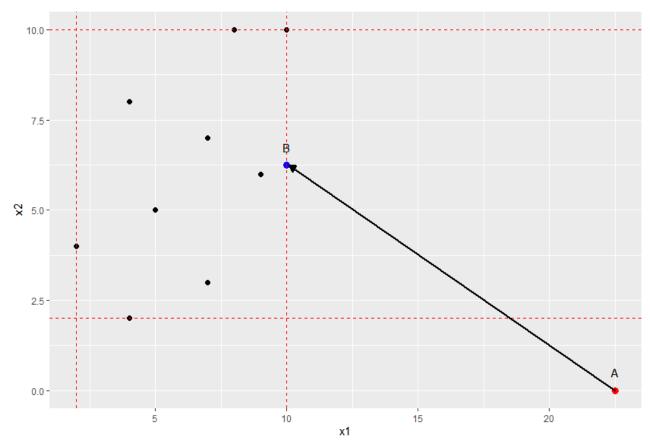


Figure 8: Suggested optimal decision change adding min-max constraints

Is just including min-max constraints for these types of problems enough?

Curtailing extrapolation risk using data-driven constraints

Consider if x_1 or x_2 boundary points (points on red dotted lines) were actually much further away from the other points – such as an "outlier." For example (point D).

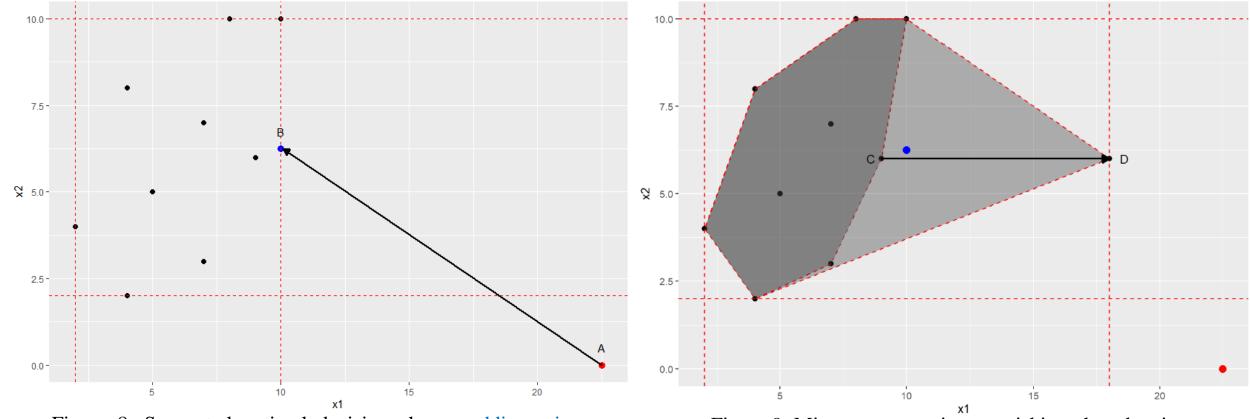


Figure 8: Suggested optimal decision change adding min-max constraints

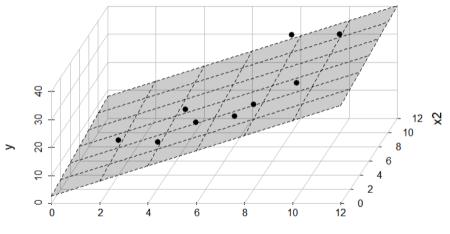
Figure 9: Min-max constraints are riskier when data is not tight or outliers exists

If you could envelop the historical data more tightly, maybe this could lead to improved "data supported" decisions?

```
# Predictive to Prescriptive Analytics
   # Matthew A. Lanham
   # Section 1. Example ideas and graphs
                    Section 1. Example ideas and graphs
   # This example dataset demonstrates the idea of prediction
   # and optimization to motivate future considerations
12 x1 \leftarrow c(2,4,4,5,7,7,9,8,10)
   x2 \leftarrow c(4,8,2,5,7,3,6,10,10)
   y \leftarrow c(12.5,13.3,16.9,16.4,17.8,23.7,27.8,35,35.1)
   d <- data.frame(cbind(y,x1,x2))</pre>
  rm(x1,x2,y)
   cost_parameters = c(10,20)
   cost_constraint_param = 225
   quality_constraint_param = 29
```

•	у ‡	x1 [‡]	x2 [‡]
1	12.5	2	4
2	13.3	4	8
3	16.9	4	2
4	16.4	5	5
5	17.8	7	7
6	23.7	7	3
7	27.8	9	6
8	35.0	8	10
9	35.1	10	10

```
# Visualize relationship
   #3d visual of problem
   names(d)
   par(mfrow=c(1,1))
   library(scatterplot3d)
   plot3d <- scatterplot3d(x = dx1, y = dx2, z = d$y
                             , xlab="x1", ylab="x2", zlab="y"
28
                              , xlim=c(0,12), ylim=c(0,12), zlim=c(0,40)
                              bg="black", color="white", angle=65, scale.y=0.7
                              cex.symbols=1.6, pch=16
                             , box=F, col.grid="grey", lty.grid=par("lty"))
   # add light grey grid
   source('http://www.sthda.com/sthda/RDoc/functions/addgrids3d.r')
   addgrids3d(d[,c(3,2,1)], grid=c("xy", "xz", "yz")
               , angle = 65, x \lim_{x \to 0} (0,12), y \lim_{x \to 0} (0,12), z \lim_{x \to 0} (0,40)
               \cdot scale. y=0.7)
   # put points back on top of grid
   plot3d$points3d(x=d$x1, y=d$x2, z=d$y, type="p", pch=16, cex=1, col="black")
   # fit a multiple linear regression
   f \leftarrow lm(y \sim x1 + x2, data=d)
   summary(f)
   # show output nicely
   # https://cran.r-project.org/web/packages/jtools/vignettes/summ.html
   library(jtools)
   summ(f, pvals = T, confint=T)
   # fit a multiple linear regression WITH interaction terms
   fint <- lm(y \sim x1 + x2 + I(x1*x2), data=d)
   summary(fint)
   # add the fitted regression plane to the 3d-plot
   plot3d$plane3d(f, lty.box="dashed", draw_lines=T, draw_polygon=T)
```



х1

```
87 # maximize quality
 89 library(lpSolveAPI)
    library(lpSolve)
91 # we'll just start with 0 constraints and add them later
92 # there are two decision variables.
93 (lps.model <- make.lp(nrow=0, ncol=3))
94 set.type(lps.model, columns=1, type="real") # decision variable is "real" number
95 set.type(lps.model, columns=2, type="real") # decision variable is "real" number
96 set.type(lps.model, columns=3, type="real") # decision variable is "real" number
97 # set objective function
98 lp.control(lps.model, sense="max")
   set.objfn(lps.model, obj=c(f$coefficients[["(Intercept)"]]
                               ,f$coefficients[["x1"]]
100
                               ,f$coefficients[["x2"]]))
101
    # define constraints
    add.constraint(lps.model, c(f$coefficients[["(Intercept)"]]
                                ,f$coefficients[["x1"]],f$coefficients[["x2"]])
104
                   , ">=", quality_constraint_param)
105
106 add.constraint(lps.model, c(0,cost_parameters), "\Leftarrow", cost_constraint_param)
    add.constraint(lps.model, c(1,0,0), "=", 1) #makes first d.v. 1 (this is to keep
    #intercept term in)
   # (Optional - can provide some constrain names - not necessary)
110 dimnames(lps.model) <- list(c("quality constraint", "cost constraint"
                                  ,"intercept constraint"),
111
                               c("intercept scalar", "# x1", "# x2"))
112
```

Stage 1: Prediction

$$\hat{y} = 2.674 + .685x_1 + 0.437x_2$$

> f\$coefficients (Intercept) **x**1 2.6746044 2.6851545 0.4374529



$$\max y = 2.674 + 2.685x_1 + 0.437x_2$$
 [1] s.t.

