

Comp305

Biocomputation

Lecturer: Yi Dong

Comp305 Module Timetable



Semester 1 View - Module: COMP305 - Biocomp

	08:00	08:30	09:00	09:30	10:00	10:30	11:00	11:30	12:00	12:30	13:00	13:30	14:00	14:30	15:00	15:30	16:00	16:30	17:00	17:30	18:00
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One of them

Mandatory

There will be **26-30** lectures, thee per week. The lecture slides will appear on Canvas. Please use Canvas to access the lecture information. There will be **9** tutorials, one per week.

Lecture/Tutorial Rules

Questions are welcome as soon as they arise, because

1. Questions give feedback to the lecturer;
2. Questions help your understanding;
3. Your questions help your classmates, who might experience difficulties with formulating the same problems/doubts in the form of a question.

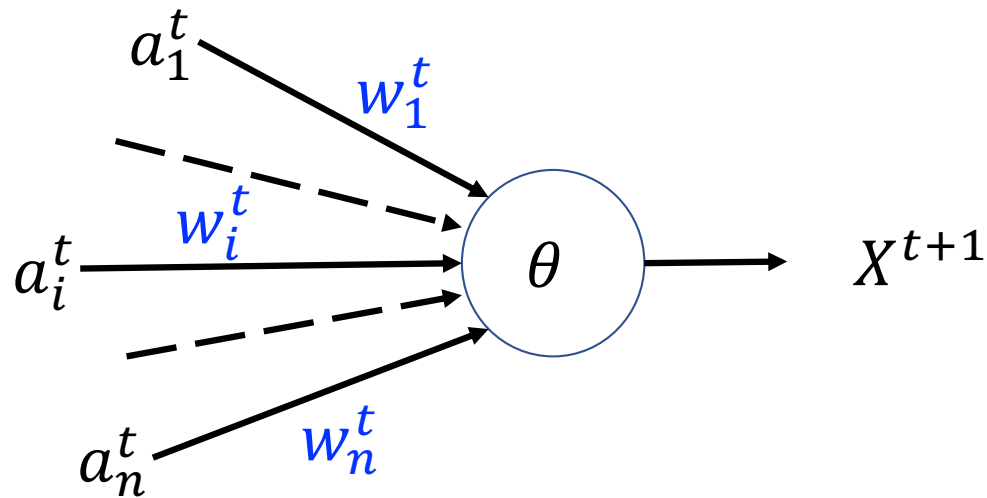
Comp305 Part I.

Artificial Neural Networks

ANN Learning Rules

- The ***McCulloch-Pitts*** neuron made a base for a machine (network of units) capable of
 - *storing information and*
 - *producing logical and arithmetical operations on it*
- The next step
 - must be to realise another important function of the brain, which is
to acquire new knowledge through experience, i.e. learning.

ANN Learning Rules

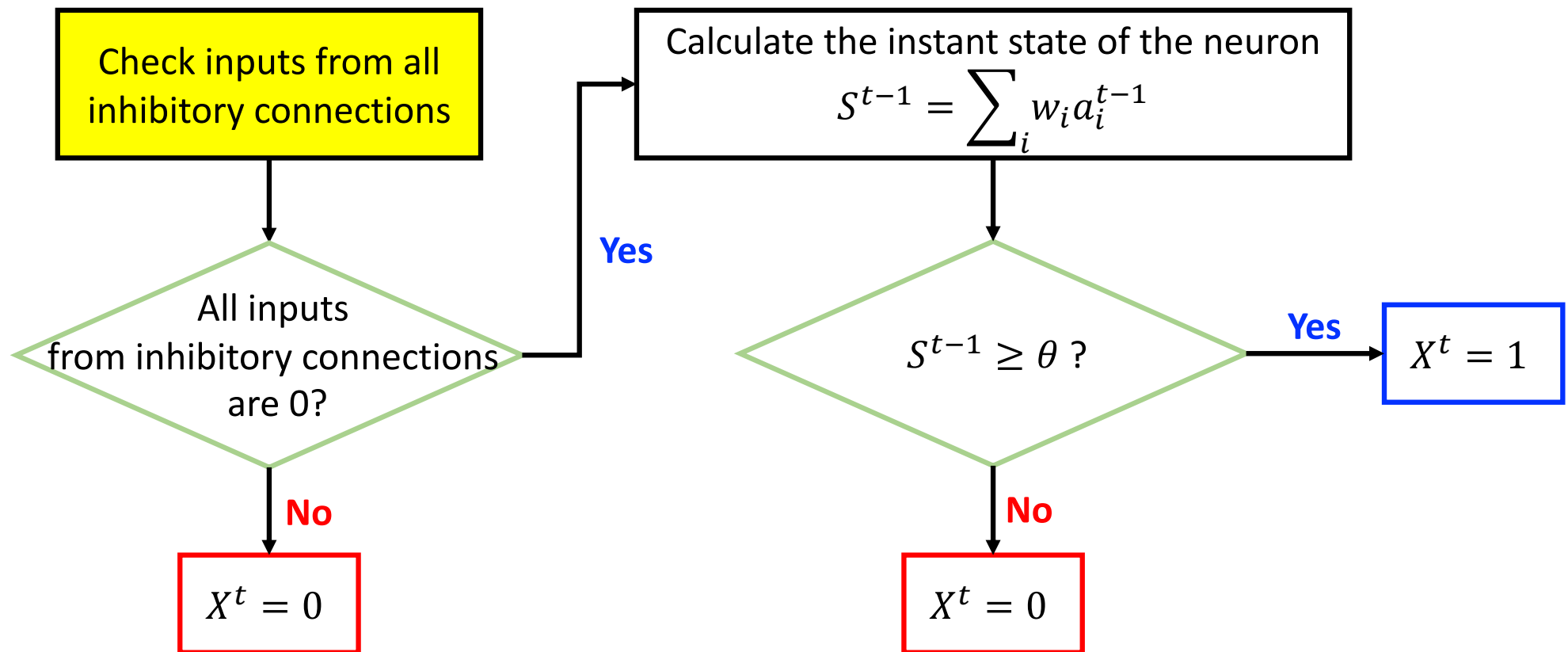


Definition:

ANN learning rule is
the rule how to adjust the weights of connections to get desirable output.

