

*Comp305*

***Biocomputation***

*Lecturer: Yi Dong*

# Comp305 Module Timetable



## Semester 1 View - Module: COMP305 - Biocomp

	08:00	08:30	09:00	09:30	10:00	10:30	11:00	11:30	12:00	12:30	13:00	13:30	14:00	14:30	15:00	15:30	16:00	16:30	17:00	17:30	18:00
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One of them

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There will be **26-30** lectures, thee per week. The lecture slides will appear on Canvas. Please use Canvas to access the lecture information. There will be **9** tutorials, one per week.

# Lecture/Tutorial Rules

Questions are welcome as soon as they arise, because

1. Questions give feedback to the lecturer;
2. Questions help your understanding;
3. Your questions help your classmates, who might experience difficulties with formulating the same problems/doubts in the form of a question.

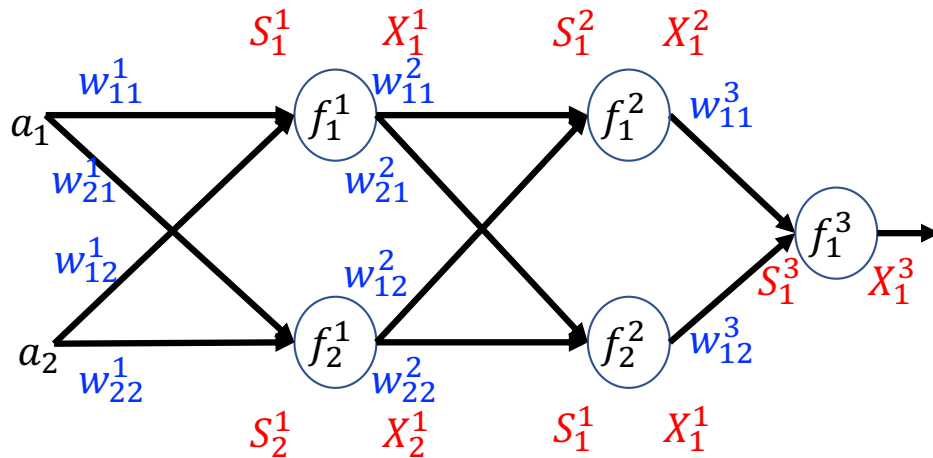
Comp305 Part I.

# Artificial Neural Networks

Topic 5.

# Multilayer Perceptron

# Gradient of a Weight



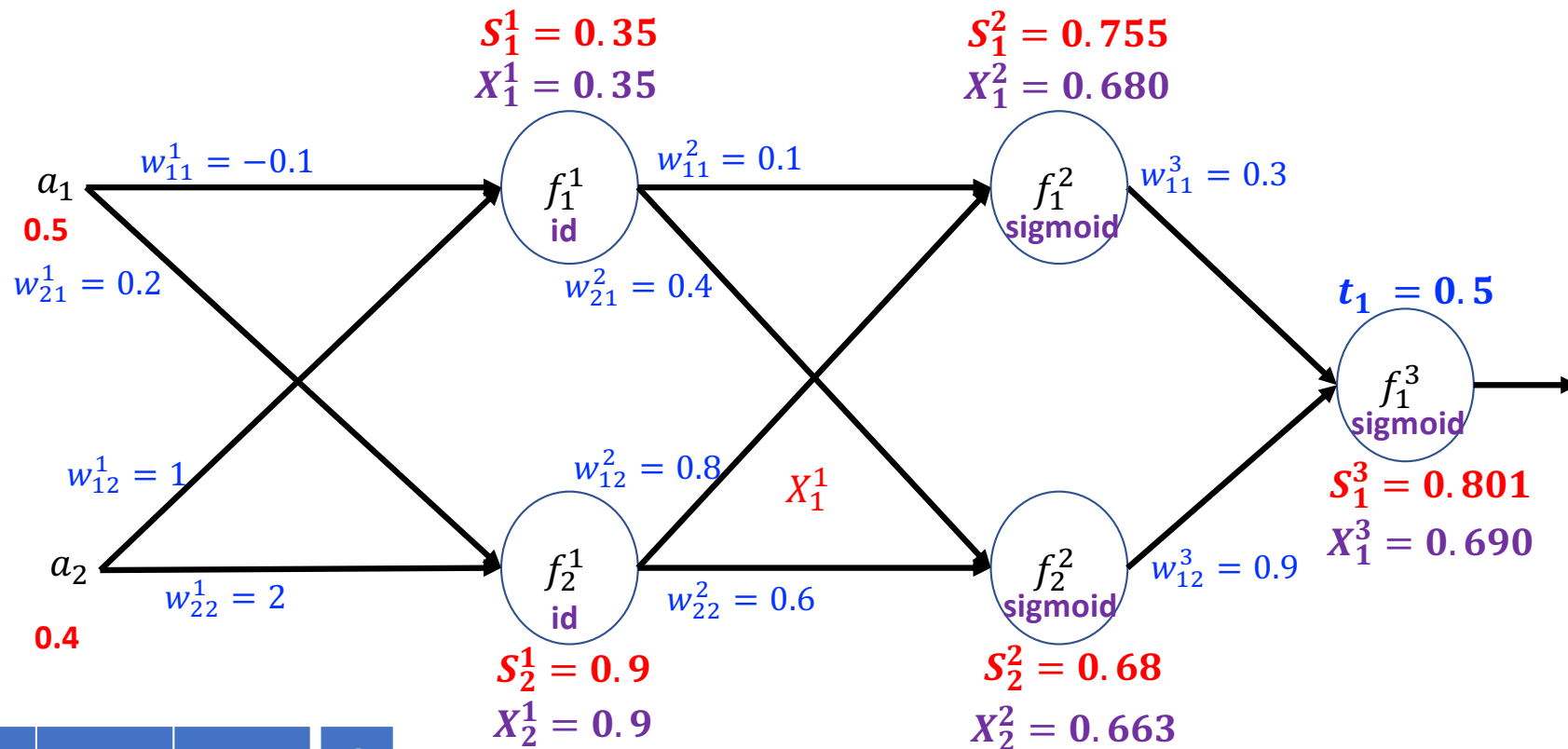
We consider the **error function**  $E$  for a **single input**:

$$E = \frac{1}{2} \sum_{j=1}^m e_j^2 = \frac{1}{2} \sum_{j=1}^m (t_j - X_j)^2$$

$$= \frac{1}{2} \sum_{j=1}^m (t_j - X_j^l)^2$$

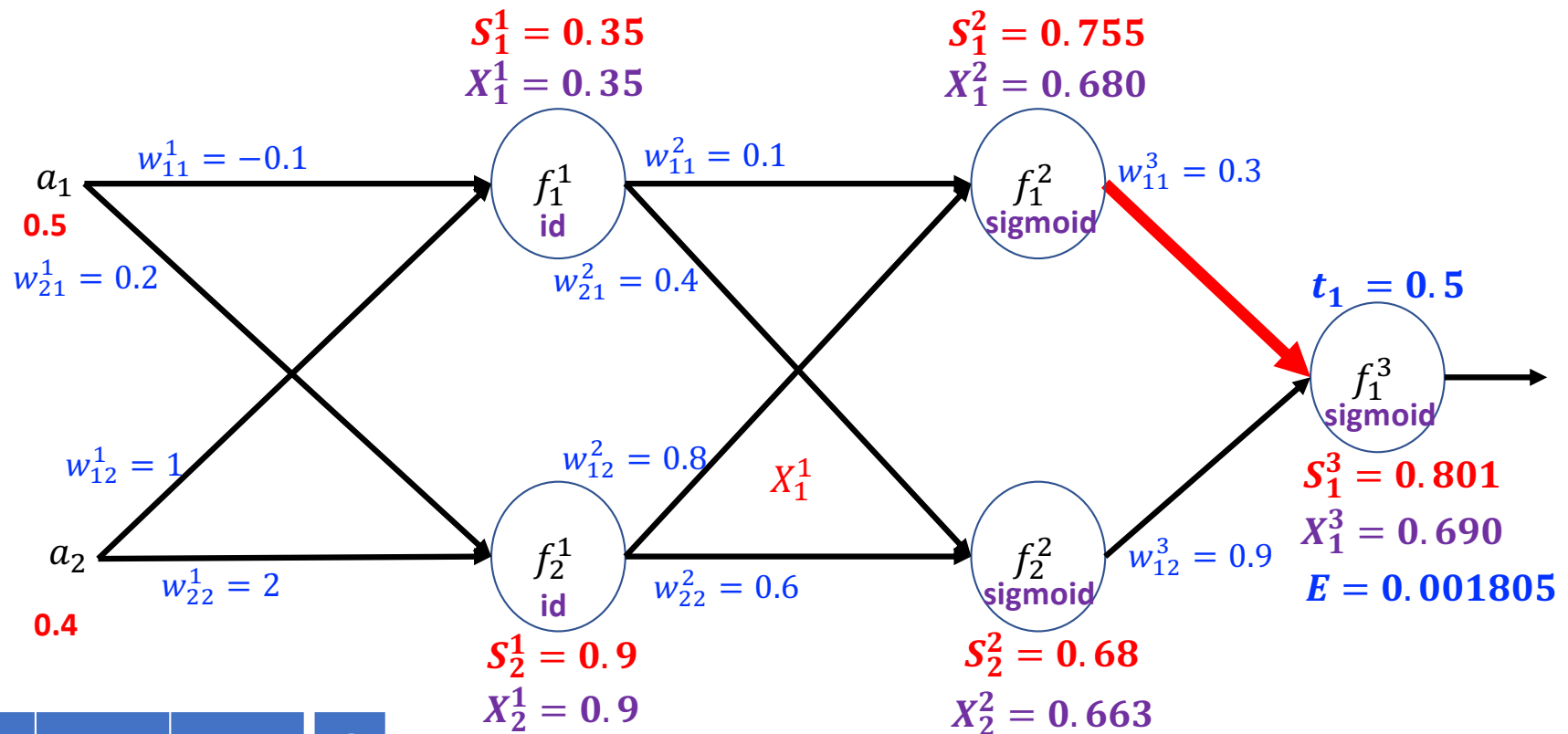
$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \begin{cases} (X_{j_0}^{l_0} - t_{j_0}) \cdot (f_{j_0}^{l_0})' (S_{j_0}^{l_0}) \cdot X_{i_0}^{l_0-1} & \text{When } l = l_0 \\ \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( (f_j^l)' (S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j_0}^{l_0})' (S_{j_0}^l) \cdot X_{i_0}^{l-1} \right) \right) & \text{When } l \neq l_0 \end{cases}$$

