## Assignment 1 (50 pts)

Due online before class

## Thursday, September 1

- **1.(10 pts)** Consider a point p = (2, 6).
  - (a) (4 pts) Suppose that the point undergoes first a translation by b = (1, -2) and then a rotation about the origin through  $\frac{\pi}{3}$ . Give the coordinates of the resulting point p'.
  - (b) (4 pts) In a second scenario, p at its original position (2,6) first rotates about the origin through  $\frac{\pi}{3}$ , and then translates by b. Give the coordinates of the resulting point p''.
  - (c) (2 pts) Are rotation and translation commutative?
- **2.(10 pts)** Consider three points  $p_1 = (2,3)$ ,  $p_2 = (5,1)$ , and q = (1,1). Find the point on the line  $\ell$  through  $p_1$  and  $p_2$  that is the closest to q. You are required to use homogeneous coordinates.
- **3.(8 pts)** Consider a planar displacement T that starts with a rotation about the origin through  $\pi/3$  and follows with a translation  $\binom{1}{0}$ . Locate the point s that is not changed under T. (This point is called the *pole* of T.)
- **4.(10 pts)** Two coordinate frames x-y and u-v share the same origin in the plane. Let  $\hat{i}$  and  $\hat{j}$  be the unit vectors along the u- and v-axes, respectively. They are represented in x- and y-coordinates.
  - (a) (5 pts) Give the matrix R describing the rotation from the xy-frame to the uv-frame, that is, the matrix mapping a point p in the uv-coordinates  $\binom{p_u}{p_v}$  to its xy-coordinates  $R\binom{p_u}{p_v}$ .
  - (b) (5 pts) Let  $\hat{i} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$  and  $\hat{j} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$ . Suppose that a point p has coordinates  $\begin{pmatrix} p_x \\ p_y \end{pmatrix} = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$  in the xy-frame. What are its coordinates  $\begin{pmatrix} p_u \\ p_v \end{pmatrix}$  in the uv-frame?
- **5.**(12 pts) In this problem you are required to use homogeneous coordinates.
  - (a) (6 pts) Determine the line passing through (2, -4) and (11, 13).
  - (b) (6 pts) Give the point of intersection of the lines -2x + 3y 8 = 0 and 5x + 2y + 6 = 0.