Linear Regression

CS434

A regression problem

- We want to learn to predict a person's height based on his/her knee height and/or arm span
- This is useful for patients who are bed bound and cannot stand to take an accurate measurement of their height
- Training data:
 - The measurements that past students have taken

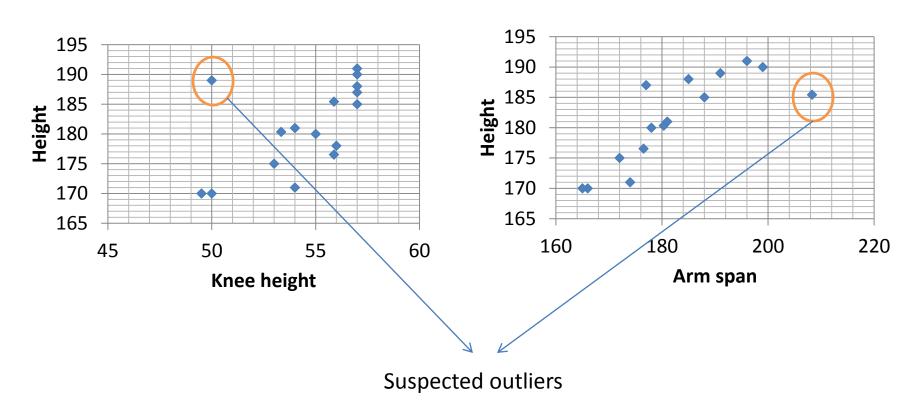
Target Function

- Let y represent a person's height, and x represents the measurements we would use to predict y
- Here x contains two measurements— referred to as features, knee height and arm span

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
 Arm span
 $\begin{bmatrix} x_2 \\ x_2 \end{bmatrix}$ Knee height

- We need to learn a function $y = f(\mathbf{x})$ to predict y given \mathbf{x}
- In statistics, y is called the dependent variable, and \mathbf{x} called the independent variables

Our Training Data



Ignoring these outlier points, there seems to be a reasonable linear relationship between the features and our target variable

Target Function Representation

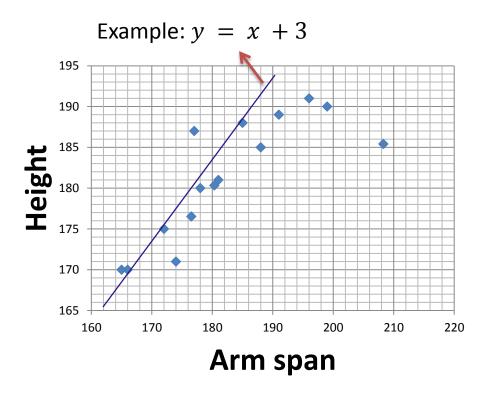
• We will consider linear function (thus the name *linear regression*):

$$y = w_1 x_1 + w_2 x_2 + b$$

- Let's start with just one feature x_1
- To make notations simple, we will for now call it x, and our goal is thus to learn a function

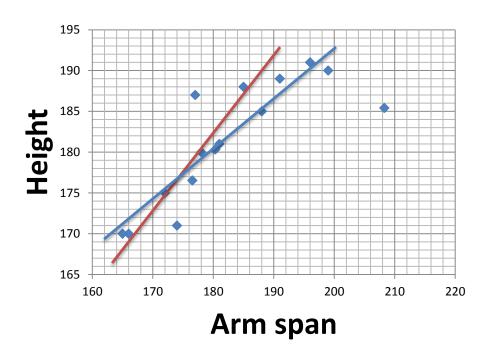
$$y = wx + b$$

One-dimensional Regression



- Goal: fit a line through the points
- Problem: the data does not exactly go through a line

One-dimensional regression



- Which line is better?
- The blue line seems better, but in what way?
- How can we define this goodness precisely?

Let's formalize it a bit more

	arm	Height
ID	span (x)	(y)
1	166	170
2	196	191
3	191	189
4	180.34	180.34
5	174	171
6	176.53	176.53
7	177	187
8	208.28	185.42
9	199	190
10	181	181
11	178	180
12	172	175
13	185	188
14	188	185
15	165	170

- Given a set of training examples $\{(x_i, y_i): i = 1, ..., n\}$
- Goal: learn w and b from the training data, so that y = wx + b predicts y_i from x_i accurately
- In mathematical terms, we would like to find the w and b that minimizes

$$E(w,b) = \sum_{i=1}^{n=15} (y_i - wx_i - b)^2$$

Objective

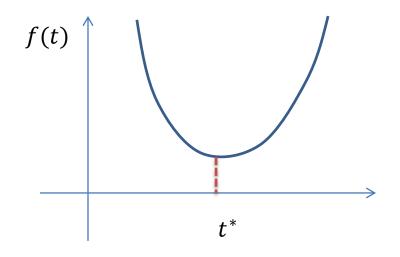
 Our objective is to find the minimizer of the following function:

$$E(w,b) = \sum_{i=1}^{n} (y_i - wx_i - b)^2$$

Often called Sum of Squared Error (SSE).