# Gradient of a Weight



$a_1$	$a_2$	$t_1$	$C$
0.5	0.4	0.5	1

# Gradient of a Weight

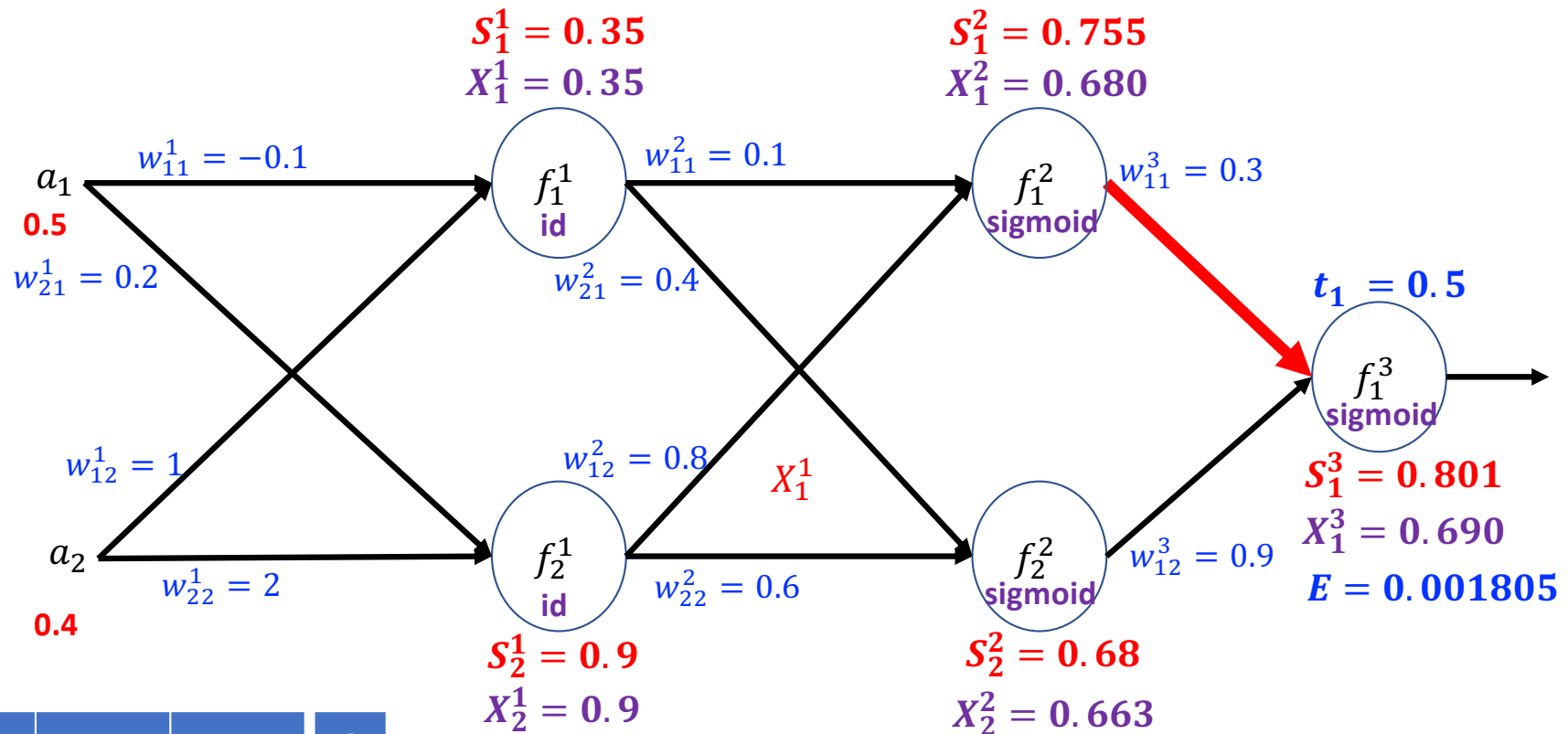


$a_1$	$a_2$	$t_1$	$C$
0.5	0.4	0.5	1

$$\frac{\partial E}{\partial w_{11}^3} = (X_1^3 - t_1) \cdot (\text{sig})'(S_1^3) \cdot X_1^2$$



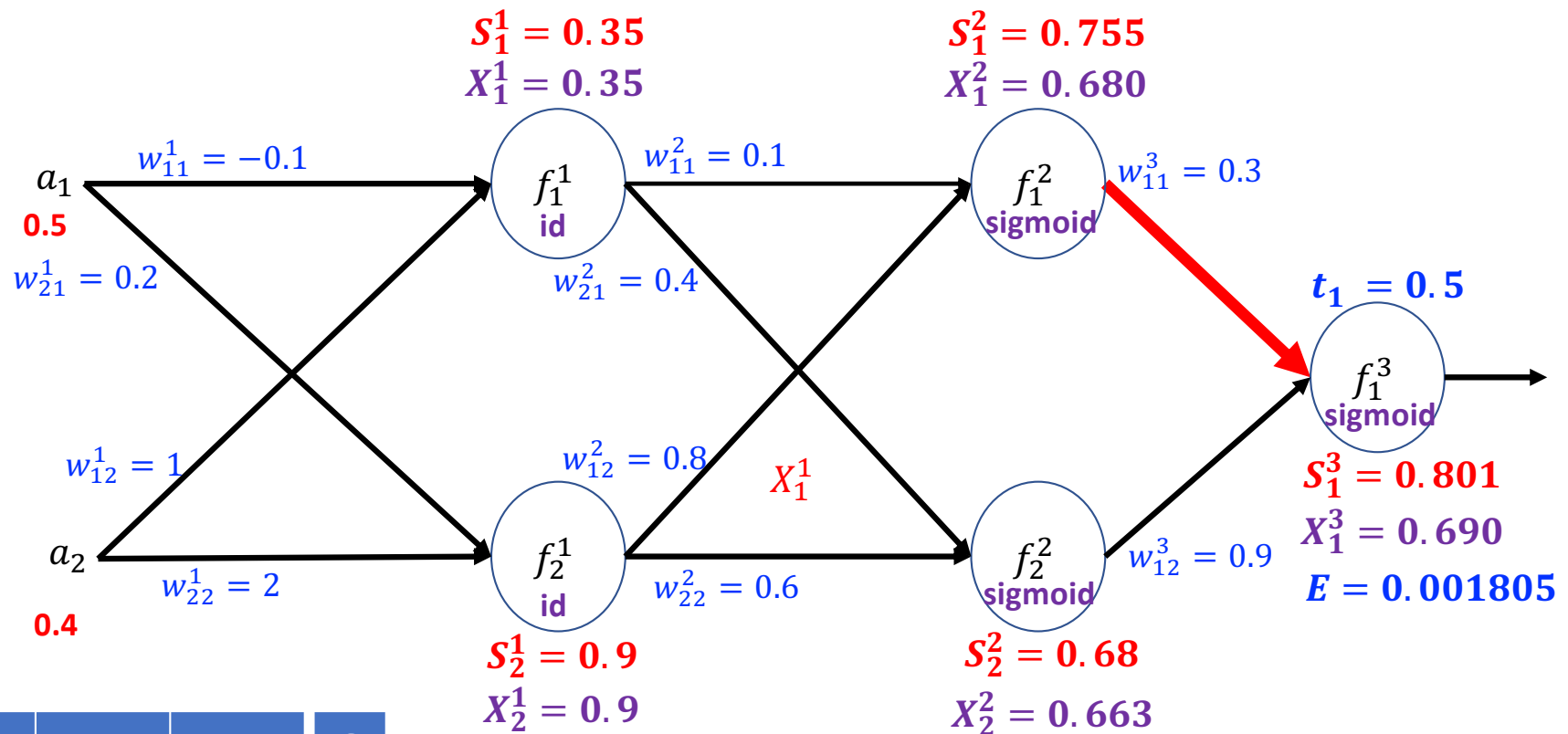
# Gradient of a Weight



$a_1$	$a_2$	$t_1$	$C$
0.5	0.4	0.5	1

$$\frac{\partial E}{\partial w_{11}^3} = \frac{(X_1^3 - t_1)}{0.19} \cdot \frac{(sig)'(s_1^3)}{0.69 \times (1 - 0.69)} \cdot \frac{X_1^2}{0.68} = 0.02763$$

# Gradient of a Weight



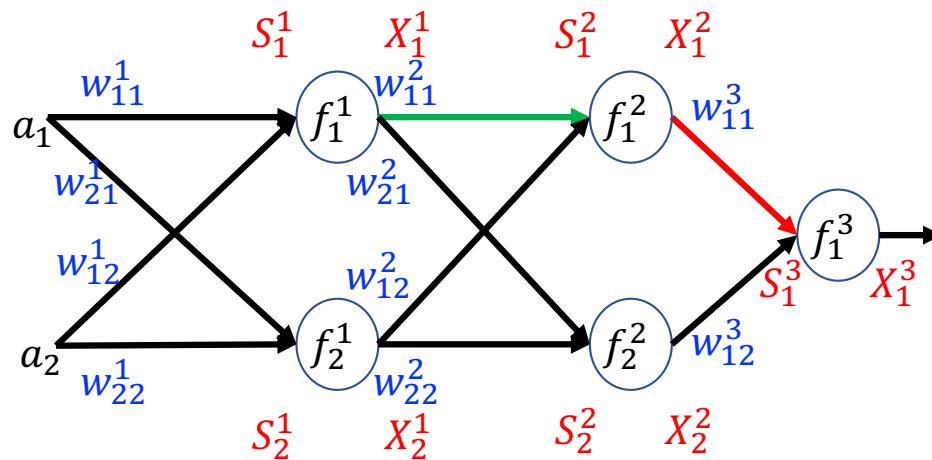
$a_1$	$a_2$	$t_1$	$C$
0.5	0.4	0.5	1

$$w_{11}^3 = w_{11}^3 - C \frac{\partial E}{\partial w_{11}^3} = 0.3 - 1 \times 0.02763 = 0.27237$$

# Topic of Today's Lecture

Backpropagation.

