Node.h Node.cpp

```
#ifndef NODE
#define NODE
//Please add headers here:
#include<RobotSDK.h>
//Port configuration
#undef NODE CLASS
#define NODE CLASS Node
#undef INPUT_PORT_NUM
#define INPUT_PORT_NUM 2
#undef OUTPUT PORT NUM
#define OUTPUT PORT NUM 3
//Uncomment below PORT DECL and set input node class name
//PORT_DECL(0, InputNodeClassName)
//PORT DECL(1, InputNodeClassName)
//Params types configuration
//If you need refer params type of other node class, please uncomment below and comment its own params type.
//NODE PARAMS TYPE REF(RefNodeClassName)
class NODE PARAMS TYPE: public NODE PARAMS BASE TYPE
//Vars types configuration
//If you need refer vars type of other node class, please uncomment below and comment its own vars type.
//NODE VARS TYPE REF(RefNodeClassName)
class NODE VARS TYPE: public NODE VARS BASE TYPE
//Data types configuration
//If you need refer data type of other node class, please uncomment below and comment its own data type.
//NODE DATA TYPE REF(RefNodeClassName)
class NODE DATA TYPE: public NODE DATA BASE TYPE
//You can declare functions here
#endif
```

```
#include"Node.h"
     //If you need use extended node, please uncomment below and comment the using of default node
     //USE EXTENDED NODE(ExtendedNodeClass[,...])
     USE DEFAULT NODE
     //Original node functions
     //If you don't need initialize node, you can delete this code segment
     NODE FUNC DEF EXPORT(bool, initializeNode)
         return 1;
     //If you don't need manually open node, you can delete this code segment
     NODE FUNC DEF EXPORT(bool, openNode)
         return 1;
     //If you don't need manually close node, you can delete this code segment
     NODE FUNC DEF EXPORT(bool, closeNode)
         return 1;
     //This is original main function, you must keep it
29 - NODE_FUNC_DEF_EXPORT(bool, main)
         return 1;
```