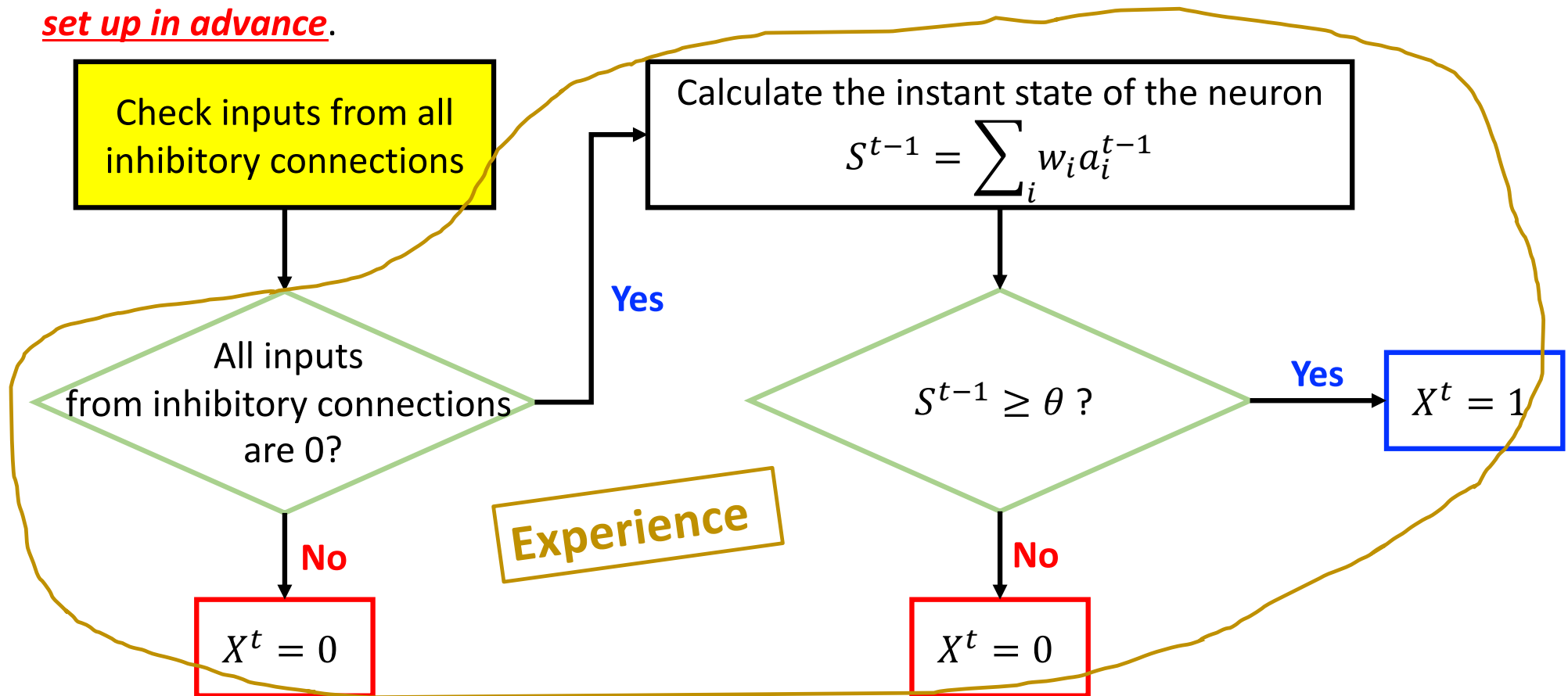
MP Neuron vs. Hebb's Rule

Given a fixed MP neuron, that is, **all weights of connections** and neuron threshold are set up in advance.



MP Neuron vs. Hebb's Rule

Given a fixed MP neuron, that is, **all weights of connections** and neuron threshold are set up in advance.



MP Neuron vs. Hebb's Rule

1. Set the neuron threshold value θ .
2. Set random initial values for the weights of connections w_i^t .
3. Give instant input values a_i^t by the input units.
4. Compute the instant state of the neuron $S^t = \sum_i w_i^t a_i^t$
5. Compute the instant output of the neuron X^{t+1}
$$X^{t+1} = g(S^t) = H(S^t - \theta) = \begin{cases} 1, & S^t \geq \theta; \\ 0, & S^t < \theta. \end{cases}$$
6. Compute the instant corrections to the weights of connections $\Delta w_i^t = C a_i^t X^{t+1}$
7. Update the weights of connections $w_i^{t+1} = w_i^t + \Delta w_i^t$
8. Go to the step 3.

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Experience

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Learning

Unsupervised Learning

- Unsupervised learning is a type of machine learning in which the algorithm **is not provided with any pre-assigned labels or scores for the training data**. As a result, unsupervised learning algorithms must first **self-discover any naturally occurring patterns** in that training data set.
- Hebb's rule, Oja's rule, Kohonen rule are all unsupervised learning rules.

ANN Learning Rules

- As for the first time the problem was formulated in **1940s**, when experimental neuroscience was limited, the classic definitions of these learning rules came not from biology, but

from psychological studies of
Donald Hebb and **Frank Rosenblatt**.

Unsupervised learning

ANN Learning Rules

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Unsupervised learning

Supervised learning

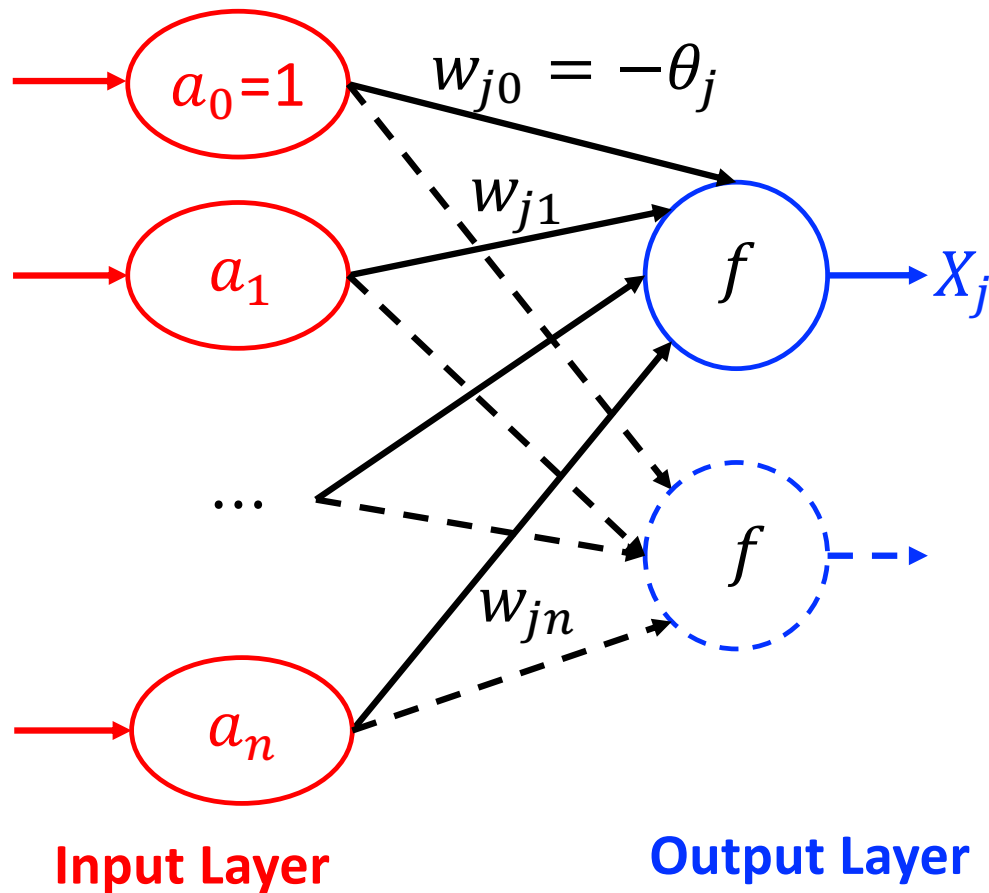
Topic 6.