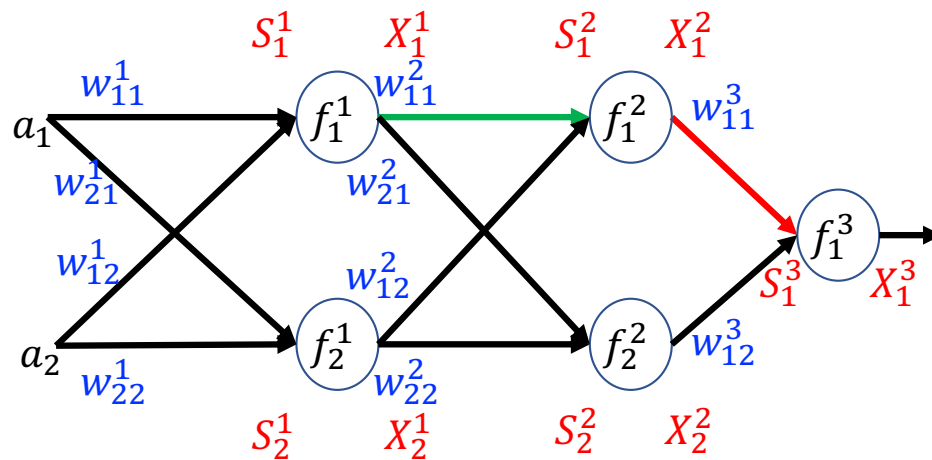
# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = (X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2$$

$$\frac{\partial E}{\partial w_{11}^2} = (X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1$$

# Backpropagation

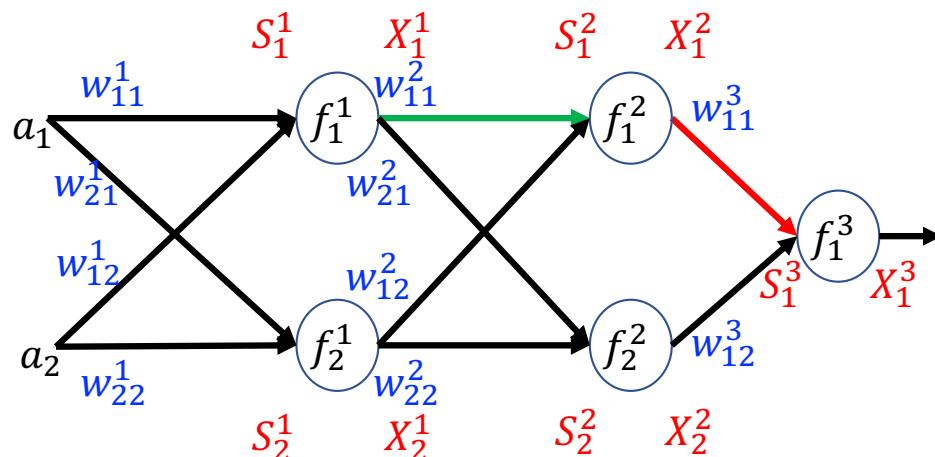


$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

- The closer the connection is to the output, the simpler the formula of the partial derivative of its weight is.
- There are some overlap between two formulas, indicating it is possible to store the overlap to avoid duplicate computation.

# Backpropagation



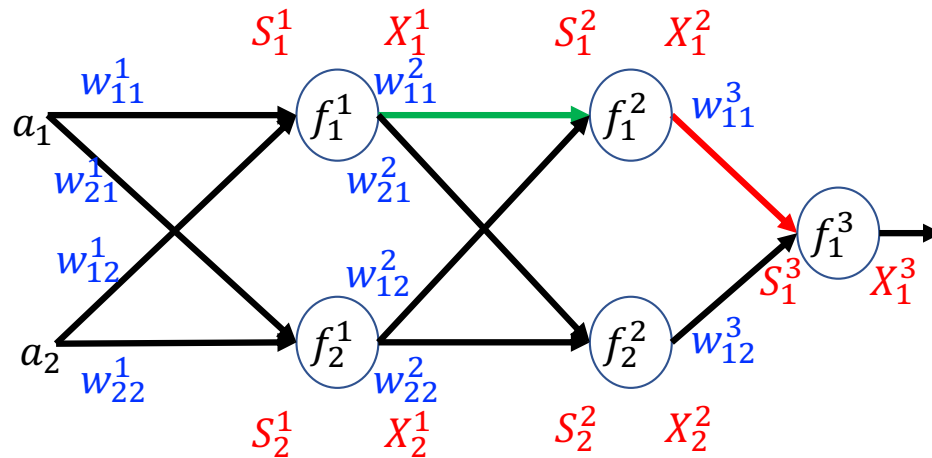
$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot X_1^2$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1$$

First, we need to rewrite the following partial derivative formula we introduced previously.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \begin{cases} (X_{j_0}^{l_0} - t_{j_0}) \cdot (f_{j_0}^{l_0})' (S_{j_0}^{l_0}) \cdot X_{i_0}^{l_0-1} & \text{When } l = l_0 \\ \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( (f_j^l)'(S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j_0}^{l_0})' (S_{j_0}^{l_0}) \cdot X_{i_0}^{l_0-1} \right) \right) & \text{When } l \neq l_0 \end{cases}$$

# Backpropagation



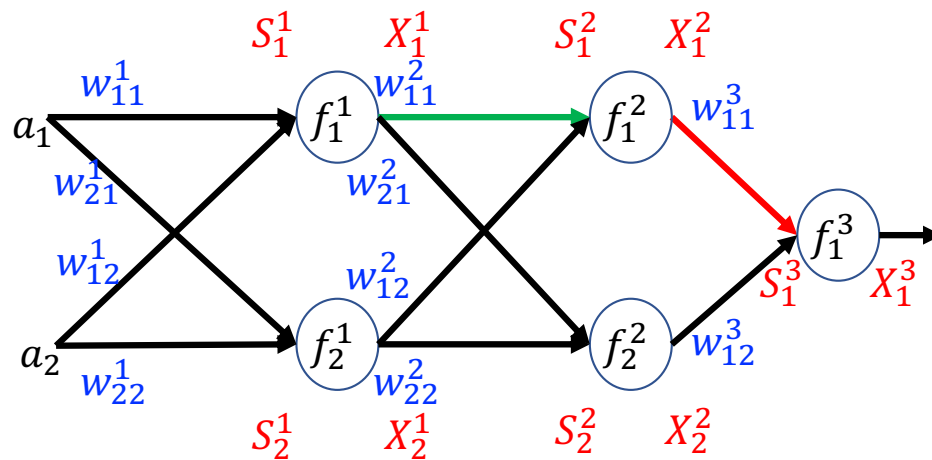
$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot X_1^2$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1$$

Step 1. Rewrite the partial derivative.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \begin{cases} \left( X_{j_0}^{l_0} - t_{j_0} \right) \cdot (f_{j_0}^{l_0})' (S_{j_0}^{l_0}) \cdot X_{i_0}^{l_0-1} & \text{When } l = l_0 \\ \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( (f_j^l)'(S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j_0}^{l_0})' (S_{j_0}^{l_0}) \cdot X_{i_0}^{l_0-1} \right) \right) & \text{When } l \neq l_0 \end{cases}$$

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

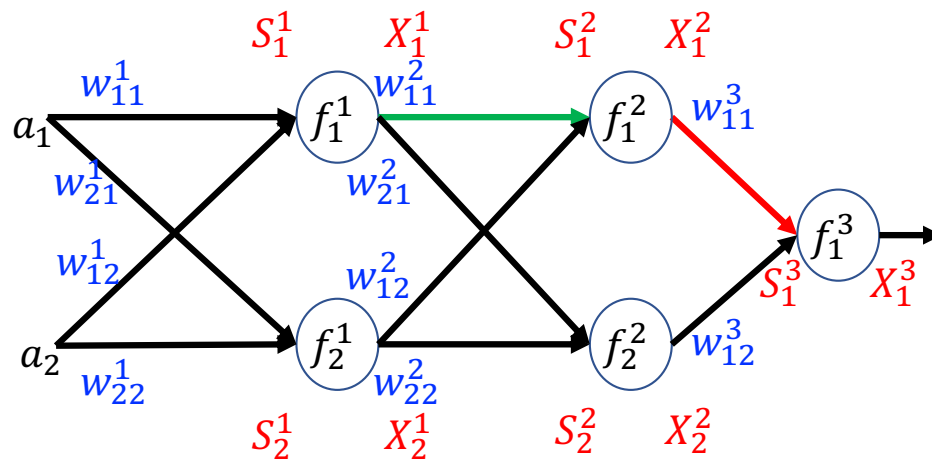
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 1. Rewrite the partial derivative.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \begin{cases} \sum_{j'=1}^{n^{l_0}} (X_{j'}^{l_0} - t_{j'}) \cdot (f_{j'}^{l_0})' (S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} & \text{When } l = l_0 \\ \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( (f_j^l)' (S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j'}^{l_0})' (S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \right) \right) & \text{When } l \neq l_0 \end{cases}$$



# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

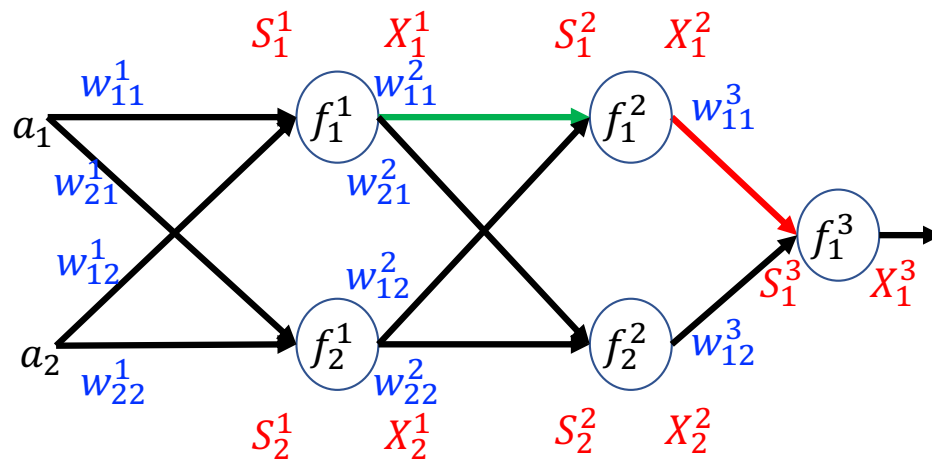
Why do we rewrite it?