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$$10x_1 + $20x_2 \le $225$$
 [3] $x_i \ge 0$ [4]

$$x_i \ge 0$$

```
# lets review our LP model
115 lps.model
116—# solve the model
    solve(lps.model)
    get.objective(lps.model) # optimal obj. value (i.e. our maximum profit)
get.variables(lps.model) # optimal soln of d.v.'s (i.e. our decisions to make)
120
121 # save results
    (results <- data.frame(matrix(NA,nrow=1,ncol=5)))</pre>
123 (names(results) <- c("Model", "x1", "x2", "Exp[y]", "Exp[Cost]"))
124 results $Model <- "Max[Quality]"
125 results$x1 <- get.variables(lps.model)[[2]]</pre>
126 results$x2 <- get.variables(lps.model)[[3]]</pre>
127 results$"Exp[y]" <- get.objective(lps.model)</pre>
128 results\"Exp[Cost]" <- sum(c(0,cost_parameters)*get.variables(lps.model))
129 results
```

```
\max y = 2.674 + 2.685x_1 + 0.437x_2 [1]

s.t.

2.674 + 2.685x_1 + 0.437x_2 \ge 29[2]

\$10x_1 + \$20x_2 \le \$225[3]

x_i \ge 0[4]
```

```
> get.objective(lps.model)
[1] 63.09058
> get.variables(lps.model)
[1] 1.0 22.5 0.0
```

```
Model name:
                       intercept scalar
                                                      # x1
                                                                         # x2
Maximize
                          2.67460437076
                                              2.6851544838
                                                               0.437452901281
quality constraint
                          2.67460437076
                                              2.6851544838
                                                               0.437452901281
cost constraint
                                                        10
                                                                           20
                                                                                   225
intercept constraint
                                                         0
Kind
                                    Std
                                                       Std
                                                                          Std
Type
                                   Rea1
                                                      Real
                                                                         Rea1
                                    Inf
                                                       Inf
                                                                          Inf
Upper
                                      0
                                                                            0
Lower
```

```
# lets review our LP model
115 lps.model
116—# solve the model
    solve(lps.model)
    get.objective(lps.model) # optimal obj. value (i.e. our maximum profit)
get.variables(lps.model) # optimal soln of d.v.'s (i.e. our decisions to make)
120
121 # save results
    (results <- data.frame(matrix(NA,nrow=1,ncol=5)))</pre>
123 (names(results) <- c("Model", "x1", "x2", "Exp[y]", "Exp[Cost]"))
124 results $Model <- "Max[Quality]"
125 results$x1 <- get.variables(lps.model)[[2]]</pre>
126 results$x2 <- get.variables(lps.model)[[3]]</pre>
127 results$"Exp[y]" <- get.objective(lps.model)</pre>
128 results\"Exp[Cost]" <- sum(c(0,cost_parameters)*get.variables(lps.model))
129 results
```

```
\max y = 2.674 + 2.685x_1 + 0.437x_2 [1]

s.t.

2.674 + 2.685x_1 + 0.437x_2 \ge 29[2]

\$10x_1 + \$20x_2 \le \$225[3]

x_i \ge 0[4]
```

```
> get.objective(lps.model)
[1] 63.09058
> get.variables(lps.model)
[1] 1.0 22.5 0.0
```

```
Model name:
                       intercept scalar
                                                      # x1
                                                                         # x2
Maximize
                          2.67460437076
                                              2.6851544838
                                                               0.437452901281
quality constraint
                          2.67460437076
                                              2.6851544838
                                                               0.437452901281
cost constraint
                                                        10
                                                                           20
                                                                                   225
intercept constraint
                                                         0
Kind
                                    Std
                                                       Std
                                                                          Std
Type
                                   Rea1
                                                      Real
                                                                         Rea1
                                    Inf
                                                       Inf
                                                                          Inf
Upper
                                      0
                                                                            0
Lower
```

```
142 # maximize quality w/ min-max constraints
library(lpSolveAPI)
145 library(lpSolve)
146 # we'll just start with 0 constraints and add them later
147 # there are two decision variables.
    (lps.model <- make.lp(nrow=0, ncol=3))
149 set.type(lps.model, columns=1, type="real") # decision variable is "real" number
150 set.type(lps.model, columns=2, type="real") # decision variable is "real" number
151 set.type(lps.model, columns=3, type="real") # decision variable is "real" number
    get.type(lps.model) # to see what types are defined for each D.V.
153 # set objective function
    lp.control(lps.model, sense="max")
155 set.objfn(lps.model, obj=c(f$coefficients[["(Intercept)"]]
156
                               ,f$coefficients[["x1"]],f$coefficients[["x2"]]))
    # define constraints
    add.constraint(lps.model, c(f$coefficients[["(Intercept)"]]
                                ,f$coefficients[["x1"]],f$coefficients[["x2"]])
159
                   , ">=", quality_constraint_param)
160
    add.constraint(lps.model, c(0,cost_parameters), "<=", cost_constraint_param)
    add.constraint(lps.model, c(1,0,0), "=", 1) #makes first d.v. 1 (this is to
163 #keep intercept term in)
164 add.constraint(lps.model, c(0,1,0), "<=", max(d$x1)) #min-max for x1
165 add.constraint(lps.model, c(0,1,0), ">=", min(d$x1)) #min-max for x1
    add.constraint(lps.model, c(0,0,1), "<=", max(d$x2)) #min-max for x2
    add.constraint(lps.model, c(0,0,1), ">=", min(d$x2)) #min-max for x2
168 # in the lpSolve linear program model object.
    dimnames(lps.model) <- list(c("quality constraint", "cost constraint"</pre>
                                  ,"intercept constraint", "min x1 constr."
170
                                  ,"max x1 constr.","min x2 constr.","max x2 constr.
171
                                c("intercept scalar", "# x1", "# x2"))
```

Stage 1: Prediction

$$\hat{y} = 2.674 + .685x_1 + 0.437x_2$$

> f\$coefficients (Intercept) x1 x2 2.6746044 2.6851545 0.4374529



max y =
$$2.674 + 2.685x_1 + 0.437x_2$$
 [1] subject to:

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$\$10x_1 + \$20x_2 \le \$225 \tag{3}$$

$$\min(x_1) \le x_1 \le \max(x_1) \tag{4}$$

$$\min(x_2) \le x_2 \le \max(x_2) \tag{5}$$

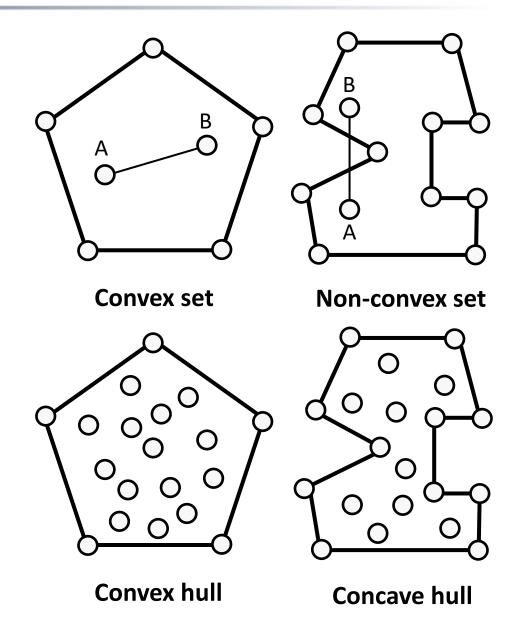
$$x_i \ge 0 \tag{6}$$

Convex Hull Constraints

A **convex set** or convex region is a subset that intersects every line into an individual line segment. Formally, a subset *C* of *S* is convex if, for all x and y in *C*, the line segment connecting x and y is included in *C*.

