

操作系统实验二 Shell 的实现

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一、实验内容

实现具有管道、重定向功能的 **shell**，能够执行一些简单的基本命令，如进程执行、列目录等。

二、实验目的

通过实验，让学生了解 Shell 实现机制。

三、实验流程与结果展示

（一）管道的实现——myShell.c 代码设计

（1）命令执行和管道处理

该部分主要负责处理命令的执行，包括管道操作和输入/输出重定向。**pipel** 函数用于处理管道，而 **redirect** 函数用于处理输入/输出重定向。

```
67 static NODE * head;
68 struct HELP_DOC * help_doc;
69
70 > int pipel(char *cmd) { ...
98
99 > int redirect(char *cmd) { ...
207
208 int is_back(char *order) {
```

（2）后台任务管理

处理后台任务的管理，包括检测命令是否需要在后台运行、处理子进程的退出和停止信号。

```
53 int is_back(char *order);
54 void handle_sigchld(int s);
55 void handle_sigstcp(int s);
56 // back process
57 typedef struct BACK_JOBS {
58     pid_t pid ;
59     char * cmd;
60     int status;
61 } BACK_JOB ;
```

(3) 命令解析和执行

包含一些辅助函数，用于解析和执行命令，如去除空格、检查命令是否存在、执行 `cd` 命令、显示帮助文档以及打印当前工作目录。

```
42 char * trim (const char *str);
43 char * if_exist (char *order);
44 void do_help(char *);
45 void do_pwd();
46 void do_cd(char *argv[]);
47
```

(4) 信号处理

处理信号，主要是中断信号（SIGINT），用于处理用户键入 `Ctrl+C` 的情况。

```
47
48 void handle_sigint (int s);
49
```

(5) 帮助文档和初始化

用于初始化帮助文档结构，并提供显示帮助文档的函数。

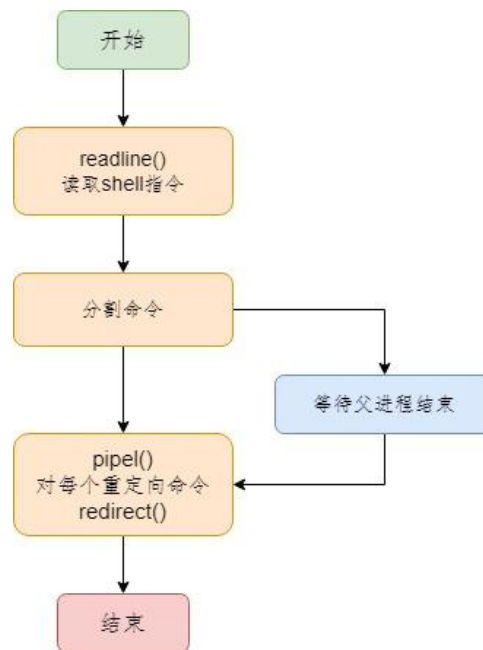
```
37
38 struct HELP_DOC {
39     char * usage[lengthOfBUILTIN_COMMANDS];
40     char * info [lengthOfBUILTIN_COMMANDS];
41 };
42
43 void initWithHelpDoc (struct HELP_DOC*);
44
```

(6) 主函数和自动补全

包含主函数，其中包括程序的入口点，以及使用 `readline` 库实现的命令自动补全功能。

```
409 > char * command_generator (const char *text, int state) { ...
427
428 > char ** command_completion (const char *text, int start, int end) { ...
436
437 v void initialize_readline () {
438     rl_attempted_completion_function = (rl_completion_func_t *)command_completion;
439 }
440
441 > int main (void) { ...
```

(二) 算法流程图



(三) myShell.c 的编译执行

gcc 编译后执行即可，其中 readline 库和 termcap 库需要手动 wget 并安装。

```
[root@localhost exp2]# ls
myShell.c
[root@localhost exp2]# gcc myShell.c -o myShell -lreadline -ltermcap
myShell.c:238: 警告: 与 'do_help' 类型冲突
myShell.c:50: 警告: 'do_help' 的上一个声明在此
[root@localhost exp2]# ls
myShell  myShell.c
[root@localhost exp2]# ./myShell
-----*Welcome*-----
root:/home/seu/exp2$
```