Step 1. Rewrite the partial derivative.

Unify the representations in two cases.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \begin{cases} \sum_{j'=1}^{n^{l_0}} \underline{(X_{j'}^{l_0} - t_{j'}) \cdot (f_{j'}^{l_0})'(S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}}} & \text{When } l = l_0 \\ \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( (f_j^l)'(S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j'}^{l_0})'(S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \right) \right) & \text{When } l \neq l_0 \end{cases}$$

# Backpropagation



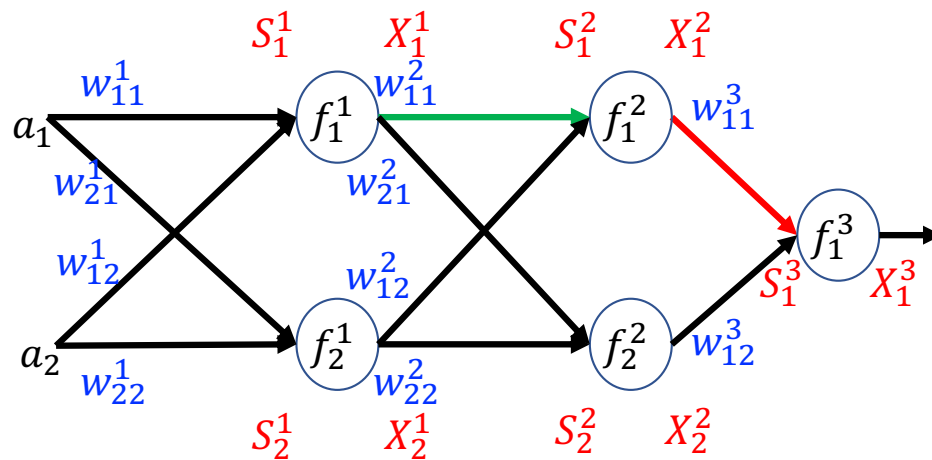
$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 1. Rewrite the partial derivative.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( (f_j^l)'(S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j'}^{l_0})' (S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \right) \right)$$

# Backpropagation

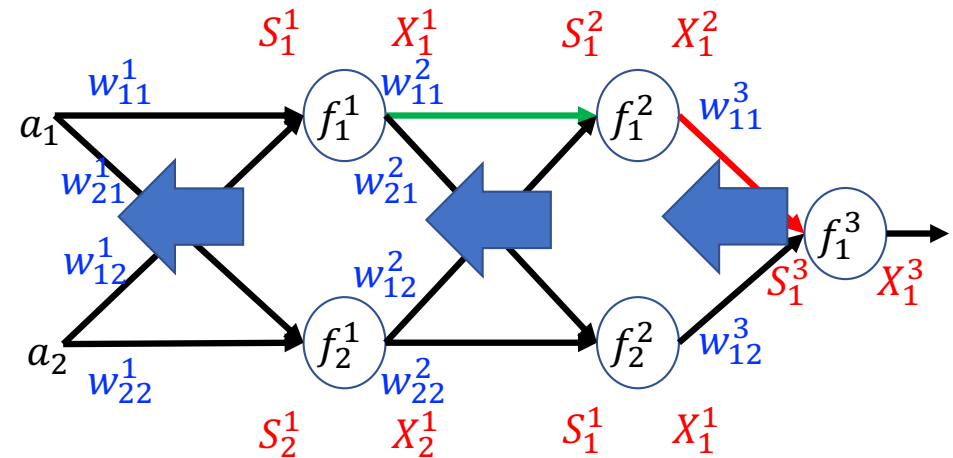


Step 2. Rewrite the formula in a matrix form.

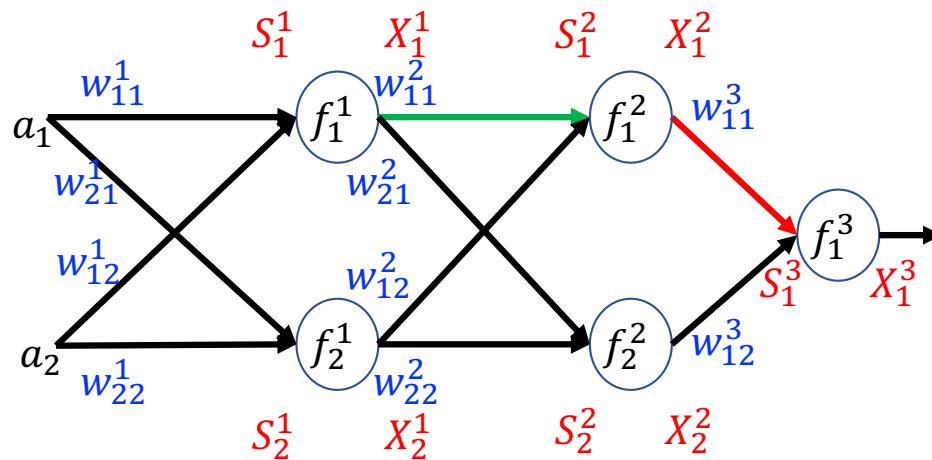
The objective of this step is to derive the relation between the partial derivatives between two layers.

$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot X_1^2$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1$$



# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

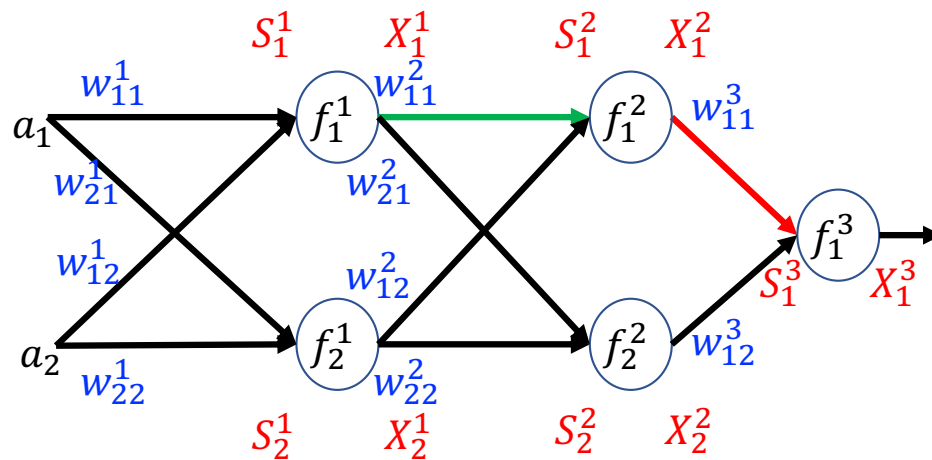
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 2. Rewrite the formula in a matrix form.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \sum_{j=1}^{n^l} \underline{(X_j^l - t_j)} \cdot \left( (f_j^l)'(S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j'}^{l_0})' (S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \right) \right)$$

1

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

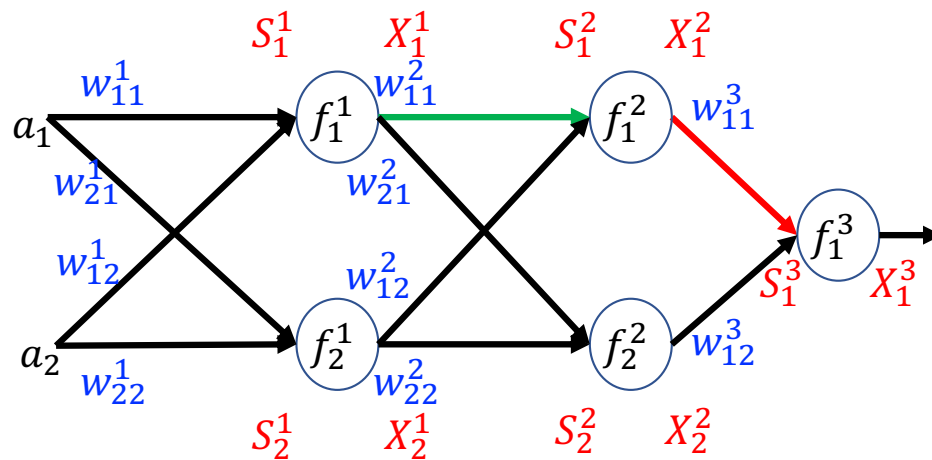
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 2. Rewrite the formula in a matrix form. Let

$$\nabla_{X^l} E \triangleq \left( \frac{\partial E}{\partial X_1^l} \quad \cdots \quad \frac{\partial E}{\partial X_{n^l}^l} \right) = (X_1^l - t_1 \quad \cdots \quad X_{n^l}^l - t_{n^l})$$

be the gradient of the  $l$ -th layer.