Perceptron

Perceptron (1958)

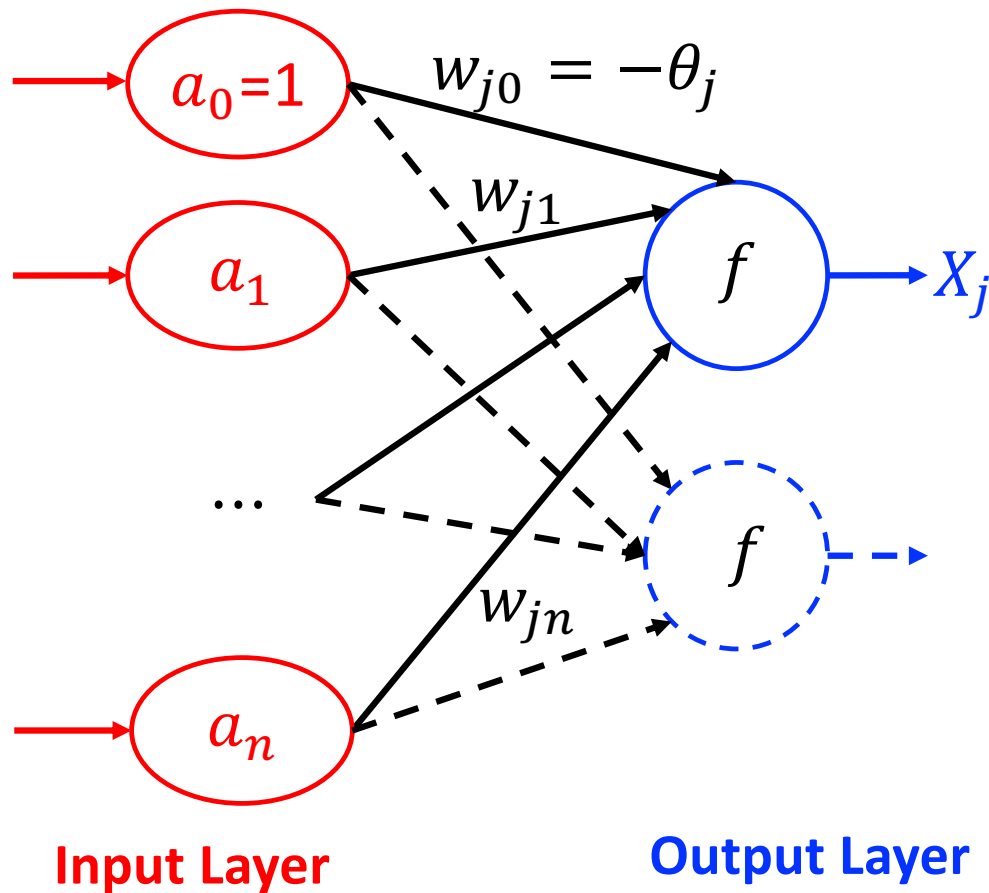
- **Rosenblatt** (1958) explicitly considered the ***problem of pattern recognition***, where a “*teacher*” is essential. (Consider the difference with unsupervised learning)
- A *Perceptron* is a neural network that changes with “experience” using an *error-correction rule*.
- According to the rule, **weight of a neuron changes when it makes error response to the input presented to the network.**

Perceptron (1958)



The simplest architecture of perceptron comprises **one layer of idealised “neurons”**, which we also sometimes call “units” of the network.