(三) 测试 myShell

(1) 执行并进入 myShell

```
[root@localhost exp2]# ./myShell
-----*Welcome*-----
root:/home/seu/exp2$
```

(2) 测试部分 shell 指令

(注: a 和 b 的测试后来补的, 截图格式上稍微有些差异)

a. 重定向: **ps > test1.txt**

```
seu@localhost:/home/seu/exp2
File Edit View Terminal Tabs Help
[MYSHELL]seu@localhost.localdomain:/home/seu/exp2# cat test1.txt
[MYSHELL]seu@localhost.localdomain:/home/seu/exp2# ps > test1.txt
[MYSHELL]seu@localhost.localdomain:/home/seu/exp2# cat test1.txt
  PID TTY          TIME CMD
 3884 pts/0    00:00:00 su
 3888 pts/0    00:00:00 bash
 3909 pts/0    00:00:00 newShell
 3974 pts/0    00:00:00 ps
```

b. 重定向与管道: `ls | grep myShell > test1.txt`

```
seu@localhost:/home/seu/exp2
File Edit View Terminal Tabs Help
[MYSHELL]seu@localhost.localdomain:/home/seu/exp2# cat test1.txt
  PID TTY          TIME CMD
 3884 pts/0    00:00:00 su
 3888 pts/0    00:00:00 bash
 3909 pts/0    00:00:00 newShell
 3974 pts/0    00:00:00 ps
[MYSHELL]seu@localhost.localdomain:/home/seu/exp2# ls | grep myShell > test1.txt
[MYSHELL]seu@localhost.localdomain:/home/seu/exp2# cat test1.txt
myShell
myShell.c
myShellNew.c
```

c. `cd / pwd / ls`

```
root:/home$ls
seu
root:/home$cd seu
root:/home/seu$pwd
/home/seu
```

d. `cp / mv / rm`

```
root:/home/seu/exp2$ls
myShell myShell.c
root:/home/seu/exp2$cp myShell.c myShell_copy.c
root:/home/seu/exp2$ls
myShell myShell.c myShell_copy.c
root:/home/seu/exp2$mv myShell_copy.c myShell_copy_aftermv.c
root:/home/seu/exp2$ls
myShell myShell.c myShell_copy_aftermv.c
root:/home/seu/exp2$rm myShell_copy_aftermv.c
root:/home/seu/exp2$ls
myShell myShell.c
root:/home/seu/exp2$
```

e. `vi / cat`

```

root:/home/seu/exp2$cat myShell.c
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <unistd.h>
#include <grp.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <errno.h>
#include <signal.h>
#include <readline/readline.h>

```

(下图为执行 vi 后部分界面)

```

static int back_jobs_ptr = 0;
char *st[] = { "DONE", "RUNNING", "STOPPED" };
int currentpid; // current running pid of shell
int isCtrlz;
enum BUILTIN_COMMANDS { NO_SUCH_BUILTIN = 0, EXIT, CD, HISTORY, DO_HIS_CMD, PWD, KILL, HELP, JOBS };
//for tab completion
char *commands[] = { "cd", "cp", "chmod",
-- INSERT --

```

f. help / ps

```

root:/home/seu$help cd
cd: cd [dir]

The default DIR is the value of the HOME shell variable.
root:/home/seu$ps
  PID TTY          TIME CMD
 4007 pts/0        00:00:00 su
 4087 pts/0        00:00:00 bash
 9176 pts/0        00:00:00 ps
27172 pts/0        00:00:00 myShell
root:/home/seu$

```

g. exit

```

27172 pts/0        00:00:00 myShell
root:/home/seu$exit
-----*Goodbye*-----
[root@localhost exp2]#

```

四、实验体会

本次实验涉及对 Shell 功能的简单实现，其中包括管道和重定向。由于对 Linux 和系统调用等不够熟悉，我难以独立从零实现，因此在网络上查阅并修改代码以实现解决方案。首先，实现对运行中进程任务 (jobs) 的存储需要采用链表的方式，同时父子进程之间的联系需要通过信号进行处理。接下来，我着手实现了管道和重定向，在标准输入输出和用户定义的输入输出之间进行了转接，并实现了各个功能。