The **convex hull** is the set of all convex combinations of points in a convex set. Visually, it is the bounded or enclosed area of a subset. Formally, the convex hull of *X* is the intersection of all convex sets *Y* that contain *X*.

$$\operatorname{conv}(X) := \bigcap \{Y \subseteq \mathcal{A} : X \subseteq Y, Y \operatorname{convex}\}\$$



Here is how you can create convex hull constraints

Algorithm:

- 1. Identify the vertices of the hull denoted by the set of points (v_{j1}, v_{j2}) for all $j \in J$.
- 2. Non-negative decision variables' are included in the model as w_i , where j is the index of the jth vertex.
- 3. Sum of the vertex weights w_i must sum to 1.

Model formulation 3: Maximize quality with convex hull constraints

$$\max y = 2.674 + 2.685x_1 + 0.437x_2 \quad [1]$$

subject to:

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$\$10x_1 + \$20x_2 \le \$225 \tag{3}$$

$$\sum_{i=1}^{J} w_i v_{j1} = x_1 \tag{4}$$

$$\sum_{i=1}^{J} w_j v_{j2} = x_2 ag{5}$$

$$\sum_{i=1}^{J} w_i = 1 \tag{6}$$

$$w_i, x_i \ge 0 \tag{7}$$

Note: Every problem you encounter will likely have a different # of vertices.

Together constraints [4], [5], and [6] ensure that any linear combination of points within the hull are considered "data supported" and points outside the hull are not considered as possible decision recommendations.

Data-driven constraints via convex hull constraints

Model formulation 3: Maximize quality with convex hull constraints

max
$$y = 2.674 + 2.685x_1 + 0.437x_2$$
 [1] subject to:

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$\$10x_1 + \$20x_2 \le \$225 \tag{3}$$

$$\sum_{i=1}^{J} w_i v_{i1} = x_1 \tag{4}$$

$$\sum_{i=1}^{J} w_i v_{i2} = x_2 \tag{5}$$

$$\sum_{i=1}^{J} w_i = 1$$
 [6]

$$w_i, x_i \ge 0 \tag{7}$$



- E[y] = 30.20 (previously E[y] = 32.26)
- E[Cost] = \$225 (same as before)

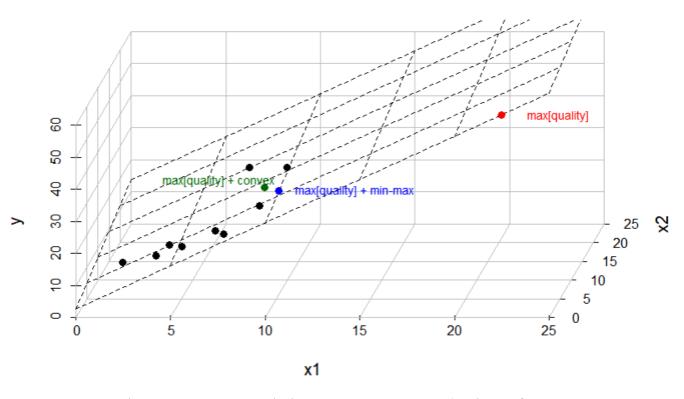


Figure 10: Decision recommendation for quality based on three model formulations

Data-driven constraints via convex hull constraints

The new point C solution provides an expected quality that is not extrapolated like the first model formulation (point A solution), and also falls within the convex hull containing the historical values, which the second model formulation did not (point B solution)

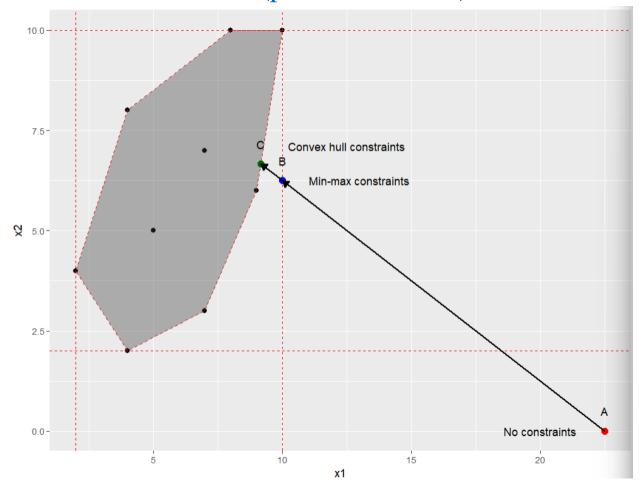


Figure 11: Outcomes using no historical data constraints, box constraints, and convex hull constraints.

- 1. We find the convex hull vertices here.
- 2. Next we will incorporate those into the optimization model as constraints.

$$\sum_{i=1}^{J} w_j v_{j1} = x_1$$
 [4]
$$\sum_{i=1}^{J} w_j v_{j2} = x_2$$
 [5]
$$\sum_{i=1}^{J} w_i = 1$$
 [6]

```
215 # max quality + convex-hull constraints
217 # there are two decision variables. Make them "real"
   (lps.model <- make.lp(nrow=0, ncol=3+num_vertex_constr))</pre>
219 for (i in 1:(3+num_vertex_constr)){
      set.type(lps.model, columns=i, type="real")
221 - }
    get.type(lps.model) # to see what types are defined for each D.V.
   # set objective function
    lp.control(lps.model, sense="max")
225 set.objfn(lps.model, obj=c(f$coefficients[["(Intercept)"]]
                               ,f$coefficients[["x1"]],f$coefficients[["x2"]]
226
227
                               ,rep(0,num_vertex_constr)))
    # define constraints
    add.constraint(lps.model, c(f$coefficients[["(Intercept)"]]
                                ,f$coefficients[["x1"]],f$coefficients[["x2"]]
230
231
                                ,rep(0,num_vertex_constr))
232
                   , ">=", quality_constraint_param)
233 add.constraint(lps.model, c(0,cost_parameters,rep(0,num_vertex_constr))
234
                   , "<=", cost_constraint_param)</pre>
235 # makes first d.v. 1 (this is to keep intercept term in)
    add.constraint(lps.model, c(1,0,0,rep(0,num_vertex_constr)), "=", 1)
    add.constraint(lps.model, c(0,1,0,rep(0,num\_vertex\_constr)), "<=", max(d$x1))
    add.constraint(lps.model, c(0,1,0,rep(0,num\_vertex\_constr)), ">=", min(d$x1))
    add.constraint(lps.model, c(0,0,1,rep(0,num\_vertex\_constr)), "<=", max(d$x2))
    add.constraint(lps.model, c(0,0,1,rep(0,num\_vertex\_constr)), ">=", min(dx2)
   add.constraint(lps.model, c(0,-1,0,hull[,1]), "=", 0) #convex hull x1s = dv1
    add.constraint(lps.model, c(0,0,-1,hull[,2]), "=", 0) #convex hull x2s = dv2
    add.constraint(lps.model, c(0,0,0,rep(1,num_vertex_constr)), "=", 1) #sum of |eig
```

Stage 1: Prediction

$$\hat{y} = 2.674 + .685x_1 + 0.437x_2$$

> f\$coefficients (Intercept) x1 x2 2.674604474 2.6881545+ 06.4374529



-max
$$y = 2.674 + 2.685x_1 + 0.437x_2$$
 [1] subject to:

