

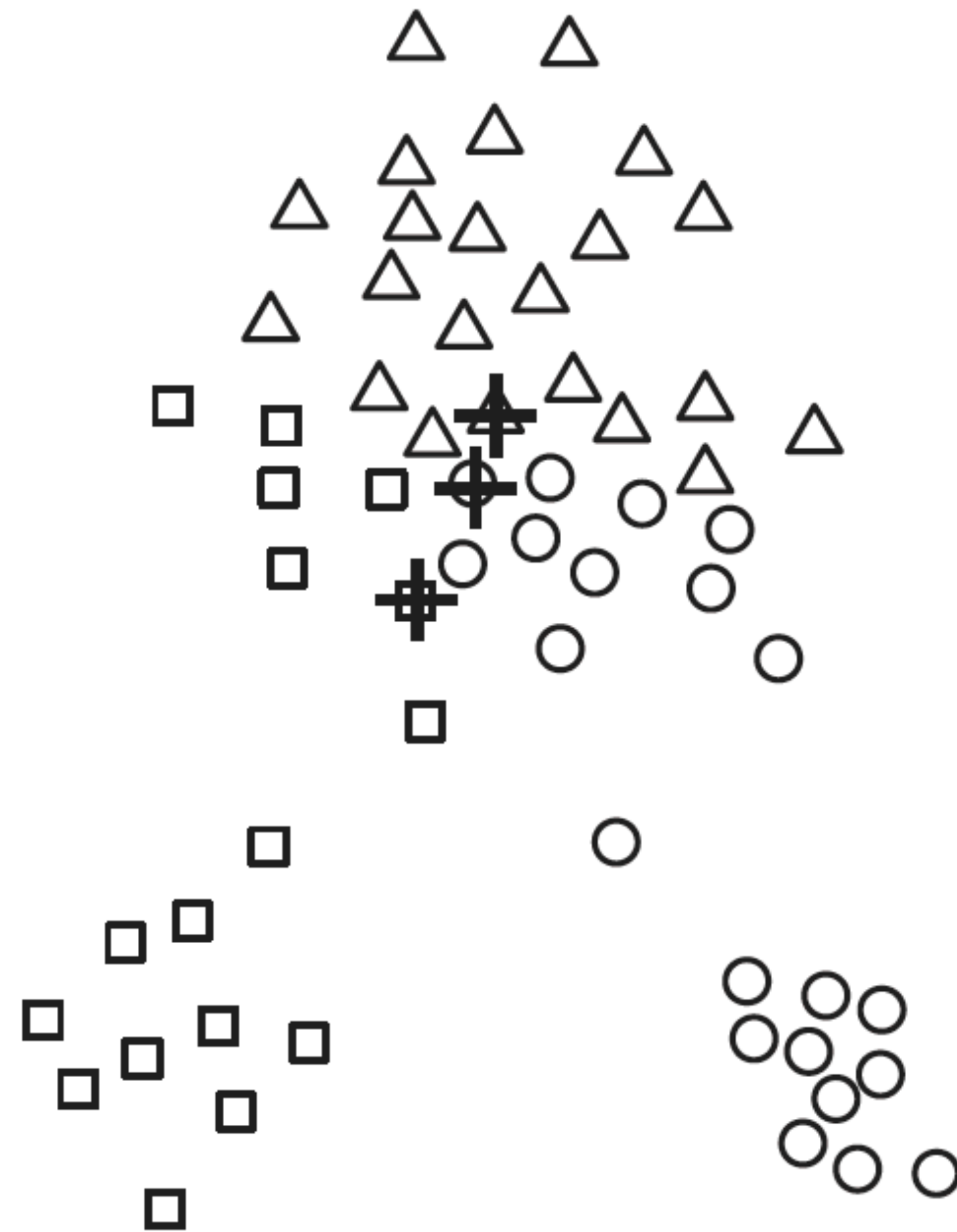
k-Means algorithm

How to choose initial cluster representatives?

How to choose initial cluster representatives

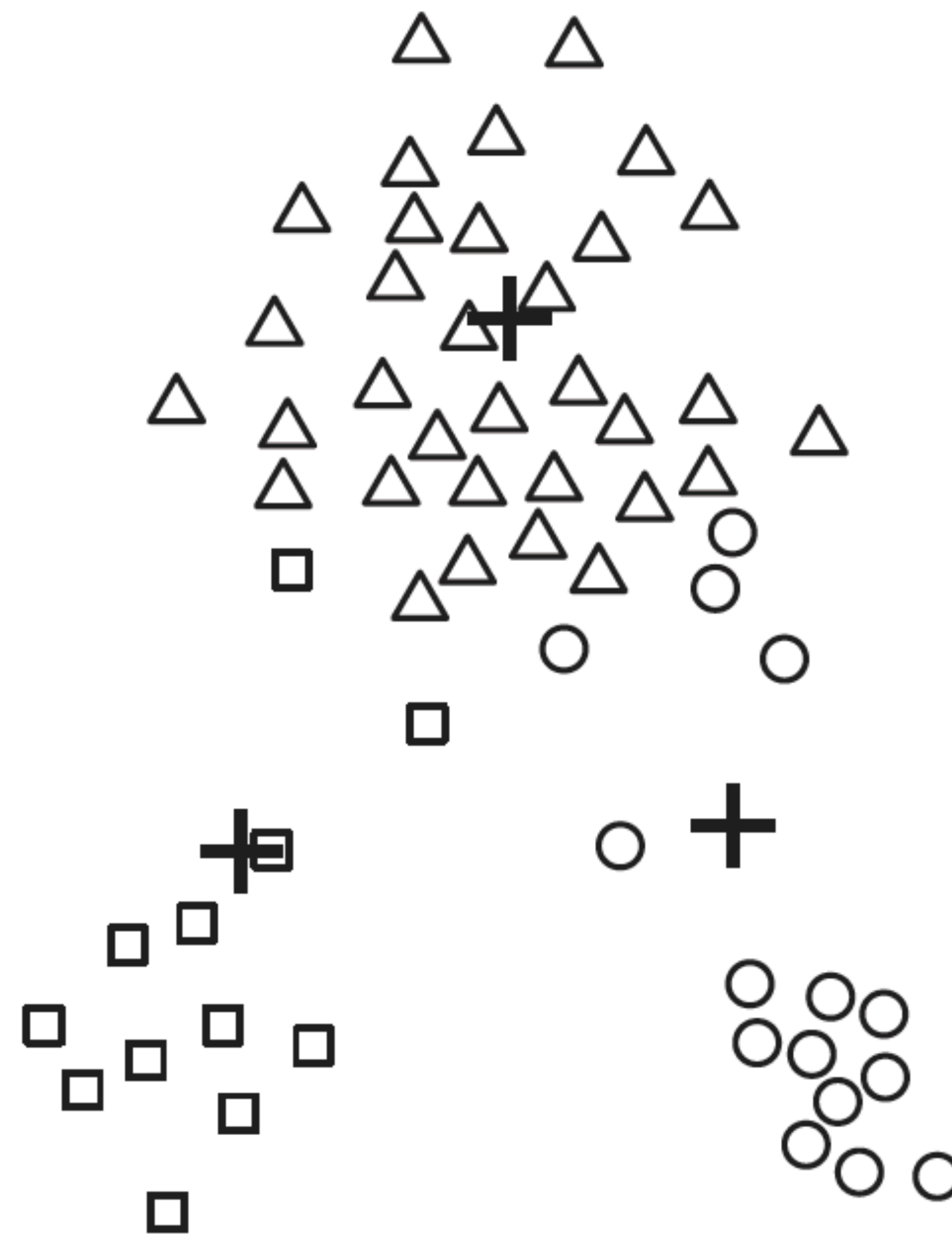
1. Randomly
2. Randomly repeat several times
3. Sampling + hierarchical clustering
4. Furthest points
5. k-means++

