# Logistic regression



### Probabilistic vs "ordinary" classifier

• "Ordinary" classifier is a function f that assigns to an input object  $\overline{X}$  a predicted class c from a fixed set of classes  $\{c_1, c_2, \ldots, c_k\}$ , i.e.

$$c = f(\overline{X}).$$

• Probabilistic classifier is a <u>conditional distribution P(C|X)</u>. For an input object  $\overline{X}$  it gives probabilities  $p_1, p_2, ..., p_k$ , where

$$p_i = P(c_i \mid \overline{X})$$

and 
$$p_1 + p_2 + ... + p_k = 1$$
.

### Two types of models: discriminative vs generative

#### **Discriminative**

- Assume that the conditional distribution P(C|X) (i.e. the probabilistic classifier) has specific form  $P_{\theta}(C|X)$  depending on some parameters  $\theta=(\theta_1,\ldots,\theta_k)$
- Use training data set to **find** / **learn** parameters  $\theta_1, \ldots, \theta_k$  such that the resulting distribution is "best possible" among all distributions of the assumed form

#### Generative

- Assume that data come from specific distribution  $P_{\theta}(X,C)$  depending on some parameters  $\theta = (\theta_1, ..., \theta_k)$
- Use training data set to **find** / **learn** parameters  $\theta_1, \ldots, \theta_k$  such that the resulting distribution is "best possible" among all distributions of the assumed form
- Use  $P_{\theta}(X, C)$  to classify new objects

### Probabilistic classifiers

#### Generative

• Naive Bayes 
$$P(H \mid E) = \frac{P(E, H)}{P(E)} = \frac{P(E \mid H)P(H)}{P(E)}$$

. . .

#### **Discriminative**

- Logistic regression (today!)
- Multilayer perceptrons (neural networks)

. . .

### Setup

- We consider the binary classification problems with classes  $\{-1, +1\}$
- We want to build a probabilistic classifier that outputs the probability of a particular training instance  $\overline{X}$  being positive (y = +1) or negative (y = -1)

• Define a separating hyperplane H parameterised by the feature weights  $\overline{W} = (w_1, ..., w_d)$  and a bias parameter b, i.e.