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$10x_1 + 20x_2 \le 25$$
 [3]

$$\sum_{i=1}^{J} w_i v_{j1} = x_1 \tag{4}$$

$$\sum_{i=1}^{J} w_j v_{j2} = x_2 \tag{5}$$

$$\sum_{i=1}^{J} w_j = 1 \tag{6}$$

$$w_i, x_i \ge 0 \tag{7}$$

225

R Time!

```
# lets review our LP model
   lps.model
247 # solve the model
248 solve(lps.model)
   get.objective(lps.model) # optimal obj. value (i.e. our maximum profit)
250 get.variables(lps.model) # optimal solution of d.v.'s (our decisions to make)
 get.objective(lps.model) # optimal obj. value (i.e. our maximum profit)
[1] 30.20487
> get.variables(lps.model) # optimal solution of d.v.'s (our decisions to make)
 [10] 0.1666667
  (results <- rbind(results, results2))</pre>
                                Mode 1
                                             x1
                                                        Exp[y] Exp[Cost]
                                                     x2
                          Max[Quality] 22.500000 0.000000 63.09058
                                                                      225
     Max[Quality] + Min-Max Constraints 10.000000 6.250000 32.26023
                                                                      225
 Max[Quality] + Convex Hull Constraints 9.166667 6.666667 30.20487
```

Stage 2: Other optimization model formulations

Another possible formulation that could reasonably occur in practice would be to incorporate the predictive model as a constraint into the optimization model, rather than directly formulating it into the optimization model's objective function.

Model formulation 4: Minimize cost

min $$10x_1 + $20x_2$ [1] subject to:

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$10x_1 + 20x_2 \le 225$$
 [3]

$$x_i \ge 0$$
 [4]

Model formulation 5:

Minimize cost with min-max constraint

min
$$$10x_1 + $20x_2$$
 [1] subject to:

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$\$10x_1 + \$20x_2 \le 225 \tag{3}$$

$$\min(x_1) \le x_1 \le \max(x_1) \tag{4}$$

$$\min(x_2) \le x_2 \le \max(x_2) \tag{5}$$

$$x_i \ge 0 \tag{6}$$

Model formulation 6:

Minimize cost with convex hull constraint

$$\min_{1 \le 1} \$10x_1 + \$20x_2 \tag{1}$$

subject to:

$$2.674 + 2.685x_1 + 0.437x_2 \ge 29$$
 [2]

$$\$10x_1 + \$20x_2 \le \$225 \tag{3}$$

$$\sum_{i=1}^{J} w_i v_{i1} = x_1 \tag{4}$$

$$\sum_{i=1}^{J} w_j v_{j2} = x_2 ag{5}$$

$$\sum_{i=1}^{J} w_j = 1 \tag{6}$$

$$x_i \ge 0 \tag{7}$$

Comparison of solutions

Solving the maximizing stability model formulations and comparing them to the minimizing cost model formulations.

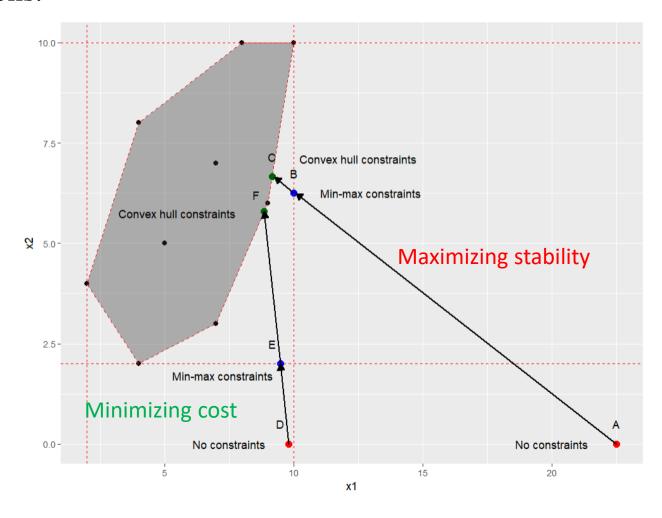
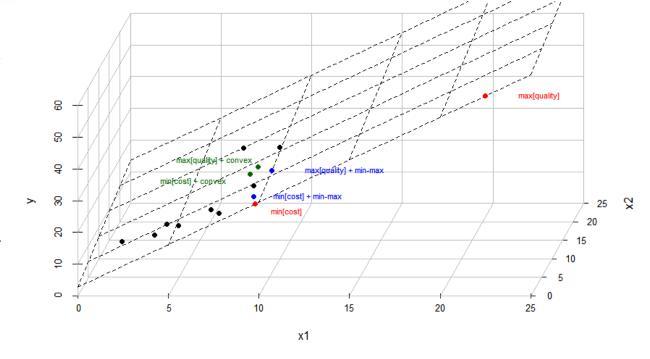


Figure 12: Visualization of six solved model formulations

How did the constraints perform?

- Both formulations using the estimated predictive model in either objective function or constraint had an extrapolated prediction or recommendation.
- Both formulations using convex hull constraints led to "data supported" decisions recommendations
- Now, you must consider the risk of the expected quality (y). Remember it could be higher or lower (it's an expected value).



	Point ID	x1	x2	Exp[y]	Exp[Cost]
Max[Quality]	A	22.5	0	63.09	225
Max[Quality] + Convex Hull Constraints	В	9.17	6.67	30.2	225
Max[Quality] + Min-Max Constraints	С	10	6.25	32.26	225
Min[Cost]	D	9.8	0	29	98.04
Min[Cost] + Min-Max Constraints	Е	9.48	2	29	134.78
Min[Cost] + Convex Hull Constraints	F	8.86	5.79	29	204.42

Table 4: Summary of model formulation experiments

First, lets say the problem or data is just a bit bigger....

This problem we have been toying with is just a small sample from a carpet manufacturing process, where the technician is trying to find the best settings of three confidential chemical inputs we refer to as X_1, X_2 , and X_3 . We have to achieve at least 80% stability...



Fig. Synthetic fibers coating process

- We know carpet stability is considered the primary KPI.
- Stability is a measure of the fibers after being stored in a warehouse for six months.
- Retailers require that stability be greater than or equal to 80% for all carpet types
- The dataset contains 150 different chemical experiments from an established process.