Choosing randomly: lucky choice



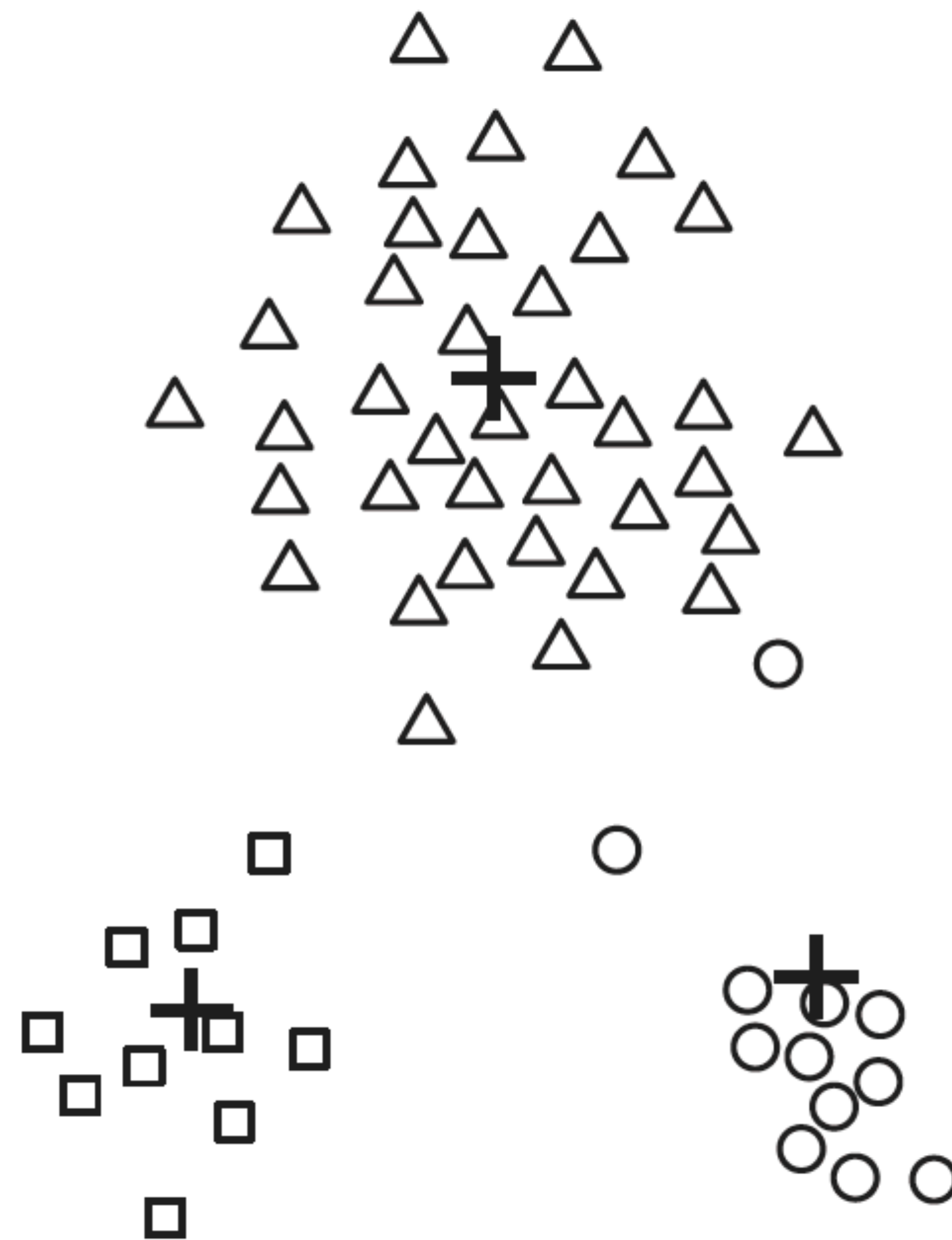
Iteration 1

Choosing randomly: lucky choice



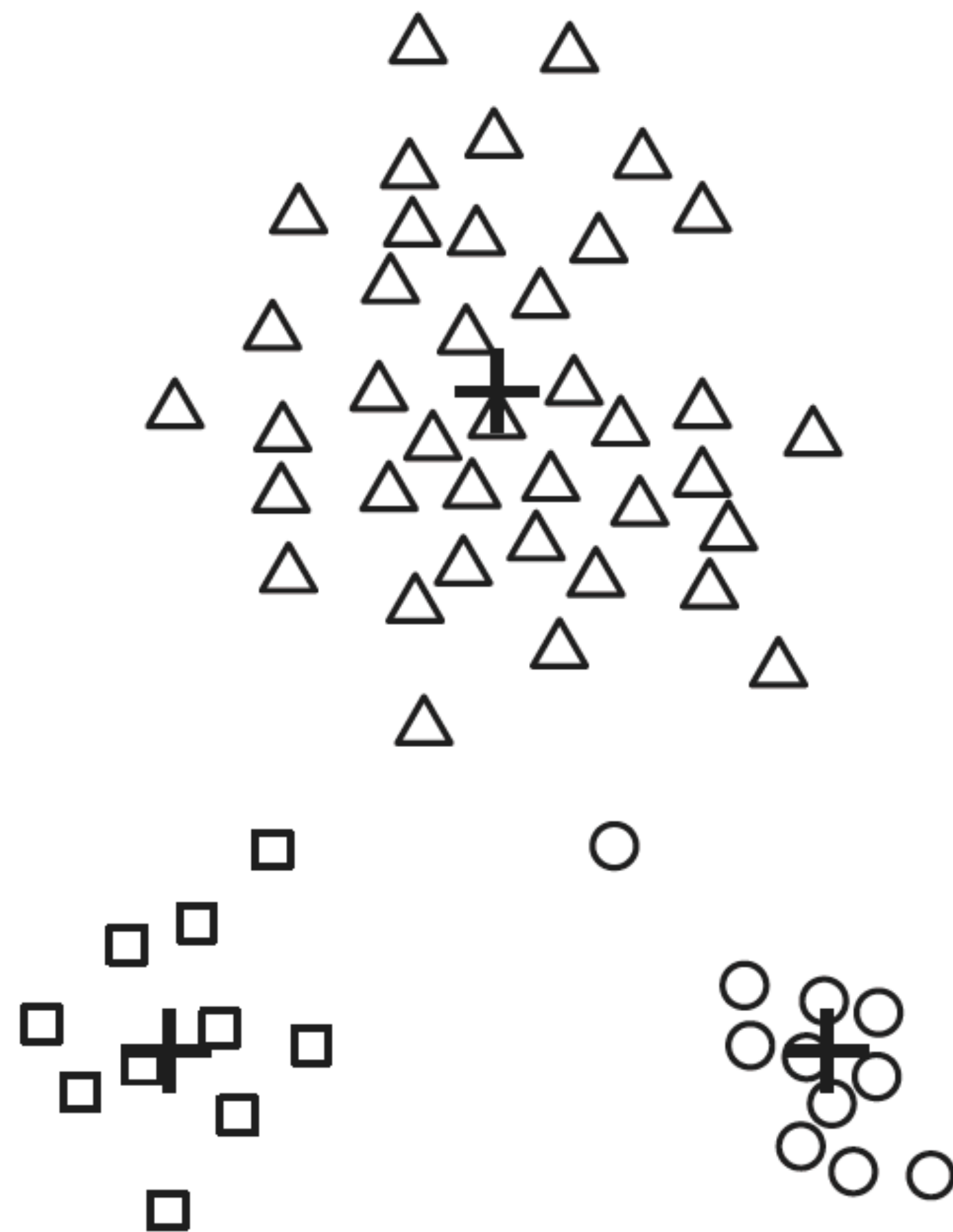
Iteration 2

Choosing randomly: lucky choice



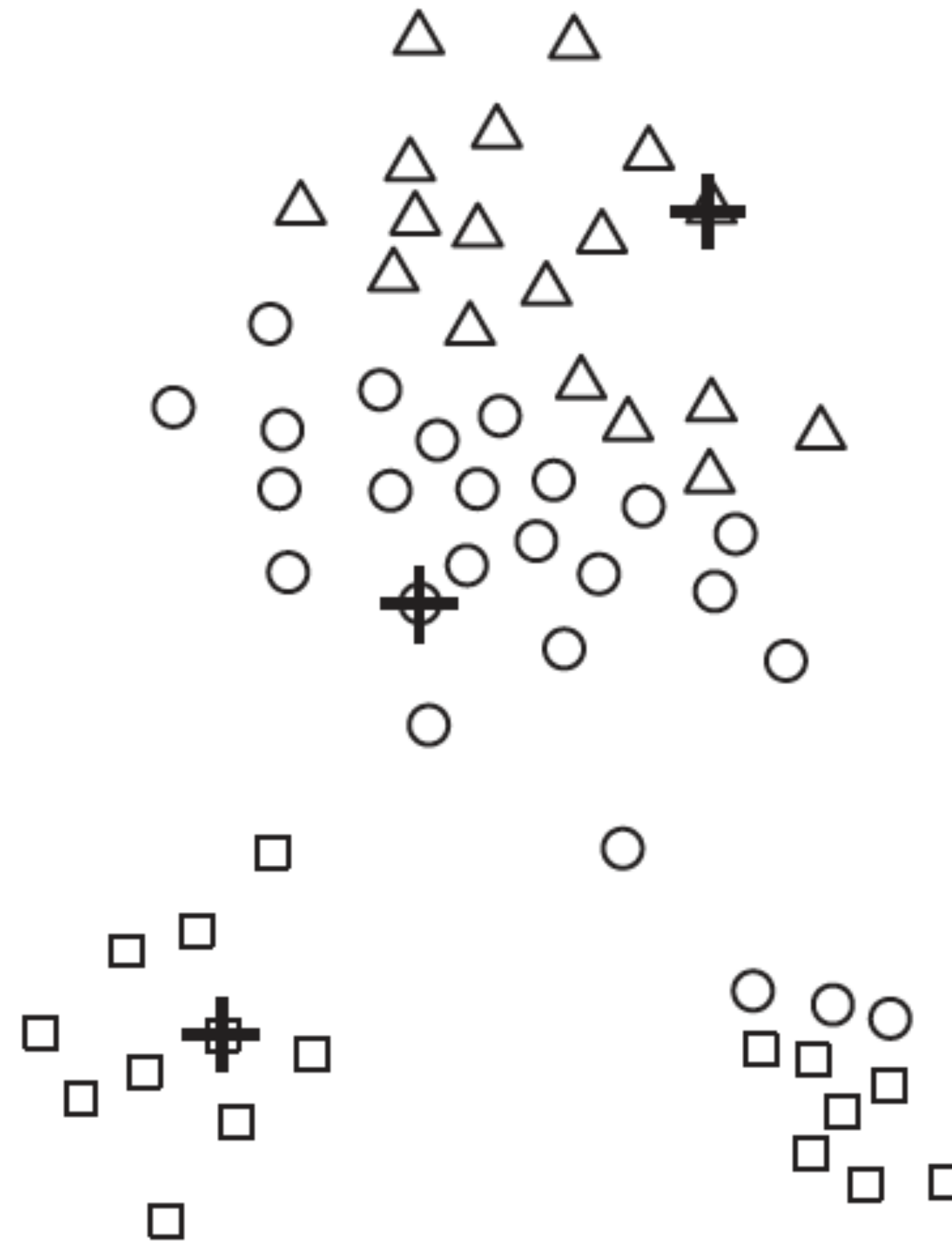
