

# Compact Stars

## via Smoothed Particle Hydrodynamics

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- 2 Smoothed Particle Hydrodynamics
- 3 Implementation
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  - Leapfrog
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# Compact Object Physics and Rotation

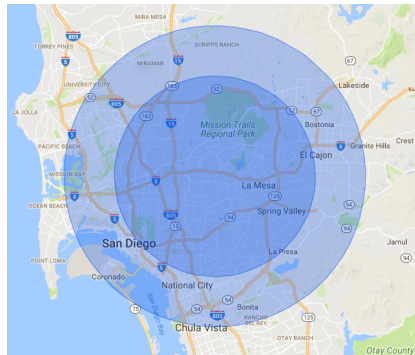
## Compact Object Physics and Rotation

# Compact Objects: A Primer

- Classical Mechanics and General Relativity.
- White Dwarfs, Black Holes

# Compact Objects: A Primer

- Classical Mechanics and General Relativity.
- White Dwarfs, Black Holes
- ...And Neutron Stars.



A neutron star the size of San Diego  
Thanks to: Google Maps and [obettie.github.io](https://github.com/obettie)

# (Differential) Rotation

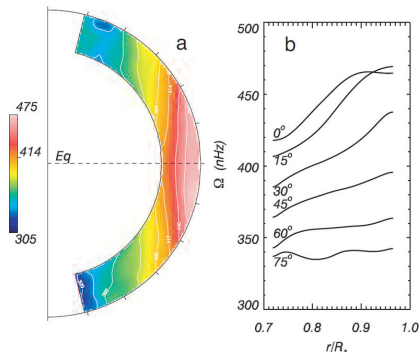
- Rotation in Compact Objects
- Differential Rotation AKA Rotating w.r.t. Rotation

$$j(\Omega) = A^2(\Omega_c - \Omega)$$

$$\frac{\Omega}{\Omega_c} = \frac{A^2}{A^2 + r^2 \sin^2 \theta}$$

$$A = aR_{\text{star}}$$

Muller and Eriguchi (1985)



Differential Rotation of the Sun (Brun et. al. 2004)

# Smoothed Particle Hydrodynamics

SPH: What is it? How does it work? Let's find out!

# Smoothed Particle Hydrodynamics (SPH)

- The N-Body Problem and the Mean-Field approximation... solving the Advection Equation.



# Smoothed Particle Hydrodynamics (SPH)

- The N-Body Problem and the Mean-Field approximation... solving the Advection Equation.
- SPH Mathematics: the Basics

$$\mathcal{L}_{sph} = \sum_{i=1}^N m_i \left[ \frac{1}{2} v_i^2 - u(\rho_i) \right]$$

$$A(r) = \int A(r') W(r - r', h) dr' \rightarrow A(r) = \sum_b m_b \frac{A_b}{\rho_b} W(r - r_b, h)$$

The Smoothing Kernel  $W$

$$W = \frac{1}{\pi h^2} e^{-\frac{|r|^2}{2h^2}}; \quad W_{ij} = W(|r_i - r_j|; h)$$

# Smoothed Particle Hydrodynamics (SPH) - More Physics

- After some Euler-Lagrangian... (Monaghan 1992)

$$\rho(r) = \sum_j m_j W(|r - r_j|; h)$$

$$\frac{dv_i}{dt} = - \sum_j m_j \left( \frac{P_j}{\rho_j^2} + \frac{P_i}{\rho_i^2} \right) \nabla_i W_{ij}$$

$$\frac{du_i}{dt} = \frac{1}{2} \sum_j m_j \left( \frac{P_j}{\rho_j^2} + \frac{P_i}{\rho_i^2} \right) v_{ij} \cdot \nabla_i W_{ij}$$

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- Other considerations include:

$$\Pi_{ij}, \quad h \rightarrow h(i), \quad \text{and damping}$$

# Implementation

Implementation  
or: How I learned to Stop Doing Everything at Once

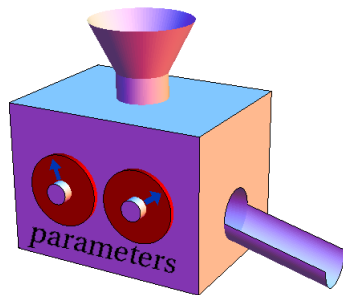
# Initial Conditions and Parameters

- Spatial Discretization?  
Grid/Mesh? Boundaries?
- Initial Conditions:  $x, v, u, \rho$
- Equation of State - Polytropic (simple)
- Parameters:  $k, \nu, \lambda, a$

$$P = k\rho^2$$

$$a_i = -n u v_i - \lambda x_i - a_{i,v1}$$

Monaghan and Price (2004)



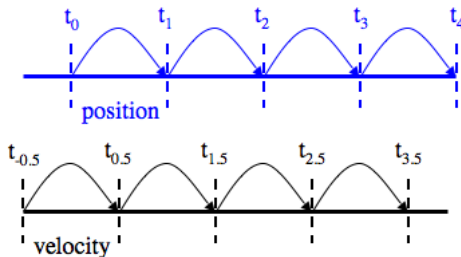
Nykamp DQ, Function machine parameters. From Math Insight.

# Leapfrogging

- Leapfrogging Through Time

$$v_{n+\frac{1}{2}} = v_{n-\frac{1}{2}} + a_n \Delta t$$

$$x_{n+1} = \Delta t v_{n+\frac{1}{2}} + x_n$$

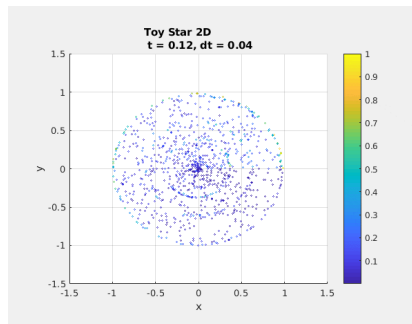


Leapfrogging for position and velocity

# Results

Normalized  $x$ ,  $y$ , Energy/time:

- Without rotation (of any kind)
- Without differential rotation
- With both kinds of rotation



# Conclusions and Extensions

- Energy and (Angular) Momentum Conservation.
- Boundary Conditions and the extent of usefulness of the 'toy' model.
- Better approximation to self-gravity and relativistic approaches.
- Extending to 3D.



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Further references available by request.