$$H = \left\{ b + \sum_{i=1}^{d} w_i x_i = 0 \mid x_1, \dots, x_d \right\}$$

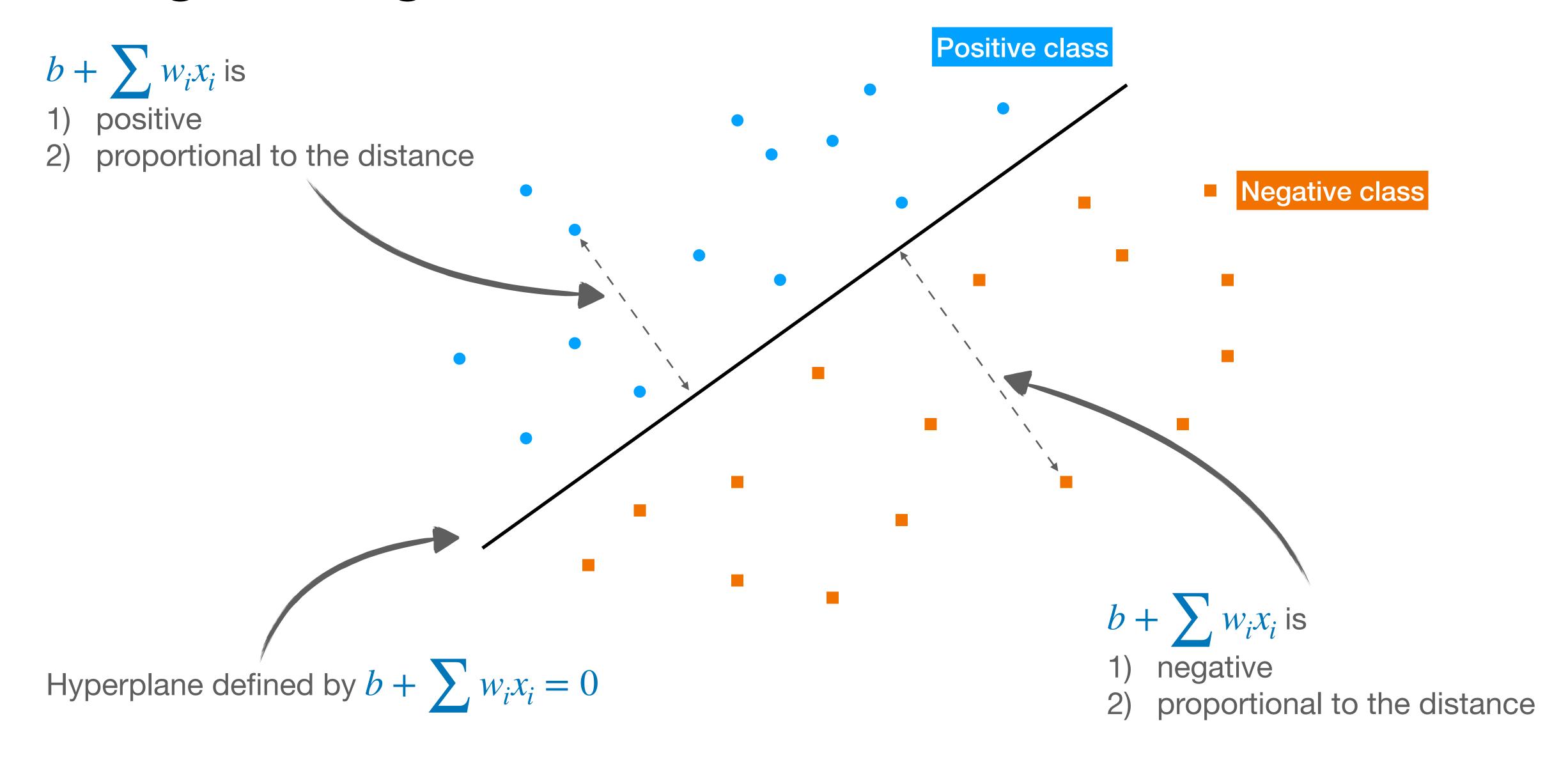
• In perceptron, to classify an input object  $\overline{X} = (x_1, \dots, x_d)$ , we used only the sign of

$$b + \overline{W}^T \overline{X} = b + \sum_{i=1}^d w_i x_i,$$

which tells in which of the two half-spaces created by the hyperplane the point is located.

• However, the actual value of  $b+\overline{W}^I\overline{X}$  conveys extra useful information: it is proportional to the distance from point  $\overline{X}$  to the hyperplane H