Optimization 101

- Given a function f(t), finding the t^* that minimizes f(t) can be a challenging or impossible in many situations
 - f(t) could be unbounded, without a minimizer
 - f(t) could have a lot of local minimizers
- For the later case, more advanced methods will be needed
- But sometimes, f(t) is well behaved and it is easy to find the optimizer



- In some cases the function is convex and (e.g., simple quadratic obj.), we have simple strategies to follow:
 - 1. Take derivative of f(t), which we call f'(t)
 - 2. Set it to zero f'(t) = 0
 - 3. Solve for t

Optimizing
$$E(w,b) = \sum_{i=1}^{n} (y_i - wx_i - b)^2$$

1. Take partial derivative of E w.r.t. w and b respectively:

$$\frac{\partial E}{\partial w} = \sum_{i=1}^{n} -2(y_i - wx_i - b)x_i; \quad \frac{\partial E}{\partial b} = \sum_{i=1}^{n} -2(y_i - wx_i - b)$$

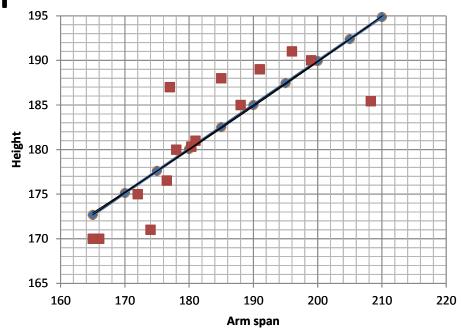
2. Setting them to zero, and solve for w and b

$$\begin{cases} \frac{\partial E}{\partial b} = \sum_{i=1}^{n} 2(y_i - wx_i - b) = 0\\ \frac{\partial E}{\partial w} = \sum_{i=1}^{n} 2(y_i x_i - wx_i^2 - bx_i) = 0 \end{cases}$$

$$b^* = \frac{1}{n} \sum_{i=1}^{n} (y_i - w^* x_i) = \bar{y} - w^* \bar{x} \qquad w^* = \frac{\bar{y} \bar{x} - \bar{y} \bar{x}}{\bar{x}^2 - \bar{x}^2}$$

Our problem

	arm	Height
ID	span (x)	(y)
1	166	170
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15	165	170



$$\bar{x} = \frac{1}{n} \sum_{i} x_{i} = 182.477$$
 $\bar{y} = \frac{1}{n} \sum_{i} y_{i} = 181.286$
 $\bar{x}^{2} = 33436.53$
 $\bar{x}\bar{y} = 31148.91$
 $\bar{x}\bar{y} = 33080.46$

$$w^* = \frac{31148.91 - 33080.46}{33436.53 - 182.477^2} = 0.493$$
$$b^* = 181.3 - 0.493 * 182.5 = 91.30$$

Supervised learning

Extending to more features

- Having more features will mean our objective has more variables to optimize over
- One can solve this similarly by
 - Taking partial derivative of each variable
 - Setting them to zero
 - Solving the system of equations simultaneously
- Alternatively, we can use vector calculus to do this in a more efficient way
- Before we do that, we will briefly review some linear algebra and vector calculus notations

Review of Linear Algebra and Vector Calculus

Adopted from notes by Andrew Rosenberg of CUNY

Definition: vector

- A vector is a one dimensional array.
- We usually denote vectors as boldface lower case letter x, and use x to denote a single variable
- If we don't specify otherwise, assume x is a column vector

$$\mathbf{x} = \begin{pmatrix} x_0 \\ x_1 \\ \dots \\ x_{n-1} \end{pmatrix}$$

Definition: matrix

A matrix is a higher dimensional array. We typically denote matrices as capital letters e.g., A. If A is an n-by-m matrix, it has the following structure

$$A = \begin{pmatrix} a_{0,0} & a_{0,1} & \dots & a_{0,m-1} \\ a_{1,0} & a_{1,1} & a_{1,m-1} \\ \vdots & \ddots & \vdots \\ a_{n-1,0} & a_{n-1,1} & \dots & a_{n-1,m-1} \end{pmatrix}$$

Transposition

Transposing a matrix or vector swaps rows and columns.

