Probabilistic Classifiers



Probabilistic vs "ordinary" classifier

• "Ordinary" classifier is a function f that assigns to an input object \overline{X} a predicted class c from a fixed set of classes $\{c_1, c_2, \ldots, c_k\}$, i.e.

$$c = f(\overline{X}).$$

• Probabilistic classifier is a <u>conditional distribution P(C|X)</u>. For an input object \overline{X} it gives probabilities $p_1, p_2, ..., p_k$, where

$$p_i = P(c_i \mid \overline{X})$$

and
$$p_1 + p_2 + ... + p_k = 1$$
.

Two types of models: discriminative vs generative

Discriminative

- Assume that the conditional distribution P(C|X) (i.e. the probabilistic classifier) has specific form $P_{\theta}(C|X)$ depending on some parameters $\theta=(\theta_1,\ldots,\theta_k)$
- Use training data set to **find** / **learn** parameters $\theta_1, \ldots, \theta_k$ such that the resulting distribution is "best possible" among all distributions of the assumed form

Generative

- Assume that data come from specific distribution $P_{\theta}(X,C)$ depending on some parameters $\theta = (\theta_1, ..., \theta_k)$
- Use training data set to **find** / **learn** parameters $\theta_1, \ldots, \theta_k$ such that the resulting distribution is "best possible" among all distributions of the assumed form
- Use $P_{\theta}(X, C)$ to classify new objects

Generative models

Data generating distribution

- Assumption: data come from some unknown probability distribution P over object-class pairs $(\overline{X}, c) \in \mathcal{X} \times \mathcal{C}$, i.e. the classification problem is characterised by P.
- Suppose we know P: for any pair $(\overline{X}, c) \in \mathcal{X} \times \mathcal{C}$ we can compute $P(\overline{X}, c)$, i.e., the probability of the event that an object with feature vector \overline{X} belongs to class c.

Then we can compute the Bayes optimal classifier $f^*(\overline{X}) = \arg\max_{c \in \mathscr{C}} P(\overline{X},c)$

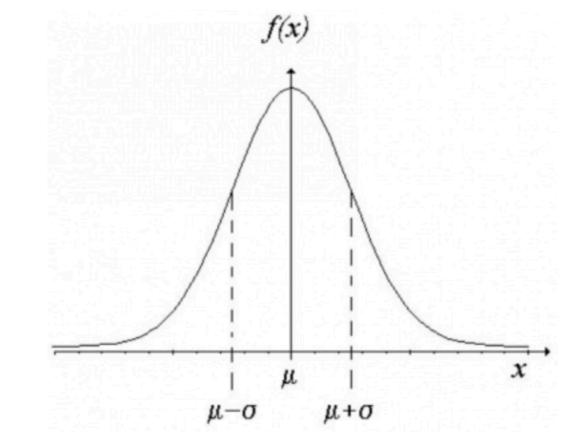
Bayes optimal classifier

The Bayes optimal classifier
$$f^*(\overline{X}) = \arg\max_{c \in \mathscr{C}} P(\overline{X}, c)$$

The Bayes optimal classifier is best possible, in the sense that

if g is another classifier, then for any $\overline{X}\in\mathcal{X}$ the probability that f^* errs on \overline{X} is smaller than the probability that g errs on \overline{X}

In practice...



- We do not now the data generating distribution P
- Instead, using training data, we can try to learn a distribution \hat{P} , which we hope to be very similar to P
- And then use \hat{P} for classification

Normal distribution $\mathcal{N}(\mu, \sigma)$ is **parametric**: the two parameters are mean (μ) and standard deviation (σ)

One of the ways to construct \hat{P}

- Assume that the distribution P belongs (or is "close" to) some family of parametric distributions (e.g. Normal distribution) (the **model assumption**)
- Estimate parameters which give specific distribution in the family that is most likely to be the generating distribution for the training data
- Key assumption: the training data is drawn from P independently, i.e. the training instances are (\overline{X}, c) are independently and identically distributed (the i.i.d. assumption)

Estimation of parameters

A common approach to estimate parameters is

Maximum likelihood estimation method

Choose the parameters that **maximise** the **probability** (i.e. **likelihood**) of the observed (i.e. training) data

Example 1

- Suppose we want to model a biased coin (or a class in binary classification problem)
- and observe data THHH, where H heads, T tails.
- Assume further:
 - All the flips came from the same coin and each flip was independent (the i.i.d. assumption)
 - The coin has a fixed probability β of coming up heads and the probability 1β of coming up tails, i.e. we assume that the data generation distribution is from the family of **Bernoulli distributions parameterised** by the probability of heads $\beta \in [0,1]$ (the **model assumption**)