First stage – develop a predictive model

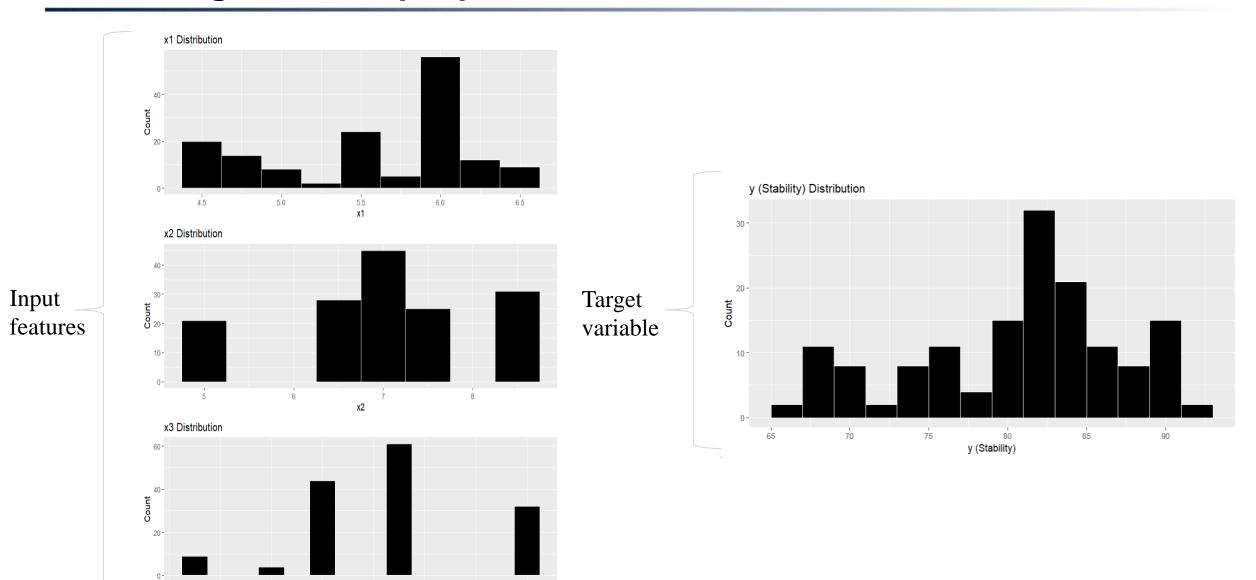
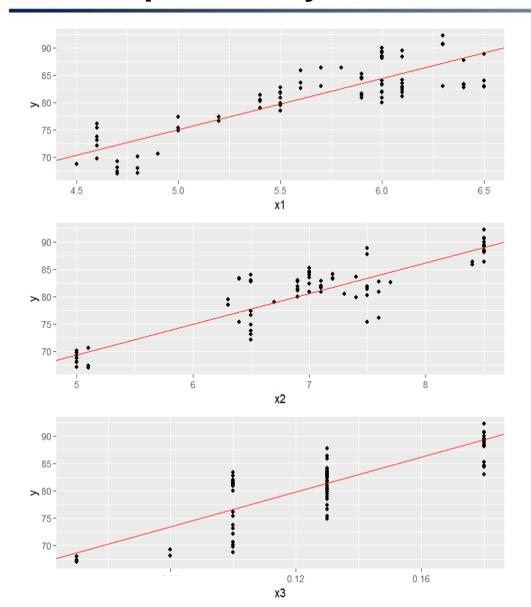


Fig. Feature distributions

Descriptive analysis of data



	x1	x2	х3	y (Stability)	VIF
x1	1	0.59	0.63	0.87	1.758
x2	0.59	1	0.72	0.89	2.223
х3	0.63	0.72	1	0.84	2.404
y (Stability)	0.87	0.89	0.84	1	

Table 9. Pearson correlation matrix and Variance Inflation Factors (VIFs)

While the correlations among the input features are moderate, calculating variance inflation factors suggest the correlations should not negatively affect the estimation of the linear model.

A general rule of thumb is if VIFs are greater than 10 this should be a cause for concern, while more conservative estimates suggest VIFs greater than 2.5 (Dodge 2008). As shown in Table 9 the largest VIF among our input features is 2.404.

Dodge, Y. (2008). The Concise Encyclopedia of Statistics, Springer New York.

Linear regressions

The model chosen uses just the main effects. Has the highest adjusted R^2 of 0.988.

	Bx0	рх0	Bx1	px1	Bx2	px2	Bx3	рхЗ	Bx1x2	px1x2	Bx1x3	px1x3	Bx2x3	px2x3	Bx1x2x3	px1x2x3	AdjR2
1	28.102	0	9.399	0.00													0.751
2	41.204	0			5.62	0.00											0.782
3	60.689	0					159.299	0.00									0.702
4	22.912	0	5.753	0.00	3.641	0.00											0.968
5	35.007	0	6.093	0.00			92.293	0.00									0.895
6	44.695	0			3.703	0.00	79.423	0.00									0.866
7	27.139	0	5.005	0.00	2.883	0.00	42.066	0.00									0.988
8	43.534	0	1.871	0.09	0.568	0.52			7.42	1.69							0.97
9	22.056	0	8.402	0.00			213.358	0.00			-21.185	0.03					0.897
10	39.877	0			4.403	0.00	123.179	0.00					-6.155	0.18			0.866
11	27.118	0	5.007	0.00	2.885	0.00	42.175	0.00							-0.003	0.99	0.988

Table 8: Linear regression estimated model parameters, coefficient p-values, and adjusted R^2

```
\hat{y} = 27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3
```

```
Coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept) 27.13912
                       0.60436
                                 44.91
x1
             5.00484
                       0.12636
                                 39.61
                                         <2e-16 ***
x2
             2.88324
                       0.08325
                                 34.63
x3
                                         <2e-16 ***
            42.06552
                       2.58881
                                 16.25
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Residual standard error: 0.717 on 146 degrees of freedom
Multiple R-squared: 0.9887,
                               Adjusted R-squared: 0.9885
F-statistic: 4261 on 3 and 146 DF, p-value: < 2.2e-16
```

Linear regression model diagnostics

There were no influential points identified in this linear model as shown in the Cook's Distance chart (Kutner, et. al. 2005) and Hadi's influence measure (Hadi, 1992)

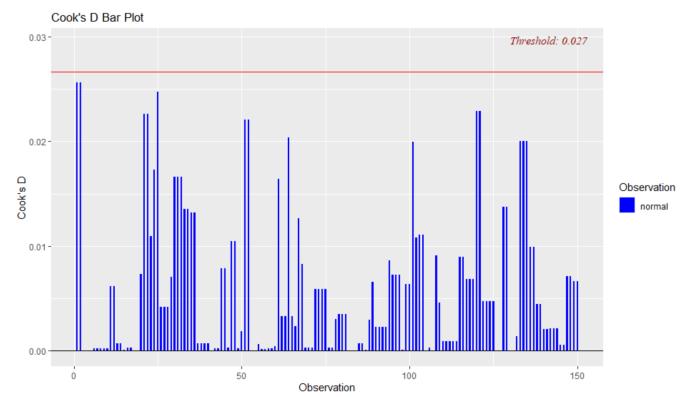


Figure 21. Cook's Distance

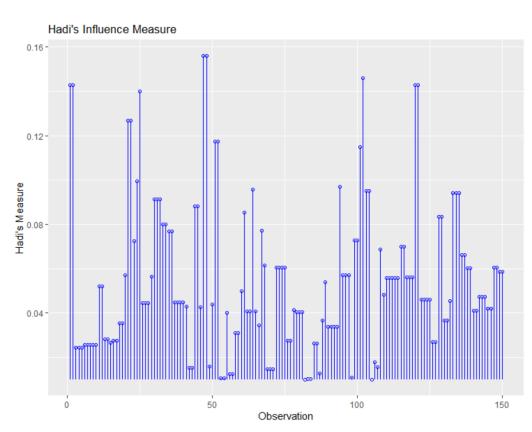


Figure 22. Hadi's influence measure

Kutner, M. H. (2005). <u>Applied linear statistical models</u>. Boston, McGraw-Hill Irwin. Hadi, A. S. (1992). "A new measure of overall potential influence in linear regression." <u>Computational Statistics & Data Analysis</u> **14**(1): 1-27.

Linear regression model diagnostics

Residuals were normally distributed and homoskedastic (constant variance).