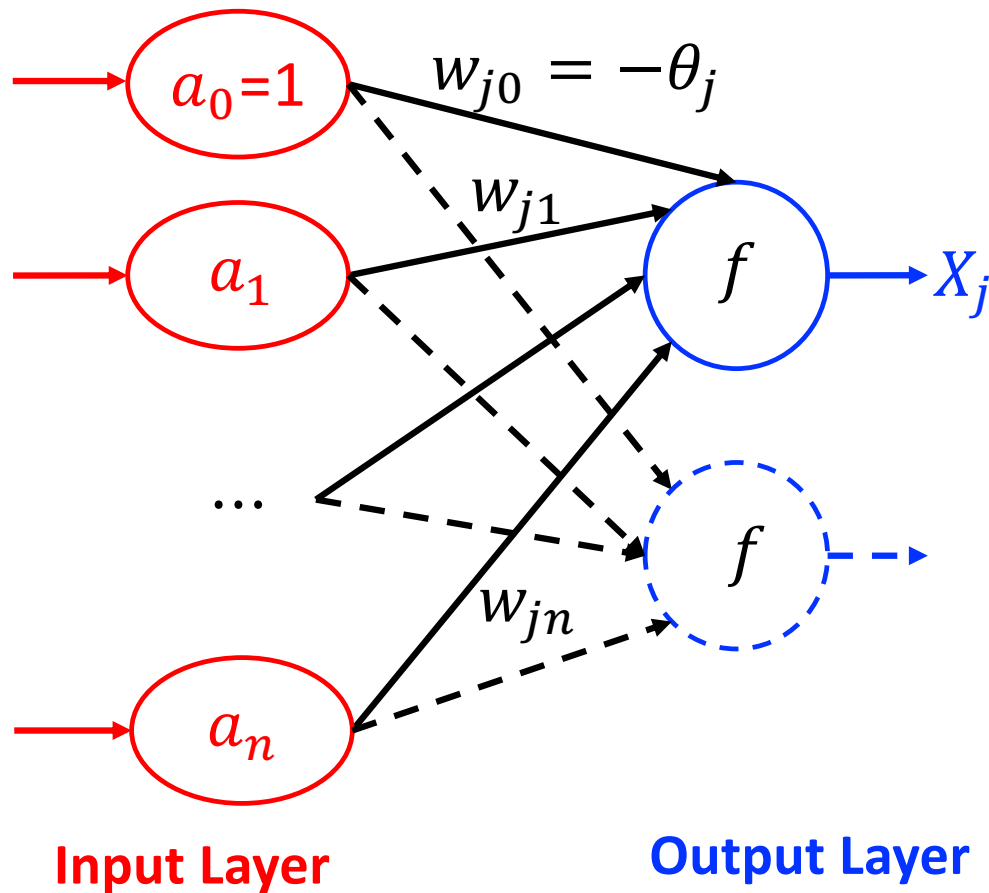
Perceptron (1958): Syntax and Structure



There are

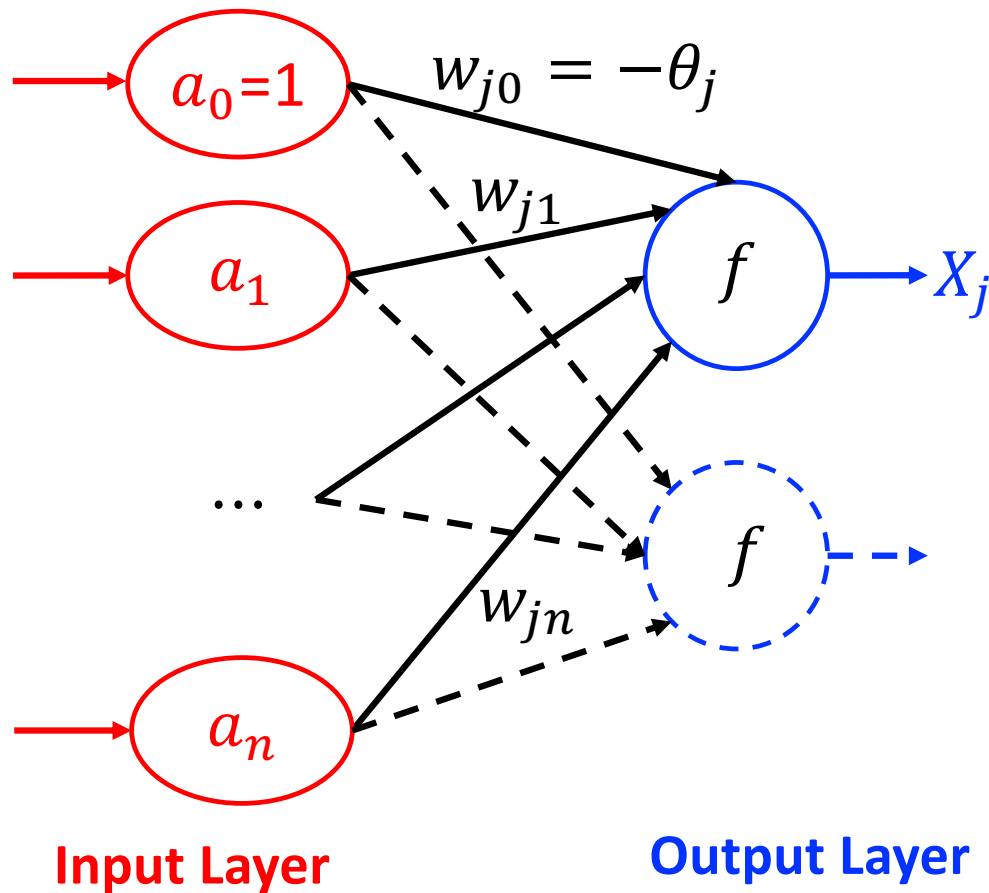
- One layer of inputs
- One layer of output neurons in the perceptron.

Perceptron (1958): Syntax and Structure



The two layers are **fully interconnected**, i.e. *every input neuron is connected to every output neuron.*

Perceptron (1958): Syntax and Structure



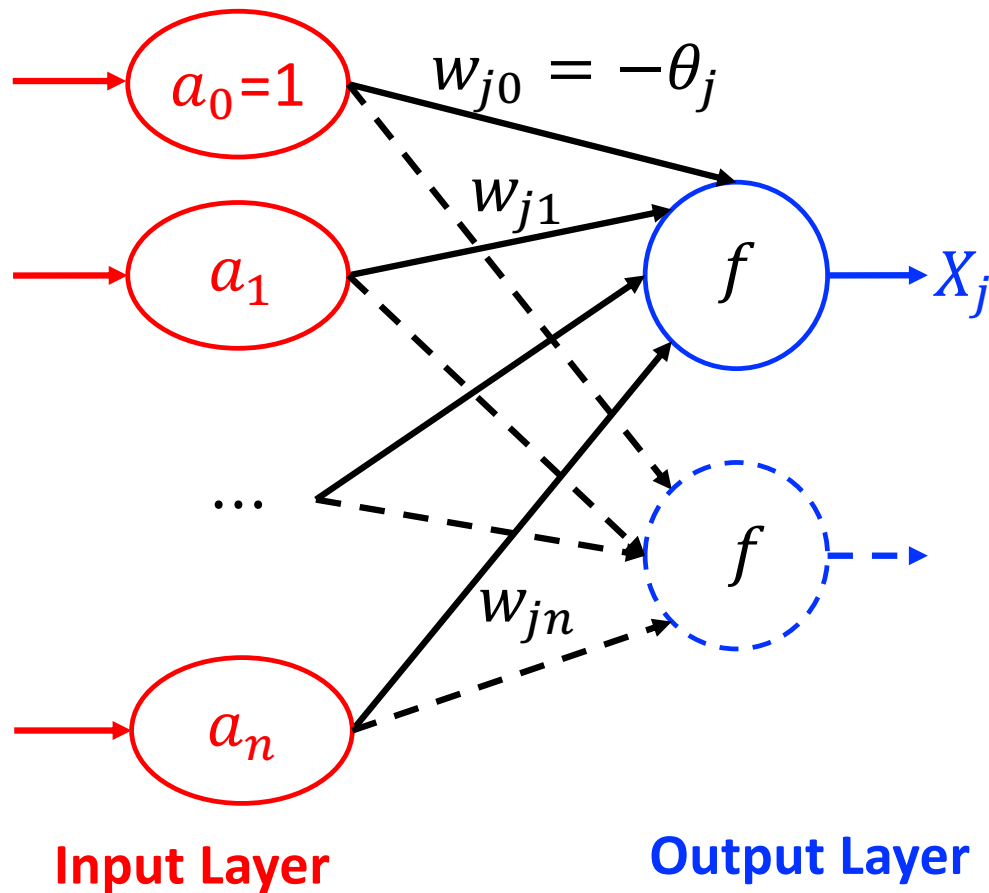
Semantically, a *perceptron* can be considered as a vector-valued function that maps the input