Iteration 3

Choosing randomly: lucky choice



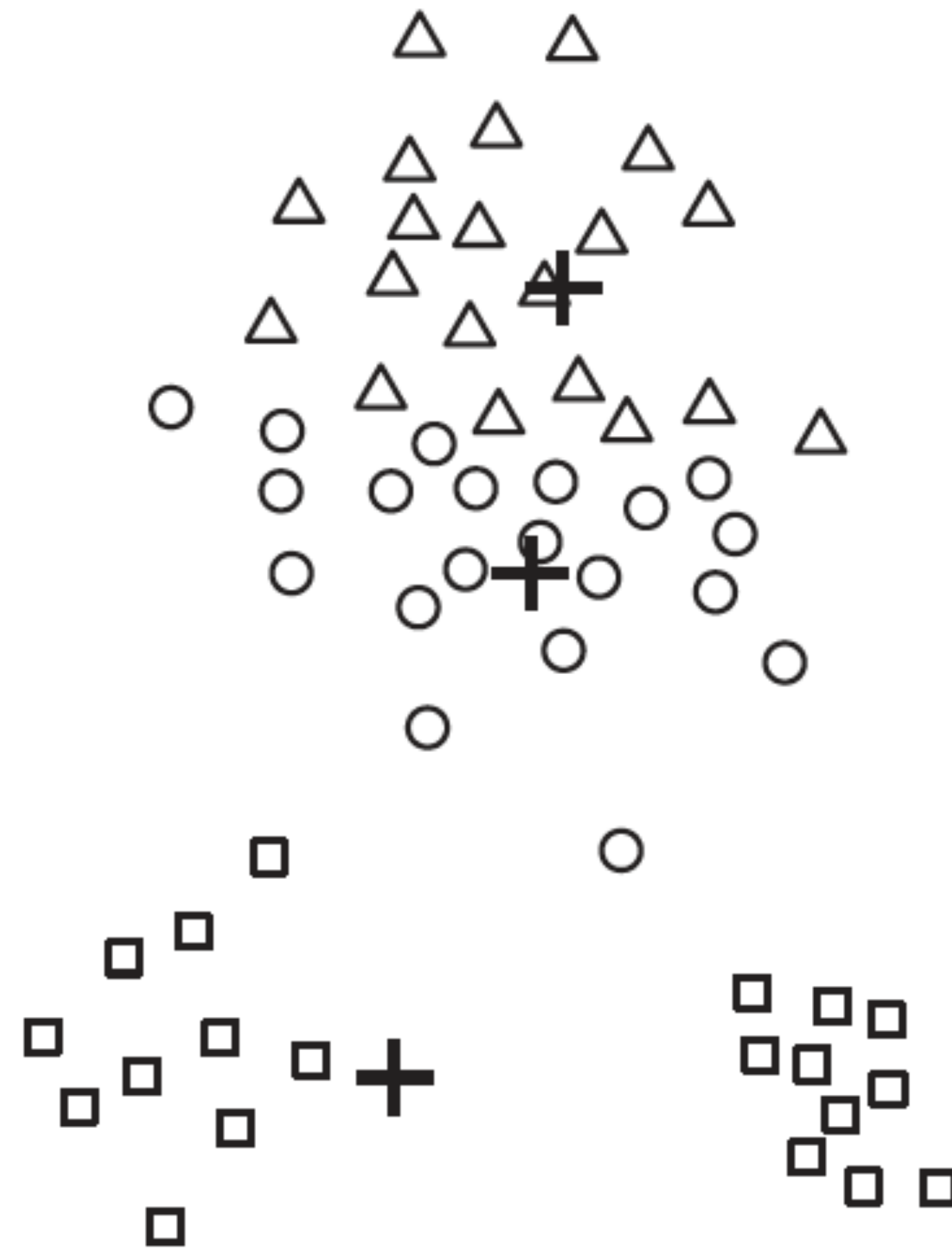
Iteration 4

Choosing randomly: **un**lucky choice



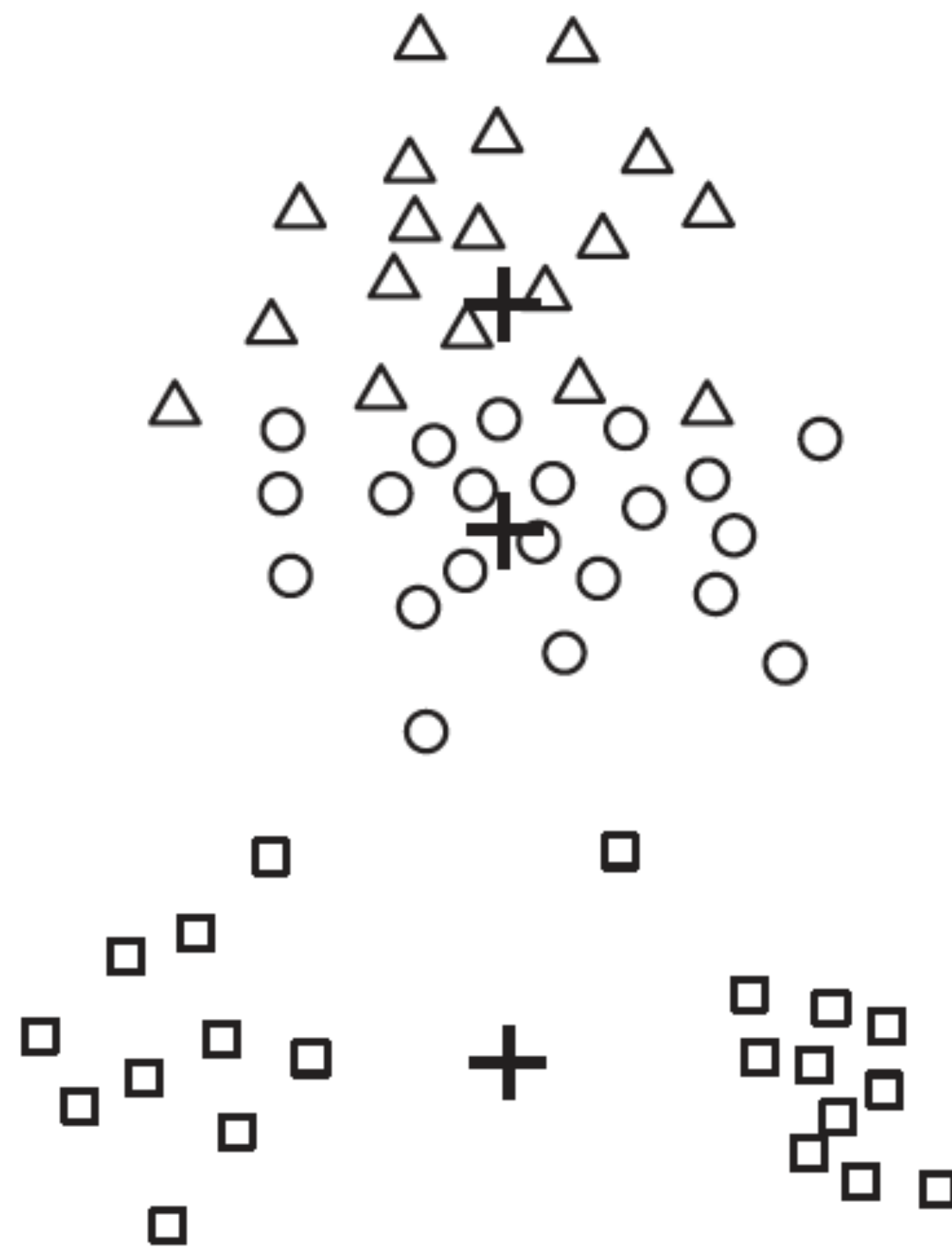
Iteration 1

Choosing randomly: **un**lucky choice