 H_0 : variance is homogenous

 H_a : variance is not homogenous

	Test Statistic	p-value
Breusch Pagan Test	1.0047	0.316
Score Test	1.2913	0.255
F-test	1.2852	0.258

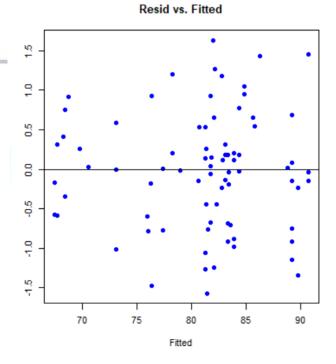
Table 10. Heteroskedasticity tests

 H_0 : errors are normally distributed

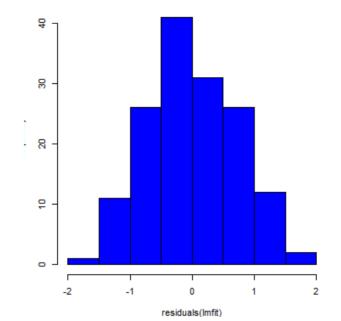
 H_a : errors are not normally distributed

	Test Statistic	p-value
Shapiro-Wilk Test	0.98771	0.208
Lilliefors (Kolmogorov-Smirnov) Test	0.06870	0.080
Anderson-Darling Test	0.53022	0.173

Table 11. Normality tests



Historgram of Residuals



Stage 2: optimization model formulation

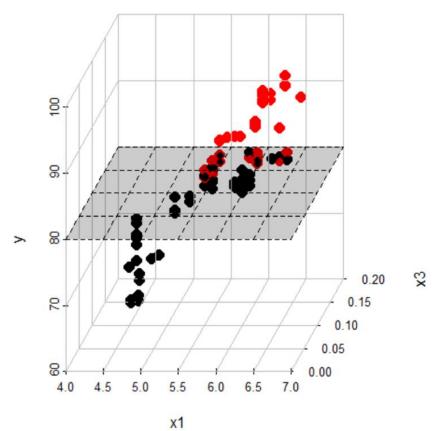


Figure 24. Scenarios that meet stability requirements (red) and do not meet stability requirements (black)

Formulating and solving this problem using the known business constraints of having a stability greater than 80 and staying within budget of \$1000 leads to a decision of:

$$x_1^* = 390.6$$

 $x_2^* = 0$
 $x_2^* = 0$
 $E[y] = 1982.15$

$$\max y = 27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3$$
 [1] s.t.

$$27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3 \ge 80 \qquad [2]$$

$$$2.56x_1 + $2.50x_2 + $21.52x_3 \le $1000 \qquad [3]$$

$$x_i \ge 0 \qquad [4]$$

Note: The costs associated with each input/decision variable are: $x_1 = \$2.56$, $x_2 = \$2.50$, $x_1 = \$21.52$

Stage 2: model formulation with min-max box constraints

Formulating and solving this problem using the known business constraints of having a specificity greater than 80 and staying within budget of \$1000 leads to a decision of:

$$x_1^* = 6.5$$
 $x_2^* = 8.5$
 $x_2^* = 0.18$
 $E[y] = 91.75$

Model formulation 9: Maximize stability w/ box constraints

$$\max y = 27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3$$
 [1] s.t.

$$27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3 \ge 80$$
 [2]

$$$2.56x_1 + $2.50x_2 + $21.52x_3 \le $1000$$
 [3]

$$\min(x_1) \le x_1 \le \max(x_1)$$
 [4]

$$\min(x_2) \le x_2 \le \max(x_2)$$
 [5]

$$\min(x_3) \le x_3 \le \max(x_3)$$
 [6]

 $x_i \geq 0$

Stage 2: model formulation with convex hull constraints

Formulating and solving this problem using the known business constraints of having a specificity greater than 80 and staying within budget of \$1000 (\$37.93) leads to a decision of:

$$x_1^* = 6.4$$
 $x_2^* = 7.5$
 $x_2^* = 0.13$
 $E[y] = 86.26$

Model formulation 3: Maximize stability w/ convex hull constraints

$$\max y = 27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3$$
 [1]

s.t.

$$27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3 \ge 80$$
 [2]

$$2.56x_1 + 2.50x_2 + 21.52x_3 \le 1000$$
 [3]

$$-x_1 + 6.4w_1 + 5.7w_2 + 5.7w_3 + 6.1w_4 + 4.8w_5 = 0$$
 [4]

$$-x_2 + 7.5w_1 + 8.5w_2 + 6.9w_3 + 7.1w_4 + 5.0w_5 = 0$$
 [5]

$$-x_3 + 0.13w_1 + 0.13w_2 + 0.18w_3 + 0.10w_4 + 0.10w_5 = 0$$
 [6]

$$w_1 + w_2 + w_3 + w_4 + w_5 = 1 [7]$$

$$w_i, x_i \ge 0 \tag{8}$$

Some experimental results

90

4.0

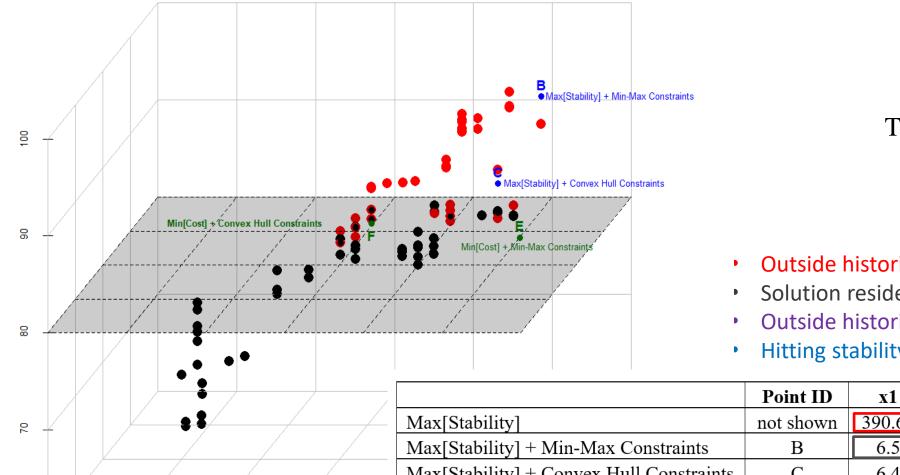
4.5

5.0

5.5

x1

6.0



	x1	x2	х3
Minimum	4.50	5.00	0.05
Average	5.60	7.03	0.13
Median	5.90	7.10	0.13
Maximum	6.50	8.50	0.18

Table : Feature summary statistics

- Outside historical values + severe extrapolation
- Solution resides on box
- Outside historical values
- Hitting stability requirement in all cases

	Point ID	x1	x2	х3	Exp[y]	Exp[Cost]
Max[Stability]	not shown	390.62	0	0	1982.16	1000
Max[Stability] + Min-Max Constraints	В	6.5	8.5	0.18	91.75	41.76
Max[Stability] + Convex Hull Constraints	C	6.4	7.5	0.13	86.26	37.93
Min[Cost]	not shown	10.56	0	0	80	27.04
Min[Cost] + Min-Max Constraints	E	6.5	5	0.14	80	32.17
Min[Cost] + Convex Hull Constraints	F	5.49	6.45	0.16	80	33.66

Table 13: Experimental results

Identify and Hedge Where There is Uncertainty (where your predictive model(s) are)



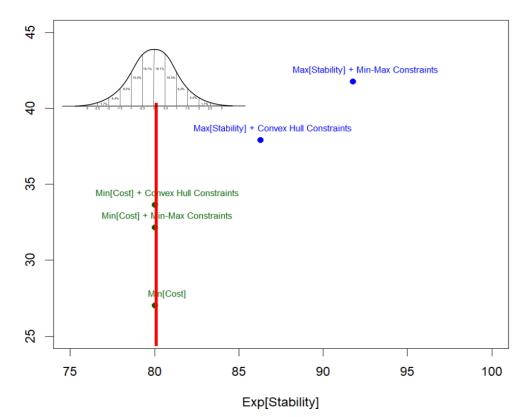
Professor Matthew Lanham
(Former) Academic Director, <u>MS BAIM</u> Program
Associate Director of Student Engagements,
<u>Krenicki Center</u> for Business Analytics & Machine Learning
<u>MatthewALanham.com</u>

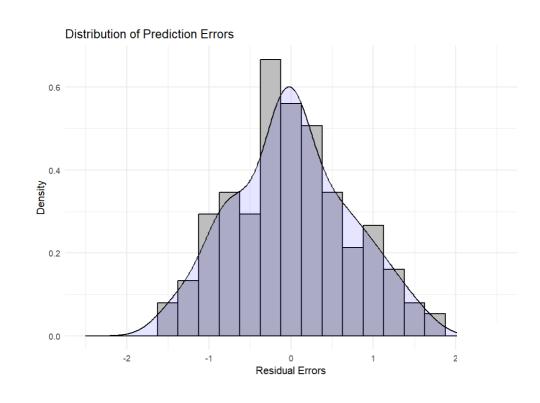
Addressing uncertainty in your prediction

If we use these input settings for x_1 , x_2 , x_3 , we might manufacturer a carpet where some portion of carpet actually has a specificity below 80!