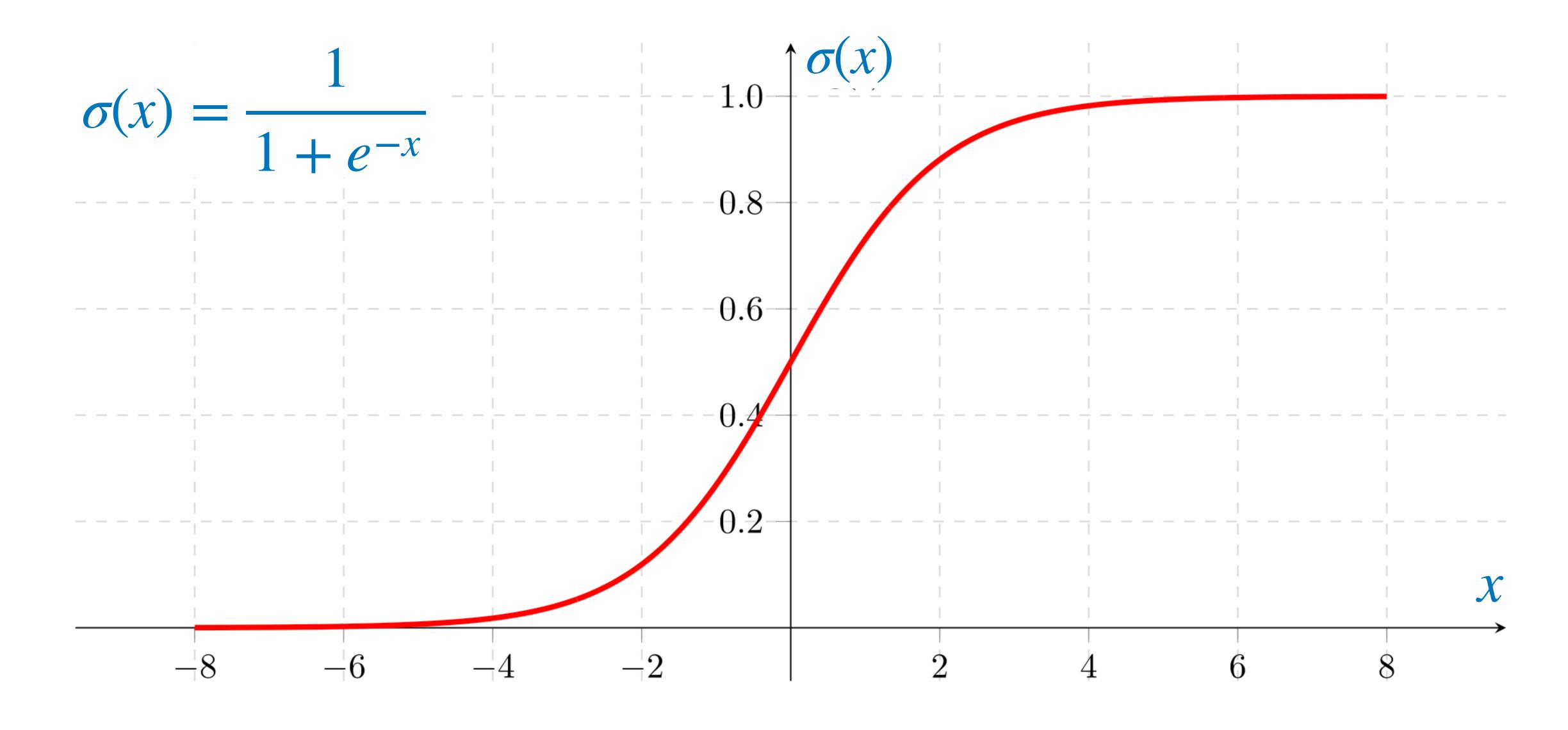
- Logistic regression uses
  - sign of  $b+\overline{W}^T\overline{X}$  to classify object  $\overline{X}$  and
  - $|b+\overline{W}^T\overline{X}|$  to **quantify our confidence** in this classification: the larger the value, the further  $\overline{X}$  from the separating hyperplane H



• To interpret the confidence score  $b + \overline{W}^T \overline{X} \in [-\infty, \infty]$  as probability we would like to transform it to a value in the interval [0,1] so that  $-\infty$  maps to 0 and  $\infty$  maps to 1.

A function that does this is the logistic sigmoid function.

## Logistic sigmoid function



### Logistic sigmoid function properties

•  $\sigma(x) \in [0,1]$  for any  $x \in [-\infty, \infty]$ 

• 
$$1 - \sigma(x) = \sigma(-x)$$

$$\frac{\partial \sigma}{\partial x} = \sigma(x) \cdot (1 - \sigma(x))$$

### Logistic regression: discriminative classifier

#### Discriminative classifier

- Assume that the conditional distribution P(C|X) (i.e. the probabilistic classifier) has specific form  $P_{\theta}(C|X)$  depending on some parameters  $\theta=(\theta_1,...,\theta_k)$
- Use training data set to **find** / **learn** parameters  $\theta_1, \ldots, \theta_k$  such that the resulting distribution is "best possible" among all distributions of the assumed form

### Logistic regression: model assumption

• For an object  $\overline{X} = (x_1, ..., x_d)$ , the probability that  $\overline{X}$  belongs to the positive class is modelled as

$$P(y = +1 \mid \overline{X}) = \sigma(a) = \frac{1}{1 + e^{-a}},$$

where  $a=b+\overline{W}^T\overline{X}$  . Hence the probability that  $\overline{X}$  belongs to the negative class is

$$P(y = -1 \mid \overline{X}) = 1 - P(y = +1 \mid \overline{X}) = 1 - \sigma(a) = \sigma(-a) = \frac{1}{1 + e^a}$$

- Let  $\mathcal{D} = \{(\overline{X_1}, y_1), (\overline{X_2}, y_2), ..., (\overline{X_n}, y_n)\}$  be the training data set
- Using the maximum likelihood estimation method we would like to find parameters  $b, w_1, w_2, ..., w_d$  that maximise the likelihood function

$$\mathcal{E}(b, w_1, w_2, \dots, w_d, \mathcal{D}) = \prod_{i=1}^n \sigma \left( y_i (b + \overline{W}^T \overline{X}_i) \right)$$