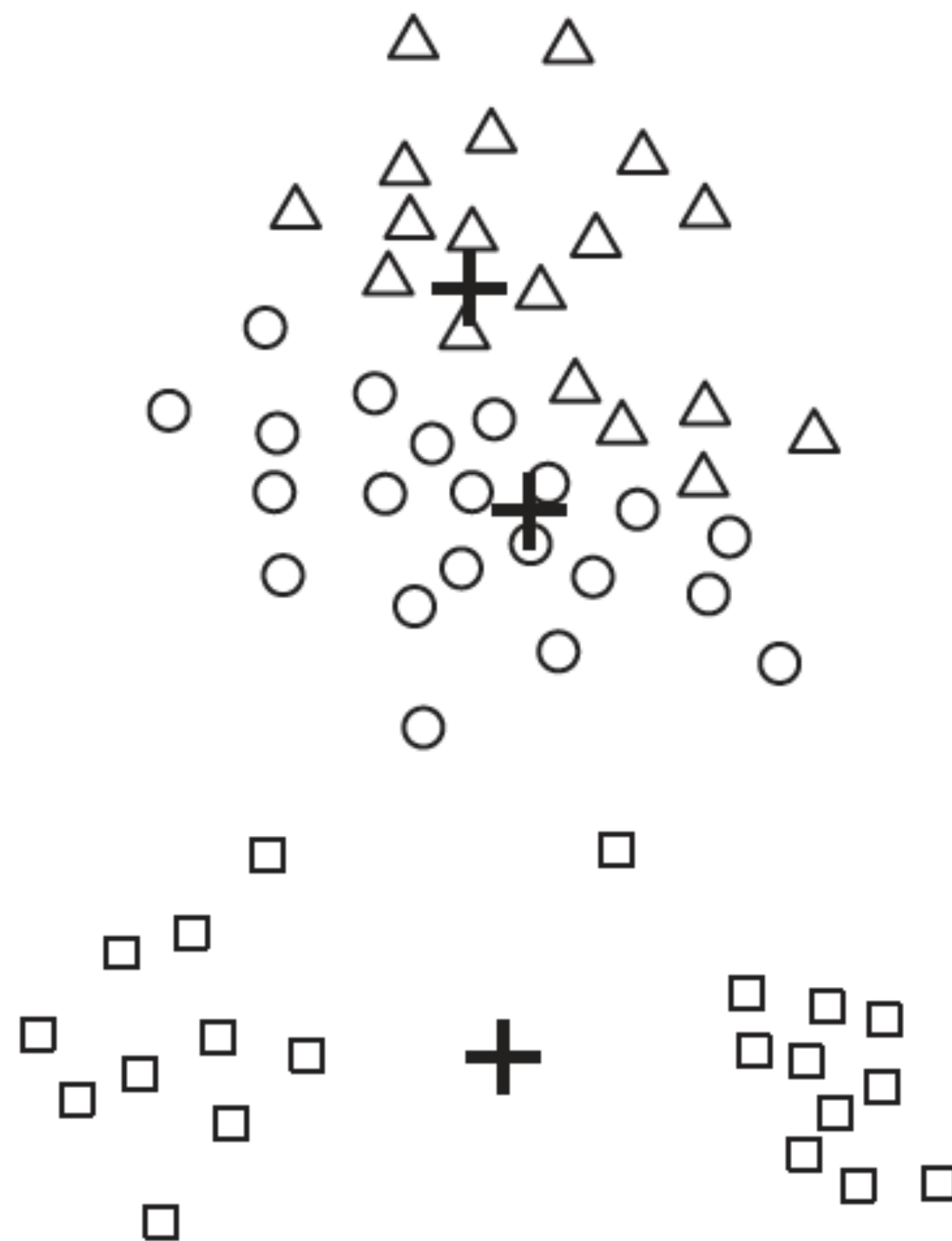
Iteration 2

Choosing randomly: **un**lucky choice



Iteration 3

Choosing randomly: **un**lucky choice

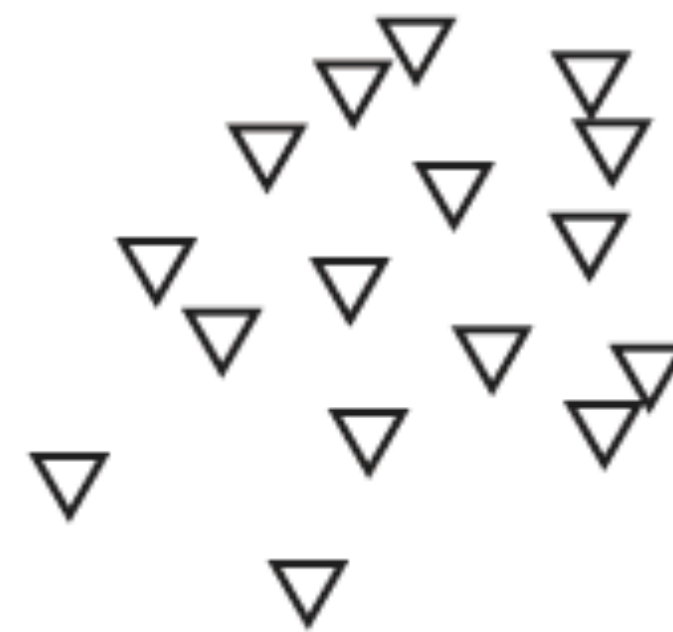
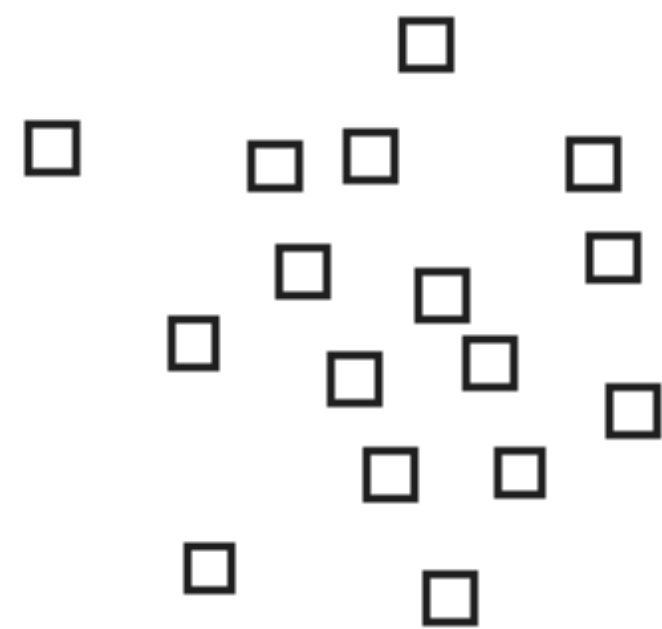
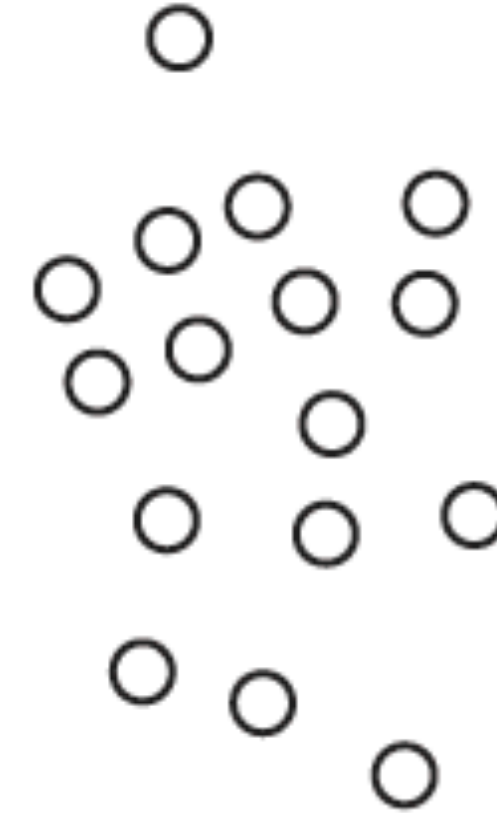