Comparing the predictions to historical values, 21.3% of the time when predicted stability is 80 or greater, the actual stability was less than 80.

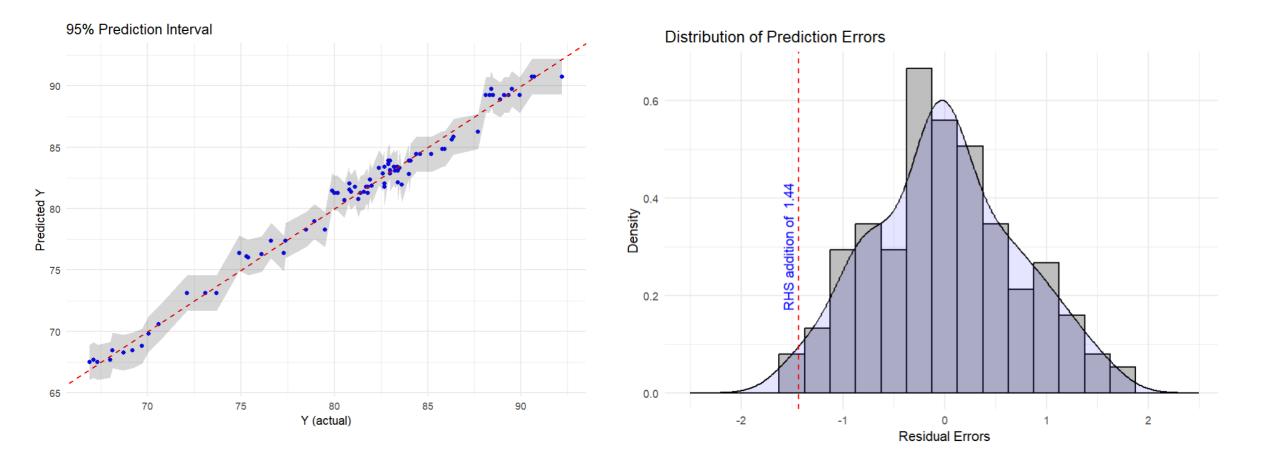
Cost (\$) vs Expected Stability (E[Y])





Possibly use a prediction interval adjustment

Estimating the prediction interval from the historical data, we would want to add 1.44 to the RHS of the stability constraint of 80 to any of our model formulations.



Add or subtract the PI bound based on the constraint type

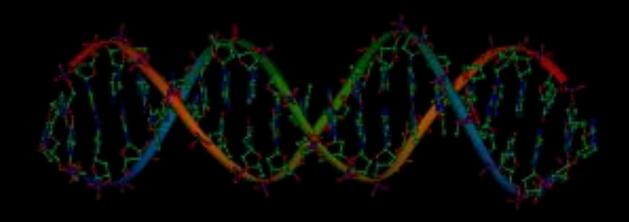
 PI_{ub} : the prediction interval upper bound increment

$$\widehat{PI}_{ub} = 1.44$$

Model formulation 11: Maximize stability w/ convex hull constraints + PI adjustments max
$$y = 27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3$$
 [1] s.t.
$$27.139 + 5.005x_1 + 2.883x_2 + 42.066x_3 \ge 80 + PI_{ub}$$
 [2]
$$$2.56x_1 + $2.50x_2 + $21.52x_3 \le $1000$$
 [3]
$$\sum_{i=1}^{J} w_i v_{j1} = x_1$$
 [4]
$$\sum_{i=1}^{J} w_j v_{j2} = x_2$$
 [5]
$$\sum_{i=1}^{J} w_j v_{j3} = x_3$$
 [6]
$$\sum_{i=1}^{J} w_j v_{j3} = 1$$
 [7]
$$w_i, x_i \ge 0$$
 [8]

Note: In our case, we are willing to have at most 5% of our carpet have a predicted stability less than 80. If that is too much risk for your situation, estimate the prediction interval increment to a higher number (e.g., 99.9 PI).

Going from parametric to non-parametric models





Professor Matthew Lanham
(Former) Academic Director, <u>MS BAIM</u> Program
Associate Director of Student Engagements,
<u>Krenicki Center</u> for Business Analytics & Machine Learning
<u>MatthewALanham.com</u>

When you have a machine learning model consider a GA

When we do not have nice parametric models anymore (e.g., linear regression, logistic regression), you are not going to be able to simply pull those β coefficients from stage 1 to put them in the stage 2 optimization. You might have some machine learning model – consider using a GA!

We could just create our own objective function as a function.

```
Optimization model using genetic algorithm
# Recall the linear regression the model
f < -lm(y \sim x1 + x2 + x3, data=d)
summary(f)
# Define the coefficients from the linear regression model
(coefficients <- coef(f))</pre>
# Objective function to maximize
objective_function <- function(params) {</pre>
  # params are x1, x2, x3
  intercept <- coefficients[1]</pre>
  x1 <- params[1]
  x2 <- params[2]
  x3 <- params[3]
  # Calculate the expected value of y
  expected_y <- (intercept + coefficients[2]*x1 + coefficients[3]*x2</pre>
                   + coefficients[4]*x3)
  # Return the expected value of y
  return(expected_y)
```

Set predictive model as our fitness (objective) function

Whatever GA library you use, it will ask you to set box constraints using the lower and upper bounds. This is our solution search space. We have learned we can create custom search spaces

Using the GA library

Objective function

Min-max constraints

(e.g., convex hull).

```
# Define the bounds for x1, x2, and x3
lower_bounds <- c(min(d$x1), min(d$x2), min(d$x3))</pre>
upper_bounds <- c(max(d$x1), max(d$x2), max(d$x3))
# Run the genetic algorithm
library(GA)
# Set seed for reproducibility
set.seed(123)
ga_result <- ga(</pre>
  type = "real-valued",
  fitness = objective_function,
  lower = lower_bounds,
  upper = upper_bounds,
  popSize = 50,  # Population size
  maxiter = 100, # Maximum number of iterations
  run = 50  # Number of generations without improvement
# Summary of GA results
summary(ga_result)
# Best solution found
best_solution <- ga_result@solution</pre>
# Calculate the maximum expected value of y
max_expected_y <- objective_function(best_solution)</pre>
```

GA found a similar solution but not exactly the same

The package will print out each iteration as it runs. You'll notice in this case the max stability with box (min-max) constraints model is similar to what we obtained previously.

```
iter = 88 |
                 Mean = 90.26375 | Best = 90.93253
    <u>iter = 89 |</u> Mean = 90.01561 | Best = 90.93253
    iter = 90 |
                Mean = 89.92768 | Best = 90.93253
    iter = 91 \mid Mean = 89.95010 \mid Best = 90.93253
    <u>iter = 92 | Mean = 89.79621 | Best = 90.93253</u>
GA
    iter = 93 |
                Mean = 89.94559 |
                                   Best = 90.93253
    iter = 94 | Mean = 89.95083
                                    Best = 90.93253
   | iter = 95 |
                 Mean = 90.08467
                                   Best = 90.93253
GA
    iter = 96 |
                Mean = 90.07542 | Best = 90.93253
GA
    iter = 97 | Mean = 90.24760 |
                                   Best = 90.93253
    iter = 98 |
                 Mean = 89.84782
                                    Best = 90.93253
    iter = 99 | Mean = 89.90236 |
                                    Best = 90.93253
   | iter = 100 | Mean = 90.17818
                                     Best = 90.93253
```

```
> # Print results
> print(paste("Best solution (x1, x2, x3):", paste(best_solution, collapse = ", ")))
[1] "Best solution (x1, x2, x3): 6.48085990877272, 8.38338147791084, 0.170839422492995"
> print(paste("Maximum expected value of y:", max_expected_y))
[1] "Maximum expected value of y: 90.9325291928572"
```