# Backpropagation



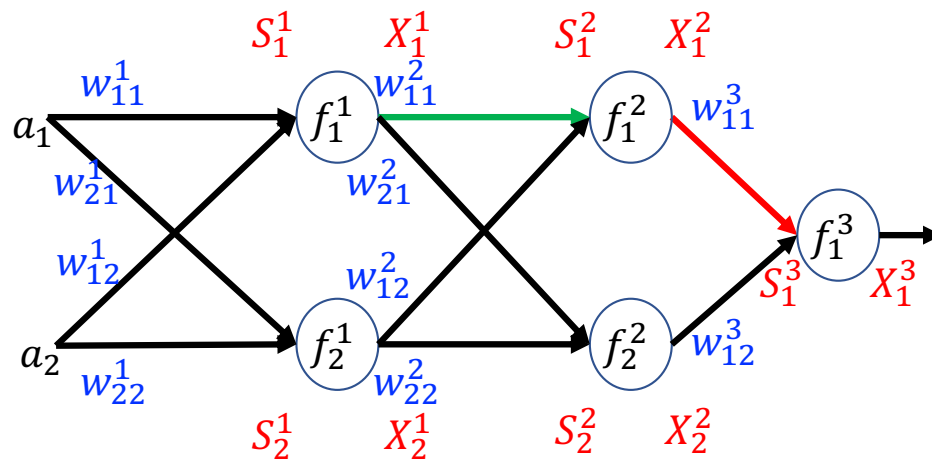
$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 2. Rewrite the formula in a matrix form.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( \underbrace{(f_j^l)'(S_j^l)}_2 \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j'}^{l_0})'(S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \right) \right)$$

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot X_1^2$$

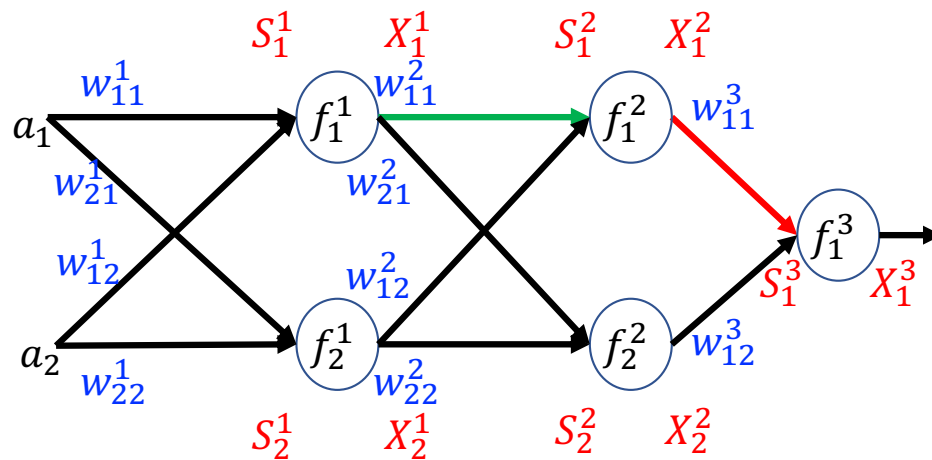
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1$$

Step 2. Rewrite the formula in a matrix form. Let

$$\frac{dX^l}{dS^l} = \frac{df^l(S^l)}{dS^l} \triangleq J_{S^l} f^l = \begin{pmatrix} \frac{df_1^l}{dS_1^l} & \cdots & \frac{df_1^l}{dS_{n^l}^l} \\ \vdots & \ddots & \vdots \\ \frac{df_{n^l}^l}{dS_1^l} & \cdots & \frac{df_{n^l}^l}{dS_{n^l}^l} \end{pmatrix} = \begin{pmatrix} (f_j^l)'(S_j^l) & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & (f_{n^l}^l)'(S_{n^l}^l) \end{pmatrix}$$

Diagonal Matrix!

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

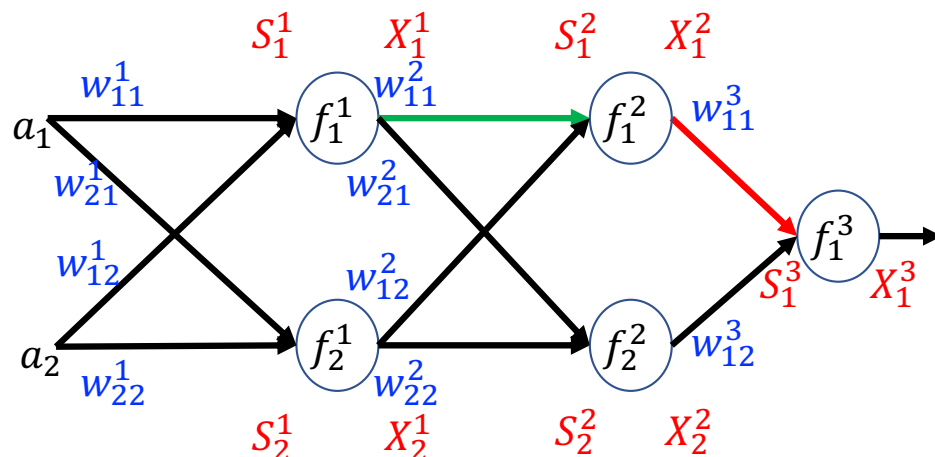
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 2. Rewrite the formula in a matrix form.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( (f_j^l)'(S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j'}^{l_0})'(S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \right) \right)$$



# Backpropagation



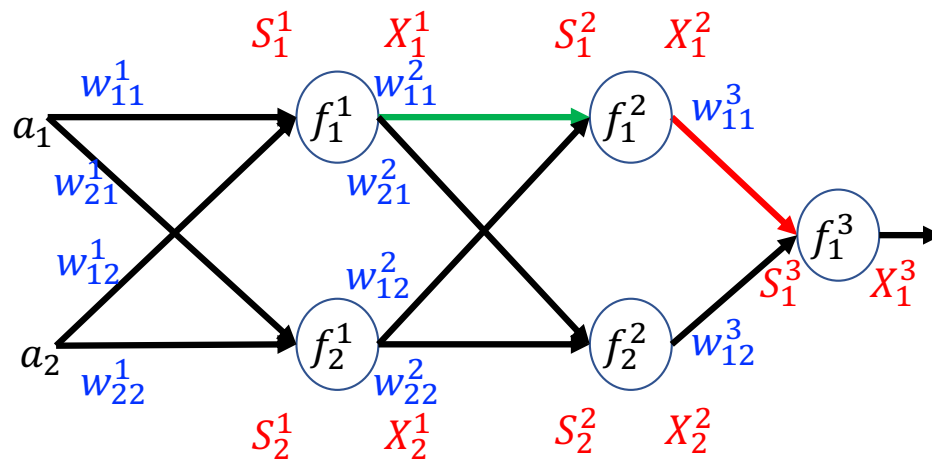
$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot X_1^2$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1$$

Step 2. Rewrite the formula in a matrix form. Let

$$\frac{dS^l}{dX^{l-1}} = \begin{pmatrix} \frac{\partial S_1^l}{\partial X_1^{l-1}} & \cdots & \frac{\partial S_1^l}{\partial X_{n^{l-1}}^{l-1}} \\ \vdots & \ddots & \vdots \\ \frac{\partial S_{n^l}^l}{\partial X_1^l} & \cdots & \frac{\partial S_{n^l}^l}{\partial X_{n^{l-1}}^{l-1}} \end{pmatrix} = \begin{pmatrix} w_{11}^l & \cdots & w_{1n^{l-1}}^l \\ \vdots & \ddots & \vdots \\ w_{n^l 1}^l & \cdots & w_{n^l n^{l-1}}^l \end{pmatrix} \triangleq w^l$$

# Backpropagation



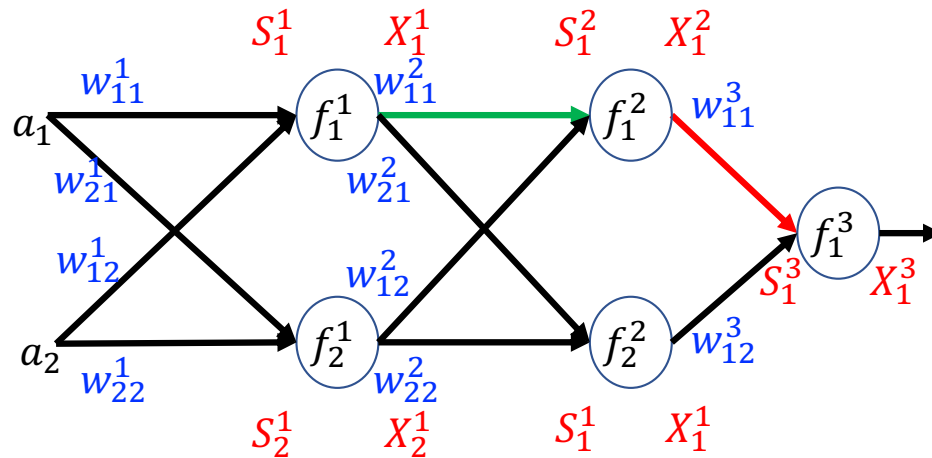
$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 2. Rewrite the formula in a matrix form.

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \sum_{j=1}^{n^l} (X_j^l - t_j) \cdot \left( (f_j^l)'(S_j^l) \cdot \sum_{i=1}^{n^{l-1}} w_{ji}^{l-1} \left( \dots (f_{j'}^{l_0})'(S_{j'}^{l_0}) \cdot \frac{\partial S_{j'}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \right) \right)$$

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

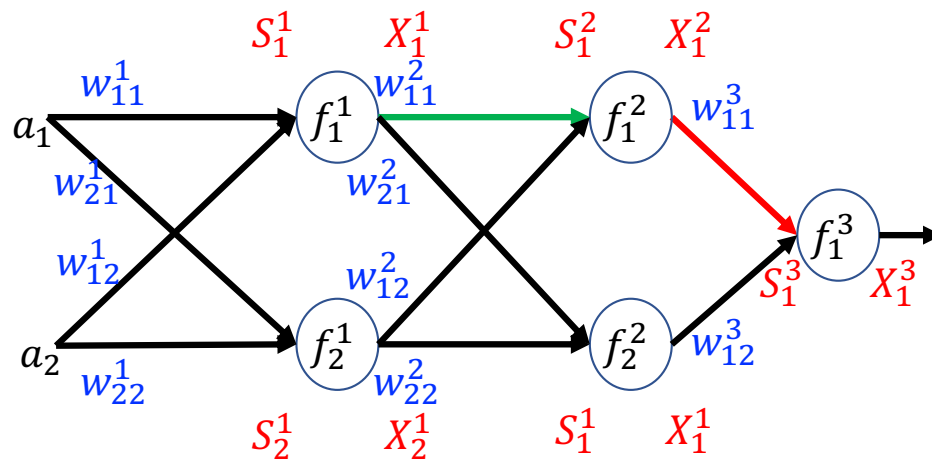
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 2. Rewrite the formula in a matrix form. Let

$$\frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \triangleq \left( \frac{\partial S_1^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \quad \dots \quad \frac{\partial S_{n^{l_0}}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \right)^T = \left( 0 \quad \dots \quad \frac{\partial S_{j_0}^{l_0}}{\partial w_{j_0 i_0}^{l_0}} \quad \dots \quad 0 \right)^T = \left( 0 \quad \dots \quad X_{i_0}^{l_0-1} \quad \dots \quad 0 \right)^T$$

$$\text{where } S^{l_0} = \left( S_1^{l_0} \quad \dots \quad S_{n^{l_0}}^{l_0} \right)^T.$$