A column-vector becomes a row-vector

$$\mathbf{x} = \begin{pmatrix} x_0 \\ x_1 \\ \dots \\ x_{n-1} \end{pmatrix}$$

$$\mathbf{x}^T = \begin{pmatrix} x_0 & x_1 & \dots & x_{n-1} \end{pmatrix}$$

Transposing a matrix or vector swaps rows and columns.

A column-vector becomes a row-vector

$$A = \begin{pmatrix} a_{0,0} & a_{0,1} & \dots & a_{0,m-1} \\ a_{1,0} & a_{1,1} & a_{1,m-1} \\ \vdots & \ddots & \vdots \\ a_{n-1,0} & a_{n-1,1} & \dots & a_{n-1,m-1} \end{pmatrix}$$

$$A^{T} = \begin{pmatrix} a_{0,0} & a_{1,0} & \dots & a_{n-1,0} \\ a_{0,1} & a_{1,1} & a_{1,m-1} \\ \vdots & \ddots & \vdots \\ a_{0,m-1} & a_{1,m-1} & \dots & a_{n-1,m-1} \end{pmatrix}$$

If A is n-by-m, then A^T is m-by-n.

Matrices can only be added if they have the same dimension.

$$A+B = \begin{pmatrix} a_{0,0} + b_{0,0} & a_{0,1} + b_{0,1} & \dots & a_{0,m-1} + b_{0,m-1} \\ a_{1,0} + b_{1,0} & a_{1,1} + b_{1,1} & a_{1,m-1} + b_{1,m-1} \\ \vdots & \ddots & \vdots \\ a_{n-1,0} + b_{n-1,0} & a_{n-1,1} + b_{n-1,1} & \dots & a_{n-1,m-1} + b_{n-1,m-1} \end{pmatrix}$$

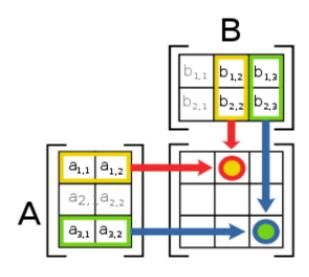
To multiply two matrices, the inner dimensions must match.

■ An *n*-by-*m* can be multiplied by an n'-by-m' matrix iff m = n'.

$$AB = C$$

$$c_{ij} = \sum_{k=0}^{m} a_{ik} * b_{kj}$$

That is, multiply the *i*-th row by the *j*-th column.



- To multiply two vectors, they must also have their dimensions aligned
- For example:

$$\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = x_1 y_1 + x_2 y_2 + x_3 y_3$$

- This is often called the inner (or dot) product of two vectors, written as: $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^T \mathbf{y}$
- Or, alternatively:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} [y_1 \quad y_2 \quad y_3] = \begin{bmatrix} x_1 y_1 & x_1 y_2 & x_1 y_3 \\ x_2 y_1 & x_2 y_2 & x_2 y_3 \\ x_3 y_1 & x_3 y_2 & x_3 y_3 \end{bmatrix}$$

This is often called the outer product of two vectors, written as:

$$\mathbf{x} \otimes \mathbf{y} = \mathbf{x} \mathbf{y}^T$$

Useful operations

- Inversion of a matrix
- Norm of a vector

Matrix Inversion

• The inverse of a <u>square matrix</u> A is a matrix A^{-1} such that $AA^{-1} = I$, where I is called an identity matrix. For example:

$$A = \begin{bmatrix} 1 & 0 \\ 1 & \frac{1}{2} \end{bmatrix}, A^{-1} = \begin{bmatrix} 1 & 0 \\ -2 & 2 \end{bmatrix}$$

- A square matrix A is invertible iff $|A| \neq 0$, i.e., determinant of A is nonzero
- One way to test if the determinant of A is nonzero if to see if you can come up with a linear combination of the vectors of A so that it equals zero
- if not, we say the columns of A are independent of each other, and $|A| \neq 0$

Some useful Matrix Inversion Properties

$$(A^{-1})^{-1} = A$$

$$(kA)^{-1} = k^{-1}A^{-1}$$

$$(A^T)^{-1} = (A^{-1})^T$$

$$(AB)^{-1} = B^{-1}A^{-1}$$

Multi-dimensional Regression

- Now we will consider the more general case that considers multiple features
- Eg, each example is described by $[x_1 \ x_2]^T$, where x_1 denotes the arm span, x_2 denotes the knee height
- We want to learn

$$y = w_1 x_1 + w_2 x_2 + b$$

- It is inconvenient to have to represent b separately, so we will use a small trick to represent all the coefficients jointly
 - Include a constant 1 as a dummy input features: $\mathbf{x} = \begin{bmatrix} 1 & x_1 & x_2 \end{bmatrix}^T$
 - Let w denote the vector of all coefficients: $w = [b \ w_1 \ w_2]^T$
 - The function can be compactly represented as $y = x^T w$ or equivalently $y = w^T x$