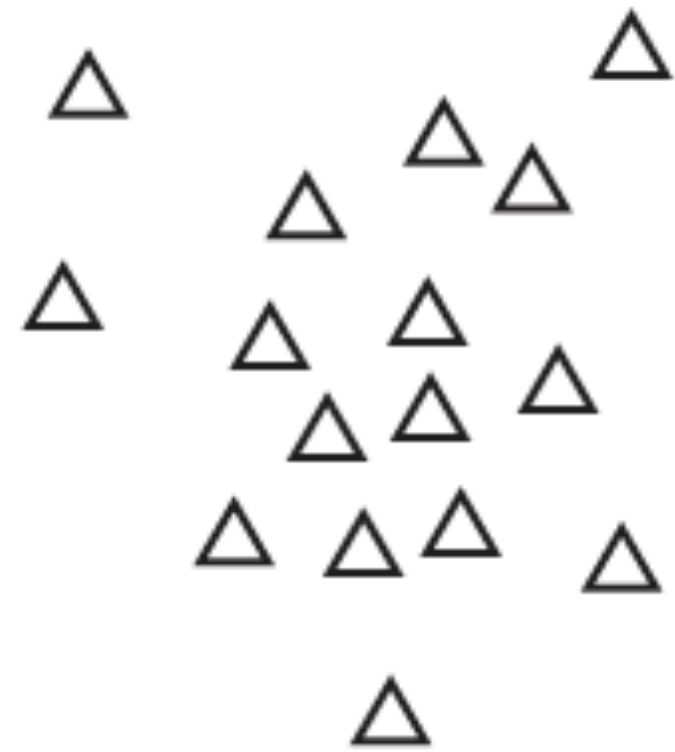


Iteration 4

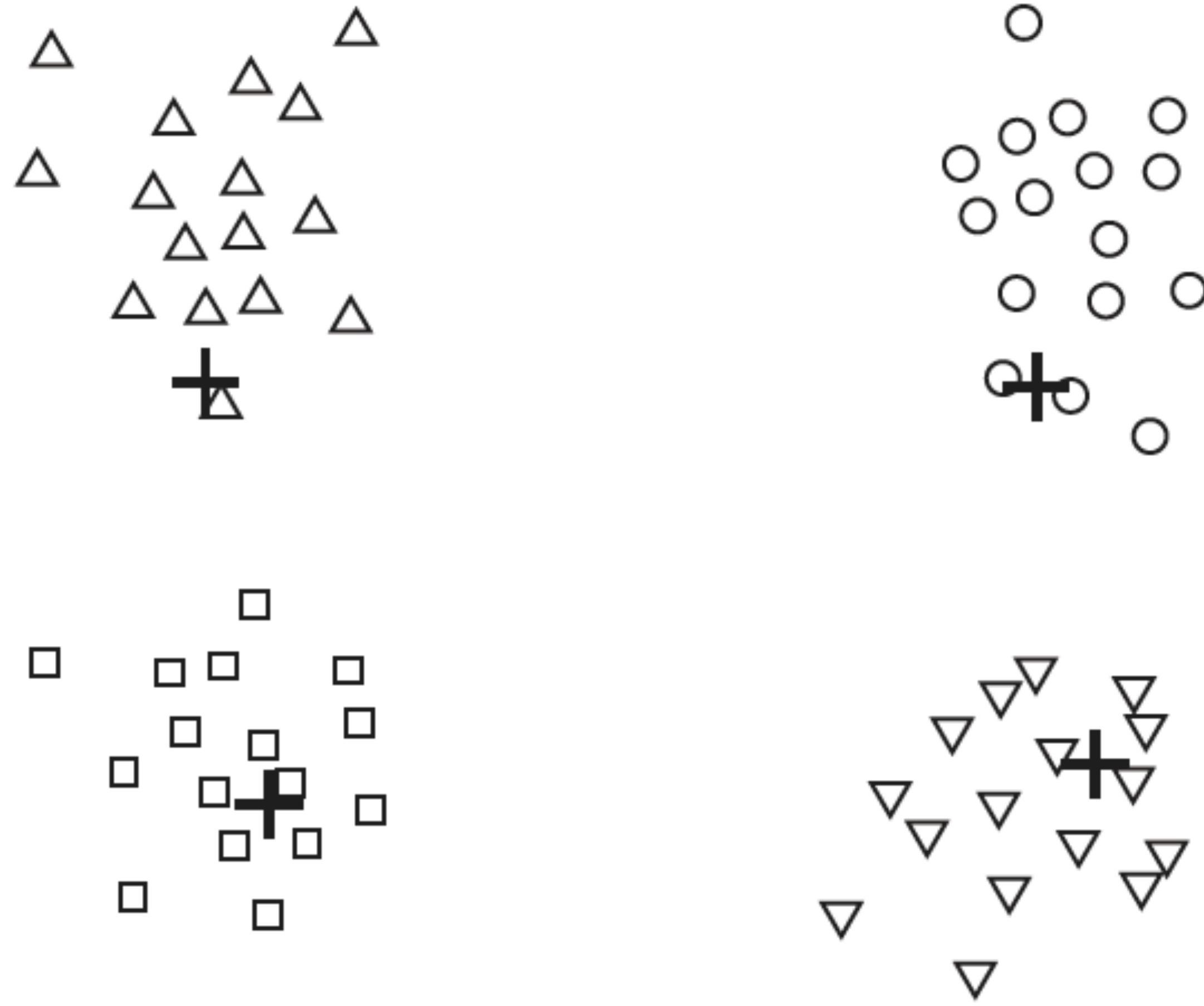
Choosing randomly several times

1. Select initial cluster representatives randomly
2. Run k-means
3. Repeat steps 1-2 several times and choose the best clustering