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

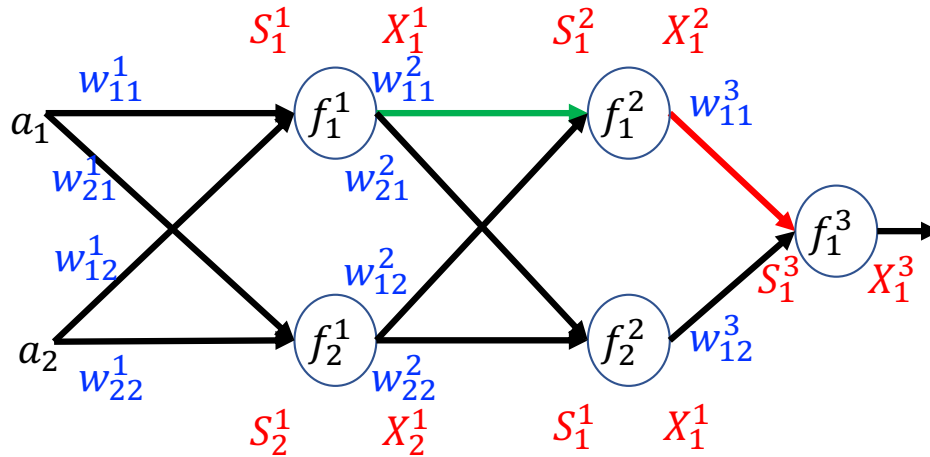
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

Step 2. Rewrite the formula in a matrix form. Now we obtain:

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \frac{dE}{dX^l} \cdot \frac{dX^l}{dS^l} \cdot \frac{dS^l}{dX^{l-1}} \cdot \frac{dX^{l-1}}{dS^{l-1}} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}}$$

This is the **multivariate (vector) version of chain rule!**

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

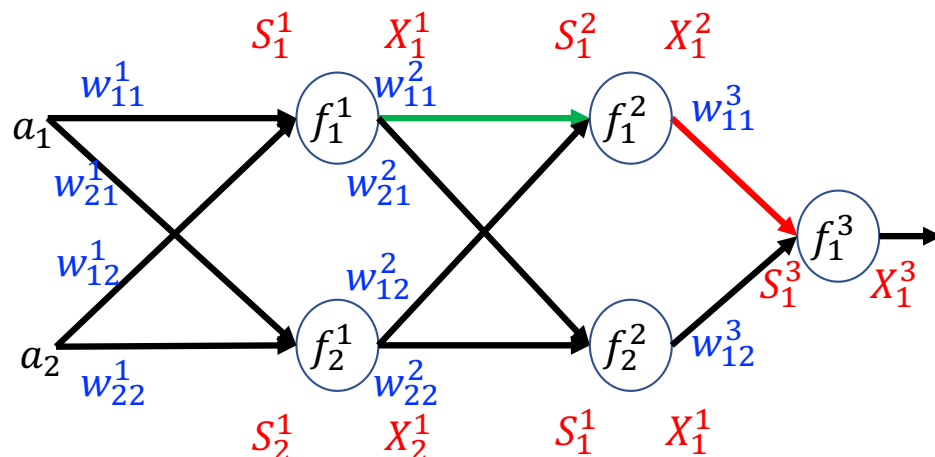
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \frac{dE}{dX^l} \cdot \frac{dX^l}{dS^l} \cdot \frac{dS^l}{dX^{l-1}} \cdot \frac{dX^{l-1}}{dS^{l-1}} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}}$$

Let  $\delta^h = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \mathcal{J}_{S^h} f^h$ . Then we have

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \delta^{l_0} \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \delta^{l_0} \cdot \begin{pmatrix} 0 & \dots & X_{i_0}^{l_0-1} & \dots & 0 \end{pmatrix}^T$$

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \frac{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}{\text{red underline}}$$

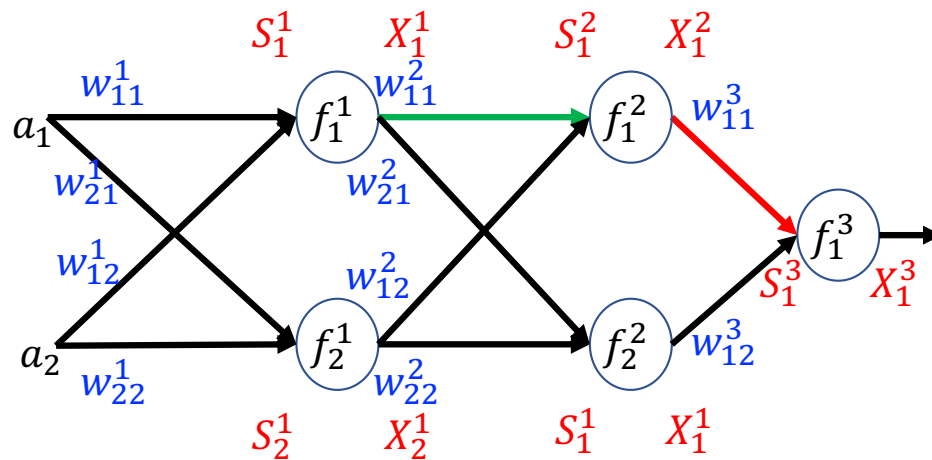
$$\frac{\partial E}{\partial w_{11}^2} = \frac{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}{\text{red underline}}$$

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \frac{dE}{dX^l} \cdot \frac{dX^l}{dS^l} \cdot \frac{dS^l}{dX^{l-1}} \cdot \frac{dX^{l-1}}{dS^{l-1}} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}}$$

Let  $\delta^h = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \mathcal{J}_{S^h} f^h$ . Then we have

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \delta^{l_0} \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \delta^{l_0} \cdot \left( 0 \quad \dots \quad X_{i_0}^{l_0-1} \quad \dots \quad 0 \right)^T$$

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}$$

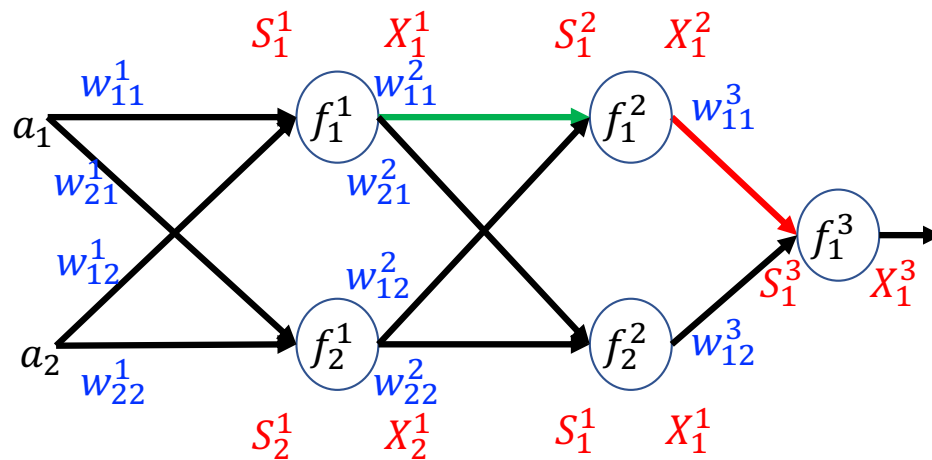
$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}$$

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \frac{dE}{dX^l} \cdot \frac{dX^l}{dS^l} \cdot \frac{dS^l}{dX^{l-1}} \cdot \frac{dX^{l-1}}{dS^{l-1}} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}}$$

Let  $\delta^h = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \mathcal{J}_{S^h} f^h$ . Meanwhile,  $\delta^h$  can be computed recursively:

$$\delta^{h-1} = \delta^h \cdot w^h \cdot \mathcal{J}_{S^{h-1}} f^{h-1}$$

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot X_1^2$$

$$\frac{\partial E}{\partial w_{11}^2} = \underline{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3)} \cdot \underline{w_{11}^3 \cdot (f_1^2)'(S_1^2)} \cdot X_1^1$$

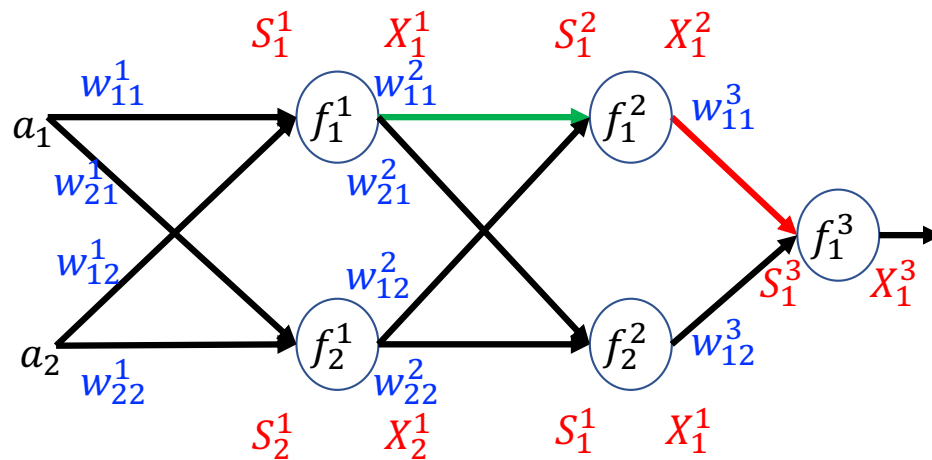
$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \frac{dE}{dX^l} \cdot \frac{dX^l}{dS^l} \cdot \frac{dS^l}{dX^{l-1}} \cdot \frac{dX^{l-1}}{dS^{l-1}} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}}$$

Let  $\delta^h = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \mathcal{J}_{S^h} f^h$ . Meanwhile,  $\delta^h$  can be computed recursively:

$$\delta^{h-1} = \delta^h \cdot \underline{w^h \cdot \mathcal{J}_{S^{h-1}} f^{h-1}}$$



# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \frac{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}{\partial w_{11}^3}$$