Objective

Previous objective:

$$E(w,b) = \sum_{i=1}^{n} (y_i - wx_i - b)^2$$

Updated form

$$E(\mathbf{w}) = \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

- Let $y = [y_1, y_2, ..., y_n]^T$
- Let $X = [x_1, x_2, ..., x_n]^T$

		\mathbf{x}_1^T		y_1	
X =	=	•	$\mathbf{y} =$	•	
		\mathbf{X}_{n}^{T}		\mathcal{Y}_n	

Example n

Example 1

$$E(w) = \sum_{i=1}^{n} (y_i - w^T x_i)^2 = (y - Xw)^T (y - Xw)$$

Optimizing $E(\mathbf{w})$

$$E(\mathbf{w}) = (\mathbf{y} - \mathbf{X}\mathbf{w})^T (\mathbf{y} - \mathbf{X}\mathbf{w})$$

Take the gradient and setting to zero:

$$\nabla E(\mathbf{w}) = -2\mathbf{X}^{T}(\mathbf{y} - \mathbf{X}\mathbf{w}) = \mathbf{0}_{d+1}$$

d: # of input features

$$\Rightarrow \mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{X}^T \mathbf{y}$$

$$\Rightarrow \mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

Matrix cookbook is a good resource to help you with this type of manipulations.

	knee	arm
height	height	span
170	50	166
191	57	196
189	50	191
180.34	53.34	180.34
171	54	174
176.53	55.88	176.53
187	57	177
185.42	55.88	208.28
190	57	199
181	54	181
180	55	178
175	53	172
188	57	185
170	49.5	165
185	57	188

$$X = \begin{bmatrix} 1 & 50 & 166 \\ 1 & 57 & 196 \\ 1 & 50 & 191 \\ 1 & 53.34 & 180.34 \\ 1 & 54 & 174 \\ 1 & 55.88 & 176.53 \\ 1 & 57 & 177 \\ 1 & 55.88 & 208.28 \\ 1 & 57 & 199 \\ 1 & 54 & 181 \\ 1 & 55 & 178 \\ 1 & 53 & 172 \\ 1 & 57 & 185 \\ 1 & 49.5 & 165 \\ 1 & 57 & 188 \end{bmatrix}$$

$$X^T X = \begin{bmatrix} 15 & 815.6 & 2737.2 \\ 815.6 & 44451.6 & 149081 \\ 2737.2 & 149081 & 501547.9 \end{bmatrix}$$

$$\mathbf{w} = \begin{bmatrix} 70.19 \\ 0.656 \\ 0.413 \end{bmatrix}$$

180.34

176.53

185.42

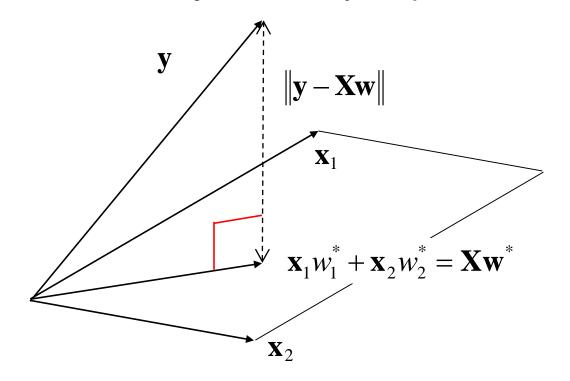
Height = 70.19+.656*knee height + 0.413 * arm span

What is the effect of adding one feature?

- By using both armspan and knee height, can we do better than using just armspan?
- How do we compare?
- SSE with only arm span: 257.445
- SSE with armspan and knee height: 225.680
- Does it mean the model with two features is better?

Geometric interpretation

- \mathbf{y} is a vector in \mathbb{R}^n
- Each column of X is also a vector in \mathbb{R}^n
- Xw is a linear combination of the columns of X, and lies in range(X)
- We want Xw to match y as closely as possible



Summary

- We introduce linear regression, which assumes that the function that maps from x to y is linear
- The goal is to find w that minimizes the sum squared error objective

$$E(\mathbf{w}) = (\mathbf{y} - \mathbf{X}\mathbf{w})^T (\mathbf{y} - \mathbf{X}\mathbf{w})$$

The solution is given by:

$$\mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

- Although we make the linear assumption, it is easy to use this to learn nonlinear functions as well
 - Introduce nonlinear features, e.g., x_1^2 , x_2^2 , x_1x_2