Choosing randomly several times: lucky choice

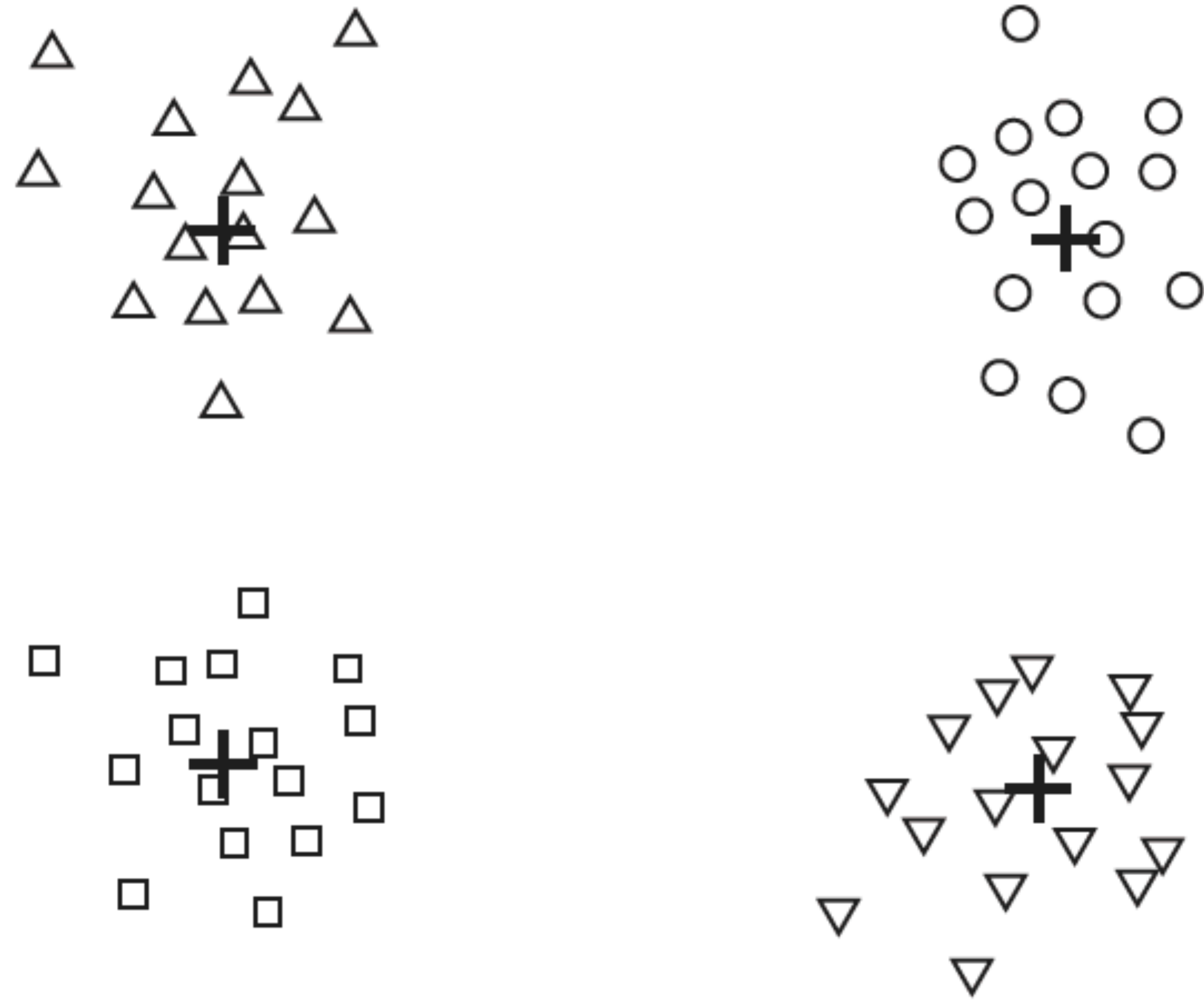


Choosing randomly several times: lucky choice



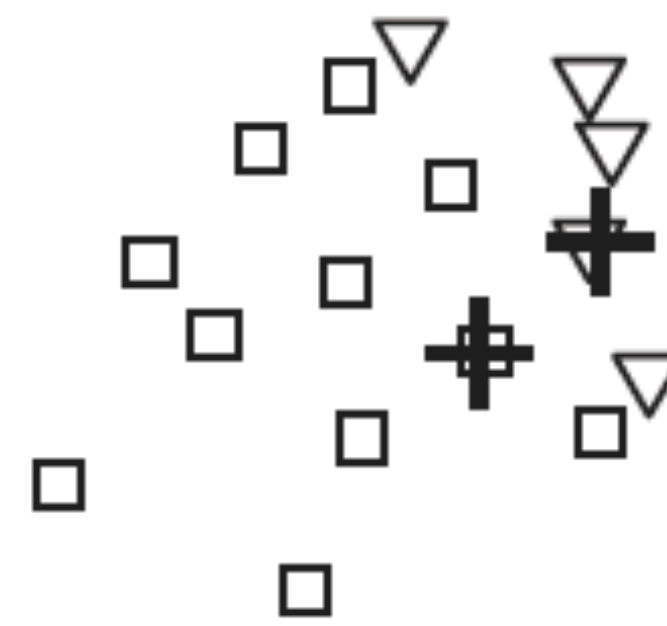
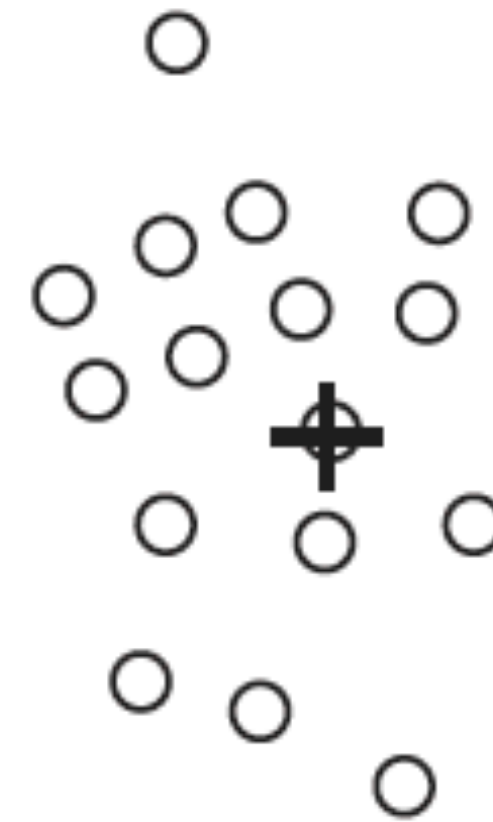
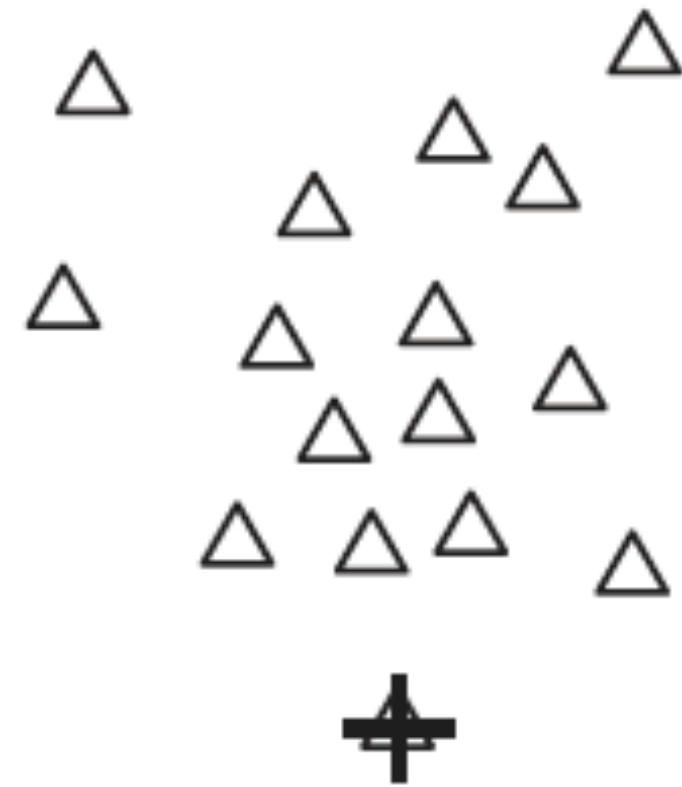
Iteration 2