最后在编译 `myshell.c` 文件时，在阅读实验手册时我了解了 GCC 动态链接库的使用技巧。成功编译并实现了 Shell 的功能。

五、源代码与注释

```
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <unistd.h>
#include <grp.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <errno.h>
#include <signal.h>
#include <readline/readline.h>
#include <readline/history.h>

#define STD_IN 0
#define STD_OUT 1
#define MAXORD 20
#define MAXPARA 8
#define MAX_BACK_JOBS_NUM 20
#define SIGSTCP 20
#define lengthOfBUILTIN_COMMANDS 10
```

```
static int back_jobs_ptr = 0;
char *st[] = { "DONE" , "RUNNING" , "STOPPED" };
int currentpid; // current running pid of shell
int isCtrlz;
enum BUILTIN_COMMANDS { NO_SUCH_BUILTIN =0, EXIT, CD, HISTORY, DO_HIS_CMD , PWD, KILL ,
HELP , JOBS };
//for tab completion
char *commands[] = { "cd" , "cp" , "chmod" ,
                    "exit" ,
                    "mv" , "man" ,
                    "rm" , "rmdir" ,
                    "vi" , "bg" , "fg" , "grep" , "ls" , "cat" ,
                    "history" , "help" ,
                    "jobs" , "kill" ,
                    "ps" , "pwd" };;
```

```
struct HELP_DOC {
    char * usage[lengthOfBUILTIN_COMMANDS];
```

```

    char * info [lengthOfBUILTIN_COMMANDS];
};
char * trim (const char *str);
int is_back(char *order);
int pipel(char *cmd);
char * if_exist (char *order);
void handle_sigchld(int s);
void handle_sigint (int s);
void handle_sigstcp(int s);
void initWithHelpDoc (struct HELP_DOC*);
void do_help(char *);
void do_pwd();

```

```

// back process
typedef struct BACK_JOBS {
    pid_t pid ;
    char * cmd;
    int status;
} BACK_JOB ;

```

```

typedef struct Node {
    int id;
    char cmd[100];
    struct Node * next;
} NODE ;

```

```

struct BACK_JOBS *back_jobs[MAX_BACK_JOBS_NUM];
static NODE *head;
struct HELP_DOC * help_doc;

```

```

int pipel(char *cmd) {
    char * trim (const char *str);
    int redirect (char *cmd);

```

```

    int fd[2], status, pid;
    char *order, *other;
    order = trim( strtok(cmd, "|" ));
    other = trim( strtok (NULL, "" ));
    if (!other)
        redirect(order);
    else {
        pipe(&fd[0]);
        if ((pid = fork ()) == 0) {
            close(fd[0]);
            close(STD_OUT);
            dup(fd[1]);

```

```

        close(fd[1]);
        redirect(order);
    } else {
        close(fd[1]);
        close(STD_IN);
        dup(fd[0]);
        close(fd[0]);
        waitpid (pid, &status, 0);
        pipel(other);
    }
}

return 1;
}

```

```

int redirect (char *cmd) {
    char * trim (const char *str);
    void do_cd(char *argv[]);

    char *order = trim(cmd), *order_path, *real_order;
    char *infile, *outfile, *arg[MAXPARA];
    int i, type = 2, fd_out, fd_in;

    for (i = 0; i < strlen(cmd); ++i) {
        if (cmd[i] == '<')
            ++type;
        if (cmd[i] == '>')
            type = type * 2;
    }
    if (type == 3 || type == 6)
        real_order = trim( strtok (cmd, "<" ));
    else if (type == 4 || type == 5)
        real_order = trim( strtok (cmd, ">" ));
    else if (type == 2)
        real_order = trim(cmd);
    else {
        fprintf (stderr, "#error: bad redirection form\n" );
        return -1;
    }
}