$$\underline{a} = \{a_0, a_1, \dots, a_n\}$$

to the output

$$X = \{X_1, X_2, \dots, X_m\}$$

Perceptron (1958): Syntax and Structure



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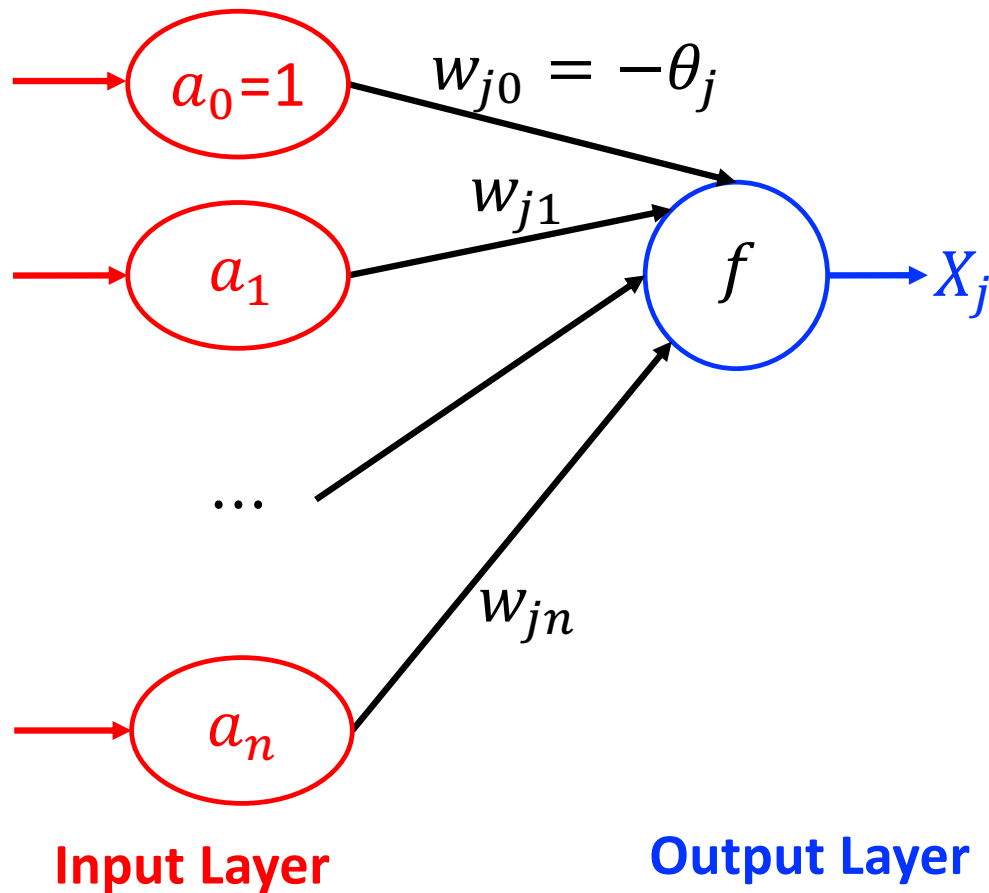
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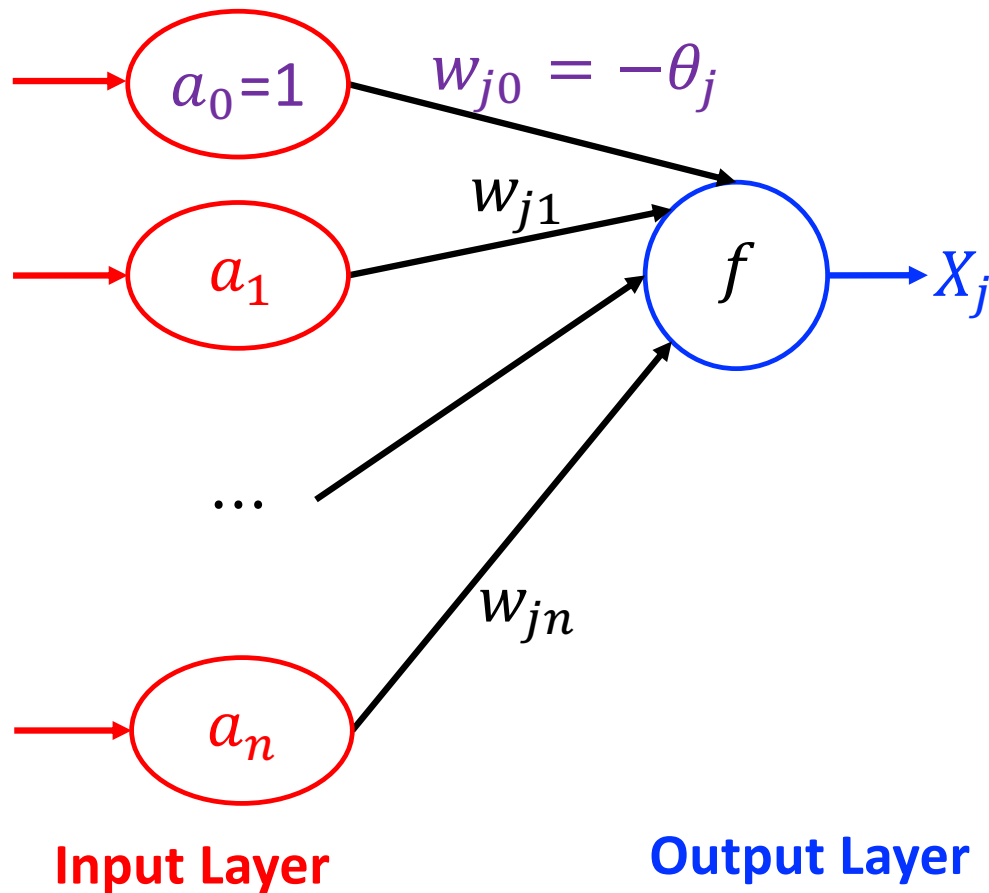
Similar to the model considered in Kohonen rule, a perceptron allows *real inputs*.

Perceptron (1958): Syntax and Structure



Each output neuron has the **same inputs**, that is, the total input layer. But individual outputs are with **individual connections and therefore have different weights** of connections. Thus, we can consider each output independently. For instance, let us consider the j -th output neuron.

Perceptron (1958): Semantics



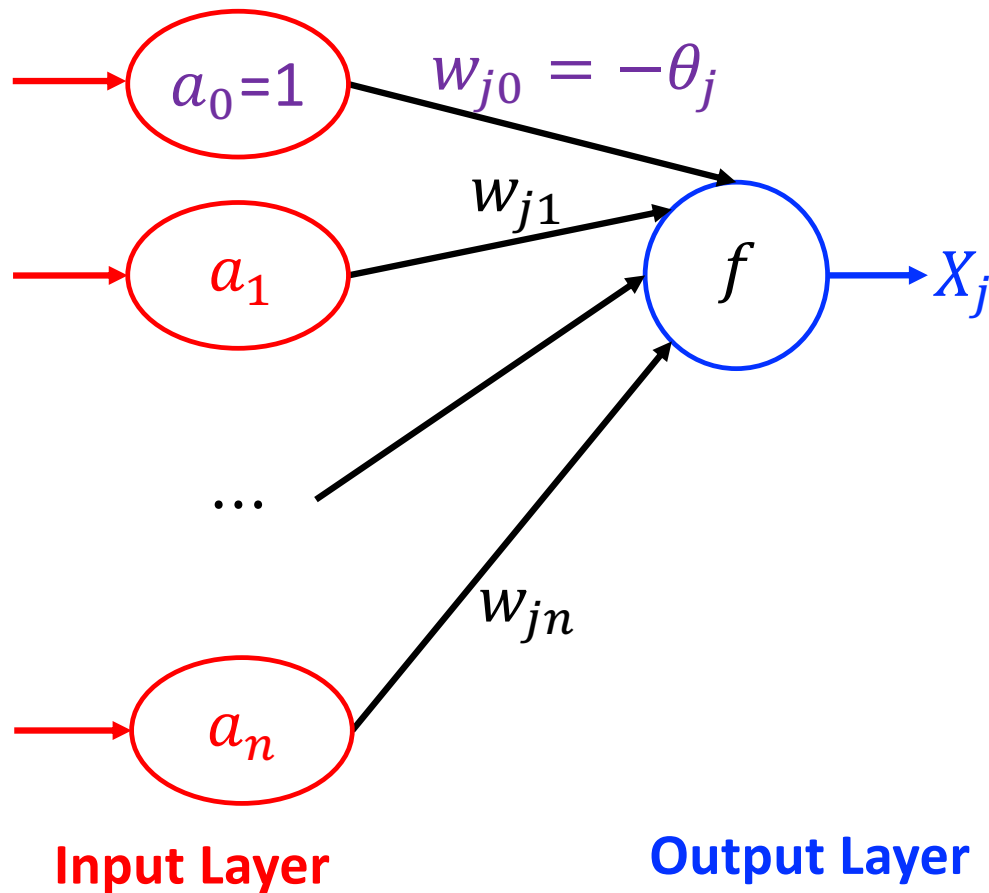
The weighted input to the j -th output neuron is