• This is equivalent to minimising  $-\ell$  or minimising the negative log-likelihood function

$$-\ell\ell = -\log\ell = -\sum_{i=1}^{n}\log\sigma\left(y_{i}(b + \overline{W}^{T}\overline{X}_{i})\right)$$

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$$\nabla_{b,w_1,\dots,w_d}(-\ell\ell) = -\nabla_{b,w_1,\dots,w_d}\ell\ell$$

Denote 
$$a_i = b + \overline{W}^T \overline{X}_i$$

We need to compute 
$$\frac{\partial \ell\ell}{\partial b}$$
 and  $\frac{\partial \ell\ell}{\partial w_k}$  for every  $k=1,\ldots,d$ .

$$\mathscr{E}\mathscr{E} = \log \mathscr{E} = \sum_{i=1}^{n} \log \sigma \left( y_i (b + \overline{W}^T \overline{X}_i) \right) = \sum_{i=1}^{n} \log \sigma \left( y_i \cdot a_i \right)$$

$$\frac{\partial \ell\ell}{\partial b} =$$

#### Logistic sigmoid function properties

1) 
$$\frac{\partial \sigma}{\partial x} = \sigma(x) \cdot (1 - \sigma(x))$$

**2)** 
$$1 - \sigma(x) = \sigma(-x)$$

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$$\frac{\partial \ell \ell}{\partial b} = \sum_{i=1}^{n} y_i \cdot \sigma \left( -y_i (b + \overline{W}^T \overline{X}_i) \right) = \sum_{i=1}^{n} y_i \cdot \sigma \left( -y_i \cdot a_i \right)$$

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$$\frac{\partial \ell\ell}{\partial w_k} =$$

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$$\frac{\partial \ell \ell}{\partial w_k} = \sum_{i=1}^n y_i \cdot \sigma \left( -y_i (b + \overline{W}^T \overline{X}_i) \right) \cdot x_k^{(i)} = \sum_{i=1}^n y_i \cdot \sigma \left( -y_i \cdot a_i \right) \cdot x_k^{(i)},$$

where 
$$\overline{X}_i = (x_1^{(i)}, x_2^{(i)}, \dots, x_d^{(i)})$$

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Interpretation of 
$$\sum_{i=1}^{n} y_i \cdot \sigma(-y_i \cdot a_i)$$

- If  $y_i = +1$ , then  $\sigma(-y_i \cdot a_i) = \sigma(-a_i) = 1 \sigma(a_i) = P(y = -1 \mid \overline{X}_i)$
- If  $y_i = -1$ , then  $\sigma(-y_i \cdot a_i) = \sigma(a_i) = P(y = +1 \mid \overline{X}_i)$
- Hence  $\sigma(-y_i \cdot a_i)$  is the probability of misclassifying the training object  $X_i$

$$\sum_{i=1}^{n} y_i \cdot \sigma(-y_i \cdot a_i) = \sum_{\overline{X}_i \in \mathcal{D}_+} P(y = -1 \mid \overline{X}_i) - \sum_{\overline{X}_i \in \mathcal{D}_-} P(y = +1 \mid \overline{X}_i)$$

### Logistic regression: update rule

### Gradient Descent method for finding local minimum of $f(\overline{Z}) = f(z_1, ..., z_d)$

- 1. Pick an initial point  $\overline{Z}_0$
- 2. Iterate according to

$$\overline{Z}_{i+1} = \overline{Z}_i - \gamma_i \cdot \left( (\nabla_{\overline{Z}} f)(\overline{Z}_i) \right)$$

where  $\gamma_1, \gamma_2, \ldots$ , are step-sizes.