```

```

arg[0] = trim( strtok (real_order, " " ));
for (i = 1; (arg[i] = trim( strtok (NULL, " " ))) != NULL; ++i);
if (strcmp (arg[0], "history" ) == 0) {
    while (head->next != NULL) {
        printf ("id:%d %s\n" , head->id , head->cmd);
        head = head->next;
    }
    exit(1);
}

```



```

        return 1;
    }
    if (strcmp (arg[0], "jobs" ) == 0) {
        int i = 1;
        for (; i < MAX_BACK_JOBS_NUM; ++i) {
            if (back_jobs[i] != NULL)
                printf ("%d] %d %s\t\t\t%s\n" , i, back_jobs[i]-> pid ,
                    st[back_jobs[i]-> status], back_jobs[i]-> cmd);
        }
        exit(1);
        return 1;
    }
    if (strcmp (arg[0], "help" ) == 0) {
        do_help(arg[1]);
        exit(1);
        return 1;
    }
    if (strcmp (arg[0], "pwd" ) == 0) {
        do_pwd();
        exit(1);
        return 1;
    }
    if ((order_path = if_exist(arg[0])) == NULL) {
        fprintf (stderr, "#error: this command doesn't exist\n" );
        exit(1);
        return -1;
    }
    switch (type) {
        case 2:
            break;
        case 3:
            infile = trim( strtok (NULL, "" ));
            break;
        case 4:

            outfile = trim( strtok(NULL, "" ));
            break;
        case 5:

            outfile = trim( strtok(NULL, "<" ));
            infile = trim( strtok (NULL, "" ));
            break;
        case 6:

            infile = trim( strtok (NULL, ">" ));
            outfile = trim( strtok(NULL, "" ));
            break;
    }

```

```
default :  
    return -1;  
}
```

```
if (type == 4 || type == 5 || type == 6) {  
    if ((fd_out = creat(outfile, 0755)) == -1) {  
        fprintf (stderr, "#error: redirect standard out error\n" );  
        return -1;  
    }  
    close(STD_OUT);  
    dup(fd_out);  
    close(fd_out);  
}  
  
if (type == 3 || type == 5 || type == 6) {  
    if ((fd_in = open(infile, O_RDONLY, S_IRUSR | S_IWUSR)) == -1) {  
        fprintf (stderr, "#error: can't open inputfile '%s'\n" , infile);  
        return -1;  
    }  
    close(STD_IN);  
    dup(fd_in);  
    close(fd_in);  
}  
  
execv(order_path, arg);
```

```
exit(0);  
return 1;  
}
```

```
int is_back(char *order) {  
    int len = strlen(order);  
    if (order[len - 1] == '&') {  
        order[len] = '\0';  
        return 1;  
    } else  
        return 0;  
}
```

```
void do_cd(char *argv[]) {  
    if (argv[1] != NULL) {  
        if (chdir (argv[1]) < 0) {  
            switch (errno) {  
                case ENOENT:  
                    fprintf (stderr, "#error: directory can't be found\n" );  
                    break ;  
                case ENOTDIR:
```

```

        fprintf (stderr, "#error: this is not a directory name\n" );
        break ;
    case EACCES:
        fprintf (stderr, "#error: you have no right to access\n" );
        break ;
    default :
        fprintf (stderr, "#error: unknown error\n" );
    }
}
}
}
}

```

```

do_help(char *argv){
    int i;
    if(argv == NULL){
        i = HELP;
    }
    else if(strcmp(argv, "cd" )==0){
        i = CD;
    } else if(strcmp(argv, "exit" )==0){
        i = EXIT;
    } else if(strcmp(argv, "history" )==0){
        i = HISTORY;
    } else if(strcmp(argv, "pwd" )==0){
        i = PWD;
    } else if(strcmp(argv, "help" )==0){
        i = HELP;
    } else if(strcmp(argv, "jobs" )==0){
        i = JOBS;
    }
    printf ("%s\n" ,help_doc-> usage[i]);
    printf ("%s\n" ,help_doc-> info [i]);
    return ;
}

```

```

char * if_exist(char *order) {
    char *all_path, *p, *path, *buffer;
    int len;
    all_path = getenv("PATH" );
    buffer = trim(all_path);
    len = strlen(all_path) + strlen(order);
    if ((path = ( char *) malloc(len * ( sizeof(char) ))) == 0) {
        fprintf (stderr, "#error: can't malloc enough space for buffer\n" );
        return NULL;
    }
    p = strtok (buffer, ":" );
    while (p) {