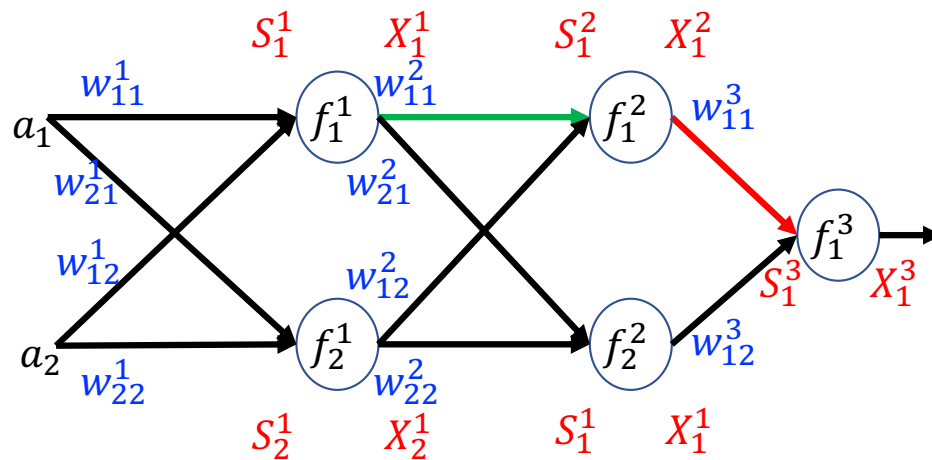
$$\frac{\partial E}{\partial w_{11}^2} = \frac{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}{\partial w_{11}^2}$$

$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \frac{dE}{dX^l} \cdot \frac{dX^l}{dS^l} \cdot \frac{dS^l}{dX^{l-1}} \cdot \frac{dX^{l-1}}{dS^{l-1}} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}}$$

Let  $\delta^h = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \mathcal{J}_{S^h} f^h$ . Meanwhile,  $\delta^h$  can be computed recursively:

$$\delta^{h-1} = \delta^h \cdot w^h \cdot \mathcal{J}_{S^{h-1}} f^{h-1}$$

# Backpropagation



$$\frac{\partial E}{\partial w_{11}^3} = \frac{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot X_1^2}{\partial w_{11}^3}$$

$$\frac{\partial E}{\partial w_{11}^2} = \frac{(X_1^3 - t_1) \cdot (f_1^3)'(S_1^3) \cdot w_{11}^3 \cdot (f_1^2)'(S_1^2) \cdot X_1^1}{\partial w_{11}^2}$$

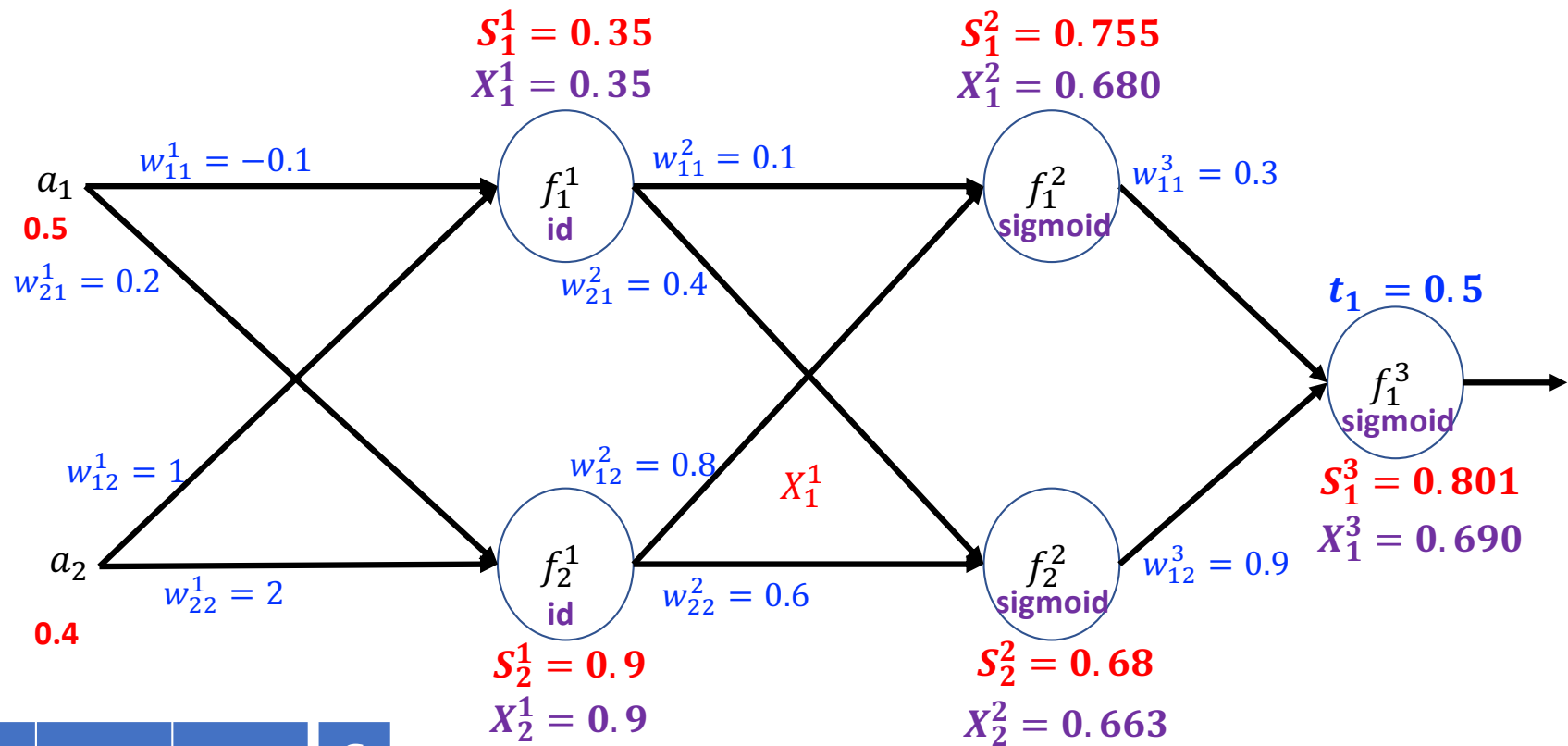
$$\frac{\partial E}{\partial w_{j_0 i_0}^{l_0}} = \frac{dE}{dX^l} \cdot \frac{dX^l}{dS^l} \cdot \frac{dS^l}{dX^{l-1}} \cdot \frac{dX^{l-1}}{dS^{l-1}} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}} = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \frac{\partial S^{l_0}}{\partial w_{j_0 i_0}^{l_0}}$$

Let  $\delta^h = \nabla_{X^l} E \cdot \mathcal{J}_{S^l} f^l \cdot w^l \cdot \mathcal{J}_{S^{l-1}} f^{l-1} \cdot \dots \cdot \mathcal{J}_{S^h} f^h$ . Meanwhile,  $\delta^h$  can be computed recursively:

$$\delta^{h-1} = \delta^h \cdot w^h \cdot \mathcal{J}_{S^{h-1}} f^{h-1}$$

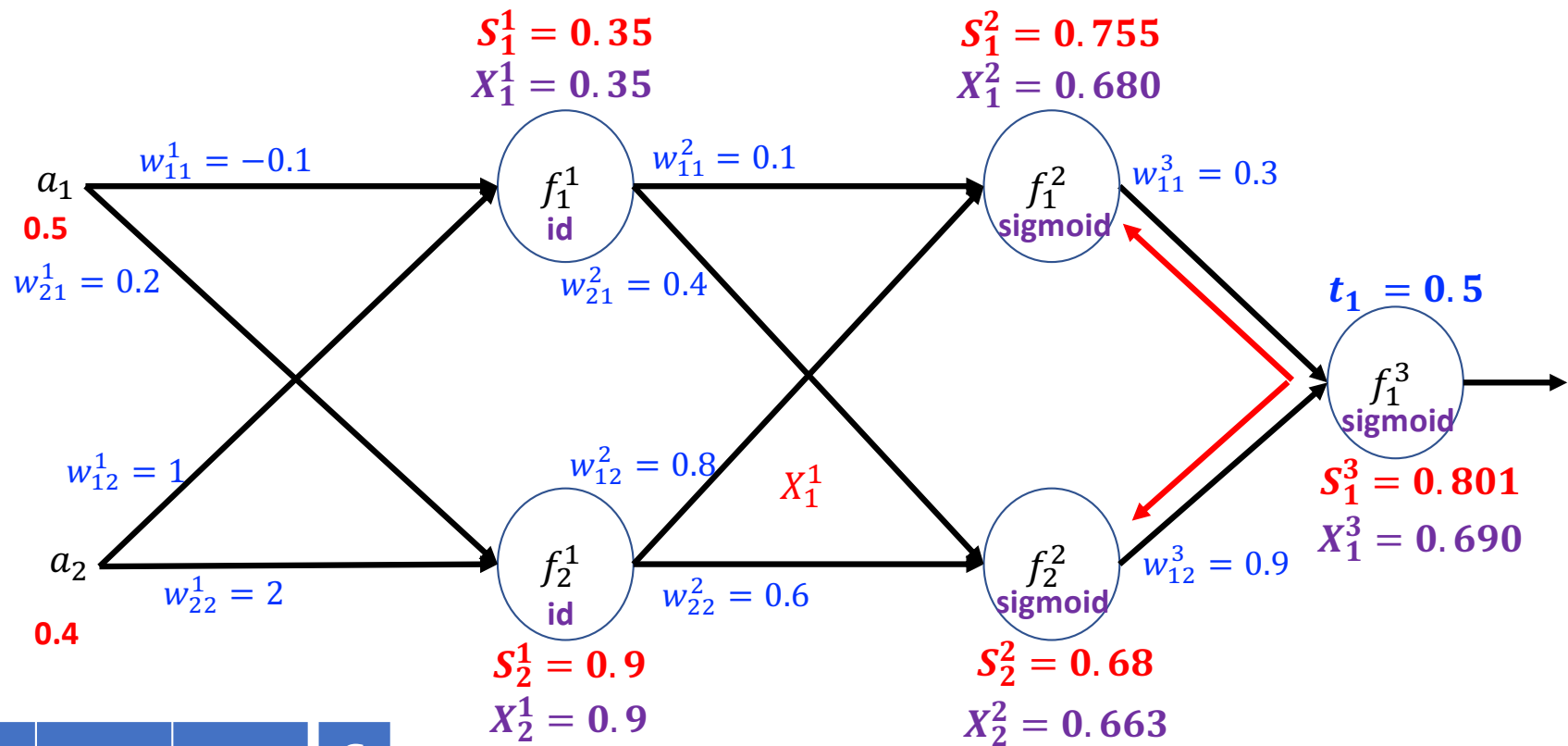
This recursive computing rule is called **backpropagation**!

