

Input

Node::node3

Output

Developing...

Config.xml

Open Node

Show Widget

Port_0

Port_1

Change ExName

Change Library

Change Config File

Change Config Values

Generate Code

Delete Node

Node.cpp

Node.h

Generate Code for Node::node3

alexanderhmw SDK RobotSDK_4.0 Modules **Sensor** Create Folder

Places

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Robot-X

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Name	Size	Modified
CameraSensor.cpp	3.2 kB	Saturday
CameraSensor.h	2.2 kB	Friday
CameraVelodyneFusion.cpp	3.4 kB	Saturday
CameraVelodyneFusion.h	2.0 kB	Saturday
ImagePointCloudFusionViewer.cpp	3.4 kB	Saturday
ImagePointCloudFusionViewer.h	2.7 kB	Saturday
ImageProcessor.cpp	4.8 kB	Saturday
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ImageViewer.cpp	2.5 kB	Saturday
ImageViewer.h	2.0 kB	Friday
PointCloudViewer.cpp	2.4 kB	Thursday
PointCloudViewer.h	1.7 kB	Friday
Sensor.pro	1.4 kB	Saturday
Sensor.pro.user	18.5 kB	Saturday
VelodyneSensor.cpp	3.4 kB	Saturday
VelodyneSensor.h	2.2 kB	Friday

Cancel Open