	I.				
Max[Stability] + Min-Max Constraints	В	6.5	8.5	0.18	91.75

Lets predict with ML in S1, then optimize using GA in S2

Used the caret library to train the models using a 3fold CV, but it does not really matter what you use here.

```
Random Forest
```

- 3. XG-Boost
- Neural Net

```
Integrating a machine learning models into an optimization model using a
                          genetic algorithm
                          Set seed for reproducibility
                        set.seed(123)
                        library(caret)
                          defined a 3-fold cross-validation design
                        ctrl <- trainControl(method="cv", # cross-validation set approach to use
                                             number=3. # k number of times to do k-fold
                                             classProbs = F, # if you want probabilities
                                             #summaryFunction = twoClassSummary, # for classification
                                             summaryFunction = defaultSummary, # for regression
                                             allowParallel=T)
                          Train different models
                          train various machine learning models
Support Vector Regression # https://topepo.github.io/caret/available-models.html
                        rf <- train(y~x1+x2+x3, data=d, method="rf", trControl=ctrl, metric="Rsquared")
                        svr <- train(y~x1+x2+x3, data=d, method="svmPoly", trControl=ctrl, metric="Rsquared")
                        xgb <- train(y~x1+x2+x3, data=d, method="xgbLinear", trControl=ctrl, metric="Rsquared")
                        ann <- train(y~x1+x2+x3, data=d, method="glmnet", trControl=ctrl, metric="Rsquared")
```

Captured cross-validated performance

For this toy problem with nice linear relationships, that is also highly accurate, we did not need to use an ML model. Recall out linear regression model had an R^2 of 0.988.

We observe similar predictive R^2 performance

- 1. Random Forest
- 2. Support Vector Regression
- 3. XG-Boost
- 4. Neural Net

```
# final model
(ml_stats = data.frame(matrix(nrow=4, ncol=2, data=NA)))
(names(ml_stats) <- c("model","R2"))
top <- tolerance(rf$results, metric="Rsquared", tol=0.01, maximize=TRUE)
ml_stats[1,] <- c(model="rf", R2=rf$results[top,1:6][["Rsquared"]])
top <- tolerance(svr$results, metric="Rsquared", tol=0.01, maximize=TRUE)
ml_stats[2,] <- c(model="svr", R2=svr$results[top,1:6][["Rsquared"]])
top <- tolerance(xgb$results, metric="Rsquared", tol=0.01, maximize=TRUE)
ml_stats[3,] <- c(model="xgb", R2=xgb$results[top,1:6][["Rsquared"]])
top <- tolerance(ann$results, metric="Rsquared", tol=0.01, maximize=TRUE)
ml_stats[4,] <- c(model="ann", R2=ann$results[top,1:6][["Rsquared"]])
ml_stats$R2 <- as.numeric(ml_stats$R2)
ml_stats[,2] <- round(ml_stats[,2],4)
ml_stats</pre>
```

```
> ml_stats
  model     R2
1     rf 0.9853
2     svr 0.9896
3     xgb 0.9860
4     ann 0.9878
```

Lets capture our stage 2 experimental results

Here I added in some columns to capture our experimental results for our 3 decision variables and they expected stability (a.k.a. "best_soln")

```
ml_stats[,3:6] <- NA
names(ml_stats)[3:6] <- c("x1","x2","x3","best_soln")
ml_stats
ml_models <- ml_stats$model</pre>
```

Lets run some experiments

```
for (i in 1:4) {
# Objective function to maximize
objective_function <- function(params, model=get(ml_models[[i]])) {
    # params are x1, x2, x3
    x1 <- params[1]
    x2 <- params[2]
    x3 <- params[3]
    # Create a new data frame for prediction
    new_data <- data.frame(x1 = x1, x2 = x2, x3 = x3)
    # Predict y using the random forest model
    predicted_y <- predict(model, new_data)
    # Return the predicted value of y
    return(predicted_y)
}

# Define the bounds for x1, x2, and x3
lower_bounds <- c(min(d$x1), min(d$x2), min(d$x3))
upper_bounds <- c(max(d$x1), max(d$x2), max(d$x3))</pre>
```

We set up the GA with minmax constraints

Capture solution and decision reccommendations

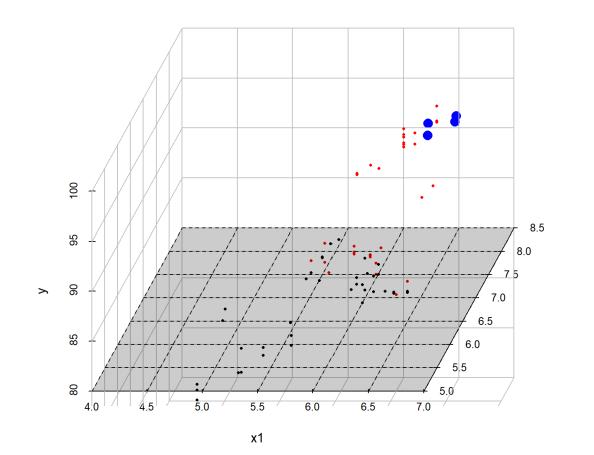
Lets set up our stage 2 objective function. We'll just loop through and try our four different ML models

```
Run the genetic algorithm
ga_result <- ga(</pre>
  type = "real-valued",
  fitness = objective_function,
  lower = lower_bounds,
  upper = upper_bounds,
  popSize = 50,
                    # Population size
  maxiter = 100, # Maximum number of iterations
  run = 50
                    # Number of generations without improvement
# Summary of GA results
summary(ga_result)
# Best solution found
best_solution <- ga_result@solution</pre>
best_solution <- best_solution[1,]</pre>
best_solution
ml_stats[i,3:5] <- best_solution</pre>
# Calculate the maximum expected value of y
max_expected_y <- objective_function(best_solution)</pre>
max_expected_y
ml_stats[i,6] <- max_expected_y</pre>
```

Iterations... final results!

```
Mean = 90.66990
                              Best = 90.97535
iter = 25
iter = 26
            Mean = 90.41697
                              Best = 90.97535
iter = 27
            Mean = 90.37301
                              Best = 90.97535
iter = 28
            Mean = 90.05512
                              Best = 90.97535
iter = 29
            Mean = 90.50967
                              Best = 90.97535
iter = 30
            Mean = 90.28027
                              Best = 90.97535
iter = 31
            Mean = 89.60918
                              Best = 90.97535
```

Here we can see the various "best" solutions using a GA on top of each of the four ML models tried.



Take-Aways

- ☐ In toy-sized problems you will likely be able to "see" where weird things are and account for them with custom constraints, but bigger problems beware out of sight out of mind.
- ☐ Box constraints can help safeguard against extrapolating.
- □ Convex hull constraints might be better based on how much you are willing to deviate from historical values.
- ☐ Do not forget to identify and hedge where the uncertainty lies (e.g., RHS adjustment).

☐ When you move from parametric-type models to non-parametric (ML), genetic algorithms (GA) can be an option.