# Recall the Example



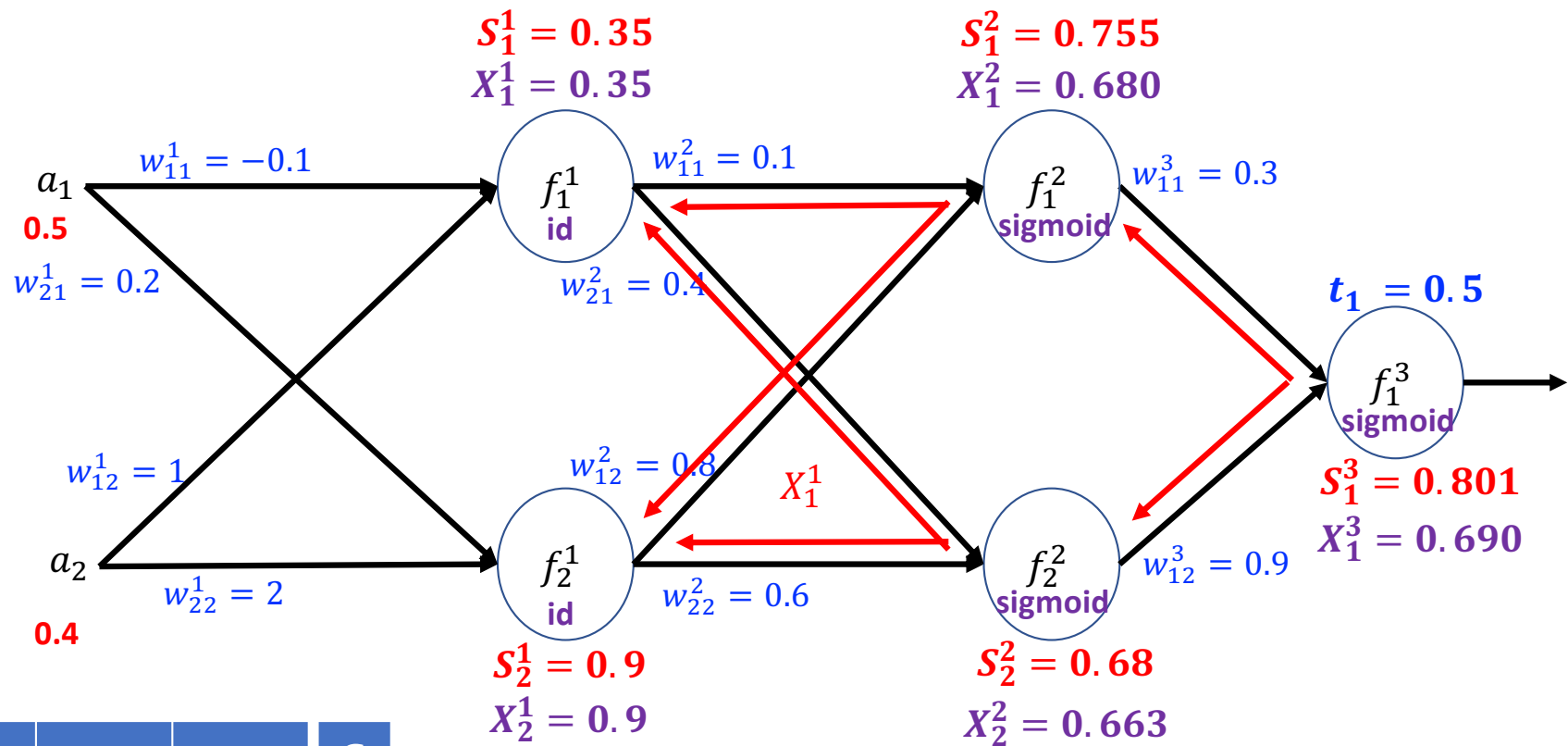
$a_1$	$a_2$	$t_1$	$C$
0.5	0.4	0.5	1

# Recall the Example



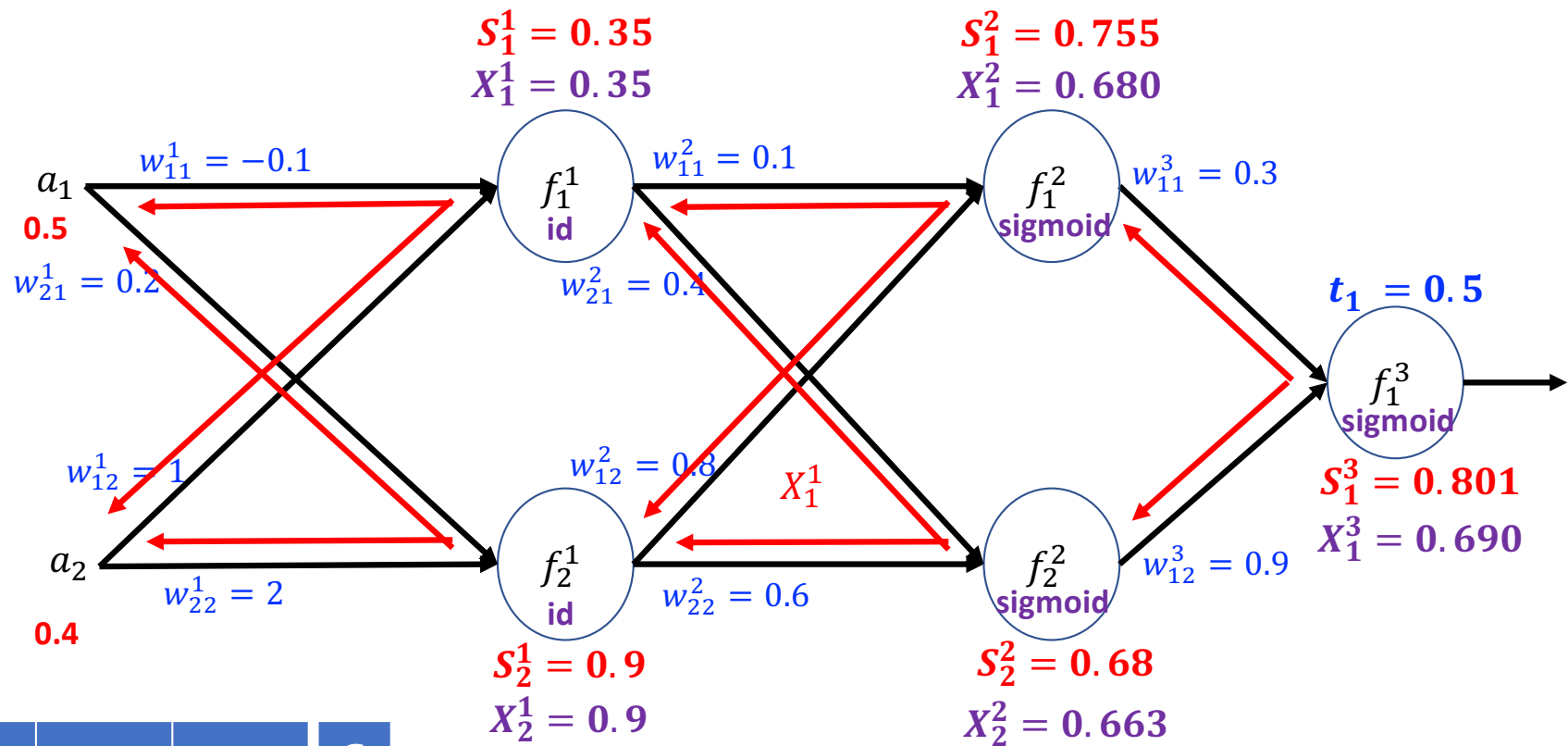
$a_1$	$a_2$	$t_1$	$C$
0.5	0.4	0.5	1

# Recall the Example



$a_1$	$a_2$	$t_1$	$C$
0.5	0.4	0.5	1

# Recall the Example



$a_1$	$a_2$	$t_1$	$C$
0.5	0.4	0.5	1

# Comparing to the Naïve Computation

- Computing  $\delta^{h-1}$  in terms of  $\delta^h$  avoids obvious duplicate computation, more specifically multiplication, of layers  $h$  and beyond.
- Multiplying starting from the output layer – propagating the error **backwards** – means that each step simply multiplies a vector ( $\delta^h$ ) and a weight matrix ( $w^{h-1}$ ), which makes matrix operations so important in neural network forward/backpropagation.

Table 3. Performance Improvements Optimizing  $C = AA^T$  Matrix Multiplication

Optimization	NVIDIA Tesla V100
No optimization	12.8 GB/s
Using shared memory to coalesce global reads	140.2 GB/s
Removing bank conflicts	199.4 GB/s

Source: Nvidia CUDA C++ Best Practices Guide

# Learning Algorithm

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**Algorithm 3: Multilayer Perceptron Learning Algorithm**

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**Data:** Labelled data set  $D$ :  $r$   $n$ -dimensional input points, each of which has  $m$  labels. Small positive real  $\delta$ . Learning rate  $C$ .

**Result:** Weights  $w$  of all the connections.

```
1 Initialize weights  $w$  randomly;
2 while !convergence ( $E \leq \delta$ ) do
3   Pick random  $a \in D$ ;
4   Compute the output  $X$ ;
5   Compute the output error  $E_a$  for this input  $a$ ;
6    $\delta^l = \nabla_{X^l} E_a \cdot \mathcal{J}_{S^l} f^l$ ;
7   for  $h = l, \dots, 1$  do
8      $\frac{\partial E_a}{\partial w^h} = \delta^h \cdot X^h$ ;
9      $\delta^{h-1} = \delta^h \cdot w^h \cdot \mathcal{J}_{S^{h-1}} f^{h-1}$ ;
10  end
11  for  $h = l, \dots, 1$  do
12    for  $j = 1, \dots, n^h$  do
13      for  $i = 1, \dots, n^{h-1}$  do
14         $w_{j,i}^h = w_{j,i}^h - C \frac{\partial E_a}{\partial w_{j,i}^h}$ ;
15      end
16    end
17  end
18 end
19 return  $w$ ;
```

---

- Randomly set initial values of parameters to be learnt.
- Compute the output error by forward propagation.
- The first FOR loop is to compute the partial derivative for each layer by backpropagation.
- We then update the weight of every connection in the network by gradient decent (lazy update).