Example 1

- Observed data: THHH
- For the heads probability β the probability of observed data:

$$P_{\beta}(THHHH) = P_{\beta}(T) \cdot P_{\beta}(H) \cdot P_{\beta}(H) \cdot P_{\beta}(H)$$
$$= (1 - \beta)\beta\beta\beta = (1 - \beta)\beta^3 = \beta^3 - \beta^4$$

Example 1

- To find β that maximises $P_{\beta}(THHH) = \beta^3 \beta^4$
 - compute the derivative of $\beta^3 \beta^4$ $\frac{\partial}{\partial \beta} [\beta^3 \beta^4] = 3\beta^2 4\beta^3$
 - set it equal to 0
 - and solve for β

$$3\beta^2 - 4\beta^3 = 0 \Leftrightarrow 3\beta^2 = 4\beta^3$$

$$\beta = \frac{3}{4}$$
 — the maximum likelihood estimate of β

Example 2 (generalisation)

- Assume that the observed data consists of h heads and t tails
- Then the probability of the observed data is $\beta^h(1-\beta)^t$
- Instead of maximising the probability it is often more convenient to maximise its logarithm (this is called the log likelihood or log probability)
- In our example log likelihood = $\log(\beta^h(1-\beta)^t) = h\log\beta + t\log(1-\beta)$

Exercise compute the maximum likelihood estimate of β .

Example 3

- Suppose we want to model a K-sided die (or a class in multiclass classification problem)
- We can model this with parameters $\beta_1, \beta_2, ..., \beta_K$, where β_i is the probability of having the i-th side of the die. Since β 's are probabilities, we should also assume:
 - $\beta_i \ge 0$ for every i = 1, ..., K, and
 - $\beta_1 + \beta_2 + ... + \beta_K = 1$

The model assumption is that the data generating distribution is from the parametric family of generalised Bernoulli distribution

Example 3

- Suppose the observed data consists of x_1 rolls of 1, x_2 rolls of 2, and so on
- Then the probability of this data is $\beta_1^{x_1} \cdot \beta_2^{x_2} \cdot \ldots \cdot \beta_K^{x_K}$ and
- The log probability (i.e. log likelihood) is

$$\sum_{i=1}^{K} x_i \log \beta_i$$

• Thus to find the maximum likelihood estimate of β 's we need to find β 's that maximise the log likelihood subject to constraint $\beta_1 + \beta_2 + \ldots + \beta_K = 1$

Example 3

$$\max_{\beta_1,...,\beta_K} \sum_{i=1}^K x_i \log \beta_i$$
subject to
$$\sum_{i=1}^K \beta_i - 1 = 0$$

Using the method of Lagrange multipliers we obtain the following Lagrangian

$$\mathscr{L}(\overline{\beta}, \lambda) = \mathscr{L}(\beta_1, \dots, \beta_K, \lambda) = \sum_{i=1}^K x_i \log \beta_i - \lambda \left(\sum_{i=1}^K \beta_i - 1\right)$$

Example 3

• For fixed i, we have

$$\frac{\partial \mathcal{L}(\overline{\beta}, \lambda)}{\partial \beta_i} = \frac{x_i}{\beta_i} - \lambda$$

$$\frac{\partial \mathcal{L}(\overline{\beta}, \lambda)}{\partial \beta_i} = \frac{\beta_i}{\beta_i}$$

Setting $\frac{\partial \mathscr{L}(\overline{\beta},\lambda)}{\partial \beta_i}$ to 0 and solving with respect to β_i we get

$$\beta_i = \frac{x_i}{\lambda}$$

Example 3

From the constraint $\beta_1+\beta_2+\ldots+\beta_K=1$, (which is equivalent to $\frac{\partial \mathcal{L}(\overline{\beta},\lambda)}{\partial \lambda}=0$) we have

$$\frac{x_1 + \ldots + x_K}{\lambda} = 1$$

and hence
$$\lambda = \sum_{i=1}^{K} x_i$$
.

Thus the maximum likelihood estimate of β 's is

$$\beta_i = \frac{x_i}{\sum_{i=1}^K x_i} \text{ for every } i = 1, \dots, K$$

Probabilistic classifiers

Generative

Naive Bayes

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Discriminative

- Logistic regression
- Multilayer perceptrons (neural networks)

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