```

```

        strcat(strcat(stpcpy(path, p), "/" ), order);
        if (access(path, F_OK) == 0) {
            return path;
        }
        p = strtok (NULL, ":", );
    }
    stpcpy(path, order);
    if (access(path, F_OK) == 0)
        return path;
    return NULL;
}

```

```

char * trim (const char *str) {
    int i, j, k;
    char *order;
    if (str == NULL)
        return NULL;
    for (i = 0; i < strlen(str); ++i)
        if (str[i] != ' ' && str[i] != '\t')
            break ;
    for (j = strlen(str) - 1; j > -1; --j)
        if (str[j] != ' ' && str[j] != '\t')
            break ;
    if (i <= j) {
        if ((order = ( char *) malloc((j - i + 2) * ( sizeof(char ) ))) == 0) {
            fprintf (stderr, "#error: can't malloc enough space\n" );
            return NULL;
        }
        for (k = 0; k < j - i + 1; ++k)
            order[k] = str[k + i];
        order[k] = '\0';
        return order;
    } else
        return NULL;
}

```

```

void handle_sigchld( int s) {
    /* execute non-blocking waitpid, loop because we may only receive
    * a single signal if multiple processes exit around the same time.
    */
    // printf("recieve %d pid %d.\n",s,currentpid);
}

```

```

int i = 1;
if(isCtrlz == 0) {
    for (; i < MAX_BACK_JOBS_NUM; ++i) {
        if (back_jobs[i] == NULL)
            continue;
    }
}

```

```

        if (back_jobs[i]-> pid == currentpid) {
            back_jobs[i]-> status = 0;
            break;
        }
    }
} else{
    isCtrlz = 0;
}

pid_t pid;
while ((pid = waitpid (0, NULL, WNOHANG)) > 0) {
    int i = 1;
    for (; i < MAX_BACK_JOBS_NUM; ++i) {
        if (back_jobs[i] == NULL)
            continue;
        if (back_jobs[i]-> pid == pid) {
            back_jobs[i]-> status = 0;
            break ;
        }
    }
}
}
}

```

```

void handle_sigint (int s) {
    //printf("A sigint receive.");
    return ;
}

```

```

void handle_sigstop(int s) {
    int i = 1;
    isCtrlz = 1; //告诉另一个信号处理函数，这是一个 ctrlz
    int flag = 0; //如果等于 0， 则代表这个程序没有被后台过。
    printf ("\n" );
    // kill(currentpid,SIGSTCP);
    for (; i < MAX_BACK_JOBS_NUM; ++i) {
        if (back_jobs[i] == NULL)
            continue;
        if (back_jobs[i]-> pid == currentpid) {
            back_jobs[i]-> status = 2;
            flag = 1;
            break ;
        }
    }
}

```

```

if(flag == 0){
    ++back_jobs_ptr;
    back_jobs[back_jobs_ptr] = ( struct BACK_JOBS *) malloc(sizeof(struct BACK_JOBS *));
    back_jobs[back_jobs_ptr]-> pid = currentpid;
}

```

```

        back_jobs[back_jobs_ptr]--> cmd = (char *) malloc(100);
        strcpy(back_jobs[back_jobs_ptr]--> cmd, "This is a stop process." );
        back_jobs[back_jobs_ptr]--> status = 2;
        printf ("%d] %d %s\t\t\t\t%s\n" , back_jobs_ptr, back_jobs[back_jobs_ptr]--> pid ,
                st[back_jobs[back_jobs_ptr]--> status], back_jobs[back_jobs_ptr]--> cmd);
    }
    return ;
}

```

```

void initWithHelpDoc (struct HELP_DOC *help_doc) {
    help_doc-> usage[ EXIT ] = "exit: exit" ;
    help_doc-> info [EXIT ] = "Exit the shell." ;
}

