

# Compact Stars

## via Smoothed Particle Hydrodynamics

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# Outline

- 1 Motivation
  - Compact Objects
  - Rotation
- 2 Smoothed Particle Hydrodynamics
- 3 Parallel Approach
- 4 Results, Conclusions, and Extensions

# Compact Object Physics and Rotation

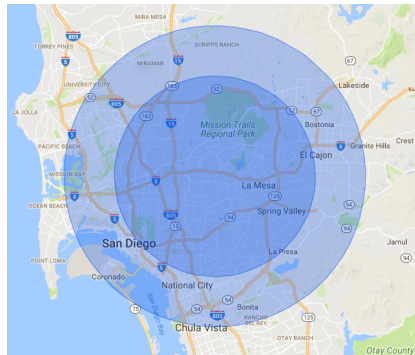
## Compact Object Physics and Rotation

# Compact Objects: A Primer

- Classical Mechanics and General Relativity.
- White Dwarfs, Black Holes

# Compact Objects: A Primer

- Classical Mechanics and General Relativity.
- White Dwarfs, Black Holes
- ...And Neutron Stars.



A neutron star the size of San Diego  
Thanks to: Google Maps and [obettie.github.io](https://github.com/obettie)

# (Differential) Rotation

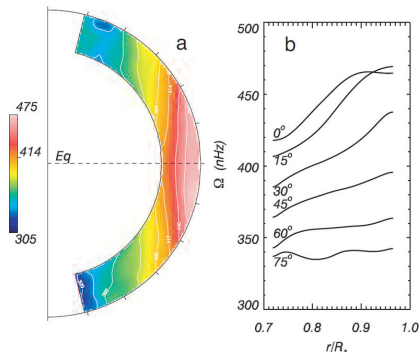
- Rotation in Compact Objects
- Differential Rotation AKA Rotating w.r.t. Rotation

$$j(\Omega) = A^2(\Omega_c - \Omega)$$

$$\frac{\Omega}{\Omega_c} = \frac{A^2}{A^2 + r^2 \sin^2 \theta}$$

$$A = aR_{\text{star}}$$

Muller and Eriguchi (1985)



Differential Rotation of the Sun (Brun et. al. 2004)

# Smoothed Particle Hydrodynamics

SPH: What is it? How does it work? Let's find out!

# Smoothed Particle Hydrodynamics (SPH)

- The N-Body Problem and the Mean-Field approximation



# Smoothed Particle Hydrodynamics (SPH)

- The N-Body Problem and the Mean-Field approximation
- SPH Mathematics: the Basics

$$\mathcal{L}_{sph} = \sum_{i=1}^N m_i \left[ \frac{1}{2} v_i^2 - u(\rho_i) \right]$$

$$A(r) = \int A(r') W(r - r', h) dr' \rightarrow A(r) = \sum_b m_b \frac{A_b}{\rho_b} W(r - r_b, h)$$

The Smoothing Kernel  $W$

$$W = \frac{1}{\pi h^2} e^{-\frac{|r|^2}{2h^2}}; \quad W_{ij} = W(|r_i - r_j|; h)$$

# Smoothed Particle Hydrodynamics (SPH) - More Physics

- After some Euler-Lagrangian... (Monaghan 1992)

$$\rho(r) = \sum_j m_j W(|r - r_j|; h)$$

$$\frac{dv_i}{dt} = - \sum_j m_j \left( \frac{P_j}{\rho_j^2} + \frac{P_i}{\rho_i^2} \right) \nabla_i W_{ij}$$

$$\frac{du_i}{dt} = \frac{1}{2} \sum_j m_j \left( \frac{P_j}{\rho_j^2} + \frac{P_i}{\rho_i^2} \right) v_{ij} \cdot \nabla_i W_{ij}$$

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- Other considerations include:

$$\Pi_{ij}, \quad h \rightarrow h(i), \quad \text{and damping}$$

# Parallel Approach

Parallel Approach feat. CUDA

# Parallelization

- Solving the Advection Equation: Forward Differencing  $\rightarrow$  Leap-Frog

```

for  $t = 1$  to  $MaxTime$  do
    Update  $\vec{x}$ ;
    Update  $\vec{v}$ ;
    Initialize  $\vec{a}$ ;
    for  $i = 1$  to  $N$  do
        for  $j = i + 1$  to  $N$  do
             $\vec{a}_i += \dots \nabla W_{ij}$ ;
             $\vec{a}_j -= \dots \nabla W_{ij}$ ;
             $ut_i += \dots \cdot \nabla W_{ij}$ ;
             $ut_j += \dots \cdot \nabla W_{ij}$ ;
        end
    end
end
  
```

# Implementation

! PARALLELIZING -----

```
tblock = dim3(32,32,1)
grid = dim3(ceiling(real(maxn)/tblock%x),ceiling(real(maxn)/tblock%y),1)
```

```
pos_d(:, :) = pos(:, :)
```

```
CALL gweighf<<<grid, tblock>>>(pos_d, hsm, grad_d)
```

```
grad(:, :) = grad_d(:, :)
```

```
do i = 1,maxn
```

```
    ratioi = P(i)/(rho(i)*rho(i))
```

```
    do j = i+1, maxn
```

```
        ratioj = P(j)/(rho(j)*rho(j))
```

! Monaghan & Price (2004)

! Acceleration due to pressure

```
    temp = m(j)*(ratioi + ratioj)
```

```
    accel(:,i) = accel(:,i) - temp*grad(1,j)
```

```
    accel(:,j) = accel(:,j) + temp*grad(2,j)
```

! Thermal Energy per unit mass/dt.

```
    temp = temp*abs(dot_product(vel(:,i)-vel(:,j),grad(:,j)))
```

```
    ut(i) = ut(i) + temp
```

```
    ut(j) = ut(j) + temp
```

! Assume no thermal conduction between adjacent particles. Just another term that would have to be added.

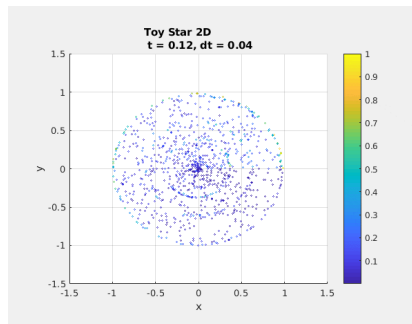
```
    enddo
```

```
enddo
```

# Results

Normalized  $x$ ,  $y$ , Energy/time:

- Without rotation (of any kind)
- Without differential rotation
- With both kinds of rotation



# Conclusions and Extensions

- Expected Speed-up
- Parameterization of the model
- Extending to 3D in problem space and CUDA



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