Choosing randomly several times: lucky choice



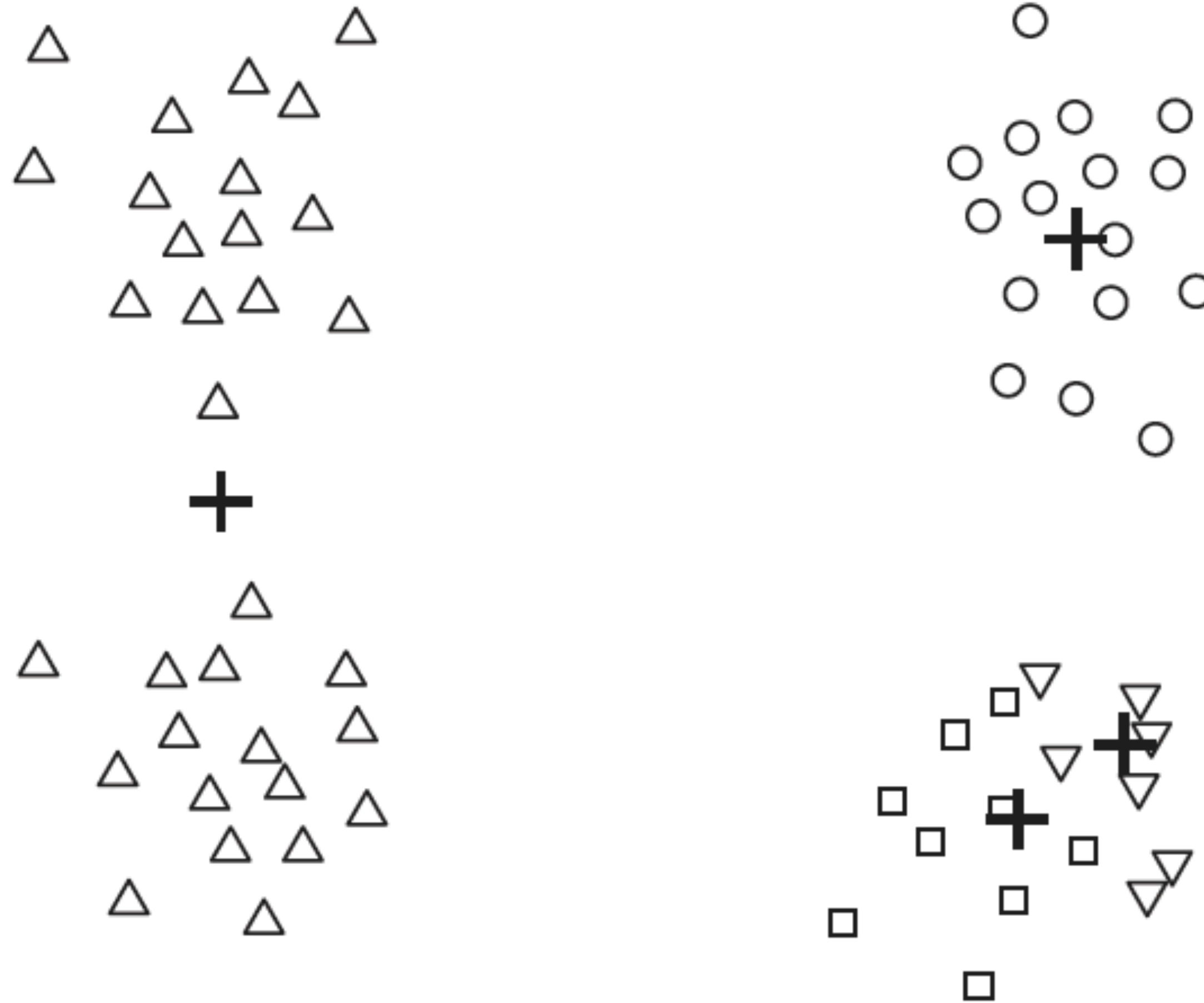
Iteration 3

Choosing randomly several times: **unlucky** choice



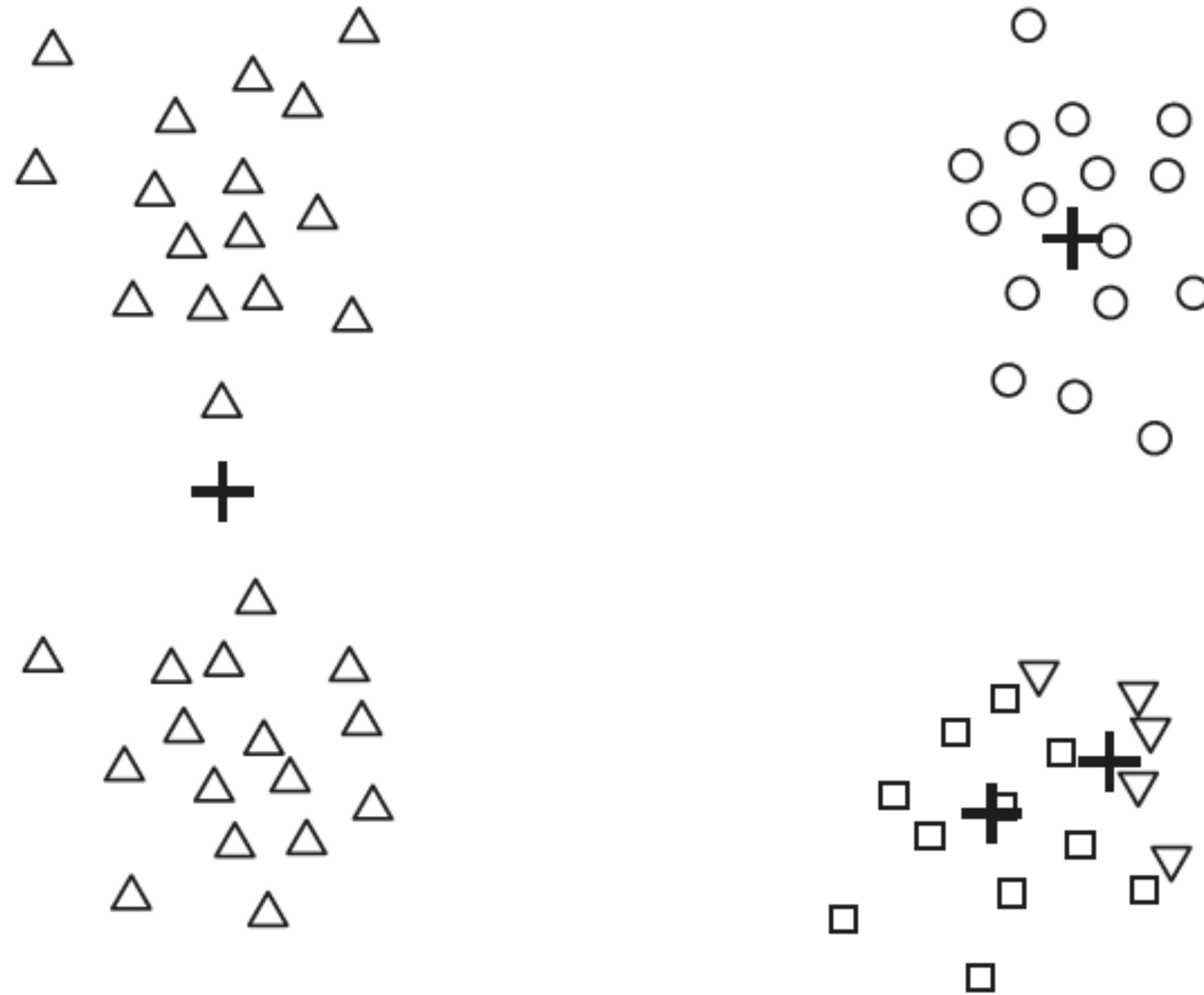
Iteration 1

Choosing randomly several times: **un**lucky choice



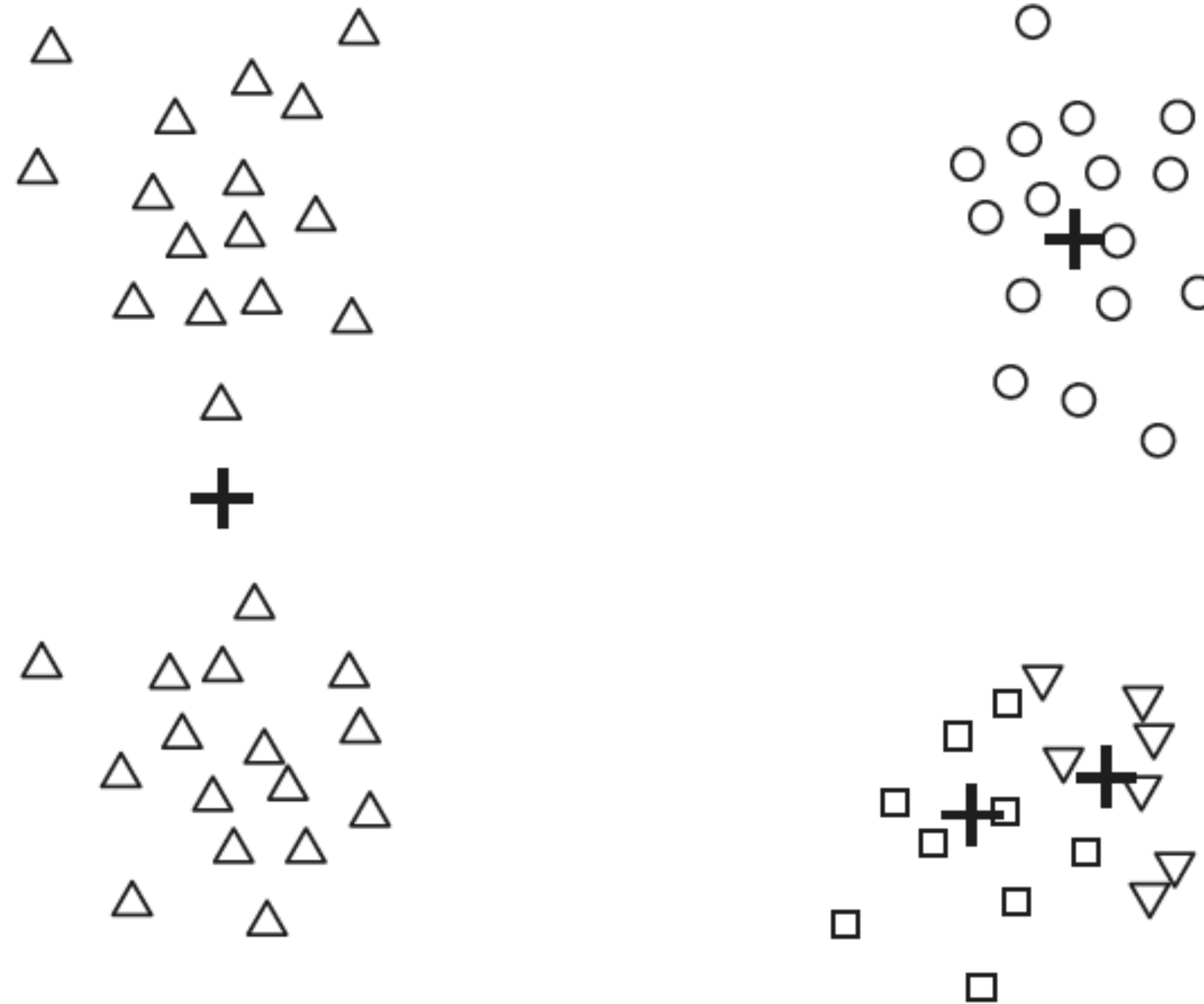
Iteration 2

Choosing randomly several times: **unlucky** choice



Iteration 3

Choosing randomly several times: **unlucky** choice



Iteration 4

Sampling + hierarchical clustering

1. Sample subset \mathcal{D}' of points from the dataset \mathcal{D}
2. Cluster \mathcal{D}' using a hierarchical clustering technique.
3. Extract k clusters from the hierarchical clustering.
4. Compute the means of these k clusters, and use them as the initial cluster representatives
5. Proceed with the standard k-means with these cluster representatives

Sampling + hierarchical clustering

Often works well, but it is practical only if

1. The sampled subset \mathcal{D}' is relatively small (a few hundred to a few thousand), as hierarchical clustering is expensive
2. k is relatively small compared to the size of the sampled set \mathcal{D}'

Selecting furthest points

For an object \bar{X} in the dataset \mathcal{D} let $R(\bar{X})$ be the distance from \bar{X} to the closest cluster representative we have already chosen.

1. Select one representative \bar{Y}_1 uniformly at random from \mathcal{D} .
2. For every $i = 2, \dots, k$
 1. Select representative \bar{Y}_i from \mathcal{D} with the maximum value of $R(\cdot)$
3. Proceed with the standard k-means using $\bar{Y}_1, \dots, \bar{Y}_k$ as initial cluster representatives

Selecting furthest points

The main drawback:

such an approach can select outliers, rather than points in clusters

k-means++

For an object \bar{X} in the dataset \mathcal{D} let $R(\bar{X})$ be the distance from \bar{X} to the closest cluster representative we have already chosen.

1. Select one representative \bar{Y}_1 uniformly at random from \mathcal{D} .
2. For every $i = 2, \dots, k$
 1. Select representative \bar{Y}_i from \mathcal{D} with probability $\bar{Y}_i = \bar{X}$ being equal to
$$\frac{R(\bar{X})^2}{\sum_{\bar{X} \in \mathcal{D}} R(\bar{X})^2}$$
3. Proceed with the standard k-means using $\bar{Y}_1, \dots, \bar{Y}_k$ as initial cluster representatives

k-means++

Within cluster sum of squares: $\phi = \sum_{x \in \mathcal{X}} \min_{c \in \mathcal{C}} \|x - c\|^2.$

Theorem 3.1. *If \mathcal{C} is constructed with **k-means++**, then the corresponding potential function ϕ satisfies, $E[\phi] \leq 8(\ln k + 2)\phi_{\text{OPT}}.$*

k-means++ **vs** k-means: experimental study

- Synthetic datasets Norm-10 and Norm-25.
 - Chose 10 (respectively 25) “real” centers uniformly at random from the hypercube of side length 500.