$$S_j = \sum_{i=0}^n w_{ji} a_i,$$

a_0 is a special input neuron with fixed input value of +1.

If we rename the weight of w_{j0} for the j -th output as $-\theta_j$...

Perceptron (1958): Semantics



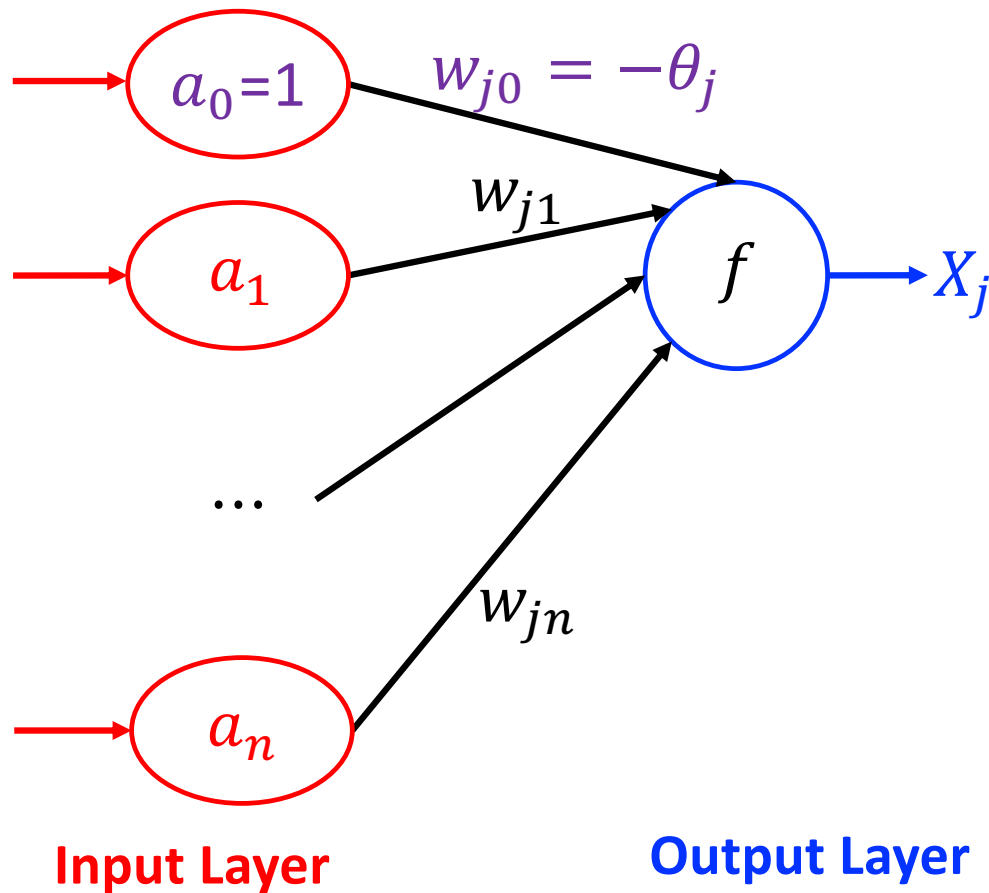
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$$\begin{aligned} S_j &= w_{j0} a_0 + \sum_{i=1}^n w_{ji} a_i \\ &= \underline{-\theta_j + \sum_{i=1}^n w_{ji} a_i} \end{aligned}$$

Perceptron (1958): Semantics



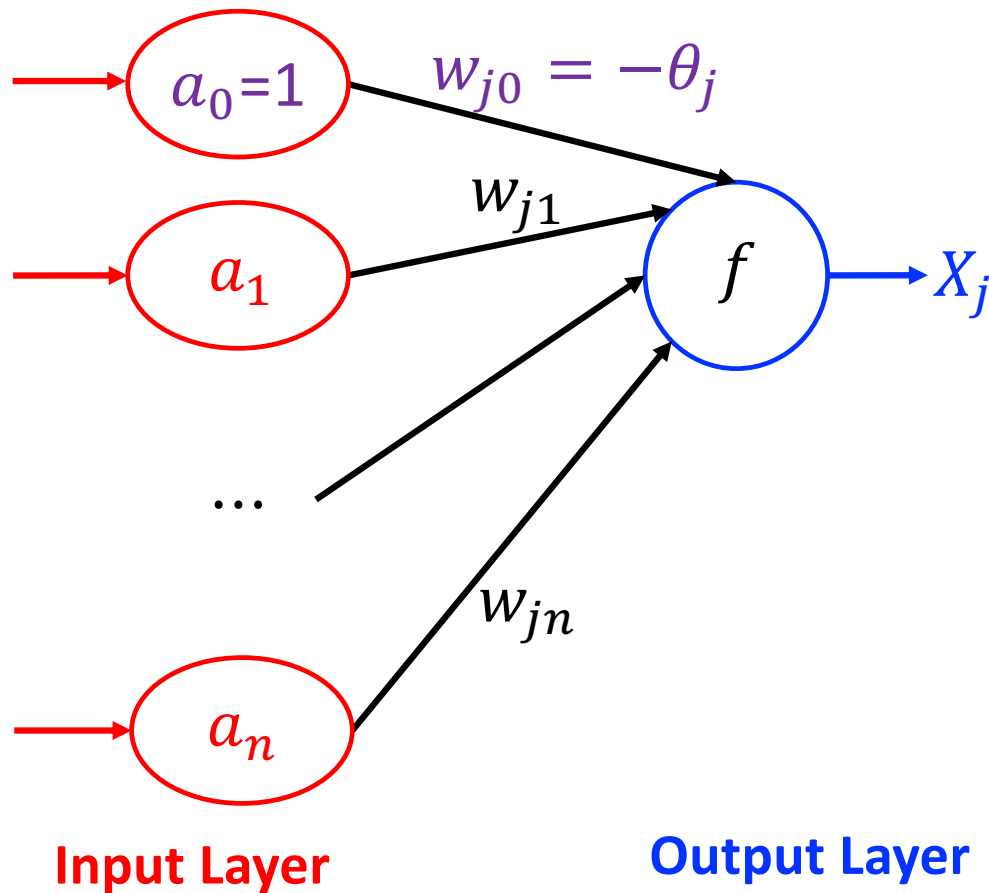
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With this trick, we have no need to set a threshold manually. Now we can **train the threshold like weights**.