```

```

help_doc-> usage[CD] = "cd: cd [dir]" ;
help_doc-> info [CD] = "\n\tThe default DIR is the value of the HOME shell variable." ;

```

```

help_doc-> usage[HISTORY] = "history: history [-c] [-s num]" ;
help_doc-> info [HISTORY ] = "\n\tentry with a `*. \n\t\n\t -s num\tsize of the history buffer to num" ;

```

```

help_doc-> usage[PWD] = "pwd: pwd" ;
help_doc-> info [PWD] = "Print the name of the current working directory." ;

```

```

help_doc-> usage[HELP ] = "help: help [pattern ...]" ;
help_doc-> info [HELP ] = "\n\tPATTERN Pattern specifying a help topic" ;

```

```

help_doc-> usage[JOBS] = "jobs: jobs" ;
help_doc-> info [JOBS] = "\n\tLists the active jobs. JOBSPEC restricts output to that job." ;
}

```

```

void do_pwd() {
    char dirname[100];
    if(getcwd(dirname, 99) == NULL) {
        fprintf (stderr, "getcwd error\n" );
    }
    else {
        printf ("%s \n" ,dirname);
    }
}

```

```

char * command_generator (const char *text, int state) {
    char *name;
    static int list_index, len;
}

```

```

if (!state) {
    list_index = 0;
}

```

```
    len = strlen (text);  
}
```

```
while (name = commands[list_index]) {  
    ++list_index;
```

```
    if (strcmp(name, text, len) == 0)  
        return (strdup (name));  
}
```

```
return ((char *)NULL);  
}
```

```
char ** command_completion (const char *text, int start, int end) {  
    char **matches = NULL;
```

```
    if (start == 0)  
        matches = rl_completion_matches (text, command_generator);
```

```
    return (matches);  
}
```

```
void initialize_readline () {  
    rl_attempted_completion_function = (rl_completion_func_t *)command_completion;  
}
```

```
int main (void) {  
    signal(SIGCHLD, handle_sigchld);  
    signal(SIGINT, handle_sigint);  
    signal(SIGSTCP, handle_sigstop);
```

```
    char all_order[100], *order[MAXORD];  
    int i, pid, status, number = 1, back, historyid = 1;  
    char buf[80], prompt[100];  
    char tmp[80];  
    memset(tmp, 0, sizeof(tmp));  
    char *username, *arg[MAXPARA];  
    struct group *data;
```

```
    head = (NODE *) malloc( sizeof(NODE) );  
    strcat (head->cmd, "initial" );  
    data = getgrgid(getgid());  
    username = data->gr_name;  
    strcat (tmp, "/home/" );
```



```
strcat (tmp, username);
```

```
//help 文档
help_doc = ( struct HELP_DOC *) malloc(20* sizeof(struct HELP_DOC *));
initialize_readline();
initWithHelpDoc(help_doc);
printf ("-----*Welcome*-----\n" );
while (1) {
    getcwd(buf, sizeof(buf));
    if (strcmp(tmp, buf) == 0) {
        memset(buf, 0, sizeof(buf));
        buf[0] = '~';
        buf[1] = '\0';
    }
    sprintf (prompt, "%s:%s$", username, buf);
    // printf("%s",prompt);
    // strcat(prompt,username);
    // strcat(prompt,".");
    // strcat(prompt,buf);
    // strcat(prompt,"$");
    // printf("%s",prompt);
```

```
//fgets(all_order,sizeof(all_order),stdin);
// gets(all_order);
char *t;
t = readline (prompt);
sprintf (all_order, "%s" , t);
if (all_order == NULL || trim(all_order) == NULL)
    continue;
//储存历史命令
NODE *next;
next = (NODE *) malloc( sizeof(NODE) );
next-> id = historyid++;
strcpy(next-> cmd, trim(all_order));
next-> next = head;
head = next;
add_history(all_order);
```

```
back = is_back(trim(all_order));
if (strcmp(trim(all_order), "exit" ) == 0) {
    int i = 1;
    int e = 1;
    for (; i < MAX_BACK_JOBS_NUM; ++i) {
        if (back_jobs[i] != NULL) {
            if (back_jobs[i]-> status != 0) {
                e = 0;
                break;
            }
        }
    }
}
```

```

    }
}

if (e == 0) {
    fprintf (stdout, "Some jobs are undone, please stop them first.\n" );
    fprintf (stdout, "Type \"jobs\" to see them.\n" );
    continue;
} else {
    printf ("-----*Goodbye*-----\n" );
    exit(-1);
}
}

if (trim(all_order)[0] == '!' &&trim(all_order)[1]== '-') {
    int i;
    sscanf(trim(all_order), "!-%d" , &i);
    if(i < 0)
        fprintf (stderr, "!# # must be a negative number." );
    NODE * p;
    p = head;
    int j,flag = 0;
    for(j = 0; j < i; ++j){
        p = p-> next;
        if(p == NULL){
            fprintf (stderr, "!# # must be a less than history number." );
            flag=1;
        }
    }
    if(flag == 1) continue;
    strcpy(all_order,p-> cmd);
    --historyid;
    head=head->next;
} else if(trim(all_order)[0] == '!'){
    int i;
    sscanf(trim(all_order), "!!%d" , &i);
    if(i < 0)
        fprintf (stderr, "!# # must be a negative number." );
    i = historyid-i - 1;
    NODE * p;
    p = head;
    int j, flag = 0;
    for(j = 0; j < i; ++j){
        p = p->next;
        if ( p== NULL){
            fprintf (stderr, "!# # must be a less than history number." );
            flag = 1;
        }
    }
}