 - Then added points from a Gaussian distribution of variance 1, centered at each of the real centers.
 - Thus, we have a number of well separated Gaussians with the the real centers providing a good approximation to the optimal clustering.

k-means++ **vs** k-means: experimental study

- Synthetic datasets Norm-10.

k	Average ϕ		Minimum ϕ	
	k-means	k-means++	k-means	k-means++
10	10898	5.122	2526.9	5.122
25	787.992	4.46809	4.40205	4.41158
50	3.47662	3.35897	3.40053	3.26072

Table 1: Experimental results on the *Norm-10* dataset ($n = 10000$, $d = 5$)

Within cluster sum of squares: $\phi = \sum_{x \in \mathcal{X}} \min_{c \in \mathcal{C}} \|x - c\|^2$.

k-means++ **vs** k-means: experimental study

- Synthetic datasets Norm-25.

k	Average ϕ		Minimum ϕ	
	k-means	k-means++	k-means	k-means++
10	135512	126433	119201	111611
25	48050.5	15.8313	25734.6	15.8313
50	5466.02	14.76	14.79	14.73

Table 2: Experimental results on the *Norm-25* dataset ($n = 10000$, $d = 15$)

Within cluster sum of squares: $\phi = \sum_{x \in \mathcal{X}} \min_{c \in \mathcal{C}} \|x - c\|^2$.

k-means++ **vs** k-means: experimental study

- The synthetic datasets: the k-means method does not perform well, because
 - the random seeding will inevitably merge clusters together, and the algorithm will never be able to split them apart.
 - the careful seeding method of k-means++ avoids this problem altogether, and it almost always attains the optimal results on the synthetic datasets

k-means++ **vs** k-means: experimental study

- Real datasets: Cloud dataset

k	Average ϕ		Minimum ϕ	
	k-means	k-means++	k-means	k-means++
10	7553.5	6151.2	6139.45	5631.99
25	3626.1	2064.9	2568.2	1988.76
50	2004.2	1133.7	1344	1088

Table 3: Experimental results on the *Cloud* dataset ($n = 1024$, $d = 10$)

Within cluster sum of squares: $\phi = \sum_{x \in \mathcal{X}} \min_{c \in \mathcal{C}} \|x - c\|^2.$

k-means++ **vs** k-means: experimental study

- Real datasets: Intrusion dataset

k	Average ϕ		Minimum ϕ	
	k-means	k-means++	k-means	k-means++
10	$3.45 \cdot 10^8$	$2.31 \cdot 10^7$	$3.25 \cdot 10^8$	$1.79 \cdot 10^7$
25	$3.15 \cdot 10^8$	$2.53 \cdot 10^6$	$3.1 \cdot 10^8$	$2.06 \cdot 10^6$
50	$3.08 \cdot 10^8$	$4.67 \cdot 10^5$	$3.08 \cdot 10^8$	$3.98 \cdot 10^5$

Table 4: Experimental results on the *Intrusion* dataset ($n = 494019$, $d = 35$)

Within cluster sum of squares: $\phi = \sum_{x \in \mathcal{X}} \min_{c \in \mathcal{C}} \|x - c\|^2$.

k-means++ **vs** k-means: experimental study

- The real-world datasets
- On the **Cloud** dataset, k-means++ terminates almost **twice** as fast while achieving potential function (within cluster sum of squares) values about **20% better**.
- On the larger **Intrusion** dataset: the potential value obtained by k-means++ is better by factors of **10 to 1000** and is also obtained **up to 70% faster**.