Perceptron (1958): Semantics



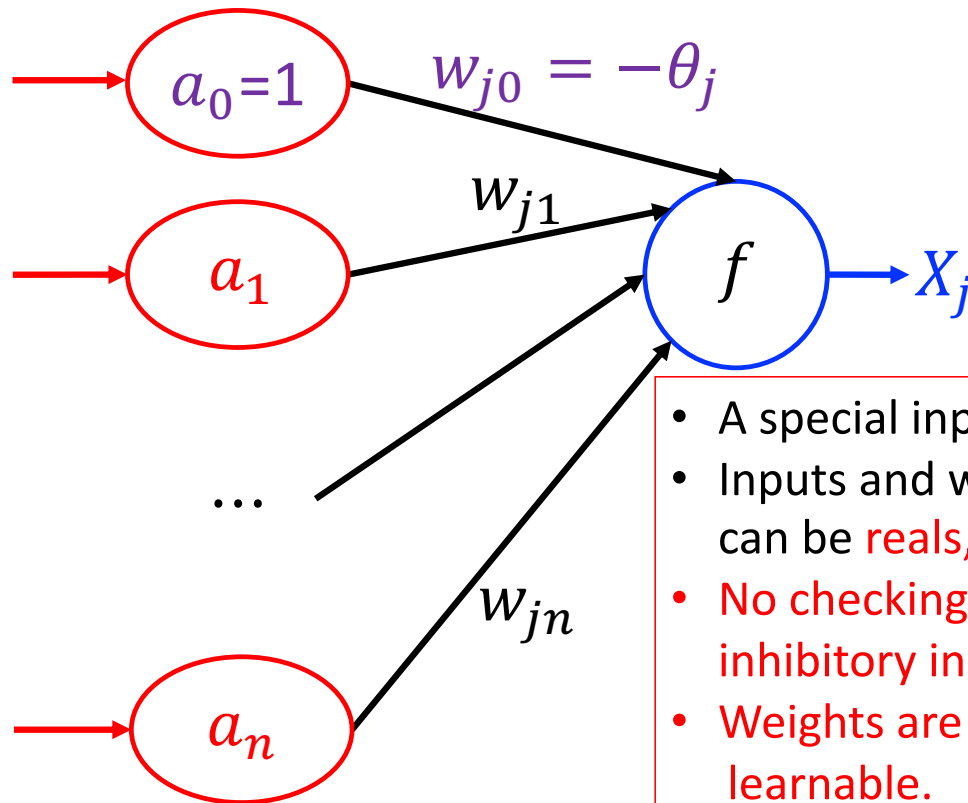
The value X_j of j -th output neuron depends on whether the weighted input is greater than **0**.

$$X_j = f(S_j) = \begin{cases} 1, & S_j \geq 0, \\ 0, & S_j < 0. \end{cases}$$

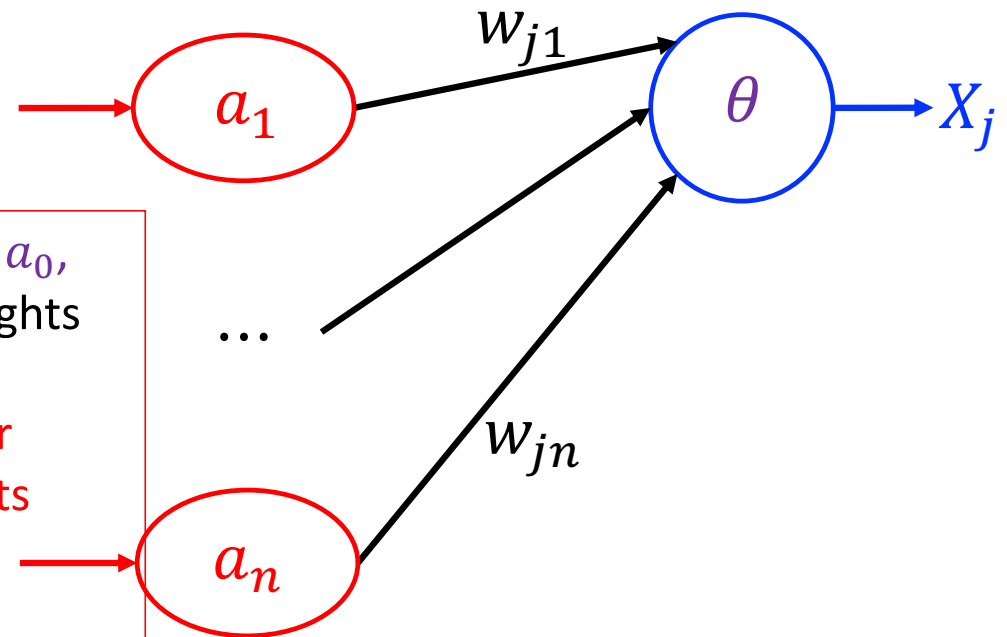
We call f as **activation function**.

MP Neuron vs. Perceptron (Syntax and Semantics)

Perceptron (one output)