### Logistic regression: update rule

$$\begin{aligned} & \text{minimize} - \ell\ell = -\log\ell = -\sum_{i=1}^n \log\sigma\left(y_i(b + \overline{W}^T \overline{X_i})\right) \\ & \frac{\partial\ell\ell}{\partial b} = \sum_{i=1}^n y_i \cdot \sigma\left(-y_i \cdot a_i\right) & \frac{\partial\ell\ell}{\partial w_k} = \sum_{i=1}^n y_i \cdot \sigma\left(-y_i \cdot a_i\right) \cdot x_k^{(i)}, k = 1, \dots, d \end{aligned}$$

Hence we have the following update rule

$$b \leftarrow b + \mu \cdot \sum_{i=1}^{n} y_i \cdot \sigma(-y_i \cdot a_i)$$

$$\overline{W} \leftarrow \overline{W} + \mu \cdot \sum_{i=1}^{n} y_i \cdot \sigma(-y_i \cdot a_i) \overline{X}_i$$

uses whole training set

### Online vs Batch

#### **Batch**

- Uses the entire training dataset in every iteration to update the weight vector
- Popular optimisation algorithm for the batch learning of logistic regression is the Limited Memory BFGS (L-BFGS) algorithm
- Batch version is slow compared to the online version. But shows slightly improved accuracies in many cases

#### **Online**

- Uses only one training object in every iteration to update the weight vector
- The Stochastic Gradient Descent algorithm (SGD)
- SGD version can require multiple iterations over the dataset before it converges (if ever)
- SGD is a technique that is frequently used with large scale machine learning tasks (even when the objective function is non-convex)

### Logistic regression online algorithm (Stochastic Gradient Descent)

**LogisticRegression**(Training data:  $\{(\overline{X}_1, y_1), ..., (\overline{X}_n, y_n)\}$ , Learning rate  $\mu$ , MaxIter)

1: 
$$w_i = 0$$
 for all  $i = 1, ..., d$ ;

$$2: b = 0$$

4: 
$$for i = 1 ... n do$$

5: 
$$a_i = b + \overline{W}^T \overline{X}_i$$

6: 
$$w_s = w_s + \mu \cdot y_i \cdot \sigma(-y_i \cdot a_i) \cdot x_s^{(i)}, \text{ for all } s = 1, \dots, d$$

7: 
$$b = b + \mu \cdot y_i \cdot \sigma(-y_i \cdot a_i)$$

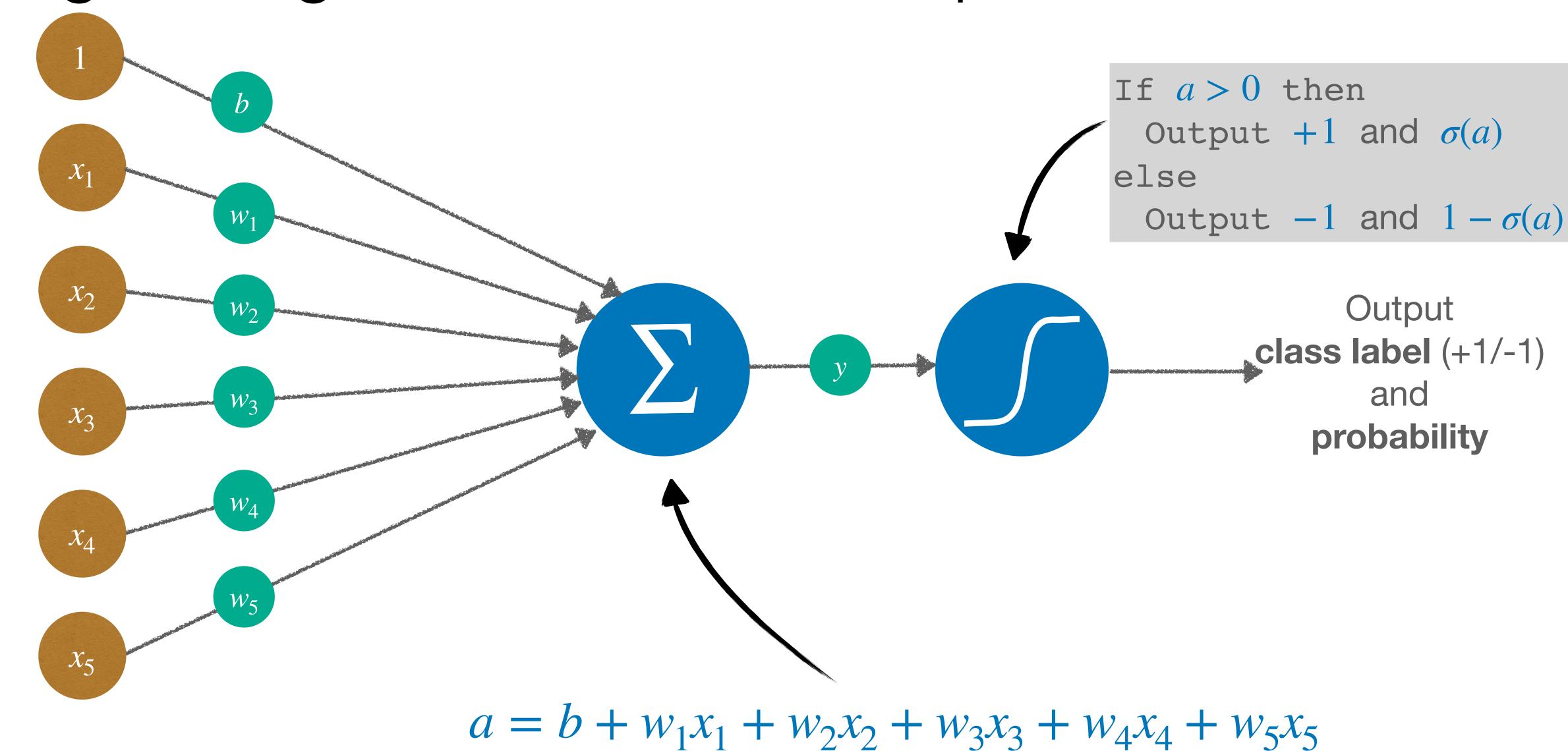
8: **return** 
$$b, w_1, w_2, ..., w_d$$