```

```

    }
    if(flag == 1)
        continue;
    strcpy(all_order,p->cmd);
    --historyid;
    head = head->next;
}

if(trim(all_order)[0]== 'f' && trim(all_order)[1] == 'g'){
    int i;
    sscanf(trim(all_order), "fg%d" , &i);
    if(back_jobs[i]->status == 0){
        continue;
    }
    currentpid=back_jobs[i]-> pid ;
    kill (back_jobs[i]-> pid ,SIGCONT);
    back_jobs[i]-> status = 1;
    waitpid (back_jobs[i]-> pid, &status, WUNTRACED);
    continue;
}

```

```

if(trim(all_order)[0]== 'b' && trim(all_order)[1]== 'g'){
    int i;
    sscanf(trim(all_order), "bg%d" , &i);
    if(back_jobs[i]->status == 0){
        printf ("It is already done.\n" );
        continue;
    }
    currentpid = 0;
    // printf ("%d",back_jobs[i]->pid);
    kill (back_jobs[i]-> pid ,SIGCONT);
    back_jobs[i]->status = 1;
    continue;
}

```

```

arg[0] = trim( strtok (trim(all_order), " " ));
for (i = 1; (arg[i] = trim( strtok (NULL, " " ))) != NULL; ++i);
if (strcmp(arg[0], "cd" ) == 0) {
    do_cd(arg);
    continue;
}

order[0] = trim( strtok (all_order, "&" ));
for (i = 1; (order[i] = trim( strtok (NULL, "&" ))) != NULL; ++i)
    ++number;
for (i = 0; i < number - 1; ++i) {
    if (fork () == 0) {
        pipel(order[i]);
    }
}

```

```

    }
}

//不是后台程序运行方案
if ((pid = fork ()) == 0) {
    pipel(order[i]);
} else if (back == 0){
    currentpid = pid;
    waitpid (pid, &status, WUNTRACED);
} else {
    ++back_jobs_ptr;
    back_jobs[back_jobs_ptr] = ( struct BACK_JOBS *) malloc(sizeof(struct BACK_JOBS *));
    back_jobs[back_jobs_ptr]->pid = pid;
    back_jobs[back_jobs_ptr]->cmd = (char *) malloc(100);
    strcpy(back_jobs[back_jobs_ptr]-> cmd, all_order);
    back_jobs[back_jobs_ptr]->status = 1;
    printf ("%d] %d %s\t\t\t%s\n" , back_jobs_ptr,
            back_jobs[back_jobs_ptr]->pid ,
            st[back_jobs[back_jobs_ptr]->status],
            back_jobs[back_jobs_ptr]->cmd);
}

    number = 1;
}

return 1;
}

```