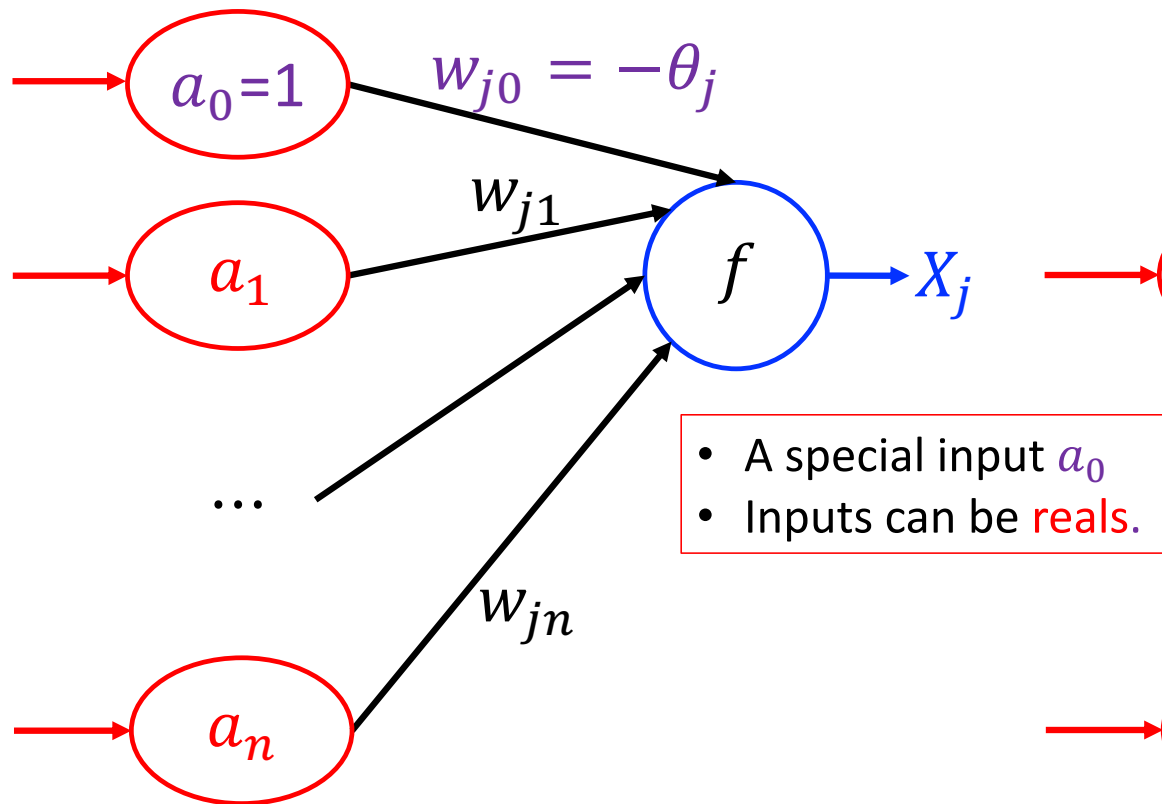
MP neuron (one output)



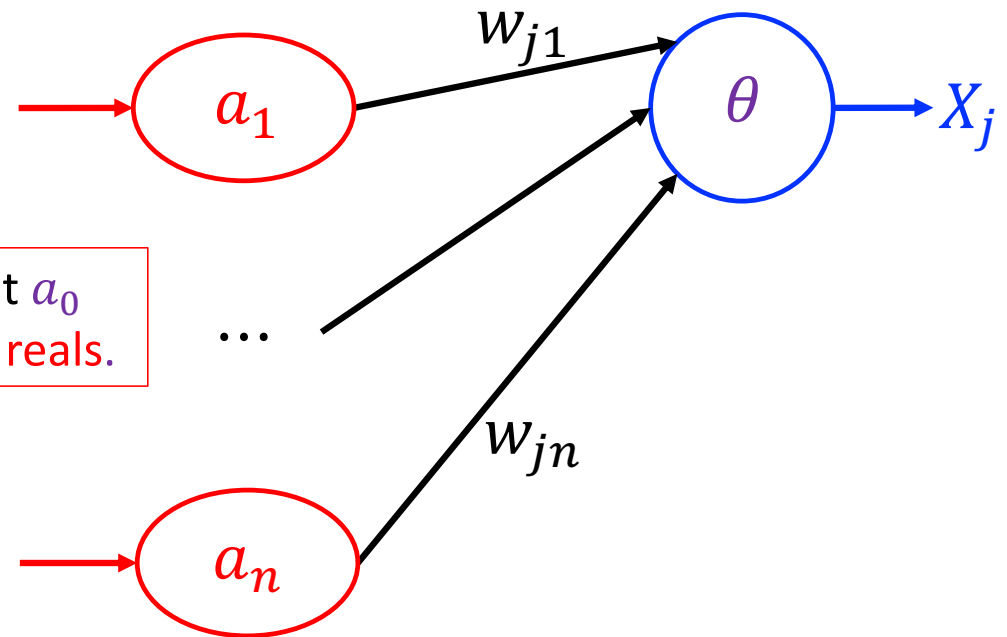
- A special input a_0 ,
- Inputs and weights can be **reals**,
- **No checking for inhibitory inputs**
- **Weights are learnable.**

Neuron Model in Hebb's Rule vs. Perceptron

Perceptron (one output)

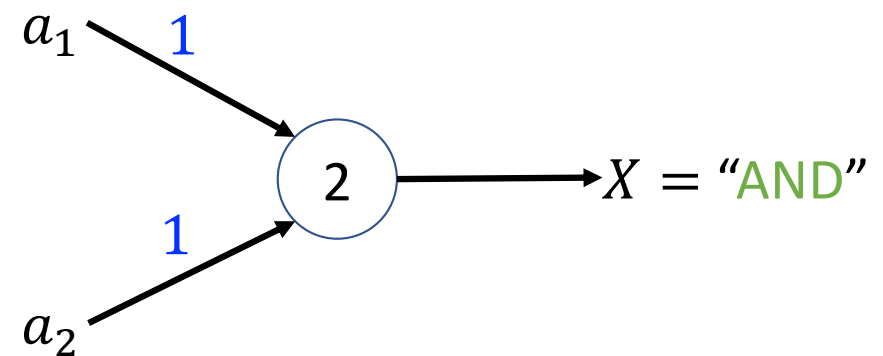


Neuron Model (Hebb's rule)



Recall MP Neuron

a_1	a_2	"AND"
1	1	1
0	1	0
1	0	0
0	0	0



MP neuron can only **"describe"**, but not **"learn"**.

Recall Unsupervised Learning

$$w_i^{t+1} = w_i^t + \Delta w_i^t,$$

Where

$$\Delta w_i^t = C a_i^t X^{t+1}$$

Hebb's Rule

$$w_i^{t+1} = w_i^t + \Delta w_i^t,$$

Where

$$\Delta w_i^t = C a_i^t X^{t+1}$$

Normalization:

$$\|w^t\| = 1$$

Oja's Rule

- The j^* -th output neuron has maximum weighted input at that instant t .

$$S_{j^*}^t = \max(S_1^t, \dots, S_m^t)$$

- Then the weight of the j -th neuron is updated as

$$w_{ji}^{t+1} = w_{ji}^t + \Delta w_{ji}^t$$

where $i = 1, \dots, n$, for $j = 1, \dots, m$.

- The incremental term Δw_{ji}^{t+1} :

$$\Delta w_{ji}^{t+1} = C(t)(a_i^t - w_{ji}^t)\theta(j, j^*)$$

Where $\theta(j, j^*)$ is a restraint function due to the distance between neuron j and j^* .

Kohonen Rule

Unsupervised learning can only learn “**similarity**”,
but not predict “**desired output**”.

What can a Perceptron be used for?

- Similar to Hebb's rule, we adjust weights (training) between two layers to learn knowledge from a given data set.
- If the data set is unlabeled, we can train the perceptron network to cluster the inputs to different groups (unsupervised learning).

What can a Perceptron be used for?

- Similar to Hebb's rule, we adjust weights (training) between two layers to learn knowledge from a given data set.
- If the data set is unlabeled, we can train the perceptron network to cluster the inputs to different groups (unsupervised learning).
- If the data set is labeled, we can train the perceptron network to produce the desired output in response to certain inputs (supervised learning).