$$\overline{W} \leftarrow \overline{W} + \mu \cdot y_i \cdot \sigma(-y_i \cdot a_i) \overline{X}_i$$
$$b \leftarrow b + \mu \cdot y_i \cdot \sigma(-y_i \cdot a_i)$$

### Logistic regression prediction

```
LogisticRegressionTest(b, w_1, w_2, ..., w_d, \overline{X})
1: a = b + \overline{W}^T \overline{X}
2: if a > 0 then
     predicted label = +1 #positive class
     probability that \overline{X} belongs to the positive class = \sigma(a) #confidence
5: else
     predicted label = -1 #negative class
6:
     probability that \overline{X} belongs to the negative class = 1 - \sigma(a) #confidence
```

### Logistic regression: neuron interpretation



### L2 regularisation

- Let us denote by  $L(\mathcal{D},\overline{W})$  the Loss of classifying a dataset  $\mathcal{D}$  using a model represented by a weight vector  $\overline{W}$
- We would like to impose L2 regularisation on  $\overline{W}$ .
- The overall objective to minimise can then be written as follows

$$J(\mathcal{D}, \overline{W}) = L(\mathcal{D}, \overline{W}) + \lambda ||\overline{W}||_2^2 = L(\mathcal{D}, \overline{W}) + \lambda \sum_{i=1}^d w_i^2.$$

Here  $\lambda$  is called the **regularisation coefficient** and is usually set via **cross-validation**.

• The gradient of the overall objective simply becomes the addition of the loss-gradient and the scaled weight vector  $\overline{W}$ .

$$\nabla_{\overline{W}}J(\mathcal{D},\overline{W}) = \nabla_{\overline{W}}L(\mathcal{D},\overline{W}) + 2\lambda\overline{W}$$

### L2 regularisation in logistic regression

L2 regularised logistic regression update rule for training object  $(\overline{X}, y)$  with  $a = b + \overline{W}^T X$ 

No regularisation: 
$$\overline{W} \leftarrow \overline{W} + \mu \cdot y \cdot \sigma (-y \cdot a) \cdot \overline{X}$$

With regularisation:

$$\overline{W} \leftarrow \overline{W} - \mu \cdot \left( -y \cdot \sigma(-y \cdot a) \cdot \overline{X} + 2\lambda \overline{W} \right)$$

$$= \overline{W} + \mu \cdot y \cdot \sigma(-y \cdot a) \cdot \overline{X} - 2\mu\lambda \overline{W}$$

$$= (1 - 2\mu\lambda)\overline{W} + \mu \cdot y \cdot \sigma(-y \cdot a) \cdot \overline{X}$$